



中认信通

CHINA CERTIFICATION ICT CO., LTD (DONGGUAN)



SAR TEST REPORT

Applicant: Quanzhou VBTER Electronics Co.,Ltd.

Address: 427-432,4F Wanxiang Mall, Yuquan Middle Street, Quanzhou, China

FCC ID: 2A4RP-VBT-GT3

Product Name: Two-way radio

Standard(s): 47 CFR Part 2(2.1093)

The above device has been tested and found compliant with the requirement of the relative standards by China Certification ICT Co., Ltd (Dongguan)

Report Number: 2603T34877E-20

Date Of Issue: 2026/06/24

Reviewed By: Ken Zong

Ken Zong

Title: SAR Tester

Approved By: Karl Gong

Karl Gong

Title: SAR Test Supervisor

Test Laboratory: China Certification ICT Co., Ltd (Dongguan)

Room 101 & 201, Building 2, 256 Pingdong Road, Dalang Town, Dongguan City, Guangdong, China

Tel: +86-769-83085888

www.ccttt.com.cn

SAR TEST RESULTS SUMMARY

Operation Frequency Bands	Highest Reported 1g SAR (W/kg)		Limits (W/kg)
	Head Face Up (Gap 25mm)	Body-Worn (Gap 0mm)	
PTT(462.55-467.7125MHz)	0.09	0.21	1.6
Maximum Simultaneous Transmission SAR			
Items	Head Face Up (Gap 25mm)	Body-Worn (Gap 0mm)	Limits (W/kg)
Sum SAR(W/kg)	N/A	N/A	1.6
EUT Received Date:	2026/05/13		
Tested Date:	2026/05/28		
Tested Result:	Pass		

Test Facility

The Test site used by China Certification ICT Co., Ltd (Dongguan) to collect test data is located on the Room 101 & 201, Building 2, 256 Pingdong Road, Dalang Town, Dongguan City, Guangdong, China.

The lab has been recognized as the FCC accredited lab under the KDB 974614 D01 and is listed in the FCC Public Access Link (PAL) database, FCC Registration No. : 442868, the FCC Designation No. : CN1314.

Declarations

China Certification ICT Co., Ltd (Dongguan) is not responsible for the authenticity of any test data provided by the applicant. Data included from the applicant that may affect test results are marked with a triangle symbol “▲”. Customer model name, addresses, names, trademarks etc. are not considered data.

Unless otherwise stated the results shown in this test report refer only to the sample(s) tested.

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Each test item follows the test standard(s) without deviation.

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DOCUMENT REVISION HISTORY

Revision Number	Report Number	Description of Revision	Date of Revision
1.0	2603T34877E-20	Original Report	2026/06/24

1. GENERAL INFORMATION

1.1 Product Description for Equipment under Test (EUT)

EUT Name:	Two-way radio
EUT Model:	VBT-GT3
Multiple Models:	VBT-GT3 Plus, VBT-GT3 Pro, VBT-GT3 Max, VBT-GT7, VBT-GT7 Plus, VBT-GT7 Pro, VBT-GT7 Max, VBT-GT5, VBT-GT5 Plus, VBT-GT5 Pro, VBT-GT5 Max, VBT-GT6, VBT-GT6 Plus, VBT-GT6 Pro, VBT-GT6 Max
Device Type:	Portable
Exposure Category:	Population /Uncontrolled
Antenna Type(s):	Spring Antenna
Body-Worn Accessories:	Belt Clip
Face-Head Accessories:	None
Operation modes:	PTT_FM
Frequency Band:	462MHz(462.5500-462.7250 MHz) 467MHz(462.5625-467.7125 MHz)
Dimensions (L*W*H):	169 mm (L) * 56 mm (W) * 30 mm (H) (not including Belt Clip) (The dimensions of each model are the same)
Rated Input Voltage:	DC 3.7 V from Rechargeable Battery
Serial Number:	3LW6-1
Normal Operation:	Face Up and Body
<i>Note: The Multiple models are electrically identical with the test model except for model name and appearance (horn mouth). Please refer to the declaration letter for more detail, which was provided by manufacturer.</i>	

1.2 Test Specification, Methods and Procedures

The tests documented in this report were performed in accordance with FCC 47 CFR § 2.1093, IEEE 1528-2013, the following FCC Published RF exposure KDB procedures:

KDB 447498 D01 General RF Exposure Guidance v06
KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz v01r04
KDB 865664 D02 RF Exposure Reporting v01r02
KDB 643646 D01 SAR Test for PTT Radios v01r03

TCB Workshop April 2019: RF Exposure Procedures

1.3 SAR Limits

FCC Limit

EXPOSURE LIMITS	SAR (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)
Spatial Average (averaged over the whole body)	0.08	0.4
Spatial Peak (averaged over any 1 g of tissue)	1.60	8.0
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

Population/Uncontrolled Environments are defined as locations where there is the exposure of individual who have no knowledge or control of their exposure.

Occupational/Controlled Environments are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure (i.e. as a result of employment or occupation).

General Population/Uncontrolled environments Spatial Peak limit 1.6W/kg for 1g SAR applied to the EUT.

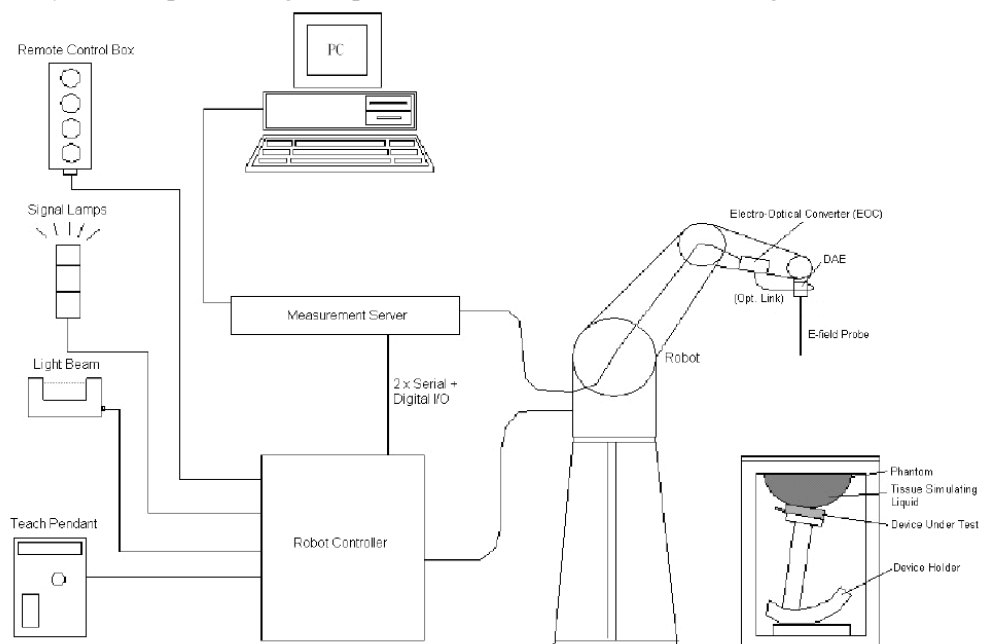
2. SAR MEASUREMENT SYSTEM

These measurements were performed with the automated near-field scanning system DASY5 from Schmid & Partner Engineering AG (SPEAG) which is the Fifth generation of the system shown in the figure hereinafter:



DASY5 System Description

The DASY5 system for performing compliance tests consists of the following items:



- A standard high precision 6-axis robot with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal application, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running Win7 professional operating system and the DASY52 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

DASY5 Measurement Server

The DASY5 measurement server is based on a PC/104 CPU board with a 400MHz Intel ULV Celeron, 128MB chip-disk and 128MB RAM. The necessary circuits for communication with the DAE4 (or DAE3) electronics box, as well as the 16 bit AD-converter system for optical detection and digital I/O interface are contained on the DASY5 I/O board, which is directly connected to the PC/104 bus of the CPU board.



The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized point out, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.

Data Acquisition Electronics

The data acquisition electronics (DAE4) consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of both the DAE4 as well as of the DAE3 box is 200M Ω ; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.

ES3DV2 E-Field Probes

Frequency	10 MHz - 4 GHz Linearity: ± 0.2 dB (30 MHz to 4 GHz)
Directivity	± 0.2 dB in TSL (rotation around probe axis) ± 0.3 dB in TSL (rotation normal to probe axis)
Dynamic Range	5 μ W/g to > 100 mW/g Linearity: ± 0.2 dB (noise: typically < 1 μ W/g)
Dimensions	Overall length: 337 mm (Tip: 20 mm) Tip diameter: 3.9 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 2.0 mm
Application	General dosimetry up to 4 GHz Dosimetry in strong gradient fields Compliance tests of mobile phones
Compatibility	DASY3, DASY4, DASY52, DASY6, DASY8 SAR, EASY6, EASY4/MRI

ELI Phantom

The ELI phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30MHz to 6 GHz. ELI is fully compatible with the latest draft of the standard IEEE 1528-2013 and the use of all known tissue simulating liquids. ELI has been optimized for performance and can be integrated into a SPEAG standard phantom table. A cover is provided to prevent evaporation of water and changes in liquid parameters. Reference markings on the phantom allow installation of the complete setup, including all predefined phantom positions and measurement grids, by teaching three points.



The phantom can be used with the following tissue simulating liquids:

- Sugar-water-based liquids can be left permanently in the phantom. Always cover the liquid when the system is not in use to prevent changes in liquid parameters due to water evaporation.
- DGBE-based liquids should be used with care. As DGBE is a softener for most plastics, the liquid should be taken out of the phantom, and the phantom should be dried when the system is not in use (desirable at least once a week).
- Do not use other organic solvents without previously testing the solvent resistivity of the phantom.



Approximately 25 liters of liquid is required to _fill the ELI phantom

Robots

The DASY5 system uses the high precision industrial robot. The robot offers the same features important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchrony motors; no stepper motors)
- Low ELF interference (motor control fields shielded via the closed metallic construction shields)

The above mentioned robots are controlled by the Staubli CS8c robot controllers. All information regarding the use and maintenance of the robot arm and the robot controller is contained on the CDs delivered along with the robot. Paper manuals are available upon request direct from Staubli.

SAR Scan Procedures

Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. The minimum distance of probe sensors to surface is 1.4 mm. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

Step 2: Area Scans

Area scans are defined prior to the measurement process being executed with a user defined variable spacing between each measurement point (integral) allowing low uncertainty measurements to be conducted. Scans defined for FCC applications utilize a 15mm 2 step integral, with 1.5mm interpolation used to locate the peak SAR area used for zoom scan assessments.

Where the system identifies multiple SAR peaks (which are within 25% of peak value) the system will provide the user with the option of assessing each peak location individually for zoom scan averaging.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz

	≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 mm $\pm$ 1 mm	$\frac{1}{2} \cdot \delta \cdot \ln(2)$ mm $\pm$ 0.5 mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location	$30^\circ \pm 1^\circ$	$20^\circ \pm 1^\circ$
Maximum area scan spatial resolution: Δx_{Area} , Δy_{Area}	≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm
	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

Step 3: Zoom Scan (Cube Scan Averaging)

The averaging zoom scan volume utilized in the DASY5 software is in the shape of a cube and the side dimension of a 1 g or 10 g mass is dependent on the density of the liquid representing the simulated tissue. A density of 1000 kg/m³ is used to represent the head and body tissue density and not the phantom liquid density, in order to be consistent with the definition of the liquid dielectric properties, i.e. the side length of the 1g cube is 10mm, with the side length of the 10g cube is 21.5mm.

Zoom Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz

			$\leq 3 \text{ GHz}$	$> 3 \text{ GHz}$
Maximum zoom scan spatial resolution: $\Delta x_{\text{Zoom}}, \Delta y_{\text{Zoom}}$			$\leq 2 \text{ GHz}: \leq 8 \text{ mm}$ $2 - 3 \text{ GHz}: \leq 5 \text{ mm}^*$	$3 - 4 \text{ GHz}: \leq 5 \text{ mm}^*$ $4 - 6 \text{ GHz}: \leq 4 \text{ mm}^*$
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{\text{Zoom}}(n)$		$\leq 5 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 4 \text{ mm}$ $4 - 5 \text{ GHz}: \leq 3 \text{ mm}$ $5 - 6 \text{ GHz}: \leq 2 \text{ mm}$
	graded grid	$\Delta z_{\text{Zoom}}(1)$: between 1 st two points closest to phantom surface	$\leq 4 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 3 \text{ mm}$ $4 - 5 \text{ GHz}: \leq 2.5 \text{ mm}$ $5 - 6 \text{ GHz}: \leq 2 \text{ mm}$
		$\Delta z_{\text{Zoom}}(n>1)$: between subsequent points	$\leq 1.5 \cdot \Delta z_{\text{Zoom}}(n-1) \text{ mm}$	
Minimum zoom scan volume	x, y, z		$\geq 30 \text{ mm}$	$3 - 4 \text{ GHz}: \geq 28 \text{ mm}$ $4 - 5 \text{ GHz}: \geq 25 \text{ mm}$ $5 - 6 \text{ GHz}: \geq 22 \text{ mm}$
Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see IEEE Std 1528-2013 for details.				
* When zoom scan is required and the <i>reported</i> SAR from the <i>area scan based 1-g SAR estimation</i> procedures of KDB Publication 447498 is $\leq 1.4 \text{ W/kg}$, $\leq 8 \text{ mm}$, $\leq 7 \text{ mm}$ and $\leq 5 \text{ mm}$ zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.				

Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the last Power Reference Measurement. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

When the cube intersects with the surface of the phantom, it is oriented so that 3 vertices touch the surface of the shell or the center of a face is tangent to the surface. The face of the cube closest to the surface is modified in order to conform to the tangent surface.

The zoom scan integer steps can be user defined so as to reduce uncertainty, but normal practice for typical test applications (including FCC) utilize a physical step of 7 x 7 x 7 (5mmx5mmx5mm) providing a volume of 30 mm in the X & Y & Z axis.

Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE 1528-2013

Recommended Tissue Dielectric Parameters for Head liquid

Table 3—Target dielectric properties of head tissue-equivalent material in the 300 MHz to 6000 MHz frequency range

Frequency (MHz)	Relative permittivity (ϵ_r)	Conductivity (σ) (S/m)
300	45.3	0.87
450	43.5	0.87
750	41.9	0.89
835	41.5	0.90
900	41.5	0.97
1450	40.5	1.20
1500	40.4	1.23
1640	40.2	1.31
1750	40.1	1.37
1800	40.0	1.40
1900	40.0	1.40
2000	40.0	1.40
2100	39.8	1.49
2300	39.5	1.67
2450	39.2	1.80
2600	39.0	1.96
3000	38.5	2.40
3500	37.9	2.91
4000	37.4	3.43
4500	36.8	3.94
5000	36.2	4.45
5200	36.0	4.66
5400	35.8	4.86
5600	35.5	5.07
5800	35.3	5.27
6000	35.1	5.48

NOTE—For convenience, permittivity and conductivity values at some frequencies that are not part of the original data from Drossos et al. [B60] or the extension to 5800 MHz are provided (i.e., the values shown in italics). These values were linearly interpolated between the values in this table that are immediately above and below these values, except the values at 6000 MHz that were linearly extrapolated from the values at 3000 MHz and 5800 MHz.

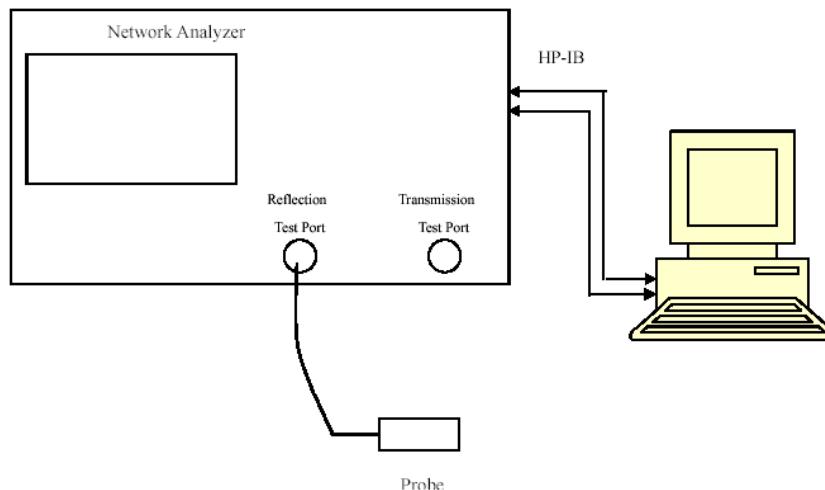
3. EQUIPMENT LIST AND CALIBRATION

3.1 Equipments List & Calibration Information

Equipment	Model	S/N	Calibration Date	Calibration Due Date
DASY5 Test Software	DASY52.10	N/A	NCR	NCR
DASY5 Measurement Server	DASY5 4.5.12	1567	NCR	NCR
Data Acquisition Electronics	DAE4	1354	2025/12/1	2026/11/30
E-Field Probe	ES3DV2	3019	2026/2/18	2027/2/17
Mounting Device	MD4HHTV5	BJPCTC0152	NCR	NCR
Oval Flat Phantom	ELI V8.0	2051	NCR	NCR
Dipole, 450MHz	D450V3	1096	2025/7/7	2028/7/6
Simulated Tissue 450 MHz Head	TS-450H	2509045001	Each Time	/
Network Analyzer	E5071C	MY46528621	2025/11/10	2026/11/9
Dielectric assessment kit	1319	SM DAK 040 CA	NCR	NCR
MXG Vector Signal Generator	N5182B	MY57301579	2025/11/14	2026/11/13
Power Meter	ML2495A	1106009	2025/8/5	2026/8/4
USB Average Power Sensor	U2001H	MY50000432	2026/2/27	2027/2/26
Power Amplifier	HPABSCT-20M6G50W	Z1B5R071464	2025/11/16	2026/11/15
Directional Coupler	4226-20	03328	NCR	NCR
Attenuator	757C-30dB	35612	2025/11/13	2026/11/12
Attenuator	20dB, 100W	LN749	NCR	NCR
Thermometer	DTM3000	3892	2026/3/29	2027/3/28
Thermo-hygrometer	JR311	20251218-2	2025/11/10	2026/11/9
Spectrum Analyzer	FSU26	200256	2026/2/27	2027/2/26

4. SAR MEASUREMENT SYSTEM VERIFICATION

4.1 Liquid Verification



Liquid Verification Setup Block Diagram

Liquid Verification Results

Frequency (MHz)	Liquid Type	Liquid Parameter		Target Value		Delta (%)		Tolerance (%)
		ϵ_r	σ (S/m)	ϵ_r	σ (S/m)	$\Delta\epsilon_r$	$\Delta\sigma$	
450	Simulated Tissue 450 MHz Head	43.927	0.879	43.5	0.87	0.98	1.03	± 5
462.6375	Simulated Tissue 450 MHz Head	43.746	0.887	43.43	0.87	0.73	1.95	± 5
467.6375	Simulated Tissue 450 MHz Head	43.693	0.889	43.41	0.87	0.65	2.18	± 5

*Liquid Verification above was performed on 2026/05/28.

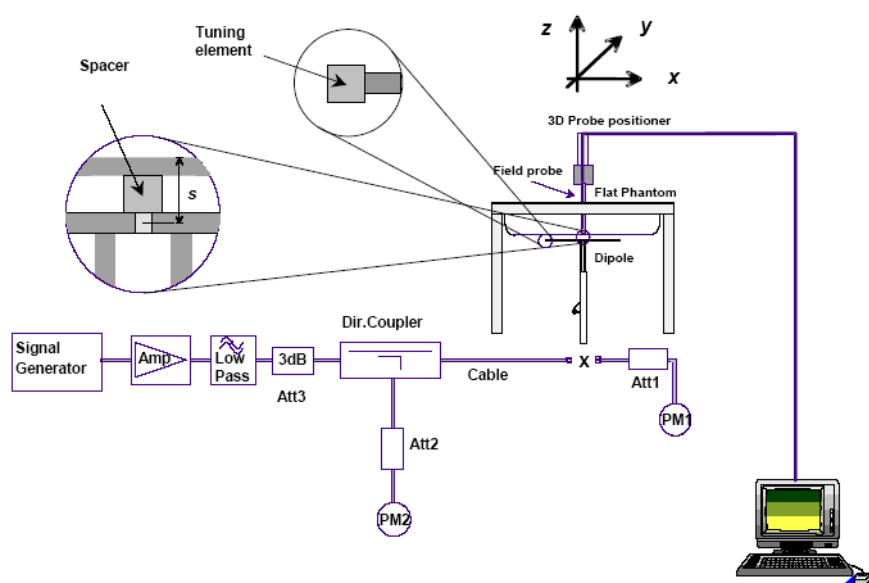
4.2 System Accuracy Verification

Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of $\pm 10\%$. The validation results are tabulated below. And also the corresponding SAR plot is attached as well in the SAR plots files.

The spacing distances in the **System Verification Setup Block Diagram** is given by the following:

- $s = 15 \text{ mm} \pm 0,2 \text{ mm}$ for $300 \text{ MHz} \leq f \leq 1\,000 \text{ MHz}$;
- $s = 10 \text{ mm} \pm 0,2 \text{ mm}$ for $1\,000 \text{ MHz} < f \leq 3\,000 \text{ MHz}$;
- $s = 10 \text{ mm} \pm 0,2 \text{ mm}$ for $3\,000 \text{ MHz} < f \leq 6\,000 \text{ MHz}$.

System Verification Setup Block Diagram



System Accuracy Check Results

Date	Frequency Band	Liquid Type	Input Power (W)	Measured SAR (W/kg)		Target Value (W/kg)	Delta (%)	Tolerance (%)
2026/05/28	450 MHz	Simulated Tissue 450 MHz Head	1	1g	4.49	4.58	-1.97	± 10

4.3 SAR SYSTEM VALIDATION DATA

System Performance 450 MHz Head

DUT: Dipole 450 MHz; Type: D450V3; Serial: 1096

Communication System: CW; Frequency: 450 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 450$ MHz; $\sigma = 0.879$ S/m; $\epsilon_r = 43.927$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: ES3DV2 - SN3019; ConvF(6.84, 6.84, 6.84) @ 450 MHz; Calibrated: 2026/2/18
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2025/12/1
- Phantom: ELI v8.0; Type: QDOVA002AA; Serial: TP:2051
- Measurement SW: DASY52, Version 52.10 (4); SEMCAD X Version 14.6.14 (7501)

Area Scan (8x21x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 5.04 W/kg

Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 71.60 V/m; Power Drift = -0.14 dB

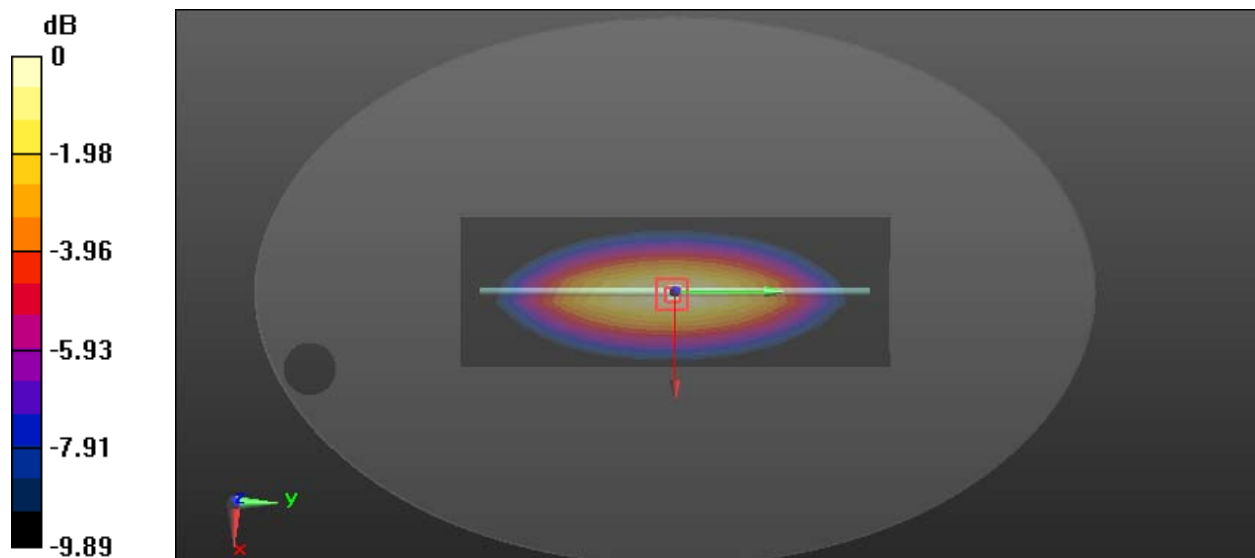
Peak SAR (extrapolated) = 6.83 W/kg

SAR(1 g) = 4.49 W/kg; SAR(10 g) = 2.98 W/kg

Smallest distance from peaks to all points 3 dB below: Larger than measurement grid (> 16 mm)

Ratio of SAR at M2 to SAR at M1 = 66.3%

Maximum value of SAR (measured) = 5.18 W/kg



0 dB = 5.18 W/kg = 7.14 dBW/kg

5. EUT TEST STRATEGY AND METHODOLOGY

5.1 Test positions for Front-of-face configurations

Passive body-worn and audio accessories generally do not apply to the head SAR of PTT radios. Head SAR is measured with the front surface of the radio positioned at 2.5 cm parallel to a flat phantom. A phantom shell thickness of 2 mm is required. When the front of the radio has a contour or non-uniform surface with a variation of 1.0 cm or more, the average distance of such variations is used to establish the 2.5 cm test separation from the phantom.

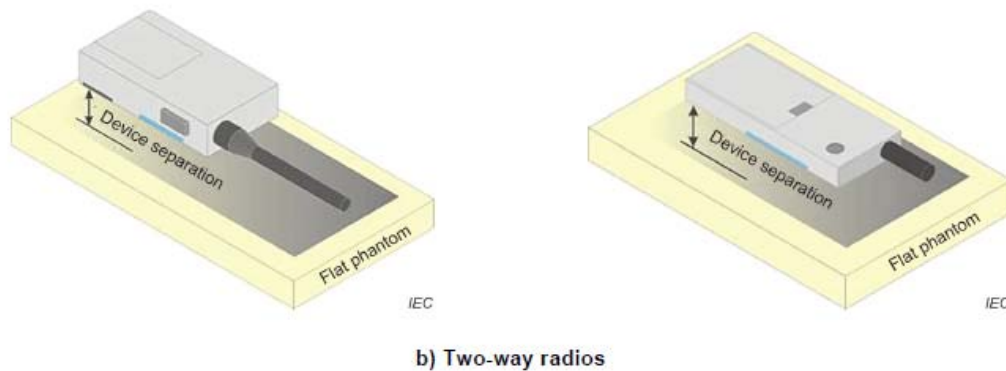


Figure 10 – Test positions for front-of-face devices

5.2 Test positions for body-worn and other configurations

Body-worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a headset output should be tested with a headset connected to the device. When multiple accessories that do not contain metallic components are supplied with the device, the device may be tested with only the accessory that dictates the closest spacing to the body. When multiple accessories that contain metallic components are supplied with the device, the device must be tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (e.g., the same metallic belt-clip used with different holsters with no other metallic components), only the accessory that dictates the closest spacing to the body must be tested.

Body-worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances. Other separation distances may be used, but they should not exceed 2.5 cm. In these cases, the device may use body-worn accessories that provide a separation distance greater than that tested for the device provided however that the accessory contains no metallic components.

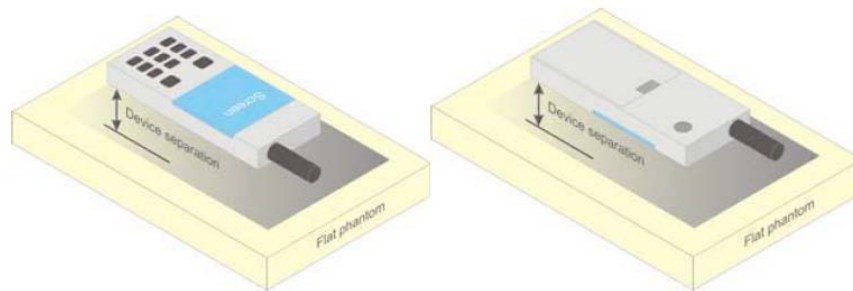


Figure 5 – Test positions for body-worn devices

5.3 Test Distance for SAR Evaluation

In this case the DUT(Device Under Test) is set directly against the phantom, the test distance is 0mm for Body Back mode; for Face Up mode the distance is 25mm.

5.4 SAR Evaluation Procedure

The evaluation was performed with the following procedure:

Step 1: Measurement of the SAR value at a fixed location above the ear point or central position was used as a reference value for assessing the power drop. The SAR at this point is measured at the start of the test and then again at the end of the testing.

Step 2: The SAR distribution at the exposed side of the head was measured at a distance of 4 mm from the inner surface of the shell. The area covered the entire dimension of the head or radiating structures of the EUT, the horizontal grid spacing was 15 mm x 15 mm, and the SAR distribution was determined by integrated grid of 1.5mm x 1.5mm. Based on these data, the area of the maximum absorption was determined by spline interpolation. The first Area Scan covers the entire dimension of the EUT to ensure that the hotspot was correctly identified.

Step 3: Around this point, a volume of 30 mm x 30 mm x 30 mm was assessed by measuring 7x 7 x 7 points. On the basis of this data set, the spatial peak SAR value was evaluated under the following procedure:

1) The data at the surface were extrapolated, since the center of the dipoles is 1.2 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.3 mm. The extrapolation was based on a least square algorithm. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.

2) The maximum interpolated value was searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g or 10 g) were computed by the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one dimensional splines with the "Not a knot"-condition (in x, y and z-directions). The volume was integrated with the trapezoidal-algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the averages.

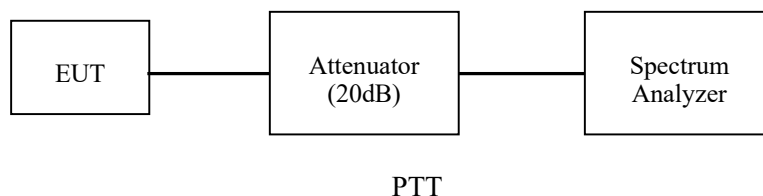
All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

Step 4: Re-measurement of the SAR value at the same location as in Step 1. If the value changed by more than 5%, the evaluation was repeated.

6. CONDUCTED OUTPUT POWER MEASUREMENT

6.1 Test Procedure

The RF output of the transmitter was connected to the input of the Spectrum Analyzer through sufficient attenuation.



The Spectrum Analyzer setting:

RBW	VBW
100 kHz	300 kHz

6.2 Maximum Target Output Power

Frequency Band	Max. ERP(with tolerance) for Production Unit (dBm)
462MHz(462.5500-462.7250MHz)	29
467MHz(467.5625-467.7125 MHz)	27

6.3 Test Results:

Mode	Frequency (MHz)	Conducted Output Power(dBm)	Antenna Gain(dBd) ▲	(ERP) (dBm)
462MHz(462.5500-462.7250MHz)	462.6375	28.31	0	28.31
467MHz(467.5625-467.7125 MHz)	467.6375	26.84	0	26.84

Note: ERP=Conducted Output Power+ Antenna Gain(dBd)

Note:

Per IEEE1528:2013, the width of the transmit frequency band, $\Delta f = f_{\text{high}} - f_{\text{low}}$ (where f_{high} is the highest frequency in the band and f_{low} is the lowest) does not exceeds 1% of its center frequency f_c . then only **center frequency** need be tested.

Antennas Location:

EUT Front View

7. SAR MEASUREMENT RESULTS

This page summarizes the results of the performed dosimetric evaluation.

7.1 SAR Test Data

Environmental Conditions

Temperature:	23.2-23.6°C
Relative Humidity:	52%
ATM Pressure:	100.4kPa
Test Date:	2026/5/28

Testing was performed by Aixlee Li.

Test Results:

Test Mode	Frequency (MHz)	Max. ERP (dBm)	Max. Rated Power (dBm)	1 g SAR Value(W/kg)				
				Power Scaled Factor	Meas. SAR	PTT 75% Factor	Scaled SAR	Plot
Face Up (25 mm)	462.6375	28.31	29	1.172	0.104	0.078	0.09	1#
	467.6375	26.84	27	1.038	0.077	0.05775	0.06	2#
Body Back With Belt Clip (0 mm)	462.6375	28.31	29	1.172	0.235	0.17625	0.21	3#
	467.6375	26.84	27	1.038	0.19	0.1425	0.15	4#

Note:

1. KDB 447498 D01 - A duty factor of 75% may be applied for PTT radios with Bluetooth or voice activated transmission capabilities to avoid the justification required for using a lower duty factor than what is supported by certain features built-in within the radio.
2. Passive body-worn and audio accessories generally do not apply to the head SAR of PTT radios.
3. The whole antenna and radiating structures that may contribute to the measured SAR or influence the SAR distribution has been included in the area scan.

8. Measurement Variability

In accordance with published RF Exposure KDB procedure 865664 D01 SAR measurement 100 MHz to 6 GHz v01. These additional measurements are repeated after the completion of all measurements requiring the same head or body tissue-equivalent medium in a frequency band. The test device should be returned to ambient conditions (normal room temperature) with the battery fully charged before it is re-mounted on the device holder for the repeated measurement(s) to minimize any unexpected variations in the repeated results

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps 2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg ($\sim 10\%$ from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20 .

Note: The same procedures should be adapted for measurements according to extremity and occupational exposure limits by applying a factor of 2.5 for extremity exposure and a factor of 5 for occupational exposure to the corresponding SAR thresholds.

The Highest Measured SAR Configuration in Each Frequency Band

Head

SAR probe calibration point	Frequency Band	Freq.(MHz)	EUT Position	Meas. SAR (W/kg)		Largest to Smallest SAR Ratio
				Original	Repeated	
/	/	/	/	/	/	/

Body

SAR probe calibration point	Frequency Band	Freq.(MHz)	EUT Position	Meas. SAR (W/kg)		Largest to Smallest SAR Ratio
				Original	Repeated	
/	/	/	/	/	/	/

Note:

1. Second Repeated Measurement is not required since the ratio of the largest to smallest SAR for the original and first repeated measurement is not > 1.20 .
2. The measured SAR results **do not** have to be scaled to the maximum tune-up tolerance to determine if repeated measurements are required.
3. SAR measurement variability must be assessed for each frequency band, which is determined by the **SAR probe calibration point and tissue-equivalent medium** used for the device measurements.

9. DUT HOLDER PERTURBATIONS

In accordance with TCB workshop October 2016:

- 1) SAR perturbation due to test device holders, depending on antenna locations, buttons locations on phones or device, form factor (e.g. dongles etc.), the measured SAR could be influenced by the relative positions of the test device and its holder
- 2) SAR measurement standards have included protocols to evaluate this with a flat phantom, with and without the device holder
- 3) When the highest reported SAR of an antenna is > 1.2 W/kg, holder perturbation verification is required for each antenna, using the highest SAR configuration among all applicable frequency bands in the same exact device and holder positions used for head and body SAR measurements; i.e. same device/button locations in the holder

Per IEEE 1528: 2013/Annex E/E.4.1.1: Device holder perturbation tolerance for a specific test device: Type B

When it is unknown if a device holder perturbs the fields of a test device, the SAR uncertainty shall be assessed with a flat phantom (see Clause 5) by comparing the SAR with and without the device holder according to the following tests:

The SAR tolerance for device holder disturbance is computed using Equation (E.21) and entered in the corresponding row of the appropriate uncertainty table with an assumed rectangular probability distribution and $\nu_i = \infty$ degrees of freedom:

$$SAR_{\text{tolerance}}[\%] = 100 \times \left(\frac{SAR_{\text{w/holder}} - SAR_{\text{w/o holder}}}{SAR_{\text{w/o holder}}} \right) \quad (\text{E.21})$$

The Highest Measured SAR Configuration among all applicable Frequency Band

Frequency Band	Freq.(MHz)	EUT Position	Meas. SAR (W/kg)		The Device holder perturbation uncertainty
			With holder	Without holder	
/	/	/	/	/	/

10. SAR SIMULTANEOUS TRANSMISSION DESCRIPTION

10.1 Simultaneous Transmission:

Note: There is no multiple transmitters for the product, so simultaneous transmission need not to evaluate.

11. SAR Plots

Plot 1#: 462.6375MHz Face Up

DUT: Two-way radio; Type: VBT-GT3; Serial: 3LW6-1

Communication System: UID 0, FM (0); Frequency: 462.637 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 462.637$ MHz; $\sigma = 0.887$ S/m; $\epsilon_r = 43.746$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: ES3DV2 - SN3019; ConvF(6.84, 6.84, 6.84) @ 462.637 MHz; Calibrated: 2026/2/18
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2025/12/1
- Phantom: ELI v8.0; Type: QDOVA002AA; Serial: TP:2051
- Measurement SW: DASY52, Version 52.10 (4); SEMCAD X Version 14.6.14 (7501)

Area Scan (7x9x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (measured) = 0.121 W/kg

Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 11.97 V/m; Power Drift = -0.13 dB

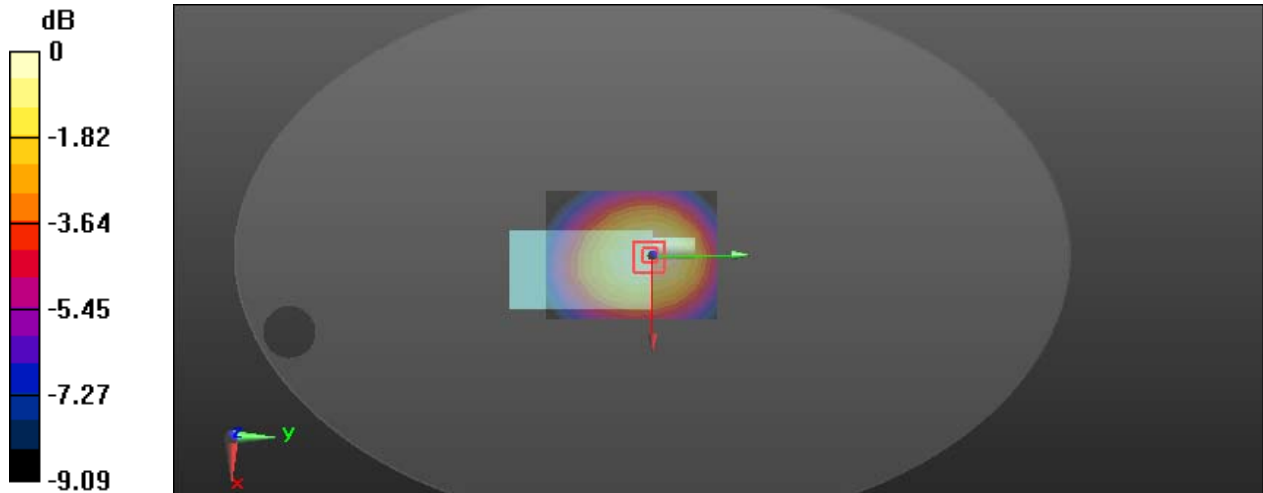
Peak SAR (extrapolated) = 0.146 W/kg

SAR(1 g) = 0.104 W/kg; SAR(10 g) = 0.075 W/kg

Smallest distance from peaks to all points 3 dB below: Larger than measurement grid (> 16 mm)

Ratio of SAR at M2 to SAR at M1 = 72.1%

Maximum value of SAR (measured) = 0.117 W/kg



0 dB = 0.117 W/kg = -9.32 dBW/kg

Plot 2#: 467.6375MHz Face Up**DUT: Two-way radio; Type: VBT-GT3; Serial: 3LW6-1**

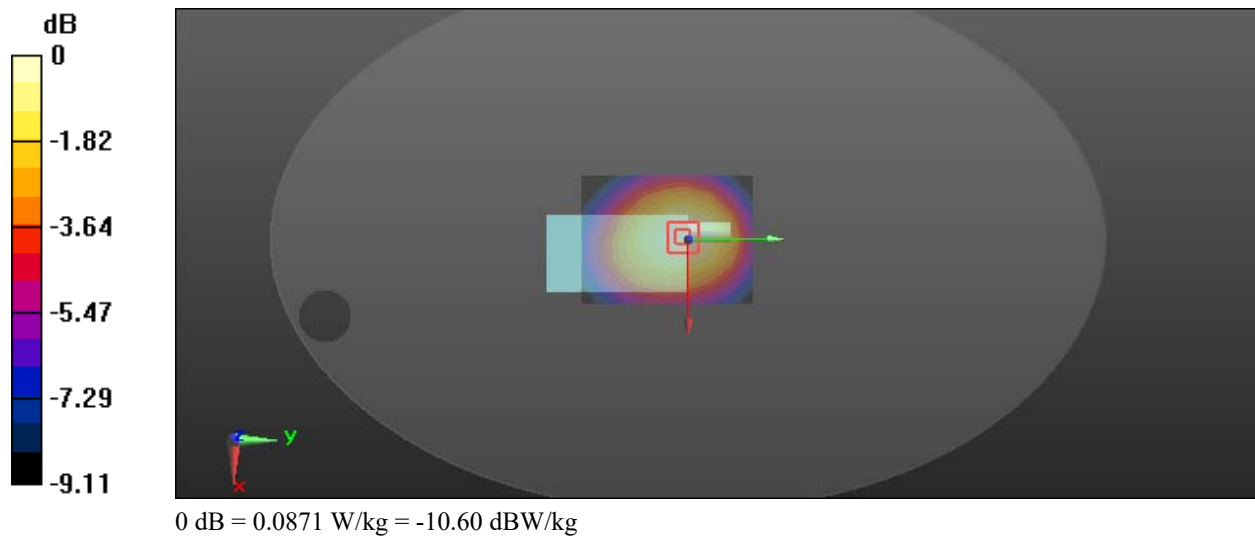
Communication System: UID 0, FM (0); Frequency: 467.637 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 467.637 \text{ MHz}$; $\sigma = 0.889 \text{ S/m}$; $\epsilon_r = 43.693$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY5 Configuration:

- Probe: ES3DV2 - SN3019; ConvF(6.84, 6.84, 6.84) @ 467.637 MHz; Calibrated: 2026/2/18
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2025/12/1
- Phantom: ELI v8.0; Type: QDOVA002AA; Serial: TP:2051
- Measurement SW: DASY52, Version 52.10 (4); SEMCAD X Version 14.6.14 (7501)

Area Scan (7x9x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$ Maximum value of SAR (measured) = 0.0879 W/kg **Zoom Scan (5x5x7)/Cube 0:** Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$ Reference Value = 10.11 V/m ; Power Drift = -0.19 dB Peak SAR (extrapolated) = 0.109 W/kg **SAR(1 g) = 0.077 W/kg ; SAR(10 g) = 0.056 W/kg** Smallest distance from peaks to all points 3 dB below: Larger than measurement grid ($> 16 \text{ mm}$)Ratio of SAR at M2 to SAR at M1 = 71.8% Maximum value of SAR (measured) = 0.0871 W/kg 

Plot 3#: 462.6375MHz Body Back**DUT: Two-way radio; Type: VBT-GT3; Serial: 3MGN-1**

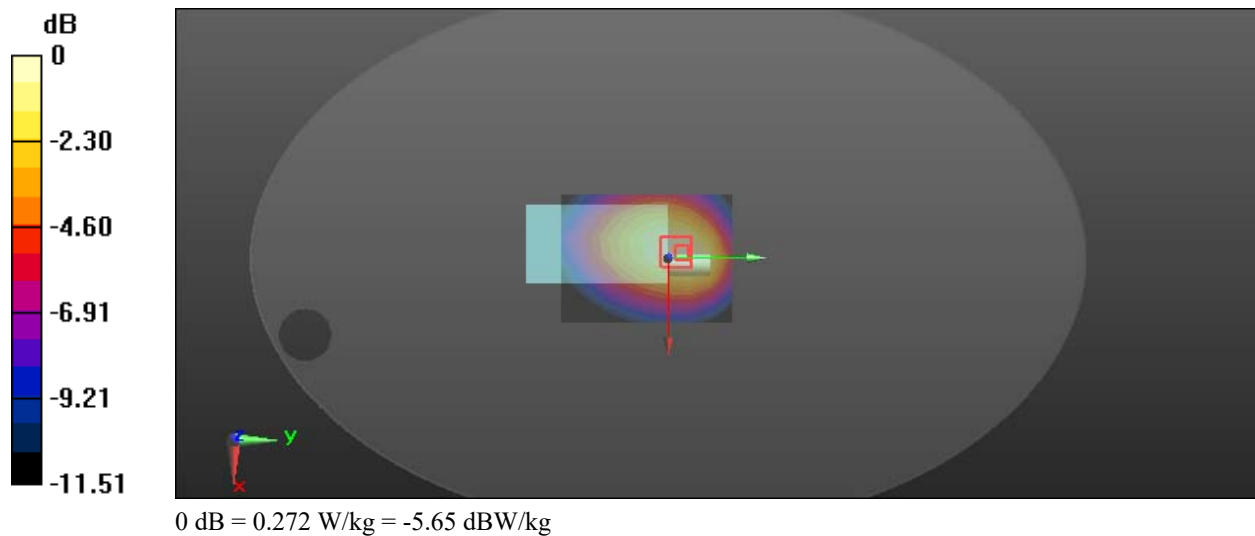
Communication System: UID 0, FM (0); Frequency: 462.637 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 462.637 \text{ MHz}$; $\sigma = 0.887 \text{ S/m}$; $\epsilon_r = 43.746$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY5 Configuration:

- Probe: ES3DV2 - SN3019; ConvF(6.84, 6.84, 6.84) @ 462.637 MHz; Calibrated: 2026/2/18
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2025/12/1
- Phantom: ELI v8.0; Type: QDOVA002AA; Serial: TP:2051
- Measurement SW: DASY52, Version 52.10 (4); SEMCAD X Version 14.6.14 (7501)

Area Scan (7x9x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$ Maximum value of SAR (measured) = 0.271 W/kg **Zoom Scan (5x5x7)/Cube 0:** Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$ Reference Value = 17.31 V/m ; Power Drift = -0.15 dB Peak SAR (extrapolated) = 0.365 W/kg **SAR(1 g) = 0.235 W/kg ; SAR(10 g) = 0.160 W/kg** Smallest distance from peaks to all points 3 dB below: Larger than measurement grid ($> 16 \text{ mm}$)Ratio of SAR at M2 to SAR at M1 = 67.4% Maximum value of SAR (measured) = 0.272 W/kg 

Plot 4#: 467.6375MHz Body Back**DUT: Two-way radio; Type: VBT-GT3; Serial: 3MGN-1**

Communication System: UID 0, FM (0); Frequency: 467.637 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 467.637 \text{ MHz}$; $\sigma = 0.889 \text{ S/m}$; $\epsilon_r = 43.693$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY5 Configuration:

- Probe: ES3DV2 - SN3019; ConvF(6.84, 6.84, 6.84) @ 467.637 MHz; Calibrated: 2026/2/18
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2025/12/1
- Phantom: ELI v8.0; Type: QDOVA002AA; Serial: TP:2051
- Measurement SW: DASY52, Version 52.10 (4); SEMCAD X Version 14.6.14 (7501)

Area Scan (7x12x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Maximum value of SAR (measured) = 0.215 W/kg

Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$

Reference Value = 14.20 V/m; Power Drift = -0.20 dB

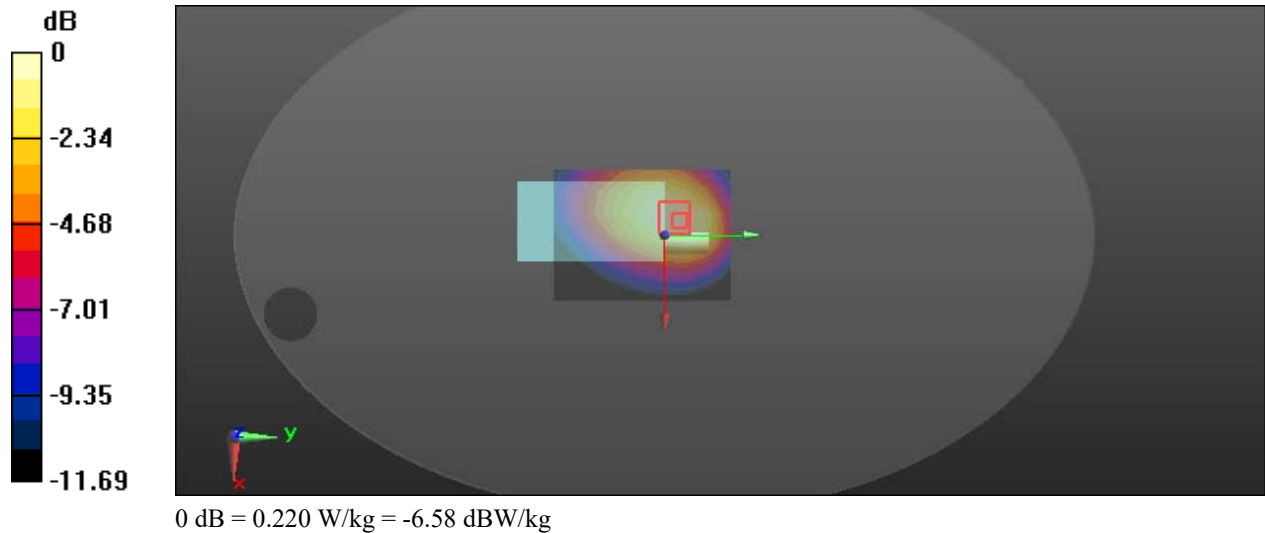
Peak SAR (extrapolated) = 0.301 W/kg

SAR(1 g) = 0.190 W/kg; SAR(10 g) = 0.129 W/kg

Smallest distance from peaks to all points 3 dB below = 20.8 mm

Ratio of SAR at M2 to SAR at M1 = 67.2%

Maximum value of SAR (measured) = 0.220 W/kg



APPENDIX A MEASUREMENT UNCERTAINTY

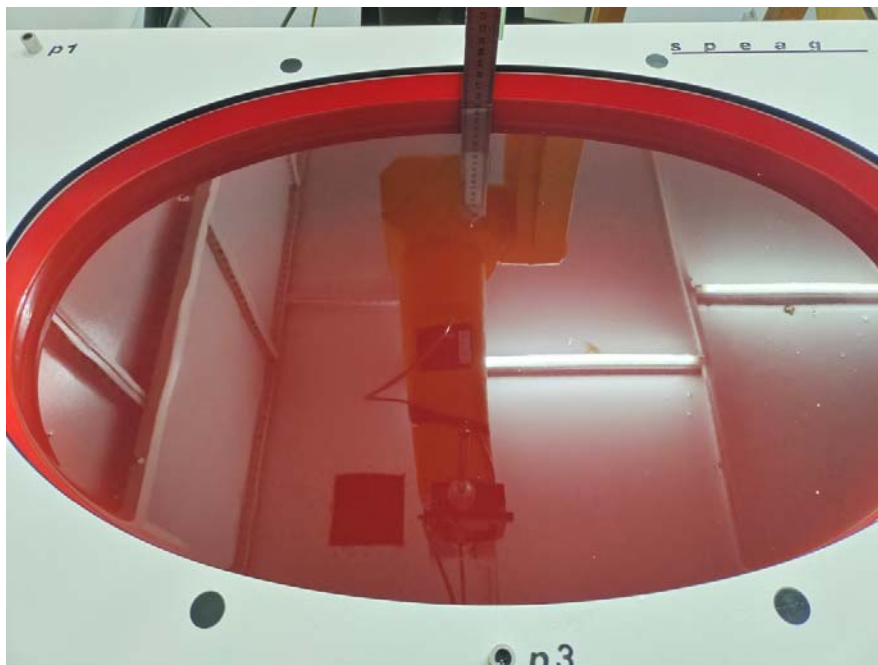
The uncertainty budget has been determined for the measurement system and is given in the following Table.

Measurement uncertainty evaluation for IEEE1528-2013 SAR test

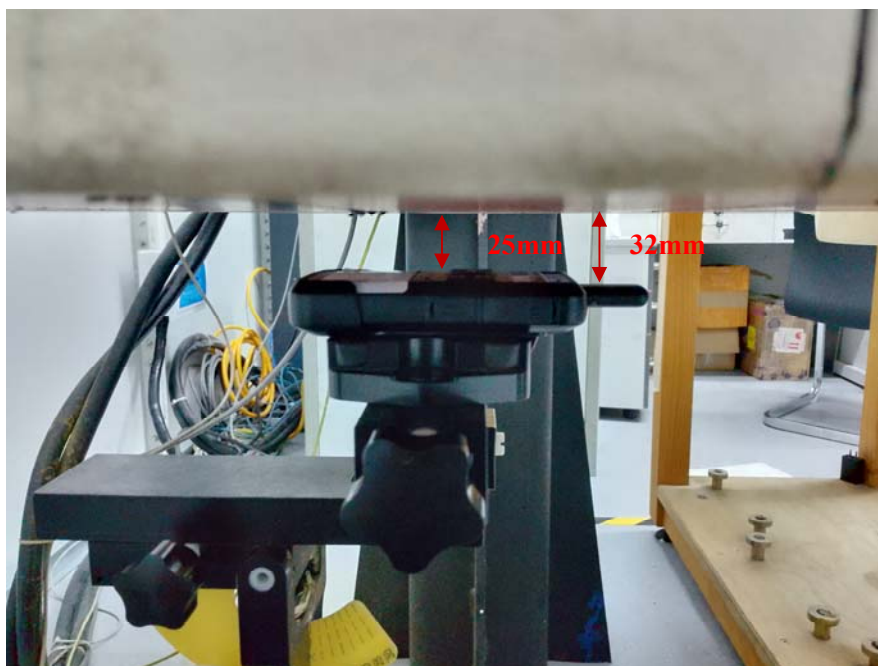
Source of uncertainty	Tolerance/ uncertainty ± %	Probability distribution	Divisor	ci (1 g)	ci (10 g)	Standard uncertainty ± %, (1 g)	Standard uncertainty ± %, (10 g)
Measurement system							
Probe calibration	6.55	N	1	1	1	6.3	6.3
Axial Isotropy	4.7	R	$\sqrt{3}$	1	1	2.7	2.7
Hemispherical Isotropy	9.6	R	$\sqrt{3}$	0	0	0.0	0.0
Boundary effect	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Linearity	4.7	R	$\sqrt{3}$	1	1	2.7	2.7
Detection limits	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Readout electronics	0.3	N	1	1	1	0.3	0.3
Response time	0.0	R	$\sqrt{3}$	1	1	0.0	0.0
Integration time	0.0	R	$\sqrt{3}$	1	1	0.0	0.0
RF ambient conditions – noise	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
RF ambient conditions– reflections	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Probe positioner mech. Restrictions	0.8	R	$\sqrt{3}$	1	1	0.5	0.5
Probe positioning with respect to phantom shell	6.7	R	$\sqrt{3}$	1	1	3.9	3.9
Post-processing	2.0	R	$\sqrt{3}$	1	1	1.2	1.2
Test sample related							
Test sample positioning	2.8	N	1	1	1	2.8	2.8
Device holder uncertainty	5.7	N	1	1	1	5.7	5.7
Drift of output power	5.0	R	$\sqrt{3}$	1	1	2.9	2.9
Phantom and set-up							
Phantom uncertainty (shape and thickness tolerances)	4.0	R	$\sqrt{3}$	1	1	2.3	2.3
Liquid conductivity target)	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2
Liquid conductivity meas.)	2.5	N	1	0.64	0.43	1.6	1.1
Liquid permittivity target)	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4
Liquid permittivity meas.)	2.5	N	1	0.6	0.49	1.5	1.2
Combined standard uncertainty		RSS				12.2	12.0
Expanded uncertainty 95 % confidence interval)						24.1	23.7

APPENDIX B EUT TEST POSITION PHOTOS

Liquid depth $\geq 15\text{cm}$



Face Up Setup Photo (25mm)



Body Back Setup Photo (0mm)



APPENDIX C CALIBRATION CERTIFICATES**Calibration Laboratory of**Schmid & Partner
Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland

**S** Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
S Servizio svizzero di taratura
S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)

The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificatesAccreditation No.: **SCS 0108**

Client

BACL

Sunnyvale, USA

Certificate No.

ES-3019_Feb26**CALIBRATION CERTIFICATE**Object **ES3DV2 - SN:3019**Calibration procedure(s) **QA CAL-01.v10, QA CAL-12.v10, QA CAL-23.v6, QA CAL-25.v8,
QA CAL-48.v2
Calibration procedure for dosimetric E-field probes**Calibration date **February 18, 2026**This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22±3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Calibration Date (Certificate No.)	Sched. Cal.
Power Sensor R&S NRP40T	SN: 101861	29-Apr-25 (No. 2025-001450)	Apr-26
N-type mismatch combination	SN: L1119	26-Mar-25 (No. 217-04292)	Mar-26
OCP DAK-12	SN: 1016	16-Sept-25 (No. OCP-DAK12-1016_Sep25)	Sep-26
OCP DAK-3.5	SN: 1249	16-Sept-25 (No. OCP-DAK3.5-1249_Sep25)	Sep-26
Reference Probe EX3DV4	SN: 7349	29-Jan-26 (No. EX3-7349_Jan26)	Jan-27
DAE4	SN: 1301	22-Jan-26 (No. DAE4-1301_Jan26)	Jan-27

Secondary Standards	ID	Check Date (in house)	Sched. Check
ACAP 2020 Setup 1	SN: L1464	01-Oct-25 (No. IHCK_ACAP2020-1_Oct25)	Oct-26
OCP DAK-12	SN: 1029	27-Feb-25 (No. OCP-DAK12-1029_Feb25)	Feb-26
OCP DAK-3.5	SN: 1336	10-Dec-25 (No. OCP-DAK3.5-1336_Dec25)	Dec-26

	Name	Function	Signature
Calibrated by	Henrique Almeida	Laboratory Technician	
Approved by	Sven Kühn	Technical Manager	

Issued: February 18, 2026

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: ES-3019_Feb26

Page 1 of 9

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Accreditation No.: SCS 0108

Glossary

TSL	tissue simulating liquid
NORM _{x,y,z}	sensitivity in free space
ConvF	sensitivity in TSL / NORM _{x,y,z}
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\theta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEC/IEEE 62209-1528, "Measurement Procedure For The Assessment Of Specific Absorption Rate Of Human Exposure To Radio Frequency Fields From Hand-Held And Body-Worn Wireless Communication Devices – Part 1528: Human Models, Instrumentation And Procedures (Frequency Range of 4 MHz to 10 GHz)", October 2020.
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}: Assessed for E-field polarization $\theta = 0$ ($f \leq 350$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not affect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)_{x,y,z} = NORM_{x,y,z} * frequency_response (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP_{x,y,z}: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal. DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; D_{x,y,z}; VR_{x,y,z}: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800$ MHz) and inside waveguide using analytical field distributions based on power measurements for $f > 800$ MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z} * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy): in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).

ES3DV2 - SN:3019

February 15, 2026

Parameters of Probe: ES3DV2 - SN:3019**Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k = 2)
Norm ($\mu\text{V}/(\text{V}/\text{m})^2$) ^A	0.99	1.62	0.97	±10.1%
DCP (mV) ^B	104.6	110.5	106.5	±4.7%

Calibration Results for Modulation Response

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Max dev.	Max Unc ^E k = 2
0	CW	X	0.00	0.00	1.00	0.00	140.3	±0.7%	±4.7%
		Y	0.00	0.00	1.00		119.8		
		Z	0.00	0.00	1.00		141.5		

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A The uncertainties of Norm X,Y,Z do not affect the E²-field uncertainty inside TSL (see Page 5).

^B Linearization parameter uncertainty for maximum specified field strength.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

ES3DV2 - SN:3019

February 18, 2026

Parameters of Probe: ES3DV2 - SN:3019**Other Probe Parameters**

Sensor Arrangement	Triangular
Connector Angle	62.0°
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	4 mm
Probe Tip to Sensor X Calibration Point	2 mm
Probe Tip to Sensor Y Calibration Point	2 mm
Probe Tip to Sensor Z Calibration Point	2 mm
Recommended Measurement Distance from Surface	3 mm

ES3DV2 - SN:3019

February 18, 2026

Parameters of Probe: ES3DV2 - SN:3019**Calibration Parameter Determined in HSL**

f (MHz) ^C	Relative Permittivity ^F	Conductivity ^F (S/m)	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unc ^H (k = 2)
150	52.3	0.76	7.45	7.00	7.58	0.00	2.00	±13.3%
450	43.5	0.87	5.84	6.84	6.84	0.16	1.30	±13.3%

^C Frequency validity above 300 MHz of ±100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ±50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ±10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Validity of ConvF assessed at 6 MHz is 4–9 MHz, and ConvF assessed at 13 MHz is 9–19 MHz. Above 5 GHz frequency validity can be extended to ±110 MHz.

^F The probes are calibrated using tissue simulating liquids (TSL) that deviate for ϵ and σ by less than ±5% from the target values (typically better than ±3%) and are valid for TSL with deviations of up to ±10% if SAR correction is applied.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ±1% for frequencies below 3 GHz and below ±2% for frequencies between 3–6 GHz at any distance larger than half the probe tip diameter from the boundary.

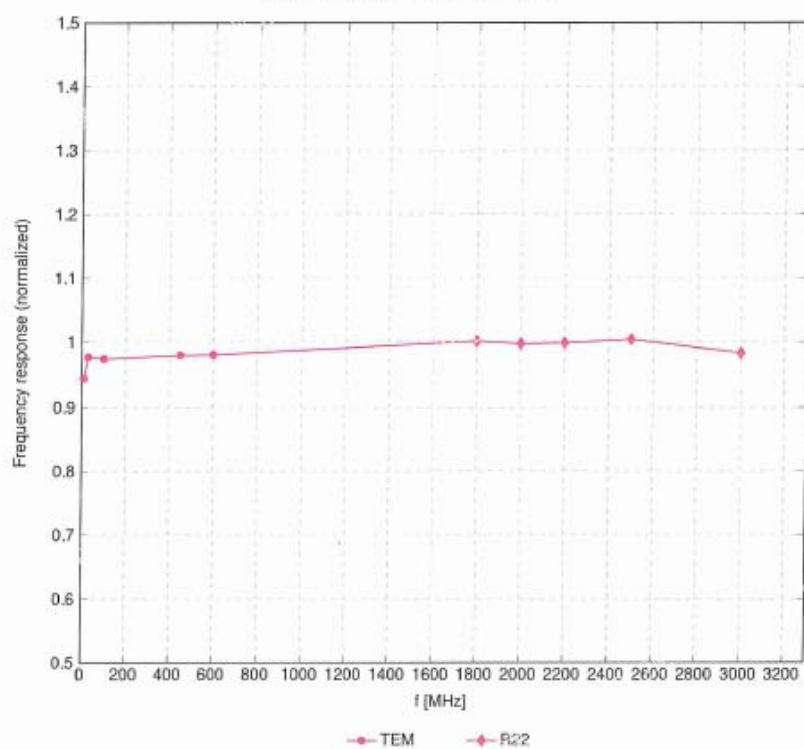
^H The stated uncertainty is the total calibration uncertainty (k = 2) of Norm-ConvF. This is equivalent to the uncertainty component with the symbol CF in Table 9 of IEC/IEEE 62209-1528:2020.

ES3DV2 - SN:3019

February 18, 2026

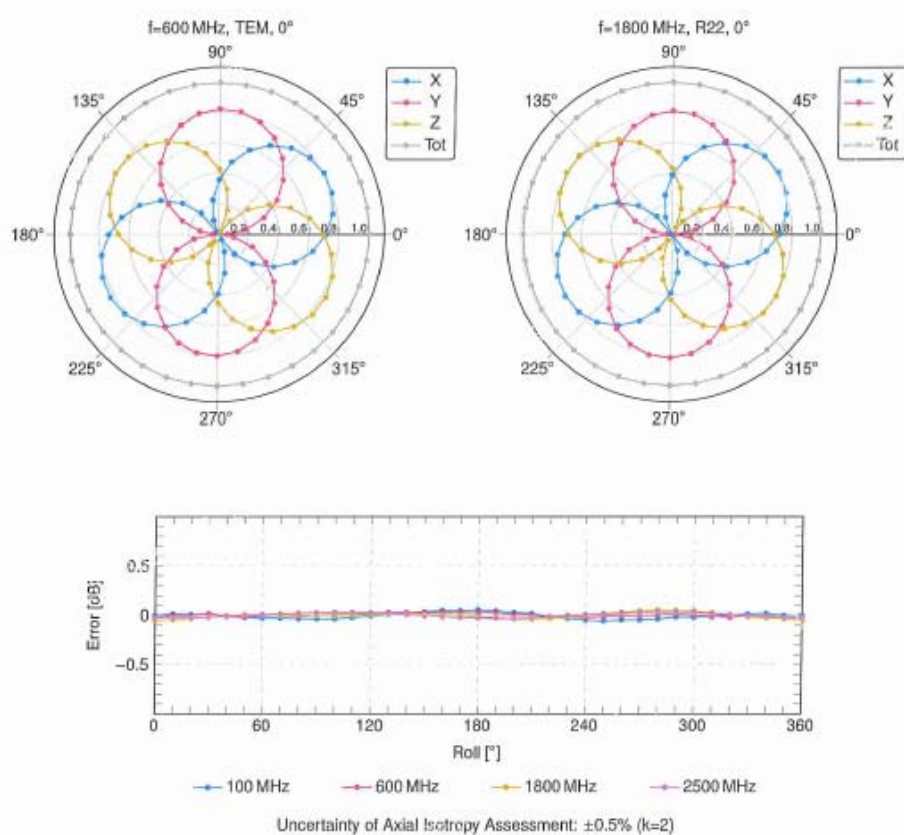
Frequency Response of E-Field

(TEM-Cell:III110 EXX, Waveguide:R22)

Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ (k=2)

ES3DV2 - SN:3019

February 18, 2026

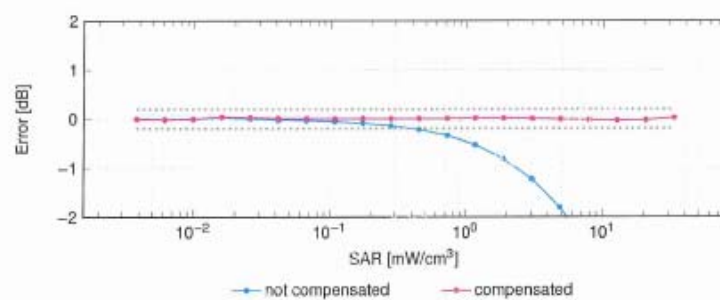
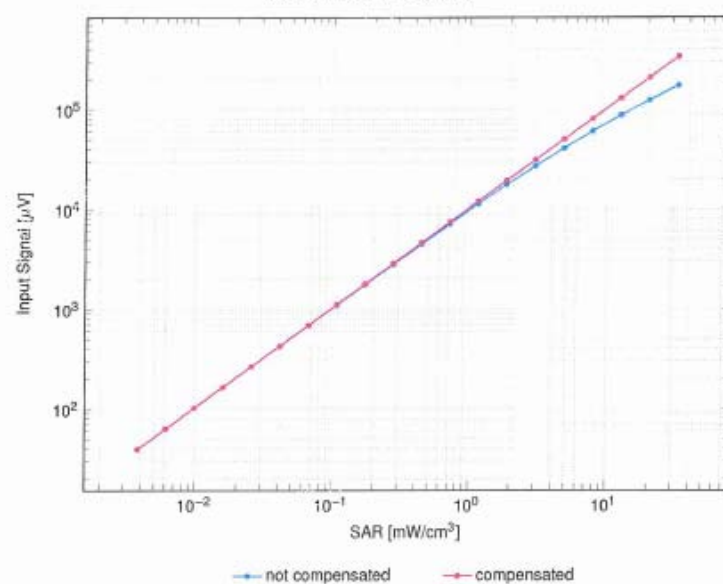
Receiving Pattern (ϕ), $\theta = 0^\circ$ 

Certificate No: ES-3019_Feb26

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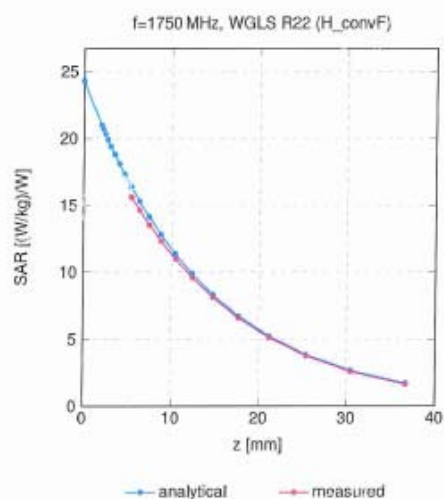
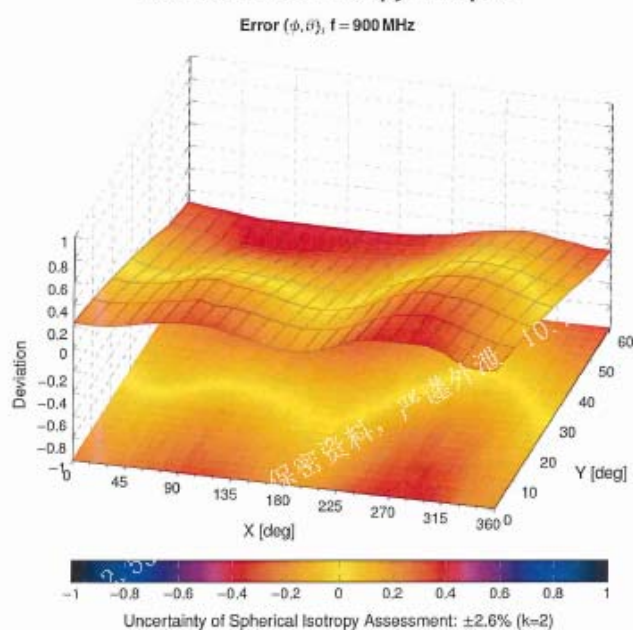
ES3DV2 - SN:3019

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Dynamic Range f(SAR_{HSL})(TEM cell, $f_{\text{eval}} = 1900 \text{ MHz}$)Uncertainty of Linearity Assessment: $\pm 0.6\%$ ($k=2$)

ES3DV2 - SN:3019

February 18, 2026

Conversion Factor Assessment**Deviation from Isotropy in Liquid**

**Calibration Laboratory of
Schmid & Partner
Engineering AG**
Zeughausstrasse 43, 8004 Zurich, Switzerland



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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Client **BACL**
Sunnyvale, USA

Certificate No. **D450V3-1096_Jul25**

CALIBRATION CERTIFICATE

Object **D450V3 - SN:1096**

Calibration procedure(s) **QA CAL-15.v11
Calibration Procedure for SAR Validation Sources below 700 MHz**

Calibration date: **July 07, 2025**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP2	SN: 104778	26-Mar-25 (No. 217-04289)	Mar-26
Power sensor NRP-Z91	SN: 103245	26-Mar-25 (No. 217-04289)	Mar-26
Reference 20 dB Attenuator	SN: CC2552 (20x)	26-Mar-25 (No. 217-04284)	Mar-26
3.5mm mismatch combination	SN: L1152	24-Mar-25 (No. 217-04293)	Mar-26
Reference Probe EX3DV4	SN: 3877	06-Jan-25 (No. EX3-3877_Jan25)	Jan-26
DAE4	SN: 654	16-Oct-24 (No. DAE4-654_Oct24)	Oct-25
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power meter NRP2	SN: 107193	08-Nov-21 (in house check Jun-24)	In house check: Jun-26
Power sensor NRP-Z91	SN: 100922	15-Dec-09 (in house check Jun-24)	In house check: Jun-26
Power sensor NRP-Z91	SN: 100418	01-Jan-04 (in house check Jun-24)	In house check: Jun-26
RF generator HP 8648C	SN: US3642U01700	04-Aug-99 (in house check Jun-24)	In house check: Jun-26
Network Analyzer Agilent E8358A	SN: US41080477	31-Mar-14 (in house check Sep-24)	In house check: Sep-26

Calibrated by: **Name** Jeffrey Katzman **Function** Laboratory Technician

Signature

Approved by: **Sven Kühn** **Technical Manager**

Issued: July 7, 2025

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Calibration Laboratory of
Schmid & Partner
Engineering AG
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Accreditation No.: **SCS 0108**

Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

Calibration is Performed According to the Following Standards:

- IEC/IEEE 62209-1528, "Measurement Procedure For The Assessment Of Specific Absorption Rate Of Human Exposure To Radio Frequency Fields From Hand-Held And Body-Worn Wireless Communication Devices - Part 1528: Human Models, Instrumentation And Procedures (Frequency Range of 4 MHz to 10 GHz)", October 2020.
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Additional Documentation:

- DASY System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL:** The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- Feed Point Impedance and Return Loss:** These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- Electrical Delay:** One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- SAR measured:** SAR measured at the stated antenna input power.
- SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.10.4
Extrapolation	Advanced Extrapolation	
Phantom	ELI4 Flat Phantom	Shell thickness: 2 ± 0.2 mm
Distance Dipole Center - TSL	15 mm	with Spacer
Zoom Scan Resolution	$dx, dy, dz = 5$ mm	
Frequency	$450 \text{ MHz} \pm 1 \text{ MHz}$	

HSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal HSL parameters	22.0°C	43.5	0.87 mho/m
Measured HSL parameters	$(22.0 \pm 0.2)^\circ\text{C}$	$42.6 \pm 6\%$	$0.88 \text{ mho/m} \pm 6\%$
HSL temperature change during test	$< 0.5^\circ\text{C}$	-----	-----

SAR result with HSL

SAR averaged over 1 cm^3 (1 g) of HSL	Condition	
SAR measured	250 mW input power	1.16 W/kg
SAR for nominal HSL parameters	normalized to 1W	$4.58 \text{ W/kg} \pm 18.1\%$ (k=2)

SAR averaged over 10 cm^3 (10 g) of HSL	condition	
SAR measured	250 mW input power	0.776 W/kg
SAR for nominal HSL parameters	normalized to 1W	$3.07 \text{ W/kg} \pm 17.6\%$ (k=2)

Appendix (Additional assessments outside the scope of SCS 0108)**Antenna Parameters with HSL**

Impedance, transformed to feed point	$58.4 \Omega + 0.4 j\Omega$
Return Loss	- 22.3 dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.354 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG
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DASY5 Validation Report for HSL

Date: 07.07.2025

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 450 MHz; Type: D450V3; Serial: D450V3 - SN:1096

Communication System: UID 0 - CW; Frequency: 450 MHz

Medium parameters used: $f = 450$ MHz; $\sigma = 0.88$ S/m; $\epsilon_r = 42.6$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: EX3DV4 - SN3877; ConvF(10.79, 10.79, 10.79) @ 450 MHz; Calibrated: 06.01.2025
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn654; Calibrated: 18.10.2024
- Phantom: ELI v6.0; Type: QDOVA003AA; Serial: TP:2034
- DASY52 52.10.4(1535); SEMCAD X 14.6.14(7501)

Dipole Calibration for Head Tissue/d=15mm, Pin=250mW/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 39.07 V/m; Power Drift = 0.01 dB

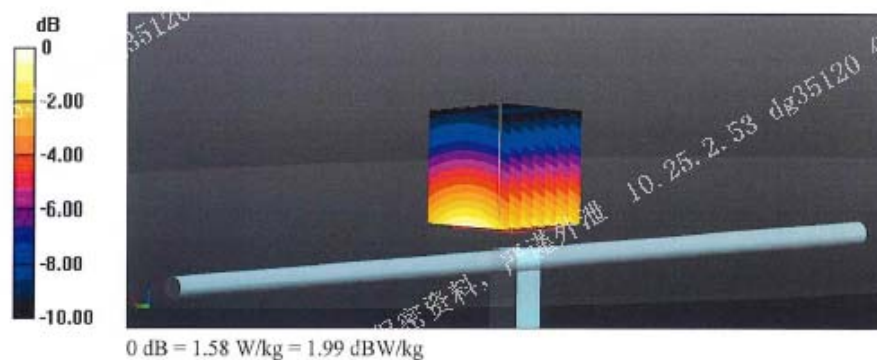
Peak SAR (extrapolated) = 1.82 W/kg

SAR(1 g) = 1.16 W/kg; SAR(10 g) = 0.776 W/kg

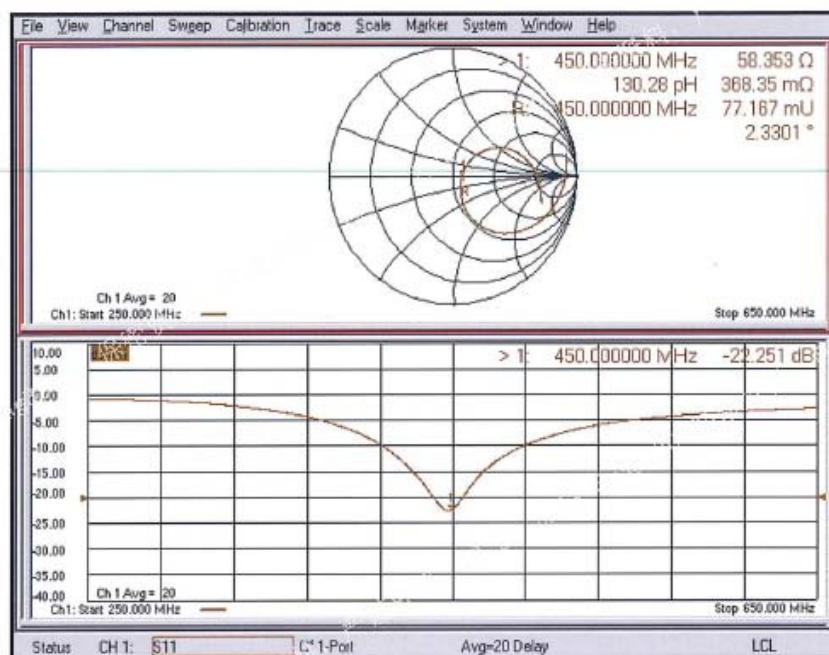
Smallest distance from peaks to all points 3 dB below: Larger than measurement grid (> 15 mm)

Ratio of SAR at M2 to SAR at M1 = 64%

Maximum value of SAR (measured) = 1.58 W/kg



Impedance Measurement Plot for HSL



***** END OF REPORT *****