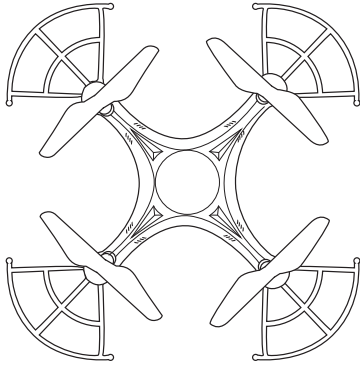


DRONES

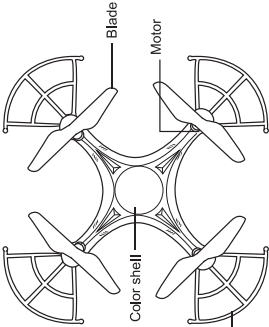
4 CH REMOTE CONTROL QUADCOPTER

Quadcopter with six-axis gyro built in

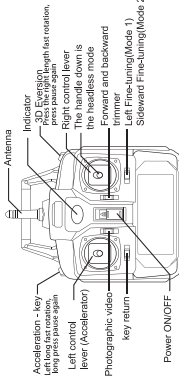


The knowledge and safety notes below are useful for you in the remote control world. Please read this manual carefully before operating this product and keep it for further reference.

Parts name



Introduction of transmitter

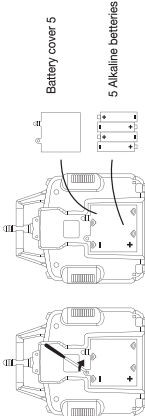


UAV's flying / inverted calibration mode when the aircraft is flying up / inverted mode landing, two joystick while playing the bottom left, bottom right corner, outer-eight click in the end in the end let go after five seconds, four aircraft bottom light starts flashing after flashing stops, the calibration was successful.

Note: 1.The visa-blade steering engine can be divided into four levels like , 50%,75% and 100% by the rudder volume fine tuning. 2.To familiarity of operatin. The remote ruder volume is 75% when turn on the power. 3.The original ruder volume has two types,one with led and one without. Even without the led, user could still distinguish the ruder volume by listening to the indication voice. 4.It's "didi" with 50%, "diddi" with 75% and "diddidi" with 100%.

Assembled remote controller

Open the battery cover on the back of remote controller,insert four #/5 alkaline batteries with the positive and negative poles correct. (Batteries should be purchased separately,old and new or different types of batteries shouldn't be mixed.)



Recharge the quadcopter battery

The factory is equipped with the charger into the power supply, connect the battery, the charging indicator light turns red.At this point it can charge, and when the light goes off when fully charged the representatives. Charging time is about 60 minutes.



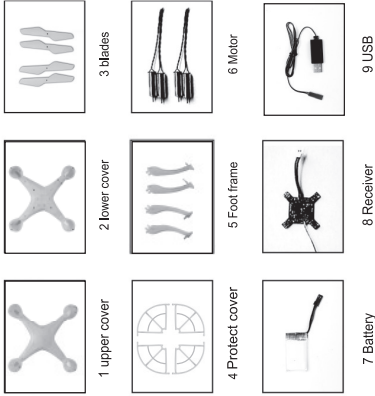
1.In case that the quadcopter might descend on a further or insecure zone due to the insufficient battery power when flying outides, the quadcopter is specially designed with the function of secure warning.When the battery power is insufficient, the quadcopter will start to sound the alarm and flashing. Then player may have time to take back the quadcopter and change the battery or recharge for the next flight.

- ### Preparation before taking off
1. Open the aircraft power switch, then open the remote control power switch.
 2. Select the open interior or no rain, snow, wind less than four outdoor environment under the flight to avoidOpen humans, animals and obstacles.
 3. The plant is equipped with a lithium polymer battery to the car, car lights flashing, the It is quiet in the flat position, wait frequency.
 4. Place the throttle lever to the lowest, open the remote control power, from the lowest to the highest throttle lever. The lowest in the back, heard the "tick" is heard, the indicator at this time become a solid aircraft. After the code is complete, it can fly.
 5. Flying time: about 7-9 minutes.

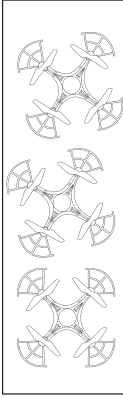
Flying controlled and fine tuning

Ascend /descend	
Turning	
Forward /backward	
Side Fly	
Turning fine tuning	
Side-fly fine tuning	
Forward backward fine tuning	

Accessories(choose to buy)



3D roll over



Press 3D mode key, the transmitter indicator turns on. fly the quadcopter to 2 meters high and press the right control stick to any direction quickly to its bottom and release it,the quadcopter will roll to the direction corresponding to the right control stick. If need to quit then press the key again

Common problem and solution instruction:

The problem	Reason	Countermeasures
The indicator light of the quadcopter is flashing and without reason when it is not operated correctly.	1.Frequency modulation between the transmitter and the receiver is not operated correctly. 2.Insufficient battery power	1.Relax to the Preparation for taking off and check the frequency. 2.Recharge the battery
The quadcopter's blades turn but the quadcopter can't take off	1.Insufficient battery power 2.the blades distorted	1.Recharge the battery 2.Replace the blades
The quadcopter shakes hardly	The blades distorted	Replace the blades
The fine tuning button are all on but the quadcopter still couldn't keep balance	1.The blades distorted 2.The motor doesn't work properly	1.Replace the blades 2.Replace the motor
The quadcopter becomes out of control after crashting	Three-axis acceleration sensor lost its balance after crashting	Put the quadcopter on the ground for 5-10 seconds

Caution:

This device complies with Part 15 of the FCC. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If you experience interference, you are encouraged to try to correct the interference by one or more of the following: —Reorient or relocate the receiving antenna. —Increase the separation between the equipment and receiver. —Connect the equipment into an outlet on a circuit different from that to which the interfering equipment is connected. —Consult the dealer or an experienced radio/TV technician for help.

MPE Reminding

To satisfy FCC RF exposure requirements, a separation distance of 20 cm or more should be maintained between the antenna of this device and persons during device operation. To ensure compliance, operations at closer than this distance is not recommended.

