

The 73006 device is BLE remote control for a pneumatic manifold unit comprising of electro-mechanical solenoid valves, pressure sensors and a PCBA with integrated compressor driver, tri-axis accelerometer and hall effect sensors. The primary intended user of this technology is commercial trucking, where it can be used to monitor primary air suspension pressure, and based on increase/decrease in pressure (due to vehicle loading) can deploy and raise lift axles, can adjust tire pressures and adjust primary air suspension.

The 73006 remote control device commands the manifold product via its integral BLE 4.2 radio at 1 MBps data rate. Details of the radio chip (Cypress CY8C4248LQ1-BL573) employed are provided in the following pages.

Please note that Cypress is an Infineon Technologies Company.

The document following this cover page is marked as “Cypress” document as this is the company that originally developed the product. Please note that Infineon will continue to offer the product to new and existing customers as part of the Infineon product portfolio.

Continuity of document content

The fact that Infineon offers the following product as part of the Infineon product portfolio does not lead to any changes to this document. Future revisions will occur when appropriate, and any changes will be set out on the document history page.

Continuity of ordering part numbers

Infineon continues to support existing part numbers. Please continue to use the ordering part numbers listed in the datasheet for ordering.

General Description

PSoC® 4 is a scalable and reconfigurable platform architecture for a family of programmable embedded system controllers with an Arm® Cortex®-M0 CPU. It combines programmable and reconfigurable analog and digital blocks with flexible automatic routing. The PSoC 4200_BLE product family, based on this platform, is a combination of a microcontroller with an integrated Bluetooth Low Energy (BLE), also known as Bluetooth Smart, radio and subsystem (BLESS). The other features include digital programmable logic, high-performance analog-to-digital conversion (ADC), opamps with Comparator mode, and standard communication and timing peripherals. The programmable analog and digital subsystems allow flexibility and in-field tuning of the design.

Features

32-bit MCU Subsystem

- 48-MHz Arm Cortex-M0 CPU with single-cycle multiply and DMA
- Up to 256 KB of flash with Read Accelerator
- Up to 32 KB of SRAM

BLE Radio and Subsystem

- BLE 4.2 support
- 2.4-GHz RF transceiver with 50-Ω antenna drive
- Digital PHY
- Link-Layer engine supporting master and slave modes
- RF output power: -18 dBm to +3 dBm
- RX sensitivity: -89 dBm
- RX current: 18.7 mA
- TX current: 15.6 mA at 0 dBm
- RSSI: 1-dB resolution

Programmable Analog

- Four opamps with reconfigurable high-drive external and high-bandwidth internal drive, Comparator modes, and ADC input buffering capability. Can operate in Deep Sleep mode.
- 12-bit, 1-Msps SAR ADC with differential and single-ended modes; Channel Sequencer with signal averaging
- Two current DACs (IDACs) for general-purpose or capacitive sensing applications on any pin
- Two low-power comparators that operate in Deep Sleep mode

Programmable Digital

- Four programmable logic blocks called universal digital blocks, (UDBs), each with eight macrocells and data path
- Cypress-provided peripheral component library, user-defined state machines, and Verilog input

Power Management

- Active mode: 1.7 mA at 3-MHz flash program execution
- Deep Sleep mode: 1.5 µA with watch crystal oscillator (WCO) on
- Hibernate mode: 150 nA with RAM retention
- Stop mode: 60 nA

Capacitive Sensing

- Cypress Capacitive Sigma-Delta (CSD) provides best-in-class SNR (>5:1) and liquid tolerance
- Cypress-supplied software component makes capacitive sensing design easy
- Automatic hardware tuning algorithm (SmartSense™)

Segment LCD Drive

- LCD drive supported on all pins (common or segment)
- Operates in Deep Sleep mode with four bits per pin memory

Serial Communication

- Two independent run-time reconfigurable serial communication blocks (SCBs) with reconfigurable I²C, SPI, or UART functionality

Timing and Pulse-Width Modulation

- Four 16-bit timer/counter pulse-width modulator (TCPWM) blocks
- Center-aligned, Edge, and Pseudo-random modes
- Comparator-based triggering of Kill signals for motor drive and other high-reliability digital logic applications

Up to 36 Programmable GPIOs

- 7 mm × 7 mm 56-pin QFN package
- 76-ball CSP package
- 68-ball CSP package
- Any GPIO pin can be CapSense, LCD, analog, or digital
- Two overvoltage-tolerant (OVT) pins; drive modes, strengths, and slew rates are programmable

PSoC Creator™ Design Environment

- Integrated Design Environment (IDE) provides schematic design entry and build (with analog and digital automatic routing)
- API components for all fixed-function and programmable peripherals

Industry-Standard Tool Compatibility

- After schematic entry, development can be done with Arm-based industry-standard development tools

More Information

Cypress provides a wealth of data at <http://www.cypress.com> to help you to select the right PSoC device for your design, and to help you to quickly and effectively integrate the device into your design. For a comprehensive list of resources, see the introduction page for [Bluetooth® Low Energy \(BLE\) Products](#). Following is an abbreviated list for PSoC BLE:

- Overview: PSoC Portfolio, PSoC Roadmap
- Product Selectors: PSoC 1, PSoC 3, PSoC 4, PSoC BLE, PSoC 4 BLE, PSoC 5LP In addition, PSoC Creator includes a device selection tool.
- Application Notes: Cypress offers a large number of PSoC application notes covering a broad range of topics, from basic to advanced level. Recommended application notes for getting started with PSoC BLE are:
 - [AN94020](#): Getting Started with PSoC BLE
 - [AN97060](#): PSoC 4 BLE and PSoC BLE - Over-The-Air (OTA) Device Firmware Upgrade (DFU) Guide
 - [AN91184](#): PSoC 4 BLE - Designing BLE Applications
 - [AN91162](#): Creating a BLE Custom Profile
 - [AN91445](#): Antenna Design and RF Layout Guidelines
 - [AN96841](#): Getting Started With EZ-BLE Module

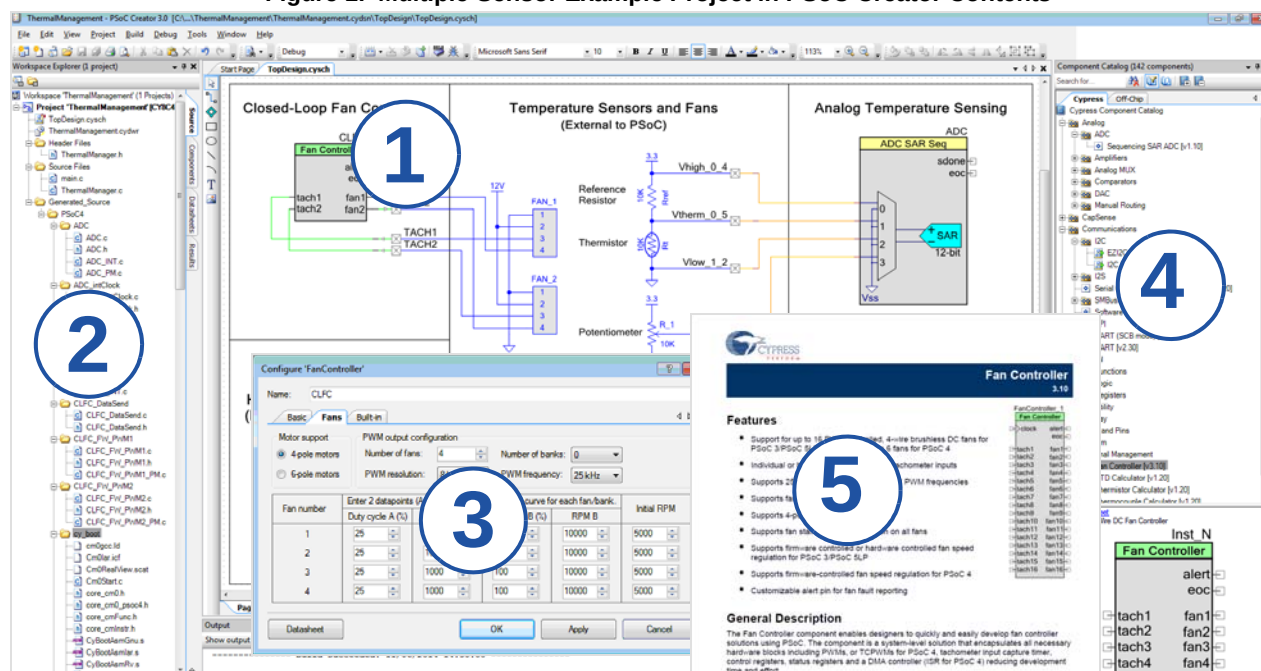
- [AN85951](#): PSoC 4 CapSense Design Guide
- [AN95089](#): PSoC 4/PRoC BLE Crystal Oscillator Selection and Tuning Techniques
- [AN92584](#): Designing for Low Power and Estimating Battery Life for BLE Applications
- Technical Reference Manual (TRM) is in two documents:
 - [Architecture TRM](#) details each PSoC BLE functional block
 - [Registers TRM](#) describes each of the PSoC BLE registers
- Development Kits:
 - [CY8CKIT-042-BLE-A](#) Pioneer Kit, is a flexible, Arduino-compatible, Bluetooth LE development kit for PSoC 4 BLE and PSoC BLE.
 - [CY8CKIT-142](#), PSoC 4 BLE Module, features a PSoC 4 BLE device, two crystals for the antenna matching network, a PCB antenna and other passives, while providing access to all GPIOs of the device.
 - [CY8CKIT-143](#), PSoC 4 BLE 256KB Module, features a PSoC 4 BLE 256KB device, two crystals for the antenna matching network, a PCB antenna and other passives, while providing access to all GPIOs of the device.
 - The [MiniProg3](#) device provides an interface for flash programming and debug.

PSoC Creator

PSoC Creator is a free Windows-based Integrated Design Environment (IDE). It enables concurrent hardware and firmware design of PSoC 3, PSoC 4, and PSoC 5LP based systems. Create designs using classic, familiar schematic capture supported by over 100 pre-verified, production-ready PSoC Components; see the [list of component datasheets](#). With PSoC Creator, you can:

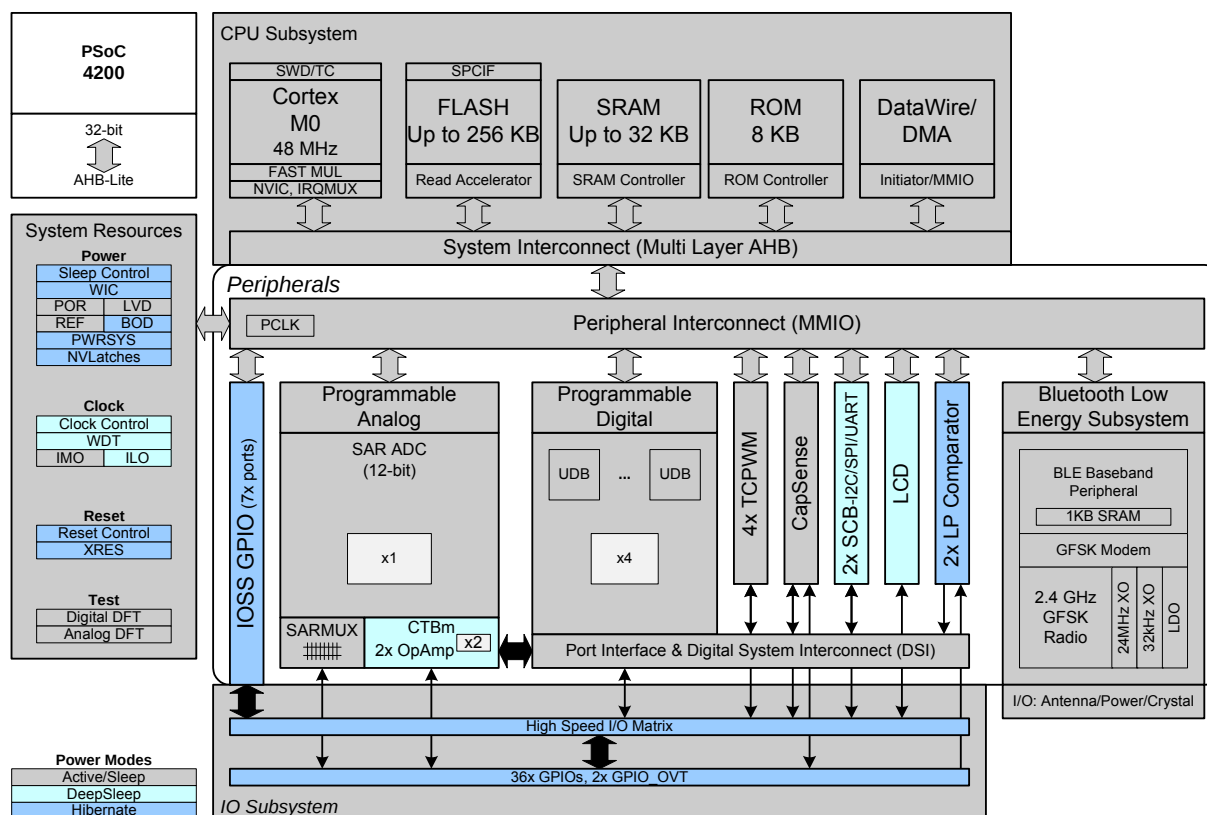
1. Drag and drop component icons to build your hardware system design in the main design workspace
2. Codesign your application firmware with the PSoC hardware, using the PSoC Creator IDE C compiler
3. Configure components using the configuration tools
4. Explore the library of 100+ components
5. Review component datasheets

Figure 1. Multiple-Sensor Example Project in PSoC Creator Contents



Contents

Functional Definition	5	Memory	29
CPU and Memory Subsystem	5	System Resources	30
System Resources	5	Ordering Information.....	37
BLE Radio and Subsystem	6	Ordering Code Definitions	38
Analog Blocks.....	7	Packaging.....	39
Programmable Digital	8	WLCSP Compatibility	41
Fixed-Function Digital.....	9	Acronyms	45
GPIO	9	Document Conventions	47
Special-Function Peripherals	10	Units of Measure	47
Pinouts	11	Revision History	48
Power	16	Sales, Solutions, and Legal Information	49
Development Support	17	Worldwide Sales and Design Support.....	49
Documentation	17	Products	49
Online	17	PSoC® Solutions	49
Tools.....	17	Cypress Developer Community.....	49
Electrical Specifications	18	Technical Support	49
Absolute Maximum Ratings	18		
Device-Level Specifications	18		
Analog Peripherals	23		
Digital Peripherals	27		

Figure 2. Block Diagram


The PSoC 4200_BLE devices include extensive support for programming, testing, debugging, and tracing both hardware and firmware.

The Arm SWD interface supports all programming and debug features of the device.

Complete debug-on-chip functionality enables full-device debugging in the final system using the standard production device. It does not require special interfaces, debugging pods, simulators, or emulators. Only the standard programming connections are required to fully support debugging.

The PSoC Creator IDE provides fully integrated programming and debugging support for the PSoC 4200_BLE devices. The SWD interface is fully compatible with industry-standard third-party tools. With the ability to disable debug features, very robust flash protection, and allowing customer-proprietary functionality to be implemented in on-chip programmable blocks, the PSoC 4200_BLE family provides a level of security not possible with multi-chip application solutions or with microcontrollers.

Debug circuits are enabled by default and can only be disabled in firmware. If not enabled, the only way to re-enable them is to erase the entire device, clear flash protection, and reprogram the device with the new firmware that enables debugging.

Additionally, all device interfaces can be permanently disabled (device security) for applications concerned about phishing attacks due to a maliciously reprogrammed device or attempts to defeat security by starting and interrupting flash programming sequences. Because all programming, debug, and test interfaces are disabled when maximum device security is enabled, PSoC 4200_BLE with device security enabled may not be returned for failure analysis. This is a trade-off the PSoC 4200_BLE allows the customer to make.

Functional Definition

CPU and Memory Subsystem

CPU

The Cortex-M0 CPU in PSoC 4200_BLE is part of the 32-bit MCU subsystem, which is optimized for low-power operation with extensive clock gating. It mostly uses 16-bit instructions and executes a subset of the Thumb-2 instruction set. This enables fully compatible binary upward migration of the code to higher-performance processors such as Cortex-M3 and M4. The Cypress implementation includes a hardware multiplier that provides a 32-bit result in one cycle. It includes a nested vectored interrupt controller (NVIC) block with 32 interrupt inputs and a wakeup interrupt controller (WIC). The WIC can wake the processor up from the Deep Sleep mode, allowing power to the main processor to be switched off when the chip is in the Deep Sleep mode. The Cortex-M0 CPU provides a nonmaskable interrupt (NMI) input, which is made available to the user when it is not in use for system functions requested by the user.

The CPU also includes an SWD interface, which is a 2-wire form of JTAG; the debug configuration used for PSoC 4200_BLE has four break-point (address) comparators and two watchpoint (data) comparators.

Flash

The PSoC 4200_BLE device has a flash module with 256 KB of flash memory, tightly coupled to the CPU to improve average access times from the flash block. The flash block is designed to deliver 2 wait-state (WS) access time at 48 MHz and with 1-WS access time at 24 MHz. The flash accelerator delivers 85% of single-cycle SRAM access performance on average. Part of the flash module can be used to emulate EEPROM operation if required. Maximum erase and program time is 20 ms per row (256 bytes). This also applies to the emulated EEPROM.

SRAM

SRAM memory is retained during Hibernate.

SRAM

The 8-KB supervisory ROM contains a library of executable functions for flash programming. These functions are accessed through supervisory calls (SVC) and enable in-system programming of the flash memory.

DMA

A DMA engine, with eight channels, is provided that can do 32-bit transfers and has chainable ping-pong descriptors.

System Resources

Power System

The power system is described in detail in the section [Power on page 16](#). It provides an assurance that the voltage levels are as required for the respective modes, and can either delay the mode entry (on power-on reset (POR), for example) until voltage levels are as required or generate resets (brownout detect (BOD)) or interrupts when the power supply reaches a particular programmable level between 1.8 and 4.5 V (low voltage detect (LVD)).

PSoC 4200_BLE operates with a single external supply (1.71 to 5.5 V without radio, and 1.9 V to 5.5 V with radio). The device has five different power modes; transitions between these modes are managed by the power system. PSoC 4200_BLE provides Sleep, Deep Sleep, Hibernate, and Stop low-power modes. Refer to the *Technical Reference Manual* for more details.

Clock System

The PSoC 4200_BLE clock system is responsible for providing clocks to all subsystems that require clocks and for switching between different clock sources without glitching. In addition, the clock system ensures that no metastable conditions occur.

The clock system for PSoC 4200_BLE consists of the internal main oscillator (IMO), the internal low-speed oscillator (ILO), the 24-MHz external crystal oscillator (ECO) and the 32-kHz watch crystal oscillator (WCO). In addition, an external clock may be supplied from a pin.

IMO Clock Source

The IMO is the primary source of internal clocking in PSoC 4200_BLE. It is trimmed during testing to achieve the specified accuracy. Trim values are stored in nonvolatile latches (NVL). Additional trim settings from flash can be used to compensate for changes. The IMO default frequency is 24 MHz and it can be adjusted between 3 to 48 MHz in steps of 1 MHz. The IMO tolerance with Cypress-provided calibration settings is $\pm 2\%$.

ILO Clock Source

The ILO is a very low-power oscillator, which is primarily used to generate clocks for the peripheral operation in the Deep Sleep mode. ILO-driven counters can be calibrated to the IMO to improve accuracy. Cypress provides a software component, which does the calibration.

External Crystal Oscillator (ECO)

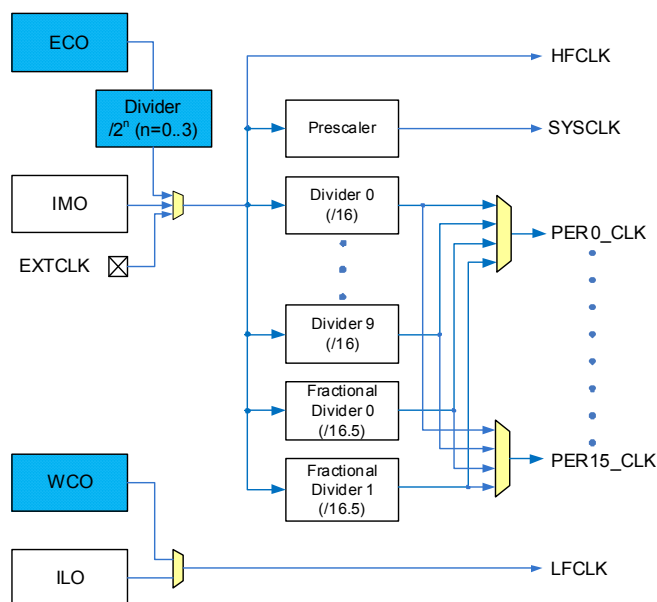
The ECO is used as the active clock for the BLE subsystem to meet the ± 50 -ppm clock accuracy of the Bluetooth 4.2 Specification. PSoC 4200_BLE includes a tunable load capacitor to tune the crystal clock frequency by measuring the actual clock frequency. The high-accuracy ECO clock can also be used as a system clock.

Watch Crystal Oscillator (WCO)

The WCO is used as the sleep clock for the BLE subsystem to meet the ± 500 -ppm clock accuracy for the Bluetooth 4.2 Specification. The sleep clock provides an accurate sleep timing and enables wakeup at the specified advertisement and connection intervals. The WCO output can be used to realize the real-time clock (RTC) function in firmware.

Watchdog Timer

A watchdog timer is implemented in the clock block running from the ILO or from the WCO; this allows the watchdog operation during Deep Sleep and generates a watchdog reset if not serviced before the timeout occurs. The watchdog reset is recorded in the Reset Cause register. With the WCO and firmware, an accurate real-time clock (within the bounds of the 32-kHz crystal accuracy) can be realized.

Figure 3. PSoC 4200_BLE MCU Clocking Architecture


The HFCLK signal can be divided down (see Figure 3) to generate synchronous clocks for the UDBs, and the analog and digital peripherals. There are a total of 12 clock dividers for PSoC 4200_BLE: ten with 16-bit divide capability and two with 16.5-bit divide capability. This allows the generation of 16 divided clock signals, which can be used by peripheral blocks. The analog clock leads the digital clocks to allow analog events to occur before the digital clock-related noise is generated. The 16-bit and 16.5-bit dividers allow a lot of flexibility in generating fine-grained frequency values and are fully supported in PSoC Creator.

Reset

PSoC 4200_BLE device can be reset from a variety of sources including a software reset. Reset events are asynchronous and guarantee reversion to a known state. The reset cause is recorded in a register, which is sticky through resets and allows the software to determine the cause of the reset. An XRES pin is reserved for an external reset to avoid complications with the configuration and multiple pin functions during power-on or reconfiguration. The XRES pin has an internal pull-up resistor that is always enabled.

Voltage Reference

The PSoC 4200_BLE reference system generates all internally required references. A one-percent voltage reference spec is provided for the 12-bit ADC. To allow better signal-to-noise ratios (SNR) and better absolute accuracy, it is possible to bypass the internal reference using a GPIO pin or use an external reference for the SAR. Refer to Table 19, "SAR ADC AC Specifications," on page 26 for details.

BLE Radio and Subsystem

PSoC 4200_BLE incorporates a Bluetooth Smart subsystem that contains the Physical Layer (PHY) and Link Layer (LL) engines with an embedded AES-128 security engine. The physical layer consists of the digital PHY and the RF transceiver that transmits and receives GFSK packets at 1 Mbps over a 2.4-GHz ISM band, which is compliant with Bluetooth Smart Bluetooth Specification 4.2. The baseband controller is a composite hardware and firmware implementation that supports both master and slave modes. Key protocol elements, such as HCI and link control, are implemented in firmware. Time-critical functional blocks, such as encryption, CRC, data whitening, and access code correlation, are implemented in hardware (in the LL engine).

The RF transceiver contains an integrated balun, which provides a single-ended RF port pin to drive a 50-Ω antenna via a matching/filtering network. In the receive direction, this block converts the RF signal from the antenna to a digital bit stream after performing GFSK demodulation. In the transmit direction, this block performs GFSK modulation and then converts a digital baseband signal to a radio frequency before transmitting it to air through the antenna.

The Bluetooth Smart Radio and Subsystem (BLESS) requires a 1.9-V minimum supply (the range varies from 1.9 V to 5.5 V).

Key features of BLESS are as follows:

- Master and slave single-mode protocol stack with logical link control and adaptation protocol (L2CAP), attribute (ATT), and security manager (SM) protocols
- API access to generic attribute profile (GATT), generic access profile (GAP), and L2CAP
- L2CAP connection-oriented channel
- GAP features
 - Broadcaster, Observer, Peripheral, and Central roles
 - Security mode 1: Level 1, 2, 3, and 4
 - Security mode 2: Level 1 and 2
 - User-defined advertising data
 - Multiple bond support
- GATT features
 - GATT client and server
 - Supports GATT sub-procedures
 - 32-bit universally unique identifier (UUID)
- Security Manager (SM)
 - Pairing methods: Just works, Passkey Entry, Out of Band and Numeric Comparison
 - Authenticated man-in-the-middle (MITM) protection and data signing
 - LE Secure Connections (Bluetooth 4.2 feature)
- Link Layer (LL)
 - Master and Slave roles
 - 128-bit AES engine
 - Encryption
 - Low-duty cycle advertising
 - LE Ping
 - LE Data Packet Length Extension (Bluetooth 4.2 feature)
 - Link Layer Privacy (with extended scanning filter policy, Bluetooth 4.2 feature)
- Supports all SIG-adopted BLE profiles

Analog Blocks

12-bit SAR ADC

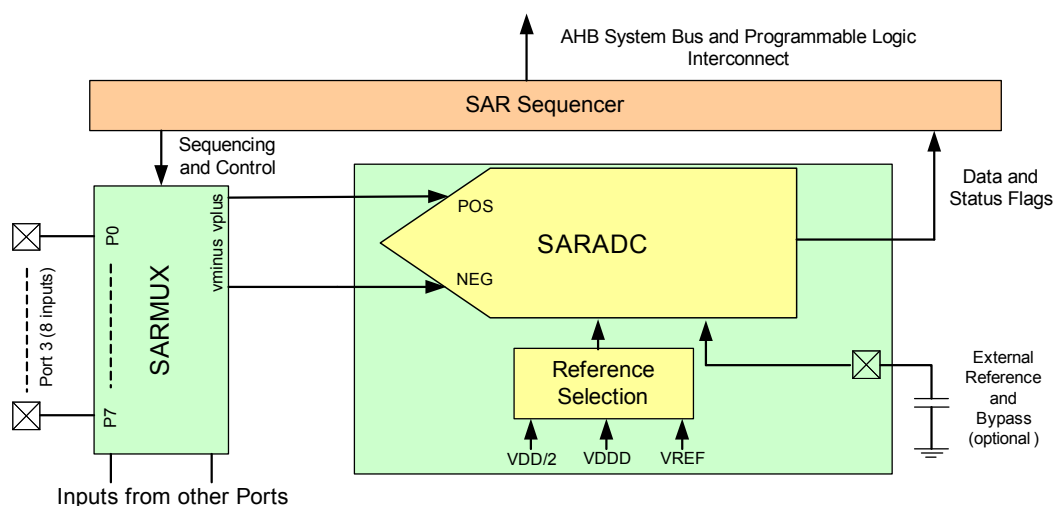
The 12-bit, 1-Msps SAR ADC can operate at a maximum clock rate of 18 MHz and requires a minimum of 18 clocks at that frequency to do a 12-bit conversion.

The block functionality is augmented for the user by adding a reference buffer to it (trimmable to $\pm 1\%$) and by providing the choice of three internal voltage references, V_{DD} , $V_{DD}/2$, and V_{REF} (nominally 1.024 V), as well as an external reference through a GPIO pin. The Sample-and-Hold (S/H) aperture is programmable; it allows the gain bandwidth requirements of the amplifier driving the SAR inputs, which determine its settling time, to be relaxed if required. System performance will be 65 dB for true 12-bit precision provided appropriate references are used and system noise levels permit it. To improve the performance in noisy conditions, it is possible to provide an external bypass (through a fixed pin location) for the internal reference amplifier.

The SAR is connected to a fixed set of pins through an 8-input sequencer. The sequencer cycles through the selected channels autonomously (sequencer scan) and does so with zero switching overhead (that is, the aggregate sampling bandwidth is equal to 1 Msps whether it is for a single channel or distributed over several channels). The sequencer switching is effected through a state machine or through firmware-driven switching. A feature provided by the sequencer is the buffering of each channel to reduce CPU interrupt-service requirements. To accommodate signals with varying source impedances and frequencies, it is possible to have different sample times programmable for each channel. Also, the signal range specification through a pair of range registers (low and high range values) is implemented with a corresponding out-of-range interrupt if the digitized value exceeds the programmed range; this allows fast detection of out-of-range values without having to wait for a sequencer scan to be completed and the CPU to read the values and check for out-of-range values in software.

The SAR is able to digitize the output of the on-chip temperature sensor for calibration and other temperature-dependent functions. The SAR is not available in Deep Sleep and Hibernate modes as it requires a high-speed clock (up to 18 MHz). The SAR operating range is 1.71 to 5.5 V.

Figure 4. SAR ADC System Diagram



Opamps (CTBm Block)

PSoC 42X8_BLE has four opamps with Comparator modes, which allow most common analog functions to be performed on-chip, eliminating external components. PGAs, voltage buffers, filters, transimpedance amplifiers, and other functions can be realized with external passives saving power, cost, and space. The on-chip opamps are designed with enough bandwidth to drive the sample-and-hold circuit of the ADC without requiring external buffering.

Temperature Sensor

PSoC 4200_BL has an on-chip temperature sensor. This consists of a diode, which is biased by a current source that can be disabled to save power. The temperature sensor is connected

to the ADC, which digitizes the reading and produces a temperature value by using a Cypress-supplied software that includes calibration and linearization.

Low-Power Comparators

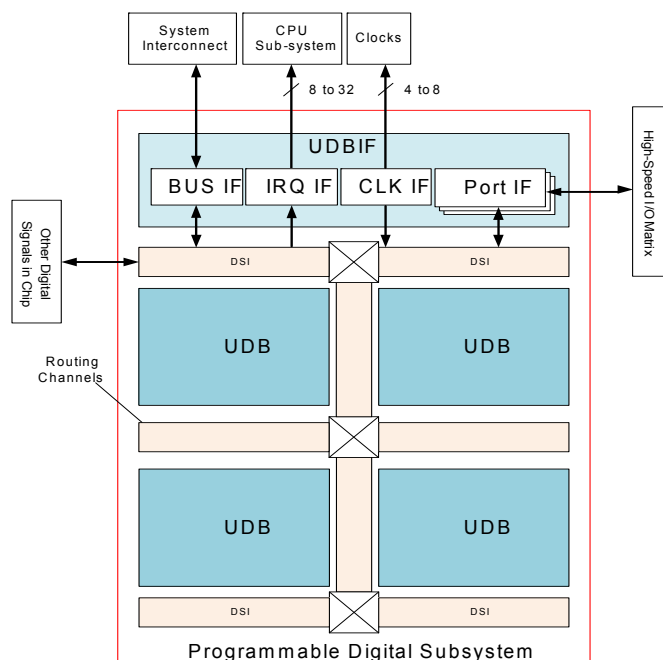
PSoC 4200_BL has a pair of low-power comparators, which can also operate in Deep Sleep and Hibernate modes. This allows the analog system blocks to be disabled while retaining the ability to monitor external voltage levels during low-power modes. The comparator outputs are normally synchronized to avoid metastability unless operating in an asynchronous power mode (Hibernate) where the system wake-up circuit is activated by a comparator-switch event.

Programmable Digital

Universal Digital Blocks (UDBs) and Port Interfaces

The PSoC 4XX8 BLE 4.2 has four UDBs; the UDB array also provides a switched Digital System Interconnect (DSI) fabric that allows signals from peripherals and ports to be routed to and through the UDBs for communication and control.

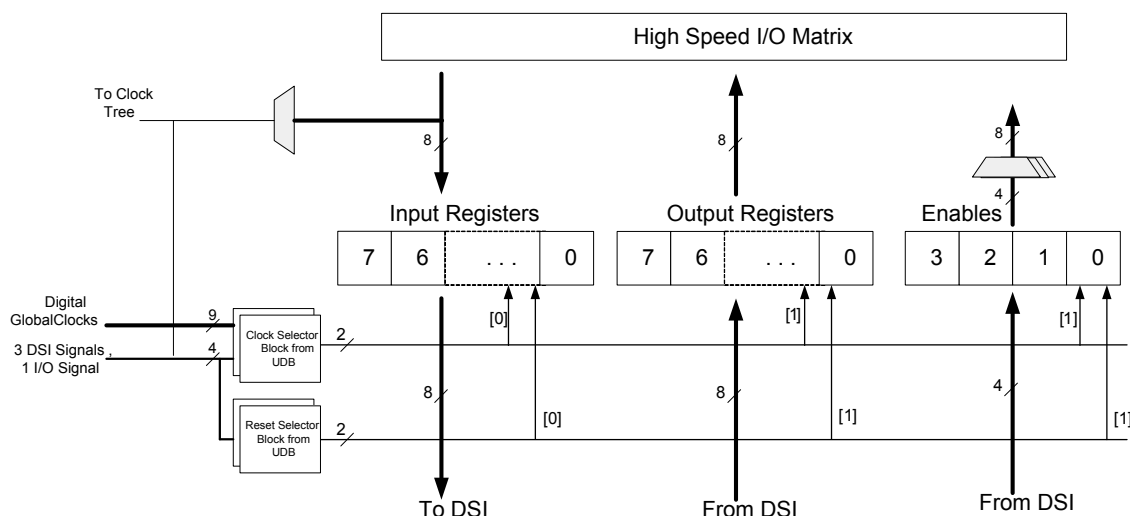
Figure 5. UDB Array



UDBs can be clocked from a clock-divider block, from a port interface (required for peripherals such as SPI), and from the DSI network directly or after synchronization.

A port interface is defined, which acts as a register that can be clocked with the same source as the PLDs inside the UDB array. This allows a faster operation because the inputs and outputs can be registered at the port interface close to the I/O pins and at the edge of the array. The port interface registers can be clocked by one of the I/Os from the same port. This allows interfaces such as SPI to operate at higher clock speeds by eliminating the delay for the port input to be routed over DSI and used to register other inputs (see Figure 6).

Figure 6. Port Interface



UDBs can generate interrupts (one UDB at a time) to the interrupt controller. UDBs retain the ability to connect to any pin on the chip through the DSI.

Fixed-Function Digital

Timer/Counter/PWM Block

The timer/counter/PWM block consists of four 16-bit counters with user-programmable period length. There is a Capture register to record the count value at the time of an event (which may be an I/O event), a period register which is used to either stop or auto-reload the counter when its count is equal to the period register, and compare registers to generate compare value signals which are used as PWM duty cycle outputs. The block also provides true and complementary outputs with programmable offset between them to allow the use as deadband programmable complementary PWM outputs. It also has a Kill input to force outputs to a predetermined state; for example, this is used in motor-drive systems when an overcurrent state is indicated and the PWMs driving the FETs need to be shut off immediately with no time for software intervention.

Serial Communication Blocks (SCB)

PSoC 4200_BLE has two SCBs, each of which can implement an I²C, UART, or SPI interface.

I²C Mode: The hardware I²C block implements a full multi-master and slave interface (it is capable of multimaster arbitration). This block is capable of operating at speeds of up to 1 Mbps (Fast Mode Plus) and has flexible buffering options to reduce the interrupt overhead and latency for the CPU. It also supports EzI²C that creates a mailbox address range in the memory of PSoC 4200_BLE and effectively reduces the I²C communication to reading from and writing to an array in the memory. In addition, the block supports an 8-deep FIFO for receive and transmit, which, by increasing the time given for the CPU to read the data, greatly reduces the need for clock stretching caused by the CPU not having read the data on time. The FIFO mode is available in all channels and is very useful in the absence of DMA.

The I²C peripheral is compatible with I²C Standard-mode, Fast-mode, and Fast-Mode Plus devices as defined in the NXP I²C-bus specification and user manual (UM10204). The I²C bus I/O is implemented with GPIO in open-drain modes.

SCB1 is fully compliant with Standard mode (100 kHz), Fast mode (400 kHz), and Fast-Mode Plus (1 MHz) I²C signaling specifications when routed to GPIO pins P5[0] and P5[1], except for hot-swap capability during I²C active communication. The remaining GPIOs do not meet the hot-swap specification (V_{DD} off; draw < 10- μ A current) for Fast mode and Fast-Mode Plus, I_{OL} Spec (20 mA) for Fast-Mode Plus, hysteresis spec (0.05 V_{DD}) for Fast mode and Fast-Mode Plus, and minimum fall time spec for Fast mode and Fast-Mode Plus.

- GPIO cells, including P5.0 and P5.1, cannot be hot-swapped or powered up independent of the rest of the I²C system.
- The GPIO pins P5.0 and P5.1 are over-voltage tolerant but cannot be hot-swapped or powered up independent of the rest of the I²C system
- Fast-Mode Plus has an I_{OL} specification of 20 mA at a V_{OL} of 0.4 V. The GPIO cells can sink a maximum of 8 mA I_{OL} with a V_{OL} maximum of 0.6 V.

- Fast-mode and Fast-Mode Plus specify minimum Fall times, which are not met with the GPIO cell; the Slow-Strong mode can help meet this spec depending on the bus load.

UART Mode: This is a full-feature UART operating at up to 1 Mbps. It supports automotive single-wire interface (LIN), infrared interface (IrDA), and SmartCard (ISO7816) protocols, all of which are minor variants of the basic UART protocol. In addition, it supports the 9-bit multiprocessor mode that allows the addressing of peripherals connected over common RX and TX lines. Common UART functions such as parity error, break detect, and frame error are supported. An 8-deep FIFO allows much greater CPU service latencies to be tolerated. Note that hardware handshaking is not supported. This is not commonly used and can be implemented with a UDB-based UART in the system, if required.

SPI Mode: The SPI mode supports full Motorola SPI, TI Secure Simple Pairing (SSP) (essentially adds a start pulse that is used to synchronize SPI Coders), and National Microwire (half-duplex form of SPI). The SPI block can use the FIFO for transmit and receive.

GPIO

PSoC 4200_BLE has 36 GPIOs. The GPIO block implements the following:

- Eight drive strength modes:
 - Analog input mode (input and output buffers disabled)
 - Input only
 - Weak pull-up with strong pull-down
 - Strong pull-up with weak pull-down
 - Open drain with strong pull-down
 - Open drain with strong pull-up
 - Strong pull-up with strong pull-down
 - Weak pull-up with weak pull-down
- Input threshold select (CMOS or LVTTTL)
- Pins 0 and 1 of Port 5 are overvoltage-tolerant pins
- Individual control of input and output buffer enabling/disabling in addition to drive-strength modes
- Hold mode for latching previous state (used for retaining the I/O state in Deep Sleep and Hibernate modes)
- Selectable slew rates for dV/dt-related noise control to improve EMI

The pins are organized in logical entities called ports, which are 8-bit in width. During power-on and reset, the blocks are forced to the disable state so as not to crowbar any inputs and/or cause excess turn-on current. A multiplexing network known as a high-speed I/O matrix (HSIOM) is used to multiplex between various signals that may connect to an I/O pin. Pin locations for fixed-function peripherals are also fixed to reduce internal multiplexing complexity (these signals do not go through the DSI network). DSI signals are not affected by this and any pin may be routed to any UDB through the DSI network.

Data output and pin-state registers store, respectively, the values to be driven on the pins and the states of the pins themselves.

Every I/O pin can generate an interrupt if so enabled and each I/O port has an interrupt request (IRQ) and interrupt service routine (ISR) vector associated with it (5 for PSoC 4200_BLE).

Special-Function Peripherals

LCD Segment Drive

PSoC 4200_BL has an LCD controller, which can drive up to four commons and up to 32 segments. It uses full digital methods to drive the LCD segments requiring no generation of internal LCD voltages. The two methods used are referred to as digital correlation and PWM.

The digital correlation method modulates the frequency and levels of the common and segment signals to generate the highest RMS voltage across a segment to light it up or to keep the RMS signal zero. This method is good for STN displays but may result in reduced contrast with TN (cheaper) displays.

The PWM method drives the panel with PWM signals to effectively use the capacitance of the panel to provide the integration of the modulated pulse-width to generate the desired LCD voltage. This method results in higher power consumption but can result in better results when driving TN displays. LCD operation is supported during Deep Sleep mode, refreshing a small display buffer (four bits; one 32-bit register per port).

CapSense

CapSense is supported on all pins in PSoC 4200_BL through a CapSense Sigma-Delta (CSD) block that can be connected to any pin through an analog mux bus that any GPIO pin can be connected to via an Analog switch. CapSense function can thus be provided on any pin or group of pins in a system under software control. A Component is provided for the CapSense block to make it easy for the user.

The shield voltage can be driven on another mux bus to provide liquid-tolerance capability. Liquid tolerance is provided by driving the shield electrode in phase with the sense electrode to keep the shield capacitance from attenuating the sensed input.

The CapSense block has two IDACs which can be used for general purposes if CapSense is not being used (both IDACs are available in that case) or if CapSense is used without liquid tolerance (one IDAC is available).

Pinouts

Table 1 shows the pin list for the PSoC 4200_BLE device. Port 3 consists of the high-speed analog inputs for the SAR mux. All pins support CSD CapSense and analog mux bus connections.

Table 1. PSoC 4200_BLE Pin List (QFN Package)

Pin	Name	Type	Description
1	VDDD	POWER	1.71-V to 5.5-V digital supply
2	XTAL32O/P6.0	CLOCK	32.768-kHz crystal
3	XTAL32I/P6.1	CLOCK	32.768-kHz crystal or external clock input
4	XRES	RESET	Reset, active LOW
5	P4.0	GPIO	Port 4 Pin 0, lcd, csd
6	P4.1	GPIO	Port 4 Pin 1, lcd, csd
7	P5.0	GPIO	Port 5 Pin 0, lcd, csd
8	P5.1	GPIO	Port 5 Pin 1, lcd, csd
9	VSSD	GROUND	Digital ground
10	VDDR	POWER	1.9-V to 5.5-V radio supply
11	GANT1	GROUND	Antenna shielding ground
12	ANT	ANTENNA	Antenna pin
13	GANT2	GROUND	Antenna shielding ground
14	VDDR	POWER	1.9-V to 5.5-V radio supply
15	VDDR	POWER	1.9-V to 5.5-V radio supply
16	XTAL24I	CLOCK	24-MHz crystal or external clock input
17	XTAL24O	CLOCK	24-MHz crystal
18	VDDR	POWER	1.9-V to 5.5-V radio supply
19	P0.0	GPIO	Port 0 Pin 0, lcd, csd
20	P0.1	GPIO	Port 0 Pin 1, lcd, csd
21	P0.2	GPIO	Port 0 Pin 2, lcd, csd
22	P0.3	GPIO	Port 0 Pin 3, lcd, csd
23	VDDD	POWER	1.71-V to 5.5-V digital supply
24	P0.4	GPIO	Port 0 Pin 4, lcd, csd
25	P0.5	GPIO	Port 0 Pin 5, lcd, csd
26	P0.6	GPIO	Port 0 Pin 6, lcd, csd
27	P0.7	GPIO	Port 0 Pin 7, lcd, csd
28	P1.0	GPIO	Port 1 Pin 0, lcd, csd
29	P1.1	GPIO	Port 1 Pin 1, lcd, csd
30	P1.2	GPIO	Port 1 Pin 2, lcd, csd
31	P1.3	GPIO	Port 1 Pin 3, lcd, csd
32	P1.4	GPIO	Port 1 Pin 4, lcd, csd
33	P1.5	GPIO	Port 1 Pin 5, lcd, csd
34	P1.6	GPIO	Port 1 Pin 6, lcd, csd
35	P1.7	GPIO	Port 1 Pin 7, lcd, csd
36	VDDA	POWER	1.71-V to 5.5-V analog supply
37	P2.0	GPIO	Port 2 Pin 0, lcd, csd
38	P2.1	GPIO	Port 2 Pin 1, lcd, csd
39	P2.2	GPIO	Port 2 Pin 2, lcd, csd

Table 1. PSoC 4200_BLE Pin List (QFN Package) (continued)

Pin	Name	Type	Description
40	P2.3	GPIO	Port 2 Pin 3, lcd, csd
41	P2.4	GPIO	Port 2 Pin 4, lcd, csd
42	P2.5	GPIO	Port 2 Pin 5, lcd, csd
43	P2.6	GPIO	Port 2 Pin 6, lcd, csd
44	P2.7	GPIO	Port 2 Pin 7, lcd, csd
45	VREF	REF	1.024-V reference
46	VDDA	POWER	1.71-V to 5.5-V analog supply
47	P3.0	GPIO	Port 3 Pin 0, lcd, csd
48	P3.1	GPIO	Port 3 Pin 1, lcd, csd
49	P3.2	GPIO	Port 3 Pin 2, lcd, csd
50	P3.3	GPIO	Port 3 Pin 3, lcd, csd
51	P3.4	GPIO	Port 3 Pin 4, lcd, csd
52	P3.5	GPIO	Port 3 Pin 5, lcd, csd
53	P3.6	GPIO	Port 3 Pin 6, lcd, csd
54	P3.7	GPIO	Port 3 Pin 7, lcd, csd
55	VSSA	GROUND	Analog ground
56	VCCD	POWER	Regulated 1.8-V supply, connect to 1.3-μF capacitor.
57	EPAD	GROUND	Ground paddle for the QFN package

Table 2. PSoC 4200_BLE Pin List (WLCSP Package)

Pin	Name	Type	Description
A1	NC	NC	Do not connect
A2	VREF	REF	1.024-V reference
A3	VSSA	GROUND	Analog ground
A4	P3.3	GPIO	Port 3 Pin 3, analog/digital/lcd/csd
A5	P3.7	GPIO	Port 3 Pin 7, analog/digital/lcd/csd
A6	VSSD	GROUND	Digital ground
A7	VSSA	GROUND	Analog ground
A8	VCCD	POWER	Regulated 1.8-V supply, connect to 1-μF capacitor
A9	VDDD	POWER	1.71-V to 5.5-V digital supply
B1	NB	NO BALL	No Ball
B2	P2.3	GPIO	Port 2 Pin 3, analog/digital/lcd/csd
B3	VSSA	GROUND	Analog ground
B4	P2.7	GPIO	Port 2 Pin 7, analog/digital/lcd/csd
B5	P3.4	GPIO	Port 3 Pin 4, analog/digital/lcd/csd
B6	P3.5	GPIO	Port 3 Pin 5, analog/digital/lcd/csd
B7	P3.6	GPIO	Port 3 Pin 6, analog/digital/lcd/csd
B8	XTAL32I/P6.1	CLOCK	32.768-kHz crystal or external clock input
B9	XTAL32O/P6.0	CLOCK	32.768-kHz crystal
C1	NC	NC	Do not connect

Table 2. PSoC 4200_BLE Pin List (WLCSP Package) (continued)

Pin	Name	Type	Description
C2	VSSA	GROUND	Analog ground
C3	P2.2	GPIO	Port 2 Pin 2, analog/digital/lcd/csd
C4	P2.6	GPIO	Port 2 Pin 6, analog/digital/lcd/csd
C5	P3.0	GPIO	Port 3 Pin 0, analog/digital/lcd/csd
C6	P3.1	GPIO	Port 3 Pin 1, analog/digital/lcd/csd
C7	P3.2	GPIO	Port 3 Pin 2, analog/digital/lcd/csd
C8	XRES	RESET	Reset, active LOW
C9	P4.0	GPIO	Port 4 Pin 0, analog/digital/lcd/csd
D1	NC	NC	Do not connect
D2	P1.7	GPIO	Port 1 Pin 7, analog/digital/lcd/csd
D3	VDDA	POWER	1.71-V to 5.5-V analog supply
D4	P2.0	GPIO	Port 2 Pin 0, analog/digital/lcd/csd
D5	P2.1	GPIO	Port 2 Pin 1, analog/digital/lcd/csd
D6	P2.5	GPIO	Port 2 Pin 5, analog/digital/lcd/csd
D7	VSSD	GROUND	Digital ground
D8	P4.1	GPIO	Port 4 Pin 1, analog/digital/lcd/csd
D9	P5.0	GPIO	Port 5 Pin 0, analog/digital/lcd/csd
E1	NC	NC	Do not connect
E2	P1.2	GPIO	Port 1 Pin 2, analog/digital/lcd/csd
E3	P1.3	GPIO	Port 1 Pin 3, analog/digital/lcd/csd
E4	P1.4	GPIO	Port 1 Pin 4, analog/digital/lcd/csd
E5	P1.5	GPIO	Port 1 Pin 5, analog/digital/lcd/csd
E6	P1.6	GPIO	Port 1 Pin 6, analog/digital/lcd/csd
E7	P2.4	GPIO	Port 2 Pin 4, analog/digital/lcd/csd
E8	P5.1	GPIO	Port 5 Pin 1, analog/digital/lcd/csd
E9	VSSD	GROUND	Digital ground
F1	NC	NC	Do not connect
F2	VSSD	GROUND	Digital ground
F3	P0.7	GPIO	Port 0 Pin 7, analog/digital/lcd/csd
F4	P0.3	GPIO	Port 0 Pin 3, analog/digital/lcd/csd
F5	P1.0	GPIO	Port 1 Pin 0, analog/digital/lcd/csd
F6	P1.1	GPIO	Port 1 Pin 1, analog/digital/lcd/csd
F7	VSSR	GROUND	Radio ground
F8	VSSR	GROUND	Radio ground
F9	VDDR	POWER	1.9-V to 5.5-V radio supply
G1	NC	NC	Do not connect
G2	P0.6	GPIO	Port 0 Pin 6, analog/digital/lcd/csd
G3	VDDD	POWER	1.71-V to 5.5-V digital supply
G4	P0.2	GPIO	Port 0 Pin 2, analog/digital/lcd/csd
G5	VSSD	GROUND	Digital ground

Table 2. PSoC 4200_BLE Pin List (WLCSP Package) (continued)

Pin	Name	Type	Description
G6	VSSR	GROUND	Radio ground
G7	VSSR	GROUND	Radio ground
G8	GANT	GROUND	Antenna shielding ground
G9	VSSR	GROUND	Radio ground
H1	NC	NC	Do not connect
H2	P0.5	GPIO	Port 0 Pin 5, analog/digital/lcd/csd
H3	P0.1	GPIO	Port 0 Pin 1, analog/digital/lcd/csd
H4	XTAL24O	CLOCK	24-MHz crystal
H5	XTAL24I	CLOCK	24-MHz crystal or external clock input
H6	VSSR	GROUND	Radio ground
H7	VSSR	GROUND	Radio ground
H8	ANT	ANTENNA	Antenna pin
J1	NC	NC	Do not connect
J2	P0.4	GPIO	Port 0 Pin 4, analog/digital/lcd/csd
J3	P0.0	GPIO	Port 0 Pin 0, analog/digital/lcd/csd
J4	VDDR	POWER	1.9-V to 5.5-V radio supply
J7	VDDR	POWER	1.9-V to 5.5-V radio supply
J8	NO CONNECT	—	—

High-speed I/O matrix (HSIOM) is a group of high-speed switches that routes GPIOs to the resources inside the device. These resources include CapSense, TCPWMs, I²C, SPI, UART, and LCD. HSIOM_PORT_SELx are 32-bit-wide registers that control the routing of GPIOs. Each register controls one port; four dedicated bits are assigned to each GPIO in the port. This provides up to 16 different options for GPIO routing as shown in [Table 3](#).

Table 3. HSIOM Port Settings

Value	Description
0	Firmware-controlled GPIO
1	Output is firmware-controlled, but Output Enable (OE) is controlled from DSI.
2	Both output and OE are controlled from DSI.
3	Output is controlled from DSI, but OE is firmware-controlled.
4	Pin is a CSD sense pin
5	Pin is a CSD shield pin
6	Pin is connected to AMUXA
7	Pin is connected to AMUXB
8	Pin-specific Active function #0
9	Pin-specific Active function #1
10	Pin-specific Active function #2

Table 3. HSIOM Port Settings (continued)

Value	Description
11	Reserved
12	Pin is an LCD common pin
13	Pin is an LCD segment pin
14	Pin-specific Deep-Sleep function #0
15	Pin-specific Deep-Sleep function #1

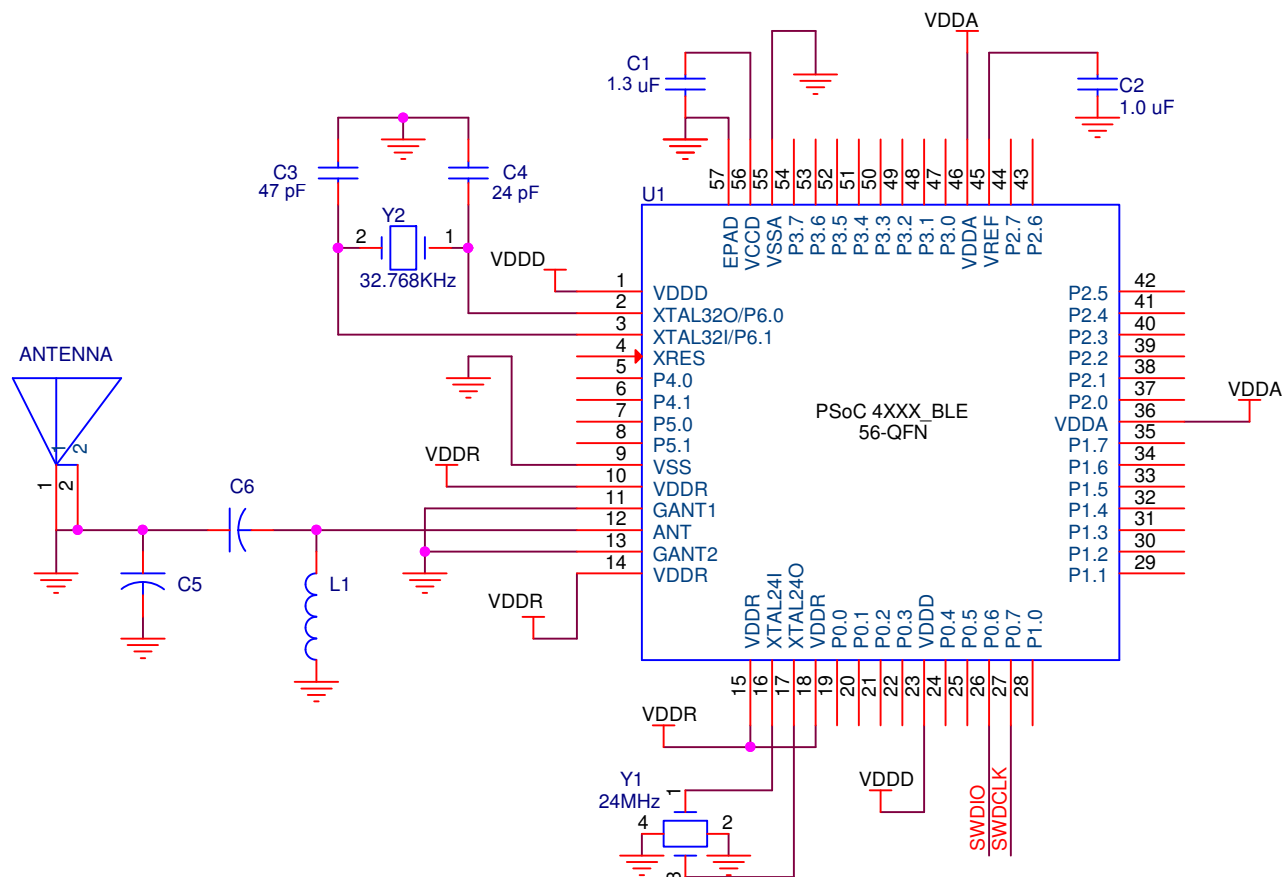
The selection of peripheral function for different GPIO pins is given in [Table 4](#).

Table 4. Port Pin Connections

Name	Analog	Digital					
		GPIO	Active #0	Active #1	Active #2	Deep Sleep #0	Deep Sleep #1
P0.0	COMP0_INP	GPIO	TCPWM0_P[3]	SCB1_UART_RX[1]	–	SCB1_I2C_SDA[1]	SCB1_SPI_MOSI[1]
P0.1	COMP0_INN	GPIO	TCPWM0_N[3]	SCB1_UART_TX[1]	–	SCB1_I2C_SCL[1]	SCB1_SPI_MISO[1]
P0.2	–	GPIO	TCPWM1_P[3]	SCB1_UART_RTS[1]	–	COMP0_OUT[0]	SCB1_SPI_SS0[1]
P0.3	–	GPIO	TCPWM1_N[3]	SCB1_UART_CTS[1]	–	COMP1_OUT[0]	SCB1_SPI_SCLK[1]
P0.4	COMP1_INP	GPIO	TCPWM1_P[0]	SCB0_UART_RX[1]	EXT_CLK[0]/ ECO_OUT[0]	SCB0_I2C_SDA[1]	SCB0_SPI_MOSI[1]
P0.5	COMP1_INN	GPIO	TCPWM1_N[0]	SCB0_UART_TX[1]	–	SCB0_I2C_SCL[1]	SCB0_SPI_MISO[1]
P0.6	–	GPIO	TCPWM2_P[0]	SCB0_UART_RTS[1]	–	SWDIO[0]	SCB0_SPI_SS0[1]
P0.7	–	GPIO	TCPWM2_N[0]	SCB0_UART_CTS[1]	–	SWDCLK[0]	SCB0_SPI_SCLK[1]
P1.0	CTBm1_OA0_INP	GPIO	TCPWM0_P[1]	–	–	COMP0_OUT[1]	WCO_OUT[2]
P1.1	CTBm1_OA0_INN	GPIO	TCPWM0_N[1]	–	–	COMP1_OUT[1]	SCB1_SPI_SS1
P1.2	CTBm1_OA0_OUT	GPIO	TCPWM1_P[1]	–	–	–	SCB1_SPI_SS2
P1.3	CTBm1_OA1_OUT	GPIO	TCPWM1_N[1]	–	–	–	SCB1_SPI_SS3
P1.4	CTBm1_OA1_INN	GPIO	TCPWM2_P[1]	SCB0_UART_RX[0]	–	SCB0_I2C_SDA[0]	SCB0_SPI_MOSI[1]
P1.5	CTBm1_OA1_INP	GPIO	TCPWM2_N[1]	SCB0_UART_TX[0]	–	SCB0_I2C_SCL[0]	SCB0_SPI_MISO[1]
P1.6	CTBm1_OA0_INP	GPIO	TCPWM3_P[1]	SCB0_UART_RTS[0]	–	–	SCB0_SPI_SS0[1]
P1.7	CTBm1_OA1_INP	GPIO	TCPWM3_N[1]	SCB0_UART_CTS[0]	–	–	SCB0_SPI_SCLK[1]
P2.0	CTBm0_OA0_INP	GPIO	–	–	–	–	SCB0_SPI_SS1
P2.1	CTBm0_OA0_INN	GPIO	–	–	–	–	SCB0_SPI_SS2
P2.2	CTBm0_OA0_OUT	GPIO	–	–	–	WAKEUP	SCB0_SPI_SS3
P2.3	CTBm0_OA1_OUT	GPIO	–	–	–	–	WCO_OUT[1]
P2.4	CTBm0_OA1_INN	GPIO	–	–	–	–	–
P2.5	CTBm0_OA1_INP	GPIO	–	–	–	–	–
P2.6	CTBm0_OA0_INP	GPIO	–	–	–	–	–
P2.7	CTBm0_OA1_INP	GPIO	–	–	EXT_CLK[1]/ECO_OUT[1]	–	–
P3.0	SARMUX_0	GPIO	TCPWM0_P[2]	SCB0_UART_RX[2]	–	SCB0_I2C_SDA[2]	–
P3.1	SARMUX_1	GPIO	TCPWM0_N[2]	SCB0_UART_TX[2]	–	SCB0_I2C_SCL[2]	–
P3.2	SARMUX_2	GPIO	TCPWM1_P[2]	SCB0_UART_RTS[2]	–	–	–
P3.3	SARMUX_3	GPIO	TCPWM1_N[2]	SCB0_UART_CTS[2]	–	–	–
P3.4	SARMUX_4	GPIO	TCPWM2_P[2]	SCB1_UART_RX[2]	–	SCB1_I2C_SDA[2]	–
P3.5	SARMUX_5	GPIO	TCPWM2_N[2]	SCB1_UART_TX[2]	–	SCB1_I2C_SCL[2]	–
P3.6	SARMUX_6	GPIO	TCPWM3_P[2]	SCB1_UART_RTS[2]	–	–	–
P3.7	SARMUX_7	GPIO	TCPWM3_N[2]	SCB1_UART_CTS[2]	–	–	WCO_OUT[0]
P4.0	CMOD	GPIO	TCPWM0_P[0]	SCB1_UART_RTS[0]	–	–	SCB1_SPI_MOSI[0]
P4.1	CTANK	GPIO	TCPWM0_N[0]	SCB1_UART_CTS[0]	–	–	SCB1_SPI_MISO[0]
P5.0	–	GPIO	TCPWM3_P[0]	SCB1_UART_RX[0]	EXTPA_EN	SCB1_I2C_SDA[0]	SCB1_SPI_SS0[0]
P5.1	–	GPIO	TCPWM3_N[0]	SCB1_UART_TX[0]	EXT_CLK[2]/ECO_OUT[2]	SCB1_I2C_SCL[0]	SCB1_SPI_SCLK[0]
P6.0_XTAL320	–	GPIO	–	–	–	–	–
P6.1_XTAL321	–	GPIO	–	–	–	–	–

The possible pin connections are shown for all analog and digital peripherals (except the radio, LCD, and CSD blocks, which were shown in Table 1). A typical system application connection diagram is shown in Figure 7.

Figure 7. System Application Connection Diagram



Power

The PSoc 4200_BLE device can be supplied from batteries with a voltage range of 1.9 V to 5.5 V by directly connecting to the digital supply (VDDD), analog supply (VDDA), and radio supply (VDDR) pins. Internal LDOs in the device regulate the supply voltage to the required levels for different blocks. The device has one regulator for the digital circuitry and separate regulators for radio circuitry for noise isolation. Analog circuits run directly from the analog supply (VDDA) input. The device uses separate regulators for Deep Sleep and Hibernate (lowered power supply and retention) modes to minimize the power consumption. The radio stops working below 1.9 V, but the device continues to function down to 1.71 V without RF.

Bypass capacitors must be used from VDDx (x = A, D, or R) to ground. The typical practice for systems in this frequency range is to use a capacitor in the 1- μ F range in parallel with a smaller capacitor (for example, 0.1 μ F). Note that these are simply rules of thumb and that, for critical applications, the PCB layout, lead inductance, and the bypass capacitor parasitic should be simulated to design and obtain optimal bypassing.

Power Supply	Bypass Capacitors
VDDD	The internal bandgap may be bypassed with a 1- μ F to 10- μ F.
VDDA	0.1- μ F ceramic at each pin plus bulk capacitor 1- μ F to 10- μ F.
VDDR	0.1- μ F ceramic at each pin plus bulk capacitor 1- μ F to 10- μ F.
VCCD	1.3- μ F ceramic capacitor at the VCCD pin.
VREF (optional)	The internal bandgap may be bypassed with a 1- μ F to 10- μ F capacitor.

Development Support

The PSoC 4200_BLE family has a rich set of documentation, development tools, and online resources to assist you during your development process. Visit www.cypress.com/go/psoc4ble to find out more.

Documentation

A suite of documentation supports the PSoC 4200_BLE family to ensure that you can find answers to your questions quickly. This section contains a list of some of the key documents.

Software User Guide: A step-by-step guide for using PSoC Creator. The software user guide shows you how the PSoC Creator build process works in detail, how to use source control with PSoC Creator, and much more.

Component Datasheets: The flexibility of PSoC allows the creation of new peripherals (Components) long after the device has gone into production. Component datasheets provide all of the information needed to select and use a particular Component, including a functional description, API documentation, example code, and AC/DC specifications.

Application Notes: PSoC application notes discuss a particular application of PSoC in depth; examples include creating standard and custom BLE profiles. Application notes often include example projects in addition to the application note document.

Technical Reference Manual: The Technical Reference Manual (TRM) contains all the technical detail you need to use a PSoC device, including a complete description of all PSoC registers. The TRM is available in the Documentation section at www.cypress.com/psoc4.

Online

In addition to print documentation, the Cypress PSoC forums connect you with fellow PSoC users and experts in PSoC from around the world, 24 hours a day, 7 days a week.

Tools

With industry standard cores, programming, and debugging interfaces, the PSoC 4200_BLE family is part of a development tool ecosystem. Visit us at www.cypress.com/go/psoccreator for the latest information on the revolutionary, easy to use PSoC Creator IDE, supported third party compilers, programmers, debuggers, and development kits.

Electrical Specifications

Absolute Maximum Ratings

Table 5. Absolute Maximum Ratings^[1]

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID1	V _{DDD_ABS}	Analog, digital, or radio supply relative to V _{SS} (V _{SSD} = V _{SSA})	−0.5	–	6	V	Absolute max
SID2	V _{CCD_ABS}	Direct digital core voltage input relative to V _{SSD}	−0.5	–	1.95	V	Absolute max
SID3	V _{GPIO_ABS}	GPIO voltage	−0.5	–	V _{DD} + 0.5	V	Absolute max
SID4	I _{GPIO_ABS}	Maximum current per GPIO	−25	–	25	mA	Absolute max
SID5	I _{GPIO_injection}	GPIO injection current, Max for V _{IH} > V _{DDD} , and Min for V _{IL} < V _{SS}	−0.5	–	0.5	mA	Absolute max, current injected per pin
BID57	ESD_HBM	Electrostatic discharge human body model	2200	–	–	V	–
BID58	ESD_CDM	Electrostatic discharge charged device model	500	–	–	V	–
BID61	LU	Pin current for latch-up	−200	–	200	mA	–

Device-Level Specifications

All specifications are valid for −40 °C ≤ T_A ≤ 85 °C and T_J ≤ 100 °C, except where noted. Specifications are valid for 1.71 V to 5.5 V, except where noted.

Table 6. DC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID6	V _{DD}	Power supply input voltage (V _{DDA} = V _{DDD} = V _{DD})	1.8	–	5.5	V	With regulator enabled
SID7	V _{DD}	Power supply input voltage unregulated (V _{DDA} = V _{DDD} = V _{DD})	1.71	1.8	1.89	V	Internally unregulated Supply
SID8	V _{DDR}	Radio supply voltage (Radio ON)	1.9	–	5.5	V	–
SID8A	V _{DDR}	Radio supply voltage (Radio OFF)	1.71	–	5.5	V	–
SID9	V _{CCD}	Digital regulator output voltage (for core logic)	–	1.8	–	V	–
SID10	C _{VCCD}	Digital regulator output bypass capacitor	1	1.3	1.6	μF	X5R ceramic or better
Active Mode, V_{DD} = 1.71 V to 5.5 V							–
SID13	I _{DD3}	Execute from flash; CPU at 3 MHz	–	2.1	–	mA	T = 25 °C, V _{DD} = 3.3 V
SID14	I _{DD4}	Execute from flash; CPU at 3 MHz	–	–	–	mA	T = −40 °C to 85 °C
SID15	I _{DD5}	Execute from flash; CPU at 6 MHz	–	2.5	–	mA	T = 25 °C, V _{DD} = 3.3 V
SID16	I _{DD6}	Execute from flash; CPU at 6 MHz	–	–	–	mA	T = −40 °C to 85 °C
SID17	I _{DD7}	Execute from flash; CPU at 12 MHz	–	4	–	mA	T = 25 °C, V _{DD} = 3.3 V
SID18	I _{DD8}	Execute from flash; CPU at 12 MHz	–	–	–	mA	T = −40 °C to 85 °C

Note

- Usage above the absolute maximum conditions listed in Table 5 may cause permanent damage to the device. Exposure to absolute maximum conditions for extended periods of time may affect device reliability. The maximum storage temperature is 150 °C in compliance with JEDEC Standard JESD22-A103, High Temperature Storage Life. When used below absolute maximum conditions but above normal operating conditions, the device may not operate to specification.

Table 6. DC Specifications (continued)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID19	I _{DD9}	Execute from flash; CPU at 24 MHz	–	7.1	–	mA	T = 25 °C, V _{DD} = 3.3 V
SID20	I _{DD10}	Execute from flash; CPU at 24 MHz	–	–	–	mA	T = –40 °C to 85 °C
SID21	I _{DD11}	Execute from flash; CPU at 48 MHz	–	13.4	–	mA	T = 25 °C, V _{DD} = 3.3 V
SID22	I _{DD12}	Execute from flash; CPU at 48 MHz	–	–	–	mA	T = –40 °C to 85 °C
Sleep Mode, V_{DD} = 1.8 to 5.5 V							
SID23	I _{DD13}	IMO on	–	–	–	mA	T = 25 °C, V _{DD} = 3.3 V, SYSCLK = 3 MHz
Sleep Mode, V_{DD} and V_{DDR} = 1.9 to 5.5 V							
SID24	I _{DD14}	ECO on	–	–	–	mA	T = 25 °C, V _{DD} = 3.3 V, SYSCLK = 3 MHz
Deep Sleep Mode, V_{DD} = 1.8 to 3.6 V							
SID25	I _{DD15}	WDT with WCO on	–	1.5	–	μA	T = 25 °C, V _{DD} = 3.3 V
SID26	I _{DD16}	WDT with WCO on	–	–	–	μA	T = –40 °C to 85 °C
Deep Sleep Mode, V_{DD} = 3.6 to 5.5 V							
SID27	I _{DD17}	WDT with WCO on	–	–	–	μA	T = 25 °C, V _{DD} = 5 V
SID28	I _{DD18}	WDT with WCO on	–	–	–	μA	T = –40 °C to 85 °C
Deep Sleep Mode, V_{DD} = 1.71 to 1.89 V (Regulator Bypassed)							
SID29	I _{DD19}	WDT with WCO on	–	–	–	μA	T = 25 °C
SID30	I _{DD20}	WDT with WCO on	–	–	–	μA	T = –40 °C to 85 °C
Deep Sleep Mode, V_{DD} = 1.8 to 3.6 V							
SID31	I _{DD21}	Opamp on	–	–	–	μA	T = 25 °C, V _{DD} = 3.3 V
SID32	I _{DD22}	Opamp on	–	–	–	μA	T = –40 °C to 85 °C
Deep Sleep Mode, V_{DD} = 3.6 to 5.5 V							
SID33	I _{DD23}	Opamp on	–	–	–	μA	T = 25 °C, V _{DD} = 5 V
SID34	I _{DD24}	Opamp on	–	–	–	μA	T = –40 °C to 85 °C
Deep Sleep Mode, V_{DD} = 1.71 to 1.89 V (Regulator Bypassed)							
SID35	I _{DD25}	Opamp on	–	–	–	μA	T = 25 °C
SID36	I _{DD26}	Opamp on	–	–	–	μA	T = –40 °C to 85 °C
Hibernate Mode, V_{DD} = 1.8 to 3.6 V							
SID37	I _{DD27}	GPIO and reset active	–	150	–	nA	T = 25 °C, V _{DD} = 3.3V
SID38	I _{DD28}	GPIO and reset active	–	–	–	nA	T = –40 °C to 85 °C
Hibernate Mode, V_{DD} = 3.6 to 5.5 V							
SID39	I _{DD29}	GPIO and reset active	–	–	–	nA	T = 25 °C, V _{DD} = 5 V
SID40	I _{DD30}	GPIO and reset active	–	–	–	nA	T = –40 °C to 85 °C
Hibernate Mode, V_{DD} = 1.71 to 1.89 V (Regulator Bypassed)							

Table 6. DC Specifications (continued)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID41	I _{DD31}	GPIO and reset active	–	–	–	nA	T = 25 °C
SID42	I _{DD32}	GPIO and reset active	–	–	–	nA	T = –40 °C to 85 °C
Stop Mode, V_{DD} = 1.8 to 3.6 V							
SID43	I _{DD33}	Stop mode current (V _{DD})	–	20	–	nA	T = 25 °C, V _{DD} = 3.3 V
SID44	I _{DD34}	Stop mode current (V _{DDR})	–	40	–	nA	T = 25 °C, V _{DDR} = 3.3 V
SID45	I _{DD35}	Stop mode current (V _{DD})	–	–	–	nA	T = –40 °C to 85 °C
SID46	I _{DD36}	Stop mode current (V _{DDR})	–	–	–	nA	T = –40 °C to 85 °C, V _{DDR} = 1.9 V to 3.6 V
Stop Mode, V_{DD} = 3.6 to 5.5 V							
SID47	I _{DD37}	Stop mode current (V _{DD})	–	–	–	nA	T = 25 °C, V _{DD} = 5 V
SID48	I _{DD38}	Stop mode current (V _{DDR})	–	–	–	nA	T = 25 °C, V _{DDR} = 5 V
SID49	I _{DD39}	Stop mode current (V _{DD})	–	–	–	nA	T = –40 °C to 85 °C
SID50	I _{DD40}	Stop mode current (V _{DDR})	–	–	–	nA	T = –40 °C to 85 °C
Stop Mode, V_{DD} = 1.71 to 1.89 V (Regulator Bypassed)							
SID51	I _{DD41}	Stop mode current (V _{DD})	–	–	–	nA	T = 25 °C
SID52	I _{DD42}	Stop mode current (V _{DD})	–	–	–	nA	T = –40 °C to 85 °C

Table 7. AC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID53	F _{CPU}	CPU frequency	DC	–	48	MHz	1.71 V ≤ V _{DD} ≤ 5.5 V
SID54	T _{SLEEP}	Wakeup from Sleep mode	–	0	–	μs	Guaranteed by characterization
SID55	T _{DEEPSLEEP}	Wakeup from Deep Sleep mode	–	–	25	μs	24-MHz IMO. Guaranteed by characterization.
SID56	T _{HIBERNATE}	Wakeup from Hibernate mode	–	–	0.7	ms	Guaranteed by characterization
SID57	T _{STOP}	Wakeup from Stop mode	–	–	2.2	ms	Guaranteed by characterization

GPIO
Table 8. GPIO DC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID58	V_{IH}	Input voltage HIGH threshold	$0.7 \times V_{DD}$	–	–	V	CMOS input
SID59	V_{IL}	Input voltage LOW threshold	–	–	$0.3 \times V_{DD}$	V	CMOS input
SID60	V_{IH}	LVTTL input, $V_{DD} < 2.7$ V	$0.7 \times V_{DD}$	–	–	V	–
SID61	V_{IL}	LVTTL input, $V_{DD} < 2.7$ V	–	–	$0.3 \times V_{DD}$	V	–
SID62	V_{IH}	LVTTL input, $V_{DD} \geq 2.7$ V	2.0	–	–	V	–
SID63	V_{IL}	LVTTL input, $V_{DD} \geq 2.7$ V	–	–	0.8	V	–
SID64	V_{OH}	Output voltage HIGH level	$V_{DD} - 0.6$	–	–	V	$I_{OH} = 4\text{-mA}$ at 3.3-V V_{DD}
SID65	V_{OH}	Output voltage HIGH level	$V_{DD} - 0.5$	–	–	V	$I_{OH} = 1\text{-mA}$ at 1.8-V V_{DD}
SID66	V_{OL}	Output voltage LOW level	–	–	0.6	V	$I_{OL} = 8\text{-mA}$ at 3.3-V V_{DD}
SID67	V_{OL}	Output voltage LOW level	–	–	0.6	V	$I_{OL} = 4\text{-mA}$ at 1.8-V V_{DD}
SID68	V_{OL}	Output voltage LOW level	–	–	0.4	V	$I_{OL} = 3\text{-mA}$ at 3.3-V V_{DD}
SID69	R_{pullup}	Pull-up resistor	3.5	5.6	8.5	k Ω	–
SID70	$R_{pulldown}$	Pull-down resistor	3.5	5.6	8.5	k Ω	–
SID71	I_{IL}	Input leakage current (absolute value)	–	–	2	nA	25 °C, $V_{DD} = 3.3$ V
SID72	I_{IL_CTBM}	Input leakage on CTBm input pins	–	–	4	nA	–
SID73	C_{IN}	Input capacitance	–	–	7	pF	–
SID74	V_{hysttl}	Input hysteresis LVTTL	25	40	–	mV	$V_{DD} > 2.7$ V
SID75	$V_{hyscmos}$	Input hysteresis CMOS	$0.05 \times V_{DD}$	–	–	mV	–
SID76	I_{diode}	Current through protection diode to V_{DD}/V_{SS}	–	–	100	μ A	–
SID77	I_{TOT_GPIO}	Maximum total source or sink chip current	–	–	200	mA	–

Table 9. GPIO AC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID78	T_{RISEF}	Rise time in Fast-Strong mode	2	–	12	ns	3.3-V V_{DD} , $C_{LOAD} = 25\text{-pF}$
SID79	T_{FALLF}	Fall time in Fast-Strong mode	2	–	12	ns	3.3-V V_{DD} , $C_{LOAD} = 25\text{-pF}$
SID80	T_{RISES}	Rise time in Slow-Strong mode	10	–	60	–	3.3-V V_{DD} , $C_{LOAD} = 25\text{-pF}$
SID81	T_{FALLS}	Fall time in Slow-Strong mode	10	–	60	–	3.3-V V_{DD} , $C_{LOAD} = 25\text{-pF}$
SID82	$F_{GPIOUT1}$	GPIO Fout; $3.3\text{ V} \leq V_{DD} \leq 5.5\text{ V}$. Fast-Strong mode	–	–	33	MHz	90/10%, 25-pF load, 60/40 duty cycle

Note

 2. V_{IH} must not exceed $V_{DD} + 0.2$ V.

Table 9. GPIO AC Specifications (continued)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID83	F_{GPIOOUT2}	GPIO Fout; $1.7 \text{ V} \leq V_{\text{DD}} \leq 3.3 \text{ V}$. Fast-Strong mode	–	–	16.7	MHz	90/10%, 25-pF load, 60/40 duty cycle
SID84	F_{GPIOOUT3}	GPIO Fout; $3.3 \text{ V} \leq V_{\text{DD}} \leq 5.5 \text{ V}$. Slow-Strong mode	–	–	7	MHz	90/10%, 25-pF load, 60/40 duty cycle
SID85	F_{GPIOOUT4}	GPIO Fout; $1.7 \text{ V} \leq V_{\text{DD}} \leq 3.3 \text{ V}$. Slow-Strong mode	–	–	3.5	MHz	90/10%, 25-pF load, 60/40 duty cycle
SID86	F_{GPIOIN}	GPIO input operating frequency; $1.71 \text{ V} \leq V_{\text{DD}} \leq 5.5 \text{ V}$	–	–	48	MHz	90/10% V_{IO}

Table 10. OVT GPIO DC Specifications (P5_0 and P5_1 Only)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID71A	I_{IL}	Input leakage current (absolute value), $V_{\text{IH}} > V_{\text{DD}}$	–	–	10	μA	25 °C, $V_{\text{DD}} = 0 \text{ V}$, $V_{\text{IH}} = 3.0 \text{ V}$
SID66A	V_{OL}	Output voltage LOW level	–	–	0.4	V	$I_{\text{OL}} = 20\text{-mA}$, $V_{\text{DD}} > 2.9\text{-V}$

Table 11. OVT GPIO AC Specifications (P5_0 and P5_1 Only)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID78A	$T_{\text{RISE_OVFS}}$	Output rise time in Fast-Strong mode	1.5	–	12	ns	25-pF load, 10%–90%, $V_{\text{DD}} = 3.3\text{-V}$
SID79A	$T_{\text{FALL_OVFS}}$	Output fall time in Fast-Strong mode	1.5	–	12	ns	25-pF load, 10%–90%, $V_{\text{DD}} = 3.3\text{-V}$
SID80A	T_{RISSS}	Output rise time in Slow-Strong mode	10	–	60	ns	25-pF load, 10%–90%, $V_{\text{DD}} = 3.3\text{-V}$
SID81A	T_{FALLSS}	Output fall time in Slow-Strong mode	10	–	60	ns	25-pF load, 10%–90%, $V_{\text{DD}} = 3.3\text{-V}$
SID82A	F_{GPIOOUT1}	GPIO FOUT; $3.3 \text{ V} \leq V_{\text{DD}} \leq 5.5 \text{ V}$ Fast-Strong mode	–	–	24	MHz	90/10%, 25-pF load, 60/40 duty cycle
SID83A	F_{GPIOOUT2}	GPIO FOUT; $1.71 \text{ V} \leq V_{\text{DD}} \leq 3.3 \text{ V}$ Fast-Strong mode	–	–	16	MHz	90/10%, 25-pF load, 60/40 duty cycle

XRES

Table 12. XRES DC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID87	V_{IH}	Input voltage HIGH threshold	$0.7 \times V_{\text{DDD}}$	–	–	V	CMOS input
SID88	V_{IL}	Input voltage LOW threshold	–	–	$0.3 \times V_{\text{DDD}}$	V	CMOS input
SID89	R_{pullup}	Pull-up resistor	3.5	5.6	8.5	$\text{k}\Omega$	–
SID90	C_{IN}	Input capacitance	–	3	–	pF	–
SID91	V_{HYSXRES}	Input voltage hysteresis	–	100	–	mV	–
SID92	I_{DIODE}	Current through protection diode to $V_{\text{DDD}}/V_{\text{SS}}$	–	–	100	μA	–

Table 13. XRES AC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID93	T _{RESETWIDTH}	Reset pulse width	1	–	–	μs	–

Analog Peripherals

Opamp

Table 14. Opamp Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
I_{DD} (Opamp Block Current. V_{DD} = 1.8 V. No Load)							
SID94	I _{DD_HI}	Power = high	–	1000	1850	μA	–
SID95	I _{DD_MED}	Power = medium	–	500	950	μA	–
SID96	I _{DD_LOW}	Power = low	–	250	350	μA	–
GBW (Load = 20 pF, 0.1 mA. V_{DDA} = 2.7 V)							
SID97	GBW_HI	Power = high	6	–	–	MHz	–
SID98	GBW_MED	Power = medium	4	–	–	MHz	–
SID99	GBW_LO	Power = low	–	1	–	MHz	–
I_{OUT_MAX} (V_{DDA} ≥ 2.7 V, 500 mV From Rail)							
SID100	I _{OUT_MAX_HI}	Power = high	10	–	–	mA	–
SID101	I _{OUT_MAX_MID}	Power = medium	10	–	–	mA	–
SID102	I _{OUT_MAX_LO}	Power = low	–	5	–	mA	–
I_{OUT} (V_{DDA} = 1.71 V, 500 mV From Rail)							
SID103	I _{OUT_MAX_HI}	Power = high	4	–	–	mA	–
SID104	I _{OUT_MAX_MID}	Power = medium	4	–	–	mA	–
SID105	I _{OUT_MAX_LO}	Power = low	–	2	–	mA	–
SID106	V _{IN}	Charge pump on, V _{DDA} ≥ 2.7 V	–0.05	–	V _{DDA} – 0.2	V	–
SID107	V _{CM}	Charge pump on, V _{DDA} ≥ 2.7 V	–0.05	–	V _{DDA} – 0.2	V	–
V_{OUT} (V_{DDA} ≥ 2.7 V)							
SID108	V _{OUT_1}	Power = high, I _{LOAD} =10 mA	0.5	–	V _{DDA} – 0.5	V	–
SID109	V _{OUT_2}	Power = high, I _{LOAD} =1 mA	0.2	–	V _{DDA} – 0.2	V	–
SID110	V _{OUT_3}	Power = medium, I _{LOAD} =1 mA	0.2	–	V _{DDA} – 0.2	V	–
SID111	V _{OUT_4}	Power = low, I _{LOAD} =0.1 mA	0.2	–	V _{DDA} – 0.2	V	–
SID112	V _{OS_TR}	Offset voltage, trimmed	1	±0.5	1	mV	High mode
SID113	V _{OS_TR}	Offset voltage, trimmed	–	±1	–	mV	Medium mode
SID114	V _{OS_TR}	Offset voltage, trimmed	–	±2	–	mV	Low mode
SID115	V _{OS_DR_TR}	Offset voltage drift, trimmed	–10	±3	10	μV/C	High mode
SID116	V _{OS_DR_TR}	Offset voltage drift, trimmed	–	±10	–	μV/C	Medium mode
SID117	V _{OS_DR_TR}	Offset voltage drift, trimmed	–	±10	–	μV/C	Low mode
SID118	CMRR	DC	70	80	–	dB	V _{DD} = 3.6-V
SID119	PSRR	At 1 kHz, 100-mV ripple	70	85	–	dB	V _{DD} = 3.6-V
Noise							
SID120	V _{N1}	Input referred, 1 Hz–1 GHz, power = high	–	94	–	μVrms	–
SID121	V _{N2}	Input referred, 1-kHz, power = high	–	72	–	nV/rHz	–

Table 14. Opamp Specifications (continued)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID122	V _{N3}	Input referred, 10-kHz, power = high	–	28	–	nV/rtHz	–
SID123	V _{N4}	Input referred, 100-kHz, power = high	–	15	–	nV/rtHz	–
SID124	C _{LOAD}	Stable up to maximum load. Performance specs at 50 pF	–	–	125	pF	–
SID125	Slew_rate	Cload = 50 pF, Power = High, V _{DDA} ≥ 2.7 V	6	–	–	V/μsec	–
SID126	T _{op_wake}	From disable to enable, no external RC dominating	–	300	–	μsec	–
Comp_mode (Comparator Mode; 50-mV Drive, T_{RISE} = T_{FALL} (Approx.))							
SID127	T _{PD1}	Response time; power = high	–	150	–	nsec	–
SID128	T _{PD2}	Response time; power = medium	–	400	–	nsec	–
SID129	T _{PD3}	Response time; power = low	–	2000	–	nsec	–
SID130	V _{hyst_op}	Hysteresis	–	10	–	mV	–
Deep Sleep (Deep Sleep mode operation is only guaranteed for V_{DDA} > 2.5 V)							
SID131	GBW_DS	Gain bandwidth product	–	50	–	kHz	–
SID132	IDD_DS	Current	–	15	–	μA	–
SID133	V _{os_DS}	Offset voltage	–	5	–	mV	–
SID134	V _{os_dr_DS}	Offset voltage drift	–	20	–	μV/°C	–
SID135	V _{out_DS}	Output voltage	0.2	–	V _{DD} –0.2	V	–
SID136	V _{cm_DS}	Common mode voltage	0.2	–	V _{DD} –1.8	V	–

Table 15. Comparator DC Specifications^[3]

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID140	V _{OFFSET1}	Input offset voltage, Factory trim	–	–	±10	mV	–
SID141	V _{OFFSET2}	Input offset voltage, Custom trim	–	–	±6	mV	–
SID141A	V _{OFFSET3}	Input offset voltage, ultra-low-power mode	–	±12	–	mV	V _{DDD} ≥ 2.6 V for Temp < 0 °C, V _{DDD} ≥ 1.8 V for Temp > 0 °C
SID142	V _{HYST}	Hysteresis when enabled. Common Mode voltage range from 0 to V _{DD} –1	–	10	35	mV	–
SID143	V _{ICM1}	Input common mode voltage in normal mode	0	–	V _{DDD} –0.1	V	Modes 1 and 2
SID144	V _{ICM2}	Input common mode voltage in low power mode	0	–	V _{DDD}	V	–
SID145	V _{ICM3}	Input common mode voltage in ultra low power mode	0	–	V _{DDD} –1.15	V	V _{DDD} ≥ 2.6 V for Temp < 0 °C, V _{DDD} ≥ 1.8 V for Temp > 0 °C
SID146	CMRR	Common mode rejection ratio	50	–	–	dB	V _{DDD} ≥ 2.7 V
SID147	CMRR	Common mode rejection ratio	42	–	–	dB	V _{DDD} ≤ 2.7 V
SID148	I _{CMP1}	Block current, normal mode	–	–	400	μA	–
SID149	I _{CMP2}	Block current, low power mode	–	–	100	μA	–

Note

3. ULP LCOMP operating conditions:
 – V_{DDD} 2.6 V–5.5 V for datasheet temp range < 0 °C
 – V_{DDD} 1.8 V–5.5 V for datasheet temp range ≥ 0 °C

Table 15. Comparator DC Specifications^[3] (continued)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID150	I _{CMP3}	Block current in ultra low-power mode	–	6	–	μA	V _{DDD} ≥ 2.6 V for Temp < 0 °C, V _{DDD} ≥ 1.8 V for Temp > 0 °C
SID151	Z _{CMP}	DC input impedance of comparator	35	–	–	MΩ	–

Table 16. Comparator AC Specifications^[4]

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID152	T _{RESP1}	Response time, normal mode, 50-mV overdrive	–	38	–	ns	50-mV overdrive
SID153	T _{RESP2}	Response time, low power mode, 50-mV overdrive	–	70	–	ns	50-mV overdrive
SID154	T _{RESP3}	Response time, ultra-low-power mode, 50-mV overdrive	–	2.3	–	μs	200-mV overdrive. V _{DDD} ≥ 2.6 V for Temp < 0 °C, V _{DDD} ≥ 1.8 V for Temp > 0 °C

Temperature Sensor

Table 17. Temperature Sensor Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID155	T _{SENSACC}	Temperature sensor accuracy	–5	±1	5	°C	–40 to +85 °C

SAR ADC

Table 18. SAR ADC DC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID156	A_RES	Resolution	–	–	12	bits	–
SID157	A_CHNIS_S	Number of channels - single-ended	–	–	16	–	8 full-speed
SID158	A-CHNKS_D	Number of channels - differential	–	–	8	–	Diff inputs use neighboring I/O
SID159	A-MONO	Monotonicity	–	–	–	–	Yes
SID160	A_GAINERR	Gain error	–	–	±0.1	%	With external reference.
SID161	A_OFFSET	Input offset voltage	–	–	2	mV	Measured with 1-V V _{REF}
SID162	A_ISAR	Current consumption	–	–	1	mA	–
SID163	A_VINS	Input voltage range - single-ended	V _{SS}	–	V _{DDA}	V	–
SID164	A_VIND	Input voltage range - differential	V _{SS}	–	V _{DDA}	V	–
SID165	A_INRES	Input resistance	–	–	2.2	kΩ	–
SID166	A_INCAP	Input capacitance	–	–	10	pF	–
SID312	VREFSAR	Trimmed internal reference to SAR	–1	–	1	%	Percentage of V _{bg} (1.024-V)

Note

4. ULP LCOMP operating conditions:
 – V_{DDD} 2.6 V-5.5 V for datasheet temp range < 0 °C
 – V_{DDD} 1.8 V-5.5 V for datasheet temp range ≥ 0 °C

Table 19. SAR ADC AC Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID167	A_psr	Power supply rejection ratio	70	–	–	dB	Measured at 1-V reference
SID168	A_cmrr	Common mode rejection ratio	66	–	–	dB	–
SID169	A_samp	Sample rate	–	–	1	Msp	
SID313	Fsarintref	SAR operating speed without external ref. bypass	–	–	100	Ksp	12-bit resolution
SID170	A_snr	Signal-to-noise ratio (SNR)	65	–	–	dB	Fin = 10 kHz
SID171	A_bw	Input bandwidth without aliasing	–	–	A_samp/2	kHz	–
SID172	A_inl	Integral non linearity. V _{DD} = 1.71 to 5.5 V, 1 Msp	–1.7	–	2	LSB	Vref = 1 V to V _{DD}
SID173	A_INL	Integral non linearity. V _{DD} = 1.71 to 3.6 V, 1 Msp	–1.5	–	1.7	LSB	Vref = 1.71 V to V _{DD}
SID174	A_INL	Integral non linearity. V _{DD} = 1.71 to 5.5 V, 500 Ksp	–1.5	–	1.7	LSB	Vref = 1 V to V _{DD}
SID175	A_dnl	Differential non linearity. V _{DD} = 1.71 to 5.5 V, 1 Msp	–1	–	2.2	LSB	Vref = 1 V to V _{DD}
SID176	A_DNL	Differential non linearity. V _{DD} = 1.71 to 3.6 V, 1 Msp	–1	–	2	LSB	Vref = 1.71 V to V _{DD}
SID177	A_DNL	Differential non linearity. V _{DD} = 1.71 to 5.5 V, 500 Ksp	–1	–	2.2	LSB	Vref = 1 V to V _{DD}
SID178	A_thd	Total harmonic distortion	–	–	–65	dB	Fin = 10 kHz

CSD

Table 20. CSD Block Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID179	V _{CSD}	Voltage range of operation	1.71	–	5.5	V	–
SID180	IDAC1	DNL for 8-bit resolution	–1	–	1	LSB	–
SID181	IDAC1	INL for 8-bit resolution	–3	–	3	LSB	–
SID182	IDAC2	DNL for 7-bit resolution	–1	–	1	LSB	–
SID183	IDAC2	INL for 7-bit resolution	–3	–	3	LSB	–
SID184	SNR	Ratio of counts of finger to noise	5	–	–	Ratio	Capacitance range of 9 to 35 pF, 0.1 pF sensitivity. Radio is not operating during the scan
SID185	I _{DAC1_CRT1}	Output current of IDAC1 (8 bits) in High range	–	612	–	μA	–
SID186	I _{DAC1_CRT2}	Output current of IDAC1 (8 bits) in Low range	–	306	–	μA	–
SID187	I _{DAC2_CRT1}	Output current of IDAC2 (7 bits) in High range	–	305	–	μA	–
SID188	I _{DAC2_CRT2}	Output current of IDAC2 (7 bits) in Low range	–	153	–	μA	–

Digital Peripherals

Timer

Table 21. Timer DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID189	I _{TIM1}	Block current consumption at 3 MHz	–	–	50	µA	16-bit timer
SID190	I _{TIM2}	Block current consumption at 12 MHz	–	–	175	µA	16-bit timer
SID191	I _{TIM3}	Block current consumption at 48 MHz	–	–	712	µA	16-bit timer

Table 22. Timer AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID192	T _{TIMFREQ}	Operating frequency	F _{CLK}	–	48	MHz	–
SID193	T _{CAPWINT}	Capture pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID194	T _{CAPWEXT}	Capture pulse width (external)	2 × T _{CLK}	–	–	ns	–
SID195	T _{TIMRES}	Timer resolution	T _{CLK}	–	–	ns	–
SID196	T _{TENWIDINT}	Enable pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID197	T _{TENWIDEXT}	Enable pulse width (external)	2 × T _{CLK}	–	–	ns	–
SID198	T _{TIMRESWINT}	Reset pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID199	T _{TIMRESEXT}	Reset pulse width (external)	2 × T _{CLK}	–	–	ns	–

Counter

Table 23. Counter DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID200	I _{CTR1}	Block current consumption at 3 MHz	–	–	50	µA	16-bit counter
SID201	I _{CTR2}	Block current consumption at 12 MHz	–	–	175	µA	16-bit counter
SID202	I _{CTR3}	Block current consumption at 48 MHz	–	–	712	µA	16-bit counter

Table 24. Counter AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID203	T _{CTRFREQ}	Operating frequency	F _{CLK}	–	48	MHz	–
SID204	T _{CTRPWINT}	Capture pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID205	T _{CTRPWEXT}	Capture pulse width (external)	2 × T _{CLK}	–	–	ns	–
SID206	T _{CTRES}	Counter Resolution	T _{CLK}	–	–	ns	–
SID207	T _{CENWIDINT}	Enable pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID208	T _{CENWIDEXT}	Enable pulse width (external)	2 × T _{CLK}	–	–	ns	–
SID209	T _{CTRRESWINT}	Reset pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID210	T _{CTRRESWEXT}	Reset pulse width (external)	2 × T _{CLK}	–	–	ns	–

Pulse Width Modulation (PWM)

Table 25. PWM DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID211	I _{PWM1}	Block current consumption at 3 MHz	–	–	50	µA	16-bit PWM
SID212	I _{PWM2}	Block current consumption at 12 MHz	–	–	175	µA	16-bit PWM
SID213	I _{PWM3}	Block current consumption at 48 MHz	–	–	741	µA	16-bit PWM

Table 26. PWM AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID214	T _{PWMFREQ}	Operating frequency	F _{CLK}	–	48	MHz	–
SID215	T _{PWMPWINT}	Pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID216	T _{PWMEXT}	Pulse width (external)	2 × T _{CLK}	–	–	ns	–
SID217	T _{PWMKILLINT}	Kill pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID218	T _{PWMKILLEXT}	Kill pulse width (external)	2 × T _{CLK}	–	–	ns	–
SID219	T _{PWMEINT}	Enable pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID220	T _{PWMENEXT}	Enable pulse width (external)	2 × T _{CLK}	–	–	ns	–
SID221	T _{PWMRESWINT}	Reset pulse width (internal)	2 × T _{CLK}	–	–	ns	–
SID222	T _{PWMRESWEXT}	Reset pulse width (external)	2 × T _{CLK}	–	–	ns	–

I²C
Table 27. Fixed I²C DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID223	I _{I2C1}	Block current consumption at 100 kHz	–	–	50	μA	–
SID224	I _{I2C2}	Block current consumption at 400 kHz	–	–	155	μA	–
SID225	I _{I2C3}	Block current consumption at 1 Mbps	–	–	390	μA	–
SID226	I _{I2C4}	I ² C enabled in Deep Sleep mode	–	–	1.4	μA	–

Table 28. Fixed I²C AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID227	F _{I2C1}	Bit rate	–	–	1	Mbps	–

LCD Direct Drive
Table 29. LCD Direct Drive DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID228	I _{LCDLOW}	Operating current in low-power mode	–	17.5	–	μA	16 × 4 small segment display at 50 Hz
SID229	C _{LCDCAP}	LCD capacitance per segment/common driver	–	500	5000	pF	–
SID230	LCD _{OFFSET}	Long-term segment offset	–	20	–	mV	–
SID231	I _{LCDOP1}	LCD system operating current V _{BIAS} = 5 V.	–	2	–	mA	32 × 4 segments. 50 Hz at 25 °C
SID232	I _{LCDOP2}	LCD system operating current. V _{BIAS} = 3.3 V	–	2	–	mA	32 × 4 segments 50 Hz at 25 °C

Table 30. LCD Direct Drive AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID233	F _{LCD}	LCD frame rate	10	50	150	Hz	–

Table 31. Fixed UART DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID234	I _{UART1}	Block current consumption at 100 kbps	–	–	55	μA	–
SID235	I _{UART2}	Block current consumption at 1000 kbps	–	–	360	μA	–

Table 32. Fixed UART AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID236	F _{UART}	Bit rate	–	–	1	Mbps	–

SPI Specifications

Table 33. Fixed SPI DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID237	I _{SPI1}	Block current consumption at 1 Mbps	–	–	360	μA	–
SID238	I _{SPI2}	Block current consumption at 4 Mbps	–	–	560	μA	–
SID239	I _{SPI3}	Block current consumption at 8 Mbps	–	–	600	μA	–

Table 34. Fixed SPI AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID240	F _{SPI}	SPI operating frequency (master; 6X oversampling)	–	–	8	MHz	–

Table 35. Fixed SPI Master Mode AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID241	T _{DMO}	MOSI valid after Sclock driving edge	–	–	18	ns	–
SID242	T _{DSI}	MISO valid before Sclock capturing edge. Full clock, late MISO sampling used	20	–	–	ns	Full clock, late MISO sampling
SID243	T _{HMO}	Previous MOSI data hold time	0	–	–	ns	Referred to Slave capturing edge

Table 36. Fixed SPI Slave Mode AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID244	T _{DMI}	MOSI valid before Sclock capturing edge	40	–	–	ns	–
SID245	T _{DSO}	MISO valid after Sclock driving edge	–	–	42 + 3 × T _{CPU}	ns	–
SID246	T _{DSO_ext}	MISO valid after Sclock driving edge in external clock mode	–	–	53	ns	V _{DD} < 3.0 V
SID247	T _{HSO}	Previous MISO data hold time	0	–	–	ns	–
SID248	T _{SSELSCK}	SSEL valid to first SCK valid edge	100	–	–	ns	–

Memory

Table 37. Flash DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID249	V _{PE}	Erase and program voltage	1.71	–	5.5	V	–
SID309	T _{WS48}	Number of Wait states at 32–48 MHz	2	–	–		CPU execution from flash
SID310	T _{WS32}	Number of Wait states at 16–32 MHz	1	–	–		CPU execution from flash
SID311	T _{WS16}	Number of Wait states for 0–16 MHz	0	–	–		CPU execution from flash

Table 38. Flash AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID250	$T_{\text{ROWWRITE}}^{[5]}$	Row (block) write time (erase and program)	–	–	20	ms	Row (block) = 128 bytes for 128 KB flash devices Row (block) = 256 bytes for 256 KB flash devices
SID251	$T_{\text{ROWERASE}}^{[5]}$	Row erase time	–	–	13	ms	–
SID252	$T_{\text{ROWPROGRAM}}^{[5]}$	Row program time after erase	–	–	7	ms	–
SID253	$T_{\text{BULKERASE}}^{[5]}$	Bulk erase time (256 KB)	–	–	35	ms	–
SID254	$T_{\text{DEVPROG}}^{[5]}$	Total device program time	–	–	50	seconds	256 KB
SID254A			–	–	25		128 KB
SID255	F_{END}	Flash endurance	100 K	–	–	cycles	–
SID256	F_{RET}	Flash retention. $T_A \leq 55^\circ\text{C}$, 100 K P/E cycles	20	–	–	years	–
SID257	F_{RET2}	Flash retention. $T_A \leq 85^\circ\text{C}$, 10 K P/E cycles	10	–	–	years	–

System Resources

Power-on-Reset (POR)

Table 39. POR DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID258	V_{RISEIPOR}	Rising trip voltage	0.80	–	1.45	V	–
SID259	V_{FALLIPOR}	Falling trip voltage	0.75	–	1.40	V	–
SID260	V_{IPORHYST}	Hysteresis	15	–	200	mV	–

Table 40. POR AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID264	$T_{\text{PPOR_TR}}$	PPOR response time in Active and Sleep modes	–	–	1	μs	–

Table 41. Brown-Out Detect

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID261	V_{FALLPPOR}	BOD trip voltage in Active and Sleep modes	1.64	–	–	V	–
SID262	$V_{\text{FALLDPSLP}}$	BOD trip voltage in Deep Sleep mode	1.4	–	–	V	–

Table 42. Hibernate Reset

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID263	V_{HBRTRIP}	BOD trip voltage in Hibernate mode	1.1	–	–	V	–

Note

- It can take as much as 20 milliseconds to write to flash. During this time, the device should not be reset, or flash operations will be interrupted and cannot be relied on to have completed. Reset sources include the XRES pin, software resets, CPU lockup states and privilege violations, improper power supply levels, and watchdogs. Make certain that these are not inadvertently activated.

Voltage Monitors

Table 43. Voltage Monitor DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID265	V _{LVI1}	LVI_A/D_SEL[3:0] = 0000b	1.71	1.75	1.79	V	–
SID266	V _{LVI2}	LVI_A/D_SEL[3:0] = 0001b	1.76	1.80	1.85	V	–
SID267	V _{LVI3}	LVI_A/D_SEL[3:0] = 0010b	1.85	1.90	1.95	V	–
SID268	V _{LVI4}	LVI_A/D_SEL[3:0] = 0011b	1.95	2.00	2.05	V	–
SID269	V _{LVI5}	LVI_A/D_SEL[3:0] = 0100b	2.05	2.10	2.15	V	–
SID270	V _{LVI6}	LVI_A/D_SEL[3:0] = 0101b	2.15	2.20	2.26	V	–
SID271	V _{LVI7}	LVI_A/D_SEL[3:0] = 0110b	2.24	2.30	2.36	V	–
SID272	V _{LVI8}	LVI_A/D_SEL[3:0] = 0111b	2.34	2.40	2.46	V	–
SID273	V _{LVI9}	LVI_A/D_SEL[3:0] = 1000b	2.44	2.50	2.56	V	–
SID274	V _{LVI10}	LVI_A/D_SEL[3:0] = 1001b	2.54	2.60	2.67	V	–
SID2705	V _{LVI11}	LVI_A/D_SEL[3:0] = 1010b	2.63	2.70	2.77	V	–
SID276	V _{LVI12}	LVI_A/D_SEL[3:0] = 1011b	2.73	2.80	2.87	V	–
SID277	V _{LVI13}	LVI_A/D_SEL[3:0] = 1100b	2.83	2.90	2.97	V	–
SID278	V _{LVI14}	LVI_A/D_SEL[3:0] = 1101b	2.93	3.00	3.08	V	–
SID279	V _{LVI15}	LVI_A/D_SEL[3:0] = 1110b	3.12	3.20	3.28	V	–
SID280	V _{LVI16}	LVI_A/D_SEL[3:0] = 1111b	4.39	4.50	4.61	V	–
SID281	LVI_IDD	Block current	–	–	100	μA	–

Table 44. Voltage Monitor AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID282	T _{MONTRIP}	Voltage monitor trip time	–	–	1	μs	–

SWD Interface

Table 45. SWD Interface Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID283	F _{SWDCLK1}	$3.3\text{ V} \leq V_{DD} \leq 5.5\text{ V}$	–	–	14	MHz	SWDCLK ≤ 1/3 CPU clock frequency
SID284	F _{SWDCLK2}	$1.71\text{ V} \leq V_{DD} \leq 3.3\text{ V}$	–	–	7	MHz	SWDCLK ≤ 1/3 CPU clock frequency
SID285	T _{SWDI_SETUP}	T = 1/f SWDCLK	0.25 × T	–	–	ns	–
SID286	T _{SWDI_HOLD}	T = 1/f SWDCLK	0.25 × T	–	–	ns	–
SID287	T _{SWDO_VALID}	T = 1/f SWDCLK	–	–	0.5 × T	ns	–
SID288	T _{SWDO_HOLD}	T = 1/f SWDCLK	1	–	–	ns	–

Internal Main Oscillator

Table 46. IMO DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID289	I _{IMO1}	IMO operating current at 48 MHz	–	–	1000	μA	–
SID290	I _{IMO2}	IMO operating current at 24 MHz	–	–	325	μA	–
SID291	I _{IMO3}	IMO operating current at 12 MHz	–	–	225	μA	–
SID292	I _{IMO4}	IMO operating current at 6 MHz	–	–	180	μA	–
SID293	I _{IMO5}	IMO operating current at 3 MHz	–	–	150	μA	–

Table 47. IMO AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID296	F _{IMOTOL3}	Frequency variation from 3 to 48 MHz	–	–	±2	%	With API-called calibration
SID297	F _{IMOTOL3}	IMO startup time	–	–	12	µs	–

Internal Low-Speed Oscillator
Table 48. ILO DC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID298	I _{ILO2}	ILO operating current at 32 kHz	–	0.3	1.05	µA	–

Table 49. ILO AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID299	T _{STARTILO1}	ILO startup time	–	–	2	ms	–
SID300	F _{ILOTRIM1}	32-kHz trimmed frequency	15	32	50	kHz	–

Table 50. External Clock Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
SID301	ExtClkFreq	External clock input frequency	0	–	48	MHz	CMOS input level only
SID302	ExtClkDuty	Duty cycle; Measured at V _{DD/2}	45	–	55	%	CMOS input level only

Table 51. UDB AC Specifications

Spec ID	Parameter	Description	Min	Typ	Max	Units	Details/Conditions
Data Path performance							
SID303	F _{MAX-TIMER}	Max frequency of 16-bit timer in a UDB pair	–	–	48	MHz	–
SID304	F _{MAX-ADDER}	Max frequency of 16-bit adder in a UDB pair	–	–	48	MHz	–
SID305	F _{MAX_CRC}	Max frequency of 16-bit CRC/PRS in a UDB pair	–	–	48	MHz	–
PLD Performance in UDB							
SID306	F _{MAX_PLD}	Max frequency of 2-pass PLD function in a UDB pair	–	–	48	MHz	–
Clock to Output Performance							
SID307	T _{CLK_OUT_UBD1}	Prop. delay for clock in to data out at 25 °C, Typical	–	15	–	ns	–
SID308	T _{CLK_OUT_UBD2}	Prop. delay for clock in to data out, Worst case	–	25	–	ns	–

Table 52. BLE Subsystem

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
RF Receiver Specification							
SID340	RXS, IDLE	RX sensitivity with idle transmitter	–	–89	–	dBm	–
SID340A		RX sensitivity with idle transmitter excluding Balun loss	–	–91	–	dBm	Guaranteed by design simulation
SID341	RXS, DIRTY	RX sensitivity with dirty transmitter	–	–87	–70	dBm	RF-PHY Specification (RCV-LE/CA/01/C)
SID342	RXS, HIGHGAIN	RX sensitivity in high-gain mode with idle transmitter	–	–91	–	dBm	–
SID343	PRXMAX	Maximum input power	–10	–1	–	dBm	RF-PHY Specification (RCV-LE/CA/06/C)
SID344	CI1	Co-channel interference, Wanted signal at –67 dBm and Interferer at FRX	–	9	21	dB	RF-PHY Specification (RCV-LE/CA/03/C)
SID345	CI2	Adjacent channel interference Wanted signal at –67 dBm and Interferer at FRX ±1 MHz	–	3	15	dB	RF-PHY Specification (RCV-LE/CA/03/C)
SID346	CI3	Adjacent channel interference Wanted signal at –67 dBm and Interferer at FRX ±2 MHz	–	–29	–	dB	RF-PHY Specification (RCV-LE/CA/03/C)
SID347	CI4	Adjacent channel interference Wanted signal at –67 dBm and Interferer at ≥FRX ±3 MHz	–	–39	–	dB	RF-PHY Specification (RCV-LE/CA/03/C)
SID348	CI5	Adjacent channel interference Wanted Signal at –67 dBm and Interferer at Image frequency (F_{IMAGE})	–	–20	–	dB	RF-PHY Specification (RCV-LE/CA/03/C)
SID349	CI6	Adjacent channel interference Wanted signal at –67 dBm and Interferer at Image frequency ($F_{\text{IMAGE}} \pm 1$ MHz)	–	–30	–	dB	RF-PHY Specification (RCV-LE/CA/03/C)
SID350	OBB1	Out-of-band blocking, Wanted signal at –67 dBm and Interferer at F = 30–2000 MHz	–30	–27	–	dBm	RF-PHY Specification (RCV-LE/CA/04/C)
SID351	OBB2	Out-of-band blocking, Wanted signal at –67 dBm and Interferer at F = 2003–2399 MHz	–35	–27	–	dBm	RF-PHY Specification (RCV-LE/CA/04/C)
SID352	OBB3	Out-of-band blocking, Wanted signal at –67 dBm and Interferer at F = 2484–2997 MHz	–35	–27	–	dBm	RF-PHY Specification (RCV-LE/CA/04/C)
SID353	OBB4	Out-of-band blocking, Wanted signal a –67 dBm and Interferer at F = 3000–12750 MHz	–30	–27	–	dBm	RF-PHY Specification (RCV-LE/CA/04/C)
SID354	IMD	Intermodulation performance Wanted signal at –64 dBm and 1-Mbps BLE, third, fourth, and fifth offset channel	–50	–	–	dBm	RF-PHY Specification (RCV-LE/CA/05/C)
SID355	RXSE1	Receiver spurious emission 30 MHz to 1.0 GHz	–	–	–57	dBm	100-kHz measurement bandwidth ETSI EN300 328 V1.8.1

Table 52. BLE Subsystem (continued)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID356	RXSE2	Receiver spurious emission 1.0 GHz to 12.75 GHz	–	–	–47	dBm	1-MHz measurement bandwidth ETSI EN300 328 V1.8.1
RF Transmitter Specifications							
SID357	TXP, ACC	RF power accuracy	–	±1	–	dB	–
SID358	TXP, RANGE	RF power control range	–	20	–	dB	–
SID359	TXP, 0dBm	Output power, 0-dB Gain setting (PA7)	–	0	–	dBm	–
SID360	TXP, MAX	Output power, maximum power setting (PA10)	–	3	–	dBm	–
SID361	TXP, MIN	Output power, minimum power setting (PA1)	–	–18	–	dBm	–
SID362	F2AVG	Average frequency deviation for 10101010 pattern	185	–	–	kHz	RF-PHY Specification (TRM-LE/CA/05/C)
SID363	F1AVG	Average frequency deviation for 11110000 pattern	225	250	275	kHz	RF-PHY Specification (TRM-LE/CA/05/C)
SID364	EO	Eye opening = $\Delta F2AVG/\Delta F1AVG$	0.8	–	–		RF-PHY Specification (TRM-LE/CA/05/C)
SID365	FTX, ACC	Frequency accuracy	–150	–	150	kHz	RF-PHY Specification (TRM-LE/CA/06/C)
SID366	FTX, MAXDR	Maximum frequency drift	–50	–	50	kHz	RF-PHY Specification (TRM-LE/CA/06/C)
SID367	FTX, INITDR	Initial frequency drift	–20	–	20	kHz	RF-PHY Specification (TRM-LE/CA/06/C)
SID368	FTX, DR	Maximum drift rate	–20	–	20	kHz/ 50 μ s	RF-PHY Specification (TRM-LE/CA/06/C)
SID369	IBSE1	In-band spurious emission at 2-MHz offset	–	–	–20	dBm	RF-PHY Specification (TRM-LE/CA/03/C)
SID370	IBSE2	In-band spurious emission at ≥ 3 -MHz offset	–	–	–30	dBm	RF-PHY Specification (TRM-LE/CA/03/C)
SID371	TXSE1	Transmitter spurious emissions (average), <1.0 GHz	–	–	–55.5	dBm	FCC-15.247
SID372	TXSE2	Transmitter spurious emissions (average), >1.0 GHz	–	–	–41.5	dBm	FCC-15.247
RF Current Specifications							
SID373	IRX	Receive current in normal mode	–	18.7	–	mA	–
SID373A	IRX_RF	Radio receive current in normal mode	–	16.4	–	mA	Measured at V_{DDR}
SID374	IRX, HIGHGAIN	Receive current in high-gain mode	–	21.5	–	mA	–
SID375	ITX, 3dBm	TX current at 3-dBm setting (PA10)	–	20	–	mA	–
SID376	ITX, 0dBm	TX current at 0-dBm setting (PA7)	–	16.5	–	mA	–
SID376A	ITX_RF, 0dBm	Radio TX current at 0 dBm setting (PA7)	–	15.6	–	mA	Measured at V_{DDR}
SID376B	ITX_RF, 0dBm	Radio TX current at 0 dBm excluding Balun loss	–	14.2	–	mA	Guaranteed by design simulation
SID377	ITX, –3dBm	TX current at –3-dBm setting (PA4)	–	15.5	–	mA	–

Table 52. BLE Subsystem (continued)

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID378	ITX,-6dBm	TX current at -6-dBm setting (PA3)	–	14.5	–	mA	–
SID379	ITX,-12dBm	TX current at -12-dBm setting (PA2)	–	13.2	–	mA	–
SID380	ITX,-18dBm	TX current at -18-dBm setting (PA1)	–	12.5	–	mA	–
SID380A	Iavg_1sec, 0dBm	Average current at 1-second BLE connection interval	–	17.1	–	μA	TXP: 0 dBm; ±20-ppm master and slave clock accuracy.
SID380B	Iavg_4sec, 0dBm	Average current at 4-second BLE connection interval	–	6.1	–	μA	TXP: 0 dBm; ±20-ppm master and slave clock accuracy.
General RF Specifications							
SID381	FREQ	RF operating frequency	2400	–	2482	MHz	–
SID382	CHBW	Channel spacing	–	2	–	MHz	–
SID383	DR	On-air data rate	–	1000	–	kbps	–
SID384	IDLE2TX	BLE.IDLE to BLE. TX transition time	–	120	140	μs	–
SID385	IDLE2RX	BLE.IDLE to BLE. RX transition time	–	75	120	μs	–
RSSI Specifications							
SID386	RSSI, ACC	RSSI accuracy	–	±5	–	dB	–
SID387	RSSI, RES	RSSI resolution	–	1	–	dB	–
SID388	RSSI, PER	RSSI sample period	–	6	–	μs	–

Table 53. ECO Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID389	F _{ECO}	Crystal frequency	–	24	–	MHz	–
SID390	F _{TOL}	Frequency tolerance	–50	–	50	ppm	–
SID391	ESR	Equivalent series resistance	–	–	60	Ω	–
SID392	PD	Drive level	–	–	100	μW	–
SID393	T _{START1}	Startup time (Fast Charge on)	–	–	850	μs	–
SID394	T _{START2}	Startup time (Fast Charge off)	–	–	3	ms	–
SID395	C _L	Load capacitance	–	8	–	pF	–
SID396	C ₀	Shunt capacitance	–	1.1	–	pF	–
SID397	I _{ECO}	Operating current	–	1400	–	μA	–

Table 54. WCO Specifications

Spec ID#	Parameter	Description	Min	Typ	Max	Units	Details/ Conditions
SID398	F_{WCO}	Crystal frequency	–	32.768	–	kHz	–
SID399	FTOL	Frequency tolerance	–	50	–	ppm	–
SID400	ESR	Equivalent series resistance	–	50	–	k Ω	–
SID401	PD	Drive level	–	–	1	μ W	–
SID402	T_{START}	Startup time	–	–	500	ms	–
SID403	C_L	Crystal load capacitance	6	–	12.5	pF	–
SID404	C0	Crystal shunt capacitance	–	1.35	–	pF	–
SID405	I_{WCO1}	Operating current (High-Power mode)	–	–	8	μ A	–
SID406	I_{WCO2}	Operating current (Low-Power mode)	–	–	2.6	μ A	–

Ordering Information

The PSoC 4200_BLE part numbers and features are listed in [Table 55](#).

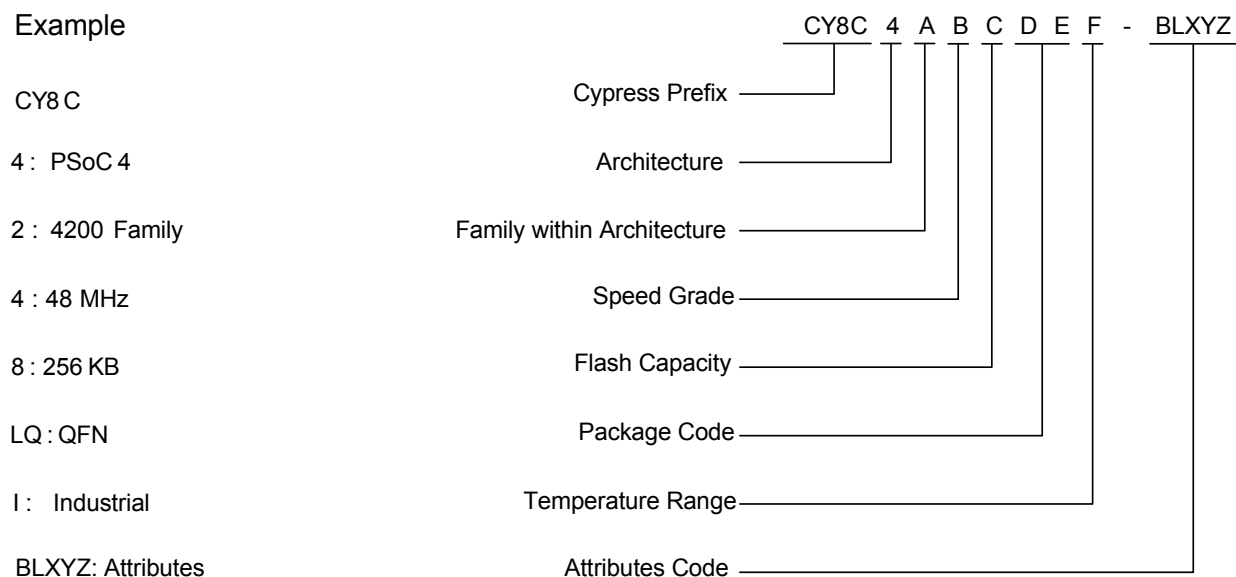
Table 55. PSoC 4200_BLE Part Numbers

Product Family	MPN	Max CPU Speed (MHz)	BLE subsystem	Flash (KB)	SRAM (KB)	UDB	Opamp	CapSense	TMG (Gestures)	Direct LCD Drive	12-bit SAR ADC	DMA	LP Comparators	TCPWM Blocks	SCB Blocks	GPIO	Package	Temperature Range
PSoC 4200_BLE	CY8C4247LQI-BL473	48	4.1	128	16	4	4	–	–	–	1 Msps	–	2	4	2	36	QFN	85 °C
	CY8C4247FNI-BL473	48	4.1	128	16	4	4	–	–	–	1 Msps	–	2	4	2	36	CSP	85 °C
	CY8C4247LQI-BL453	48	4.1	128	16	4	4	1	–	–	1 Msps	–	2	4	2	36	QFN	85 °C
	CY8C4247LQI-BL463	48	4.1	128	16	4	4	–	–	1	1 Msps	–	2	4	2	36	QFN	85 °C
	CY8C4247LQI-BL483	48	4.1	128	16	4	4	1	–	1	1 Msps	–	2	4	2	36	QFN	85 °C
	CY8C4247LQI-BL493	48	4.1	128	16	4	4	1	1	1	1 Msps	–	2	4	2	36	QFN	85 °C
	CY8C4247FNI-BL483	48	4.1	128	16	4	4	1	–	1	1 Msps	–	2	4	2	36	68-CSP	85 °C
	CY8C4247FNI-BL493	48	4.1	128	16	4	4	1	1	1	1 Msps	–	2	4	2	36	68-CSP	85 °C
	CY8C4247FNQ-BL483	48	4.1	128	16	4	4	1	–	1	1 Msps	–	2	4	2	36	68-CSP	105 °C
	CY8C4247LQQ-BL483	48	4.1	128	16	4	4	1	–	1	1 Msps	–	2	4	2	36	QFN	105 °C
	CY8C4247FLI-BL493	48	4.1	128	16	4	4	1	1	1	1 Msps	–	2	4	2	36	Thin 68-CSP	85 °C
	CY8C4248LQI-BL473	48	4.1	256	32	4	4	–	–	–	1 Msps	1	2	4	2	36	QFN	85 °C
	CY8C4248LQI-BL453	48	4.1	256	32	4	4	1	–	–	1 Msps	1	2	4	2	36	QFN	85 °C
	CY8C4248LQI-BL483	48	4.1	256	32	4	4	1	–	1	1 Msps	1	2	4	2	36	QFN	85 °C
	CY8C4248FNI-BL483	48	4.1	256	32	4	4	1	–	1	1 Msps	1	2	4	2	36	76-CSP	85 °C
	CY8C4248FLI-BL483	48	4.1	256	32	4	4	1	–	1	1 Msps	1	2	4	2	36	Thin 76-CSP	85 °C
	CY8C4248LQI-BL543	48	4.2	256	32	–	2	–	–	–	1 Msps	1	–	4	2	36	QFN	85 °C
	CY8C4248FNI-BL543	48	4.2	256	32	–	2	–	–	–	1 Msps	1	–	4	2	36	76-CSP	85 °C
	CY8C4248LQI-BL573	48	4.2	256	32	4	4	–	–	–	1 Msps	1	2	4	2	36	QFN	85 °C
	CY8C4248FNI-BL573	48	4.2	256	32	4	4	–	–	–	1 Msps	1	2	4	2	36	76-CSP	85 °C
	CY8C4248LQI-BL553	48	4.2	256	32	4	4	1	–	–	1 Msps	1	2	4	2	36	QFN	85 °C
	CY8C4248FNI-BL553	48	4.2	256	32	4	4	1	–	–	1 Msps	1	2	4	2	36	76-CSP	85 °C
	CY8C4248LQI-BL563	48	4.2	256	32	4	4	–	–	1	1 Msps	1	2	4	2	36	QFN	85 °C
	CY8C4248FNI-BL563	48	4.2	256	32	4	4	–	–	1	1 Msps	1	2	4	2	36	76-CSP	85 °C
	CY8C4248LQI-BL583	48	4.2	256	32	4	4	1	–	1	1 Msps	1	2	4	2	36	QFN	85 °C
	CY8C4248FNI-BL583	48	4.2	256	32	4	4	1	–	1	1 Msps	1	2	4	2	36	76-CSP	85 °C
	CY8C4248FLI-BL583	48	4.2	256	32	4	4	1	–	1	1 Msps	1	2	4	2	36	Thin 76-CSP	85 °C
	CY8C4248LQQ-BL583	48	4.2	256	32	4	4	1	–	1	1 Msps	1	2	4	2	36	QFN	105 °C
	CY8C4248FNQ-BL583	48	4.2	256	32	4	4	1	–	1	1 Msps	1	2	4	2	36	76-CSP	105 °C
	CY8C4248LQI-BL593	48	4.2	256	32	4	4	1	1	1	1 Msps	1	2	4	2	36	QFN	85 °C
	CY8C4248FNI-BL593	48	4.2	256	32	4	4	1	1	1	1 Msps	1	2	4	2	36	76-CSP	85 °C

PSoC 4 devices follow the part numbering convention described in the following table. All fields are single-character alphanumeric (0, 1, 2, ..., 9, A,B, ..., Z) unless stated otherwise.

Ordering Code Definitions

Example



The Field Values are listed in the following table:

Field	Description	Values	Meaning
CY8C	Cypress Prefix		
4	Architecture	4	PSoC 4
A	Family within architecture	2	4200-BLE Family
B	CPU Speed	4	48 MHz
C	Flash Capacity	8, 7	256, 128 KB respectively
DE	Package Code	FN	WLCSP
		LQ	QFN
		FL	Thin CSP
F	Temperature Range	I	Industrial
BLXYZ	Attributes Code	BL400-BL499	Bluetooth 4.1 compliant
		BL500-BL599	Bluetooth 4.2 compliant

Packaging

Table 56. Package Characteristics

Parameter	Description	Conditions	Min	Typ	Max	Units
T _A	Operating ambient temperature	–	–40	25.00	105	°C
T _J	Operating junction temperature	–	–40	–	125	°C
T _{JA}	Package θ_{JA} (56-pin QFN)	–	–	16.9	–	°C/watt
T _{JC}	Package θ_{JC} (56-pin QFN)	–	–	9.7	–	°C/watt
T _{JA}	Package θ_{JA} (76-ball WLCSP)	–	–	20.1	–	°C/watt
T _{JC}	Package θ_{JC} (76-ball WLCSP)	–	–	0.19	–	°C/watt
T _{JA}	Package θ_{JA} (76-ball Thin WLCSP)	–	–	20.9	–	°C/watt
T _{JC}	Package θ_{JC} (76-ball Thin WLCSP)	–	–	0.17	–	°C/watt
T _{JA}	Package θ_{JA} (68-ball WLCSP)	–	–	16.6	–	°C/watt
T _{JC}	Package θ_{JC} (68-ball WLCSP)	–	–	0.19	–	°C/watt
T _{JA}	Package θ_{JA} (68-ball Thin WLCSP)	–	–	16.6	–	°C/watt
T _{JC}	Package θ_{JC} (68-ball Thin WLCSP)	–	–	0.19	–	°C/watt

Table 57. Solder Reflow Peak Temperature

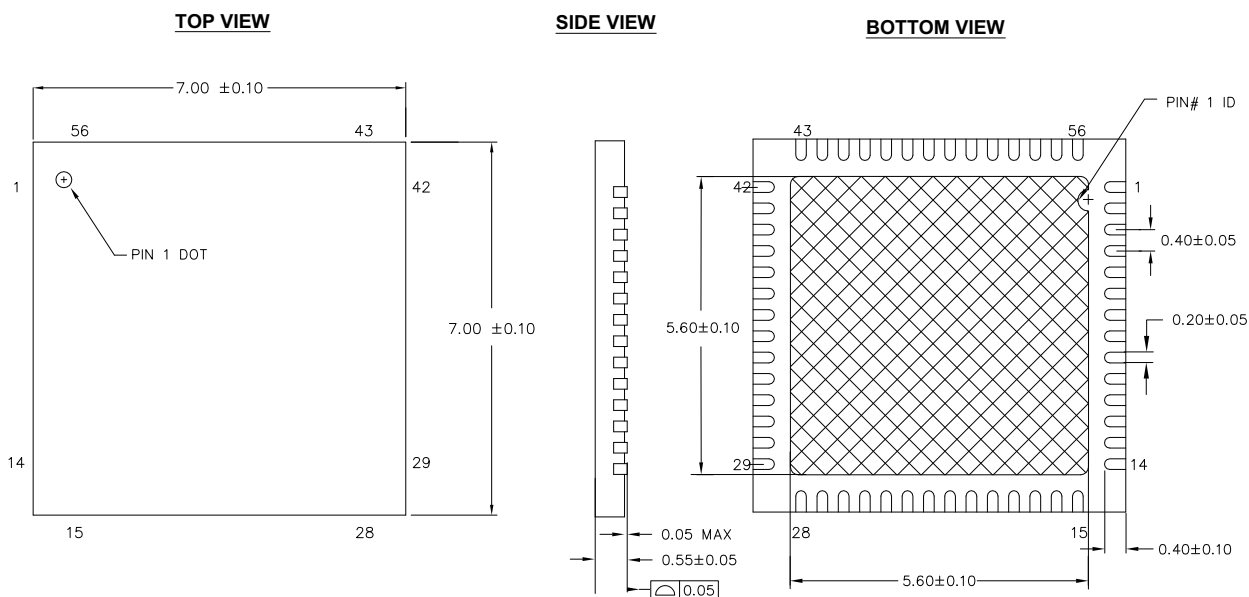
Package	Maximum Peak Temperature	Maximum Time at Peak Temperature
All packages	260 °C	30 seconds

Table 58. Package Moisture Sensitivity Level (MSL), IPC/JEDEC J-STD-2

Package	MSL
56-pin QFN	MSL 3
All WLCSP packages	MSL 1

Table 59. Package Details

Spec ID	Package	Description
001-58740 Rev. *C	56-pin QFN	7.0 mm × 7.0 mm × 0.6 mm
001-96603 Rev. *A	76-ball WLCSP	4.04 mm × 3.87 mm × 0.55 mm
002-10658, Rev. **	76-ball thin WLCSP	4.04 mm × 3.87 mm × 0.4 mm
001-92343 Rev. *A	68-ball WLCSP	3.52 mm × 3.91 mm × 0.55 mm
001-99408 Rev **	68-ball Thin WLCSP	52 mm × 3.91 mm × 0.4 mm

Figure 8. 56-Pin QFN 7 × 7 × 0.6 mm

NOTES:

1.  HATCH AREA IS SOLDERABLE EXPOSED PAD
2. BASED ON REF JEDEC # MO-248
3. ALL DIMENSIONS ARE IN MILLIMETERS

001-58740 °C

The center pad on the QFN package should be connected to ground (VSS) for best mechanical, thermal, and electrical performance.

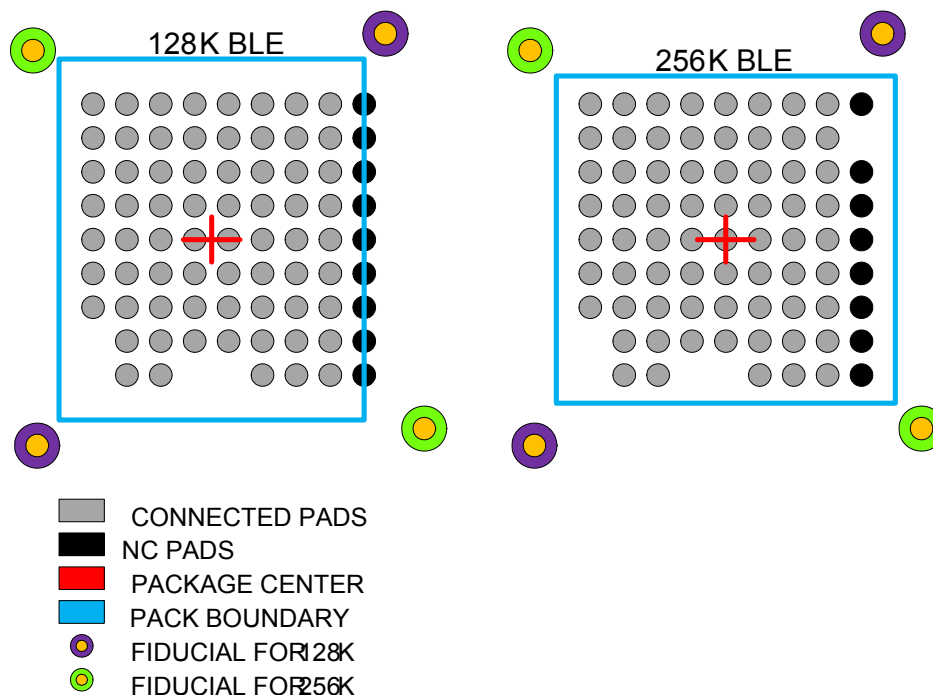
WLCSP Compatibility

The PSoC 4XXX_BLE family has products with 128 KB (16KB SRAM) and 256 KB (32KB SRAM) Flash. Package pin-outs and sizes are identical for the 56-pin QFN package but are different in one dimension for the 68-ball WLCSP.

The 256KB Flash product has an extra column of balls which are required for mechanical integrity purposes in the Chip-Scale package. With consideration for this difference, the land pattern on the PCB may be designed such that either product may be used with no change to the PCB design.

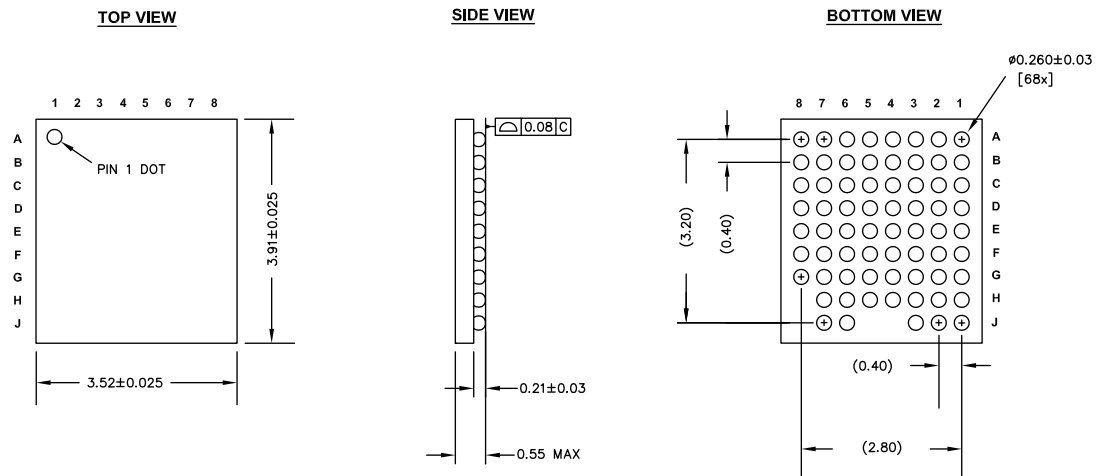
Figure 9 shows the 128KB and 256 KB Flash CSP packages.

Figure 9. 128KB and 256 KB Flash CSP Packages



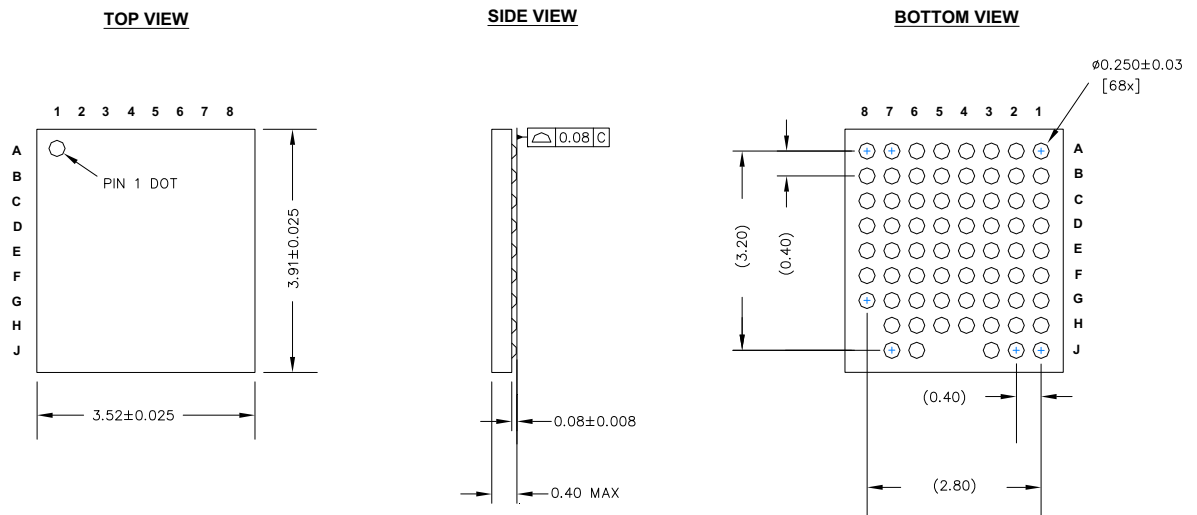
The rightmost column of (all NC, No Connect) balls in the 256K BLE WLCSP is for mechanical integrity purposes. The package is thus wider (3.2 mm versus 2.8 mm). All other dimensions are identical. Cypress will provide layout symbols for PCB layout.

The scheme in Figure 9 is implemented to design the PCB for the 256K BLE package with the appropriate space requirements thus allowing use of either package at a later time without redesigning the Printed Circuit Board.

Figure 10. 68-Ball WLCSP Package Outline

NOTES:

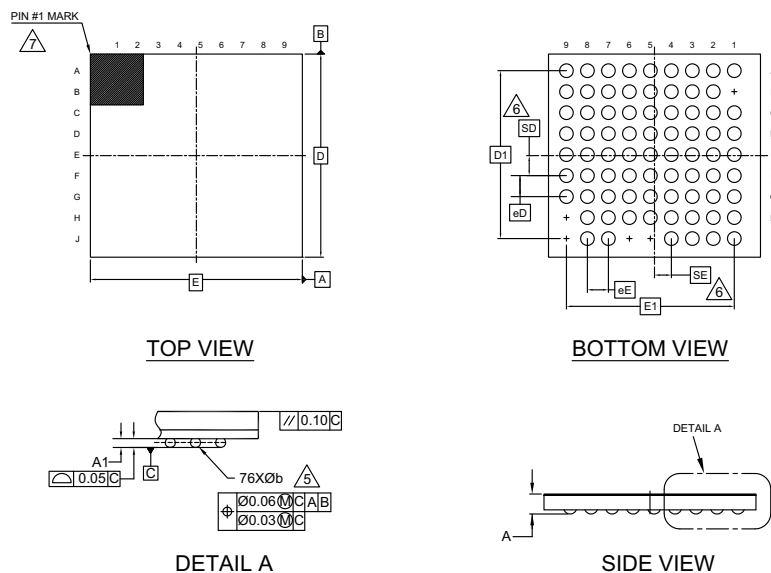
1. REFERENCE JEDEC PUBLICATION 95, DESIGN GUIDE 4.18
2. ALL DIMENSIONS ARE IN MILLIMETERS

001-92343 *A

Figure 11. 68-Ball Thin WLCSP

NOTES:

1. REFERENCE JEDEC PUBLICATION 95, DESIGN GUIDE 4.18
2. ALL DIMENSIONS ARE IN MILLIMETERS

001-99408 **

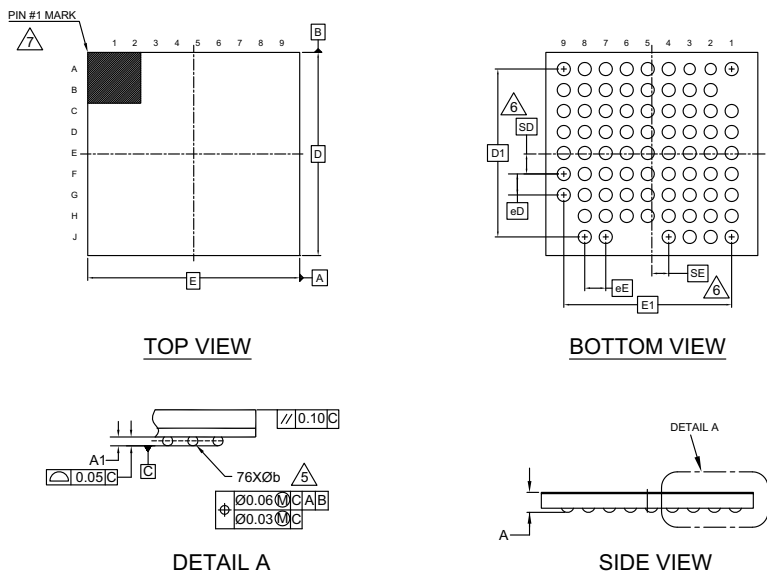
Figure 12. 76-Ball WLCSP Package Outline


SYMBOL	DIMENSIONS		
	MIN.	NOM.	MAX.
A	-	-	0.55
A1	0.18	0.21	0.24
D	3.87 BSC		
E	4.04 BSC		
D1	3.20 BSC		
E1	3.20 BSC		
MD	9		
ME	9		
N	76		
Ø b	0.23	0.26	0.29
eD	0.40 BSC		
eE	0.40 BSC		
SD	0.381 BSC		
SE	0.321 BSC		

NOTES:

- ALL DIMENSIONS ARE IN MILLIMETERS.
- SOLDER BALL POSITION DESIGNATION PER JEP95, SECTION 3, SPP-020.
- "e" REPRESENTS THE SOLDER BALL GRID PITCH.
- SYMBOL "MD" IS THE BALL MATRIX SIZE IN THE "D" DIRECTION.
SYMBOL "ME" IS THE BALL MATRIX SIZE IN THE "E" DIRECTION.
N IS THE NUMBER OF POPULATED SOLDER BALL POSITIONS FOR MATRIX SIZE MD X ME.
- DIMENSION "b" IS MEASURED AT THE MAXIMUM BALL DIAMETER IN A PLANE PARALLEL TO DATUM C.
- "SD" AND "SE" ARE MEASURED WITH RESPECT TO DATUMS A AND B AND DEFINE THE POSITION OF THE CENTER SOLDER BALL IN THE OUTER ROW. WHEN THERE IS AN ODD NUMBER OF SOLDER BALLS IN THE OUTER ROW, "SD" OR "SE" = 0.
WHEN THERE IS AN EVEN NUMBER OF SOLDER BALLS IN THE OUTER ROW, "SD" = eD/2 AND "SE" = eE/2.
- A1 CORNER TO BE IDENTIFIED BY CHAMFER, LASER OR INK MARK METALIZED MARK, INDENTATION OR OTHER MEANS.
- "+" INDICATES THE THEORETICAL CENTER OF DEPOPULATED SOLDER BALLS.
- JEDEC SPECIFICATION NO. REF : N/A

001-96603 *B

Figure 13. 76-Ball Thin WLCSP Package Outline


SYMBOL	DIMENSIONS		
	MIN.	NOM.	MAX.
A	-	-	0.40
A1	0.072	0.08	0.088
D	3.87 BSC		
E	4.04 BSC		
D1	3.20 BSC		
E1	3.20 BSC		
MD	9		
ME	9		
N	76		
Ø b	0.22	0.25	0.28
eD	0.40 BSC		
eE	0.40 BSC		
SD	0.381		
SE	0.321		

NOTES:

- ALL DIMENSIONS ARE IN MILLIMETERS.
- SOLDER BALL POSITION DESIGNATION PER JEP95, SECTION 3, SPP-020.
- "e" REPRESENTS THE SOLDER BALL GRID PITCH.
- SYMBOL "MD" IS THE BALL MATRIX SIZE IN THE "D" DIRECTION. SYMBOL "ME" IS THE BALL MATRIX SIZE IN THE "E" DIRECTION. N IS THE NUMBER OF POPULATED SOLDER BALL POSITIONS FOR MATRIX SIZE MD X ME.
- DIMENSION "b" IS MEASURED AT THE MAXIMUM BALL DIAMETER IN A PLANE PARALLEL TO DATUM C.
- "SD" AND "SE" ARE MEASURED WITH RESPECT TO DATUMS A AND B AND DEFINE THE POSITION OF THE CENTER SOLDER BALL IN THE OUTER ROW. WHEN THERE IS AN ODD NUMBER OF SOLDER BALLS IN THE OUTER ROW, "SD" OR "SE" = 0. WHEN THERE IS AN EVEN NUMBER OF SOLDER BALLS IN THE OUTER ROW, "SD" = eD/2 AND "SE" = eE/2.
- A1 CORNER TO BE IDENTIFIED BY CHAMFER, LASER OR INK MARK METALIZED MARK, INDENTATION OR OTHER MEANS.
- "+" INDICATES THE THEORETICAL CENTER OF DEPOPULATED SOLDER BALLS.

002-10658 **

Acronyms

Table 60. Acronyms Used in this Document

Acronym	Description
abus	analog local bus
ADC	analog-to-digital converter
AG	analog global
AHB	AMBA (advanced microcontroller bus architecture) high-performance bus, an Arm data transfer bus
ALU	arithmetic logic unit
AMUXBUS	analog multiplexer bus
API	application programming interface
APSR	application program status register
Arm®	advanced RISC machine, a CPU architecture
ATM	automatic thump mode
BW	bandwidth
CAN	Controller Area Network, a communications protocol
CMRR	common-mode rejection ratio
CPU	central processing unit
CRC	cyclic redundancy check, an error-checking protocol
DAC	digital-to-analog converter, see also IDAC, VDAC
DFB	digital filter block
DIO	digital input/output, GPIO with only digital capabilities, no analog. See GPIO.
DMIPS	Dhrystone million instructions per second
DMA	direct memory access, see also TD
DNL	differential nonlinearity, see also INL
DNU	do not use
DR	port write data registers
DSI	digital system interconnect
DWT	data watchpoint and trace
ECC	error correcting code
ECO	external crystal oscillator
EEPROM	electrically erasable programmable read-only memory
EMI	electromagnetic interference
EMIF	external memory interface
EOC	end of conversion
EOF	end of frame
EPSR	execution program status register
ESD	electrostatic discharge

Table 60. Acronyms Used in this Document *(continued)*

Acronym	Description
ETM	embedded trace macrocell
FIR	finite impulse response, see also IIR
FPB	flash patch and breakpoint
FS	full-speed
GPIO	general-purpose input/output, applies to a PSoC pin
HVI	high-voltage interrupt, see also LVI, LVD
IC	integrated circuit
IDAC	current DAC, see also DAC, VDAC
IDE	integrated development environment
I ² C, or IIC	Inter-Integrated Circuit, a communications protocol
IIR	infinite impulse response, see also FIR
ILO	internal low-speed oscillator, see also IMO
IMO	internal main oscillator, see also ILO
INL	integral nonlinearity, see also DNL
I/O	input/output, see also GPIO, DIO, SIO, USBIO
IPOR	initial power-on reset
IPSR	interrupt program status register
IRQ	interrupt request
ITM	instrumentation trace macrocell
LCD	liquid crystal display
LIN	Local Interconnect Network, a communications protocol.
LR	link register
LUT	lookup table
LVD	low-voltage detect, see also LVI
LVI	low-voltage interrupt, see also HVI
LVTTTL	low-voltage transistor-transistor logic
MAC	multiply-accumulate
MCU	microcontroller unit
MISO	master-in slave-out
NC	no connect
NMI	nonmaskable interrupt
NRZ	non-return-to-zero
NVIC	nested vectored interrupt controller
NVL	nonvolatile latch, see also WOL
opamp	operational amplifier
PAL	programmable array logic, see also PLD

Table 60. Acronyms Used in this Document *(continued)*

Acronym	Description
PC	program counter
PCB	printed circuit board
PGA	programmable gain amplifier
PHUB	peripheral hub
PHY	physical layer
PICU	port interrupt control unit
PLA	programmable logic array
PLD	programmable logic device, see also PAL
PLL	phase-locked loop
PMDD	package material declaration data sheet
POR	power-on reset
PRES	precise power-on reset
PRS	pseudo random sequence
PS	port read data register
PSoC®	Programmable System-on-Chip™
PSRR	power supply rejection ratio
PWM	pulse-width modulator
RAM	random-access memory
RISC	reduced-instruction-set computing
RMS	root-mean-square
RTC	real-time clock
RTL	register transfer language
RTR	remote transmission request
RX	receive
SAR	successive approximation register
SC/CT	switched capacitor/continuous time
SCL	I ² C serial clock
SDA	I ² C serial data
S/H	sample and hold
SINAD	signal to noise and distortion ratio
SIO	special input/output, GPIO with advanced features. See GPIO.
SOC	start of conversion
SOF	start of frame
SPI	Serial Peripheral Interface, a communications protocol
SR	slew rate
SRAM	static random access memory
SRES	software reset
SWD	serial wire debug, a test protocol

Table 60. Acronyms Used in this Document *(continued)*

Acronym	Description
SWV	single-wire viewer
TD	transaction descriptor, see also DMA
THD	total harmonic distortion
TIA	transimpedance amplifier
TRM	technical reference manual
TTL	transistor-transistor logic
TX	transmit
UART	Universal Asynchronous Transmitter Receiver, a communications protocol
UDB	universal digital block
USB	Universal Serial Bus
USBIO	USB input/output, PSoC pins used to connect to a USB port
VDAC	voltage DAC, see also DAC, IDAC
WDT	watchdog timer
WOL	write once latch, see also NVL
WRES	watchdog timer reset
XRES	external reset I/O pin
XTAL	crystal

Document Conventions

Units of Measure

Table 61. Units of Measure

Symbol	Unit of Measure
°C	degrees Celsius
dB	decibel
fF	femto farad
Hz	hertz
KB	1024 bytes
kbps	kilobits per second
Khr	kilohour
kHz	kilohertz
kΩ	kilo ohm
ksps	kilosamples per second
LSB	least significant bit
Mbps	megabits per second
MHz	megahertz
MΩ	mega-ohm
Msps	megasamples per second
μA	microampere
μF	microfarad
μH	microhenry
μs	microsecond
μV	microvolt
μW	microwatt
mA	milliampere
ms	millisecond
mV	millivolt
nA	nanoampere
ns	nanosecond
nV	nanovolt
Ω	ohm
pF	picofarad
ppm	parts per million
ps	picosecond
s	second
sps	samples per second
sqrtHz	square root of hertz
V	volt

Revision History

Description Title: PSoC [®] 4: 4200_BLE Family Datasheet Programmable System-on-Chip (PSoC [®]) Document Number: 002-23053				
Revision	ECN	Orig. of Change	Submission Date	Description of Change
**	6078076	PMAD/ WKA	02/22/2018	New datasheet

Sales, Solutions, and Legal Information

Worldwide Sales and Design Support

Cypress maintains a worldwide network of offices, solution centers, manufacturer's representatives, and distributors. To find the office closest to you, visit us at [Cypress Locations](#).

Products

Arm® Cortex® Microcontrollers	cypress.com/arm
Automotive	cypress.com/automotive
Clocks & Buffers	cypress.com/clocks
Interface	cypress.com/interface
Internet of Things	cypress.com/iot
Memory	cypress.com/memory
Microcontrollers	cypress.com/mcu
PSoC	cypress.com/psoc
Power Management ICs	cypress.com/pmic
Touch Sensing	cypress.com/touch
USB Controllers	cypress.com/usb
Wireless Connectivity	cypress.com/wireless

PSoC® Solutions

[PSoC 1](#) | [PSoC 3](#) | [PSoC 4](#) | [PSoC 5LP](#) | [PSoC 6 MCU](#)

Cypress Developer Community

[Community](#) | [Projects](#) | [Video](#) | [Blogs](#) | [Training](#) | [Components](#)

Technical Support

cypress.com/support

© Cypress Semiconductor Corporation, 2018. This document is the property of Cypress Semiconductor Corporation and its subsidiaries, including Spansion LLC ("Cypress"). This document, including any software or firmware included or referenced in this document ("Software"), is owned by Cypress under the intellectual property laws and treaties of the United States and other countries worldwide. Cypress reserves all rights under such laws and treaties and does not, except as specifically stated in this paragraph, grant any license under its patents, copyrights, trademarks, or other intellectual property rights. If the Software is not accompanied by a license agreement and you do not otherwise have a written agreement with Cypress governing the use of the Software, then Cypress hereby grants you a personal, non-exclusive, nontransferable license (without the right to sublicense) (1) under its copyright rights in the Software (a) for Software provided in source code form, to modify and reproduce the Software solely for use with Cypress hardware products, only internally within your organization, and (b) to distribute the Software in binary code form externally to end users (either directly or indirectly through resellers and distributors), solely for use on Cypress hardware product units, and (2) under those claims of Cypress's patents that are infringed by the Software (as provided by Cypress, unmodified) to make, use, distribute, and import the Software solely for use with Cypress hardware products. Any other use, reproduction, modification, translation, or compilation of the Software is prohibited.

TO THE EXTENT PERMITTED BY APPLICABLE LAW, CYPRESS MAKES NO WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, WITH REGARD TO THIS DOCUMENT OR ANY SOFTWARE OR ACCOMPANYING HARDWARE, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY AND FITNESS FOR A PARTICULAR PURPOSE. No computing device can be absolutely secure. Therefore, despite security measures implemented in Cypress hardware or software products, Cypress does not assume any liability arising out of any security breach, such as unauthorized access to or use of a Cypress product. In addition, the products described in these materials may contain design defects or errors known as errata which may cause the product to deviate from published specifications. To the extent permitted by applicable law, Cypress reserves the right to make changes to this document without further notice. Cypress does not assume any liability arising out of the application or use of any product or circuit described in this document. Any information provided in this document, including any sample design information or programming code, is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Cypress products are not designed, intended, or authorized for use as critical components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or system could cause personal injury, death, or property damage ("Unintended Uses"). A critical component is any component of a device or system whose failure to perform can be reasonably expected to cause the failure of the device or system, or to affect its safety or effectiveness. Cypress is not liable, in whole or in part, and you shall and hereby do release Cypress from any claim, damage, or other liability arising from or related to all Unintended Uses of Cypress products. You shall indemnify and hold Cypress harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of Cypress products.

Cypress, the Cypress logo, Spansion, the Spansion logo, and combinations thereof, WICED, PSoC, CapSense, EZ-USB, F-RAM, and Traveo are trademarks or registered trademarks of Cypress in the United States and other countries. For a more complete list of Cypress trademarks, visit cypress.com. Other names and brands may be claimed as property of their respective owners.