

FCC SAR TEST REPORT

Client Name : Volterman Inc.
Address : 2035 Sunset Lake Road, Suite B-2, Newark, Delaware,
United States
Product Name : Smart Terminal.
Date : Mar,26, 2019

Shenzhen Anbotech Compliance Laboratory Limited

Contents

1. Statement of Compliance	6
2. General Information	7
2.1 Client Information	7
2.2 Testing Laboratory Information	7
2.3 Description of Equipment Under Test (EUT).....	7
2.4 Device Category and SAR Limits	7
2.5 Applied Standard	8
2.6 Environment of Test Site.....	8
2.7 Test Configuration.....	8
3. Specific Absorption Rate (SAR).....	9
3.1 Introduction.....	9
3.2 SAR Definition.....	9
4. SAR Measurement System	10
4.1 E-Field Probe	11
4.2 Data Acquisition Electronics (DAE).....	11
4.3 Robot.....	12
4.4 Measurement Server.....	12
4.5 Phantom.....	13
4.6 Device Holder.....	14
4.7 Data Storage and Evaluation	15
5. Test Equipment List	17
6. Tissue Simulating Liquids	18
7. System Verification Procedures.....	20
8. EUT Testing Position	22
8.1 Body Position	22
9. Measurement Procedures	23
9.1 Spatial Peak SAR Evaluation	23
9.2 Power Reference Measurement.....	24
9.3 Area & Zoom Scan Procedures.....	24
9.4 Volume Scan Procedures.....	25
9.5 SAR Averaged Methods.....	25
9.6 Power Drift Monitoring	25
10. Conducted Power.....	26
11. Transmit Antennas and SAR Measurement Position	28
12. SAR Test Results Summary	29
12.1 Body SAR Results	29
13. SAR Measurement Variability	31
14. Simultaneous Transmission analysis	32
15. Measurement Uncertainty	34
Appendix A. EUT Photos and Test Setup Photos	36

Appendix B.	Plots of SAR System Check	38
Appendix C.	Plots of SAR Test Data	40
Appendix D.	DASY System Calibration Certificate	42

TEST REPORT

Applicant : Volterman Inc.
Manufacturer : 2035 Sunset Lake Road, Suite B-2, Newark, Delaware, United States
Product Name : Smart Terminal.
Model No. : Wallet 1, Wallet 2, Wallet 3, Luggage 1, Luggage 2, Luggage 3, Bag 1, Bag 2, Smart 1, Smart 2, Smart 3
Trade Mark : Volterman
Rating(s) : DC 3.8V

**Test Standard(s) : ANSI/IEEE C95.1: 1999, IEEE 1528: 2013
KDB 865664 D01, KDB 865664 D02, KDB 447498 D01,
KDB248227, KDB941225 D01**

The device described above is tested by Shenzhen Anbotech Compliance Laboratory Limited to determine the maximum emission levels emanating from the device and the severe levels of the device can endure and its performance criterion. The measurement results are contained in this test report and Shenzhen Anbotech Compliance Laboratory Limited is assumed full of responsibility for the accuracy and completeness of these measurements. Also, this report shows that the EUT (Equipment Under Test) is technically compliant with the FCC requirements.

This report applies to above tested sample only and shall not be reproduced in part without written approval of Shenzhen Anbotech Compliance Laboratory Limited.

Date of Receipt

Mar, 24, 2019

Date of Test

Mar, 25~ Mar, 26, 2019

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Version

Version No.	Date	Description
01	Mar,26, 2019	Original

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1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing are as follows.

<Highest SAR Summary>

FrequencyBand	Highest Reported 1g-SAR(W/Kg)	SAR Test Limit (W/Kg)
	Body (0mm)	
WCDMA BAND V	1.16	1.6
WIFI 2.4G	0.33	
Simultaneous SAR	1.49	
Test Result	PASS	

According to IEEE Std C95.1, 1999:((IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 KHz to 300 GHz).

It specifies the maximum exposure limit of 1.6 W/kg as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

2. General Information

2.1 Client Information

Applicant:	Volterman Inc.
Address of Applicant:	2035 Sunset Lake Road, Suite B-2, Newark, Delaware, United States
Manufacture:	Shenzhen Smart NRE Technology Co., Ltd.
Address of Manufacture:	4/F, D building, Xinda Technology Park, Baotian 2nd Road, Xixiang, Bao'an, Shenzhen,China

2.2 Testing Laboratory Information

Test Site:	Shenzhen Anbotech Compliance Laboratory Limited
Address:	1/F, Building D, Sogood Science and Technology Park, Sanwei community, Hangcheng Street, Bao'an District, Shenzhen, Guangdong, China.518102

2.3 Description of Equipment Under Test (EUT)

Equipment	Smart Terminal.
Brand Name	/
Model Name	Wallet 1, Wallet 2, Wallet3, Luggage 1, Luggage 2, Luggage 3, Bag 1, Bag 2, Smart 1, Smart 2, Smart 3
Tx Frequency	WCDMA BAND V: 826.4 MHz ~ 846.6 MHz BT: 2402 MHz ~ 2480 MHz WIFI 2.4GHz: 2412 MHz ~ 2462 MHz
Type of Modulation	WCDMA: RMC, 12.2Kbps, HSDPA, HSUPA BT: GFSK, 8DPSK, π /4DQPSK WIFI 2.4GHz: BPSK, QPSK, 16QAM, 64QAM
Category of device	Portable device
Remark: The above DUT's information was declared by manufacturer. Please refer to the specifications or user's manual for more detailed description.	

2.4 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user.

according to IEEE Std C95.1, 1999: ((IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 KHz to 300 GHz).

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It specifies the maximum exposure limit of 1.6 W/kg as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

2.5 Applied Standard

The Specific Absorption Rate (SAR) testing specification, method, and procedure for this device is in accordance with the following standards:

- ANSI/IEEE C95.1: 1999, IEEE 1528: 2013
- KDB 865664 D01, KDB 865664 D02, KDB 447498 D01, KDB248227, KDB941225 D01

2.6 Environment of Test Site

Items	Required	Actual
Temperature (°C)	18-25	22~23
Humidity (%RH)	30-70	55~65

2.7 Test Configuration

The device was controlled by a base station emulator. Communication between the device and the emulator was established by air link. The distance between the EUT and the antenna of the emulator is larger than 50 cm and the output power radiated from the emulator antenna is at least 30 dB smaller than the output power of EUT. The EUT was set from the emulator to radiate maximum output power during all tests. For WIFI and BT SAR testing, WLAN engineering testing software installed on the EUT can provide continuous transmitting RF signal.

3. Specific Absorption Rate (SAR)

3.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

3.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ).The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dv} \right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = C \left(\frac{\delta T}{\delta t} \right)$$

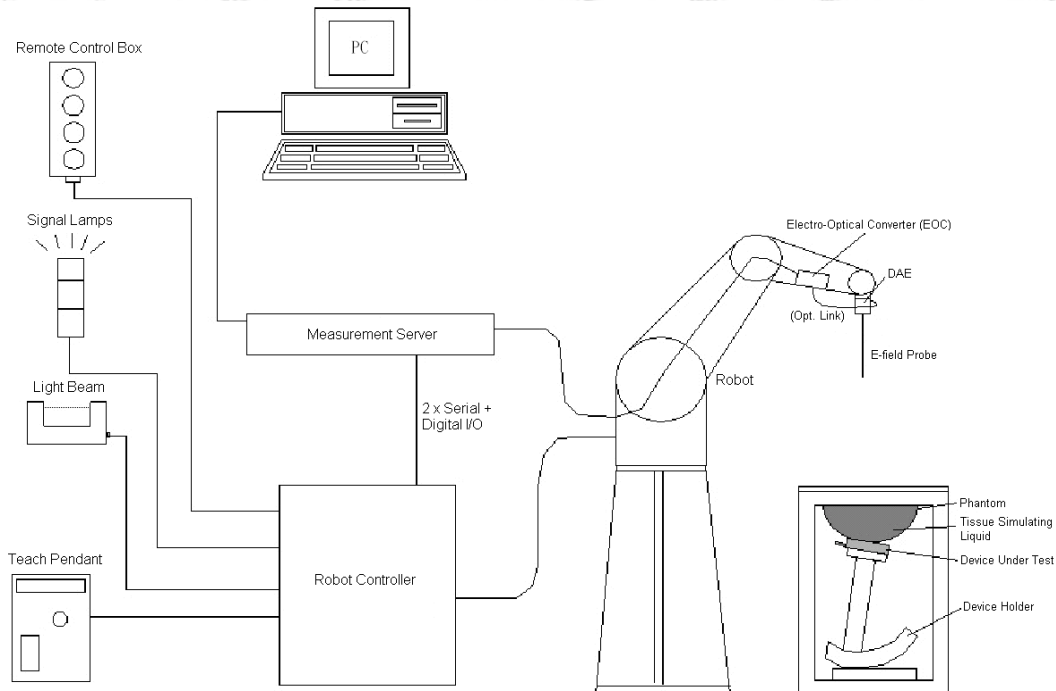
Where: C is the specific head capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of the tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

4. SAR Measurement System



DASY System Configurations

The DASY system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (EOC) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY software
- Remote control with teach pendant and additional circuitry for robot safety such as warming lamps, etc.
- The SAM twin phantom
- A device holder
- Tissue simulating liquid
- Dipole for evaluating the proper functioning of the system

components are described in details in the following sub-sections.

4.1 E-Field Probe

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG).The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

➤ E-Field Probe Specification

<EX3DV4 Probe>

Construction	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	 Photo of EX3DV4
Frequency	10 MHz to 6 GHz; Linearity: ± 0.2 dB	
Directivity	± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis)	
Dynamic Range	10 μ W/g to 100 mW/g; Linearity: ± 0.2 dB (noise: typically < 1 μ W/g)	
Dimensions	Overall length: 330 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm	

➤ E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than $\pm 10\%$. The spherical isotropy shall be evaluated and within ± 0.25 dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data can be referred to appendix C of this report.

4.2 Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The input impedance of the DAE is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.

**Photo of DAE**

4.3 Robot

The SPEAG DASY system uses the high precision robots (DASY5: TX60XL) type from Stäubli SA (France). For the 6-axis controllersystem, the robot controller version (DASY5: CS8c) from Stäubli is used. The Stäublirobot series have many features that are important for our application:

- High precision (repeatability ± 0.035 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)

**Photo of DASY5**

4.4 Measurement Server

The measurement server is based on a PC/104 CPU board with CPU (DASY5: 400 MHz, Intel Celeron), chipdisk (DASY5: 128 MB), RAM (DASY5: 128 MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O board, which is directly connected to the PC/104 bus of the CPU board.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.



Photo of Server for DASYS5

4.5 Phantom

<SAM Twin Phantom>

Shell Thickness	2 ± 0.2 mm; Center ear point: 6 ± 0.2 mm
Filling Volume	Approx. 25 liters
Dimensions	Length: 1000 mm; Width: 500 mm; Height: adjustable feet
Measurement Areas	Left Hand, Right Hand, Flat Phantom



Photo of SAM Phantom

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

<ELI4 Phantom>

Shell Thickness	2 ± 0.2 mm (sagging: <1%)
Filling Volume	Approx. 30 liters
Dimensions	Major ellipse axis: 600 mm Minor axis: 400 mm

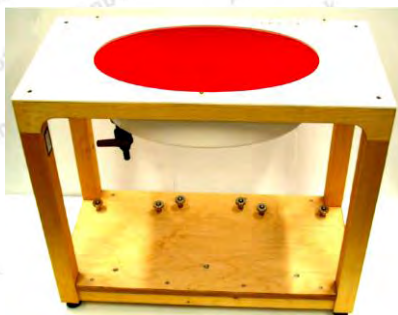


Photo of ELI4 Phantom

The ELI4 phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.

4.6 Device Holder

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5 mm distance, a positioning uncertainty of $\pm 0.5\text{mm}$ would produce a SAR uncertainty of $\pm 20\%$. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

The DASY device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



Device Holder

4.7 Data Storage and Evaluation

➤ Data Storage

The DASY software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files. The post-processing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a non-lose media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

➤ Data Evaluation

The DASY post-processing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Norm _i , a _{i0} , a _{i1} , a _{i2}
	- Conversion factor	ConvF _i
	- Diode compression point	dcp _i
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power.

The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with V_i = compensated signal of channel i, (i = x, y, z)

U_i = input signal of channel i, (i = x, y, z)

cf = crest factor of exciting field (DASY parameter)

dcp_i = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated:

$$\text{E-field Probes: } E_i = \sqrt{\frac{V_i}{\text{Norm}_i \cdot \text{ConvF}}}$$

$$\text{H-field Probes: } H_i = \sqrt{V_i \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}}$$

with V_i = compensated signal of channel i, (i = x, y, z)

Norm_i = sensor sensitivity of channel i, (i = x, y, z), $\mu\text{V}/(\text{V/m})^2$ for E-field Probes

ConvF = sensitivity enhancement in solution

a_{ij} = sensor sensitivity factors for H-field probes

f = carrier frequency [GHz]

E_i = electric field strength of channel i in V/m

H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{\text{tot}} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$\text{SAR} = E_{\text{tot}}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

E_{tot} = total field strength in V/m

σ = conductivity in [mho/m] or [Siemens/m]

ρ = equivalent tissue density in g/cm³

Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

5. Test Equipment List

Manufacturer	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	Due Date
SPEAG	835MHz System Validation Kit	D835V2	4d154	Jun 16,2018	Jun 15,2021
SPEAG	2450MHz System Validation Kit	D2450V2	910	Jun 15,2018	Jun 14,2021
Rohde & Schwarz	UNIVERSAL RADIO COMMUNICATION TESTER	CMU 200	117888	Nov. 05, 2018	Nov. 04, 2019
SPEAG	Data Acquisition Electronics	DAE4	387	Sept.06,2018	Sept.05,2019
SPEAG	Dosimetric E-Field Probe	EX3DV4	7396	May 12,2018	May 11,2019
Agilent	ENA Series Network Analyzer	E5071C	MY46317418	May.23, 2018	May. 22, 2019
SPEAG	DAK	DAK-3.5	1226	NCR	NCR
SPEAG	SAM Twin Phantom	QD000P40CD	1802	NCR	NCR
SPEAG	ELI Phantom	QDOVA004AA	2058	NCR	NCR
AR	Amplifier	ZHL-42W	QA1118004	NCR	NCR
Agilent	Power Meter	N1914A	MY50001102	Oct. 28, 2018	Oct. 27, 2019
Agilent	Power Sensor	N8481H	MY51240001	Oct. 29, 2018	Oct. 28, 2019
R&S	Spectrum Analyzer	N9020A	MY51170037	May.23, 2018	May. 22, 2019
Agilent	Signal Generation	N5182A	MY48180656	May.23, 2018	May. 22, 2019
Worken	Directional Coupler	0110A05601O-10	COM5BNW1A2	May.23, 2018	May. 22, 2019

Note:

1. The calibration certificate of DASY can be referred to appendix C of this report.
2. The dipole calibration interval can be extended to 3 years with justification. The dipoles are also not physically damaged, or repaired during the interval.
3. The Insertion Loss calibration of Dual Directional Coupler and Attenuator were characterized via the network analyzer and compensated during system check.
4. The dielectric probe kit was calibrated via the network analyzer, with the specified procedure (calibrated in pure water) and calibration kit (standard) short circuit, before the dielectric measurement. The specific procedure and calibration kit are provided by Agilent.
5. In system check we need to monitor the level on the power meter, and adjust the power amplifier level to have precise power level to the dipole; the measured SAR will be normalized to 1W input power according to the ratio of 1W to the input power to the dipole. For system check, the calibration of the power amplifier is deemed not critically required for correct measurement; the power meter is critical and we do have calibration for it

6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. For head SAR testing, the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15 cm, which is shown in Fig. 6.1. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15 cm, which is shown as followed:

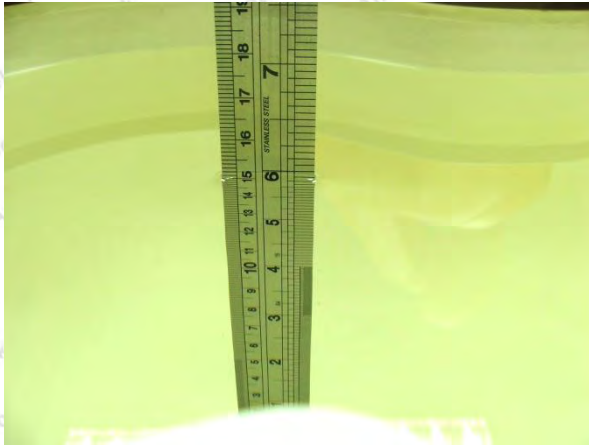


Photo of Liquid Height for Head SAR



Photo of Liquid Height for Body SAR

The following table gives the recipes for tissue simulating liquid.

Frequency (MHz)	Water (%)	Sugar (%)	Cellulose (%)	Salt (%)	Preventol (%)	DGBE (%)	Conductivity (σ)	Permittivity (ϵ_r)
For Head								
835	40.3	57.9	0.2	1.4	0.2	0	0.9	41.5
1800,1900,2000	55.2	0	0	0.3	0	44.5	1.4	40
2450	55	0	0	0	0	45	1.8	39.2
For Body								
835	50.8	48.2	0	0.9	0.1	0	0.97	55.2
1800.1900.2000	70.2	0	0	0.4	0	29.4	1.52	53.3
2450	68.6	0	0	0	0	31.4	1.95	52.7

The following table shows the measuring results for simulating liquid.

Dielectric performance of Body tissue simulating liquid				
Frequency (MHz)	Description	DielectricParameters		Temp
		ϵ_r	σ (s/m)	°C
835	Recommended result $\pm 5\%$ window	55.2 52.44 to 57.96	0.97 0.92 to 1.02	/
	Measurement value 2019-03-25	55.15	0.96	21
2450	Recommended result $\pm 5\%$ window	52.7 50.07 to 55.34	1.95 1.85 to 2.05	/
	Measurement value 2019-03-26	52.52	1.94	21

7. System Verification Procedures

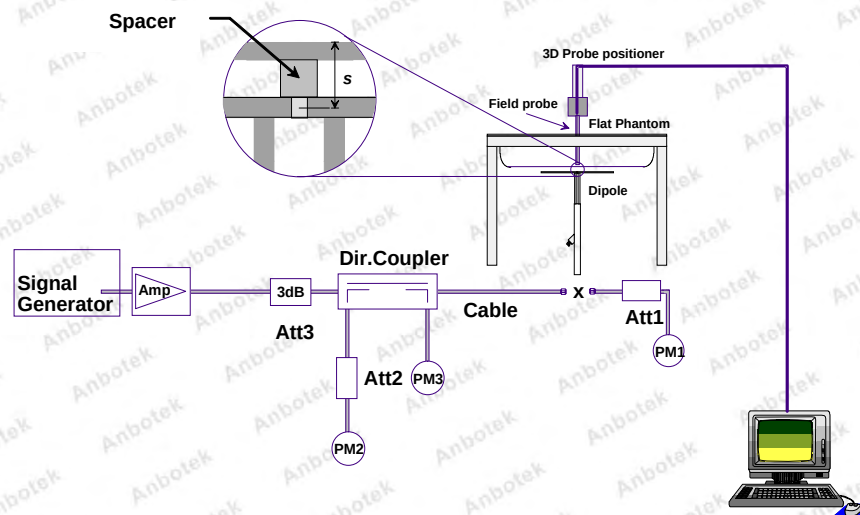
Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

➤ Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

➤ System Setup

In the simplified setup for system evaluation, the EUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



System Setup for System Evaluation

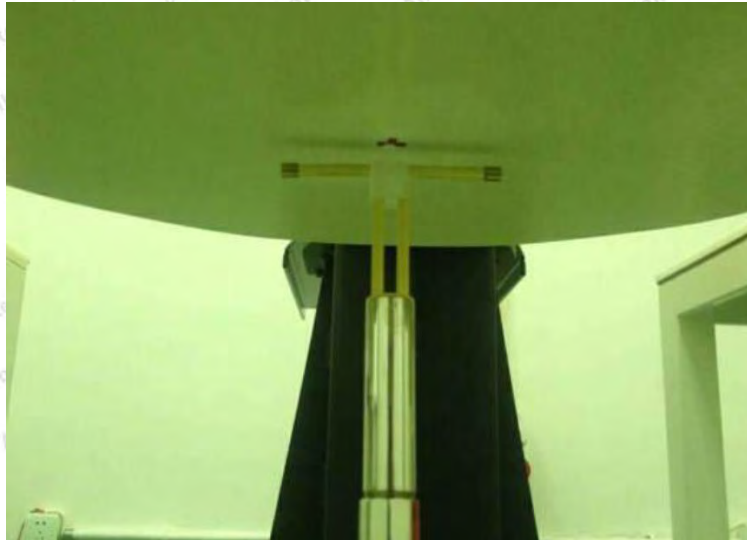


Photo of Dipole Setup

➤ **Validation Results**

Comparing to the original SAR value provided by SPEAG, the verification data should be within its specification of 10 %. The table below shows the target SAR and measured SAR after normalized to 1W input power. It indicates that the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

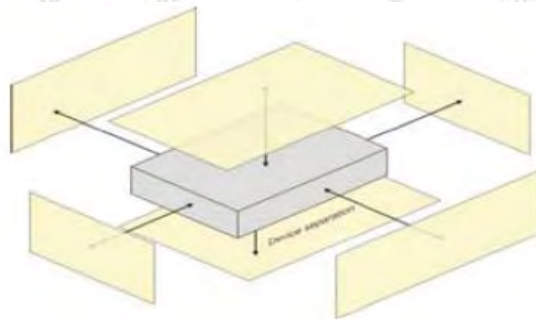
Frequency (MHz)	Power fed onto reference dipole (mW)	Targeted SAR 1g(W/kg)	Measured SAR 1g(W/kg)	Normalized SAR 1g(W/kg)	Deviation (%)	Test Date
835	250	9.57	2.47	9.88	3.24	03/25/2019
2450	250	51.80	12.86	51.44	-0.69	03/26/2019

Target and Measurement SAR after Normalized

8. EUT Testing Position

8.1. Body Position

The hotspot mode and body-worn accessory SAR test configurations may overlap for handsets. When the same wireless mode transmission configurations for voice and data are required for SAR measurements, the more conservative configuration with a smaller separation distance should be tested for the overlapping SAR configurations. This typically applies to the back and front surfaces of a handset when SAR is required for both hotspot mode and body-worn accessory exposure conditions. Depending on the form factor and dimensions of a device, the test separation distance used for hotspot mode SAR measurement is **0 mm**.



Body Position

9. Measurement Procedures

The measurement procedures are as follows:

- (a) Use base station simulator (if applicable) or engineering software to transmit RF power continuously (continuous Tx) in the middle channel.
- (b) Keep EUT to radiate maximum output power or 100% duty factor (if applicable)
- (c) Measure output power through RF cable and power meter.
- (d) Place the EUT in the positions as setup photos demonstrates.
- (e) Set scan area, grid size and other setting on the DASY software.
- (f) Measure SAR transmitting at the middle channel for all applicable exposure positions.
- (g) Identify the exposure position and device configuration resulting the highest SAR
- (h) Measure SAR at the lowest and highest channels at the worst exposure position and device configuration if applicable.

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

9.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface

(f)

(g) Calculation of the averaged SAR within masses of 1g and 10g

9.2 Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

9.3 Area & Zoom Scan Procedures

Measure the local SAR at a test point within 8 mm of the phantom inner surface that is closest to the DUT.

Measure the two-dimensional SAR distribution within the phantom (area scan procedure). The boundary of the measurement area shall not be closer than 20 mm from the phantom side walls. The distance between the measurement points should enable the detection of the location of local maximum with an accuracy of better than half the linear dimension of the tissue cube after interpolation. A maximum grid spacing of 20 mm for frequencies below 3 GHz and $(60/f \text{ [GHz]})$ mm for frequencies of 3 GHz and greater is recommended. The maximum distance between the geometrical center of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\ln(2)/2$ mm for frequencies of 3 GHz and greater, where $\ln(x)$ is the natural logarithm. The maximum variation of the sensor-phantom surface distance shall be 1 mm for frequencies below 3 GHz and 0.5 mm for frequencies of 3 GHz and greater. At all measurement points the angle of the probe with respect to the line normal to the surface should be less than 5° . If this cannot be achieved for a measurement distance to the phantom inner surface shorter than the probe diameter, additional uncertainty evaluation is needed.

From the scanned SAR distribution, identify the position of the maximum SAR value, in addition identify the positions of any local maxima with SAR values within 2 dB of the maximum value that will not be within the zoom scan of other peaks; additional peaks shall be measured only when the primary peak is within 2 dB of the SAR compliance limit (e.g., 1 W/kg for 1,6 W/kg 1 g limit, or 1,26 W/kg for 2 W/kg, 10 g limit).

Measure the three-dimensional SAR distribution at the local maxima locations identified in step c) (zoom scan procedure). The horizontal grid step shall be $(24 / f \text{ [GHz]})$ mm or less but not more than 8 mm. The minimum zoom scan size is 30 mm by 30 mm by 30 mm for frequencies below 3 GHz. For higher frequencies, the minimum zoom scan size can be reduced to 22 mm by 22 mm by 22 mm. The grid step in the vertical direction shall be $(8/f \text{ [GHz]})$ mm or less but not more than 5 mm, if uniform spacing is used. If variable spacing is used in the vertical direction, the maximum spacing between the two closest measured points to the phantom shell shall be $(12/f \text{ [GHz]})$ mm or less but not more than 4 mm, and the spacing between farther points shall increase by an incremental factor not exceeding 1,5. When variable spacing is used, extrapolation routines shall be tested with the same spacing as used in measurements. The maximum

distance between the geometrical center of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\ln(2)/2$ mm for frequencies of 3 GHz and greater, where the plane wave skin depth and $\ln(x)$ is the natural logarithm. Separate grids shall be centered on each of the local SAR maxima found in step c). Uncertainties due to field distortion between the media boundary and the dielectric enclosure of the probe should also be minimized, which is achieved if the distance between the phantom surface and physical tip of the probe is larger than probe tip diameter. Other methods may utilize correction procedures for these boundary effects that enable high precision measurements closer than half the probe diameter. For all measurement points, the angle of the probe with respect to the flat phantom surface shall be less than 5°.

9.4 Volume Scan Procedures

The volume scan is used for assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g aggregate SAR, the EUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing. When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

9.5 SAR Averaged Methods

In DASY, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.

9.6 Power Drift Monitoring

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

10. Conducted Power

< WCDMA Power>

Band	WCDMA Band V			
TX Channel	CH4132	CH4183	CH4233	Tune-uppower (dBm)
Frequency (MHz)	826.40	836.60	846.60	
RMC 12.2Kbps	22.47	22.68	22.64	23.0
HSDPA Subtest-1	21.90	22.25	22.22	23.0
HSDPA Subtest-2	21.87	21.32	22.17	23.0
HSDPA Subtest-3	21.95	21.26	22.35	23.0
HSDPA Subtest-4	20.83	21.4	21.22	22.0
HSUPA Subtest-1	20.47	20.97	19.93	21.0
HSUPA Subtest-2	20.16	19.92	20.19	21.0
HSUPA Subtest-3	21.05	21.05	20.47	22.0
HSUPA Subtest-4	20.20	19.83	20.16	21.0
HSUPA Subtest-5	21.11	21.05	21.05	22.0

<WIFI 2.4GHzPower>

WIFI							
Mode	Channel	Frequency (MHz)	Conducted Peak Power (dBm)	Peak Tune-up power (dBm)	Conducted Average Power (dBm)	Average Tune-up power (dBm)	Data rate
802.11b	01	2412	18.59	20.0	15.86	16.0	1 Mbps
	06	2437	19.62	20.0	16.74	17.0	1 Mbps
	11	2462	20.55	21.0	17.51	18.0	1 Mbps
802.11g	01	2412	19.08	20.0	14.95	15.0	6 Mbps
	06	2437	20.29	21.0	15.85	16.0	6 Mbps
	11	2462	21.58	22.0	16.88	17.0	6 Mbps
802.11n(H20)	01	2412	19.28	20.0	14.70	15.0	6.5 Mbps
	06	2437	20.67	21.0	15.73	16.0	6.5 Mbps
	11	2462	21.89	22.0	16.66	17.0	6.5 Mbps

Note: The output power was test all data rate and recorded worst case at recorded data rate.

<Bluetooth Power>

Bluetooth				
Mode	Channel	Frequency (MHz)	Conducted power (dBm)	Tune-up power (dBm)
GFSK	0	2402	2.885	4.0
	39	2441	3.205	4.0
	78	2480	3.249	4.0
$\pi/4$ QPSK	0	2402	2.857	4.0
	39	2441	3.223	4.0
	78	2480	3.088	4.0
8DPSK	0	2402	2.891	4.0
	39	2441	3.298	4.0
	78	2480	3.232	4.0
BLE	0	2402	-5.391	-5.0
	19	2440	-5.228	-5.0
	39	2480	-5.393	-5.0

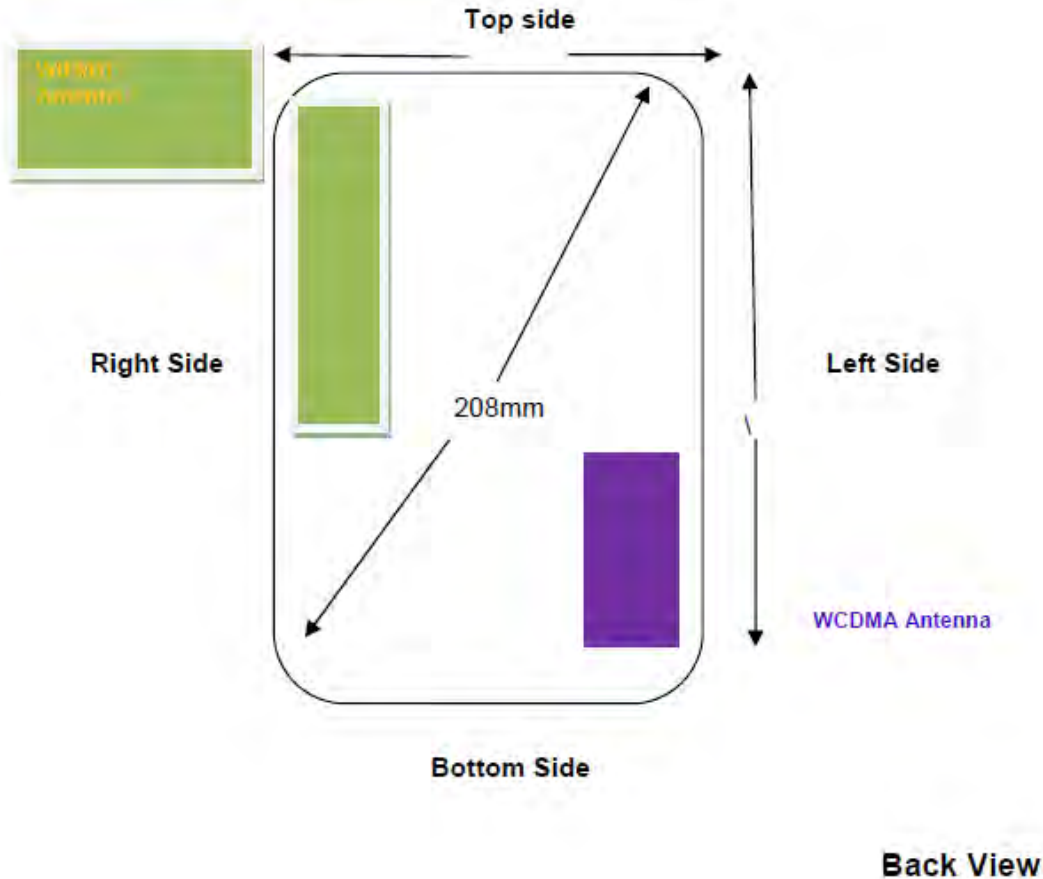
Per KDB 447498 D01, the 1-g and 10-g SAR test exclusion thresholds for 100MHz to 6GHz at test separation distances $\leq 50\text{mm}$ are determined by:

$$[(\text{max. Power of channel, including tune-up tolerance, mW}) / (\text{min. test separation distance, mm})] * [\sqrt{f(\text{GHz})}] \leq 3.0 \text{ for } 1\text{-g SAR}$$

Band/Mode	f (GHz)	Antenna Distance (mm)	RF output power (including tune-up tolerance)		SAR Test Exclusion Threshold	SAR Test Exclusion
			dBm	mW		
BT	2.441	5	4	2.512	$0.8 < 3.0$	Yes
WIFI	2.462	5	18	63.096	$19.8 > 3.0$	No

Per KDB 447498 D01, when the minimum test separation distance is $< 5\text{mm}$, a distance of 5mm is applied to determine SAR test exclusion. If The test exclusion threshold is ≤ 3 , SAR testing is not required.

11. Transmit Antennas and SAR Measurement Position



Antenna information:

GSM/WCDMA/LTE Antenna	UMTS TX/RX
WIFI/BT Antenna	WIFI/BT TX/RX

Distance of The Antenna to the EUT surface and edge

Antennas	Front	Back	Top Side	Bottom Side	Left Side	Right Side
WCDMA	<5mm	<5mm	>25mm	<5mm	<5mm	>25mm
WIFI/BT	<5mm	<5mm	<5mm	>25mm	>25mm	<5mm

Positions for SAR tests; Hotspot mode

Antennas	Front	Back	Top Side	Bottom Side	Left Side	Right Side
WCDMA	Yes	Yes	No	Yes	Yes	No
WIFI/BT	Yes	Yes	Yes	No	No	Yes

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12.SAR Test Results Summary

12.1 Body SAR Results

<WCDMA>

WCDMA Band V										
Mode	Test Position	Frequency		Conducted Power (dBm)	Tune up limit (dBm)	Tune up scaling factor	Power Drift(dB)	Measured SAR(1g) (W/kg)	Report SAR(1g) (W/kg)	Test Plot
		CH	MHz							
RMC 12.2Kbps	Front	4132	826.4	22.47	23.00	1.13	-	-	-	-
		4183	836.6	22.68	23.00	1.08	0.03	0.769	0.83	-
		4233	846.6	22.64	23.00	1.09	-	-	-	-
	Back	4132	826.4	22.47	23.00	1.13	-0.13	1.01	1.14	-
		4183	836.6	22.68	23.00	1.08	-0.09	1.08	1.16	1#
		4233	846.6	22.64	23.00	1.09	-0.10	1.06	1.15	-
	Left	4183	836.6	22.68	23.00	1.08	-0.16	0.512	0.55	-
	Right	4183	836.6	22.68	23.00	1.08	-	-	-	-
	Top	4183	836.6	22.68	23.00	1.08	-	-	-	-
	Bottom	4183	836.6	22.68	23.00	1.08	0.03	0.616	0.66	-

Note: Per FCC KDB Publication 447498 D01, if the reported (scaled) SAR measured at the middle channel or highest output power channel for each test configuration is ≤ 0.8 W/kg then testing at the other channels is optional for such test configuration(s).

WLAN										
Mode	Test Position	Frequency		Conducted Power (dBm)	Tune up limit (dBm)	Tune up scaling factor	Power Drift(dB)	Measured SAR(1g) (W/kg)	Report SAR(1g) (W/kg)	Test Plot
		CH	MHz							
802.11b 1Mbps	Front	1	2412	15.86	16.0	1.03	-	-	-	-
		6	2437	16.74	17.0	1.06	-	-	-	-
		11	2462	17.51	18.0	1.12	0.09	0.202	0.23	-
	Back	1	2412	15.86	16.0	1.03	-	-	-	-
		6	2437	16.74	17.0	1.06	-	-	-	-
		11	2462	17.51	18.0	1.12	-0.06	0.292	0.33	2#
	Left	11	2462	17.51	18.0	1.12	-	-	-	-
	Right	11	2462	17.51	18.0	1.12	0.05	0.107	0.12	-
	Top	11	2462	17.51	18.0	1.12	-0.08	0.154	0.17	-
	Bottom	-	2462	17.51	18.0	1.12	-	-	-	-

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Note:

1. Per FCC KDB Publication 447498 D01, if the reported (scaled) SAR measured at the middle channel or highest output power channel for each test configuration is ≤ 0.8 W/kg then testing at the other channels is optional for such test configuration(s).
2. According to the above table, the initial test position for body is “Back”, and its reported SAR is ≤ 0.4 W/kg. Thus further SAR measurement is not required for the other (remaining) test positions. Because the reported SAR of the highest measured maximum output power channel for the exposure configuration is ≤ 0.8 W/kg, no further SAR testing is required for 802.11b DSSS in that exposure configuration.
3. When SAR measurement is required for 2.4 GHz 802.11g/n OFDM configurations, the measurement and test reduction procedures for OFDM are applied. SAR is not required for the following 2.4 GHz OFDM conditions.
 - a) When KDB Publication 447498 D01 SAR test exclusion applies to the OFDM configuration.
 - b) When the highest *reported* SAR for DSSS is adjusted by the ratio of OFDM to DSSS specified maximum output power and the adjusted SAR is ≤ 1.2 W/kg, the 802.11g/n is not required

13.SAR Measurement Variability

SAR measurement variability must be assessed for each frequency band, which is determined by the SAR probe calibration point and tissue-equivalent medium used for the device measurements. When both head and body tissue-equivalent media are required for SAR measurements in a frequency band, the variability measurement procedures should be applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium.

The following procedures are applied to determine if repeated measurements are required.

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps 2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg ($\sim 10\%$ from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20 .

SAR Measurement Variability for Body WCDMA Band V(1g)

Frequency		Mode	Test Position	Spacing (mm)	Original SAR (W/kg)	First Repeated SAR (W/kg)	The Ratio	Second Repeated SAR (W/kg)
CH	MHz							
4183	836.6	RMC 12.2Kbps	Back	0	1.08	1.05	1.03	/

14.Simultaneous Transmission analysis

No.	Simultaneous Transmission Configurations	Body	Note
1	WCDMA (data) + Bluetooth (data)	No	
2	WCDMA (data) + WIFI (data)	YES	

General note:

1. WLAN and Bluetooth share the same antenna, and cannot transmit simultaneously.
2. EUT will choose WCDMA according to the network signal condition; therefore, they will not operate simultaneously at any moment.
3. The reported SAR summation is calculated based on the same configuration and test position
4. For simultaneous transmission analysis, Bluetooth SAR is estimated per KDB 447498 D01 based on the formula below
 - a) $[(\text{max. Power of channel, including tune-up tolerance, mW}) / (\text{min. test separation distance, mm})] * [\sqrt{f(\text{GHz})/x}] \text{W/kg}$ for test separation distances $\leq 50\text{mm}$; when $x=7.5$ for 1-g SAR, and $x=18.75$ for 10-g SAR.
 - b) When the minimum separation distance is $<5\text{mm}$, the distance is used 5mm to determine SAR test exclusion
 - c) 0.4 W/kg for 1-g SAR and 1.0W/kg for 10-g SAR, when the test separation distances is $>50\text{mm}$.

Bluetooth	Exposure position	Body
Max power	Test separation	0mm
4.0 dBm	Estimated SAR (W/kg)	0.11 W/kg

WWAN PCE + WLAN DTS				
WWAN Band	Exposure Position	Max SAR (W/kg)		Summed SAR
		WWAN PCS	WLAN DTS	(W/kg)
WCDMA Band V	Front	0.83	0.23	1.06
	Back	1.16	0.33	1.49
	Left side	0.55	-	0.55
	Right side	-	0.12	0.12
	Top side	-	0.17	0.17
	Bottom side	0.66	-	0.66

WWAN PCE + Bluetooth DSS				
WWAN Band	Exposure Position	Max SAR (W/kg)		Summed SAR
		WWAN PCS	Bluetooth DSS	(W/kg)
WCDMA Band V	Front	0.83	0.11	0.94
	Back	1.16	0.11	1.27
	Left side	0.55	0.11	0.66
	Right side	-	0.11	0.11
	Top side	-	0.11	0.11
	Bottom side	0.66	0.11	0.77

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15.Measurement Uncertainty

NO	Source	Uncert. ai (%)	Prob. Dist.	Div. k	ci (1g)	ci (10g)	Stand.Un cert. ui (1g)	Stand.Un cert. ui (10g)	Veff
1	Repeat	0.4	N	1	1	1	0.4	0.4	9
Instrument									
2	Probe calibration	7	N	2	1	1	3.5	3.5	∞
3	Axial isotropy	4.7	R	$\sqrt{3}$	0.7	0.7	1.9	1.9	∞
4	Hemispherical isotropy	9.4	R	$\sqrt{3}$	0.7	0.7	3.9	3.9	∞
5	Boundary effect	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
6	Linearity	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
7	Detection limits	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
8	Readout electronics	0.3	N	1	1	1	0.3	0.3	∞
9	Response time	0.8	R	$\sqrt{3}$	1	1	0.5	0.5	∞
10	Integration time	2.6	R	$\sqrt{3}$	1	1	1.5	1.5	∞
11	Ambient noise	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
12	Ambient reflections	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
13	Probe positioner mech. restrictions	0.4	R	$\sqrt{3}$	1	1	0.2	0.2	∞
14	Probe positioning with respect to phantom shell	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	∞
15	Max.SAR evaluation	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞

Test sample related									
16	Device positioning	3.8	N	1	1	1	3.8	3.8	99
17	Device holder	5.1	N	1	1	1	5.1	5.1	5
18	Drift of output power	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞
Phantom and set-up									
19	Phantom uncertainty	4.0	R	$\sqrt{3}$	1	1	2.3	2.3	∞
20	Liquid conductivity (target)	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
21	Liquid conductivity (meas)	2.5	N	1	0.64	0.43	1.6	1.2	∞
22	Liquid Permittivity (target)	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.5	∞
23	Liquid Permittivity (meas)	2.5	N	1	0.6	0.49	1.5	1.2	∞
Combined standard			RSS	$U_c = \sqrt{\sum_{i=1}^n C_i^2 U_i^2}$			11.4%	11.3%	236
Expanded uncertainty(P=95%)		$U = k U_c$,k=2					22.8%	22.6%	

Appendix A. EUT Photos and Test Setup Photos



Back Side(0cm)



Front Side(0cm)



Left Side(0cm)

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Right Side(0cm)



Top Side(0cm)



Bottom Side(0cm)

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Appendix B. Plots of SAR System Check

835MHz Body System Check

DUT: Dipole 835 MHz; Type: D835V2; Serial: 4d154

Communication System: CW; Frequency: 835 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 835 \text{ MHz}$; $\sigma = 0.96 \text{ S/m}$; $\epsilon_r = 55.15$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7396; ConvF(9.88, 9.88, 9.88); Calibrated: 12.05.2018;
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: 06.09.2018
- Phantom: SAM; Type: QD000P40CD; Serial: TP: 1670
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

Configuration/Pin=250mW/Area Scan (7x7x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Maximum value of SAR (measured) = 2.89 W/kg

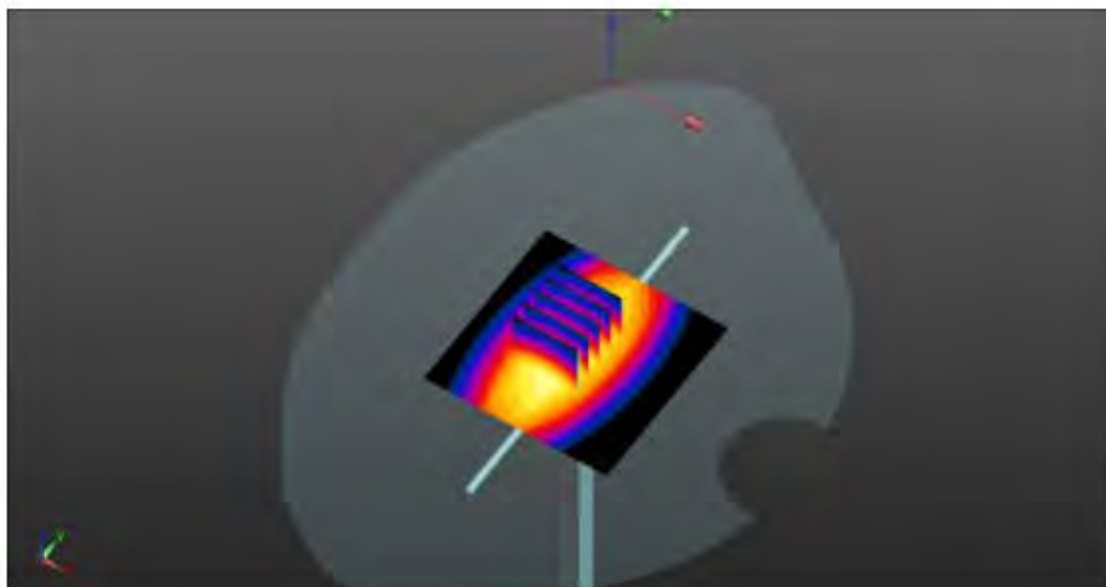
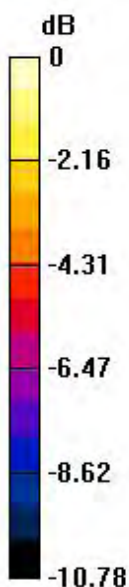
Configuration/Pin=250mW/Zoom Scan (5x5x7)/Cube 0: Measurement grid: $dx=8\text{mm}$, $dy=8\text{mm}$, $dz=5\text{mm}$

Reference Value = 50.236 V/m ; Power Drift = -0.02 dB

Peak SAR (extrapolated) = 3.339 W/kg

SAR(1 g) = 2.47 mW/g ; SAR(10 g) = 1.59 mW/g

Maximum value of SAR (measured) = 2.87 mW/g



2450MHz Body System Check**DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:910**

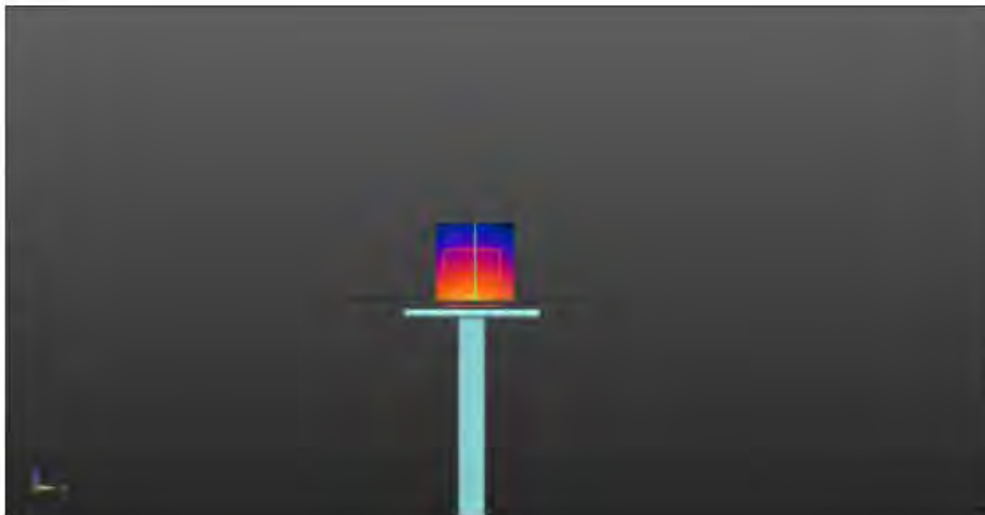
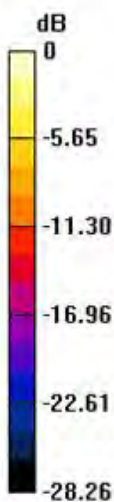
Communication System: UID 0, CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 2450 \text{ MHz}$; $\sigma = 1.94 \text{ S/m}$; $\epsilon_r = 52.52$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 – SN7396; ConvF(7.53, 7.53, 7.53); Calibrated: 12.05.2018;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: 06.09.2018
- Phantom: SAM; Type: QD000P40CD; Serial: TP:1670
- Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

Configuration/Pin=250mW/Area Scan (81x81x1): Interpolated grid: $dx=1.200 \text{ mm}$, $dy=1.200 \text{ mm}$ Maximum value of SAR (interpolated) = 20.1 W/kg **Configuration/Pin=250mW/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$ Reference Value = 87.352 V/m ; Power Drift = 0.03 dB Peak SAR (extrapolated) = 26.4 W/kg **SAR(1 g) = 12.86 W/kg ; SAR(10 g) = 5.96 W/kg** Maximum value of SAR (measured) = 19.6 W/kg 

Appendix C. Plots of SAR Test Data

#1 Date: 03/25/2019

WCDMA 850_Body Back_RMC 12.2K

Communication System: UID 0, Generic WCDMA (0); Frequency: 836.6 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 836.6$ MHz; $\sigma = 0.95$ S/m; $\epsilon_r = 55.05$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 – SN7396; ConvF(9.88, 9.88, 9.88); Calibrated: 12.05.2018;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: 06.09.2018
- Phantom: SAM; Type: QD000P40CD; Serial: TP:1670
- Measurement SW: DASY52, Version 52.8 (2); SEMCAD X Version 14.6.10 (7164)

BODY/BACK/Area Scan (8x13x1): Measurement grid: dx=15mm, dy=15mm

Maximum value of SAR (interpolated) = 1.15 mW/g

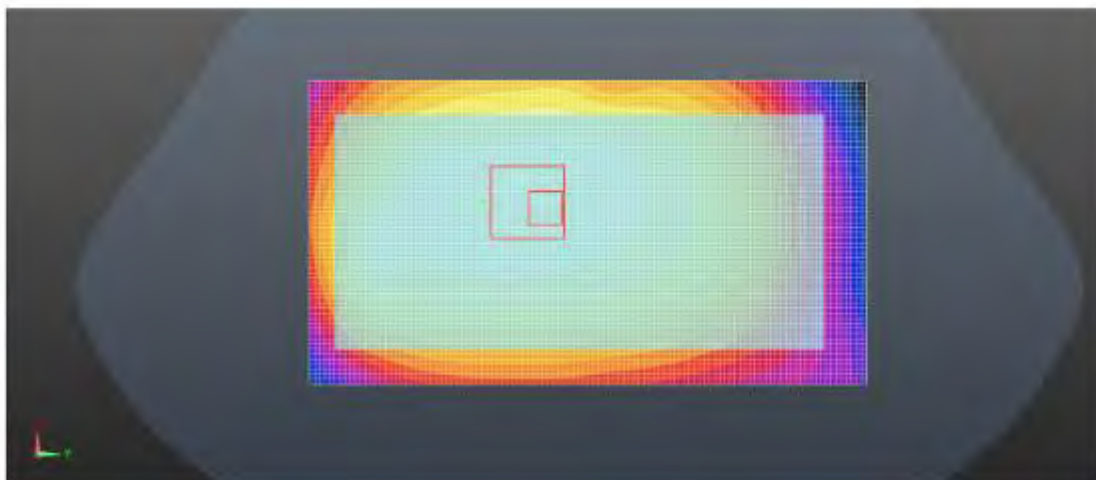
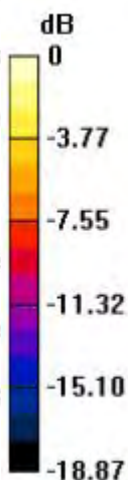
BODY/BACK/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm

Reference Value = 38.1 V/m; Power Drift = -0.09 dB

Peak SAR (extrapolated) = 1.40 W/kg

SAR(1 g) = 1.08 mW/g; SAR(10 g) = 0.851 mW/g

Maximum value of SAR (measured) = 1.16 mW/g



#2 Date: 03/26/2019

WIFI 2.4G_802.11 b_Body Back

Communication System: UID 0, wifi (0); Frequency: 2462 MHz;Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 2462 \text{ MHz}$; $\sigma = 1.92\text{S/m}$; $\epsilon_r = 52.49$; $\rho = 1000 \text{ kg/m}^3$

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7396; ConvF(7.53, 7.53, 7.53); Calibrated: 12,05.2018;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn387; Calibrated: 06.09.2018
- Phantom: SAM; Type: QD000P40CD; Serial: TP:xxxx
- Measurement SW: DASY52, Version 52.8 (7); SEMCAD X Version 14.6.10 (7164)

BODY/BACK/Area Scan (7x11x1): Measurement grid: $dx=15\text{mm}$, $dy=15\text{mm}$

Maximum value of SAR (interpolated) = 0.316 mW/g

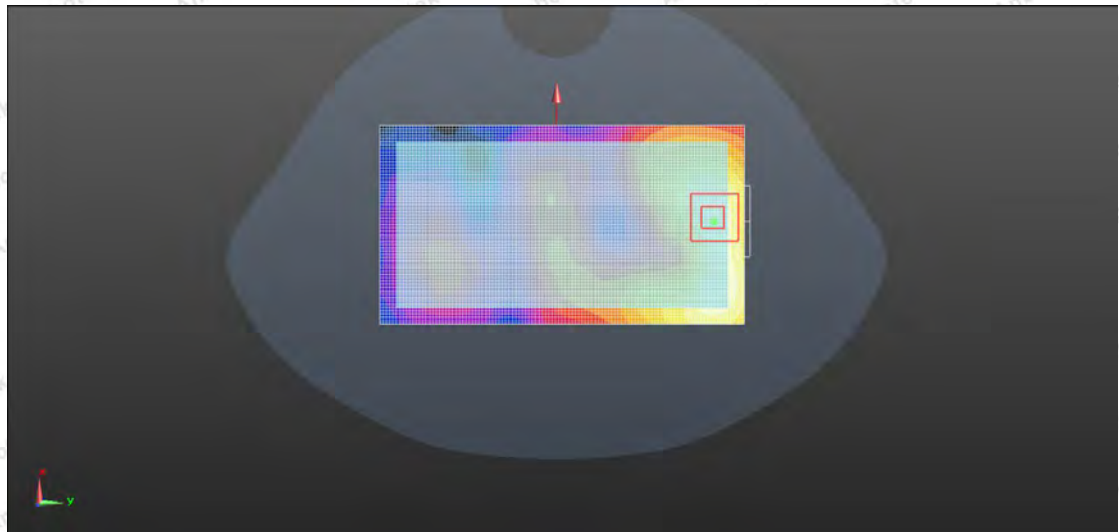
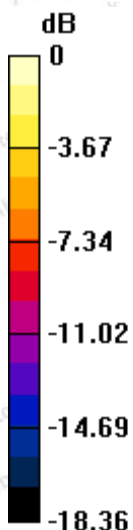
BODY/BACK/Zoom Scan (7x8x7)/Cube 0: Measurement grid: $dx=5\text{mm}$, $dy=5\text{mm}$, $dz=5\text{mm}$

Reference Value = 10.58 V/m; Power Drift = -0.06 dB

Peak SAR (extrapolated) = 0.475 W/kg

SAR(1 g) = 0.292 mW/g; SAR(10 g) = 0.155 mW/g

Maximum value of SAR (measured) = 0.315 mW/g



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Appendix D. DASY System Calibration Certificate



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CNAS L0570

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Client

Anbotek (Auden)

Certificate No: Z18-98671

CALIBRATION CERTIFICATE

Object EX3DV4 - SN:7396

Calibration Procedure(s) FF-Z12-006-08
Calibration Procedures for Dosimetric E-field Probes

Calibration date: May12, 2018

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	20-Jun-17 (CTTL, No.J17X07447)	Jun-18
Power sensor NRP-Z91	101547	20-Jun-17 (CTTL, No.J17X07447)	Jun-18
Power sensor NRP-Z91	101548	20-Jun-17 (CTTL, No.J17X07447)	Jun-18
Reference10dBAttenuator	18N50W-10dB	13-Mar-18(CTTL, No.J18X01547)	Mar-19
Reference20dBAttenuator	18N50W-20dB	13-Mar-18(CTTL, No.J18X01548)	Mar-19
Reference Probe EX3DV4	SN 7433	26-Sep-17(SPEAG, No.EX3-7433_Sep17)	Sep-18
DAE4	SN 549	13-Dec-17(SPEAG, No.DAE4-549_Dec17)	Dec -18
Secondary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
SignalGeneratorMG3700A	6201052605	27-Jun-17 (CTTL, No.J17X04776)	Jun-18
Network Analyzer E5071C	MY46110673	13-Jan-18 (CTTL, No.J18X00285)	Jan -19

	Name	Function	Signature
Calibrated by:	Yu Zongying	SAR Test Engineer	
Reviewed by:	Lin Hao	SAR Test Engineer	
Approved by:	Qi Dianyuan	SAR Project Leader	

Issued: May13, 2018

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: Z18-98671

Page 1 of 11

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Glossary:

TSL	tissue simulating liquid
NORM _{x,y,z}	sensitivity in free space
ConvF	sensitivity in TSL / NORM _{x,y,z}
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A,B,C,D	modulation dependent linearization parameters
Polarization Φ	Φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i $\theta=0$ is normal to probe axis

Connector Angle information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013
- IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300MHz to 3GHz)", February 2005
- IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\theta=0$ ($f \leq 900\text{MHz}$ in TEM-cell; $f > 1800\text{MHz}$: waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not effect the E^2 -field uncertainty inside TSL (see below ConvF).
- NORM(f)_{x,y,z} = NORM_{x,y,z} * frequency_response** (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR**: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}**: A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters**: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800\text{MHz}$) and inside waveguide using analytical field distributions based on power measurements for $f > 800\text{MHz}$. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z} * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from $\pm 50\text{MHz}$ to $\pm 100\text{MHz}$.
- Spherical isotropy (3D deviation from isotropy)**: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).





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Probe EX3DV4

SN: 7396

Calibrated: May 12, 2018

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)





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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm($\mu\text{V}/(\text{V}/\text{m})^2$) ^A	0.54	0.53	0.50	±10.0%
DCP(mV) ^B	97.8	104.5	102.5	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB· μV	C	D dB	VR mV	Unc ^E (k=2)
0	CW	X	0.0	0.0	1.0	0.00	199.9	±2.4%
		Y	0.0	0.0	1.0		203.3	
		Z	0.0	0.0	1.0		195.0	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

^A The uncertainties of Norm X, Y, Z do not affect the E²-field uncertainty inside TSL (see Page 5 and Page 6).

^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.





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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz] ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unct. (k=2)
750	41.9	0.89	9.82	9.82	9.82	0.30	0.85	± 12.1%
835	41.5	0.90	9.71	9.71	9.71	0.15	1.36	± 12.1%
900	41.5	0.97	9.87	9.87	9.87	0.16	1.37	± 12.1%
1750	40.1	1.37	8.61	8.61	8.61	0.25	1.04	± 12.1%
1900	40.0	1.40	8.13	8.13	8.13	0.24	1.01	± 12.1%
2100	39.8	1.49	8.14	8.14	8.14	0.24	1.04	± 12.1%
2300	39.5	1.67	7.85	7.85	7.85	0.40	0.75	± 12.1%
2450	39.2	1.80	7.57	7.57	7.57	0.50	0.75	± 12.1%
2600	39.0	1.96	7.38	7.38	7.38	0.64	0.68	± 12.1%
5250	35.9	4.71	5.33	5.33	5.33	0.45	1.30	± 13.3%
5600	35.5	5.07	4.89	4.89	4.89	0.45	1.35	± 13.3%
5750	35.4	5.22	4.92	4.92	4.92	0.45	1.45	± 13.3%

^C Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

^F At frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.





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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

Calibration Parameter Determined in Body Tissue Simulating Media

f [MHz] ^C	Relative Permittivity ^F	Conductivity (S/m) ^F	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unct. (k=2)
750	55.5	0.96	10.09	10.09	10.09	0.30	0.90	± 12.1%
835	55.2	0.97	9.88	9.88	9.88	0.19	1.32	± 12.1%
900	55.0	1.05	9.82	9.82	9.82	0.23	1.15	± 12.1%
1750	53.4	1.49	8.24	8.24	8.24	0.24	1.06	± 12.1%
1900	53.3	1.52	7.97	7.97	7.97	0.19	1.24	± 12.1%
2100	53.2	1.62	8.18	8.18	8.18	0.19	1.39	± 12.1%
2300	52.9	1.81	7.88	7.88	7.88	0.55	0.80	± 12.1%
2450	52.7	1.95	7.53	7.53	7.53	0.46	0.89	± 12.1%
2600	52.5	2.16	7.38	7.38	7.38	0.52	0.80	± 12.1%
5250	48.9	5.36	4.93	4.93	4.93	0.45	1.80	± 13.3%
5600	48.5	5.77	4.19	4.19	4.19	0.48	1.90	± 13.3%
5750	48.3	5.94	4.52	4.52	4.52	0.48	1.95	± 13.3%

^C Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

^F At frequency below 3 GHz, the validity of tissue parameters (ϵ and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ϵ and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.



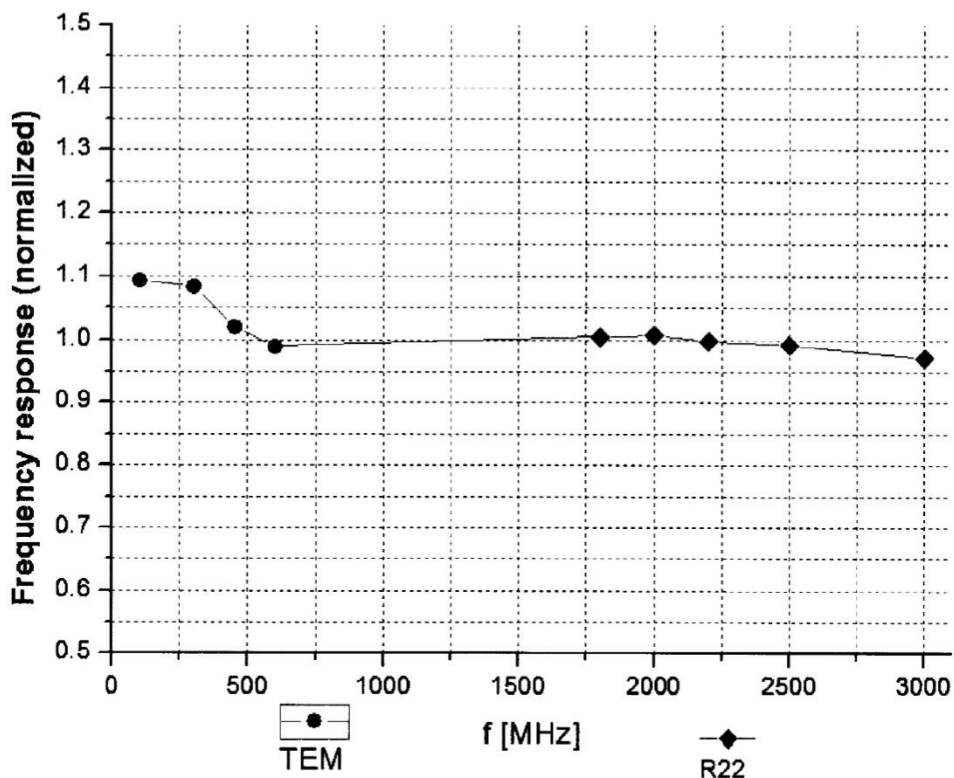


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Frequency Response of E-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: $\pm 7.4\%$ ($k=2$)





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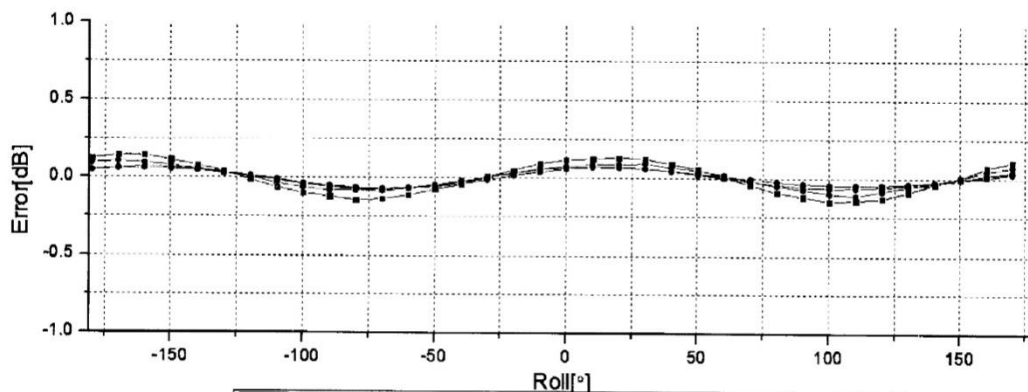
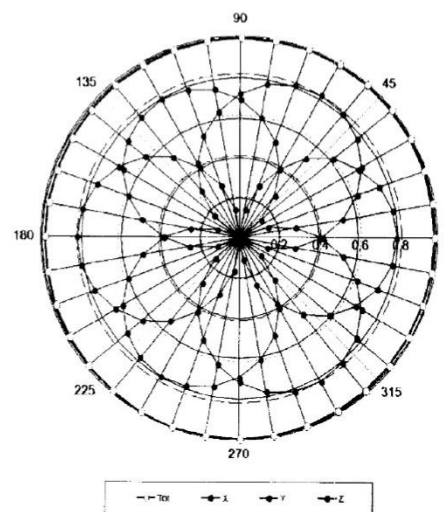
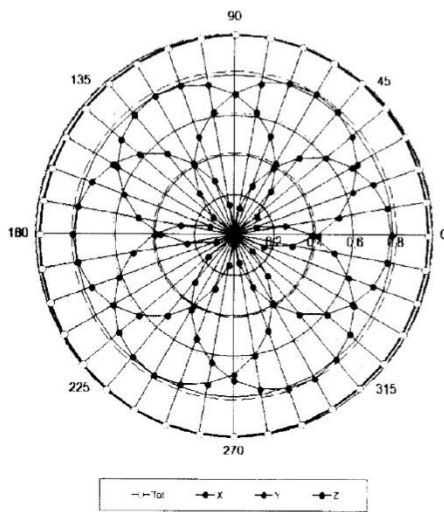
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Receiving Pattern (Φ), $\theta=0^\circ$

f=600 MHz, TEM

f=1800 MHz, R22



Uncertainty of Axial Isotropy Assessment: $\pm 1.2\%$ ($k=2$)



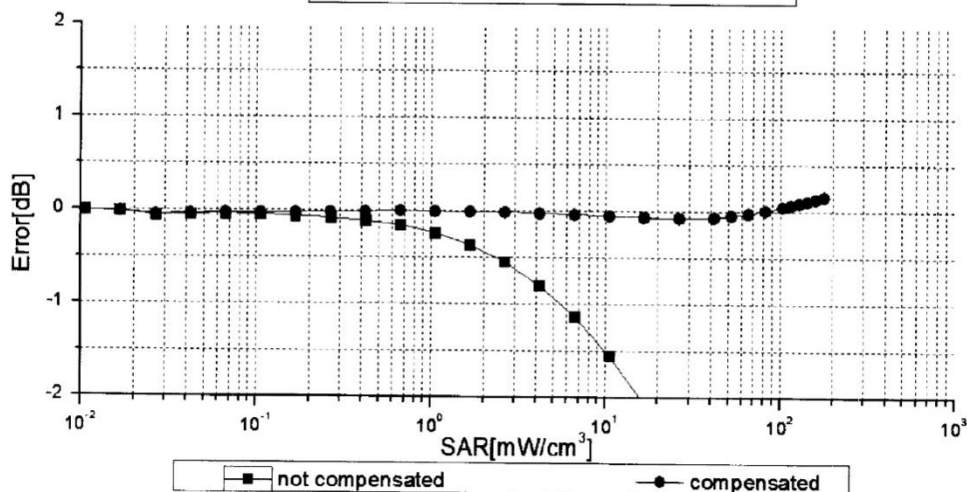
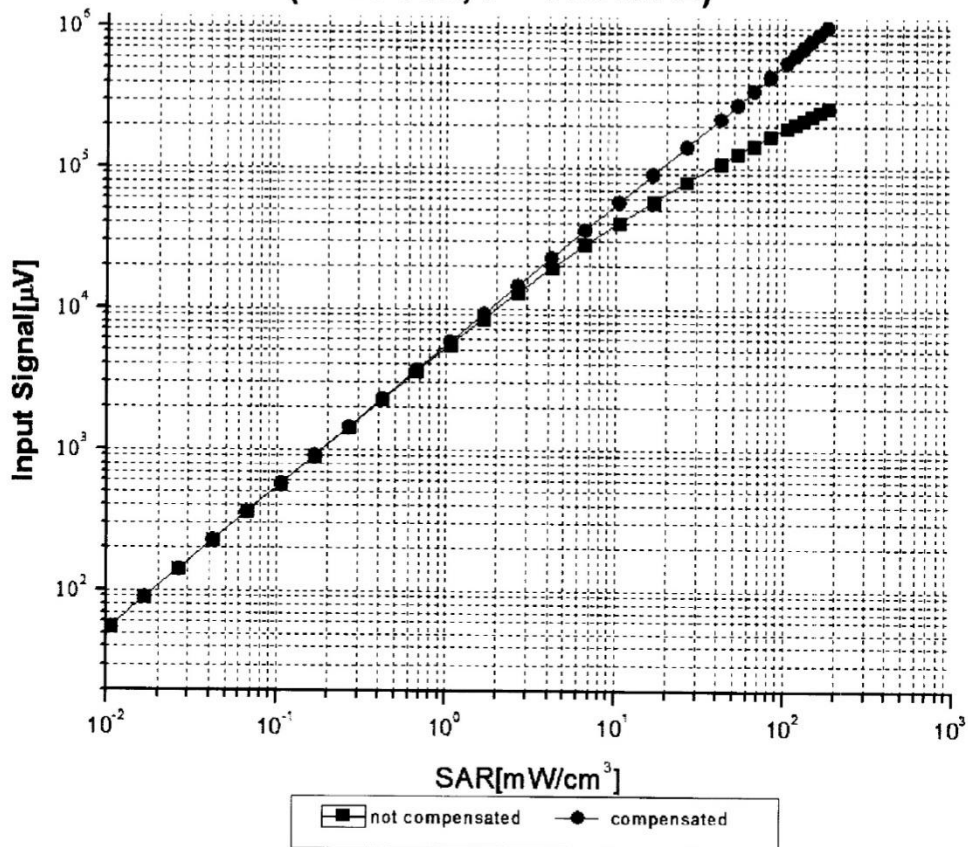


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Dynamic Range f(SAR_{head}) (TEM cell, f = 900 MHz)


Uncertainty of Linearity Assessment: $\pm 0.9\%$ ($k=2$)

Certificate No: Z18-98671

Page 9 of 11

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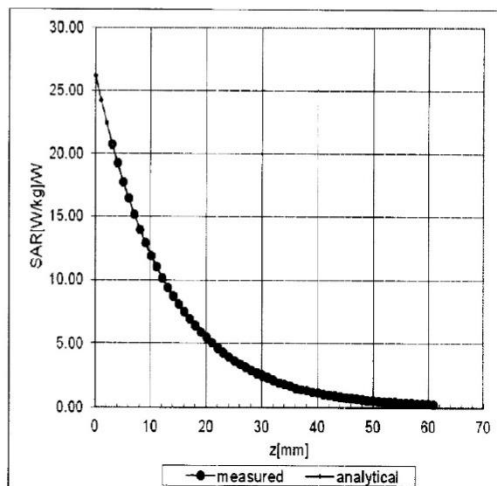
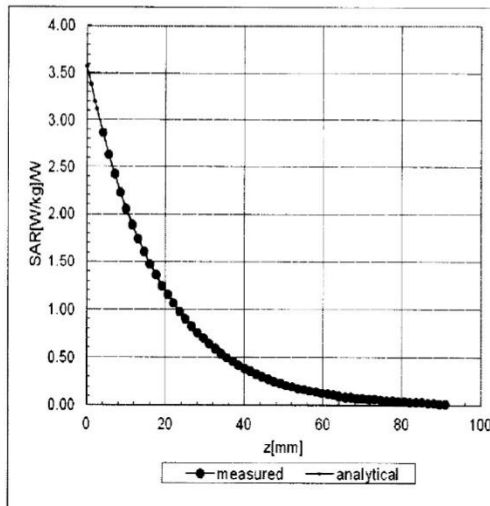


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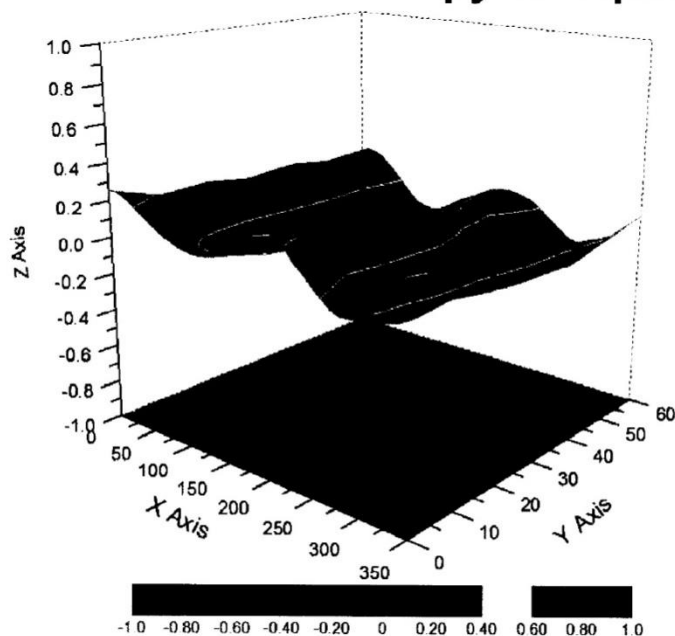
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Conversion Factor Assessment

f=900 MHz, WGLS R9(H_convF)**f=1750 MHz, WGLS R22(H_convF)**

Deviation from Isotropy in Liquid

**Uncertainty of Spherical Isotropy Assessment: $\pm 3.2\%$ (K=2)**



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DASY/EASY – Parameters of Probe: EX3DV4 – SN: 7396

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	156.9
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disable
Probe Overall Length	337mm
Probe Body Diameter	10mm
Tip Length	9mm
Tip Diameter	2.5mm
Probe Tip to Sensor X Calibration Point	1mm
Probe Tip to Sensor Y Calibration Point	1mm
Probe Tip to Sensor Z Calibration Point	1mm
Recommended Measurement Distance from Surface	1.4mm



Schmid & Partner Engineering AG

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IMPORTANT NOTICE

USAGE OF THE DAE 4

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

Battery Exchange: The battery cover of the DAE4 unit is closed using a screw, over tightening the screw may cause the threads inside the DAE to wear out.

Shipping of the DAE: Before shipping the DAE to SPEAG for calibration, remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

E-Stop Failures: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, the customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

Repair: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

DASY Configuration Files: Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

Important Note:

Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.

Important Note:

Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the E-stop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

Important Note:

To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.

Schmid & Partner Engineering

TN_BR040315AD DAE4.doc

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S Schweizerischer Kalibrierdienst
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S Swiss Calibration Service

Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA
Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 0108**

Client **Anbotek (Auden)**

Certificate No: **DAE4-387_Sep08**

CALIBRATION CERTIFICATE

Object **DAE4 - SD 000 D04 BM - SN: 387**

Calibration procedure(s) **QA CAL-06.v29
Calibration procedure for the data acquisition electronics (DAE)**

Calibration date: **September 06, 2018**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature $(22 \pm 3)^{\circ}\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	15-Aug-18 (No:21092)	Aug-19
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	05-Jan-18 (in house check)	In house check: Jan-19
Calibrator Box V2.1	SE UMS 006 AA 1002	05-Jan-18 (in house check)	In house check: Jan-19

Calibrated by:	Name Dominique Steffen	Function Laboratory Technician	Signature
Approved by:	Sven Kühn	Deputy Manager	

Issued: September 03, 2018

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

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Glossary

DAE data acquisition electronics
Connector angle information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- **DC Voltage Measurement:** Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- **Connector angle:** The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - **DC Voltage Measurement Linearity:** Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - **Common mode sensitivity:** Influence of a positive or negative common mode voltage on the differential measurement.
 - **Channel separation:** Influence of a voltage on the neighbor channels not subject to an input voltage.
 - **AD Converter Values with inputs shorted:** Values on the internal AD converter corresponding to zero input voltage
 - **Input Offset Measurement:** Output voltage and statistical results over a large number of zero voltage measurements.
 - **Input Offset Current:** Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - **Input resistance:** Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - **Low Battery Alarm Voltage:** Typical value for information. Below this voltage, a battery alarm signal is generated.
 - **Power consumption:** Typical value for information. Supply currents in various operating modes.



DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1μV , full range = -100...+300 mV

Low Range: 1LSB = 61nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.489 ± 0.02% (k=2)	404.852 ± 0.02% (k=2)	404.862 ± 0.02% (k=2)
Low Range	3.97827 ± 1.50% (k=2)	3.95875 ± 1.50% (k=2)	3.97982 ± 1.50% (k=2)

Connector Angle

Connector Angle to be used in DASY system	53.0 ° ± 1 °
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Appendix (Additional assessments outside the scope of SCS0108)

1. DC Voltage Linearity

High Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	200032.85	-3.31	-0.00
Channel X + Input	20007.64	1.88	0.01
Channel X - Input	-20003.48	1.18	-0.01
Channel Y + Input	200034.23	-1.43	-0.00
Channel Y + Input	20006.60	0.91	0.00
Channel Y - Input	-20004.04	0.72	-0.00
Channel Z + Input	200035.38	-0.83	-0.00
Channel Z + Input	20003.69	-2.11	-0.01
Channel Z - Input	-20006.38	-1.59	0.01

Low Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	2001.63	0.08	0.00
Channel X + Input	202.29	0.70	0.35
Channel X - Input	-197.90	0.60	-0.30
Channel Y + Input	2001.33	-0.07	-0.00
Channel Y + Input	200.86	-0.60	-0.30
Channel Y - Input	-199.87	-1.23	0.62
Channel Z + Input	2001.61	0.27	0.01
Channel Z + Input	200.60	-0.70	-0.35
Channel Z - Input	-199.51	-0.85	0.43

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	13.50	11.56
	- 200	-8.64	-11.18
Channel Y	200	-0.81	-1.28
	- 200	1.05	0.09
Channel Z	200	7.17	6.91
	- 200	-9.46	-9.01

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	-1.70	0.33
Channel Y	200	10.70	-	-0.38
Channel Z	200	7.11	7.89	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15969	17466
Channel Y	15661	16162
Channel Z	15990	16190

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

	Average (μ V)	min. Offset (μ V)	max. Offset (μ V)	Std. Deviation (μ V)
Channel X	0.73	-2.58	3.29	0.62
Channel Y	0.41	-0.49	1.23	0.40
Channel Z	-0.80	-1.88	0.30	0.42

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

	Zeroing (k Ω m)	Measuring (M Ω m)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9