

Hybrid Electronic Steering Terminal

Model : HT-ESA

FCCID : 2AUBBHSA-MAC

Name: LeopardWin

Scan Type: Hybrid Electronic
Steering

EIRP: 48.7dBW@0°

TX Frequency: 29.25~30GHz

POL: Full Polarization ,
Automatic Switching

Tracking Accuracy: $\leq 0.2^\circ$

Modem: XXXXX

WiFi/PWD: XXXXX

S/N: XXXXXXXXXXXXXXX

Types of Application: C0TM

Mechanical Steering Type: Auto

Frequency Band: Ka

Beam Switching Time: $\leq 3\text{ms}$

G/T: 11.4dB/K@ 0°

RX LO: 18.25/19.25 GHz

WEB IP/User/PWD: XXXXX



This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) This device must accept any interference received, including interference that may cause undesired operation.

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Hybrid Electronic Steering Terminal

Model: HT-E5A	S/N: XXXXXXXXXXXXX
FCCID: 2AURR5A-MAC	Type of Application: 011W
Name: Laserwin	Mechanical Steering Type: Auto
Scan Type: Hybrid Electronic Steering	Frequency Band: Ka
EIRP: 18.7dBW/2°	Scan Switching Time: 0.3ms
TX Frequency: 19.2~19.35GHz	G/T: 11.4dB/K @ 2°
POL: Full Polarization	RX LO: 18.7~19.35GHz
Automatic Switching	WEB IP / User: PWD: XXXXX
Tracking Accuracy: <0.2°	
Modem: XXXXX	
WiFi: PWD: XXXXX	

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