
SAR Test Report

Report No.: AGC10211260102FH01

FCC ID : 2AXWL-E2-TX

APPLICATION PURPOSE : Original Equipment

PRODUCT DESIGNATION : 2.4G wireless microphone system

BRAND NAME : SYNCO, SMART

MODEL NAME : E2-TX, E2 Pro-TX, E2 Max-TX, E2 AI-TX, E3-TX, E3 Pro-TX, E3 Max-TX, E3 AI-TX, E5-TX, E5 Pro-TX, E5 Max-TX, E5 AI-TX, E6-TX, E6 Pro-TX, E6 AI-TX, E8-TX, E8 Pro-TX, E8 AI-TX, AEM-1

APPLICANT : Guangzhou Zhiying Technology Co., Ltd

DATE OF ISSUE : Apr. 28, 2026

STANDARD(S) : IEEE Std. 1528:2013
FCC 47 CFR Part 2§2.1093
IEEE Std C95.1™-2019

REPORT VERSION : V1.0

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Report Revise Record

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	/	Apr. 28, 2026	Valid	Initial Release

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Test Report Certification

Applicant Name	Guangzhou Zhiying Technology Co., Ltd
Applicant Address	Room 2401, Room 2402, Room 2403, Room 2404, Room 2409, No. 68, Huadi Avenue Middle, Liwan District, Guangzhou
Manufacturer Name	Huizhou Dacom Technology Co., Ltd.
Manufacturer Address	No. 6-1, Shangxia Middle Road, Shangxia District, Dongjiang Science and Technology Park, Zhongkai High-tech Zone, Huizhou City, Guangdong Province, China
Factory Name	Huizhou Dacom Technology Co., Ltd.
Factory Address	No. 6-1, Shangxia Middle Road, Shangxia District, Dongjiang Science and Technology Park, Zhongkai High-tech Zone, Huizhou City, Guangdong Province, China
Product Designation	2.4G wireless microphone system
Brand Name	SYNCO, SMART
Model Name	E2-TX
Series Models	E2 Pro-TX, E2 Max-TX, E2 AI-TX, E3-TX, E3 Pro-TX, E3 Max-TX, E3 AI-TX, E5-TX, E5 Pro-TX, E5 Max-TX, E5 AI-TX, E6-TX, E6 Pro-TX, E6 AI-TX, E8-TX, E8 Pro-TX, E8 AI-TX, AEM-1
Declaration of Difference	All the same except the model name
EUT Voltage	DC3.7V by battery
Applicable Standard	IEEE Std. 1528:2013 FCC 47 CFR Part 2§2.1093 IEEE Std C95.1™-2019
Date of receipt of test item	Jan. 23, 2026
Test Date	Apr. 27, 2026
Report Template	AGCRT-US-2.4G/SAR (2021-04-20)

Note: The results of testing in this report apply to the product/system which was tested only.

Thea Huang

Prepared By

Thea Huang (Project Engineer)

Apr. 28, 2026

Jack Gui

Reviewed By

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Apr. 28, 2026

Angela Li

Approved By

Apr. 28, 2026

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Angela Li (Authorized Officer)

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1. SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Frequency Band	Highest Reported 1g-SAR(W/Kg)	SAR Test Limit (W/Kg)
	Body-worn with 0mm separation	
Custom SRD 2.4GHz	0.293	1.6
SAR Test Result	PASS	

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6W/Kg) specified in IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE Std C95.1™-2019 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v06
- KDB 865664 D01 SAR Measurement 100MHz to 6GHz v01r04

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2. GENERAL INFORMATION

2.1. EUT Description

General Information	
Product Designation	2.4G wireless microphone system
Test Model	E2-TX
Hardware Version	SMIC-V4.2
Software Version	V1.1
Device Category	Portable
RF Exposure Environment	Uncontrolled
Antenna Type	Chip antenna
Custom SRD 2.4GHz	
Operation Frequency	2404~2478MHz
Antenna Gain	4.3dBi
Type of modulation	GFSK
Conducted Peak Power	6.83dBm
Battery	DC 3.7 V & 100mAh

Note: 1.The sample used for testing is end product.

2. The test sample has no any deviation to the test method of standard mentioned in page 1.

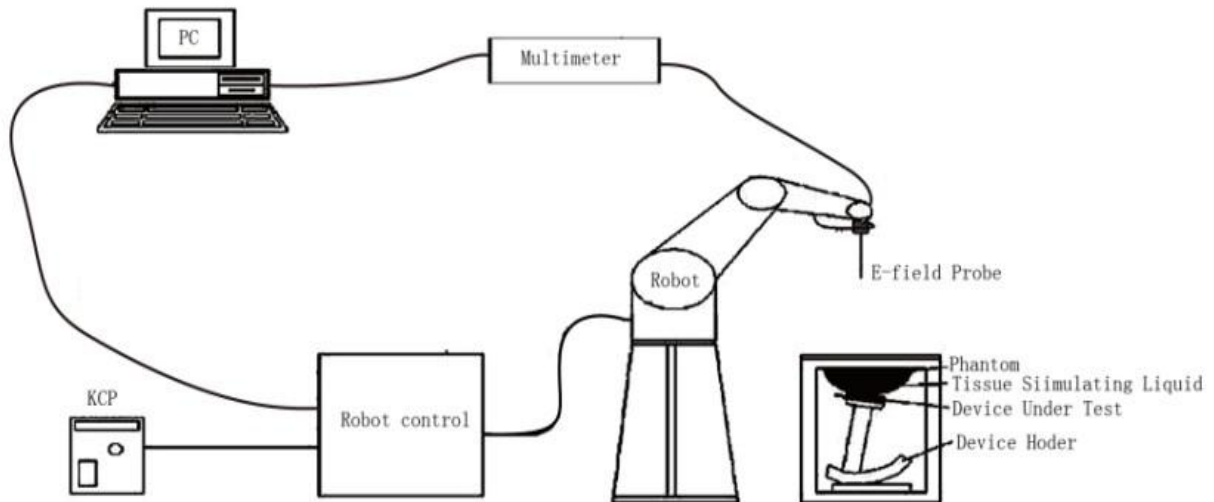
Product	Type
	☒ Production unit ☐ Identical Prototype

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3. SAR MEASUREMENT SYSTEM

3.1. The SATIMO system used for performing compliance tests consists of following items



The COMOSAR system for performing compliance tests consists of the following items:

- The PC. It controls most of the bench devices and stores measurement data. A computer running WinXP and the Opensar software.
- The E-Field probe. The probe is a 3-axis system made of 3 distinct dipoles. Each dipole returns a voltage in function of the ambient electric field.
- The Keithley multimeter measures each probe dipole voltages.
- The SAM phantom simulates a human head. The measurement of the electric field is made inside the phantom.
- The liquids simulate the dielectric properties of the human head tissues.
- The network emulator controls the mobile phone under test.
- The validation dipoles are used to measure a reference SAR. They are used to periodically check the bench to make sure that there is no drift of the system characteristics over time.
- The phantom, the device holder and other accessories according to the targeted measurement.

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3.2. COMOSAR E-Field Probe

The SAR measurement is conducted with the dosimetric probe manufactured by SATIMO. The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. SATIMO conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528 and relevant KDB files.) The calibration data are in Appendix D.

Isotropic E-Field Probe Specification

Model	SSE2		
Manufacture	MVG		
Identification No.	2023-EPGO-414		
Frequency	0.15GHz-7.5GHz Linearity:±0.10dB(0.15GHz-7.5GHz)		
Dynamic Range	0.01W/kg-100W/kg Linearity:±0.10dB		
Dimensions	Overall length:330mm Length of individual dipoles:2mm Maximum external diameter:8mm Probe Tip external diameter:2.5mm Distance between dipoles/ probe extremity:1mm		
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precisin of better 30%.		

3.3. Robot

The COMOSAR system uses the KUKA robot from SATIMO SA (France). For the 6-axis controller COMOSAR system, the KUKA robot controller version from SATIMO is used.

The XL robot series have many features that are important for our application:

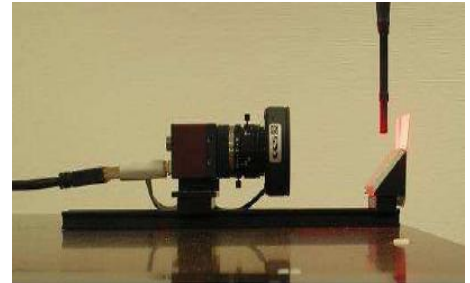
- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller



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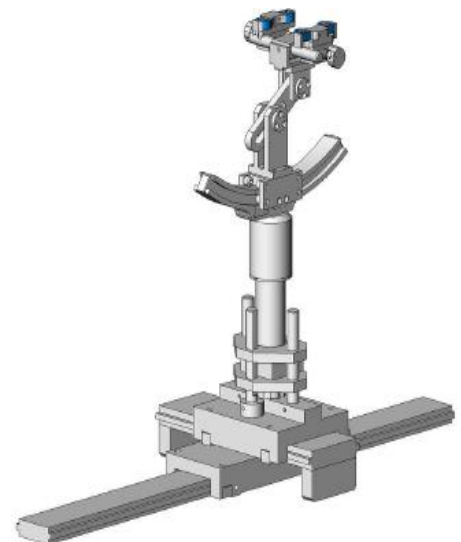
3.4. Video Positioning System

The video positioning system is used in OpenSAR to check the probe. Which is composed of a camera, LED, mirror and mechanical parts. The camera is piloted by the main computer with firewire link. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.



3.5. Device Holder

The COMOSAR device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR). Thus the device needs no repositioning when changing the angles. The COMOSAR device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon_r = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



3.6. SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left head
- Right head
- Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

ELLI39 Phantom

The Flat phantom is a fiberglass shellphantom with 2mm+/- 0.2 mm shell thickness. It has only one measurement area for Flat phantom



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4. SAR MEASUREMENT PROCEDURE

4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element(dv) of given mass density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg)

SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \left. \frac{dT}{dt} \right|_{t=0}$$

Where

SAR	is the specific absorption rate in watts per kilogram;
E	is the r.m.s. value of the electric field strength in the tissue in volts per meter;
σ	is the conductivity of the tissue in siemens per metre;
ρ	is the density of the tissue in kilograms per cubic metre;
c _h	is the heat capacity of the tissue in joules per kilogram and Kelvin;

$\left. \frac{dT}{dt} \right|_{t=0}$ is the initial time derivative of temperature in the tissue in kelvins per second

4.2. SAR Measurement Procedure

Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties,

Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in SATIMO software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	$\leq 3 \text{ GHz}$	$> 3 \text{ GHz}$
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	$5 \pm 1 \text{ mm}$	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$
Maximum probe angle from probe axis to phantom surface normal at the measurement location	$30^\circ \pm 1^\circ$	$20^\circ \pm 1^\circ$
Maximum area scan spatial resolution: $\Delta x_{\text{Area}}, \Delta y_{\text{Area}}$	$\leq 2 \text{ GHz}: \leq 15 \text{ mm}$ $2 - 3 \text{ GHz}: \leq 12 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 12 \text{ mm}$ $4 - 6 \text{ GHz}: \leq 10 \text{ mm}$
	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be $\leq$ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g and 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

Maximum zoom scan spatial resolution: Δx_{Zoom} , Δy_{Zoom}			$\leq 2 \text{ GHz}: \leq 8 \text{ mm}$ $2 - 3 \text{ GHz}: \leq 5 \text{ mm}^*$	$3 - 4 \text{ GHz}: \leq 5 \text{ mm}^*$ $4 - 6 \text{ GHz}: \leq 4 \text{ mm}^*$
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$		$\leq 5 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 4 \text{ mm}$ $4 - 5 \text{ GHz}: \leq 3 \text{ mm}$ $5 - 6 \text{ GHz}: \leq 2 \text{ mm}$
	graded grid	$\Delta z_{Zoom}(1)$: between 1 st two points closest to phantom surface	$\leq 4 \text{ mm}$	$3 - 4 \text{ GHz}: \leq 3 \text{ mm}$ $4 - 5 \text{ GHz}: \leq 2.5 \text{ mm}$ $5 - 6 \text{ GHz}: \leq 2 \text{ mm}$
		$\Delta z_{Zoom}(n>1)$: between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$	
Minimum zoom scan volume	x, y, z		$\geq 30 \text{ mm}$	$3 - 4 \text{ GHz}: \geq 28 \text{ mm}$ $4 - 5 \text{ GHz}: \geq 25 \text{ mm}$ $5 - 6 \text{ GHz}: \geq 22 \text{ mm}$
Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.				
* When zoom scan is required and the <u>reported</u> SAR from the <i>area scan based 1-g SAR estimation</i> procedures of KDB 447498 is $\leq 1.4 \text{ W/kg}$, $\leq 8 \text{ mm}$, $\leq 7 \text{ mm}$ and $\leq 5 \text{ mm}$ zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.				

Step 4: Power Drift Measurement

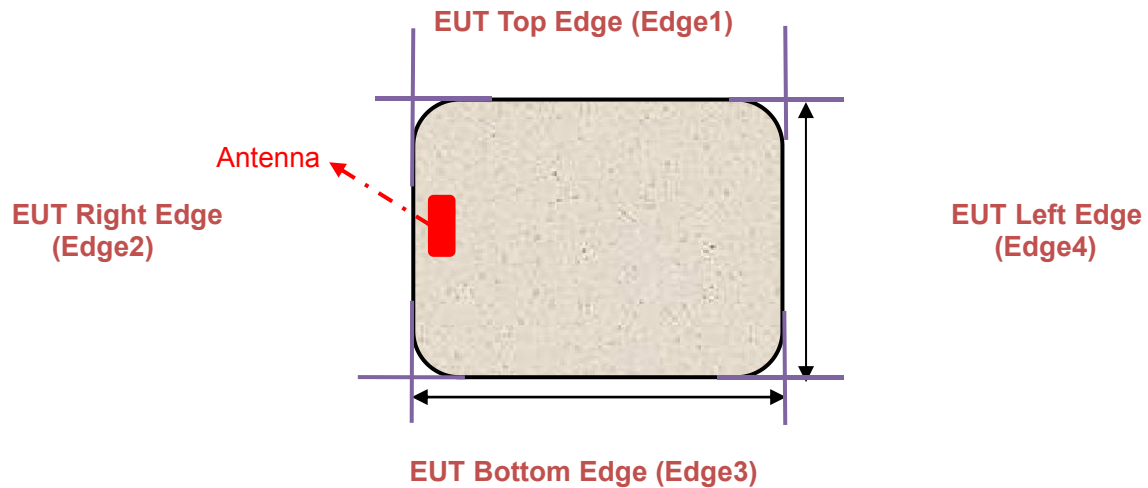
The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

4.3. RF Exposure Conditions

Test Configuration and setting:

The manufacturer has pre-programmed the chip so that it boots up immediately upon power-on.

Antenna Location: (the back view)



Test Configurations	Antenna to edges/surface
Edge 1 (Top)	12mm
Edge 2 (Right)	2mm
Edge 3 (Bottom)	10mm
Edge 4 (Left)	26mm

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5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 5.2

5.1. The composition of the tissue simulating liquid

Ingredient (% Weight) Frequency (MHz)	Water	Nacl	Polysorbate 20	DGBE	1,2 Propanediol	Triton X-100
2450 Head	71.88	0.16	0.0	7.99	0.0	19.97

5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in IEEE 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in IEEE 1528.

Target Frequency (MHz)	head		body	
	ϵ_r	σ (S/m)	ϵ_r	σ (S/m)
300	45.3	0.87	45.3	0.87
450	43.5	0.87	43.5	0.87
835	41.5	0.90	41.5	0.90
900	41.5	0.97	41.5	0.97
915	41.5	1.01	41.5	1.01
1450	40.5	1.20	40.5	1.20
1610	40.3	1.29	40.3	1.29
1800 – 2000	40.0	1.40	40.0	1.40
2450	39.2	1.80	39.2	1.80
3000	38.5	2.40	38.5	2.40

(ϵ_r = relative permittivity, σ = conductivity and $\rho = 1000 \text{ kg/m}^3$)

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5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using SATIMO Dielectric Probe Kit and R&S Network Analyzer ZVL6.

Tissue Stimulant Measurement for 2450MHz							
Head	Fr. (MHz)	Dielectric Parameters ($\pm 5\%$)		Ambient Temp [°C]	Relative Humidity (%)	Tissue Temp [°C]	Test time
		ϵ_r 39.2 (37.24-41.16)	δ [s/m] 1.80(1.71-1.89)				
	2404	40.16	1.73	21.6	58.9	21.8	Apr. 27, 2026
	2440	39.76	1.76				
	2450	38.66	1.81				
	2478	38.92	1.83				

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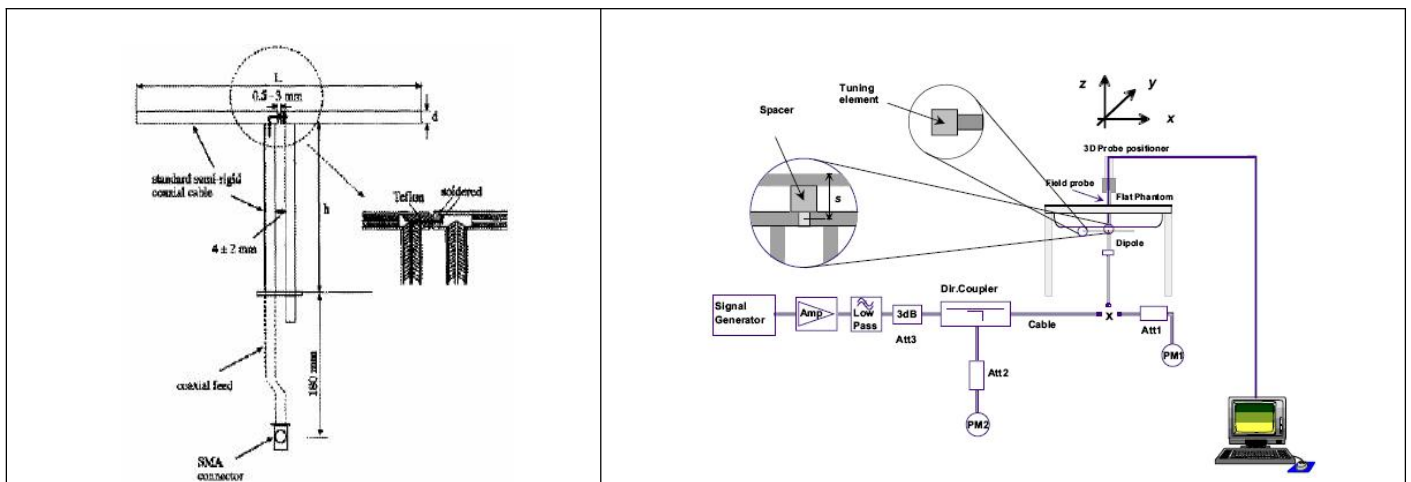
6. SAR SYSTEM CHECK PROCEDURE

6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each SATIMO system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the SATIMO software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

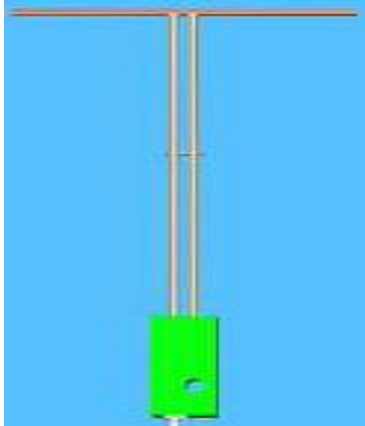
The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.



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6.2. SAR System Check

6.2.1. Dipoles

	The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of IEEE. the table below provides details for the mechanical and electrical Specifications for the dipoles.
---	---

Frequency	L (mm)	h (mm)	d (mm)
2450MHz	51.5	30.4	3.6

6.2.2. System Check Result

System Performance Check at 2450MHz for Head							
Validation Kit: SN 2915 DIP 2G450-393							
Frequency [MHz]	Target Value(W/Kg)		Reference Result ($\pm 10\%$)		Tested Value(W/Kg)		Test time
	1g	10g	1g	10g	1g	10g	
2450	52.85	24.53	47.57-58.14	22.08-26.98	54.74	24.95	Apr. 27, 2026

Note:

(1) We use a CW signal of 15dBm for system check, and then all SAR values are normalized to 1W forward power. The result must be within $\pm 10\%$ of target value.

7. EUT TEST POSITION

This EUT was tested in **Body back, Body front and 4 edges**

7.1. Body Part Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **0mm**

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8. SAR EXPOSURE LIMITS

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit (W/kg)
Spatial Peak SAR (1g cube tissue for brain or body)	1.60
Spatial Average SAR (Whole body)	0.08
Spatial Peak SAR (Limbs)	4.0

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9. TEST FACILITY

Test Site	Attestation of Global Compliance (Shenzhen) Co., Ltd
Location	1-2/F, Building 19, Junfeng Industrial Park, Chongqing Road, Heping Community, Fuhai Street, Bao'an District, Shenzhen, Guangdong, China
Designation Number	CN1259
FCC Test Firm Registration Number	975832
A2LA Cert. No.	5054.02
Description	Attestation of Global Compliance(Shenzhen) Co., Ltd is accredited by A2LA

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10. TEST EQUIPMENT LIST

No.	Equipment description	Manufacturer/ Model	Identification No.	Software version	Current calibration date	Next calibration date
AGC-HE-A103	SAR Probe	MVG	2023-EPGO-414	N/A	2025-05-06	2026-05-05
AGC-HE-A071	Phantom	SATIMO	SN_2316_ELLI39	N/A	Validated. No cal required.	Validated. No cal required.
AGC-HE-A073	Multimeter	Keithley 2000	4114939	N/A	2025-05-16	2026-05-15
AGC-HE-S003	SAR Software	MVG-OpenSAR	N/A	V5.3.15.8	N/A	N/A
AGC-HE-A061	Dipole	SATIMO SID2450	SN 2915 DIP 2G450-393	N/A	2025-05-16	2028-05-15
AGC-HE-E021	Signal Generator	Agilent-E4438C	US41461365	V5.03	2025-05-21	2026-05-20
AGC-EM-E061	EXA Signal Analyzer	Agilent / N9010A	MY53470504	N/A	2025-05-08	2026-05-07
AGC-HE-E004	Network Analyzer	Rhode & Schwarz ZVL6	101443	3.2	2025-07-18	2026-07-17
AGC-ER-A001	Attenuator	SMA-JK	N/A	N/A	2025-09-05	2027-09-04
AGC-EM-E019	Amplifier	AS0104-55_55	1004793	N/A	N/A	N/A
AGC-EM-E040	Directional Couple	Werlatone/ C5571-10	SN99463	N/A	2026-01-13	2028-01-12
AGC-EM-E041	Directional Couple	Werlatone/ C6026-10	SN99482	N/A	2026-01-13	2028-01-12
AGC-BQ-E016	Power Sensor	NRP-Z21	104604	N/A	2025-05-16	2026-05-15
AGC-HE-E023	Power Sensor	NRP-Z23	100323	N/A	2026-01-13	2027-01-12
AGC-HE-S004	Power Viewer	R&S	V2.3.1.0	N/A	N/A	N/A
AGC-HE-A001	Calibration standard parts for network sub - port	R&S/ ZV-Z132	100707	V2.3.1.0	2025-10-30	2026-10-29
AGC-HE-A002	Thermometer	DigiMate/TP677	3811930452	N/A	2025-05-24	2027-05-23

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

1. There is no physical damage on the dipole;
2. System validation with specific dipole is within 10% of calibrated value;
3. Return-loss is within 20% of calibrated measurement;
4. Impedance is within 5Ω of calibrated measurement.

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11. MEASUREMENT UNCERTAINTY

SATIMO Uncertainty- 2023-EPGO-414 Measurement uncertainty for DUT averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+-%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	vi
Measurement System									
Probe calibration	E.2.1	7.000	N	1	1	1	7.000	7.000	∞
Axial Isotropy	E.2.2	0.105	R	1.732	0.707	0.707	0.043	0.043	∞
Hemispherical Isotropy	E.2.2	0.105	R	1.732	0.707	0.707	0.043	0.043	∞
Boundary effect	E.2.3	1.000	R	1.732	1	1	0.577	0.577	∞
Linearity	E.2.4	1.105	R	1.732	1	1	0.638	0.638	∞
System detection limits	E.2.4	1.000	R	1.732	1	1	0.577	0.577	∞
Modulation response	E.2.5	3.000	R	1.732	1	1	1.732	1.732	∞
Readout Electronics	E.2.6	0.021	N	1	1	1	0.021	0.021	∞
Response Time	E.2.7	0.000	R	1.732	1	1	0.000	0.000	∞
Integration Time	E.2.8	1.400	R	1.732	1	1	0.808	0.808	∞
RF ambient conditions-Noise	E.6.1	3.000	R	1.732	1	1	1.732	1.732	∞
RF ambient conditions-reflections	E.6.1	3.000	R	1.732	1	1	1.732	1.732	∞
Probe positioner mechanical tolerance	E.6.2	1.400	R	1.732	1	1	0.808	0.808	∞
Probe positioning with respect to phantom shell	E.6.3	1.400	R	1.732	1	1	0.808	0.808	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.300	R	1.732	1	1	1.328	1.328	∞
Test sample Related									
Test sample positioning	E.4.2	2.6	N	1	1	1	2.60	2.60	∞
Device holder uncertainty	E.4.1	3	N	1	1	1	3.00	3.00	∞
Output power variation—SAR drift measurement	E.2.9	5	R	1.732	1	1	2.89	2.89	∞
SAR scaling	E.6.5	5	R	1.732	1	1	2.89	2.89	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	1.732	1	1	2.309	2.309	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.900	1.596	∞
Liquid conductivity measurement	E.3.3	4	N	1	0.78	0.71	3.120	2.840	M
Liquid permittivity measurement	E.3.3	5	N	1	0.23	0.26	1.150	1.300	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	1.732	0.78	0.71	1.126	1.025	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	1.732	0.23	0.26	0.332	0.375	∞
Combined Standard Uncertainty			RSS				10.533	10.348	
Expanded Uncertainty (95% Confidence interval)			K=2				21.065	20.695	

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SATIMO Uncertainty- 2023-EPGO-414									
System Validation uncertainty for DUT averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+-%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	vi
Measurement System									
Probe calibration	E.2.1	7.000	N	1	1	1	7.000	7.000	∞
Axial Isotropy	E.2.2	0.105	R	1.732	1.000	1.000	0.061	0.061	∞
Hemispherical Isotropy	E.2.2	0.105	R	1.732	0.000	0.000	0.000	0.000	∞
Boundary effect	E.2.3	1.000	R	1.732	1.000	1.000	0.577	0.577	∞
Linearity	E.2.4	1.105	R	1.732	1.000	1.000	0.638	0.638	∞
System detection limits	E.2.4	1.000	R	1.732	1.000	1.000	0.577	0.577	∞
Modulation response	E.2.5	3.000	R	1.732	0.000	0.000	0.000	0.000	∞
Readout Electronics	E.2.6	0.021	N	1.000	1.000	1.000	0.021	0.021	∞
Response Time	E.2.7	0.000	R	1.732	0.000	0.000	0.000	0.000	∞
Integration Time	E.2.8	1.400	R	1.732	0.000	0.000	0.000	0.000	∞
RF ambient conditions-Noise	E.6.1	3.000	R	1.732	1.000	1.000	1.732	1.732	∞
RF ambient conditions-reflections	E.6.1	3.000	R	1.732	1.000	1.000	1.732	1.732	∞
Probe positioner mechanical tolerance	E.6.2	1.400	R	1.732	1.000	1.000	0.808	0.808	∞
Probe positioning with respect to phantom shell	E.6.3	1.400	R	1.732	1.000	1.000	0.808	0.808	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.300	R	1.732	1.000	1.000	1.328	1.328	∞
System validation source									
Deviation of experimental dipole from numerical dipole	E.6.4	5	N	1	1	1	5	5	∞
Input power and SAR drift measurement	8,6.6.4	5	R	1.732	1	1	2.887	2.887	∞
Dipole axis to liquid distance	8,E.6.6	2	R	1.732	1	1	1.155	1.155	∞
Phantom and set-up									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	1.732	1	1	2.309	2.309	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1	1	0.84	1.9	1.596	∞
Liquid conductivity (temperature uncertainty)	E.3.3	4	N	1	0.78	0.71	3.12	2.84	∞
Liquid conductivity (measured)	E.3.3	5	N	1	0.23	0.26	1.15	1.3	M
Liquid permittivity (temperature uncertainty)	E.3.4	2.5	R	1.732	0.78	0.71	1.126	1.025	∞
Liquid permittivity (measured)	E.3.4	2.5	R	1.732	0.23	0.26	0.332	0.375	M
Combined Standard Uncertainty			RSS				10.466	10.279	
Expanded Uncertainty (95% Confidence interval)			K=2				20.931	20.559	

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SATIMO Uncertainty- 2023-EPGO-414									
System Check uncertainty for DUT averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+-%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	vi
Measurement System									
Probe calibration drift	E.2.1.3	0.500	N	1	1	1	0.5	0.5	∞
Axial Isotropy	E.2.2	0.105	R	1.732	0	0	0	0	∞
Hemispherical Isotropy	E.2.2	0.105	R	1.732	0	0	0	0	∞
Boundary effect	E.2.3	1.000	R	1.732	0	0	0	0	∞
Linearity	E.2.4	1.105	R	1.732	0	0	0	0	∞
System detection limits	E.2.4	1	R	1.732	0	0	0	0	∞
Modulation response	E.2.5	3	R	1.732	0	0	0	0	∞
Readout Electronics	E.2.6	0.021	N	1	0	0	0	0	∞
Response Time	E.2.7	0	R	1.732	0	0	0	0	∞
Integration Time	E.2.8	1.4	R	1.732	0	0	0	0	∞
RF ambient conditions-Noise	E.6.1	3	R	1.732	0	0	0	0	∞
RF ambient conditions-reflections	E.6.1	3	R	1.732	0	0	0	0	∞
Probe positioner mechanical tolerance	E.6.2	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Probe positioning with respect to phantom shell	E.6.3	1.4	R	$\sqrt{3}$	1	1	0.81	0.81	∞
Extrapolation, interpolation, and integrations algorithms for max. SAR evaluation	E.5	2.3	R	$\sqrt{3}$	0	0	0	0.00	∞
System check source (dipole)									
Deviation of experimental dipoles	E.6.4	2	N	1	1	1	2	2	∞
Input power and SAR drift measurement	8,6.6.4	5	R	$\sqrt{3}$	1	1	2.89	2.89	∞
Dipole axis to liquid distance	8,E.6.6	2	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Phantom and tissue parameters									
Phantom shell uncertainty—shape, thickness, and permittivity	E.3.1	4	R	$\sqrt{3}$	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviations in permittivity and conductivity	E.3.2	1.9	N	1.000	1	0.84	1.90	1.60	∞
Liquid conductivity measurement	E.3.3	4	N	1.000	0.78	0.71	3.12	2.84	∞
Liquid permittivity measurement	E.3.3	5	N	1.000	0.23	0.26	1.15	1.30	M
Liquid conductivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.78	0.71	1.13	1.02	∞
Liquid permittivity—temperature uncertainty	E.3.4	2.5	R	$\sqrt{3}$	0.23	0.26	0.33	0.38	M
Combined Standard Uncertainty			RSS				5.562	5.203	
Expanded Uncertainty (95% Confidence interval)			K=2				11.124	10.406	

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12. CONDUCTED POWER MEASUREMENT

Custom SRD 2.4GHz

Modulation	Channel	Frequency(MHz)	Peak Power (dBm)
GFSK	1	2404	5.16
	19	2440	6.74
	38	2478	6.83

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13. TEST RESULTS

13.1. SAR Test Results Summary

13.1.1. Test position and configuration

Body SAR was performed with the device 0mm from the phantom

13.1.2. Operation Mode

1. Per KDB 447498 D01 v06 ,for each exposure position, if the highest 1-g SAR is ≤ 0.8 W/kg, testing for low and high channel is optional.
2. Per KDB 865664 D01 v01r04,for each frequency band, if the measured SAR is ≥ 0.8 W/Kg, testing for repeated SAR measurement is required , that the highest measured SAR is only to be tested. When the SAR results are near the limit, the following procedures are required for each device to verify these types of SAR measurement related variation concerns by repeating the highest measured SAR configuration in each frequency band.
 - (1) When the original highest measured SAR is ≥ 0.8 W/Kg, repeat that measurement once.
 - (2) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is >1.20 or when the original or repeated measurement is ≥ 1.45 W/Kg.
 - (3) Perform a third repeated measurement only if the original, first and second repeated measurement is ≥ 1.5 W/Kg and ratio of largest to smallest SAR for the original, first and second measurement is ≥ 1.20 .
3. Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:
Maximum Scaling SAR =tested SAR (Max.) $\times$ [maximum turn-up power (mW)/ maximum measurement output power(mW)]

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13.1.3. Test Result

SAR MEASUREMENT										
Depth of Liquid (cm):>15										
Product: 2.4G wireless microphone system										
Test Mode: Custom SRD 2.4GHz										
Position	Mode	Ch.	Fr. (MHz)	Power Drift (<±5%)	SAR (1g) (W/kg)	Max. Tune-up Power (dBm)	Meas. output Power (dBm)	Tune-up Scaling factor	Scaled SAR (W/kg)	Limit W/kg
Body back	GFSK	38	2478	1.870	0.117	6.90	6.74	1.038	0.121	1.6
Body front	GFSK	1	2404	-1.860	0.196	6.90	5.16	1.493	0.293	1.6
Body front	GFSK	19	2440	-3.700	0.184	6.90	6.74	1.038	0.191	1.6
Body front	GFSK	38	2478	-4.730	0.200	6.90	6.83	1.016	0.203	1.6
Edge 1 (Top)	GFSK	38	2478	0.270	0.048	6.90	6.74	1.038	0.050	1.6
Edge 2 (Right)	GFSK	38	2478	1.440	0.060	6.90	6.74	1.038	0.062	1.6
Edge 3 (Bottom)	GFSK	38	2478	-2.330	0.046	6.90	6.74	1.038	0.048	1.6
Edge 4 (Left)	GFSK	38	2478	-2.620	0.027	6.90	6.74	1.038	0.028	1.6

Note:

(1)When the 1-g Reported SAR is ≤ 0.8 W/kg, testing for low and high channel is optional. Refer to KDB 447498.

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APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab

Date: Apr. 27, 2026

System Check Head 2450 MHz

DUT: Dipole 2450 MHz Type: SID 2450

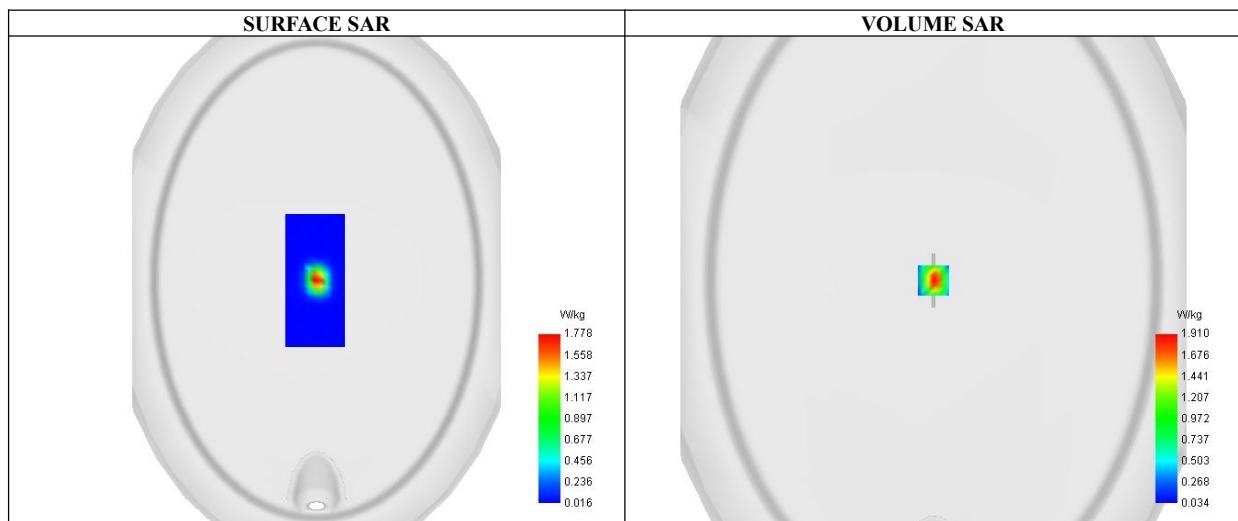
Communication System CW; Communication System Band: D2450 (2450.0 MHz); Duty Cycle: 1:1; Conv.F=2.29
Frequency: 2450 MHz; Medium parameters used: $f = 2450$ MHz; $\sigma = 1.81$ mho/m; $\epsilon_r = 38.66$; $\rho = 1000$ kg/m³ ;
Phantom section: Flat Section; Input Power=15dBm

SATIMO Configuration

- Probe: SSE2; Calibrated: 2025-05-06; Serial No.: 2023-EPGO-414
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: ELLI39 phantom
- Measurement SW: OpenSAR V5.3.15.8

Configuration/System Check 2450MHz Head/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/System Check 2450MHz Head/Zoom Scan: Measurement grid: dx=5mm, dy=5mm, dz=5mm



Maximum location: X=0.00, Y=0.00 ; SAR Peak: 3.24 W/kg

SAR 10g (W/Kg)	0.789
SAR 1g (W/Kg)	1.731
Variation (%)	1.060
Horizontal validation criteria: minimum distance (mm)	10.000000
Vertical validation criteria: SAR ratio M2/M1 (%)	48.896130

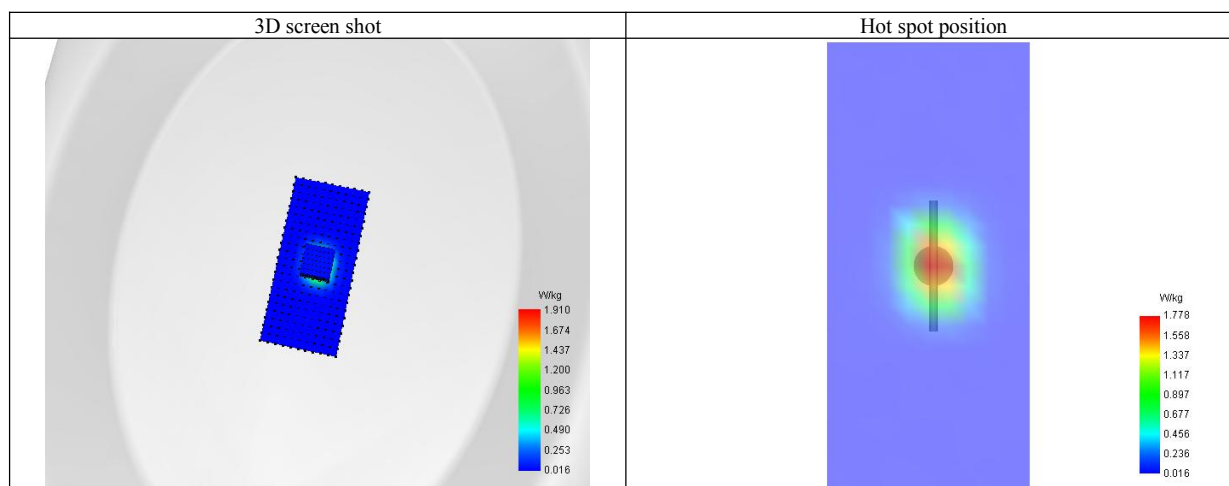
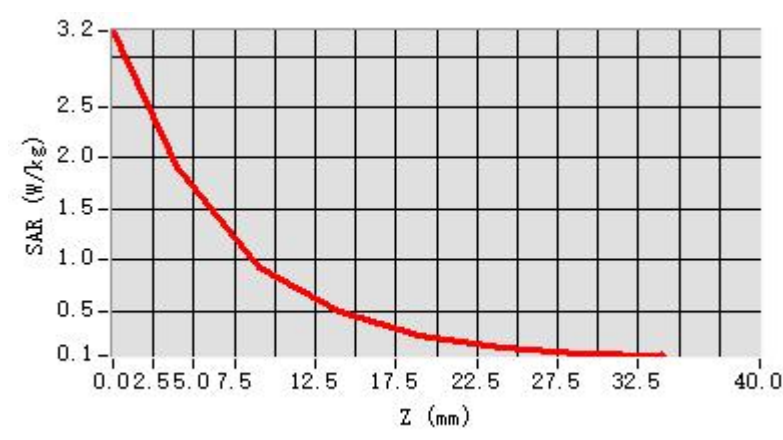
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Z (mm)	0.00	4.00	9.00	14.00	19.00	24.00	29.00
SAR (W/Kg)	3.246	1.910	0.934	0.485	0.253	0.139	0.084



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APPENDIX B. SAR MEASUREMENT DATA

Test Laboratory: AGC Lab

Date: Apr. 27, 2026

Custom SRD 2.4GHz Low-Body-Worn- Front

DUT: 2.4G wireless microphone system; Type: E2-TX

Communication System: Custom SRD 2.4GHz; Communication System Band: Custom SRD 2.4GHz; Duty Cycle: 1:1; Conv.F=2.29;

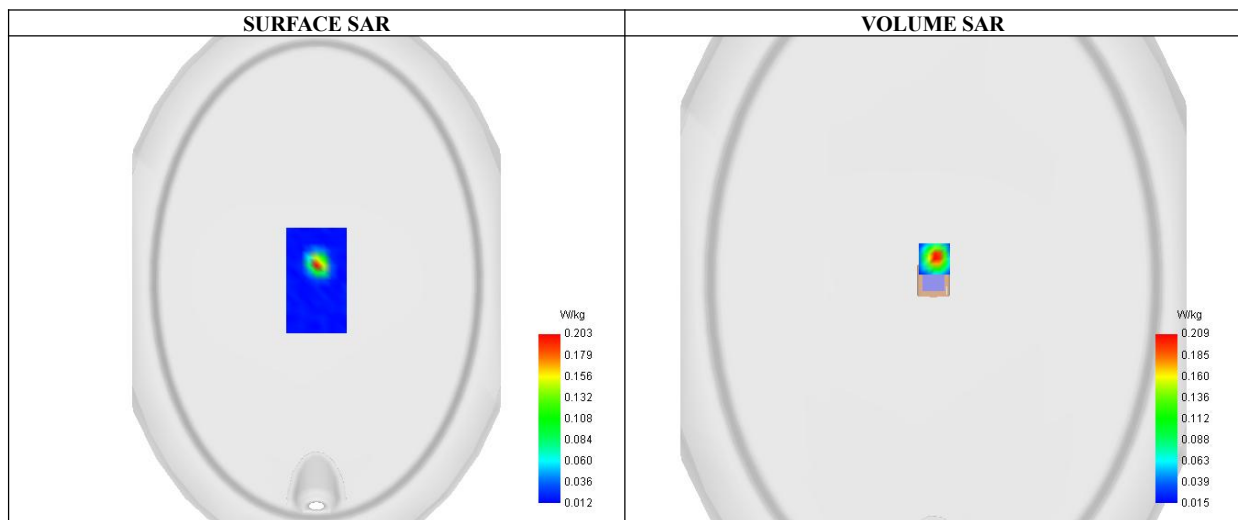
Frequency: 2404 MHz; Medium parameters used: $f = 2450$ MHz; $\sigma = 1.73$ mho/m; $\epsilon_r = 40.16$; $\rho = 1000$ kg/m³ ; Phantom section: Flat Section

SATIMO Configuration:

- Probe: SSE2; Calibrated: 2025-05-06; Serial No.: 2023-EPGO-414
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: ELLI39 phantom
- Measurement SW: OpenSAR V5.3.15.8

Configuration/Custom SRD 2.4GHz Low- Body- Front /Area Scan: Measurement grid: dx=8mm, dy=8mm
Configuration/Custom SRD 2.4GHz Low- Body- Front /Zoom Scan: Measurement grid: dx=5mm,dy=5mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm
ZoomScan	7x7x7,dx=5mm dy=5mm dz=5mm
Phantom	ELLI
Device Position	Body Front
Band	Custom SRD 2.4GHz
Channels	Low
Signal	Crest factor: 1.0



Maximum location: X=1.00, Y=21.00 ; SAR Peak: 0.40 W/kg

SAR 10g (W/Kg)	0.084
SAR 1g (W/Kg)	0.196
Variation (%)	-1.860
Horizontal validation criteria: minimum distance (mm)	10.000000
Vertical validation criteria: SAR ratio M2/M1 (%)	46.894867

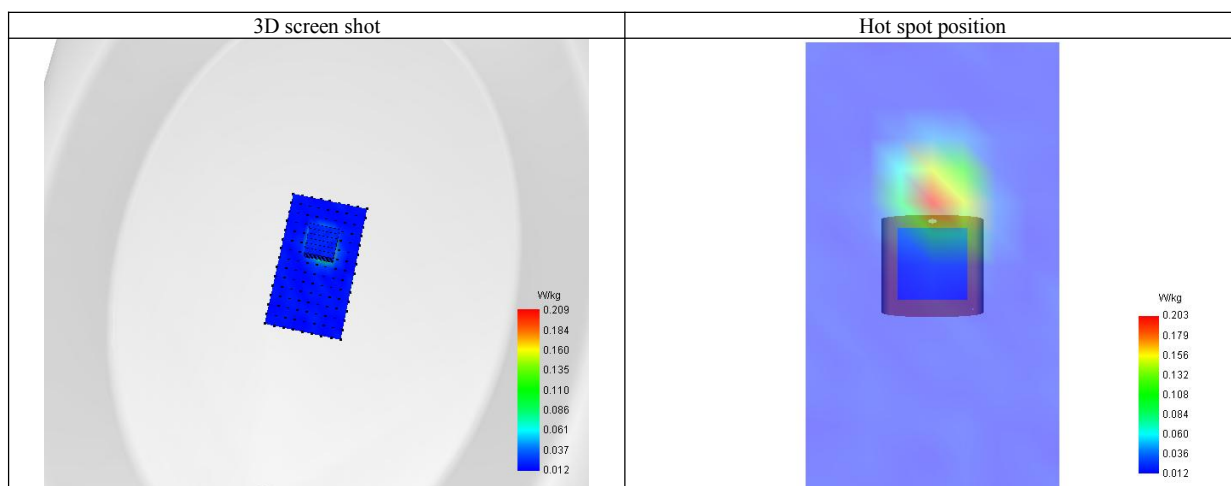
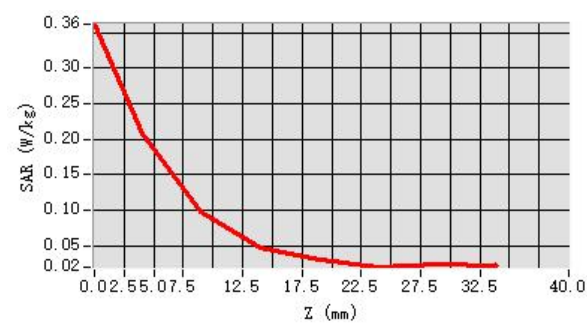
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Z (mm)	0.00	4.00	9.00	14.00	19.00	24.00	29.00
SAR (W/Kg)	0.362	0.209	0.098	0.047	0.030	0.020	0.024



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Test Laboratory: AGC Lab
Custom SRD 2.4GHz High-Body-Worn- Front
DUT: 2.4G wireless microphone system; Type: E2-TX

Date: Apr. 27, 2026

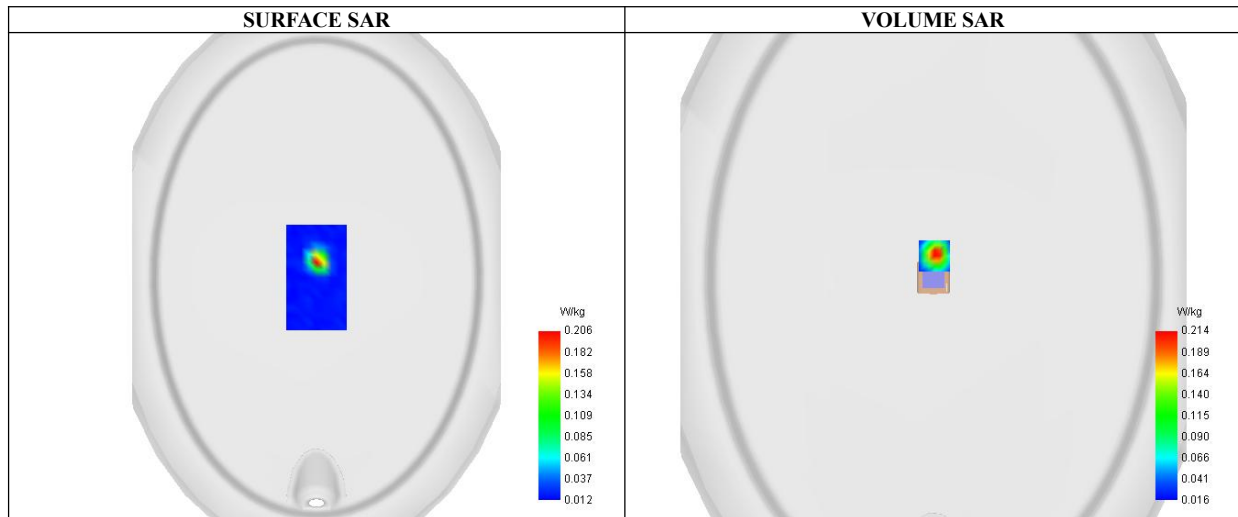
Communication System: Custom SRD 2.4GHz; Communication System Band: Custom SRD 2.4GHz; Duty Cycle: 1:1; Conv.F=2.29;
Frequency: 2478 MHz; Medium parameters used: $f = 2450$ MHz; $\sigma = 1.83$ mho/m; $\epsilon_r = 38.92$; $\rho = 1000$ kg/m³ ;
Phantom section: Flat Section

SATIMO Configuration:

- Probe: SSE2; Calibrated: 2025-05-06; Serial No.: 2023-EPGO-414
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Phantom: ELLI39 phantom
- Measurement SW: OpenSAR V5.3.15.8

Configuration/Custom SRD 2.4GHz High- Body- Front /Area Scan: Measurement grid: dx=8mm, dy=8mm
Configuration/Custom SRD 2.4GHz High- Body- Front /Zoom Scan: Measurement grid: dx=5mm,dy=5mm, dz=5mm;

Area Scan	dx=8mm dy=8mm, h= 5.00 mm
ZoomScan	7x7x7,dx=5mm dy=5mm dz=5mm
Phantom	ELLI
Device Position	Body Front
Band	Custom SRD 2.4GHz
Channels	High
Signal	Crest factor: 1.0



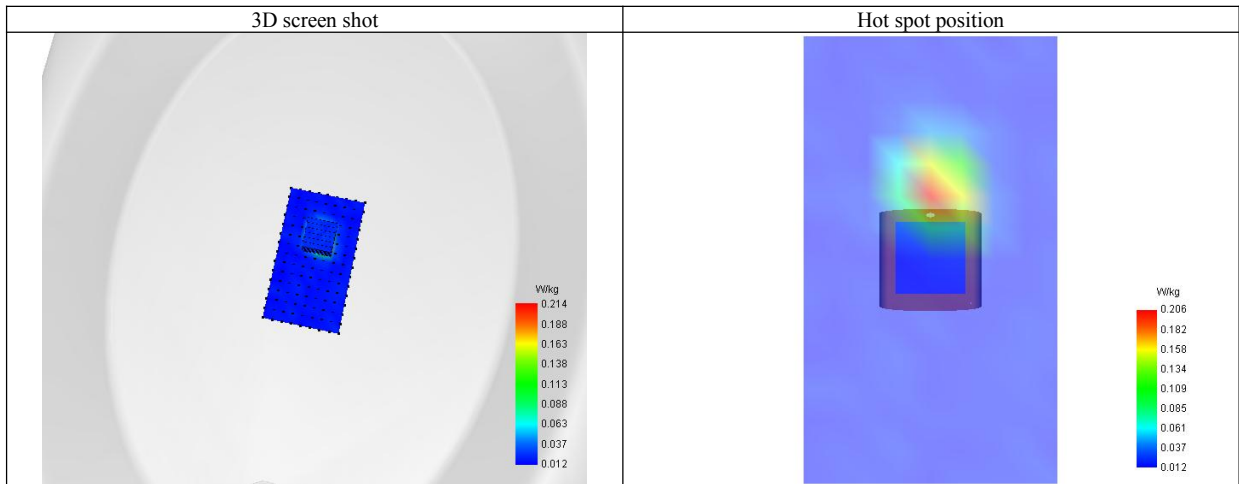
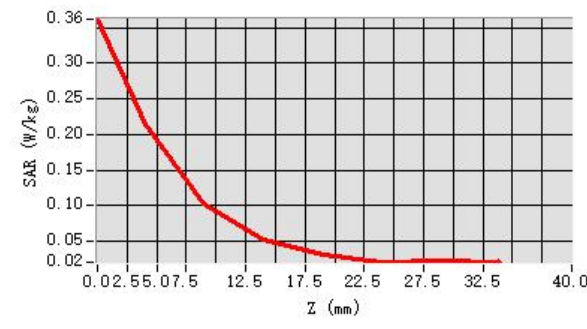
Maximum location: X=1.00, Y=21.00 ; SAR Peak: 0.39 W/kg

SAR 10g (W/Kg)	0.087
SAR 1g (W/Kg)	0.200
Variation (%)	-4.730
Horizontal validation criteria: minimum distance (mm)	10.000000
Vertical validation criteria: SAR ratio M2/M1 (%)	48.480294

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Z (mm)	0.00	4.00	9.00	14.00	19.00	24.00	29.00
SAR (W/Kg)	0.362	0.214	0.104	0.051	0.030	0.021	0.022



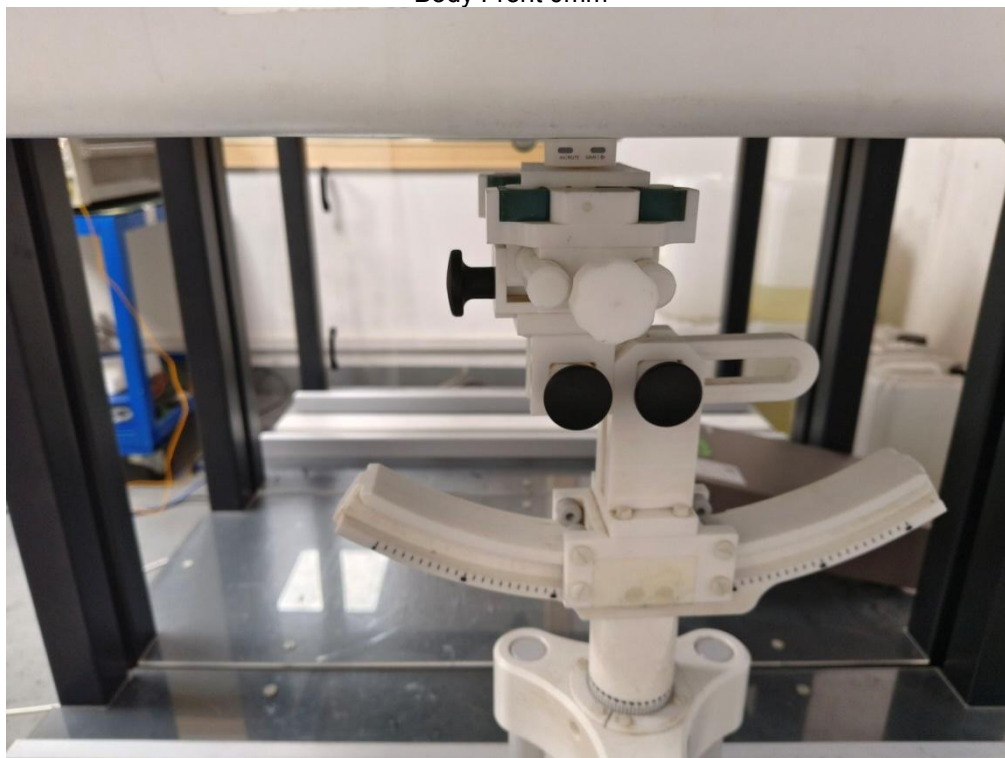
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APPENDIX C. TEST SETUP PHOTOGRAPHS

Body Back 0mm



Body Front 0mm



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Edge 1(Top) 0mm



Edge 2(Right) 0mm



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Edge 3(Bottom) 0mm



Edge 4(Left) 0mm



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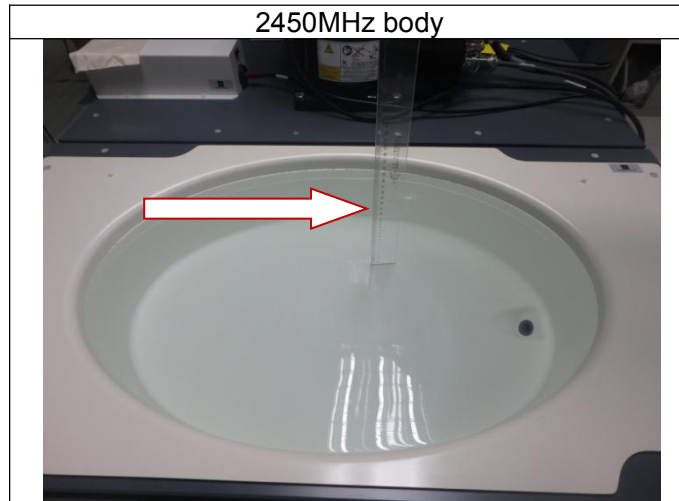
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DEPTH OF THE LIQUID IN THE PHANTOM—ZOOM IN

Note : The position used in the measurement were according to IEEE 1528-2013



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APPENDIX D. CALIBRATION DATA

Refer to Attached files.

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3. The Company shall not be called or be liable to be called to give evidence or testimony on the Report in a court of law without its prior written consent, unless required by the relevant governmental authorities, laws or court orders.
4. In the event of the improper use of the report as determined by the Company, the Company reserves the right to withdraw it, and to adopt any other additional remedies which may be appropriate.
5. Samples submitted for testing are accepted on the understanding that the Report issued cannot form the basis of, or be the instrument for, any legal action against the Company.
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7. Clients wishing to use the Report in court proceedings or arbitration shall inform the Company to that effect prior to submitting the sample for testing.
8. The Company is not responsible for recalling the electronic version of the original report when any revision is made to them. The Client assumes the responsibility to providing the revised version to any interested party who uses them.
9. Subject to the variable length of retention time for test data and report stored hereinto as otherwise specifically required by individual accreditation authorities, the Company will only keep the supporting test data and information of the test report for a period of six years. The data and information will be disposed of after the aforementioned retention period has elapsed. Under no circumstances shall we provide any data and information which has been disposed of after retention period. Under no circumstances shall we be liable for damage of any kind, including (but not limited to) compensatory damages, lost profits, lost data, or any form of special, incidental, indirect, consequential or punitive damages of any kind, whether based on breach of contract of warranty, tort (including negligence), product liability or otherwise, even if we are informed in advance of the possibility of such damages.

----END OF REPORT----

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