

说明书要求：
128g铜版纸，黑白印刷；尺寸：84x184mm
正反印刷，风琴折

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The image displays a multi-language assembly manual for a 6R robot arm. The manual is organized into sections for different languages, each containing numbered steps (1-6) with corresponding diagrams and text. The diagrams show the assembly of the robot arm's joints and components. A table of parts is provided, listing the part name, quantity, and drawing number. The manual also includes a list of safety instructions and a disclaimer.

Table of Parts:

Part Name	Quantity	Drawing Number
Base	1	001
Joint 1	1	002
Joint 2	1	003
Joint 3	1	004
Joint 4	1	005
Joint 5	1	006
Joint 6	1	007
End Effector	1	008

Safety Instructions:

- Read the manual carefully before assembly.
- Use the correct tools and techniques.
- Do not touch the robot arm while it is powered on.
- Do not touch the robot arm while it is moving.
- Do not touch the robot arm while it is lifting a load.
- Do not touch the robot arm while it is lowering a load.
- Do not touch the robot arm while it is rotating.
- Do not touch the robot arm while it is tilting.
- Do not touch the robot arm while it is yawing.
- Do not touch the robot arm while it is rolling.
- Do not touch the robot arm while it is pitching.
- Do not touch the robot arm while it is yawing.
- Do not touch the robot arm while it is rolling.
- Do not touch the robot arm while it is pitching.

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