

GALAXY ROCKET FOUR AXIS AIRCRAFT OPERATION MANUAL 银河火箭四轴飞行器 使用说明书

[illegible]

- Clean this product with a clean soft cloth. 常用干净软布清洁此产品。
- Avoid exposure to the sun or heat. 避免此产品在阳光下暴晒或受热。
- Avoid using when the wind force exceeds Grade III. 避免在风力超过三级时使用。
- Do not immerse the toy in water, otherwise the electronic parts will be damaged.
切勿将此玩具浸没在水中, 否则会导致电子零件受损。
- Check the plug and other accessories regularly. If any damage is found, please stop using it immediately until it is completely repaired.
定期检查插头及其它配件, 如发现有损坏, 请马上停止使用, 直到完全修复。

the final interpretation right of this instruction manual
本公司拥有此说明手册最终解释权

The image displays the following items:

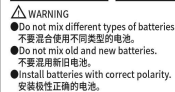
- Rocket X1** 火箭 X1: A small, white, four-armed drone with a propeller on each arm.
- Remote control X1** 遥控器 X1: A white handheld device with two antennas and several buttons.
- Spare blade** 风叶 X4: Four spare propeller blades, shown as a single unit.
- USB charger X1** USB 充电器 X1: A black cable with a USB-A connector and a micro-USB connector.
- Screwdriver X1** 螺丝刀 X1: A small, black-handled screwdriver.
- Battery module X1** 电池模块 X1: A white, rectangular battery pack with a USB port.
- Instruction manual X1** 说明书 X1: A small booklet or manual with a picture of the drone on the cover.



● Install the drone battery module in the direction shown in the figures to the drone battery holder.(Figure 1)
将电池模块按图所示方向安装到机身电池座至定位。(图1)

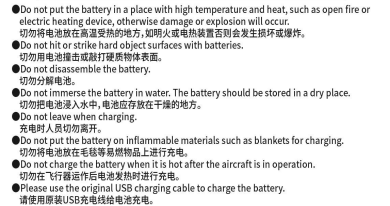


- Click the button on the battery cover with a screwdriver to take out the battery cover. (Picture 1)
 - 用螺丝刀点击电池盖上的按钮，取出电池盖。(图1)
 - Install 3x1.5V AA batteries into the battery compartment according to their polarity. (Picture 2)
 - 将3节“1.5V AA”电池按极性装入电池仓内。(图2)
 - Put on the battery cover (Picture 3)
 - 盖上电池盖。(图3)
- Note: Batteries should be inserted with the correct polarity.
注意：电池应插入正确的极性。



● Connect one end of the USB charging cable to the adapter power port, and then connect the other port to the battery charging port. When charging correctly, the USB charging cable indicator is always on.
将USB充电线一端连接到适配器电源端口,再将另一端口连接到电池充电接口,正确充电时USB充电线指示为常亮。

● The USB charging line indicator is off, indicating that the charging is complete (the charging time is about 50 minutes)
USB充电线指示灯灭,表示充电完成(充电时间大约50分钟左右)。



机身灯光

标准

Method 2: When the aircraft is at a standstill after frequency matching, press the "one button take-off" button on the remote control. After the aircraft propeller rotates slowly, it will automatically rise to an altitude of about 1.2m and hover.

方法二: 当飞行器对频完成处于静止状态, 按下遥控器“一键起飞”按键, 飞行器螺旋桨缓慢旋转后, 自动上升至约 1.2 米高度悬停。



When the quadcopter keeps flying forward / backward, you can adjust it by pressing fine-tuning buttndown/up. 飞行器起飞后,当飞行器朝前/后方向平移时,调节后/前微调功能键回到平衡;当飞行器朝后/前方向平移时,调节前/后微调功能键回到平衡。	When the quadcopter keeps flying toleft / rightside, you can adjust it by pressing fine-tuning button right / left. 飞行器起飞后,当飞行器朝左/右方向平移时,调节右/左侧微调功能键回到平衡;当飞行器朝右/左方向平移时,调节左/右侧微调功能键回到平衡。
--	---

认为低速档,按一下功
制高速档,同时遥控器
发出“顶”一声。

Press the roll button for a short time, the buzzer of the remote control will give out a "beep" sound, push the right operating lever, and the aircraft will disappear and enter the normal mode.

短按翻滚按钮,遥控器蜂鸣器发出“嘀”声,推动右操作杆,飞行器随推动方向作翻滚动作,同时响声消失,进入正常模式。

Note: When the battery is fully charged, the rollover effect is the best. There is no way to roll under the state of self-electricity.

注:当电池充满电时,翻滚效果最佳。当低电量状态下没办法翻滚。



When taking off, the remote control must be facing the tail of the Drone. After taking off, press the remote control headless mode button to enter headless mode. The light of the fuselage flickers, and the remote control buzzer makes a beep. Then press the button of headless mode to exit headless mode. 飞行器对频起飞时,遥控器必须正对飞行器尾部,对频完成起飞后,按下遥控器无头模式按键进入无头模式,机身灯光闪烁,同时遥控器蜂鸣器发出“嘀嘀”的响声,再按一下无头模式按键,退出无头模式。



During the flight, the aircraft indicator flashes slowly, and The remote control emits a beep, indicating that the battery is low. Need to end the flight.
飞行过程中,飞行器指示灯慢闪,遥控器发出“滴滴”声,表示电量电量低,需结束飞行。

● Press the button to turn on the obstacle avoidance mode, and press again to turn off the obstacle avoidance mode. Avoid obstacles on 2 sides and retreat in the opposite direction of the obstacle.
按下按钮开启避障模式，再按一下关闭避障模式。两面避障，往障碍物相反方向退。

● It is recommended to turn on the obstacle avoidance function in an indoor flight environment with a length and width of ≥ 6 meters or more.

✕



- After unlocking the aircraft, long press the one button take-off function button of the remote control, the aircraft will automatically rise to about 1.5 meters and hover.
飞行器解锁后按一下遥控器一键起飞功能按钮，飞行器会自动上升约1.5米高度悬停。
- When the DRONE is flying at high altitude, long press the one button landing function button of the remote control, the aircraft will slowly land. During the descent process, the aircraft can be controlled by the steering rod and the right operating rod to land at the designated point, and then the propeller will stop rotating.

In case of emergency during the flight, press the emergency stop button to stop the aircraft so as not to cause harm.
当飞行器在飞行过程中遇到紧急情况时,长按遥控器急停功能键,可让飞行器紧急停止,以免造

- When we short press the photo button on controller,the LED on the backside of drone flash 1 times.
短按遥控器拍照键，飞行器后面指示灯快速一闪。
- When we long press the photo button on controller, the LED on the backside of drone flash quickly, that means the drone is recording video. Long press again the LED on the backside of drone reminds of, that means the drone stop recording video.
长按遥控器拍照键，飞行器后面指示灯快速闪烁，说明飞行器正在摄像。再次长按遥控器拍照键，飞行器后面指示灯变为长亮，则表示飞行器退出摄像状态。

PROBLEM	REASON	SOLUTION
问题	原因	解决方法
The drone has no response 飞行器没有反应	① The drone has entered into lowbattery protection. ② When the power of the remote Control is weak, the power light indicator will blink. ③ The remote control is not charged properly.	① Charge up the drone. ② Charge the batteries of the remote control. ③ Charge the batteries.
The flight response of the drone is not sensitive 飞行器反应不灵敏	① The power of the remote control is weak. ② When the power of the remote Control is weak, there is an interference with the remote control. ③ The remote control is not charged properly.	① Charge the batteries. ② Change to a place where there is no interference with the same frequency. ③ Fully charge the remote control battery.
The drone is flying towards its level 飞行器正在水平飞行	① The drone is not calibrated level to the ground.	① adjust the calibration with the drone is level to the ground for further details (Function of horizontal adjustment) on Page 4 for details (水平校准功能) on Page 4 for details (水平校准功能)
In the headless state, it is hard to control the flight direction 无头模式下难以控制飞行方向	① Many collisions may cause head loss. ② Head loss is inevitable.	① define the front direction. For further details (Function of headless function) on Page 4 for details (头less功能) on Page 4 for details (头less功能)
Fixed high instability up and down movement 无头模式下上下抖动	① The drone is not calibrated level to the ground. ② The air pressure under the sensors weather condition. ③ The air pressure under the sensors weather condition. ④ violent collision resulting in data disorder of gyroscope.	① adjust the calibration with the drone is level to the ground for further details (Function of horizontal adjustment) on Page 4 for details (水平校准功能) on Page 4 for details (水平校准功能) ② Avoid to fly under the severe weather condition. ③ Avoid to fly under the severe weather condition. ④ Use horizontal adjustment again, see on Page 4 for details (水平校准功能) on Page 4 for details (水平校准功能)

-8-

FCC Statement

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions:

(1) This device may not cause harmful interference, and

(2) this device must accept any interference received, including interference that may cause undesired operation.

This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules.

These limits are designed to provide reasonable protection against harmful interference in a residential installation.

This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

. Reorient or relocate the receiving antenna.

. Increase the separation between the equipment and receiver.

. Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.

. Consult the dealer or an experienced radio/TV technician for help.

Caution: Any changes or modifications to this device not explicitly approved by manufacturer could void your authority to operate this equipment.

RF Exposure Information

The device was evaluated to meet general RF exposure requirements. This equipment should be installed and used with a minimum distance of 0 mm between the radiator and your body.