SAR TEST REPORT

Reference No.	:	WTD25D05136743W003
FCC ID.....	:	2BQL9-HC001001
Applicant	:	Hubble Research (HK) Ltd
Address	:	Unit 802, 8/F, Nan Fung Commercial Centre, 19 Lam Lok Street, Kowloon Bay, Kowloon, Hong Kong, China
Manufacturer	:	Hubble Research (HK) Ltd
Address	:	Unit 802, 8/F, Nan Fung Commercial Centre, 19 Lam Lok Street, Kowloon Bay, Kowloon, Hong Kong, China
Product	:	Hubble Connected the Bear
Model(s).....	:	HC001001
Brand Name	:	Hubble Connected
Standards	:	FCC 47 CFR Part2(2.1093) IEEE Std. C95.1-2019 IEC/IEEE 62209-1528:2020
Date of Receipt sample....	:	2025-06-04
Date of Test	:	2025-06-18
Date of Issue	:	2025-07-10
Test Result	:	**Pass**

Remarks:
The results shown in this test report refer only to the sample(s) tested, this test report cannot be reproduced, except in full, without prior written permission of the company. The report would be invalid without specific stamp of test institute and the signatures of compiler and approver.

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2 Contents

Page

1 COVER PAGE 1

2 CONTENTS 2

3 REVISION HISTORY 3

4 GENERAL INFORMATION 4

4.1 GENERAL DESCRIPTION OF E.U.T. 4
4.2 DETAILS OF E.U.T. 4
4.3 TEST FACILITY 5

5 EQUIPMENT USED DURING TEST 6

5.1 EQUIPMENT LIST 6

6 SAR INTRODUCTION 7

6.1 INTRODUCTION 7
6.2 SAR DEFINITION 7

7 SAR MEASUREMENT SETUP 8

8 EXPOSURE LIMIT 17

9 SYSTEM AND LIQUID VALIDATION 18

9.1 SYSTEM VALIDATION 18
9.2 LIQUID VALIDATION 21

10 TYPE A MEASUREMENT UNCERTAINTY 24

11 OUTPUT POWER VERIFICATION 27

11.1 TEST CONDITION 27
11.2 TEST RESULT 27

12 EXPOSURE CONDITIONS CONSIDERATION 28

12.1 EUT ANTENNA LOCATION 28
12.2 TEST POSITION CONSIDERATION 28
12.3 RF EXPOSURE 29

13 SAR TEST RESULTS 30

13.1 TEST CONDITION 30
13.2 GENERALLY TEST PROCEDURES 30
13.3 SAR SUMMARY TEST RESULT 30

14 SAR MEASUREMENT REFERENCE 32

14.1 REFERENCES 32
14.2 MAXIMUM SAR MEASUREMENT PLOTS 33

15 CALIBRATION REPORTS-PROBE AND DIPOLE 34

16 SAR SYSTEM PHOTOS 57

17 SETUP PHOTOS 58

18 EUT PHOTOS 59

3 Revision History

Test Report No.	Date of Receipt Sample	Date of Test	Date of Issue	Purpose	Comment	Approved
WTD25D05136743W003	2025-06-04	2025-06-18	2025-07-10	Original	-	Valid

4 General Information

4.1 General Description of E.U.T.

Product:	Hubble Connected the Bear
Model(s):	HC001001
Model Description:	N/A
Test Sample No.:	1-1/1
Wi-Fi Specification:	2.4G-802.11b/g/n HT20/ n HT40
Hardware Version:	V2.3
Software Version:	01.02.04RC01

4.2 Details of E.U.T.

Operation Frequency:	802.11b/g/n HT20: 2412~2462MHz 802.11n HT40: 2422~2452MHz
Max. RF output power:	15.61dBm
Max.SAR:	0.254W/kg 1g Body Tissue
Type of Modulation:	DSSS, OFDM
Antenna installation	Integrate antenna
Antenna Gain:	3.02dBi

Note:
#: The antenna gain is provided by the applicant, and the applicant should be responsible for its authenticity, WALTEK lab has not verified the authenticity of its information.

Ratings:	Input: DC 5V
Battery:	DC 2.4V, 2500mAh

4.3 Test Facility

The test facility has a test site registered with the following organizations:

ISED CAB identifier: CN0013. Test Firm Registration No.: 7760A.

Waltek Testing Group Co., Ltd. Has been registered and fully described in a report filed with the Industry Canada. The acceptance letter from the Industry Canada is maintained in our files. Registration number 7760A, October 15, 2016.

FCC Designation No.: CN1201. Test Firm Registration No.: 523476.

Waltek Testing Group Co., Ltd. EMC Laboratory `has been registered and fully described in a report filed with the (FCC) Federal Communications Commission. The acceptance letter from the FCC is maintained in our files. Registration number 523476, September 10, 2019.

5 Equipment Used during Test

5.1 Equipment List

Name of Equipment	Manufacturer	Type/Model	Serial Number	Calibration Date	Calibration Due
6 AXIS ROBOT	KUKA	KR6 R900 SIXX	502635	N/A	N/A
SATIMO Test Software	MVG	OPENSAR	OPENSAR V_4_02_27	N/A	N/A
PHANTOM TABLE	MVG	N/A	SAR_1215_01	N/A	N/A
SAM PHANTOM	MVG	SAM118	SN 11/15 SAM118	N/A	N/A
MultiMeter	Keithley	MiltiMeter 2000	4073942	2025-02-25	2026-02-24
S-Parameter Network Analyzer	Agilent	8753E	JP38160684	2024-09-15	2025-09-14
Universal Radio Communication Tester	ROHDE&SCHWARZ	CMU200	114798	2024-07-18	2025-07-17
Wideband Radio Communication Tester	ROHDE&SCHWARZ	CMW500	127818	2025-04-19	2026-04-18
E-Field Probe	MVG	SSE2	2523-EPGO-417	2024-07-29	2025-07-28
DIPOLE 2450	MVG	SID2450	SN 09/15 DIP 2G450-363	2023-08-08	2026-08-07
Limesar Dielectric Probe	MVG	SCLMP	SN 11/15 OCPG 69	2025-02-24	2026-02-23
Power Amplifier	BONN	BLWA 0830 -160/100/40D	128740	2024-07-18	2025-07-17
Signal Generator	R&S	SMB100A	105942	2024-07-18	2025-07-17
Power Meter	R&S	NRP2	102031	2024-07-18	2025-07-17
Power Meter	R&S	NRVD	102284	2024-07-18	2025-07-17
USB Wideband Power Sensor	Malaysia Keysight	U2021XA	MY54340009	2024-07-18	2025-07-17
USB Wideband Power Sensor	Malaysia Keysight	U2021XA	MY54340010	2024-07-18	2025-07-17

6 SAR Introduction

6.1 Introduction

This measurement report shows compliance of the EUT with IEEE Std. C95.1-2019 nd FCC 47 CFR Part2 (2.1093).The test procedures, as described in IEC/IEEE 62209-1528:2020 Standard for Measurement procedure for the assessment of specific absorption rate of human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices –Part 1528: Human models, instrumentation, and procedures(Frequency range of 4 MHz to 10 GHz)

6.2 SAR Definition

- SAR : Specific Absorption Rate
- The SAR characterize the absorption of energy by a quantity of tissue
- This is related to a increase of the temperature of these tissues during a time period.

$$\mathrm{DAS} = \frac{\mathrm{d}}{\mathrm{d}t}\left(\frac{\mathrm{d}W}{\mathrm{d}m}\right) = \frac{\mathrm{d}}{\mathrm{d}t}\left(\frac{\mathrm{d}W}{\rho \mathrm{d}V}\right)$$

$$\mathrm{DAS} = \frac{\sigma E^2}{\rho}$$

$$\mathrm{DAS} = c_{\mathrm{h}} \left.\frac{\mathrm{d}T}{\mathrm{d}t}\right|_{t=0}$$

SAR definition

$$SAR = \frac{\sigma E^2}{\rho}$$

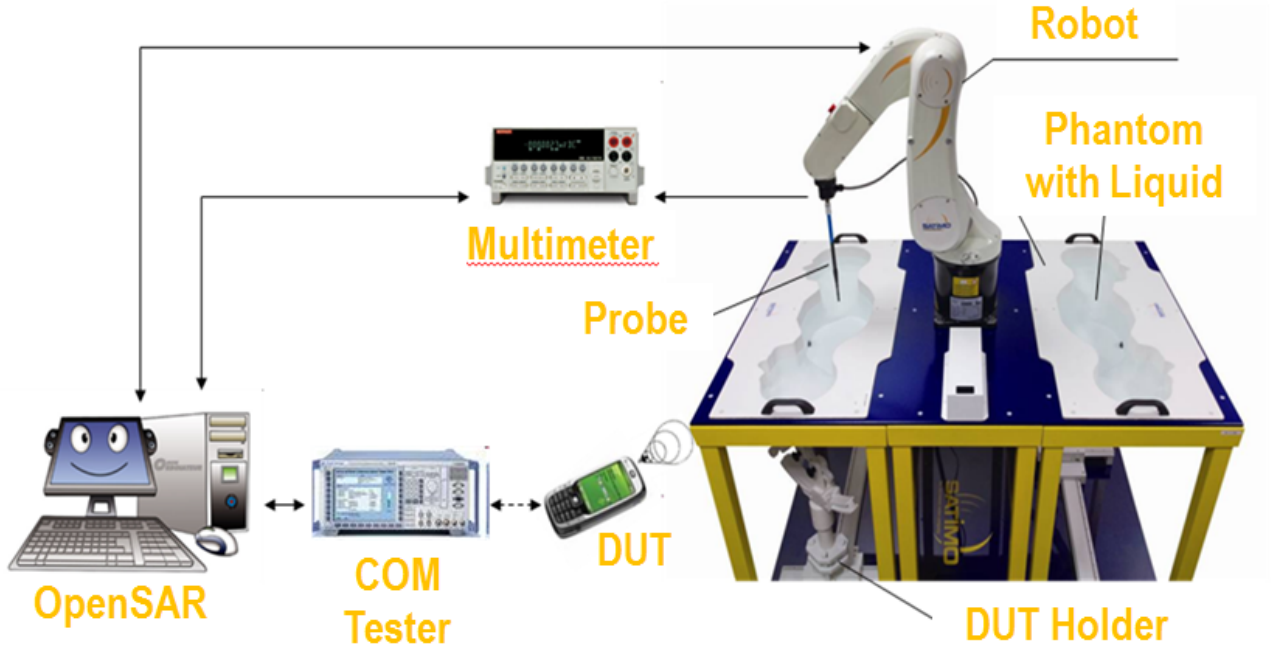
- SAR : Specific Absorption Rate
  - σ : Liquid conductivity
    - $\varepsilon_r = \varepsilon' - j\varepsilon''$ (complex permittivity of liquid)
    - $\sigma = \frac{\varepsilon'' \omega}{\varepsilon_0}$
  - ρ: Liquid density
    - ρ = 1000 g/L = 1000Kg/m³

where:

σ = conductivity of the tissue (S/m)
ρ = mass density of the tissue (kg/m3)
E = rms electric field strength (V/m)

7 SAR Measurement Setup

SAR bench sub-systems



Scanning System (robot)

- It must be able to scan all the volume of the phantom to evaluate the tridimensional distribution of SAR.
- Must be able to set the probe orthogonal of the surface of the phantom (±30°).
- Detects stresses on the probe and stop itself if necessary to keep the integrity of the probe.

SAM Phantom (Specific Anthropomorphic Mannequin)

- The probe scanning of the E-Field is done in the 2 half of the normalized head.
- The normalized shape of the phantom corresponds to the dimensions of 90% of an adult head size.
- The materials for the phantom should not affect the radiation of the device under test (DUT)
  - Permittivity < 5
- The head is filled with tissue simulating liquid.
- The hand holding the DUT does not have to be modeled.

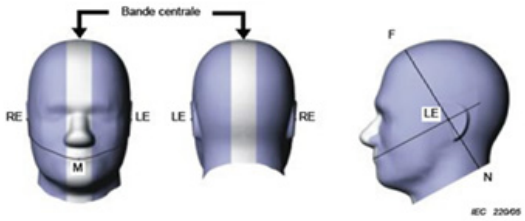
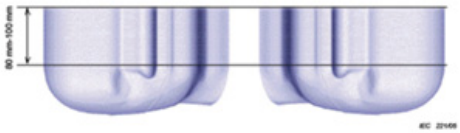
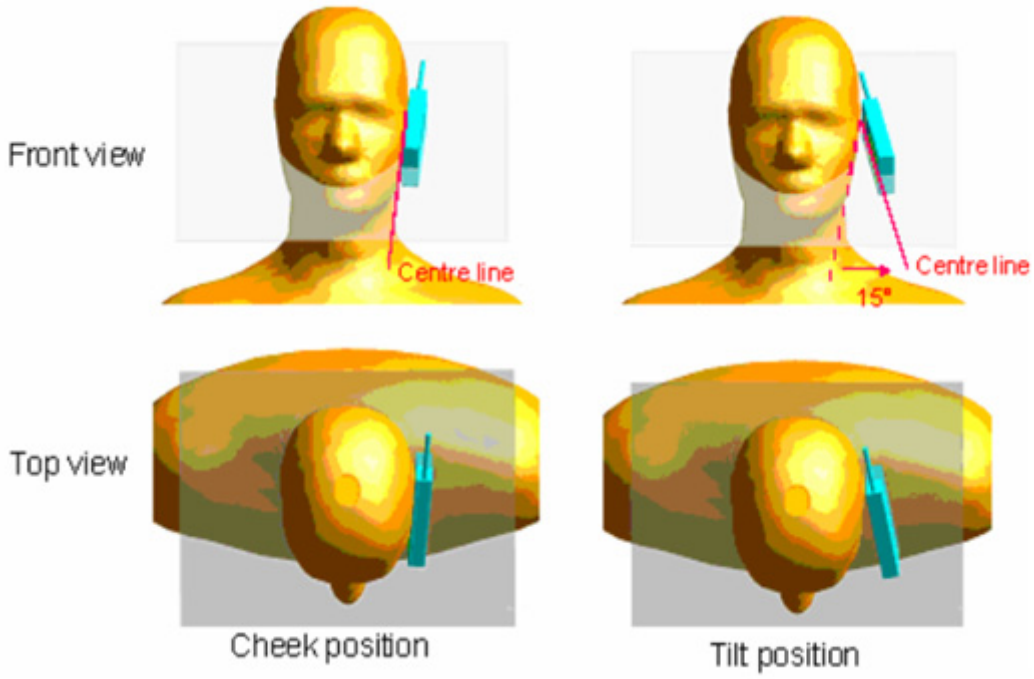


Illustration du fantôme donnant les points de référence des oreilles, RE et LE, le point de référence de la bouche, M, la ligne de référence N-F et la bande centrale



Bi-section sagittale du fantôme avec périmètre étendu (montrée sur le côté comme lors des essais de DAS de l'appareil)



The OPENSAR system for performing compliance tests consist of the following items:

1. A standard high precision 6-axis robot (KUKA) with controller and software.
2. KUKA Control Panel (KCP).
3. A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
4. The functions of the PC plug-in card are to perform the time critical task such as signal filtering, surveillance of the robot operation fast movement interrupts.
5. A computer operating Windows 7.
6. OPENSAR software.
7. Remote control with teaches pendant and additional circuitry for robot safety such as warning lamps, etc.
8. The SAM phantom enabling testing left-hand right-hand and body usage.
9. The Position device for handheld EUT.
10. Tissue simulating liquid mixed according to the given recipes (see Application Note).
11. System validation dipoles to validate the proper functioning of the system.

Data Evaluation

The OPENSAR software automatically executes the following procedure to calculate the field units from the microvolt readings at the probe connector. The parameters used in the valuation are stored in the configuration modules of the software:

Probe Parameters	- Sensitivity	$Norm_i$
	- Conversion factor	ConvFi
	- Diode compression point Dcpi	
Device Parameter	- Frequency	f
	- Crest factor	cf
Media Parametrs	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can either be found in the component documents or be imported into the software from the configuration files issued for the OPENSAR components.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

Where V_i = *Compensated signal of channel i (i = x, y, z)*
U_i = *Input signal of channel i (i = x, y, z)*
cf = *Crest factor of exciting field (DASY parameter)*
dcp_i = *Diode compression point (DASY parameter)*

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes: $$E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

H-field probes: $$H_i = \sqrt{Vi} \cdot \frac{a_{i0} + a_{i1} f + a_{i2} f^2}{f}$$

Where V_i = *Compensated signal of channel i (i = x, y, z)*
$Norm_i$ = *Sensor sensitivity of channel i (i = x, y, z)*
μV/(V/m)2 for E0field Probes
ConvF= Sensitivity enhancement in solution
a_{ij} = *Sensor sensitivity factors for H-field probes*

f = *Carrier frequency (GHz)*
E_i = *Electric field strength of channel i in V/m*
H_i = *Magnetic field strength of channel i in A/m*

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

where SAR = *local specific absorption rate in mW/g*
E_{tot} = *total field strength in V/m*
σ = *conductivity in [mho/m] or [siemens/m]*
ρ = *equivalent tissue density in g/cm3*

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770} \quad \text{or} \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

where P_{pwe} = *Equivalent power density of a plane wave in mW/cm2*
E_{tot} = *total electric field strength in V/m*
H_{tot} = *total magnetic field strength in A/m*

SAR Evaluation – Peak Spatial - Average

The procedure for assessing the peak spatial-average SAR value consists of the following steps

- **Power Reference Measurement**

  The reference and drift jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method.

- **Area Scan**

  The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in OPENSAR software can find the maximum locations even in relatively coarse grids. The scan area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom.

When the area scan's property sheet is brought-up, grid was at to 15 mm by 15 mm and can be edited by a user.

- **Zoom Scan**

  Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default zoom scan measures 5 x 5 x 7 points within a cube whose base faces are centered around the maximum found in a preceding area scan job within the same procedure. If the preceding Area Scan job indicates more then one maximum, the number of Zoom Scans has to be enlarged accordingly (The default number inserted is 1).

- **Power Drift measurement**

  The drift job measures the field at the same location as the most recent reference job within the same procedure, and with the same settings. The drift measurement gives the field difference in dB from the reading conducted within the last reference measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. In the properties of the Drift job, the user can specify a limit for the drift and have OPENSAR software stop the measurements if this limit is exceeded.

SAR Evaluation – Peak SAR

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1528 standard. It can be conducted for 1 g and 10 g. The OPENSAR system allows evaluations that combine measured data and robot positions, such as:

- maximum search
- extrapolation
- boundary correction
- peak search for averaged SAR

During a maximum search, global and local maximum searches are automatically performed in 2-D after each Area Scan measurement with at least 6 measurement points. It is based on the evaluation of the local SAR gradient calculated by the Quadratic Shepard's method. The algorithm will find the global maximum and all local maxima within -2 dB of the global maxima for all SAR distributions.

Extrapolation

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. Several measurements at different distances are necessary for the extrapolation.
They are used in the Cube Scan to obtain SAR values between the lowest measurement points and the inner phantom surface. The routine uses the fourth order least square polynomial method for extrapolation. For a grid using 5x5x7 measurement points with 5mm resolution amounting to 343 measurement points, the uncertainty of the extrapolation routines is less than 1% for 1 g and 10 g cubes.

Definition of Reference Points

Ear Reference Point

Figure 6.2 shows the front, back and side views of the SAM Phantom. The point “M” is the reference point for the center of the mouth, “LE” is the left ear reference point (ERP), and “RE” is the right ERP. The ERPs are 15mm posterior to the entrance to the ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 6.1. The plane passing through the two ear canals and M is defined as the Reference Plane. The line N-F (Neck-Front) is perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 6.1). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines are marked on the external phantom shell to facilitate handset positioning [5].

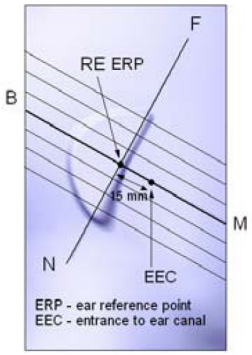


Figure 6.1 Close-up side view of ERP’s

Figure 6.2 Front, back and side view of SAM

Device Reference Points

Two imaginary lines on the device need to be established: the vertical centerline and the horizontal line. The test device is placed in a normal operating position with the “test device reference point” located along the “vertical centerline” on the front of the device aligned to the “ear reference point” (See Fig. 6.3). The “test device reference point” is than located at the same level as the center of the ear reference point. The test device is positioned so that the “vertical centerline” is bisecting the front surface of the device at it’s top and bottom edges, positioning the “ear reference point” on the outer surface of both the left and right head phantoms on the ear reference point [5].

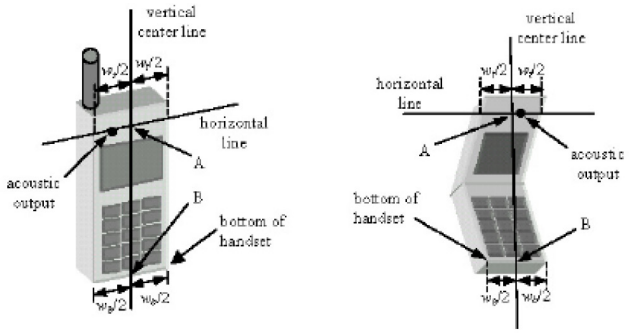


Figure 6.3 Handset Vertical Center & Horizontal Line Reference Points

Test Configuration – Positioning for Cheek / Touch

1. Position the device close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure below), such that the plane defined by the vertical center line and the horizontal line of the device is approximately parallel to the sagittal plane of the phantom

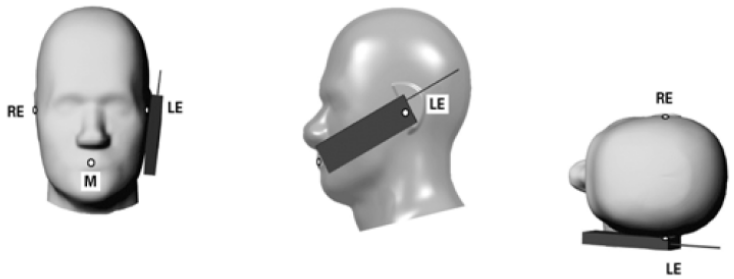


Figure 7.1 Front, Side and Top View of Cheek/Touch Position

2. Translate the device towards the phantom along the line passing through RE and LE until the device touches the ear.

3. While maintaining the device in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to MB-NF including the line MB (called the reference plane).
4. Rotate the device around the vertical centerline until the device (horizontal line) is symmetrical with respect to the line NF.

5. While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the device contact with the ear, rotate the device about the line NF until any point on the device is in contact with a phantom point below the ear (cheek). See Figure below.

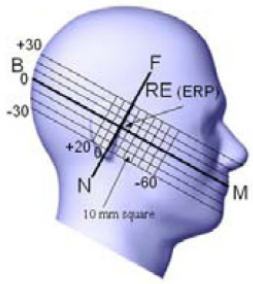


Figure 7.2 Side view w/ relevant markings

Test Configuration – Positioning for Ear / 15° Tilt

With the test device aligned in the Cheek/Touch Position":

1. While maintaining the orientation of the device, retracted the device parallel to the reference plane far enough to enable a rotation of the device by 15 degrees.

2. Rotate the device around the horizontal line by 15 degrees.

3. While maintaining the orientation of the device, move the device parallel to the reference plane until any part of the device touches the head. (In this position, point A is located on the line RE-LE). The tilted position is obtained when the contact is on the pinna. If the contact is at any location other than the pinna, the angle of the device shall be reduced. The tilted position is obtained when any part of the device is in contact with the ear as well as a second part of the device is in contact with the head (see Figure below).

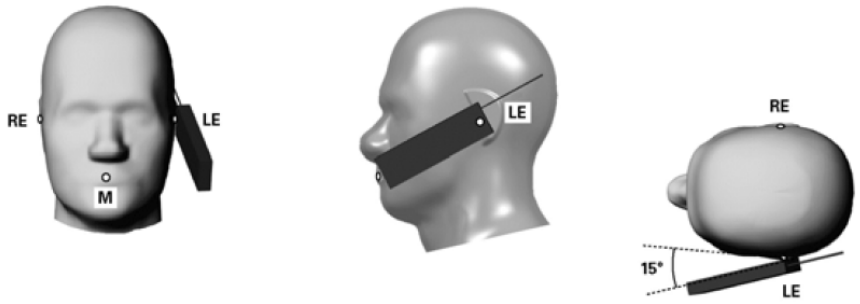
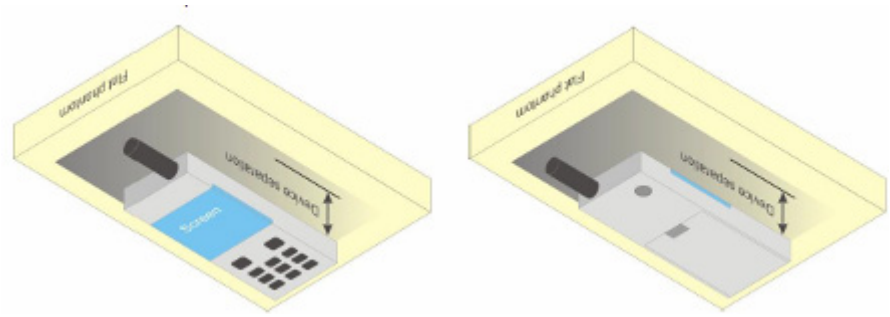


Figure 7.3 Front, Side and Top View of Ear/15˚ Tilt Position

Test Position – Body Configurations

Body Worn Position
(a) To position the device parallel to the phantom surface with either keypad up or down.
(b) To adjust the device parallel to the flat phantom.
(c) To adjust the distance between the device surface and the flat phantom to 1.0 cm or holster surface and the flat phantom to 0 cm.



8 Exposure limit

In order for users to be aware of the body-worn operating requirements for meeting RF exposure compliance, operating instructions and cautions statements are included in the user's manual.

Uncontrolled Environment

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure. The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity.

Controlled Environment

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation). In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means.

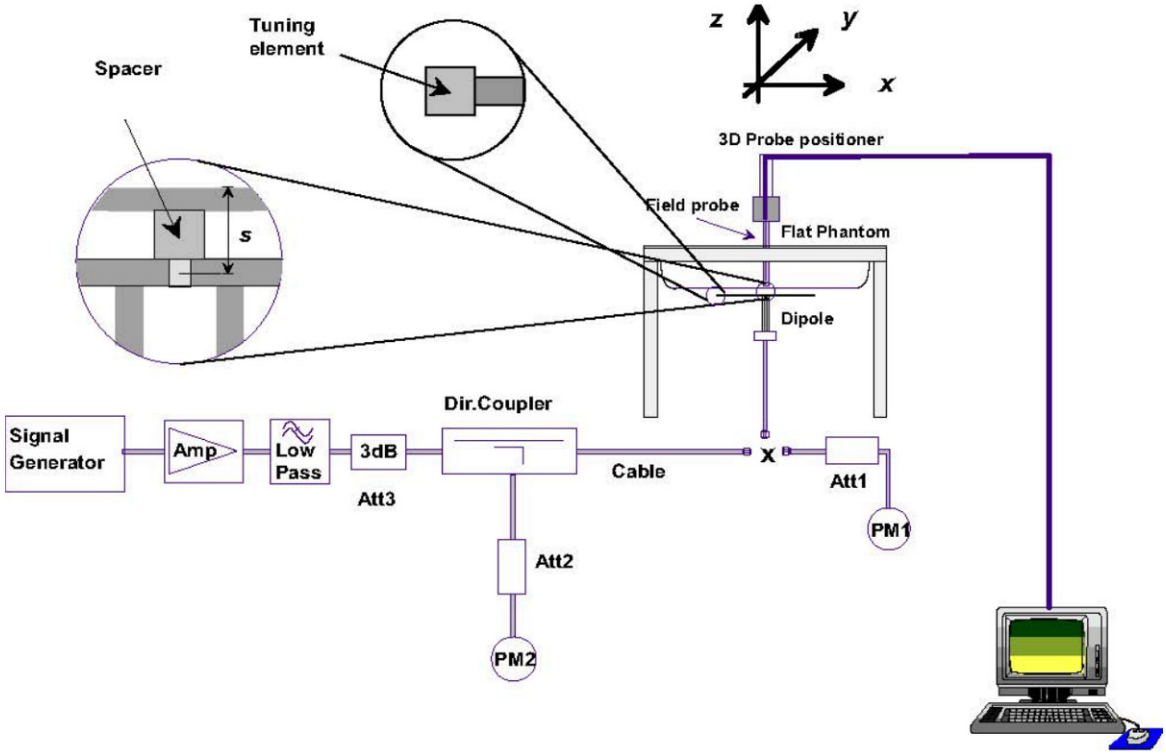
Table 8.1 Human Exposure Limits

	UNCONTROLLED ENVIRONMENT General Population (W/kg) or (mW/g)	CONTROLLED ENVIROMENT Professional Population (W/kg) or (mW/g)
SPATIAL PEAK SAR[1] Brain	1.60	8.00
SPATIAL AVERAGE SAR[2] Whole Body	0.08	0.40
SPATIAL PEAK SAR[3] Hands, Feet, Ankles, Wrists	4.00	20.00

[1] The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.
[2] The Spatial Average value of the SAR averaged over the whole body.
[3] The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

9 System and liquid validation

9.1 System validation



Verification Setup Block Diagram

Dipole Antenna Setup Photo

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. Calibrated Dipole

The output power on dipole port must be calibrated to 30 dBm (1000 mW) before dipole is connected.

Numerical reference SAR values (W/kg) for reference dipole and flat phantom

Frequency (MHz)	1g SAR	10g SAR	Local SAR at surface(above feed-point)	Local SAR at surface(y = 2 cm offset from feedpoint)
300	3.02	2.04	4.40	2.10
450	4.92	3.28	7.20	3.20
750	8.49	5.55	12.6	4.59
835	9.56	6.22	14.1	4.90
900	10.9	6.99	16.4	5.40
1450	29.0	16.0	50.2	6.50
1800	38.4	20.1	69.5	6.80
1900	39.7	20.5	72.1	6.60
2000	41.1	21.1	74.6	6.50
2450	52.4	24.0	104	7.70
2600	55.3	24.6	113	8.29
3000	63.8	25.7	140	9.50

Table 1: system validation (1g)

Measurement Date	Frequency (MHz)	Liquid Type (head/body)	1W Target SAR1g (W/kg)	Measured SAR1g (W/kg)	1W Normalized SAR1g (W/kg)	Desired Tolerance (%)	Actual Tolerance (%)
2025-06-18	2450	head	54.33	5.529	55.29	±10	1.77

Remark: system check input power: 100mW.

9.2 liquid validation

The dielectric parameters were checked prior to assessment using the HP85070C dielectric probe kit. The dielectric parameters measured are reported in each correspondent section.

KDB 865664 recommended Tissue Dielectric Parameters

The head and body tissue parameters given in this below table should be used to measure the SAR of transmitters operating in 100 MHz to 6 GHz frequency range. The tissue dielectric parameters of the tissue medium at the test frequency should be within the tolerance required in this document. The dielectric parameters should be linearly interpolated between the closest pair of target frequencies to determine the applicable dielectric parameters corresponding to the device test frequency.

The head tissue dielectric parameters recommended by IEEE Std 1528-2013 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in 1528 are derived from tissue dielectric parameters computed from the 4-Cole-Cole equations described above and extrapolated according to the head parameters specified in 1528.

Target Frequency	Head Tissue		Body Tissue	
MHz	εr	σ (S/m)	εr	σ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
750	41.9	0.89	55.5	0.96
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	**39.2**	**1.80**	**52.7**	**1.95**
2600	39.0	1.96	52.5	2.16
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE SCC-34/SC-2 in P1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness Power drifts in a human head. Other head and body tissue parameters that have not been specified in P1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in P1528.

Table 2: Recommended Dielectric Performance of Tissue

Recommended Dielectric Performance of Tissue						
Head/Body						
Ingredients (% by weight)	Frequency (MHz)					
	750	835	1800	1900	2450	2600
Water	40.52	41.45	55.2	54.9	62.7	54.8
Salt (Nacl)	1.61	1.45	0.3	0.18	0.5	0.1
Sugar	57.67	56.0	0.0	0.0	0.0	0.0
HEC	0.1	1.0	0.0	0.0	0.0	0.0
Bactericide	0.1	0.1	0.0	0.0	0.0	0.0
Triton x-100	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	44.5	44.92	0.0	45.1
Dielectric	40.93	42.54	40.0	39.9	39.8	39.0
Conductivity	0.87	0.91	1.40	1.42	1.88	1.96

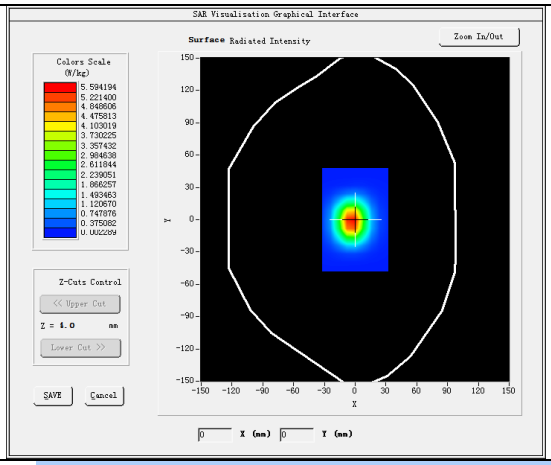
Table 3: Dielectric Performance of Head Tissue Simulating Liquid

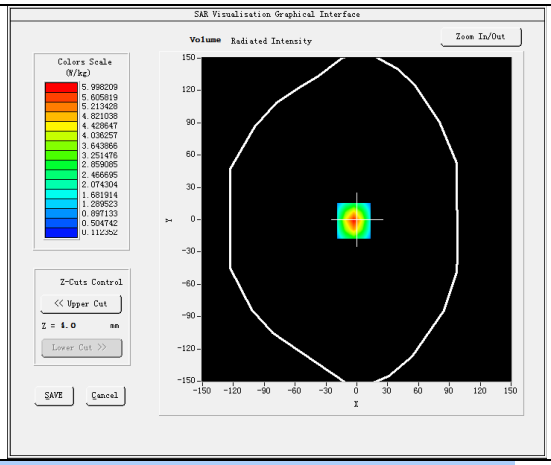
Temperature: 22.8°C , Relative humidity: 51%				
Frequency(MHz)	Measured Date	Description	Dielectric Parameters	
			εr	σ(s/m)
2450	2025-06-18	Target Value ±5% window	39.20 37.24— 41.16	1.80 1.71 — 1.89
		Measurement Value	39.23	1.79

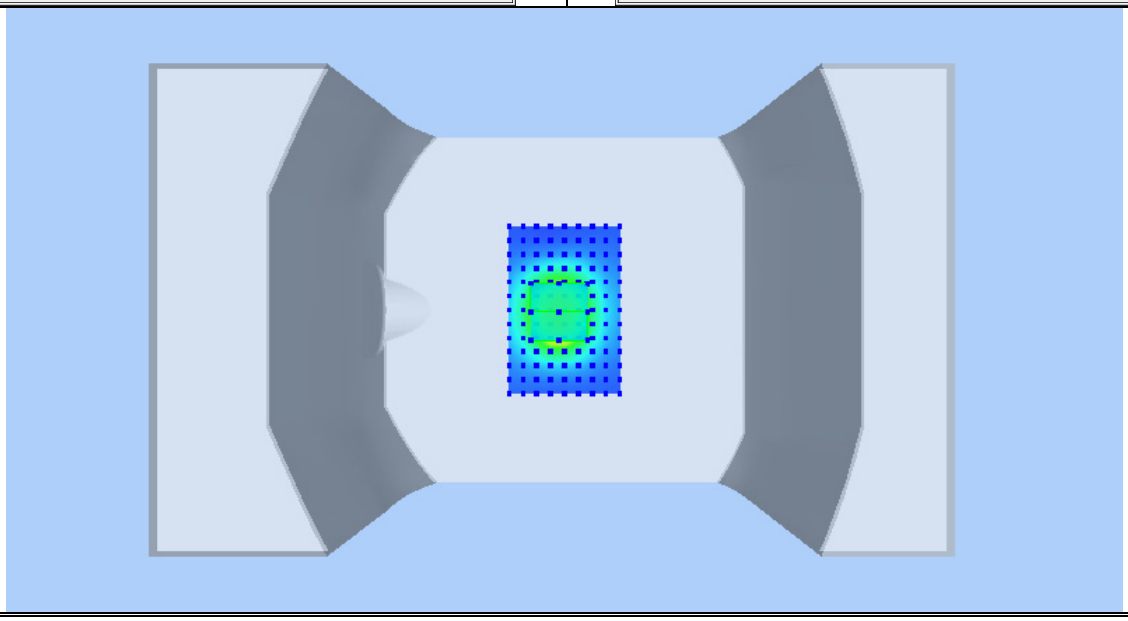
System Verification Plots

Product Description: Dipole
Model: SID2450
Test Date: 2025-06-18

Medium(liquid type)	HL2450
Frequency (MHz)	2450.000
Relative permittivity (real part)	39.23
Conductivity (S/m)	1.79
Input power	100mW
Crest factor	1.0
E-Field Probe	2523-EPGO-417
Conversion Factor	3.01
Area Scan	dx=8mm dy=8mm
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Variation (%)	0.24
SAR 10g (W/Kg)	2.612118
SAR 1g (W/Kg)	5.529064
SURFACE SAR	**VOLUME SAR**







10 Type a Measurement Uncertainty

The component of uncertainly may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainly by the statistical analysis of a series of observations is termed a Type An evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table below :

Uncertainty Distribution	Normal	Rectangle	Triangular	U Shape
Multi-plying Factor(a)	1/k(b)	1 / √3	1 / √6	1 / √2

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity
(b) κ is the coverage factor

Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type -sum- by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %.

The COMOSAR Uncertainty Budget is show in below table:

UNCERTAINTY FOR SYSTEM PERFORMANCE CHECK								
a	c	d	e= f(d,k)	f	g	h= c*f/e	i= c*g/e	k
Uncertainty Component	Tol (+- %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	Vi
Measurement System								
Probe calibration	5.8	N	1	1	1	5.80	5.80	∞
Axial Isotropy	3.5	R	√3	(1_Cp) ^1/2	(1_Cp)^1/ 2	1.43	1.43	∞
Hemispherical Isotropy	5.9	R	√3	(Cp)^1 /2	(Cp)^1/2	2.41	2.41	∞
Boundary effect	1.0	R	√3	1	1	0.58	0.58	∞
Linearity	4.7	R	√ 3	1	1	2.71	2.71	∞
System detection limits	1.0	R	√3	1	1	0.58	0.58	∞
Modulation response	0.00	N	1	1	1	0.00	0.00	∞
Readout Electronics	0.50	N	1	1	1	0.50	0.50	∞
Reponse Time	0.0	R	√3	1	1	0.00	0.00	∞
Integration Time	1.4	R	√3	1	1	0.81	0.81	∞
RF ambient Conditions - Noise	3.0	R	√3	1	1	1.73	1.73	∞
RF ambient Conditions - Reflections	3.0	R	√3	1	1	1.73	1.73	∞
Probe positioner Mechanical Tolerance	1.4	R	√3	1	1	0.81	0.81	∞
Probe positioning with respect to Phantom Shell	1.40	R	√3	1	1	0.81	0.81	∞
Extrapolation, interpolation and integration Algoritms for Max. SAR Evaluation	2.3	R	√3	1	1	1.33	1.33	∞
Dipole								
Deviation of experimental source from numerical source	4.00	N	1	1	1	4.00	4.00	∞
Input power and SAR drift measurement	5.00	R	√3	1	1	2.89	2.89	∞
Dipole axis to liquid Distance	2.00	R	√3	1	1	1.15	1.15	∞
Phantom and Tissue Parameters								
Phantom Uncertainty (Shape and thickness tolerances)	4.00	R	√3	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviation (in permittivity and conductivity)	2.00	N	1	1	1	2.00	1.68	∞
Liquid conductivity (temperature uncertainty)	2.50	N	1	0.78	0.71	1.95	1.77	∞
Liquid conductivity - measurement uncertainty	4.00	N	1	0.23	0.26	0.92	1.04	M
Liquid permittivity (temperature uncertainty)	2.50	N	1	0.78	0.71	1.95	1.77	∞
Liquid permittivity - measurement uncertainty	5.00	N	1	0.23	0.26	1.15	1.30	M
Combined Standard Uncertainty		RSS				10.21	10.12	
Expanded Uncertainty (95% Confidence interval)		k				19.91	19.73	

UNCERTAINTY EVALUATION FOR HANDSET SAR TEST								
a	c	d	e= f(d,k)	f	g	h= c*f/e	i= c*g/e	k
Uncertainty Component	Tol (+- %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	Vi
Measurement System								
Probe calibration	5.8	N	1	1	1	5.80	5.80	∞
Axial Isotropy	3.5	R	√3	(1_Cp) ^ 1/2	(1_Cp)^1/2	1.43	1.43	∞
Hemispherical Isotropy	5.9	R	√3	(Cp)^ 1/2	(Cp)^ 1/2	2.41	2.41	∞
Boundary effect	1.0	R	√3	1	1	0.58	0.58	∞
Linearity	4.7	R	√3	1	1	2.71	2.71	∞
System detection limits	1.0	R	√3	1	1	0.58	0.58	∞
Modulation response	3.00	N	1	1	1	3.00	3.00	∞
Readout Electronics	0.50	N	1	1	1	0.50	0.50	∞
Reponse Time	0.0	R	√3	1	1	0.00	0.00	∞
Integration Time	1.4	R	√3	1	1	0.81	0.81	∞
RF ambient Conditions - Noise	3.0	R	√3	1	1	1.73	1.73	∞
RF ambient Conditions - Reflections	3.0	R	√3	1	1	1.73	1.73	∞
Probe positioner Mechanical Tolerance	1.4	R	√3	1	1	0.81	0.81	∞
Probe positioning with respect to Phantom Shell	1.40	R	√3	1	1	0.81	0.81	∞
Extrapolation, interpolation and integration Algoritms for Max. SAR Evaluation	2.3	R	√3	1	1	1.33	1.33	∞
Test sample Related								
Test sample positioning	2.60	N	1	1	1	2.60	2.60	N-1
Device Holder Uncertainty	3.00	N	1	1	1	3.00	3.00	N-1
Output power Variation - SAR drift measurement	5.00	R	√3	1	1	2.89	2.89	∞
SAR scaling	2.00	R	√3	1	1	1.15	1.15	∞
Phantom and Tissue Parameters								
Phantom Uncertainty (Shape and thickness tolerances)	4.00	R	√3	1	1	2.31	2.31	∞
Uncertainty in SAR correction for deviation (in permittivity and conductivity)	2.00	N	1	1	1	2.00	1.68	∞
Liquid conductivity (temperature uncertainty)	2.50	N	1	0.78	0.71	1.95	1.77	∞
Liquid conductivity - measurement uncertainty	4.00	N	1	0.23	0.26	0.92	1.04	M
Liquid permittivity (temperature uncertainty)	2.50	N	1	0.78	0.71	1.95	1.77	∞
Liquid permittivity - measurement uncertainty	5.00	N	1	0.23	0.26	1.15	1.30	M
Combined Standard Uncertainty		RSS				10.63	10.54	
Expanded Uncertainty (95% Confidence interval)		k				20.73	20.56	

11 Output Power Verification

11.1 Test Condition

1. Conducted Measurement
   EUT was set for low, mid, high channel with modulated mode and highest RF output power.
   The base station simulator was connected to the antenna terminal.
2. Conducted Emissions Measurement Uncertainty
   All test measurements carried out are traceable to national standards. The uncertainty of the measurement at a confidence level of approximately 95% (in the case where distributions are normal), with a coverage factor of 2, in the range 30MHz – 40GHz is ±1.5dB.
3. Environmental Conditions

Temperature	22.8°C
Relative Humidity	51%
Atmospheric Pressure	1012mbar

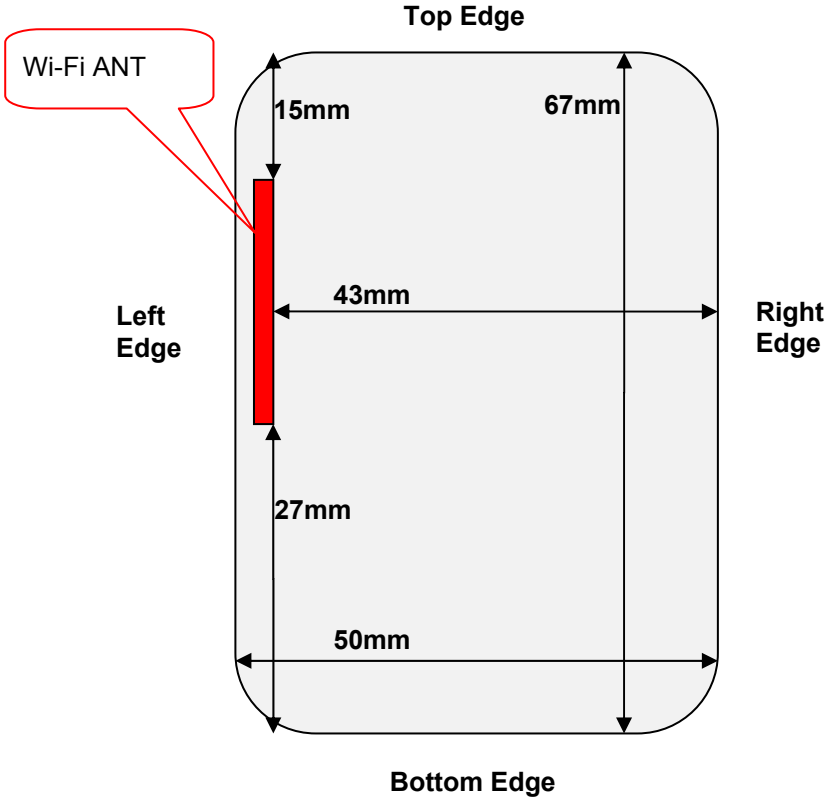
11.2 Test Result

2.4G Wi-Fi Measurement Result

Channel number	Frequency (MHz)	Average Output Power(dBm)	Tune up limited(dBm)
TX 11b	2412	**15.61**	15.0±1
	2437	15.29	15.0±1
	2462	15.26	15.0±1
TX 11g	2412	13.43	13.0±1
	2437	13.31	13.0±1
	2462	13.36	13.0±1
TX 11n HT20	2412	13.64	13.5±1
	2437	14.03	13.5±1
	2462	13.24	13.5±1
TX 11n HT40	2422	13.32	13.0±1
	2437	13.34	13.0±1
	2452	13.18	13.0±1

12 Exposure Conditions Consideration

12.1 EUT antenna location



< EUT Front View >

12.2 Test position consideration

Distance of EUT antenna-to-edge/surface(mm),						
Antennas	Back Side	Front Side	Left Edge	Right Edge	Top Edge	Bottom Edge
WLAN	＜25	＜25	＜25	43	15	27
Test distance:0mm						
Antennas	Back Side	Front Side	Left Edge	Right Edge	Top Edge	Bottom Edge
WLAN	YES	YES	YES	NO	YES	NO

Note:
1. Body SAR mode assessments are required.
2. Per KDB 447498 D01v06, for handsets the test separation distance is determined by the smallest distance between the outer surface of the device and the user, which is 0 mm for body SAR.
.

12.3 RF Exposure

Standard Requirement:
According to §15.247 (i) and §1.1307(b)(1), systems operating under the provisions of this section shall be operated in a manner that ensures that the public is not exposed to radio frequency energy level in excess of the Commission's guidelines.

The 1-g and 10-g SAR test exclusion thresholds for 100 MHz to 6 GHz at *test separation distances* ≤ 50 mm are determined by:

[(*max. power of channel, including tune-up tolerance, mW*)/(*min. test separation distance, mm*)] · [$\sqrt{f_{(GHz)}}$] ≤ 3.0 for 1-g SAR and ≤ 7.5 for 10-g extremity SAR,[16] where

- $f_{(GHz)}$ is the RF channel transmit frequency in GHz
- Power and distance are rounded to the nearest mW and mm before calculation[17]
- The result is rounded to one decimal place for comparison

The test exclusions are applicable only when the minimum *test separation distance* is ≤ 50 mm and for transmission frequencies between 100 MHz and 6 GHz. When the minimum *test separation distance* is < 5 mm, a distance of 5 mm is applied to determine SAR test exclusion.

Routine SAR evaluation refers to that specifically required by § 2.1093, using measurements or computer simulation. When routine SAR evaluation is not required, portable transmitters with output power greater than the applicable low threshold require SAR evaluation to qualify for TCB approval.

Exclusion Thresholds = $P\sqrt{F}/D$
P= Maximum turn-up power in mW
F= Channel frequency in GHz
D= Minimum test separation distance in mm

Test Distance (5mm)

Mode	MAX Power (dBm)	Tune Up Power (dBm)	Max Tune Up Power (dBm)	Max Tune Up Power (mW)	Exclusion Thresholds	Limit
2.4G Wi-Fi	15.61	15.0±1	16.0	39.81	12.37	3

13 SAR Test Results

13.1 Test Condition

1. SAR Measurement
   The distance between the EUT and the antenna of the emulator is more than 50 cm and the output power radiated from the emulator antenna is at least 30 dB less than the output power of EUT.

2 Environmental Conditions

Temperature	22.8°C
Relative Humidity	51%
Atmospheric Pressure	1012mbar

13.2 Generally Test Procedures

1. Establish communication link between EUT and base station emulation by air link.
2. Place the EUT in the selected test position. (Cheek, tilt or flat)
3. Perform SAR testing at middle or highest output power channel under the selected test mode. If the measured 1-g SAR is ≤ 0.8 W/kg, then testing for the other channel will not be performed.
4. When SAR is<0.8W/kg, no repeated SAR measurement is required

13.3 SAR Summary Test Result

Table 4: SAR Values of 2.4G Wi-Fi

Test Positions		Channel		Test Mode	Power(dBm)		SAR 1g(W/Kg), Limit(1.6W/kg)			Plot No.
		CH.	MHz		Maximum Turn-up Power (dBm)	Measured output power (dBm)	Scaling Factor	Measured SAR 1g(W/kg)	Scaled SAR 1g(W/kg)	
Body (0mm Separation)	Front Side	01	2412	802.11b	16	15.61	1.094	0.232	**0.254**	**1**
	Back Side	01	2412	802.11b	16	15.61	1.094	0.041	0.045	--
	Left Edge	01	2412	802.11b	16	15.61	1.094	0.091	0.100	--
	Top Edge	01	2412	802.11b	16	15.61	1.094	0.085	0.093	--

Measurement variability consideration

According to KDB 865664 D01v01r04 section 2.8.1, repeated measurements are required following the procedures as below:

Repeated measurement is not required when the original highest measured SAR is < 0.80W/kg; steps 2) through 4) do not apply.

When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.

Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg (~ 10% from the 1-g SAR limit).

Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

No Repeated SAR.

Simultaneous Transmission SAR Analysis.

Note: No Simultaneous Transmission SAR.

14 SAR Measurement Reference

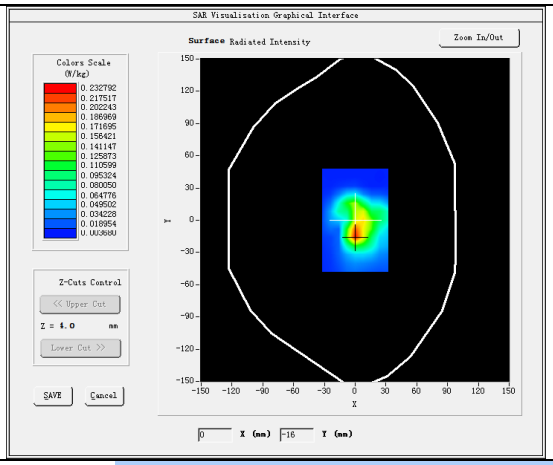
14.1 References

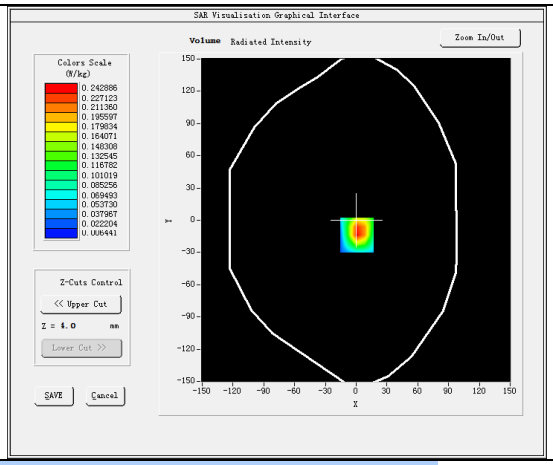
1. **FCC 47 CFR Part 2 "Frequency Allocations and Radio Treaty Matters; General Rules and Regulations"**
2. **IEEE Std. C95.1-2019, "IEEE Standards for Safety Levels with Respect to Human Exposure to Electric, Magnetic, and Electromagnetic Fields, 0 Hz to 300 GHz"**
3. **IEC/IEEE 62209-1528:2020, Measurement procedure for the assessment of specific absorption rate of human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices Part 1528: Human models, instrumentation, and procedures (Frequency range 4 MHz to 10 GHz)**
4. **FCC KDB447498 D01v06, "RF exposure requirements for mobile and portable device equipment authorizations"**
5. **FCC KDB865664 D01 v01r04, "SAR measurement procedures for devices operating between 100 MHz to 6 GHz"**
6. **FCC KDB865664 D02 v01r02, "RF Exposure Compliance Reporting and Documentation Considerations "**
7. **FCC KDB248227 D01 v02r02, "SAR measurements for devices incorporating IEEE 802.11 wireless transmitters"**

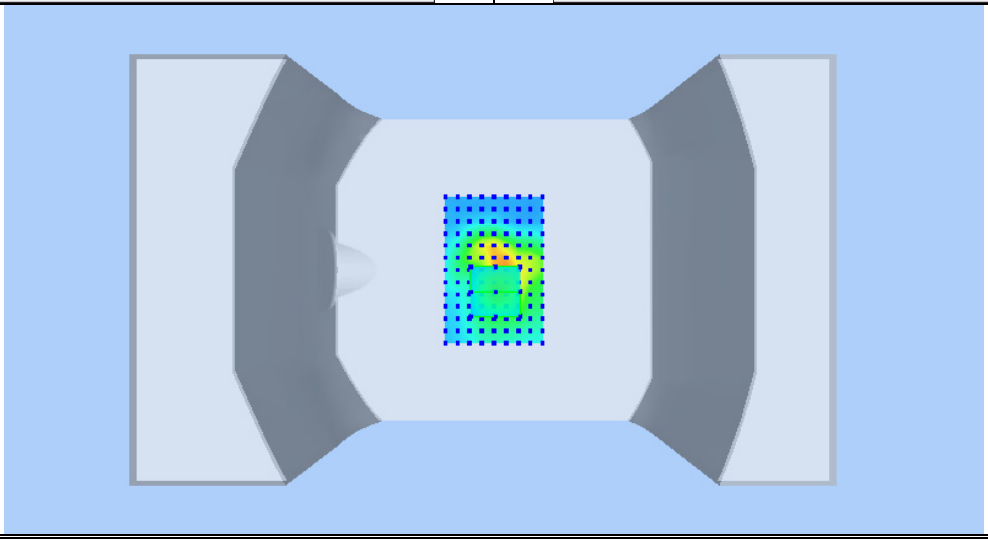
14.2 Maximum SAR measurement Plots

Plot 1: 2.4G Wi-Fi, Low channel (Body SAR, Front Side)
Product Description: Hubble Connected the Bear
Test Date: 2025-06-18

Medium(liquid type)	HL2450
Frequency (MHz)	2412.0000
Relative permittivity (real part)	39.23
Conductivity (S/m)	1.79
Signal	Duty Cycle: 1:1
E-Field Probe	2523-EPGO-417
Conversion Factor	3.01
Area Scan	dx=8mm dy=8mm
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Variation (%)	-1.19
SAR 10g (W/Kg)	0.111237
SAR 1g (W/Kg)	0.232201
SURFACE SAR	**VOLUME SAR**







15 Calibration Reports-Probe and Dipole

COMOSAR E-Field Probe Calibration Report

Ref : ACR.208.13.24.BES.A

WALTEK TESTING GROUP CO., LTD
NO,77, HOUJIE SECTION, GUANTAI ROAD, HOUJIE TOWN
DONGGUAN GUANGDONG 518105, CHINA
MVG COMOSAR DOSIMETRIC E-FIELD PROBE
SERIAL NO.: 2523-EPGO-417

Calibrated at MVG
Z.I. de la pointe du diable
Technopôle Brest Iroise – 295 avenue Alexis de Rochon
29280 PLOUZANE - FRANCE

Calibration date: 07/29/2024

Accreditations #2-6789
Scope available on www.cofrac.fr

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Summary:

This document presents the method and results from an accredited COMOSAR Dosimetric E-Field Probe calibration performed at MVG, using the CALIPROBE test bench, for use with a MVG COMOSAR system only. The test results covered by accreditation are traceable to the International System of Units (SI).

Page: 1/10

	Name	*Function*	*Date*	*Signature*
Prepared by :	Cyrille ONNEE	Measurement Responsible	7/29/2024	
Checked & approved by:	Jérôme Luc	Technical Manager	7/29/2024	
Authorized by:	Yann Toutain	Laboratory Director	7/29/2024	Yann TOUTAIN

Yann Toutain ID Signature numérique de Yann Toutain ID Date : 2024.07.29 10:49:25 +01'00'

	Customer Name
Distribution :	WALTEK TESTING GROUP CO., LTD

Issue	*Name*	*Date*	*Modifications*
A	Cyrille ONNEE	7/29/2024	Initial release

Template_ACR.DDD.N.YY.MVGB.ISSUE_COMOSAR Probe vL
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TABLE OF CONTENTS

1 Device Under Test 4
2 Product Description 4
2.1 General Information 4
3 Measurement Method 4
3.1 Sensitivity 4
3.2 Linearity 5
3.3 Isotropy 5
3.4 Boundary Effect 5
4 Measurement Uncertainty 6
5 Calibration Results 6
5.1 Calibration in air 6
5.2 Calibration in liquid 7
6 Verification Results 8
7 List of Equipment 9

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1 DEVICE UNDER TEST

Device Under Test	
Device Type	COMOSAR DOSIMETRIC E FIELD PROBE
Manufacturer	MVG
Model	SSE2
Serial Number	2523-EPGO-417
Product Condition (new / used)	New
Frequency Range of Probe	0.15 GHz-7.5GHz
Resistance of Three Dipoles at Connector	Dipole 1: R1=0.231 MΩ Dipole 2: R2=0.220 MΩ Dipole 3: R3=0.206 MΩ

2 PRODUCT DESCRIPTION

2.1 GENERAL INFORMATION

MVG's COMOSAR E field Probes are built in accordance to the IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards.

Figure 1 – *MVG COMOSAR Dosimetric E field Probe*

Probe Length	330 mm
Length of Individual Dipoles	24.5 mm
Maximum external diameter	8 mm
Probe Tip External Diameter	2.55 mm
Distance between dipoles / probe extremity	12.7 mm

3 MEASUREMENT METHOD

The IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards provide recommended practices for the probe calibrations, including the performance characteristics of interest and methods by which to assess their effect. All calibrations / measurements performed meet the fore-mentioned standards.

3.1 SENSITIVITY

The sensitivity factors of the three dipoles were determined using a two step calibration method (air and tissue simulating liquid) using waveguides as outlined in the standards for frequency range 600-7500MHz and using the calorimeter cell method (transfer method) as outlined in the standards for frequency 150-450 MHz.

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3.2 LINEARITY

The evaluation of the linearity was done in free space using the waveguide, performing a power sweep to cover the SAR range 0.01W/kg to 100W/kg.

3.3 ISOTROPY

The axial isotropy was evaluated by exposing the probe to a reference wave from a standard dipole with the dipole mounted under the flat phantom in the test configuration suggested for system validations and checks. The probe was rotated along its main axis from 0 to 360 degrees in 15-degree steps. The hemispherical isotropy is determined by inserting the probe in a thin plastic box filled with tissue-equivalent liquid, with the plastic box illuminated with the fields from a half wave dipole. The dipole is rotated about its axis (0°–180°) in 15° increments. At each step the probe is rotated about its axis (0°–360°).

3.4 BOUNDARY EFFECT

The boundary effect is defined as the deviation between the SAR measured data and the expected exponential decay in the liquid when the probe is oriented normal to the interface. To evaluate this effect, the liquid filled flat phantom is exposed to fields from either a reference dipole or waveguide. With the probe normal to the phantom surface, the peak spatial average SAR is measured and compared to the analytical value at the surface.

The boundary effect uncertainty can be estimated according to the following uncertainty approximation formula based on linear and exponential extrapolations between the surface and d_{be} + d_{step} along lines that are approximately normal to the surface:

$$\mathrm{SAR}_{\mathrm{uncertainty}}[\%] = \delta\mathrm{SAR}_{be}\frac{(d_{be}+d_{step})^2}{2d_{step}}\frac{\left(e^{-d_{be}/(\delta/2)}\right)}{\delta/2} \quad \text{for } (d_{be}+d_{step}) < 10\text{ mm}$$

where

$\mathrm{SAR}_{\mathrm{uncertainty}}$	is the uncertainty in percent of the probe boundary effect
d_{be}	is the distance between the surface and the closest *zoom-scan* measurement point, in millimetre
Δ_{step}	is the separation distance between the first and second measurement points that are closest to the phantom surface, in millimetre, assuming the boundary effect at the second location is negligible
δ	is the minimum penetration depth in millimetres of the head tissue-equivalent liquids defined in this standard, i.e., $\delta \approx$ 14 mm at 3 GHz;
$\Delta\mathrm{SAR}_{be}$	in percent of SAR is the deviation between the measured SAR value, at the distance d_{be} from the boundary, and the analytical SAR value.

The measured worst case boundary effect SARuncertainty[%] for scanning distances larger than 4mm is 1.0% Limit ,2%).

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4 MEASUREMENT UNCERTAINTY

The guidelines outlined in the IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards were followed to generate the measurement uncertainty associated with a SAR probe calibration using the waveguide or calorimetric cell technique depending on the frequency.

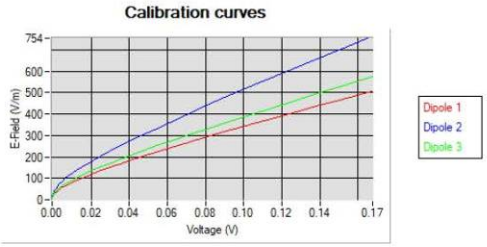
The estimated expanded uncertainty (k=2) in calibration for SAR (W/kg) is +/-11% for the frequency range 150-450MHz.
The estimated expanded uncertainty (k=2) in calibration for SAR (W/kg) is +/-14% for the frequency range 600-7500MHz.

5 CALIBRATION RESULTS

Ambient condition	
Liquid Temperature	20 +/- 1 °C
Lab Temperature	20 +/- 1 °C
Lab Humidity	30-70 %

5.1 CALIBRATION IN AIR

The following curve represents the measurement in waveguide of the voltage picked up by the probe toward the E-field generated inside the waveguide.



From this curve, the sensitivity in air is calculated using the below formula.

$$E^2 = \sum_{i=1}^{3} \frac{V_i\left(1 + {V_i}/{DCP_i}\right)}{Norm_i}$$

where
Vi=voltage readings on the 3 channels of the probe
DCPi=diode compression point given below for the 3 channels of the probe
Normi=dipole sensitivity given below for the 3 channels of the probe

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Normx dipole 1 (μV/(V/m)^2)	Normy dipole 2 (μV/(V/m)^2)	Normz dipole 3 (μV/(V/m)^2)
1.64	0.73	1.30

DCP dipole 1 (mV)	DCP dipole 2 (mV)	DCP dipole 3 (mV)
110	110	106

5.2 CALIBRATION IN LIQUID

The calorimeter cell or the waveguide is used to determine the calibration in liquid using the formula below.

$$ConvF = \frac{E_{liquid}^2}{E_{air}^2}$$

The E-field in the liquid is determined from the SAR measurement according to the below formula.

$$E_{liquid}^2 = \frac{\rho\, SAR}{\sigma}$$

where
σ=the conductivity of the liquid
ρ=the volumetric density of the liquid
SAR=the SAR measured from the formula that depends on the setup used. The SAR formulas are given below

For the calorimeter cell (150-450 MHz), the formula is:

$$SAR = c\frac{dT}{dt}$$

where
c=the specific heat for the liquid
dT/dt=the temperature rises over the time

For the waveguide setup (600-75000 MHz), the formula is:

$$SAR = \frac{4P_W}{ab\delta} e^{\frac{-2z}{\delta}}$$

where
a=the larger cross-sectional of the waveguide
b=the smaller cross-sectional of the waveguide
δ=the skin depth for the liquid in the waveguide
Pw=the power delivered to the liquid

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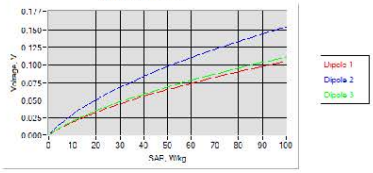
The below table summarize the ConvF for the calibrated liquid. The curves give examples for the measured SAR depending on the voltage in some liquid.

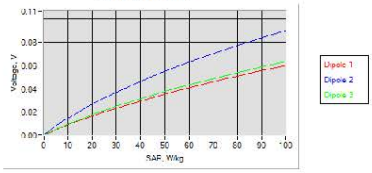
Liquid	Frequency (MHz*)	ConvF
HL750	750	2.58
HL850	835	2.46
HL900	900	2.64
HL1800	1800	2.62
HL1900	1900	2.84
HL2000	2000	2.98
HL2300	2300	2.90
HL2450	2450	3.01
HL2600	2600	2.75

(*) Frequency validity is +/-50MHz below 600MHz, +/-100MHz from 600MHz to 6GHz and +/-700MHz above 6GHz

SAR @ HL750



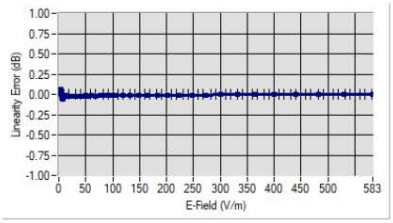
SAR @ HL2600



6 VERIFICATION RESULTS

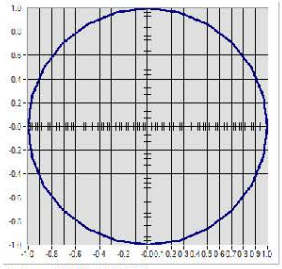
The figures below represent the measured linearity and axial isotropy for this probe. The probe specification is +/-0.2 dB for linearity and +/-0.15 dB for axial isotropy.

Linearity



Linearity:+/-1.43% (+/-0.06dB)

Isotropy curve



Isotropy:+/-0.14% (+/-0.01dB)

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7 LIST OF EQUIPMENT

Equipment Summary Sheet				
Equipment Description	**Manufacturer / Model**	**Identification No.**	**Current Calibration Date**	**Next Calibration Date**
CALIPROBE Test Bench	Version 2	NA	Validated. No cal required.	Validated. No cal required.
Network Analyzer	Rohde & Schwarz ZVM	100203	08/2021	08/2024
Network Analyzer	Agilent 8753ES	MY40003210	10/2023	10/2027
Network Analyzer – Calibration kit	HP 85033D	3423A08186	06/2021	06/2027
Network Analyzer – Calibration kit	Rohde & Schwarz ZV-Z235	101223	07/2022	07/2025
Multimeter	Keithley 2000	4013982	02/2023	02/2026
Signal Generator	Rohde & Schwarz SMB	106589	03/2022	03/2025
Amplifier	MVG	MODU-023-C-0002	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Power Meter	NI-USB 5680	170100013	06/2024	06/2027
Power Meter	Keysight U2000A	SN: MY62340002	10/2022	10/2025
Directional Coupler	Krytar 158020	131467	Characterized prior to test. No cal required.	Characterized prior to test. No cal required.
Fluoroptic Thermometer	LumaSense Luxtron 812	94264	09/2022	09/2025
Coaxial cell	MVG	SN 32/16 COAXCELL_1	Validated. No cal required.	Validated. No cal required.
Waveguide	MVG	SN 32/16 WG2_1	Validated. No cal required.	Validated. No cal required.
Liquid transition	MVG	SN 32/16 WGLIQ_0G600_1	Validated. No cal required.	Validated. No cal required.
Waveguide	MVG	SN 32/16 WG4_1	Validated. No cal required.	Validated. No cal required.
Liquid transition	MVG	SN 32/16 WGLIQ_0G900_1	Validated. No cal required.	Validated. No cal required.
Waveguide	MVG	SN 32/16 WG6_1	Validated. No cal required.	Validated. No cal required.
Liquid transition	MVG	SN 32/16 WGLIQ_1G500_1	Validated. No cal required.	Validated. No cal required.

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Waveguide	MVG	SN 32/16 WG8_1	Validated. No cal required.	Validated. No cal required.
Liquid transition	MVG	SN 32/16 WGLIQ_1G800B_1	Validated. No cal required.	Validated. No cal required.
Liquid transition	MVG	SN 32/16 WGLIQ_1G800H_1	Validated. No cal required.	Validated. No cal required.
Waveguide	MVG	SN 32/16 WG10_1	Validated. No cal required.	Validated. No cal required.
Liquid transition	MVG	SN 32/16 WGLIQ_3G500_1	Validated. No cal required.	Validated. No cal required.
Waveguide	MVG	SN 32/16 WG12_1	Validated. No cal required.	Validated. No cal required.
Liquid transition	MVG	SN 32/16 WGLIQ_5G000_1	Validated. No cal required.	Validated. No cal required.
Waveguide	MVG	SN 32/16 WG14_1	Validated. No cal required.	Validated. No cal required.
Liquid transition	MVG	SN 32/16 WGLIQ_7G000_1	Validated. No cal required.	Validated. No cal required.
Temperature / Humidity Sensor	Testo 184 H1	44225320	06/2024	06/2027

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SAR Reference Dipole Calibration Report

Ref : ACR.335.14.23.BES.A

WALTEK TESTING GROUP CO., LTD.

NO.77, HOUJIE SECTION, GUANTAI ROAD, HOUJIE TOWN, DONGGUAN, GUANGDONG 518105 , CHINA

MVG COMOSAR REFERENCE DIPOLE

FREQUENCY: 2450MHZ

SERIAL NO.: SN 09/15 DIP 2G450-363

Calibrated at MVG
Z.I. de la pointe du diable
Technopôle Brest Iroise – 295 avenue Alexis de Rochon
29280 PLOUZANE - FRANCE

Calibration date: 08/08/2023

Accreditations #2-6789 and #2-6814

Scope available on www.cofrac.fr

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Summary:

This document presents the method and results from an accredited SAR reference dipole calibration performed in MVG using the COMOSAR test bench. All calibration results are traceable to national metrology institutions.

Page: 1/13

SAR REFERENCE DIPOLE CALIBRATION REPORT

Ref: ACR.335.14.23.BES.A

	Name	*Function*	*Date*	*Signature*
Prepared by :	Jérôme Luc	Technical Manager	8/8/2023	
Checked by :	Jérôme Luc	Technical Manager	8/8/2023	
Approved by :	Yann Toutain	Laboratory Director	8/8/2023	Yann TOUTAIN 2023.08.08 10:06:13 +01'00'

	Customer Name
Distribution :	Waltek Testing Group Co., Ltd.

Issue	*Name*	*Date*	*Modifications*
A	Jérôme Luc	8/8/2023	Initial release

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TABLE OF CONTENTS

1 Introduction 4
2 Device Under Test 4
3 Product Description 4
3.1 General Information 4
4 Measurement Method 5
4.1 Return Loss Requirements 5
4.2 Mechanical Requirements 5
5 Measurement Uncertainty 5
5.1 Return Loss 5
5.2 Dimension Measurement 5
5.3 Validation Measurement 5
6 Calibration Measurement Results 6
6.1 Return Loss and Impedance In Head Liquid 6
6.2 Return Loss and Impedance In Body Liquid 6
6.3 Mechanical Dimensions 7
7 Validation measurement 7
7.1 Head Liquid Measurement 8
7.2 SAR Measurement Result With Head Liquid 8
7.3 Body Liquid Measurement 11
7.4 SAR Measurement Result With Body Liquid 12
8 List of Equipment 13

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1 INTRODUCTION

This document contains a summary of the requirements set forth by the IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards for reference dipoles used for SAR measurement system validations and the measurements that were performed to verify that the product complies with the fore mentioned standards.

2 DEVICE UNDER TEST

Device Under Test	
Device Type	COMOSAR 2450 MHz REFERENCE DIPOLE
Manufacturer	MVG
Model	SID2450
Serial Number	SN 09/15 DIP 2G450-363
Product Condition (new / used)	New

3 PRODUCT DESCRIPTION

3.1 GENERAL INFORMATION

MVG's COMOSAR Validation Dipoles are built in accordance to the IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards. The product is designed for use with the COMOSAR test bench only.

Figure 1 – *MVG COMOSAR Validation Dipole*

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4 MEASUREMENT METHOD

The IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards provide requirements for reference dipoles used for system validation measurements. The following measurements were performed to verify that the product complies with the fore mentioned standards.

4.1 RETURN LOSS REQUIREMENTS

The dipole used for SAR system validation measurements and checks must have a return loss of -20 dB or better. The return loss measurement shall be performed against a liquid filled flat phantom, with the phantom constucted as outlined in the fore mentioned standards. A direct method is used with a network analyser and its calibration kit, both with a valid ISO17025 calibration.

4.2 MECHANICAL REQUIREMENTS

The IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards specify the mechanical components and dimensions of the validation dipoles, with the dimension's frequency and phantom shell thickness dependent. The COMOSAR test bench employs a 2 mm phantom shell thickness therefore the dipoles sold for use with the COMOSAR test bench comply with the requirements set forth for a 2 mm phantom shell thickness. A direct method is used with a ISO17025 calibrated caliper.

5 MEASUREMENT UNCERTAINTY

All uncertainties listed below represent an expanded uncertainty expressed at approximately the 95% confidence level using a coverage factor of k=2, traceable to the Internationally Accepted Guides to Measurement Uncertainty.

5.1 RETURN LOSS

The following uncertainties apply to the return loss measurement:

Frequency band	Expanded Uncertainty on Return Loss
400-6000MHz	0.10 LIN

5.2 DIMENSION MEASUREMENT

The following uncertainties apply to the dimension measurements:

Length (mm)	Expanded Uncertainty on Length
3 - 300	0.05 mm
300 - 450	0.11 mm

5.3 VALIDATION MEASUREMENT

The guidelines outlined in the IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards were followed to generate the measurement uncertainty for validation measurements.

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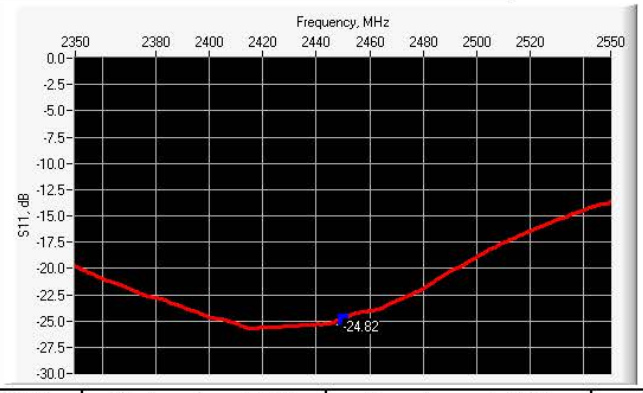
Scan Volume	Expanded Uncertainty
1 g	20.3 % (SAR)
10 g	20.1 % (SAR)

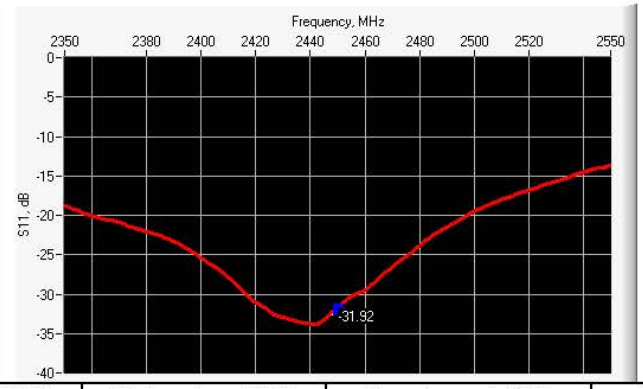
6 CALIBRATION MEASUREMENT RESULTS

6.1 RETURN LOSS AND IMPEDANCE IN HEAD LIQUID



Frequency (MHz)	Return Loss (dB)	Requirement (dB)	Impedance
2450	-24.82	-20	44.3 Ω + 0.2 jΩ

6.2 RETURN LOSS AND IMPEDANCE IN BODY LIQUID



Frequency (MHz)	Return Loss (dB)	Requirement (dB)	Impedance
2450	-31.92	-20	47.5 Ω - 0.4 jΩ

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6.3 MECHANICAL DIMENSIONS

Frequency MHz	L mm		h mm		d mm	
	required	measured	required	measured	required	measured
300	420.0 ±1 %.		250.0 ±1 %.		6.35 ±1 %.	
450	290.0 ±1 %.		166.7 ±1 %.		6.35 ±1 %.	
750	176.0 ±1 %.		100.0 ±1 %.		6.35 ±1 %.	
835	161.0 ±1 %.		89.8 ±1 %.		3.6 ±1 %.	
900	149.0 ±1 %.		83.3 ±1 %.		3.6 ±1 %.	
1450	89.1 ±1 %.		51.7 ±1 %.		3.6 ±1 %.	
1500	80.5 ±1 %.		50.0 ±1 %.		3.6 ±1 %.	
1640	79.0 ±1 %.		45.7 ±1 %.		3.6 ±1 %.	
1750	75.2 ±1 %.		42.9 ±1 %.		3.6 ±1 %.	
1800	72.0 ±1 %.		41.7 ±1 %.		3.6 ±1 %.	
1900	68.0 ±1 %.		39.5 ±1 %.		3.6 ±1 %.	
1950	66.3 ±1 %.		38.5 ±1 %.		3.6 ±1 %.	
2000	64.5 ±1 %.		37.5 ±1 %.		3.6 ±1 %.	
2100	61.0 ±1 %.		35.7 ±1 %.		3.6 ±1 %.	
2300	55.5 ±1 %.		32.6 ±1 %.		3.6 ±1 %.	
2450	51.5 ±1 %.	51.48	30.4 ±1 %.	30.42	3.6 ±1 %.	3.61
2600	48.5 ±1 %.		28.8 ±1 %.		3.6 ±1 %.	
3000	41.5 ±1 %.		25.0 ±1 %.		3.6 ±1 %.	
3300	-		-		-	
3500	37.0±1 %.		26.4 ±1 %.		3.6 ±1 %.	
3700	34.7±1 %.		26.4 ±1 %.		3.6 ±1 %.	
3900	-		-		-	
4200	-		-		-	
4600	-		-		-	
4900	-		-		-	

7 VALIDATION MEASUREMENT

The IEC/IEEE 62209-1528 and FCC KDB865664 D01 standards state that the system validation measurements must be performed using a reference dipole meeting the fore mentioned return loss and mechanical dimension requirements. The validation measurement must be performed against a liquid filled flat phantom, with the phantom constructed as outlined in the fore mentioned standards. Per the standards, the dipole shall be positioned below the bottom of the phantom, with the dipole length centered and parallel to the longest dimension of the flat phantom, with the top surface of the dipole at the described distance from the bottom surface of the phantom.

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