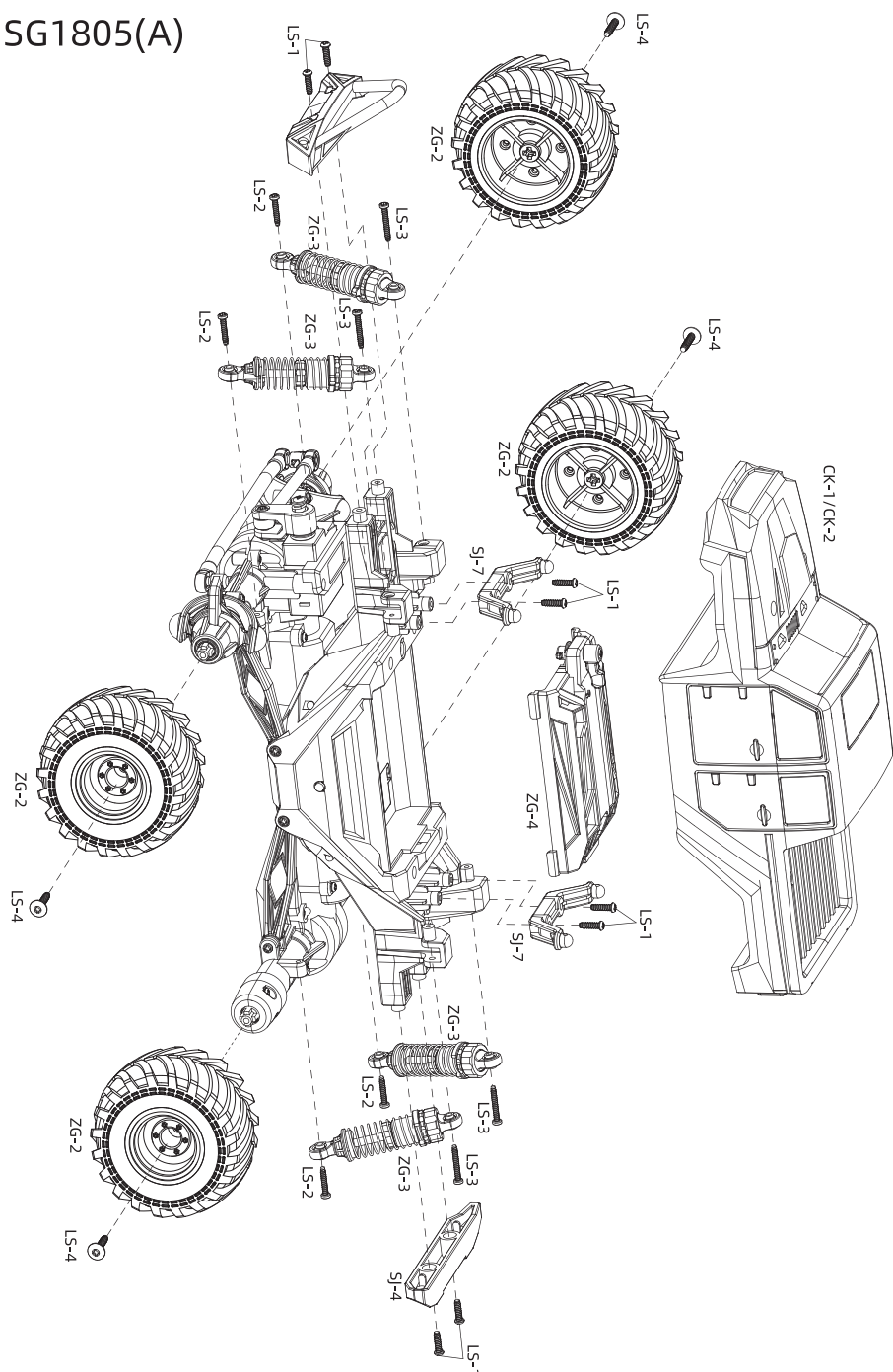


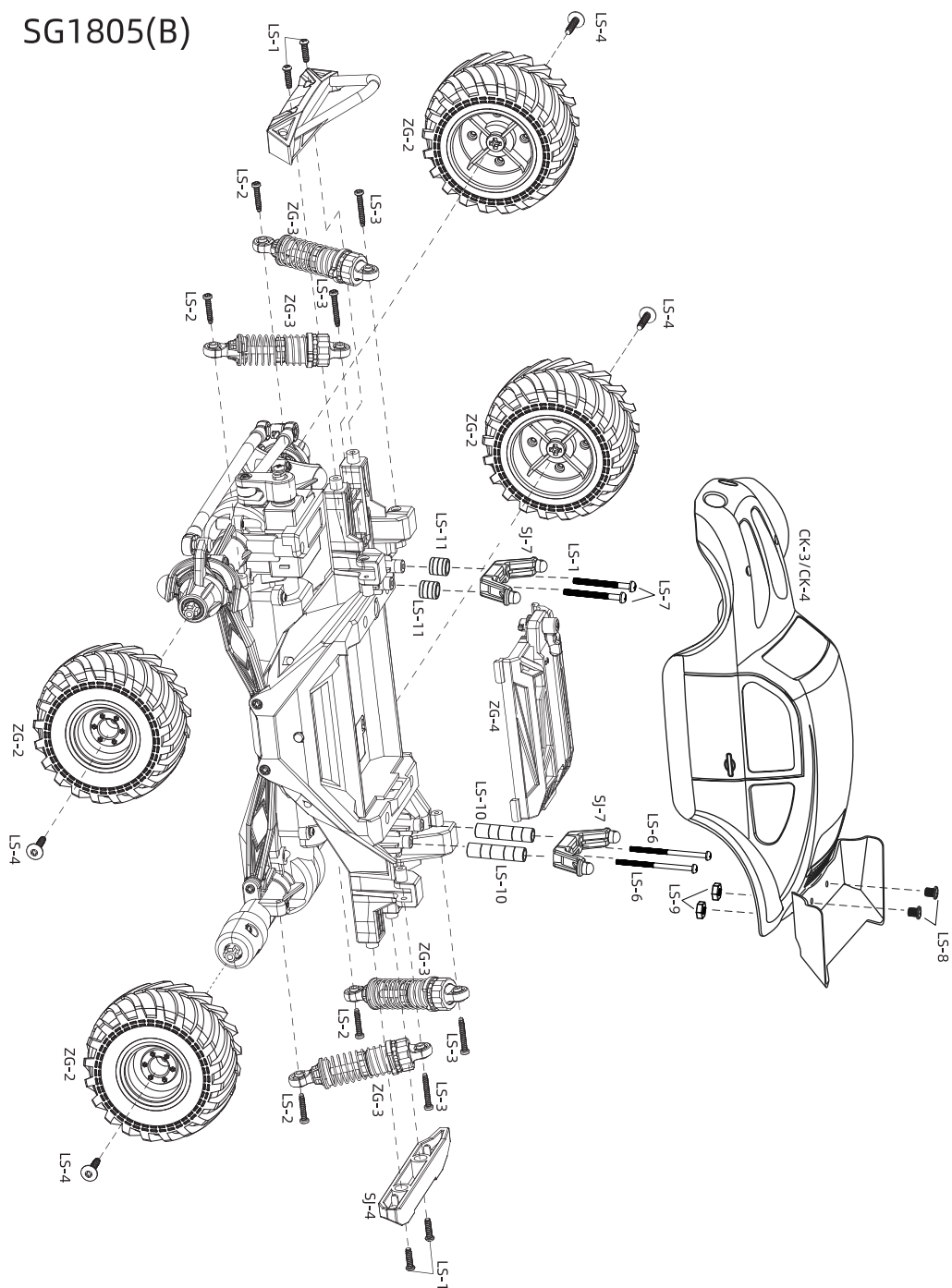
ASSEMBLY 装配

SG1805(A)



ASSEMBLY 装配

SG1805(B)



APP INSTRUCTIONS 使用说明

1. 产品简介 Product Introduction

SG1805特技车智能操控APP是专为SG1805特技遥控车量身打造的智能操控管理软件，支持多终端操控方式，涵盖主流安卓手机端及微信小程序端，无需局限单一设备即可完成车辆操控。

软件打破传统遥控车单一操控模式，集成遥控器数据回显、基础灯光车速控制、特技辅助、高精度参数微调、多模式A-ESP智能调控、陀螺仪专业调校、智能语音控制、设备升级运维等全方位功能。

本产品兼顾入门娱乐与专业调校需求，既可以满足新手玩家日常特技玩耍、简单操控使用，也可支持进阶玩家自定义车辆姿态参数、调试专属特技效果，搭配参数重置功能，可彻底规避参数调试异常问题，是SG1805特技车配套的专属智能化操控工具。

The SG1805 Stunt Car Intelligent Control APP is a dedicated intelligent control and management software tailored exclusively for the SG1805 stunt remote-controlled car. It supports multi-terminal control, covering mainstream Android smartphones and WeChat mini-programs, enabling vehicle control without being restricted to a single device.

Breaking the single control mode of traditional remote-controlled cars, the software integrates comprehensive functions including remote controller data display, basic light and speed control, stunt assistance, high-precision parameter fine-tuning, multi-mode A-ESP intelligent regulation, professional gyroscope calibration, intelligent voice control, and device upgrade & maintenance.

Designed to meet both entry-level entertainment and professional tuning needs, this product allows novice users to enjoy daily stunts and simple operation, while enabling advanced users to customize vehicle attitude parameters and adjust exclusive stunt effects. Equipped with a parameter reset function, it effectively avoids abnormal parameter tuning issues, serving as an exclusive intelligent control tool for the SG1805 stunt car.



注意
CAUTION

本说明书当前最新版本为V1.0，为SG1805特技车智能操控APP首发官方使用文档；本说明书将伴随APP软件版本、车辆固件版本迭代不定期更新，优化功能说明、操作步骤及参数规范，更新后的内容将替代旧版文档内容，敬请用户及时查阅APP里的最新版本。

The latest version of this manual is V1.0, the official launch document for the SG1805 Stunt Car Intelligent Control APP. This manual will be updated irregularly along with iterations of the APP software version and vehicle firmware version to optimize function descriptions, operation steps and parameter specifications. Updated content shall supersede previous versions. Users are advised to check the latest version in the APP in a timely manner.

2. APP下载与安装 APP Download and Installation

扫描左边的二维码，下载安装“RCHome”APP（安卓版）；或者微信扫描右边的二维码，进入“RCHome”微信小程序。

Scan the left QR code to download and install the Android version of the RCHome APP; or scan the right QR code via WeChat to access the RCHome Mini Program.



SCAN TO DOWNLOAD



RCHome Mini Program

3. APP配对连接遥控器 Remote Controller Pairing with APP

1. 打开遥控器电源。确保手机已打开蓝牙功能，运行“RCHome APP”。

Turn on the power of the remote controller. Ensure Bluetooth is enabled on your mobile phone and launch the RCHome APP.

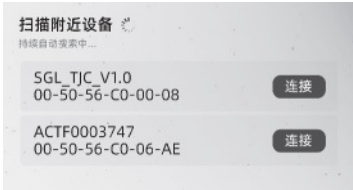
2. 进入APP，点击下方菜单栏“RC”按钮，进入设备清单页面，点击“特技抬头车”按钮；

Open the app, tap the "RC" button in the bottom menu bar to enter the device list page, then tap the "特技抬头车" button.



3. 进入“搜索蓝牙”页面，扫描附近设备。在下方的蓝牙设备中找到蓝牙名称为“SGL_TJC_****”的设备，点击“连接”按钮，进入特技车设置页面；

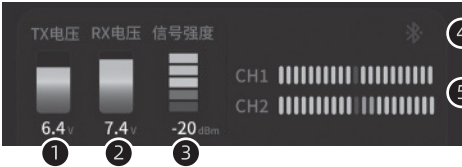
Go to the "Search Bluetooth" page and scan nearby devices. Locate the device named "SGL_TJC_****" from the listed Bluetooth devices, tap the "连接" button, and enter the stunt car settings page.



4.基础操控功能使用指南 User Guide for Basic Control Functions

本章涵盖APP日常高频基础操控功能，详细说明操作方式、使用场景。
This chapter covers frequently-used basic control functions of the APP, detailing operation methods and application scenarios.

4.1 遥控器数据回显功能 Remote Controller Data Feedback Function



- 1 遥控器电压 Transmitter Voltage
- 2 遥控车电压 Receiver Voltage
- 3 信号强度 Signal Strength
- 4 蓝牙状态 Bluetooth Status
- 5 通道行程 Channel Travel

1 TX电压：遥控器电压 Transmitter Voltage

显示当前相连的遥控器的实时电压，当电压过低时，需要更换遥控器的电池。
It displays the real-time voltage of the currently connected remote controller. Replace the remote controller batteries when the voltage is too low.

2 RX电压：遥控车电压 Receiver Voltage

显示当前相连的遥控车的实时电压，当电压过低时，需要更换遥控车的电池。
It displays the real-time voltage of the connected remote-controlled car. Replace the car's batteries when the voltage is low.

3 信号强度：信号强度 Signal Strength

遥控器与手机之间，蓝牙的连接信号强度。数字越大，说明信号越强。
It shows the Bluetooth signal strength between the remote controller and the mobile phone. A higher number indicates a stronger signal.

4 蓝牙状态显示：Bluetooth Status

显示当前的连接状态。若蓝牙已连接，图标为蓝色。若未连接，则为灰色。
Displays the current connection status. The icon turns blue when Bluetooth is connected, and gray when disconnected.

5 通道实时行程：Real-time Channel Travel

显示CH1/CH2的实时通道行程。
Displays the real-time channel travel of CH1/CH2.

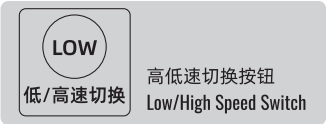
4.2 车灯控制功能 Headlight Control Function

控制遥控车的前后车灯，以及底盘灯光。
Control the front and rear lights as well as chassis lights of the remote-controlled car.



4.3 高/低速模式切换 High/Low Speed Mode Switching

切换特技车的高速/低速模式。
Switch between high-speed and low-speed modes of the stunt car.



4.4 特技辅助基础功能 Basic Stunt Assist Functions

自动抬头：点击按钮后，特技车会自动抬头并前进一段距离。建议在较空旷的地方使用该功能。

Auto Wheelie: After clicking the button, the stunt car will automatically wheelie and move forward for a short distance. It is recommended to use this function in an open area.

自动翻正：车辆行驶过程中若不慎翻车，点击该按钮，特技车可自动调整姿态，完成复位摆正，恢复正常行驶状态。

Auto-Righting Function: If the stunt car accidentally flips over while driving, tap this button, and it will automatically adjust its posture, right itself, and return to normal driving status.



4.5 转向中位微调功能 Steering Center Fine-tuning Function

用于精准校正车辆转向中位，当遥控车行驶出现跑偏、转向不对称时，可微调修正车轮居中位置，让车辆直行更平稳，提升操控精准度。

It is used to precisely calibrate the steering center of the vehicle. When the remote-controlled car drifts or has asymmetric steering during driving, fine-tune to correct the wheel center position for smoother straight-line driving and improved control accuracy.



5. 高级参数调节功能 Advanced Parameter Adjustment Functions

本章针对专业调校功能，适配进阶用户优化车辆操控手感与特技效果。
This chapter covers professional tuning functions for advanced users to optimize vehicle handling and stunt performance.

5.1 通道行程调整功能 Channel Travel Adjustment Function

调节油门、转向等动作幅度，适配不同操控手感。

Channel Travel Adjustment Function: Adjust the amplitude of throttle, steering and other actions to suit different control feels.



5.2 A-ESP介入强度 A-ESP Intervention Intensity Adjustment

可自定义车身稳定系统介入力度，高速行驶、急转弯、特技漂移时，自动修正车身姿态，抑制甩尾、侧滑、失控，适配不同操控手感。

Customize the intervention intensity of the stability control system. It automatically corrects vehicle posture and suppresses skidding and loss of control during high-speed driving, sharp turns and stunts to adapt to different control feelings.



6.A-ESP多模式自定义设置 A-ESP Multi-Mode Custom Settings

本章针对专业调校功能，适配进阶用户优化车辆操控手感与特技效果。
This chapter covers professional tuning functions for advanced users to optimize vehicle handling and stunt performance.

6.1 A-ESP模式总览 Overview of A-ESP Modes

本设备A-ESP智能稳定系统内置关闭模式、自稳模式、特技模式、自定义模式四种工作模式，四种模式定位清晰、适配场景差异化明显，可满足从新手稳定操控到专业特技调校的全场景使用需求。

The A-ESP Intelligent Stability System of this device features four operating modes: Off Mode, Stability Mode, Stunt Mode, and Custom Mode. These modes have clear positioning and distinct applicable scenarios, meeting all-scene usage requirements from stable control for beginners to professional stunt tuning.

6.2 基础模式使用说明 Instructions for Basic Modes

关闭

A-ESP关闭模式
A-ESP Off Mode

自稳

A-ESP自稳模式
A-ESP Stability Mode

特技

A-ESP特技模式
A-ESP Stunt Mode

- **A-ESP关闭模式：**系统完全关闭陀螺仪稳定介入与车身辅助矫正功能，车辆无任何电子稳定限制，动力输出、转向操控完全由用户手动掌控，操控自由度最高。适配熟练掌握车辆操控技巧的专业玩家，适合进行极限漂移、高难度自由特技创作、无约束车体动作调试等场景。
- **A-ESP自稳模式：**系统全程开启陀螺仪智能介入，实时矫正车身姿态、抑制车体侧翻、偏移、打滑问题，车速与动作幅度受到智能保护限制，操控容错率极高。专为新手玩家设计，适配日常休闲行驶、基础操控练习、平地稳定巡航等场景，最大程度避免误操作导致的车辆翻车、失控等问题。
- **A-ESP特技模式：**系统内置出厂预设特技专用参数，保留基础稳定防护的同时，放开特技动作所需的姿态限制，兼顾稳定性与灵活性，适配常规花式特技操作。适合有一定基础的进阶玩家，可流畅完成抬头、翻正、漂移、原地旋转等常规标准特技动作，无需手动调试参数，即开即用。

- **A-ESP Off Mode:**
The gyroscope stability intervention and vehicle body-assisted correction functions are fully disabled. The vehicle is free from all electronic stability limits, with power output and steering control entirely under manual user operation for maximum freedom of control. Designed for professional players with proficient vehicle-handling skills, it is ideal for extreme drifting, advanced free-style stunts, and unrestricted body-movement tuning.
- **A-ESP Stability Mode:**
The gyroscope provides continuous intelligent intervention to correct vehicle posture in real time and prevent rollover, deviation and skidding. Vehicle speed and movement range are intelligently restricted for high control tolerance. Specially developed for novice users, it suits daily casual driving, basic control practice and stable flat-ground cruising, minimizing rollovers and loss of control caused by misoperation.
- **A-ESP Stunt Mode:**
Pre-calibrated factory stunt-specific parameters are applied. While basic stability protection is retained, posture limitations for stunt maneuvers are relaxed to balance stability and flexibility for general freestyle stunts. Suitable for intermediate players with basic skills, it enables seamless execution of standard stunts such as wheelies, self-righting, drifting and spinning without manual parameter tuning, ready for instant use.

6.3 自定义模式（专业调校） Custom Mode (Professional Tuning)

- **A-ESP自定义模式：**为专业调校专属模式，关闭系统预设参数，支持用户独立、自由调节陀螺仪X、Y、Z三轴全部工作参数，可针对性调整车辆前后俯仰、左右横滚、水平转向的姿态灵敏度与介入力度，完全自定义车辆操控特性与特技风格。
适配高阶专业玩家、个性化调试场景，可根据自身操控习惯、自定义特技动作，调试出专属车辆操控参数，打造专属特技效果。
- **A-ESP Custom Mode:**
Exclusive for professional tuning. Factory preset parameters are disabled, allowing users to independently adjust all X, Y, Z-axis working parameters of the gyroscope. Posture sensitivity and intervention intensity for pitch, roll and yaw can be modified specifically to fully customize vehicle handling characteristics and stunt styles.
For advanced professional users and personalized tuning scenarios, custom handling parameters and exclusive stunt effects can be configured according to individual driving habits and self-designed stunts.

自定义

A-ESP自定义模式
A-ESP Custom Mode

6.3.1 X/Y/Z 轴车体姿态控制逻辑详解 Detailed Explanation of X/Y/Z-Axis Vehicle Posture Control Logic :

本设备陀螺仪三轴分别对应车辆三个维度的姿态感知与稳定控制，三轴相互独立、各司其职，用户可单独调节单轴灵敏度与介入强度，精准定义车辆特技手感，三轴控制逻辑具体说明如下：

The three axes of the device's gyroscope correspond to posture sensing and stability control in three dimensions of the vehicle. Each axis operates independently with dedicated functions. Users can separately adjust the sensitivity and intervention intensity of each axis to precisely define the vehicle's stunt handling feel. The detailed control logic of the three axes is described as follows:

- **X轴（横滚轴：左右倾斜控制）**
控制逻辑：X轴对应车体左右横向倾斜姿态，负责监测与修正车辆左右侧倾、侧翻、横摆幅度。
专属可调参数：开启/关闭、正反转、PRT、RIT、感度调节
1.X轴开关：单独控制X轴陀螺仪姿态稳定功能启停。关闭后车辆无左右侧倾限制，横向完全自由；开启后启用车身横滚稳定、侧翻保护功能。
2.X轴正反转：适配陀螺仪安装方向与车体姿态逻辑校正。若开启X轴后车辆左右纠偏反向、姿态补偿错乱，可切换正反转参数恢复正常控制逻辑。

3.PRT（翻滚介入值）：控制车辆左右侧倾时陀螺仪的介入响应强度。数值越高，车辆出现侧倾时系统介入越快、抑制翻滚力度越强，过弯和漂移更稳；数值越低，横向翻滚限制越宽松，可实现大角度侧倾、单边轮行驶等特技动作。

4.RIT（翻车保护值）：车辆横向翻车保护阈值参数。数值越高，车身侧防翻滚阈值越大，极限操控下不易翻车，容错性更高；数值越低，保护阈值更灵敏，轻微侧倾即会触发姿态矫正，适合极致稳定行驶场景。

5.X轴敏感度调节：X轴陀螺仪整体姿态感知灵敏度。感度越高，车身微小左右倾斜即可被快速捕捉并修正，姿态更稳；感度越低，横向姿态响应更柔和，特技动作更松弛自然。

● X-Axis (Roll Axis: Left-Right Tilt Control)

Control Logic: The X-axis corresponds to the left-right lateral tilt posture of the vehicle body, responsible for monitoring and correcting vehicle roll, overturn and yaw amplitude.

Adjustable Exclusive Parameters: On/Off, Reverse, PRT, RIT, Sensitivity Adjustment

1. X-Axis Switch: Independently enables or disables the X-axis gyroscope posture stabilization function. When disabled, the vehicle has no left-right roll restrictions with full lateral freedom. When enabled, body roll stabilization and rollover protection functions are activated.

2. X-Axis Reverse: Used to calibrate the gyroscope mounting direction and vehicle posture logic. If left-right correction is reversed or posture compensation malfunctions after enabling the X-axis, toggle this parameter to restore normal control logic.

3. PRT (Roll Intervention Value): Controls the gyroscope intervention response intensity during vehicle left-right tilting. A higher value enables faster system intervention and stronger roll suppression for improved stability during cornering and drifting. A lower value relaxes lateral roll limits, allowing extreme-angle tilting and single-wheel driving stunts.

4. RIT (Rollover Protection Value): Threshold parameter for lateral rollover protection. A higher value raises the rollover protection threshold for better fault tolerance and resistance to rollover during extreme maneuvers. A lower value delivers more sensitive protection that triggers posture correction upon slight tilting, ideal for ultra-stable driving scenarios.

5. X-Axis Sensitivity Adjustment: Overall posture-sensing sensitivity of the X-axis gyroscope. Higher sensitivity quickly detects and corrects minor left-right body tilts for enhanced stability. Lower sensitivity softens lateral posture response for more relaxed and natural stunt movements.



● Y轴（俯仰轴：前后俯仰控制 / 特技核心轴）

控制定义：管控车辆前后俯仰姿态，对应加速抬头、刹车低头、前后翻跳、翘头站立等核心特技动作，直接决定车辆特技表现力与行驶平稳性，为全车特技核心控制轴。

专属可调参数：开启/关闭、正反转、LIT、BIT、感度调节

1. Y轴开关：单独控制Y轴陀螺仪俯仰稳定功能启停。关闭后无前后姿态限制，可自由俯仰跳跃；开启后启用抬头、刹车俯仰智能矫正功能。

2. Y轴正反转：用于校正前后俯仰姿态控制方向反向问题。若车辆加速低头、刹车抬头（逻辑反向），切换此参数即可恢复正常俯仰控制逻辑。

3. LIT（抬头介入比）：控制车辆加速抬头姿态的陀螺仪介入强度。数值越高，对抬头幅度限制越强，车辆加速更平稳、不易过度翘头；数值越低，抬头限制越弱，车辆更易容易翘头、支持长时间翘头站立特技。

4. BIT（刹车介入比）：控制车辆刹车、减速时的前后俯仰矫正力度。数值越高，刹车俯冲、前倾抑制效果越好，急刹车身更稳；数值越低，刹车姿态更松弛，可实现俯冲、前倾花式动作。

5. Y轴感度调节：控制Y轴陀螺仪整体响应灵敏度。感度越高，车辆前后姿态捕捉越灵敏，俯仰矫正反应越快；感度越低，前后动作响应更柔和，直线行驶更稳定。



● Y-Axis (Pitch Axis: Front-Rear Pitch Control / Core Stunt Axis)

Control Definition: Governs the vehicle's front-rear pitch posture, corresponding to core stunts such as wheelie on acceleration, nose-dive on braking, front-rear jumping, and wheelie standing. It directly determines the vehicle's stunt performance and driving stability, serving as the core control axis for all stunts.

Exclusive Adjustable Parameters: On/Off, Reverse, LIT, BIT, Sensitivity Adjustment.

1. Y-Axis Switch: Independently enables or disables the Y-axis gyroscope pitch stabilization function. When disabled, there are no front-rear posture restrictions for free pitching and jumping. When enabled, intelligent correction for wheelie and braking pitch is activated.

2. Y-Axis Reverse: Used to correct reversed front-rear pitch control direction. If the vehicle dives forward during acceleration or lifts up during braking (reversed logic), toggle this parameter to restore normal pitch control logic.
3. LIT (Lift Intervention Ratio): Controls the gyroscope intervention intensity for wheelie posture during acceleration. A higher value imposes stronger limits on wheelie amplitude for smoother acceleration and prevents excessive wheelies. A lower value weakens wheelie restrictions, making wheelies easier to perform and supporting long-duration wheelie stunts.
4. BIT (Brake Intervention Ratio): Adjusts front-rear pitch correction intensity during braking and deceleration. A higher value better suppresses nose-dive and forward leaning for stable hard braking. A lower value delivers softer braking posture, enabling dive and forward-lean freestyle maneuvers.
5. Y-Axis Sensitivity Adjustment: Controls the overall response sensitivity of the Y-axis gyroscope. Higher sensitivity enables more precise detection of front-rear vehicle posture and faster pitch correction response. Lower sensitivity softens front-rear movement response for greater straight-line stability.

● Z轴（偏航轴：水平转向控制 / 走位稳定轴）

控制定义：管控车辆水平面转向姿态，负责直行纠偏、转向跟随、漂移回正、原地旋转稳定，决定车辆走位精准度、转向手感及轨迹稳定性。

专属可调参数：开启/关闭、正反转、GAIN、AGS、PCA

1.Z轴开关：单独控制Z轴陀螺仪功能启停。关闭后车辆无水平姿态纠偏，转向自由无限制；开启后启用水平稳定、直行矫正、转向辅助功能。

2.Z轴正反转：适配车体安装与陀螺仪方向适配，用于矫正转向姿态反向问题。若开启Z轴后车辆纠偏反向、转向姿态错乱，可切换正反转参数恢复正常逻辑。

3.GAIN（陀螺仪敏感度）：Z轴整体姿态灵敏度。数值越高，车辆对水平偏移、转向动作感知越敏锐，纠偏、回正速度越快；数值越低，转向手感更慵懒、顺滑，适合慢速平稳行驶。

4.AGS（陀螺仪阻尼）：控制Z轴姿态修正的阻尼力度。阻尼越大，转向修正越稳重、走位不飘、抑制多余晃动；阻尼越小，转向灵活度越高，甩尾、连续转圈更流畅。

5.PCA（手轮介入比）：控制用户手动转向操作与陀螺仪自动纠偏的介入比例。数值越高，系统自动纠偏占比越大，车辆直行更准、不易跑偏；数值越低，手动转向权限更高，更贴合人为操控意图，适合漂移、花式转向特技。

● Z-Axis (Yaw Axis: Horizontal Steering Control / Trajectory Stability Axis)

Control Definition: Governs the vehicle's horizontal-plane steering posture. It is responsible for straight-line deviation correction, steering follow-up, drift self-centering, and stationary spin stability, determining the vehicle's trajectory accuracy, steering feel and path stability.

Exclusive Adjustable Parameters: On/Off, Reverse, GAIN, AGS, PCA

1. Z-Axis Switch: Independently enables or disables the Z-axis gyroscope function. When disabled, the vehicle has no horizontal posture correction with unrestricted steering freedom. When enabled, horizontal stabilization, straight-line correction and steering assist functions are activated.

2. Z-Axis Reverse: Adapts to vehicle body mounting and gyroscope orientation, used to correct reversed steering posture issues. If deviation correction is reversed or steering posture malfunctions after enabling the Z-axis, toggle this parameter to restore normal logic.

3. GAIN (Gyroscope Sensitivity): Overall posture sensitivity of the Z-axis. A higher value enables sharper detection of horizontal deviation and steering movement, with faster correction and self-centering. A lower value delivers softer and smoother steering feel, suitable for low-speed stable driving.

4. AGS (Gyroscope Damping): Controls the damping intensity of Z-axis posture correction. Higher damping provides steadier steering correction, stable trajectory and suppressed unwanted shaking. Lower damping improves steering agility for smoother tail slides and continuous spinning.

5. PCA (Steering Wheel Intervention Ratio): Adjusts the intervention ratio between manual steering input and automatic gyroscope correction. A higher value increases the proportion of automatic system correction for more precise straight-line driving and reduced deviation. A lower value grants greater manual steering authority to better match user-intended control, ideal for drifting and freestyle steering stunts.



6.3.2 重置自定义参数 Reset Custom Parameters

点击顶部“重置”按钮，将自定义参数重置为模式的默认参数。
Click the "重置" button at the top to restore custom parameters to the default values of the mode.

重置

“重置”按钮
“Reset” Button

8. AI智能语音控制 AI Intelligent Voice Control

8.1 功能简介 Function Overview

内置AI智能语音控制系统，支持精准指令与模糊语义指令双重识别模式，可通过语音快捷操控车辆基础功能与特技功能。系统具备高适配性语音识别能力，无需严格固定口令，用户口语化模糊指令亦可精准识别执行，大幅提升操控便捷性与游玩趣味性，适配日常休闲游玩、花式特技操作等多种使用场景。

The APP integrates a built-in AI intelligent voice control system, supporting dual recognition modes for precise commands and vague semantic instructions. It allows quick voice-activated control of the vehicle's basic and stunt functions. Featuring highly adaptable voice recognition technology, the system does not require rigid fixed voice commands; colloquial and ambiguous user instructions can also be accurately recognized and executed. This significantly improves operation convenience and entertainment experience, fitting multiple scenarios including daily casual play and fancy stunt maneuvers.

8.2 如何使用？ How to use?

具体操作如下：
点击"AI智能语音按钮"启动语音控制，说出指令后，再次点击“AI智能语音”按钮，等待识别，即可完成对应指令。

Operations as follows:
Tap the AI Voice Control button to activate voice function. Speak your command, tap the button again and wait for recognition to execute the corresponding function.



“智能语音”按钮
“Intelligent Voice” button

8.3 指令使用说明 Command Instructions

支持口语化模糊语音指令，无需严格使用标准句式，只需说出核心关键词，系统即可识别并执行对应操作，适配日常口语习惯，操作更便捷。

It supports colloquial and vague voice commands. You don't have to follow standard sentence structures. Simply speak the core keywords, and the system will recognize and execute corresponding operations. Designed to match daily speaking habits, it delivers simpler and more convenient control.

指令举例说明：

功能	指令
前后灯	打开前后灯，关闭前后灯，前后灯开，前后灯关
高/低速切换	切换到低速，切换到高速
底盘灯光	打开底盘灯，打开底盘灯，底盘灯开启，底盘灯关闭转向
转向中位微调	转向中位微调调到10，中位微调调到10，中位微调设置到10
A-ESP	A-ESP设置到10
通道行程（CH1）	通道行程Ch1设置到10，CH1设置到10
通道行程（CH2）	通道行程Ch2设置到10，CH2设置到10



AI智能语音控制目前暂只支持中文，后期会增加英文语音控制，敬请期待。
The AI intelligent voice control currently only supports Chinese. English voice control will be added in future updates. Stay tuned.

7. APP、固件版本检测与更新 APP & Firmware Version Detection and Update

在“特技抬头车”首页，点击右上角“❗”图标，进入“关于软件”页面。在下方可查看当前的软件版本和车辆固件版本，点击“检查更新”按钮，对APP和固件分别检测是否有新版本。若有新版本，则对其进行升级更新。

The home page of the Stunt Wheelie Car, click the icon “❗” in the upper-right corner to enter the “About Software” page. You can view the current software version and vehicle firmware version below. Click the “Check for Updates” button to detect whether new versions are available for the APP and firmware respectively. If new versions exist, perform the upgrade and update.



—————> New Version Detection for APP

—————> Vehicle Firmware New Version Detection



注意
CAUTION

升级固件时，须确保车辆和遥控器的电量在80%以上，并且保持特技车、遥控器与手机三者稳定连接，避免升级中断，出现固件错误。
Before firmware upgrade, ensure the battery levels of the vehicle and remote controller are above 80%. Keep a stable connection among the stunt car, remote controller and mobile phone throughout the process to prevent upgrade interruption and firmware malfunctions.

8. 查看与下载说明书 View and Download Manual

在“特技抬头车”首页，点击右上角“❗”图标，进入“关于软件”页面。在页面下方点击“查看”或“下载”，获取说明书。
The home page of the Stunt Wheelie Car, click the icon “❗” in the upper-right corner to enter the “About Software” page. Click “View” or “Download” at the bottom of the page to obtain the user manual.



FCC Warning

This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

Any Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.

Note: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

* RF warning for Portable device:

The device has been evaluated to meet general RF exposure requirement. The device can be used in portable exposure condition without restriction.



SG-1805(A)



SG-1805(A)



SG-1805(B)



SG-1805(B)



JC1801



X801



X801-A



X2201-B1



X2201-B2



X2201-G1



X2201-G2



X2201-M1



X2201-M2



X2201-F1



X2201-F2