

HEARING AID COMPATIBILITY

Applicant Name:
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Gyeonggi-do 16677, Korea

Date of Testing:
12/20/2021
Test Site/Location:
PCTEST, Columbia, MD, USA
Test Report Serial No.:
1M2203290036-01.A3L
Date of Issue:
3/29/2022

FCC ID: A3LSMS908U

APPLICANT: SAMSUNG ELECTRONICS CO., LTD.

Scope of Test: RF Emissions Testing
Application Type: Class II Permissive Change
FCC Rule Part(s): CFR §20.19(b)
HAC Standard: ANSI C63.19-2011
285076 D01 HAC Guidance v05
285076 D02 T-Coil testing for CMRS IP v03
DUT Type: Portable Handset
Model: SM-S908U
Additional Model(s): SM-S908U1
Test Device Serial No.: Pre-Production Sample [S/N: 1244M]
Class II Permissive Change(s): See FCC Change Document

C63.19-2011 HAC Category: M3 (RF EMISSIONS CATEGORY, NR TDD Only)

This report and category pertains only to NR TDD n38 and n41 modes supported by this wireless portable device. The overall category rating of the device is determined by the lowest rating obtained over all air interfaces supported by the device. This wireless portable device has been shown to be hearing-aid compatible under the above rated category, specified in ANSI/IEEE Std. C63.19-2011 and has been tested in accordance with the specified measurement procedures. Hearing-Aid Compatibility is based on the assumption that all production units will be designed electrically identical to the device tested in this report. Test results reported herein relate only to the item(s) tested. North America bands only.

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualifications of all persons taking them.


Randy Ortanez
President



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1. INTRODUCTION

On July 10, 2003, the Federal Communications Commission (FCC) adopted new rules requiring wireless manufacturers and service providers to provide digital wireless phones that are compatible with hearing aids. The FCC has modified the exemption for wireless phones under the Hearing Aid Compatibility Act of 1998 (HAC Act) in WT Docket 01-309 RM-8658¹ to extend the benefits of wireless telecommunications to individuals with hearing disabilities. These benefits encompass business, social and emergency communications, which increase the value of the wireless network for everyone. An estimated more than 10% of the population in the United States show signs of hearing impairment and of that fraction, almost 80% use hearing aids. Approximately 500 million people worldwide suffer from hearing loss.

Compatibility Tests Involved:

The standard calls for wireless communications devices to be measured for:

- RF Electric-field emissions
- T-coil mode, magnetic-signal strength in the audio band
- T-coil mode, magnetic-signal frequency response through the audio band
- T-coil mode, magnetic-signal and noise articulation index

The hearing aid must be measured for:

- RF immunity in microphone mode
- RF immunity in T-coil mode

In the following tests and results, this report includes the evaluation for a wireless communications device.

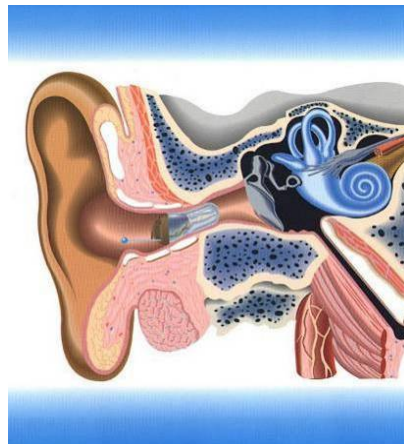


Figure 1-1 Hearing Aid *in-vitu*

¹ FCC Rule & Order, WT Docket 01-309 RM-8658

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2. DUT DESCRIPTION



FCC ID:	A3LSMS908U
Manufacturer:	Samsung Electronics Co., Ltd. 129, Samsung-ro, Maetan dong, Yeongtong-gu, Suwon-si Gyeonggi-do 16677, Korea
Model:	SM-S908U
Additional Model(s):	SM-S908U1
Serial Number:	1244M
Antenna Configurations:	Internal Antenna
DUT Type:	Portable Handset

I. Power Reduction for Licensed Modes

This device uses an independent fixed level power reduction mechanism for NR Bands n41/n38 during voice or VoIP held to ear scenarios. Reduced powers were used to evaluate for low-power exemption in Section 9.II for these modes. Detailed descriptions of the power reduction mechanism are included in the operational description.

II. NR Band Selection

This device supports NR capabilities with overlapping transmission frequency ranges. When the supported frequency range of an NR band falls completely within an NR band with a larger transmission frequency range, both NR bands have the same target power (or the band with the larger transmission frequency range has a higher target power), and both NR bands share the same transmission path and signal characteristics, hearing-aid compatibility compliance was only assessed for the band with the larger transmission frequency range.

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Table 2-1
A3LSMS908U HAC Air Interfaces

Air-Interface	Band (MHz)	Type Transport	HAC Tested	Simultaneous But Not Tested	Name of Voice Service	
GSM	850	VO	No ¹	Yes: WIFI or BT	CMRS Voice	
	1900					
	GPRS/EDGE	VD	No ¹	Yes: WIFI or BT	Google Duo	
UMTS	850	VD	No ¹	Yes: WIFI or BT	CMRS Voice	
	1700					
	1900					
	HSPA	VD	No ¹	Yes: WIFI or BT	Google Duo	
LTE (FDD)	680 (B71)	VD	No ¹	Yes: NR, WIFI or BT	VoLTE, Google Duo	
	700 (B12)					
	780 (B13)					
	790 (B14)					
	850 (B5)					
	850 (B26)					
	1700 (B4)					
	1700 (B66)					
	1900 (B2)					
	1900 (B25)					
	2300 (B30)					
	2500 (B7)					
LTE (TDD)	2600 (B38)	VD	No ¹	Yes: NR, WIFI or BT	VoLTE, Google Duo	
	2600 (B41)					
	3600 (B48)					
NR (FDD)	680 (n71)	VD	No ¹	Yes: LTE, WIFI or BT	VoNR, Google Duo	
	700 (n12)					
	850 (n5)					
	1700 (n66)					
	1900 (n2)					
	1900 (n25)					
	2300 (n30)					
	2500 (n7)					
NR (TDD)	2600 (n38)	VD	Yes	Yes: LTE, WIFI or BT	VoNR, Google Duo	
	2600 (n41)		Yes			
	3500 (n77, DoD)		No ¹			Google Duo
	3700 (n77)					
	26000 (n258)					
	28000 (n261)					
	39000 (n260)					
WIFI	2450	VD	No ¹	Yes: GSM, UMTS, LTE, or NR	VoWIFI, Google Duo	
	5200 (U-NII 1)					
	5300 (U-NII 2A)					
	5500 (U-NII 2C)					
	5800 (U-NII 3)					
	5900 (U-NII 4)					
	6175 (U-NII 5)					
	6475 (U-NII 6)					
	6700 (U-NII 7)					
	7000 (U-NII 8)					
BT	2450	DT	No	Yes: GSM, UMTS, LTE, or NR	N/A	
Type Transport VO = Voice Only DT = Digital Data - Not intended for Voice Services VD = CMRS and/or IP Voice over Data Transport			Notes: 1. This report pertains only to NR n38, n41, and n48 modes. For full data, please refer to the original test report (S/N: 1M2109090102-27-R1.A3L)			

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3. ANSI/IEEE C63.19 PERFORMANCE CATEGORIES

I. RF EMISSIONS

The ANSI Standard presents performance requirements for acceptable interoperability of hearing aids with wireless communications devices. When these parameters are met, a hearing aid operates acceptably in close proximity to a wireless communications device.

Category	Telephone RF Parameters
Near field Category	E-field emissions CW dB(V/m)
f < 960 MHz	
M1	50 to 55
M2	45 to 50
M3	40 to 45
M4	< 40
f > 960 MHz	
M1	40 to 45
M2	35 to 40
M3	30 to 35
M4	< 30
Table 3-1 WD near-field categories as defined in ANSI C63.19-2011	

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4. SYSTEM SPECIFICATIONS

EF3DV3 E-Field Probe Description

Construction:	One dipole parallel, two dipoles normal to probe axis Built-in shielding against static charges
Calibration:	In air from 30 MHz to 6.0 GHz (absolute accuracy $\pm 5.1\%$, $k=2$)
Frequency:	30 MHz to > 6 GHz; Linearity: ± 0.2 dB (30 MHz to 6 GHz)
Directivity	± 0.2 dB in air (rotation around probe axis) ± 0.4 dB in air (rotation normal to probe axis)
Dynamic Range	2 V/m to > 1000 V/m (M3 or better device readings fall well below diode compression point)
Linearity:	± 0.2 dB
Dimensions	Overall length: 337 mm (Tip: 20 mm) Tip diameter: 4.0 mm (Body: 12 mm) Distance from probe tip to dipole centers: 1.5 mm

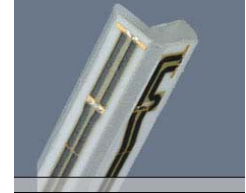
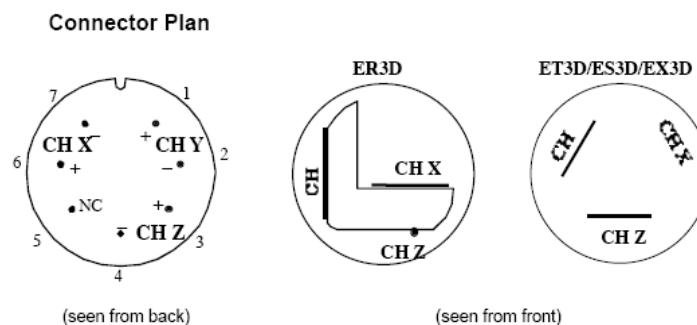


Figure 4-1
E-field Free-space
Probe

Probe Tip Description

HAC field measurements take place in the close near field with high gradients. Increasing the measuring distance from the source will generally decrease the measured field values (in case of the validation dipole approx. 10% per mm).

The electric field probes have an irregular internal geometry because it is physically not possible to have the 3 orthogonal sensors situated with the same center. The effect of the different sensor centers is accounted for in the HAC uncertainty budget ("sensor displacement").



The antistatic shielding inside the probe is connected to the probe connector case.

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Instrumentation Chain

Equation 1

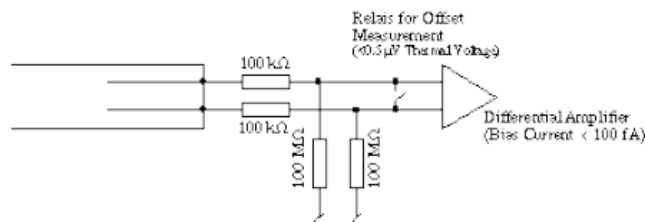
Conversion of Connector Voltage u_i to E-Field E_i

$$E_i = \sqrt{\frac{u_i + (u_i^2 \cdot CF)/(DCP)}{Norm_i \cdot ConvF}}$$

whereby

E_i : electric field in V/m
 u_i : voltage of channel i at the connector in μV
 $Norm_i$: sensitivity of channel i in $\mu V/(V/m)^2$
 $ConvF$: enhancement factor in liquid ($ConvF=1$ for Air)
 DCP : diode compression point in μV
 CF : signal crest factor (peak power/average power)

Conditions of Calibration



Please note:

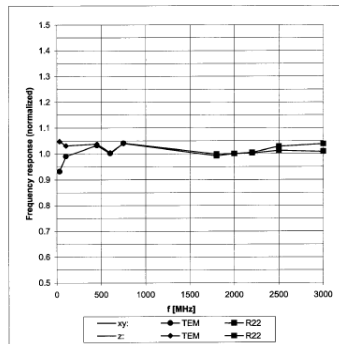
- a lower input impedance of the amplifier will result in different sensitivity factors $Norm_i$ and DCP
- larger bias currents will cause higher offset

Probe Response to Frequency

The E-field sensors have inherently a very flat frequency response. They are calibrated with a number of frequencies resulting in a common calibration factor, with the frequency behavior documented in the calibration certificate (See also below).

Frequency Response of E-Field

(TEM-Cell: if110 EXX, Waveguide R22)



Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

Figure 4-2 E-Field Probe Frequency Response

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SPEAG Robotic System

E-field measurements are performed using the DASY5 automated dosimetric assessment system. The DASY5 is made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland and consists of high precision robotics system (Staubli), robot controller, Intel CORE i7 computer, near-field probe, probe alignment sensor, and the HAC phantom. The robot is a six-axis industrial robot performing precise movements to position the probe to the location (points) of maximum electromagnetic field (EMF).



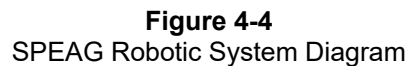
Figure 4-3
SPEAG Robotic System

System Hardware

A cell controller system contains the power supply, robot controller, teach pendant (Joystick), and a remote control used to drive the robot motors. The PC consists of the computer with operating system and RF Measurement Software DASY5 v52.8 (with HAC Extension), A/D interface card, monitor, mouse, and keyboard. The Staubli Robot is connected to the cell controller to allow software manipulation of the robot. A data acquisition electronic (DAE) circuit that performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. is connected to the Electro-optical coupler (EOC). The EOC performs the conversion from the optical into digital electric signal of the DAE and transfers data to the PC plug-in card.

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The DAE consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the PC-card is accomplished through an optical downlink for data and status information and an optical uplink for commands and clock lines. The mechanical probe mounting device includes two different sensor systems for frontal and sidewise probe contacts. They are also used for mechanical surface detection and probe collision detection. The robot uses its own controller with a built in VME-bus computer.



The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

with	V_i	= compensated signal of channel i	(i = x, y, z)
	U_i	= input signal of channel i	(i = x, y, z)
	cf	= crest factor of exciting field	(DASY parameter)
	dcp_i	= diode compression point	(DASY parameter)

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From the compensated input signals the primary field data for each channel can be evaluated:

$$E - \text{fieldprobes : } E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

with V_i = compensated signal of channel i (i = x, y, z)
 $Norm_i$ = sensor sensitivity of channel i (i = x, y, z)
 $\mu V/(V/m)^2$ for E-field Probes
 $ConvF$ = sensitivity enhancement in solution
 E_i = electric field strength of channel i in V/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

The primary field data are used to calculate the derived field units.

The measurement/integration time per point, as specified by the system manufacturer is >500ms.

The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/off switch of the power source with an integration time of 500ms and a probe response time of <5 ms. In the current implementation, DASY5 waits longer than 100ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization. The tolerances for the different systems had the worst-case of 2.6%.

Environmental Conditions

Environmental conditions such as temperature and relative humidity are monitored to ensure there are no impacts on system specifications. Proper voltage and power line frequency conditions are maintained with three phase power sources. Environmental noise and reflections are monitored through system checks.

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5. TEST PROCEDURE

I. RF EMISSIONS

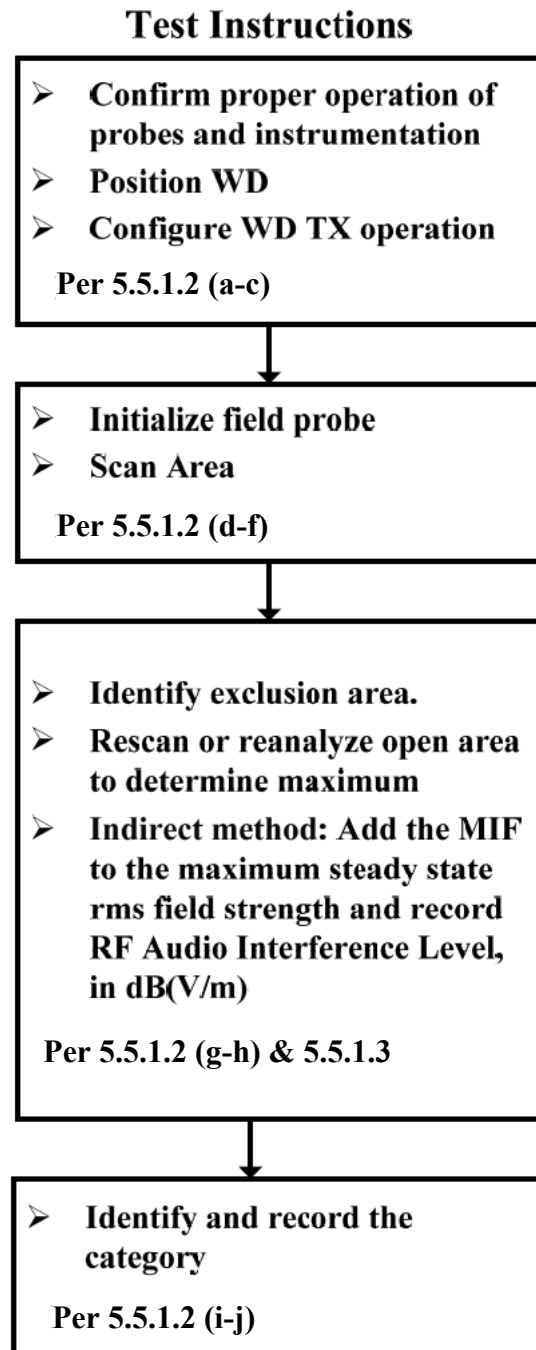


Figure 5-1 RF Emissions Flow Chart

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Test Setup

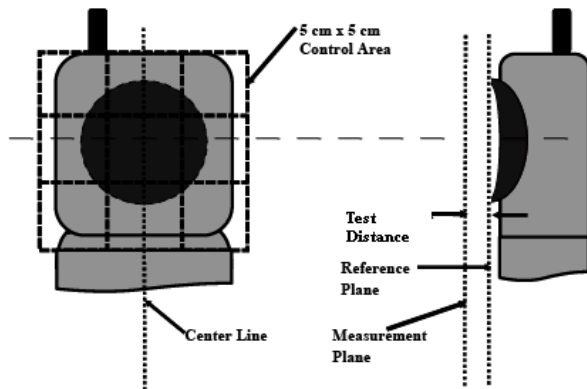


Figure 5-2

E-Field Emissions Test Setup Diagram (See Test Photographs for actual WD scan grid overlay)

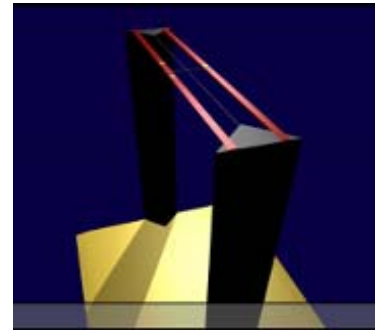


Figure 5-3
HAC Phantom

RF Emissions Test Procedure:

The following illustrate a typical RF emissions test scan over a wireless communications device:

1. Proper operation of the field probe, probe measurement system, other instrumentation, and the positioning system was confirmed.
2. WD is positioned in its intended test position, acoustic output point of the device perpendicular to the field probe.
3. The WD operation for maximum rated RF output power was configured and confirmed with the base station simulator, at the test channel and other normal operating parameters as intended for the test. The battery was ensured to be fully charged before each test.
4. The center sub-grid was centered over the center of the acoustic output (also audio band magnetic output, if applicable). The WD audio output was positioned tangent (as physically possible) to the measurement plane.
5. A surface calibration was performed before each setup change to ensure repeatable spacing and proper maintenance of the measurement plane using the HAC Phantom.
6. The measurement system measured the field strength at the reference location.
7. Measurements at 2mm or 5mm increments in the 5 x 5 cm region were performed at a distance 15 mm from the center point of the probe measurement element to the WD. Of the 9 subgrids (see Figure 5-2), 3 contiguous subgrids may be excluded from the measurement in order to account for localized areas of higher field intensities. The center subgrid containing the acoustic output or audio band magnetic output may not be excluded. A 360° rotation about the azimuth axis at the maximum interpolated position was measured. For the worst-case condition, the peak reading from this rotation was used in re-evaluating the HAC category.
8. The system performed a drift evaluation by measuring the field at the reference location. If the power drift deviated by more than 5%, the HAC test and drift measurements were repeated.

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6. SYSTEM CHECK

I. System Check Parameters

The input signal was an un-modulated continuous wave. The following points were taken into consideration in performing this check:

- Average Input Power $P = 100\text{mW RMS}$ (20dBm RMS) after adjustment for return loss
- The test fixture must meet the 2 wavelength separation criterion
- The proper measurement of the 15 mm probe to dipole separation, which is measured from top surface of the dipole to the calibration reference point of the sensor, defined by the probe manufacturer is shown in the following diagram:

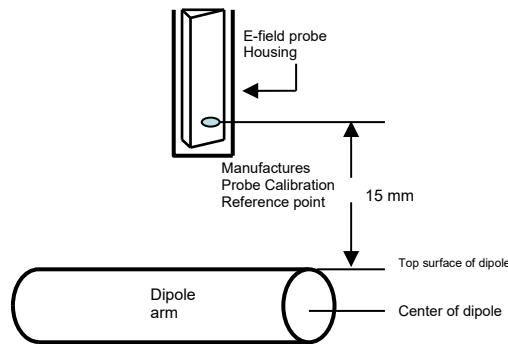


Figure 6-1
Separation Distance from Dipole to Field Probe

RF power was recorded using both an average reading meter and a peak reading meter. Readings of the probe are provided by the measurement system.

To assure proper operation of the near-field measurement probe the input power to the dipole shall be commensurate with the full rated output power of the wireless device [e.g. - for a cellular phone wireless device the average peak antenna input power will be on the order of 100mW (20dBm) RMS] after adjustment for any mismatch.

II. Validation Procedure

A dipole antenna meeting the requirements given in C63.19 was placed in the position normally occupied by the WD.

The length of the dipole was scanned, and the average peak value was recorded.

Measurement of CW

Using the near-field measurement system, scan the antenna over the radiating dipole and record the greatest field reading observed. Due to the nature of E-fields about free-space dipoles, the two E-field peaks measured over the dipole are averaged to compensate for non-parallelity of the setup (see manufacturer method on dipole calibration certificates, page 2). Field strength measurements shall be made only when the probe is stationary.

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RF power was recorded using both an average and a peak power reading meter.

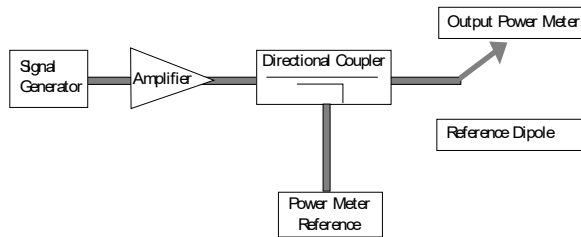


Figure 6-2

Setup for Desired Output Power to Dipole

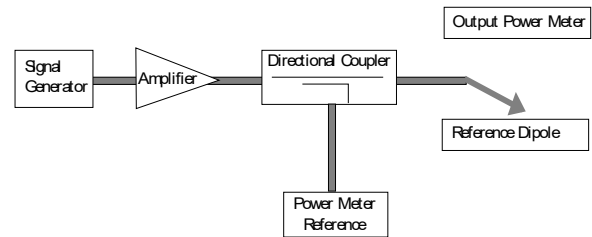


Figure 6-3

Setup to Dipole

Using this setup configuration, the signal generator was adjusted for the desired output power (100mW) at a specified frequency. The reference power from the coupled port of the directional coupler is recorded. Next, the output cable is connected to the reference dipole, as shown in Figure 6-3.

The input signal level was adjusted until the reference power from the coupled port of the directional coupler was the same as previously recorded, to compensate for the impedance mismatch between the output cable and the reference dipole. To assure proper operation of the near-field measurement probe the input power to the reference dipole was verified to the full rated output power of the wireless device. The dipole was secured in a holder in a manner to meet the 20 dB reflection. The near-field measurement probe was positioned over the dipole. The antenna was scanned over the appropriate sized area to cover the dipole from end to end. SPEAG uses 2D interpolation algorithms between the measured points. Please see below two dimensional plots showing that the interpolated values interpolate smoothly between 5mm steps for a free-space RF dipole:

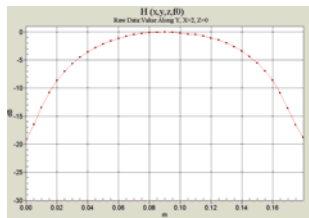


Figure 6-4

2-D Raw Data from scan along dipole axis

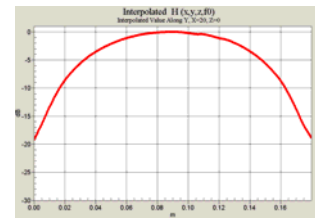


Figure 6-5

2-D Interpolated points from scan along dipole axis

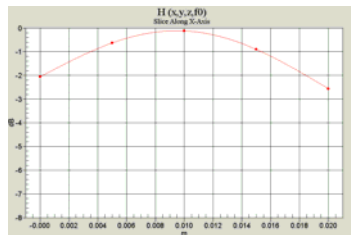


Figure 6-6

2-D Raw Data from scan along transverse axis

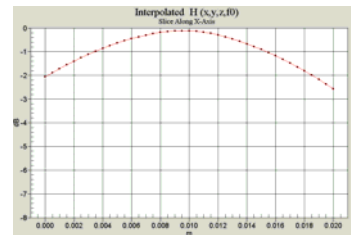


Figure 6-7

2-D Interpolated points from scan along transverse axis

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III. System Check Results

Table 6-1
RFE System Verification Results

Date	Frequency (MHz)	Probe S/N	DAE S/N	Dipole S/N	Input Power (dBm)	E-field Result (V/m)	Target Field (V/m)	% Deviation
12/20/2021	2600	4035	1530	1012	20.0	87.3	86.5	0.9%

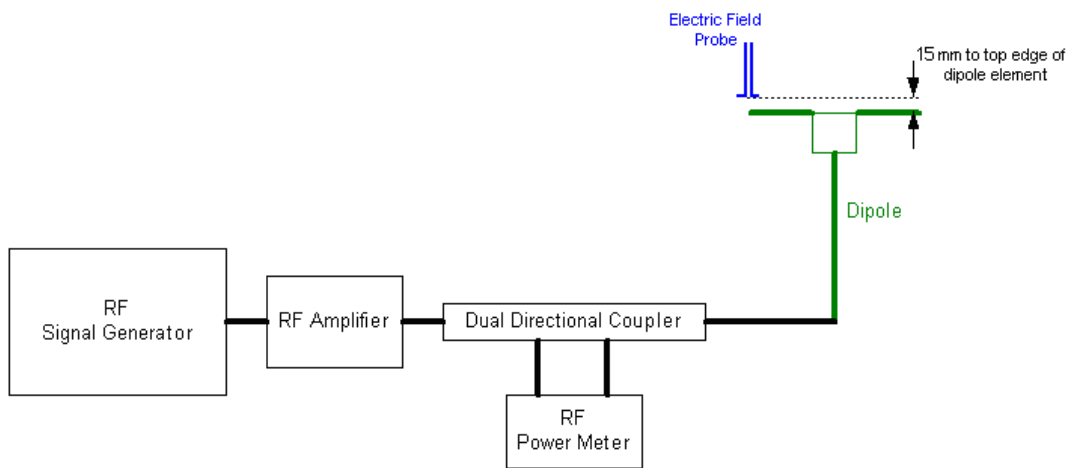


Figure 6-8
System Check Setup

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7. MODULATION INTERFERENCE FACTOR

I. Measuring Modulation Interference Factors

For any specific fixed and repeatable modulated signal, a modulation interference factor (MIF, expressed in dB) may be determined that relates its interference potential to its steady-state RMS signal level or average power level. This factor is a function only of the audio-frequency amplitude modulation characteristics of the signal and is the same for field-strength and conducted power measurements. The MIF is valid only for a specific repeatable audio-frequency amplitude modulation characteristic; any change in modulation characteristic requires determination and application of a new MIF.

The MIF may be determined using a radiated RF field or a conducted RF signal:

- Using RF illumination or conducted coupling, apply the specific modulated signal in question to the measurement system at a level within its confirmed operating dynamic range.
- Measure the steady-state RMS level at the output of the fast probe or sensor.
- Measure the steady-state average level at the weighting output.
- Without changing the square-law detector or weighting system, and using RF illumination or conducted coupling, substitute for the specific modulated signal a 1 kHz, 80% amplitude modulated carrier at the same frequency and adjust its strength until the level at the weighting output equals the step c) measurement.
- Without changing the carrier level from step d), remove the 1 kHz modulation and again measure the steady-state RMS level indicated at the output of the fast probe or sensor.
- The MIF for the specific modulation characteristic is provided by the ratio of the step e) measurement to the step b) measurement, expressed in dB ($20 \times \log[(\text{step e})/(\text{step b})]$).

The following procedure was used to measure the MIF using the SPEAG Audio Interference Analyzer (AIA), Type No: SE UMS 170 CB, Serial No.: 1010:

- The device was placed into a simulated call using a base station simulator or set to transmit using test software for a given mode.
- The device was then set to continuously transmit at maximum power.
- Using a coupler if needed, the device output signal was connected to the RF In port of the AIA, which was connected to a desktop computer. Alternatively, a radiated RF signal may be used with the AIA's built-in antenna.
- The MIF measurement procedure in the DASY software was run, and the resulting MIF value was recorded.
- Steps 1-4 were repeated for all CMRS air interfaces, frequency bands, and modulations.

The modulation interference factors obtained were applied to readings taken of the actual wireless device in order to obtain an accurate audio interference level reading using the formula:

$$\text{Audio Interference Level [dB(V/m)]} = 20 * \log[\text{Raw Field Value (V/m)}] + \text{MIF (dB)}$$

Because the MIF value is output power independent, MIF values for a given mode should be constant across all devices; however, per C63.19-2011 §D.7, MIF values should be measured for each device being evaluated. The applicable modes for this device have been investigated in this section of the report.

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II. MIF Measurement Block Diagrams

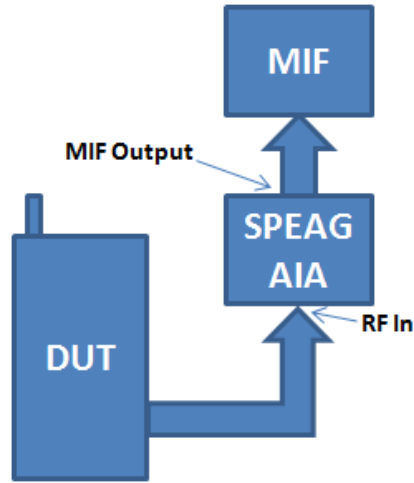


Figure 7-1
MIF Measurement Setup

III. Measured Modulation Interference Factors:

Table 7-1
NR TDD n41 Modulation Interference Factors¹

NR Band	Frequency [MHz]	Channel	Bandwidth [MHz]	Waveform	Modulation	RB Size	RB Offset	MIF [dB]
n41	2593.0	518598	100	DFT-s-OFDM	$\pi/2$ -BPSK	1	1	0.80
n41	2593.0	518598	100	DFT-s-OFDM	QPSK	1	1	0.83
n41	2593.0	518598	100	DFT-s-OFDM	16QAM	1	1	0.80
n41	2593.0	518598	100	DFT-s-OFDM	64QAM	1	1	0.77
n41	2593.0	518598	100	DFT-s-OFDM	256QAM	1	1	0.69
n41	2593.0	518598	100	CP-OFDM	QPSK	1	1	0.72
n41	2593.0	518598	100	CP-OFDM	16QAM	1	1	0.67
n41	2593.0	518598	100	CP-OFDM	64QAM	1	1	0.65
n41	2593.0	518598	100	CP-OFDM	256QAM	1	1	0.57
n41	2593.0	518598	100	DFT-s-OFDM	QPSK	1	137	0.83
n41	2593.0	518598	100	DFT-s-OFDM	QPSK	1	271	0.82
n41	2593.0	518598	100	DFT-s-OFDM	QPSK	135	0	0.79
n41	2593.0	518598	100	DFT-s-OFDM	QPSK	270	0	0.79
n41	2593.0	518598	90	DFT-s-OFDM	QPSK	1	1	0.79
n41	2593.0	518598	80	DFT-s-OFDM	QPSK	1	1	0.79
n41	2593.0	518598	70	DFT-s-OFDM	QPSK	1	1	0.77
n41	2593.0	518598	60	DFT-s-OFDM	QPSK	1	1	0.75
n41	2593.0	518598	50	DFT-s-OFDM	QPSK	1	1	0.77
n41	2593.0	518598	40	DFT-s-OFDM	QPSK	1	1	0.74
n41	2593.0	518598	30	DFT-s-OFDM	QPSK	1	1	0.76
n41	2593.0	518598	20	DFT-s-OFDM	QPSK	1	1	0.75
n41	2546.0	509202	100	DFT-s-OFDM	QPSK	1	1	0.78
n41	2569.5	513900	100	DFT-s-OFDM	QPSK	1	1	0.76
n41	2616.5	523302	100	DFT-s-OFDM	QPSK	1	1	0.75
n41	2640.0	528000	100	DFT-s-OFDM	QPSK	1	1	0.75

¹ Note: Measured MIF values may be lower than sample MIF values provided in ANSI C63.19-2011 Annex D.7 Table D.5 due to manufacturing variations for each device, however per Annex D.7, the sample MIF values of Table D.5 are not intended to substitute for measurements of actual devices under test and their respective operating modes.

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8. CONDUCTED POWER CONFIGURATIONS AND TARGETS

I. Procedures Used to Establish RF Signal for HAC Testing

The handset was configured to transmit the required air interface in a shielded chamber. Measurements were taken with a fully charged battery.

II. HAC Target Powers

All applicable modes supported by the device have their held-to-ear conducted power targets listed below and were used for the individual mode evaluations in Section 9. All conducted power targets have a tolerance of +1.0dB and -1.5dB unless otherwise noted.

III. RF Conducted Power Measurement Setup and Conditions

Output Power Verification

Maximum output power is verified for all applicable test channels for all air interfaces which require test scans. See Table 8-1 for air interface specific settings of transmit power parameters. See Table 9-1 for more information regarding which modes required test scans and had conducted power measurements taken.

Table 8-1
Power Control Parameters and Settings by Air Interface

Air Interface:	Parameter Name:	Parameter Set To:
NR	PLS	Mfr Specified

The general setup for conducted powers included in Section 10 is shown in Figure 8-1 below. The power measurement equipment could be a base station simulator, signal analyzer, or power meter depending on the applicable air interface.

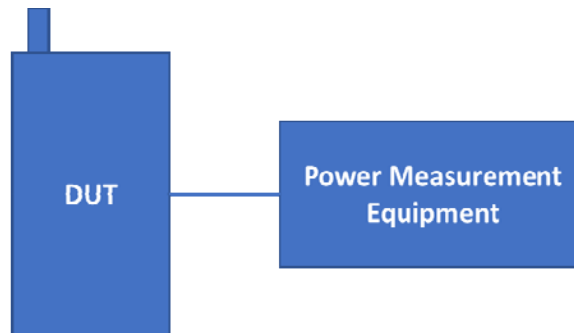


Figure 8-1
Power Measurement Setup

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IV. NR TDD Target Powers

Table 8-2
NR TDD Conducted Power Targets^{1,2}

Band	Modulated Average Output Power (in dBm)
NR Band n38	24.0
NR Band n41	24.0

¹ Note: This device utilizes independent power reduction mechanisms for the NR TDD n38/n41 transmitter in all NR TDD n38/41 bandwidths for held-to-ear scenarios.

² Note: The values listed for NR TDD n38 and n41 are using the “force peak” setting described in the operational description.

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9. JUSTIFICATION OF HELD TO EAR MODES TESTED

I. Analysis of RF Air Interface Technologies

An analysis was performed, following the guidance of §4.3 and §4.4 of the ANSI standard, of the RF air interface technologies being evaluated. The factors that will affect the RF interference potential were evaluated, and the worst-case operating modes were identified and used in the evaluation. A WD's interference potential is a function both of the WD's average near-field field strength and of the signal's audio-frequency amplitude modulation characteristics. Per §4.4, RF air interface technologies that have low power have been found to produce sufficiently low RF interference potential, so it is possible to exempt them from the product testing specified in Clause 5 of the ANSI standard. An RF air interface technology of a device is exempt from testing when its average antenna input power plus its MIF is $\leq 17\text{dBm}$ for all of its operating modes. RF air interface technologies exempted from testing in this manner are automatically assigned an M4 rating to be used in determining the overall rating for the WD.

The worst-case MIF plus the worst-case average antenna input power for all modes are investigated below to determine the testing requirements for this device.

II. Individual Mode Evaluations

Table 9-1
Max Power + MIF calculations for Low Power Exemptions

Air Interface	Maximum Average Power (dBm)	Worst Case MIF (dB)	Total (Power + MIF, dB)	C63.19 Testing Required
NR TDD - n41	18.98*	0.83	19.81	Yes

* Note: ANSI C63.19-2011 Sec. 4.4 Footnote 20 indicates the use of a long averaging time for measuring the antenna input power when using this method of exclusion. Therefore, the frame averaged power was calculated for these modes in this investigation.

III. Low-Power Exemption Conclusions

Per ANSI C63.19-2011, RF Emissions testing for this device is required for NR n41 TDD data modes.

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10. OVERALL MEASUREMENT SUMMARY

FCC ID:	A3LSMS908U
S/N:	1244M

I. E-FIELD EMISSIONS:

Table 10-1
HAC Data Summary for NR TDD n41 E-field

Mode / Band	Bandwidth (MHz)	Channel	Waveform	Mod.	RB Size	RB Offset	Scan Center	Conducted Power at BS (dBm)	Time Avg. Field (V/m)	Time Avg. Field [dB(V/m)]	MIF (dB)	Audio Interference Level [dB(V/m)]	FCC Limit (dBV/m)	FCC Margin (dB)	Result	Excl Blocks per 5.5
E-Field Emissions																
NR TDD / n41	100	509202	DFT-s-OFDM	$\pi/2$ -BPSK	1	1	Acoustic	23.82	33.94	30.61	0.78	31.39	35.00	-3.61	M3	6,8,9
	100	513900	DFT-s-OFDM	$\pi/2$ -BPSK	1	1	Acoustic	24.43	37.16	31.40	0.76	32.16	35.00	-2.84	M3	6,8,9
	100	518598	DFT-s-OFDM	$\pi/2$ -BPSK	1	1	Acoustic	23.78	37.68	31.52	0.83	32.35	35.00	-2.65	M3	6,8,9
	100	523302	DFT-s-OFDM	$\pi/2$ -BPSK	1	1	Acoustic	24.23	39.87	32.01	0.75	32.76	35.00	-2.24	M3	6,8,9
	100	528000	DFT-s-OFDM	$\pi/2$ -BPSK	1	1	Acoustic	24.09	39.65	31.96	0.75	32.71	35.00	-2.29	M3	6,8,9
	100	523302	DFT-s-OFDM	$\pi/2$ -BPSK	1	1	T-Coil	24.23	29.66	29.44	0.75	30.19	35.00	-4.81	M3	6,8,9



Figure 10-1
Sample E-field Scan Overlay
(Test Setup Photographs for actual WD overlay.)

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II. Worst-case Configuration Evaluation

Table 10-2
Peak Reading 360° Probe Rotation at Azimuth axis

Mode	Bandwidth (MHz)	Channel	Waveform	Mod.	RB Size	RB Offset	Scan Center	Time Avg. Field (V/m)	Time Avg. Field [dB(V/m)]	MIF (dB)	Audio Interference Level [dB(V/m)]	FCC Limit (dBV/m)	FCC Margin (dB)	Result	Excl Blocks per 5.5
Probe Rotation at Worst-Case															
NR TDD / n41	100	523302	DFT-s-OFDM	$\pi/2$ -BPSK	1	1	Acoustic	39.76	31.99	0.75	32.74	35.00	-2.26	M3	6,8,9

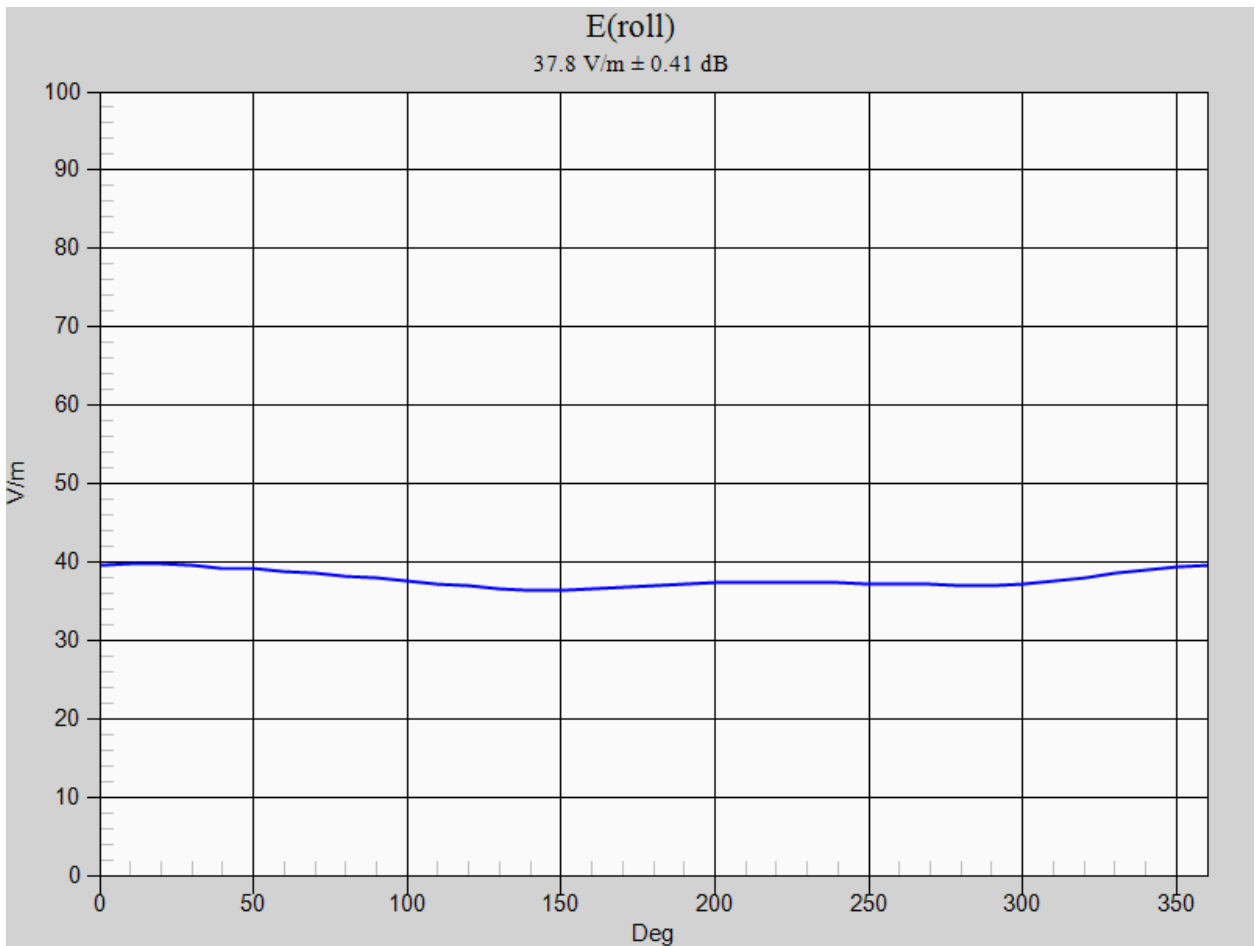


Figure 10-2
Worst-Case Probe Rotation about Azimuth axis

* Note: Locations of probe rotation (with and without exclusions) are shown in Figure 10-1 denoted by the green square markers.

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11. EQUIPMENT LIST

Table 11-1
Equipment List

Manufacturer	Model	Description	Cal Date	Cal Interval	Cal Due	Serial Number
Agilent	E4438C	ESG Vector Signal Generator	9/28/2021	Annual	9/28/2022	MY45091346
Agilent	N5182A	MXG Vector Signal Generator	7/6/2021	Annual	7/6/2022	MY48180366
Keysight Technologies	N9020A	MXA Signal Analyzer	2/24/2021	Annual	2/24/2022	MY48010233
Amplifier Research	15S1G6	Amplifier	N/A	CBT*	N/A	433978
Anritsu	MA2411B	Pulse Power Sensor	3/8/2021	Annual	3/8/2022	1339007
Anritsu	MA2411B	Pulse Power Sensor	3/9/2021	Annual	3/9/2022	1207470
Anritsu	MA24106A	USB Power Sensor	8/10/2021	Annual	8/10/2022	1231538
Anritsu	MA24106A	USB Power Sensor	8/10/2021	Annual	8/10/2022	1231535
Anritsu	ML2496A	Power Meter	2/19/2021	Annual	2/19/2022	1138001
Control Company	4040	Therm./ Clock/ Humidity Monitor	3/6/2020	Biennial	3/6/2022	200170289
Mini-Circuits	NLP-1200+	Low Pass Filter DC to 1000 MHz	N/A	CBT*	N/A	N/A
Mini-Circuits	NLP-2950+	Low Pass Filter DC to 2700 MHz	N/A	CBT*	N/A	N/A
Mini-Circuits	BW-N20W5	Power Attenuator	N/A	CBT*	N/A	1226
Pasternack	PE2237-20	Bidirectional Coupler	N/A	CBT*	N/A	N/A
Seekonk	NC-100	Torque Wrench (8" lb)	8/4/2020	Biennial	8/4/2022	N/A
SPEAG	AIA	Audio Interference Analyzer	N/A	CBT*	N/A	1010
SPEAG	EF3DV3	Freespace E-field Probe	2/15/2021	Biennial	2/15/2023	4035
SPEAG	CD2600V3	Freespace 2600MHz Dipole	1/14/2021	Biennial	1/14/2023	1012
SPEAG	DAE4	Dasy Data Acquisition Electronics	1/13/2021	Annual	1/13/2022	1530

Calibration traceable to the National Institute of Standards and Technology (NIST).

***Note: CBT (Calibrated Before Testing).** Prior to testing, the measurement paths containing a cable, attenuator, coupler or filter were connected to a calibrated source (i.e. a signal generator) to determine the losses of the measurement path. The power meter offset was then adjusted to compensate for the measurement system losses. This level offset is stored within the power meter before measurements are made. This calibration verification procedure applies to the system verification and output power measurements. The calibrated reading is then taken directly from the power meter after compensation of the losses for all final power measurements.

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12. MEASUREMENT UNCERTAINTY

Table 12-1
Uncertainty Estimation Table

Wireless Communications Device Near-Field Measurement Uncertainty Estimation							
Uncertainty Component	Data (dB)	Data Type	Prob. Dist.	Divisor	Ci (E)	Unc. (dB)	Notes/Comments
Measurement System							
RF System Reflections	0.50	Tolerance	N	1.00	1	0.50	* Refl. < -20 dB
Field Probe Calibration	0.21	Tolerance	N	1.00	1	0.21	
Field Probe Isotropy	0.01	Tolerance	N	1.00	1	0.01	
Field Probe Frequency Response	0.135	Tolerance	N	1.00	1	0.14	
Field Probe Linearity	0.013	Tolerance	N	1.00	1	0.01	
Modulation Interference Factor	0.20	Tolerance	R	1.73	1	0.12	Applicable for M-rating testing
Boundary Effects	0.105	Accuracy	R	1.73	1	0.06	*
Probe Positioning Accuracy	0.20	Accuracy	R	1.73	1	0.12	*
Probe Positioner	0.050	Accuracy	R	1.73	1	0.03	*
Extrapolation/Interpolation	0.045	Tolerance	R	1.73	1	0.03	*
Resolution to 2mm error	0.21	Tolerance	N	1.00	1	0.21	
System Detection Limit	0.05	Tolerance	R	1.73	1	0.03	*
Readout Electronics	0.015	Tolerance	N	1.00	1	0.02	*
Integration Time	0.11	Tolerance	R	1.73	1	0.06	*
Response Time	0.033	Tolerance	R	1.73	1	0.02	*
Phantom Thickness	0.10	Tolerance	R	1.73	1	0.06	*
System Repeatability (Field x 2=power)	0.17	Tolerance	N	1.00	1	0.17	*
Test Sample Related							
Device Positioning Vertical	0.2	Tolerance	R	1.73	1	0.12	*
Device Positioning Lateral	0.045	Tolerance	R	1.73	1	0.03	*
Device Holder and Phantom	0.1	Tolerance	R	1.73	1	0.06	*
Power Drift	0.21	Tolerance	R	1.73	1	0.12	
Combined Standard Uncertainty (k=1)						0.66	16.3%
Expanded Uncertainty [95% confidence]						1.31	32.6%
Expanded Uncertainty [95% confidence] on Field						0.66	16.3%

Notes:

1. Test equipments are calibrated according to techniques outlined in NIS81, NIS3003 and NIST Tech Note 1297. All equipments have traceability according to NIST. Measurement Uncertainties are defined in further detail in NIS 81 and NIST Tech Note 1297 and UKAS M3003.
2. * Uncertainty specifications from Schmidt & Partner Engineering AG (not site specific)

Measurement uncertainty reflects the quality and accuracy of a measured result as compared to the true value. Such statements are generally required when stating results of measurements so that it is clear to the intended audience that the results may differ when reproduced by different facilities. Measurement results vary due to the measurement uncertainty of the instrumentation, measurement technique, and test engineer. Most uncertainties are calculated using the tolerances of the instrumentation used in the measurement, the measurement setup variability, and the technique used in performing the test. While not generally included, the variability of the equipment under test also figures into the overall measurement uncertainty. Another component of the overall uncertainty is based on the variability of repeated measurements (so-called Type A uncertainty). This may mean that the Hearing Aid immunity tests may have to be repeated by taking down the test setup and resetting it up so that there are a statistically significant number of repeat measurements to identify the measurement uncertainty. By combining the repeat measurement results with that of the instrumentation chain using the technique contained in NIS 81 and NIS 3003, the overall measurement uncertainty was estimated.

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13. TEST DATA

See following Attached Pages for Test Data.

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**DUT: CD2600V3 - SN1012**

Type: CD2600V3

Serial: 1012

Communication System: CW; Frequency: 2600 MHz;

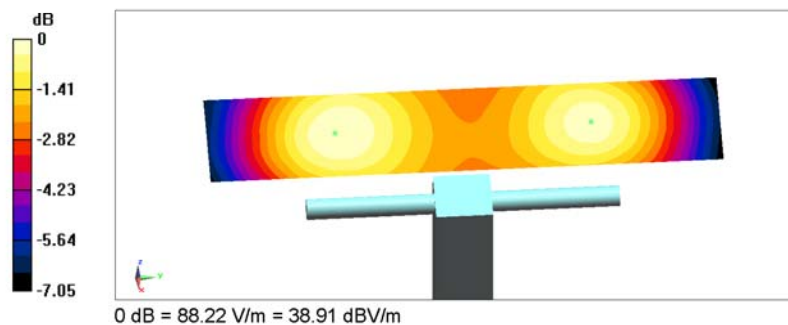
Measurement Standard: DASYS (IEEE/IEC/ANSI C63.19-2011)

DASY5 Configuration:

- Probe: EF3DV3 - SN4035; Calibrated: 2/15/2021
- Sensor-Surface: 0mm (Fix Surface)
- Electronics: DAE4 Sn1530; Calibrated: 1/13/2021
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA;
- Measurement SW: DASY52, Version 52.10 (4);

2600 MHz / 100mW HAC Dipole Validation at 15mm/Hearing Aid Compatibility Test (41x181x1):

Interpolated grid: dx=0.5000 mm, dy=0.5000 mm
 Device Reference Point: 0, 0, -6.3 mm
 Reference Value = 68.09 V/m; Power Drift = -0.15 dB
 Applied MIF = 0.00 dB
 Average value of Peak (interpolated) = 87.3 V/m



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**DUT: A3LSMS908U**

Type: Portable Handset

Serial: 1244M

Backlight off

Duty Cycle: 1:4

Communication System: NR n41; Frequency: 2616.51 MHz;

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY5 Configuration:

- Probe: EF3DV3 - SN4035; Calibrated: 2/15/2021
- Sensor-Surface: (Fix Surface)
- Electronics: DAE4 Sn1530; Calibrated: 1/13/2021
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA;
- Measurement SW: DASY52, Version 52.10 (4);

**NR n41 Mid High Channel, 100MHz, DFT-s-OFDM, $\pi/2$ -BPSK, 1RB, 1RB Offset
Hearing Aid Compatibility Test (101x101x1):**

Interpolated grid: dx=0.5000 mm, dy=0.5000 mm

Device Reference Point: 0, 0, -6.3 mm

Reference Value = 56.77 V/m; Power Drift = 0.03 dB

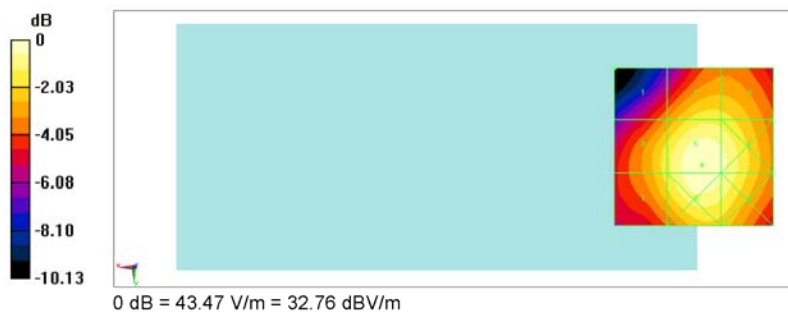
Applied MIF = 0.75 dB

RF audio interference level = 32.76 dBV/m

Emission category: M3

MIF scaled E-field

Grid 1 M4 29.45 dBV/m	Grid 2 M3 31.22 dBV/m	Grid 3 M3 31.1 dBV/m
Grid 4 M3 31.18 dBV/m	Grid 5 M3 32.76 dBV/m	Grid 6 M3 32.34 dBV/m
Grid 7 M3 31.08 dBV/m	Grid 8 M3 32.7 dBV/m	Grid 9 M3 32.26 dBV/m



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14. CALIBRATION CERTIFICATES

The following pages include the probe calibration used to evaluate HAC for the DUT.

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Calibration Laboratory of
Schmid & Partner
Engineering AG
 Zeughausstrasse 43, 8004 Zurich, Switzerland



S Schweizerischer Kalibrierdienst
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Accreditation No.: **SCS 0108**

Client **PC Test**

Certificate No: **EF3_4035_Feb21**

CALIBRATION CERTIFICATE

Object **EF3DV3- SN:4035**

Calibration procedure(s) **QA CAL-02.v9, QA CAL-25.v7**
Calibration procedure for E-field probes optimized for close near field
evaluations in air

Calibration date: **February 15, 2021**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature $(22 \pm 3)^\circ\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	01-Apr-20 (No. 217-03100/03101)	Apr-21
Power sensor NRP-Z91	SN: 103244	01-Apr-20 (No. 217-03100)	Apr-21
Power sensor NRP-Z91	SN: 103245	01-Apr-20 (No. 217-03101)	Apr-21
Reference 20 dB Attenuator	SN: CC2552 (20x)	31-Mar-20 (No. 217-03106)	Apr-21
DAE4	SN: 789	23-Dec-20 (No. DAE4-789_Dec20)	Dec-21
Reference Probe ER3DV6	SN: 2328	05-Oct-20 (No. ER3-2328_Oct20)	Oct-21
Secondary Standards	ID	Check Date (in house)	Scheduled Check
Power meter E4419B	SN: GB41293874	06-Apr-16 (in house check Jun-20)	In house check: Jun-22
Power sensor E4412A	SN: MY41498087	06-Apr-16 (in house check Jun-20)	In house check: Jun-22
Power sensor E4412A	SN: 000110210	06-Apr-16 (in house check Jun-20)	In house check: Jun-22
RF generator HP 8648C	SN: US3642U01700	04-Aug-99 (in house check Jun-20)	In house check: Jun-22
Network Analyzer E8358A	SN: US41080477	31-Mar-14 (in house check Oct-20)	In house check: Oct-21

Calibrated by: **Michael Weber** **Laboratory Technician** *[Signature]*

Approved by: **Katja Pokovic** **Technical Manager** *[Signature]*

Issued: February 16, 2021

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Certificate No: EF3_4035_Feb21

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FCC ID: A3LSMS908U	PCTEST Proud to be part of	HAC (RF EMISSIONS) TEST REPORT		Approved by: Quality Manager
Filename: 1M2203290036-01.A3L	Test Dates: 12/20/2021	DUT Type: Portable Handset		Page 30 of 48

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6/22/2020

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Accreditation No.: **SCS 0108**

Glossary:

$NORM_{x,y,z}$	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
E_n	incident E-field orientation normal to probe axis
E_p	incident E-field orientation parallel to probe axis
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005
- CTIA Test Plan for Hearing Aid Compatibility, Rev 3.1.1, May 2017

Methods Applied and Interpretation of Parameters:

- $NORM_{x,y,z}$: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- $NORM(f)_{x,y,z} = NORM_{x,y,z} \cdot frequency_response$ (see Frequency Response Chart).
- $DCP_{x,y,z}$: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- $A_{x,y,z}$; $B_{x,y,z}$; $C_{x,y,z}$; $D_{x,y,z}$; $VR_{x,y,z}$: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the $NORM_x$ (no uncertainty required).

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DASY/EASY - Parameters of Probe: EF3DV3 - SN:4035**Basic Calibration Parameters**

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu\text{V}/(\text{V/m})^2$)	0.90	0.73	1.19	$\pm 10.1\%$
DCP (mV) ^g	96.3	101.2	98.2	

Calibration results for Frequency Response (30 MHz – 6 GHz)

Frequency MHz	Target E-Field V/m	Measured E-field (En) V/m	Deviation E-normal in %	Measured E-field (Ep) V/m	Deviation E-normal in %	Unc (k=2) %
30	77.1	77.0	-0.2%	77.2	0.1%	$\pm 5.1\%$
100	77.2	78.3	1.4%	77.8	0.7%	$\pm 5.1\%$
450	77.2	78.4	1.6%	77.9	1.0%	$\pm 5.1\%$
600	77.1	77.9	1.1%	77.4	0.5%	$\pm 5.1\%$
750	77.1	77.8	0.9%	77.3	0.3%	$\pm 5.1\%$
1800	143.1	139.0	-2.8%	139.4	-2.6%	$\pm 5.1\%$
2000	135.1	131.3	-2.7%	131.5	-2.6%	$\pm 5.1\%$
2200	127.7	123.4	-3.3%	124.5	-2.5%	$\pm 5.1\%$
2500	125.5	122.4	-2.5%	123.5	-1.6%	$\pm 5.1\%$
3000	79.4	75.6	-4.7%	76.7	-3.3%	$\pm 5.1\%$
3500	256.9	246.8	-3.9%	243.9	-4.8%	$\pm 5.1\%$
3700	251.2	240.8	-4.2%	237.9	-5.0%	$\pm 5.1\%$
5200	50.8	51.4	1.3%	51.7	1.9%	$\pm 5.1\%$
5500	47.0	46.8	-0.5%	48.2	2.7%	$\pm 5.1\%$
5800	48.8	48.6	-0.6%	47.1	-3.6%	$\pm 5.1\%$

Calibration Results for Modulation Response

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Max dev.	Unc ^E (k=2)
0	CW	X	0.0	0.0	1.0	0.00	141.8	$\pm 3.8\%$	$\pm 4.7\%$
		Y	0.0	0.0	1.0		172.6		
		Z	0.0	0.0	1.0		171.7		

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

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DASY/EASY - Parameters of Probe: EF3DV3 - SN:4035**Sensor Frequency Model Parameters**

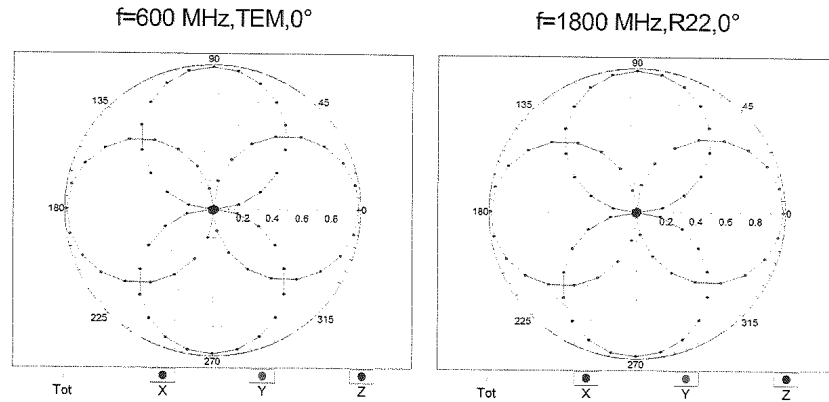
	Sensor X	Sensor Y	Sensor Z
Frequency Corr. (LF)	0.22	0.19	5.72
Frequency Corr. (HF)	2.82	2.82	2.82

Other Probe Parameters

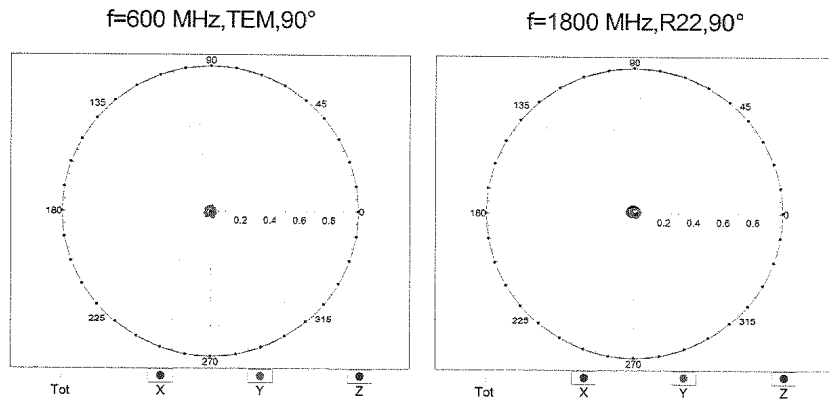
Sensor Arrangement	Rectangular
Connector Angle (°)	-126.8
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	12 mm
Tip Length	25 mm
Tip Diameter	4 mm
Probe Tip to Sensor X Calibration Point	1.5 mm
Probe Tip to Sensor Y Calibration Point	1.5 mm
Probe Tip to Sensor Z Calibration Point	1.5 mm

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Receiving Pattern (ϕ), $\theta = 0^\circ$

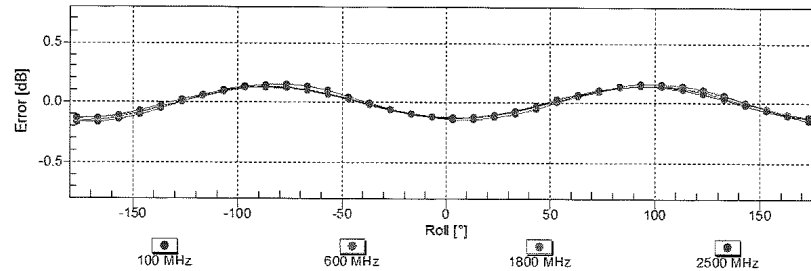


Receiving Pattern (ϕ), $\theta = 90^\circ$



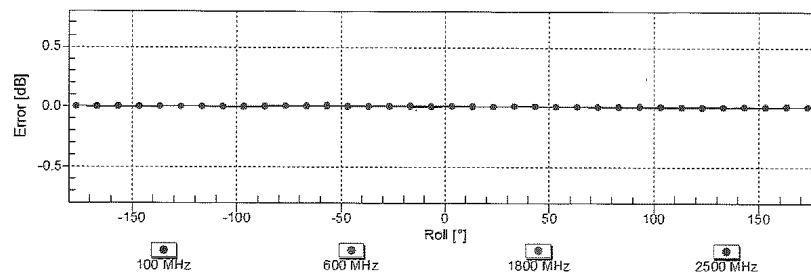
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Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

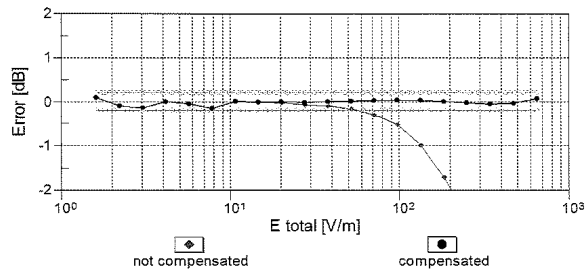
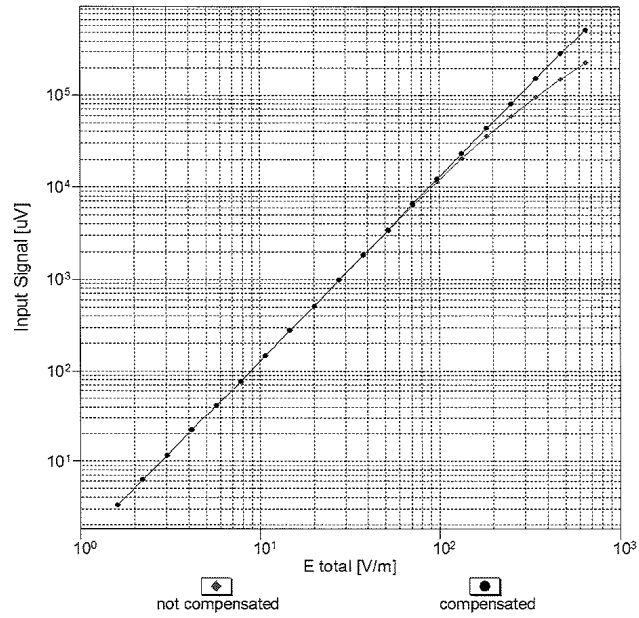
Receiving Pattern (ϕ), $\vartheta = 90^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

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Dynamic Range f(E-field) (TEM cell, f = 900 MHz)

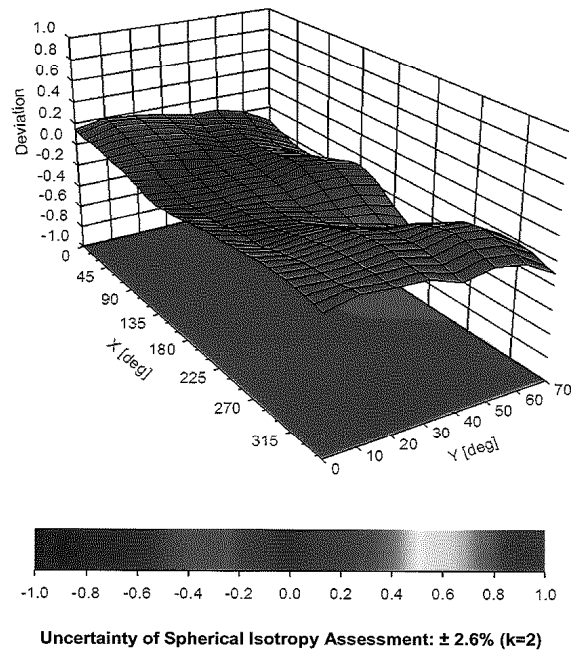


Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

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Deviation from Isotropy in Air

Error (ϕ , θ), $f = 900$ MHz



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Accreditation No.: **SCS 0108**

Client **PC Test**

Certificate No: **CD2600V3-1012_Jan21**

CALIBRATION CERTIFICATE

Object **CD2600V3 - SN: 1012**

Calibration procedure(s) **QA CAL-20.v7
 Calibration Procedure for Validation Sources in air**

Calibration date: **January 14, 2021**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	01-Apr-20 (No. 217-03100/03101)	Apr-21
Power sensor NRP-Z91	SN: 103244	01-Apr-20 (No. 217-03100)	Apr-21
Power sensor NRP-Z91	SN: 103245	01-Apr-20 (No. 217-03101)	Apr-21
Reference 20 dB Attenuator	SN: BH9394 (20k)	31-Mar-20 (No. 217-03106)	Apr-21
Type-N mismatch combination	SN: 310982 / 06327	31-Mar-20 (No. 217-03104)	Apr-21
Probe EF3DV3	SN: 4013	28-Dec-20 (No. EF3-4013_Dec20)	Dec-21
DAE4	SN: 781	23-Dec-20 (No. DAE4-781_Dec20)	Dec-21
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power meter Agilent 4419B	SN: GB42420191	09-Oct-09 (in house check Oct-20)	In house check: Oct-23
Power sensor HP E4412A	SN: US38485102	05-Jan-10 (in house check Oct-20)	In house check: Oct-23
Power sensor HP 8482A	SN: US37295597	09-Oct-09 (in house check Oct-20)	In house check: Oct-23
RF generator R&S SMT-06	SN: 837633/005	10-Jan-19 (in house check Oct-20)	In house check: Oct-23
Network Analyzer Agilent E8358A	SN: US41080477	31-Mar-14 (in house check Oct-20)	In house check: Oct-21

	Name	Function	Signature
Calibrated by:	Leif Klysner	Laboratory Technician	
Approved by:	Katja Pokovic	Technical Manager	

Issued: January 16, 2021

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Certificate No: CD2600V3-1012_Jan21

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References

- [1] ANSI-C63.19-2011
American National Standard, Methods of Measurement of Compatibility between Wireless Communications
Devices and Hearing Aids.

Methods Applied and Interpretation of Parameters:

- **Coordinate System:** y-axis is in the direction of the dipole arms. z-axis is from the basis of the antenna (mounted on the table) towards its feed point between the two dipole arms. x-axis is normal to the other axes. In coincidence with the standards [1], the measurement planes (probe sensor center) are selected to be at a distance of 15 mm above the top metal edge of the dipole arms.
- **Measurement Conditions:** Further details are available from the hardcopies at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated. The forward power to the dipole connector is set with a calibrated power meter connected and monitored with an auxiliary power meter connected to a directional coupler. While the dipole under test is connected, the forward power is adjusted to the same level.
- **Antenna Positioning:** The dipole is mounted on a HAC Test Arch phantom using the matching dipole positioner with the arms horizontal and the feeding cable coming from the floor. The measurements are performed in a shielded room with absorbers around the setup to reduce the reflections. It is verified before the mounting of the dipole under the Test Arch phantom, that its arms are perfectly in a line. It is installed on the HAC dipole positioner with its arms parallel below the dielectric reference wire and able to move elastically in vertical direction without changing its relative position to the top center of the Test Arch phantom. The vertical distance to the probe is adjusted after dipole mounting with a DASY5 Surface Check job. Before the measurement, the distance between phantom surface and probe tip is verified. The proper measurement distance is selected by choosing the matching section of the HAC Test Arch phantom with the proper device reference point (upper surface of the dipole) and the matching grid reference point (tip of the probe) considering the probe sensor offset. The vertical distance to the probe is essential for the accuracy.
- **Feed Point Impedance and Return Loss:** These parameters are measured using a Vector Network Analyzer. The impedance is specified at the SMA connector of the dipole. The influence of reflections was eliminating by applying the averaging function while moving the dipole in the air, at least 70cm away from any obstacles.
- **E-field distribution:** E field is measured in the x-y-plane with an isotropic E-field probe with 100 mW forward power to the antenna feed point. In accordance with [1], the scan area is 20mm wide, its length exceeds the dipole arm length (180 or 90mm). The sensor center is 15 mm (in z) above the metal top of the dipole arms. Two 3D maxima are available near the end of the dipole arms. Assuming the dipole arms are perfectly in one line, the average of these two maxima (in subgrid 2 and subgrid 8) is determined to compensate for any non-parallelity to the measurement plane as well as the sensor displacement. The E-field value stated as calibration value represents the maximum of the interpolated 3D-E-field, in the plane above the dipole surface.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

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Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.10.4
Phantom	HAC Test Arch	
Distance Dipole Top - Probe Center	15 mm	
Scan resolution	dx, dy = 5 mm	
Frequency	2600 MHz $\pm$ 1 MHz	
Input power drift	< 0.05 dB	

Maximum Field values at 2600 MHz

E-field 15 mm above dipole surface	condition	Interpolated maximum
Maximum measured above high end	100 mW input power	86.8 V/m = 38.77 dBV/m
Maximum measured above low end	100 mW input power	86.3 V/m = 38.72 dBV/m
Averaged maximum above arm	100 mW input power	86.5 V/m $\pm$ 12.8 % (k=2)

Appendix (Additional assessments outside the scope of SCS 0108)

Antenna Parameters

Frequency	Return Loss	Impedance
2450 MHz	20.9 dB	43.7 Ω - 5.7 j Ω
2550 MHz	32.2 dB	48.5 Ω + 1.9 j Ω
2600 MHz	35.0 dB	51.4 Ω + 1.1 j Ω
2650 MHz	31.6 dB	52.4 Ω - 1.2 j Ω
2750 MHz	22.3 dB	48.4 Ω - 7.4 j Ω

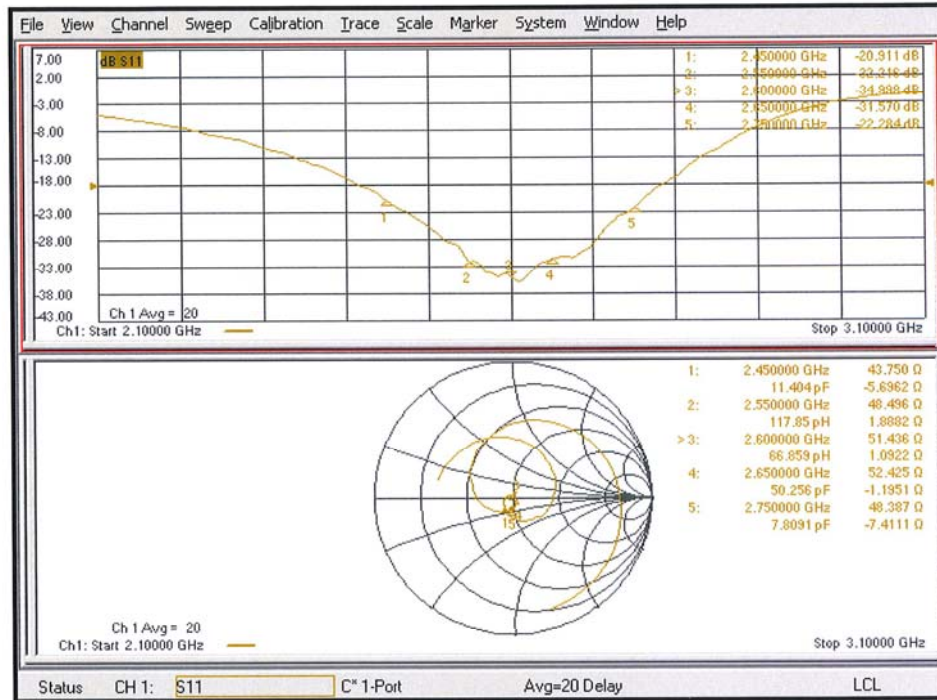
3.2 Antenna Design and Handling

The calibration dipole has a symmetric geometry with a built-in two stub matching network, which leads to the enhanced bandwidth.
The dipole is built of standard semirigid coaxial cable. The internal matching line is open ended. The antenna is therefore open for DC signals.
Do not apply force to dipole arms, as they are liable to bend. The soldered connections near the feedpoint may be damaged. After excessive mechanical stress or overheating, check the impedance characteristics to ensure that the internal matching network is not affected.

After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

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Impedance Measurement Plot



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DASY5 E-field Result

Date: 14.01.2021

Test Laboratory: SPEAG Lab2

DUT: HAC Dipole 2600 MHz; Type: CD2600V3; Serial: CD2600V3 - SN: 1012

Communication System: UID 0 - CW ; Frequency: 2600 MHz

Medium parameters used: $\sigma = 0$ S/m, $\epsilon_r = 1$; $\rho = 0$ kg/m³

Phantom section: RF Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: EF3DV3 - SN4013; ConvF(1, 1, 1) @ 2600 MHz; Calibrated: 28.12.2020
- Sensor-Surface: (Fix Surface)
- Electronics: DAE4 Sn781; Calibrated: 23.12.2020
- Phantom: HAC Test Arch with AMCC; Type: SD HAC P01 BA; Serial: 1070
- DASY52 52.10.4(1527); SEMCAD X 14.6.14(7483)

Dipole E-Field measurement @ 2600MHz/E-Scan - 2600MHz d=15mm/Hearing Aid Compatibility Test (41x181x1):

Interpolated grid: dx=0.5000 mm, dy=0.5000 mm

Device Reference Point: 0, 0, -6.3 mm

Reference Value = 67.09 V/m; Power Drift = -0.03 dB

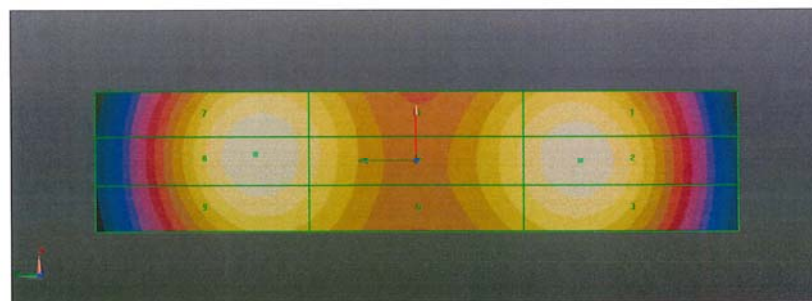
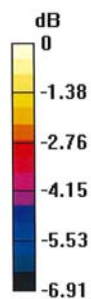
Applied MIF = 0.00 dB

RF audio interference level = 38.77 dBV/m

Emission category: M2

MIF scaled E-field

Grid 1 M2	Grid 2 M2	Grid 3 M2
38.56 dBV/m	38.72 dBV/m	38.5 dBV/m
Grid 4 M2	Grid 5 M2	Grid 6 M2
38.08 dBV/m	38.12 dBV/m	37.92 dBV/m
Grid 7 M2	Grid 8 M2	Grid 9 M2
38.69 dBV/m	38.77 dBV/m	38.5 dBV/m



0 dB = 86.78 V/m = 38.77 dBV/m

Certificate No: CD2600V3-1012_Jan21

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15. CONCLUSION

The measurements indicate that NR TDD n38, and n41 modes for the referenced wireless communications device comply with the HAC limits specified in accordance with the ANSI C63.19 Standard and FCC WT Docket No. 01-309 RM-8658. Precise laboratory measures were taken to assure repeatability of the tests. The tested device complies with the requirements in respect to all parameters specific to the test. The test results and statements relate only to the item(s) tested.

Please note that the M-rating for this equipment only represents the field interference possible against a hypothetical and typical hearing aid. The measurement system and techniques presented in this evaluation are proposed in the ANSI standard as a means of best approximating wireless device compatibility with a hearing-aid. The literature is under continual re-construction.

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16. REFERENCES

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