TEST REPORT

No.B19N01091-SAR

For

Plantronics, Inc.

Bluetooth Headset

Model Name: BF6100S

With

Hardware Version: V01

Software Version: V1.0.0.16

FCC ID: AL8-BF6100S

Issued Date: 2019-05-31

Designation Number: CN1210

Note:

The test results in this test report relate only to the devices specified in this report. This report shall not be reproduced except in full without the written approval of SAICT.

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REPORT HISTORY

Report Number	Revision	Issue Date	Description
B19N01091-SAR	Rev.0	2019-05-31	Initial creation of test report

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1 Test Laboratory

1.1 Testing Location

Company Name:	Shenzhen Academy of Information and Communications Technology
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1.2 Testing Environment

Temperature:	18°C~25 °C
Relative humidity:	30%~ 70%
Ground system resistance:	<4Ω
Ambient noise & Reflection:	< 0.012 W/kg

1.3 Project Data

Testing Start Date:	May 29, 2019
Testing End Date:	May 29, 2019

1.4 Signature

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Deputy Director of the laboratory

(Approved this test report)

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2 Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for Plantronics, Inc. Bluetooth Headset BF6100S are as follows:

Table 2.1: Highest Reported SAR for Head (1g)

Exposure Configuration	Technology Band	Highest Reported SAR 1g(W/Kg)	Equipment Class
Head (Separation Distance 0 mm)	Bluetooth 2.4G	0.02	DSS

The SAR values found for the EUT are below the maximum recommended levels of 1.6 W/Kg as averaged over any 1g tissue according to the ANSI C95.1-1992.

The EUT battery must be fully charged and checked periodically during the test to ascertain uniform power output.

The measurement together with the test system set-up is described in annex C of this test report. A detailed description of the equipment under test can be found in chapter 4 of this test report.

The highest reported SAR value is obtained at the case of **(Table 2.1),** and the values are**: 0.02 W/kg (1g).**

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3 Client Information

3.1 Applicant Information

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3.2 Manufacturer Information

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Email:	mark.lawson@plantronics.com
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Fax:	831-429-5731

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4 Equipment under Test (EUT) and Ancillary Equipment (AE)

4.1 About EUT

Description:	Bluetooth Headset
Model Name:	BF6100S
Condition of EUT as received	No obvious damage in appearance
Operating mode(s):	Bluetooth
Tested Tx Frequency:	2402 – 2480MHz (Bluetooth 2.4G)
Test device Production information:	Production unit
Device type:	Portable device
Antenna type:	Integrated antenna

4.2 Internal Identification of EUT used during the test

EUT ID*	IMEI	HW Version	SW Version
EUT1	/	V1.0	V1.0.0.16

*EUT ID: is used to identify the test sample in the lab internally.

Note: It is performed to test SAR with the EUT 1.

4.3 Internal Identification of AE used during the test

AE ID*	Description	Model	Manufacturer
AE1	/	/	/

*AE ID: is used to identify the test sample in the lab internally.

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5 Test Methodology

5.1 Applicable Limit Regulations

ANSI C95.1–1992: IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz.

It specifies the maximum exposure limit of **1.6 W/kg** as averaged over any 1 gram of tissue for portable devices being used within 20 cm of the user in the uncontrolled environment.

5.2 Applicable Measurement Standards

IEEE 1528–2013: Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Experimental Techniques.

KDB 447498 D01 General RF Exposure Guidance v06: Mobile and Portable Devices RF Exposure Procedures and Equipment Authorization Policies.

KDB 865664 D01SAR measurement 100 MHz to 6 GHz v01r04: SAR Measurement Requirements for 100 MHz to 6 GHz.

KDB 865664 D02 RF Exposure Reporting v01r02: RF Exposure Compliance Reporting and Documentation Considerations

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6 Specific Absorption Rate (SAR)

6.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

6.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ) . The equation description is as below:

$$SAR = \frac{d}{dt}(\frac{dW}{dm}) = \frac{d}{dt}(\frac{dW}{\rho dv})$$

SAR is expressed in units of Watts per kilogram (W/kg)
SAR measurement can be either related to the temperature elevation in tissue by

$$SAR = c(\frac{\delta T}{\delta t})$$

Where: C is the specific head capacity, δT is the temperature rise and δt is the exposure duration, or related to the electrical field in the tissue by

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of tissue and E is the RMS electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

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7 Tissue Simulating Liquids

7.1 Targets for tissue simulating liquid

Table 7.1: Targets for tissue simulating liquid

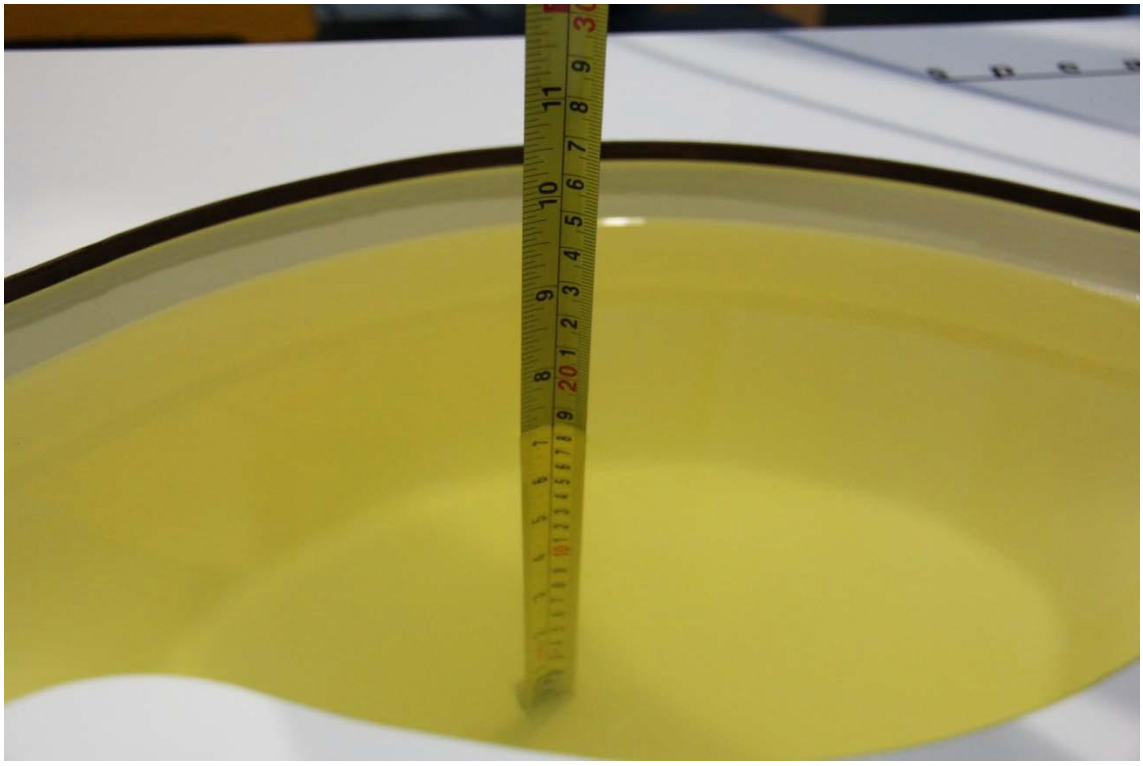
Frequency (MHz)	Liquid Type	Conductivity (σ)	± 5% Range	Permittivity (ε)	± 5% Range
2450	Head	1.80	1.71～1.89	39.20	37.2～41.2

7.2 Dielectric Performance

Table 7.2: Dielectric Performance of Tissue Simulating Liquid

Measurement Date (yyyy-mm-dd)	Type	Frequency	Conductivity σ (S/m)	Drift (%)	Permittivity ε	Drift (%)
2019-5-29	Head	2450	1.832	1.78	38.45	-1.91

Note: The liquid temperature is 22.0°C.



Picture 7-1: Liquid depth in the Flat Phantom(2450MHz)

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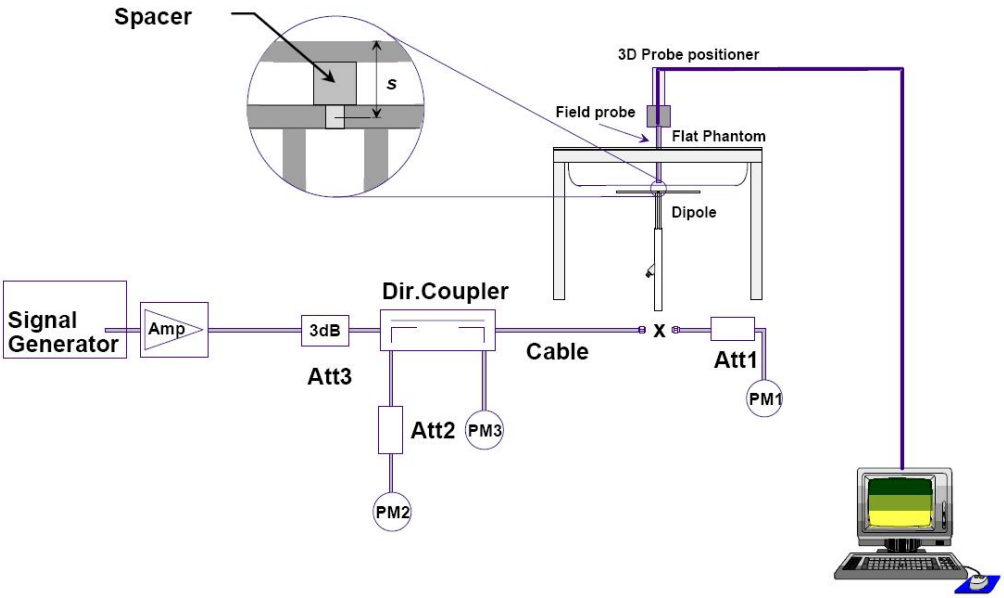
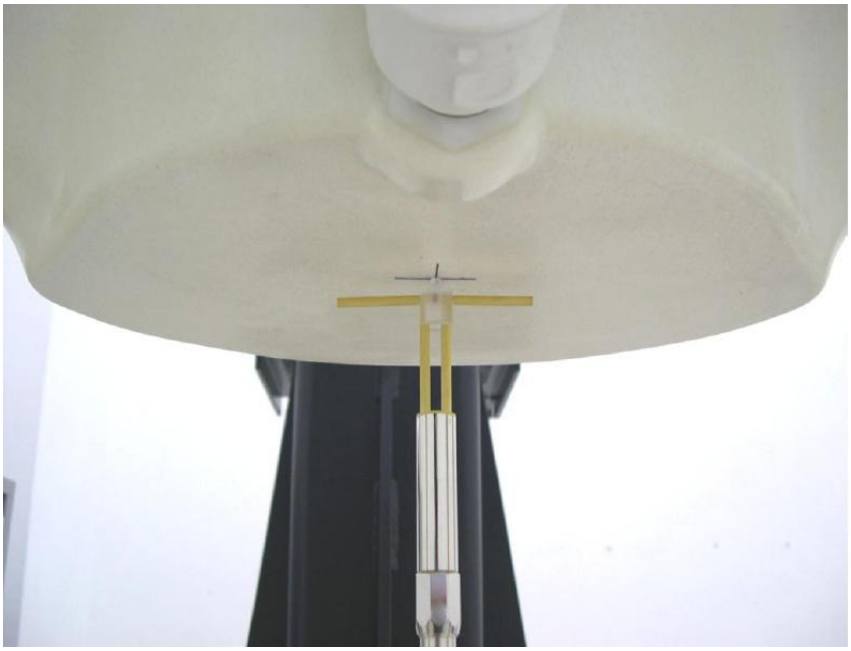
8 System verification

8.1 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave that comes from a signal generator. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:



Picture 8.1 System Setup for System Evaluation



Picture 8.2 Photo of Dipole Setup

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8.2 System Verification

SAR system verification is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device.

Table 8.1: System Verification of Head

Measurement Date (yyyy-mm-dd)	Frequency	Target value (W/kg)		Measured value (W/kg)		Deviation (%)	
		10 g Average	1 g Average	10 g Average	1 g Average	10 g Average	1 g Average
2019-5-29	2450 MHz	24.1	52.5	24.44	53.60	1.41	3.08

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9 Measurement Procedures

9.1 Tests to be performed

In order to determine the highest value of the peak spatial-average SAR of a handset, all device positions, configurations and operational modes shall be tested for each frequency band according to steps 1 to 3 below. A flowchart of the test process is shown in picture 9.1.

Step 1: The tests described in 9.2 shall be performed at the channel that is closest to the center of the transmit frequency band (f_c) for:

a) all device positions (cheek and tilt, for both left and right sides of the SAM phantom, as described in annex D),
b) all configurations for each device position in a), e.g., antenna extended and retracted, and
c) all operational modes, e.g., analogue and digital, for each device position in a) and configuration in b) in each frequency band.

If more than three frequencies need to be tested according to 11.1 (i.e., N_c > 3), then all frequencies, configurations and modes shall be tested for all of the above test conditions.

Step 2: For the condition providing highest peak spatial-average SAR determined in Step 1, perform all tests described in 9.2 at all other test frequencies, i.e., lowest and highest frequencies. In addition, for all other conditions (device position, configuration and operational mode) where the peak spatial-average SAR value determined in Step 1 is within 3 dB of the applicable SAR limit, it is recommended that all other test frequencies shall be tested as well.

Step 3: Examine all data to determine the highest value of the peak spatial-average SAR found in Steps 1 to 2.

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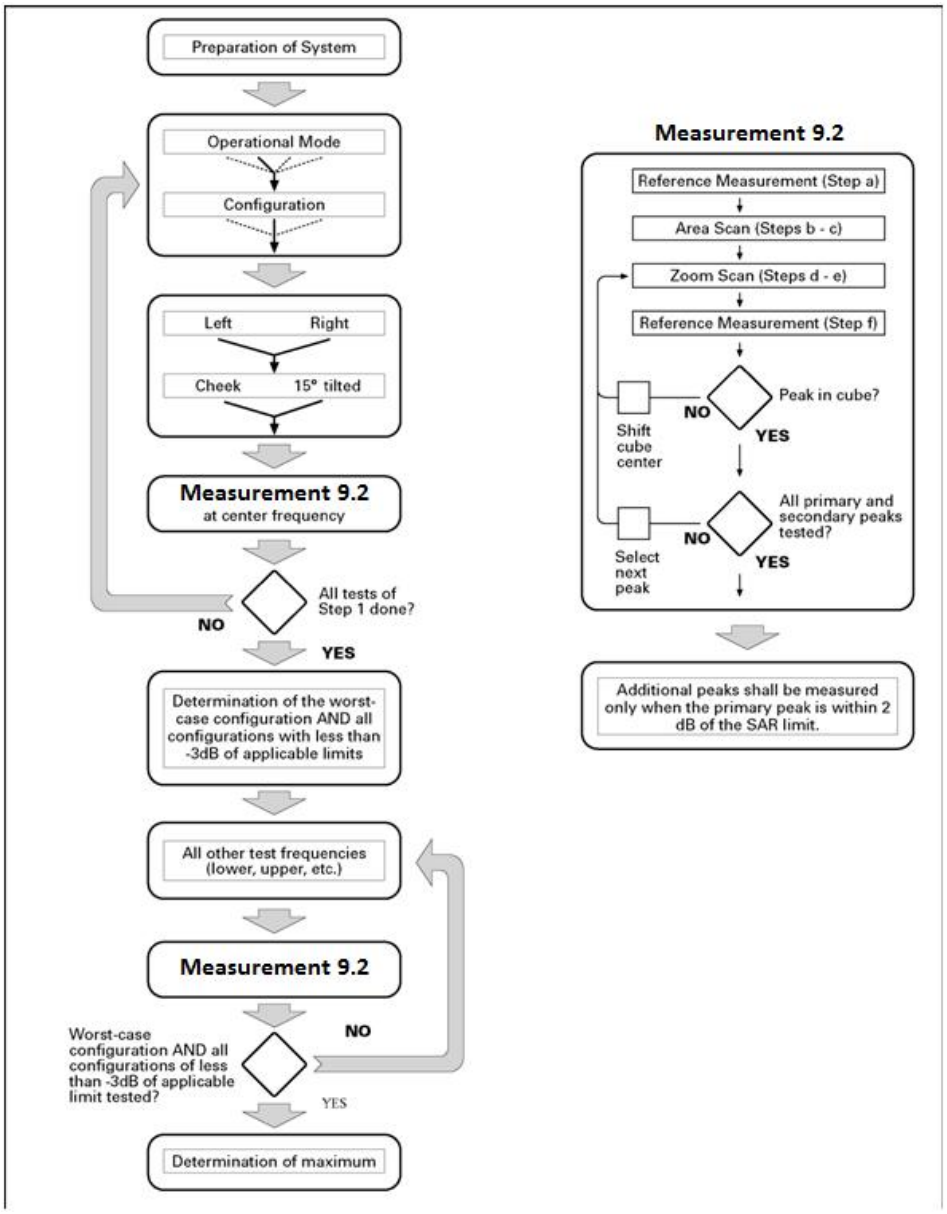

Picture 9.1 Block diagram of the tests to be performed

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9.2 General Measurement Procedure

The area and zoom scan resolutions specified in the table below must be applied to the SAR measurements and fully documented in SAR reports to qualify for TCB approval. Probe boundary effect error compensation is required for measurements with the probe tip closer than half a probe tip diameter to the phantom surface. Both the probe tip diameter and sensor offset distance must satisfy measurement protocols; to ensure probe boundary effect errors are minimized and the higher fields closest to the phantom surface can be correctly measured and extrapolated to the phantom surface for computing 1-g SAR. Tolerances of the post-processing algorithms must be verified by the test laboratory for the scan resolutions used in the SAR measurements, according to the reference distribution functions specified in IEEE Std 1528-2013. The results should be documented as part of the system validation records and may be requested to support test results when all the measurement parameters in the following table are not satisfied.

			≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface			5 ± 1 mm	½·δ·ln(2) ± 0.5 mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location			30° ± 1°	20° ± 1°
Maximum area scan spatial resolution: Δx_{Area}, Δy_{Area}			≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm
			When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	
Maximum zoom scan spatial resolution: Δx_{Zoom}, Δy_{Zoom}			≤ 2 GHz: ≤ 8 mm 2 – 3 GHz: ≤ 5 mm*	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$		≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
	graded grid	$\Delta z_{Zoom}(1)$: between 1st two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
		$\Delta z_{Zoom}(n>1)$: between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$	
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm

Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.

* When zoom scan is required and the *reported* SAR from the area scan based *1-g SAR estimation* procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.

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9.3 Bluetooth Measurement Procedures for SAR

Normal network operating configurations are not suitable for measuring the SAR of 802.11 transmitters in general. Unpredictable fluctuations in network traffic and antenna diversity conditions can introduce undesirable variations in SAR results. The SAR for these devices should be measured using chipset based test mode software to ensure that the results are consistent and reliable.

Chipset based test mode software is hardware dependent and generally varies among manufacturers. The device operating parameters established in a test mode for SAR measurements must be identical to those programmed in production units, including output power levels, amplifier gain settings and other RF performance tuning parameters. The test frequencies should correspond to actual channel frequencies defined for domestic use. SAR for devices with switched diversity should be measured with only one antenna transmitting at a time during each SAR measurement, according to a fixed modulation and data rate. The same data pattern should be used for all measurements.

9.4 Power Drift

To control the output power stability during the SAR test, DASY5 system calculates the power drift by measuring the E-field at the same location at the beginning and at the end of the measurement for each test position. These drift values can be found in Section 14 labeled as: (Power Drift [dB]). This ensures that the power drift during one measurement is within 5%.

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10 Conducted Output Power

10.1 Bluetooth Measurement result

Table 10.1: The conducted Power measurement results for Bluetooth

Bluetooth	Tune up	Averaged Power (dBm)		
Mode		Ch0 (2402 MHz)	Ch39 (2441 MHz)	Ch78 (2480 MHz)
GFSK	7	5.61	5.67	5.66
EDR2M-4_DQPSK	7	5.44	5.43	5.34
EDR3M-8DPSK	7	5.60	5.59	5.48
BLE	Tune up	Ch0（2402MHz）	Ch19（2440MHz）	Ch39（2480MHz）
	7	5.90	6.00	**6.03**

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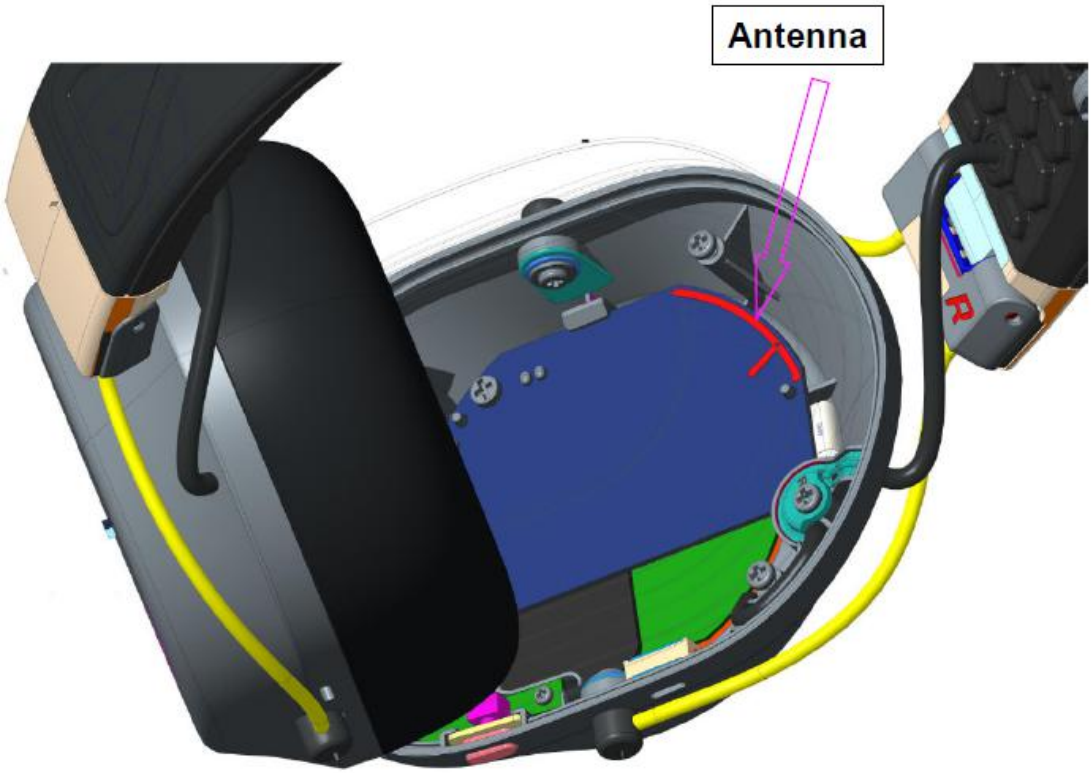
11 Bluetooth Antenna

11.1 Transmit Antenna Separation Distances



Picture 11.1 Antenna Locations

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12 SAR Test Result

The calculated SAR is obtained by the following formula:

$$\text{Reported SAR} = \text{Measured SAR} \times 10^{(P_{Target} - P_{Measured})/10}$$

Where P_{Target} is the power of manufacturing upper limit;

$P_{Measured}$ is the measured power in chapter 10.

Table 12.1: SAR Values (Bluetooth 2.4G -Head)

Ambient Temperature: 22.5°C Liquid Temperature: 22.0°C									
Frequency		Test Mode	Test Position	Figure No.	Conducted Power (dBm)	Max. tune-up Power (dBm)	Measured SAR(1g) (W/kg)	Reported SAR(1g) (W/kg)	Power Drift(dB)
MHz	Ch.								
2480	78	GFSK	Rear	/	5.66	7	0.008	**0.01**	0.03
2441	39	GFSK	Rear	/	5.67	7	0.012	**0.02**	0.10
2402	0	GFSK	Rear	**Fig.1**	5.61	7	0.016	**0.02**	0.06
2480	78	DQPSK	Rear	/	5.34	7	0.006	**0.01**	0.05
2441	39	DQPSK	Rear	/	5.43	7	0.008	**0.01**	0.11
2402	0	DQPSK	Rear	/	5.44	7	0.010	**0.01**	0.06
2480	78	8DPSK	Rear	/	5.48	7	0.007	**0.01**	0.08
2441	39	8DPSK	Rear	/	5.59	7	0.009	**0.01**	0.08
2402	0	8DPSK	Rear	/	5.60	7	0.007	**0.01**	0.12
2480	39	BLE	Rear	/	6.03	7	0.003	**< 0.01**	0.11
2440	19	BLE	Rear	/	6.00	7	0.005	**0.01**	0.08
2402	0	BLE	Rear	/	5.90	7	0.008	**0.01**	0.06

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13 SAR Measurement Variability

SAR measurement variability must be assessed for each frequency band, which is determined by the SAR probe calibration point and tissue-equivalent medium used for the device measurements. When both head and body tissue-equivalent media are required for SAR measurements in a frequency band, the variability measurement procedures should be applied to the tissue medium with the highest measured SAR, using the highest measured SAR configuration for that tissue-equivalent medium.

The following procedures are applied to determine if repeated measurements are required.

1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps 2) through 4) do not apply.

2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.

3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg (~ 10% from the 1-g SAR limit).

4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20.

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14 Measurement Uncertainty

14.1 Measurement Uncertainty for Normal SAR Tests (300MHz~3GHz)

No.	Error Description	Type	Uncertainty value	Probably Distribution	Div.	(Ci) 1g	(Ci) 10g	Std. Unc. (1g)	Std. Unc. (10g)	Degree of freedom
Measurement system										
1	Probe calibration	B	12	N	2	1	1	6.0	6.0	∞
2	Isotropy	B	7.4	R	$\sqrt{3}$	1	1	4.3	4.3	∞
3	Boundary effect	B	1.1	R	$\sqrt{3}$	1	1	0.6	0.6	∞
4	Linearity	B	4.7	R	$\sqrt{3}$	1	1	2.7	2.7	∞
5	Detection limit	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
6	Readout electronics	B	1.0	N	1	1	1	1.0	1.0	∞
7	Response time	B	0.0	R	$\sqrt{3}$	1	1	0.0	0.0	∞
8	Integration time	B	1.7	R	$\sqrt{3}$	1	1	1.0	1.0	∞
9	RF ambient conditions-noise	B	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
10	RF ambient conditions-reflection	B	3.0	R	$\sqrt{3}$	1	1	1.7	1.7	∞
11	Probe positioned mech. restrictions	B	0.35	R	$\sqrt{3}$	1	1	0.2	0.2	∞
12	Probe positioning with respect to phantom shell	B	2.9	R	$\sqrt{3}$	1	1	1.7	1.7	∞
13	Post-processing	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
Test sample related										
14	Test sample positioning	A	3.3	N	1	1	1	3.3	3.3	5
15	Device holder uncertainty	A	3.4	N	1	1	1	3.4	3.4	5
16	Drift of output power	B	5.0	R	$\sqrt{3}$	1	1	2.9	2.9	∞
Phantom and set-up										
17	Phantom uncertainty	B	1.0	R	$\sqrt{3}$	1	1	0.6	0.6	∞
18	Liquid conductivity (target)	B	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2	∞
19	Liquid conductivity (meas.)	A	1.3	N	1	0.64	0.43	0.83	0.56	9
20	Liquid permittivity (target)	B	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4	∞
21	Liquid permittivity (meas.)	A	1.6	N	1	0.6	0.49	0.96	0.78	9
Combined standard uncertainty		$u_c' = \sqrt{\sum_{i=1}^{21} c_i^2 u_i^2}$						10.4	10.3	95.5
Expanded uncertainty (Confidence interval of 95 %)		$u_e = 2u_c$						20.8	20.6	

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15 Main Test Instruments

Table 15.1: List of Main Instruments

No.	Name	Type	Serial Number	Calibration Date	Valid Period
01	Network analyzer	Agilent E5071C	MY46103759	2018-11-16	One year
02	Dielectric probe	85070E	MY44300317	/	/
03	Power meter	E4418B	MY50000366	2018-12-14	One year
04	Power sensor	E9304A	MY50000188		
05	Power meter	NRP	101460	2019-02-04	One year
06	Power sensor	NRP-Z91	100553		
07	Signal Generator	E8257D	MY47461211	2018-06-04	One year
08	Amplifier	VTL5400	0404	/	/
09	E-field Probe	SPEAG ES3DV3	3151	2018-12-19	One year
10	DAE	SPEAG DAE4	1527	2018-11-08	One year
11	Dipole Validation Kit	SPEAG D2450V2	873	2018-10-26	Three year

END OF REPORT BODY

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ANNEX A Graph Results

Bluetooth 2.4G Head

Date: 2019-5-29

Electronics: DAE4 Sn1527

Medium: Head 2450 MHz

Medium parameters used: f = 2402 MHz; σ = 1.776 S/m; ε_r = 38.622; ρ = 1000 kg/m^3

Ambient Temperature: 22.0ºC Liquid Temperature: 21.5ºC

Communication System: UID 0, BT (0) Frequency: 2402 MHz Duty Cycle: 1:1

Probe: ES3DV3 - SN3151 ConvF (4.66, 4.66, 4.66)

Rear Side Low/Area Scan (61x71x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm

Maximum value of SAR (interpolated) = 0.018 W/kg

Rear Side Low/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 0.114 V/m; Power Drift = 0.06 dB

Peak SAR (extrapolated) = 0.035 W/kg

SAR(1 g) = 0.016 W/kg; SAR(10 g) = 0.006 W/kg

Maximum value of SAR (measured) = 0.023 W/kg

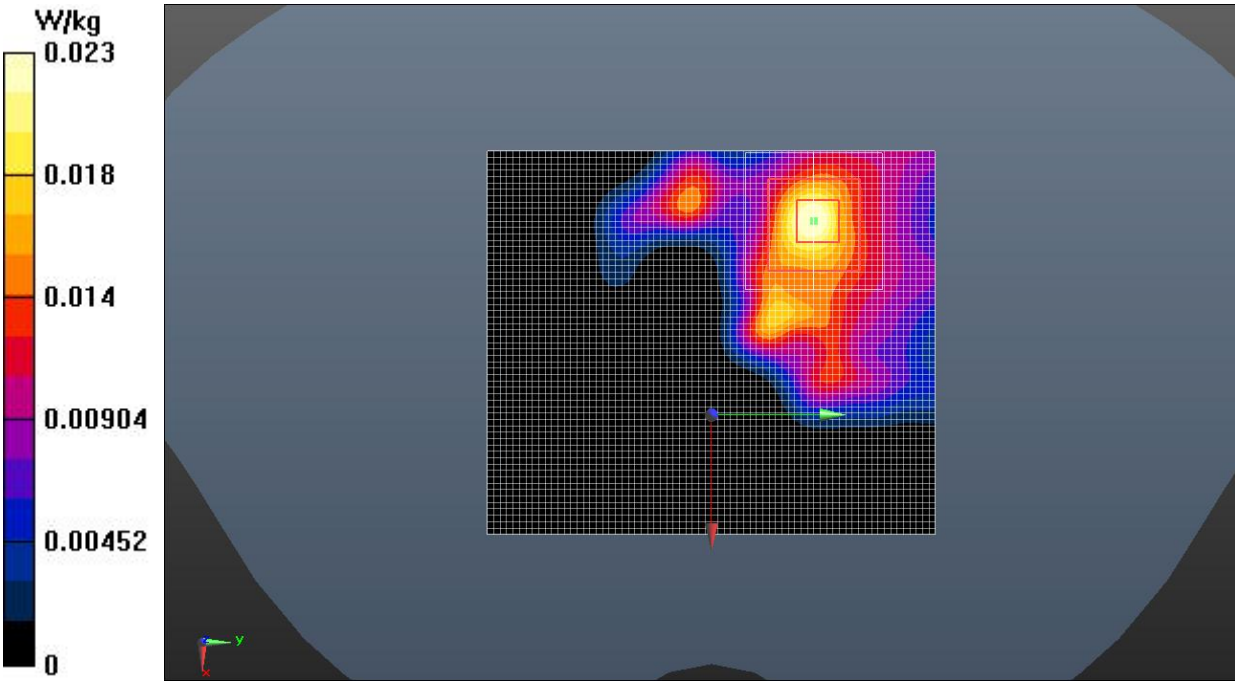

Fig.1 Bluetooth 2.4G

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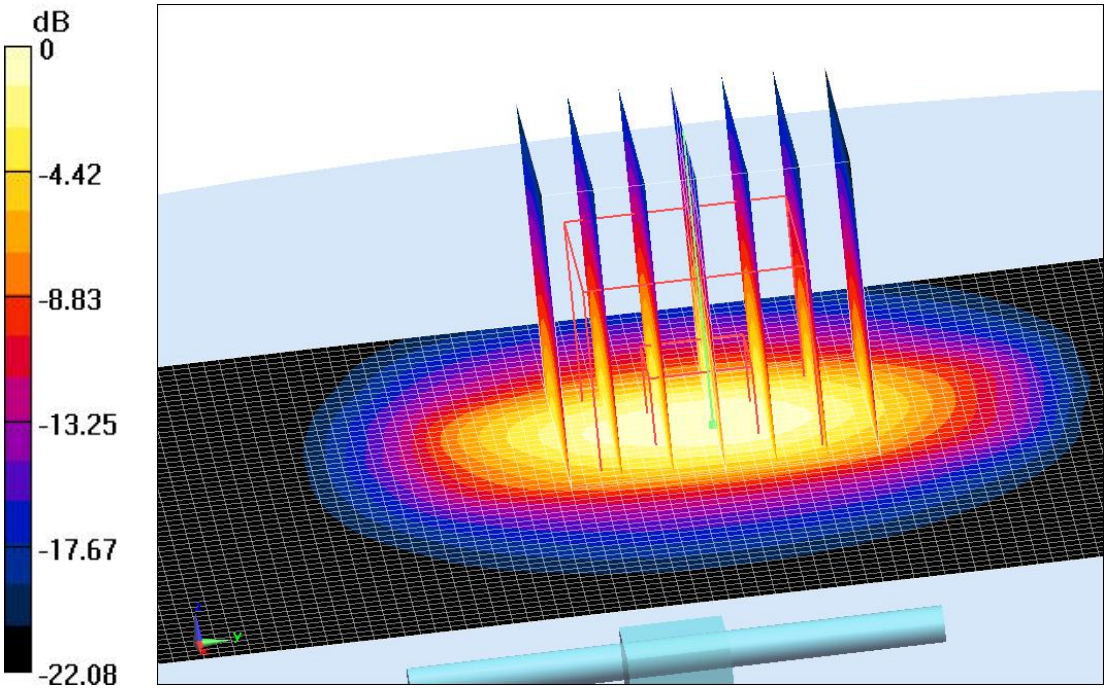
ANNEX B SystemVerification Results

2450MHz

Date: 2019-5-29
Electronics: DAE4 Sn1527
Medium: Head 2450 MHz
Medium parameters used: f = 2450 MHz; σ = 1.832 S/m; ε_r = 38.449; ρ = 1000 kg/m^3
Ambient Temperature: 22.0ºC Liquid Temperature: 21.6ºC
Communication System: CW Frequency: 2450 MHz Duty Cycle: 1:1
Probe: ES3DV3 - SN3151 ConvF (4.66, 4.66, 4.66)

System Validation /Area Scan (61x81x1): Interpolated grid: dx=1.000 mm, dy=1.000 mm
Reference Value = 90.202 V/m; Power Drift = -0.09 dB
SAR(1 g) = 13.5 W/kg; SAR(10 g) = 6.14 W/kg
Maximum value of SAR (interpolated) = 15.5 W/kg

System Validation /Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 90.202 V/m; Power Drift = -0.09 dB
Peak SAR (extrapolated) = 25.9 W/kg
SAR(1 g) = 13.4 W/kg; SAR(10 g) = 6.11 W/kg
Maximum value of SAR (measured) = 15.2 W/kg



0 dB = 15.2 W/kg = 11.82 dB W/kg

Fig.B.1. Validation 2450MHz 250mW

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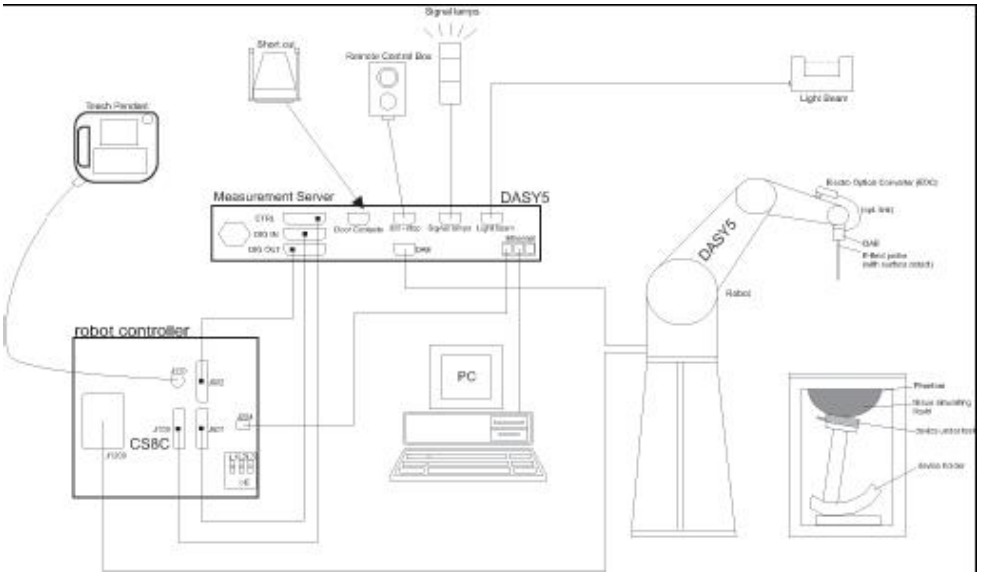
ANNEX C SAR Measurement Setup

C.1 Measurement Set-up

DASY5 system for performing compliance tests is illustrated above graphically. This system consists of the following items:



Picture C.1 SAR Lab Test Measurement Set-up

- A standard high precision 6-axis robot (Stäubli TX=RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP and the DASY5 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as
- warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

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C.2 DASY5 E-field Probe System

The SAR measurements were conducted with the dosimetric probe designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY5 software reads the reflection durning a software approach and looks for the maximum using 2ndord curve fitting. The approach is stopped at reaching the maximum.

Probe Specifications:

Model: ES3DV3, EX3DV4
Frequency 10MHz — 6.0GHz(EX3DV4)
Range: 10MHz — 4GHz(ES3DV3)
Calibration: In head and body simulating tissue at Frequencies from 835 up to 5800MHz
Linearity: ± 0.2 dB(30 MHz to 6 GHz) for EX3DV4
± 0.2 dB(30 MHz to 4 GHz) for ES3DV3
Dynamic Range: 10 mW/kg — 100W/kg
Probe Length: 330 mm
Probe Tip Length: 20 mm
Body Diameter: 12 mm
Tip Diameter: 2.5 mm (3.9 mm for ES3DV3)
Tip-Center: 1 mm (2.0mm for ES3DV3)
Application: SAR Dosimetry Testing
Compliance tests of mobile phones
Dosimetry in strong gradient fields

Picture C.2 Near-field Probe

Picture C.3 E-field Probe

C.3 E-field Probe Calibration

Each E-Probe/Probe Amplifier combination has unique calibration parameters. A TEM cell calibration procedure is conducted to determine the proper amplifier settings to enter in the probe parameters. The amplifier settings are determined for a given frequency by subjecting the probe to a known E-field density (1 mW/cm^2) using an RF Signal generator, TEM cell, and RF Power Meter.

The free space E-field from amplified probe outputs is determined in a test chamber. This calibration can be performed in a TEM cell if the frequency is below 1 GHz and inn a waveguide or

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other methodologies above 1 GHz for free space. For the free space calibration, the probe is placed in the volumetric center of the cavity and at the proper orientation with the field. The probe is then rotated 360 degrees until the three channels show the maximum reading. The power density readings equates to 1 mW/ cm^2.

E-field temperature correlation calibration is performed in a flat phantom filled with the appropriate simulated brain tissue. The E-field in the medium correlates with the temperature rise in the dielectric medium. For temperature correlation calibration a RF transparent thermistor-based temperature probe is used in conjunction with the E-field probe.

$$SAR = C\frac{\Delta T}{\Delta t}$$

Where:

Δt = Exposure time (30 seconds),

C = Heat capacity of tissue (brain or muscle),

ΔT = Temperature increase due to RF exposure.

$$SAR = \frac{|E|^2 \cdot \sigma}{\rho}$$

Where:

σ = Simulated tissue conductivity,

ρ = Tissue density (kg/m^3).

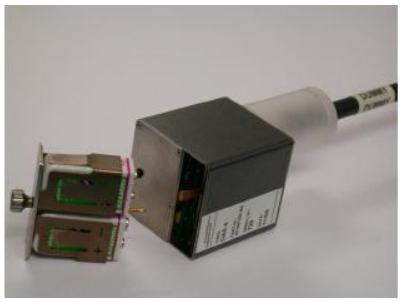
C.4 Other Test Equipment

C.4.1 Data Acquisition Electronics (DAE)

The data acquisition electronics consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



PictureC.4: DAE

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C.4.2 Robot

The SPEAG DASY system uses the high precision robots (DASY5: RX160L) type from Stäubli SA (France). For the 6-axis controller system, the robot controller version from Stäubli is used. The Stäubli robot series have many features that are important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchron motors; no stepper motors)
- Low ELF interference (motor control fields shielded via the closed metallic construction shields)

Picture C.5 DASY 5

C.4.3 Measurement Server

The Measurement server is based on a PC/104 CPU broad with CPU (DASY5: 400 MHz, Intel Celeron), chipdisk (DASY5:128MB), RAM (DASY5:128MB). The necessary circuits for communication with the DAE electronic box, as well as the 16 bit AD converter system for optical detection and digital I/O interface are contained on the DASY I/O broad, which is directly connected to the PC/104 bus of the CPU broad.

The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized pinout, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.

Picture C.6 Server for DASY 5

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C.4.4 Device Holder for Phantom

The SAR in the phantom is approximately inversely proportional to the square of the distance between the source and the liquid surface. For a source at 5mm distance, a positioning uncertainty of ±0.5mm would produce a SAR uncertainty of ±20%. Accurate device positioning is therefore crucial for accurate and repeatable measurements. The positions in which the devices must be measured are defined by the standards.

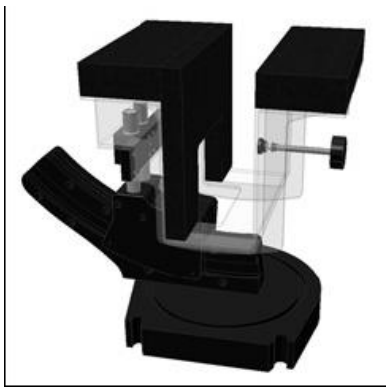
The DASY device holder is designed to cope with the different positions given in the standard. It has two scales for device rotation (with respect to the body axis) and device inclination (with respect to the line between the ear reference points). The rotation centers for both scales is the ear reference point (ERP). Thus the device needs no repositioning when changing the angles.

The DASY device holder is constructed of low-loss POM material having the following dielectric parameters: relative permittivity ε =3 and loss tangent δ=0.02. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

<Laptop Extension Kit>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the Mounting Device in place of the phone positioner. The extension is fully compatible with the Twin-SAM and ELI phantoms.

Picture C.7-1: Device Holder



Picture C.7-2: Laptop Extension Kit

C.4.5 Phantom

The SAM Twin Phantom V4.0 is constructed of a fiberglass shell integrated in a table. The shape of the shell is based on data from an anatomical study designed to

Represent the 90th percentile of the population. The phantom enables the dissymmetric evaluation of SAR for both left and right handed handset usage, as well as body-worn usage using the flat phantom region. Reference markings on the Phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points in the robot. The shell phantom has a 2mm shell thickness (except the ear region where shell thickness increases to 6 mm).

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Shell Thickness: 2 ± 0. 2 mm
Filling Volume: Approx. 25 liters
Dimensions: 810 x l000 x 500 mm (H x L x W)
Available: Special

Picture C.8: SAM Twin Phantom

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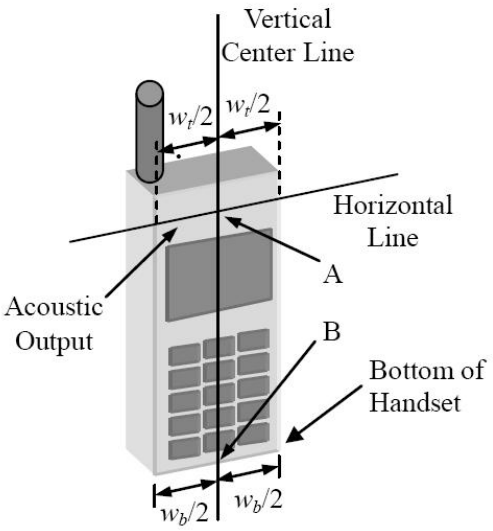
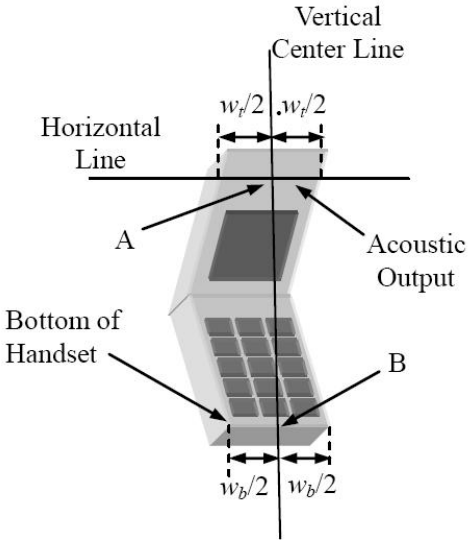
ANNEX D Position of the wireless device in relation to the phantom

D.1 General considerations

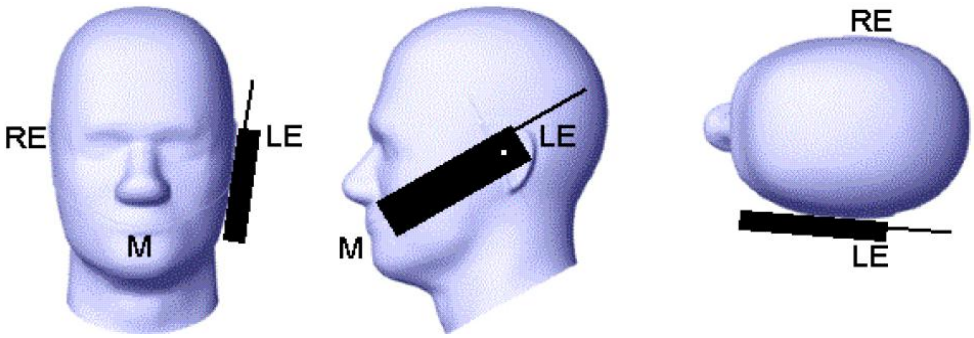
This standard specifies two handset test positions against the head phantom – the “cheek” position and the “tilt” position.





w_t	Width of the handset at the level of the acoustic
w_b	Width of the bottom of the handset
A	Midpoint of the width w_t of the handset at the level of the acoustic output
B	Midpoint of the width w_b of the bottom of the handset

Picture D.1-a Typical “fixed” case handset **Picture D.1-b Typical “clam-shell” case handset**



Picture D.2 Cheek position of the wireless device on the left side of SAM

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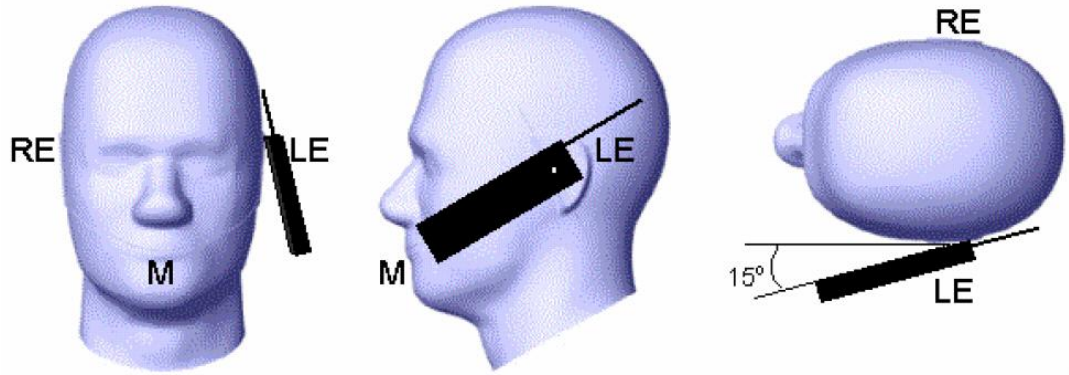
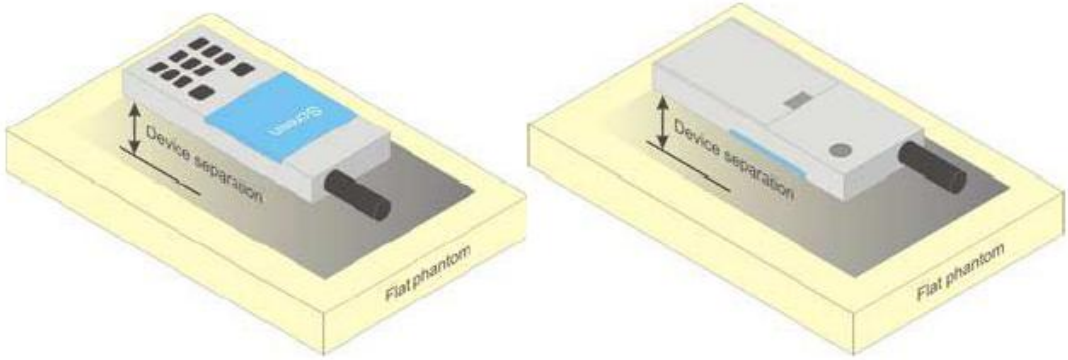


Picture D.3 Tilt position of the wireless device on the left side of SAM

D.2 Body-worn device

A typical example of a body-worn device is a mobile phone, wireless enabled PDA or other battery operated wireless device with the ability to transmit while mounted on a person's body using a carry accessory approved by the wireless device manufacturer.



Picture D.4 Test positions for body-worn devices

D.3 Desktop device

A typical example of a desktop device is a wireless enabled desktop computer placed on a table or desk when used.

The DUT shall be positioned at the distance and in the orientation to the phantom that corresponds to the intended use as specified by the manufacturer in the user instructions. For devices that employ an external antenna with variable positions, tests shall be performed for all antenna positions specified. Picture 8.5 show positions for desktop device SAR tests. If the intended use is not specified, the device shall be tested directly against the flat phantom.

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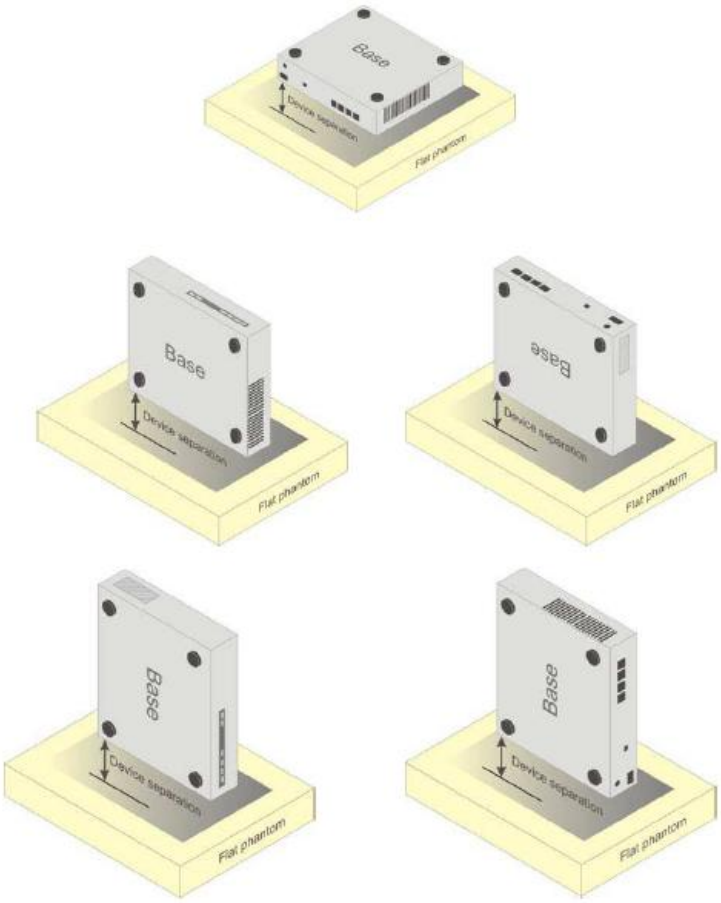

Picture D.5 Test positions for desktop devices

D.4 DUT Setup Photos

Picture D.6

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ANNEX E Equivalent Media Recipes

The liquid used for the frequency range of 700-6000 MHz consisted of water, sugar, salt, preventol, glycol monobutyl and Cellulose. The liquid has been previously proven to be suited for worst-case. The Table E.1 shows the detail solution. It's satisfying the latest tissue dielectric parameters requirements proposed by the IEEE 1528 and IEC 62209.

Table E.1: Composition of the Tissue Equivalent Matter

Frequency (MHz)	835 Head	835 Body	1900 Head	1900 Body	2450 Head	2450 Body	5800 Head	5800 Body
Ingredients (% by weight)								
Water	41.45	52.5	55.242	69.91	58.79	72.60	65.53	65.53
Sugar	56.0	45.0	\	\	\	\	\	\
Salt	1.45	1.4	0.306	0.13	0.06	0.18	\	\
Preventol	0.1	0.1	\	\	\	\	\	\
Cellulose	1.0	1.0	\	\	\	\	\	\
Glycol Monobutyl	\	\	44.452	29.96	41.15	27.22	\	\
Diethylenglycol monohexylether	\	\	\	\	\	\	17.24	17.24
Triton X-100	\	\	\	\	\	\	17.24	17.24
Dielectric Parameters Target Value	ε=41.5 σ=0.90	ε=55.2 σ=0.97	ε=40.0 σ=1.40	ε=53.3 σ=1.52	ε=39.2 σ=1.80	ε=52.7 σ=1.95	ε=35.3 σ=5.27	ε=48.2 σ=6.00

Note: There is a little adjustment respectively for 750, 1800, 2600, 5200, 5300, and 5600, based on the recipe of closest frequency in table E.1

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ANNEX F System Validation

The SAR system must be validated against its performance specifications before it is deployed. When SAR probes, system components or software are changed, upgraded or recalibrated, these must be validated with the SAR system(s) that operates with such components.

Table F.1: System Validation

Probe SN.	Liquid name	Validation date	Frequency point	Status (OK or Not)
3151	Head 750MHz	2018-12-28	750 MHz	OK
3151	Head 900MHz	2018-12-28	900 MHz	OK
3151	Head 1750MHz	2018-12-28	1800 MHz	OK
3151	Head 1900MHz	2018-12-29	1900 MHz	OK
3151	Head 2450MHz	2018-12-29	2450 MHz	OK
3151	Head 2550MHz	2018-12-29	2550 MHz	OK
3151	Body 750MHz	2018-12-28	750 MHz	OK
3151	Body 900MHz	2018-12-28	900 MHz	OK
3151	Body 1750MHz	2018-12-28	1800 MHz	OK
3151	Body 1900MHz	2018-12-29	1900 MHz	OK
3151	Body 2450MHz	2018-12-29	2450 MHz	OK
3151	Body 2550MHz	2018-12-29	2550 MHz	OK

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ANNEX G DAE Calibration Certificate

DAE4 SN: 1527 Calibration Certificate

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Client : CTTL(South Branch) Certificate No: Z18-60482

CALIBRATION CERTIFICATE

Object	DAE4 - SN: 1527
Calibration Procedure(s)	FF-Z11-002-01 Calibration Procedure for the Data Acquisition Electronics (DAEx)
Calibration date:	November 08, 2018

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)℃ and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Process Calibrator 753	1971018	20-Jun-18 (CTTL, No.J18X05034)	June-19

	Name	Function	Signature
Calibrated by:	Yu Zongying	SAR Test Engineer	
Reviewed by:	Lin Hao	SAR Test Engineer	
Approved by:	Qi Dianyuan	SAR Project Leader	

Issued: November 10, 2018

This calibration certificate shall not be reproduced except in full without written approval of the laboratory.

Certificate No: Z18-60482 Page 1 of 3

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Glossary:

DAE	data acquisition electronics
Connector angle	information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters:

- *DC Voltage Measurement*: Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle*: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The report provide only calibration results for DAE, it does not contain other performance test results.

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DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1μV , full range = -100...+300 mV
Low Range: 1LSB = 61nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	403.865 ± 0.15% (k=2)	403.585 ± 0.15% (k=2)	403.804 ± 0.15% (k=2)
Low Range	3.96012 ± 0.7% (k=2)	3.98948 ± 0.7% (k=2)	3.96752 ± 0.7% (k=2)

Connector Angle

Connector Angle to be used in DASY system	223° ± 1 °

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ANNEX H Probe Calibration Certificate

Probe ES3DV3-SN: 3151 Calibration

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CNAS L0570

Client CTTL(South Branch) Certificate No: Z18-60544

CALIBRATION CERTIFICATE

Object	ES3DV3 - SN:3151
Calibration Procedure(s)	FF-Z11-004-01 Calibration Procedures for Dosimetric E-field Probes
Calibration date:	December 19, 2018

This calibration Certificate documents the traceability to national standards, which realize the physical units of measurements(SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature(22±3)°C and humidity<70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
Power Meter NRP2	101919	20-Jun-18 (CTTL, No.J18X05032)	Jun-19
Power sensor NRP-Z91	101547	20-Jun-18 (CTTL, No.J18X05032)	Jun-19
Power sensor NRP-Z91	101548	20-Jun-18 (CTTL, No.J18X05032)	Jun-19
Reference10dBAttenuator	18N50W-10dB	09-Feb-18(CTTL, No.J18X01133)	Feb-20
Reference20dBAttenuator	18N50W-20dB	09-Feb-18(CTTL, No.J18X01132)	Feb-20
Reference Probe EX3DV4	SN 3846	25-Jan-18(SPEAG,No.EX3-3846_Jan18)	Jan-19
DAE4	SN 777	15-Dec-17(SPEAG, No.DAE4-777_Dec17)	Dec -18
DAE4	SN 1555	20-Aug-18(SPEAG, No.DAE4-1555_Aug18)	Aug -19
Secondary Standards	ID #	Cal Date(Calibrated by, Certificate No.)	Scheduled Calibration
SignalGeneratorMG3700A	6201052605	21-Jun-18 (CTTL, No.J18X05033)	Jun-19
Network Analyzer E5071C	MY46110673	24-Jan-18 (CTTL, No.J18X00561)	Jan -19

	Name	Function	Signature
Calibrated by:	Yu Zongying	SAR Test Engineer	
Reviewed by:	Lin Hao	SAR Test Engineer	
Approved by:	Qi Dianyuan	SAR Project Leader	

Issued: December 21, 2018

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Certificate

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Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConvF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A,B,C,D	modulation dependent linearization parameters
Polarization Φ	Φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i θ=0 is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2013, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", June 2013

b) IEC 62209-1, "Measurement procedure for the assessment of Specific Absorption Rate (SAR) from hand-held and body-mounted devices used next to the ear (frequency range of 300 MHz to 6 GHz)", July 2016

c) IEC 62209-2, "Procedure to determine the Specific Absorption Rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)", March 2010

d) KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization θ=0 (f≤900MHz in TEM-cell; f>1800MHz: waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E^2-field uncertainty inside TSL (see below ConvF).
- *NORM(f)x,y,z = NORMx,y,z* frequency_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics.
- *Ax,y,z; Bx,y,z; Cx,y,z;VRx,y,z:*A,B,C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- *ConvF and Boundary Effect Parameters:* Assessed in flat phantom using E-field (or Temperature Transfer Standard for f≤800MHz) and inside waveguide using analytical field distributions based on power measurements for f >800MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty valued are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORMx,y,z* ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from±50MHz to±100MHz.
- *Spherical isotropy (3D deviation from isotropy):* in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- *Sensor Offset:* The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- *Connector Angle:* The angle is assessed using the information gained by determining the *NORMx* (no uncertainty required).

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Probe ES3DV3

SN: 3151

Calibrated: December 19, 2018

Calibrated for DASY/EASY Systems

(Note: non-compatible with DASY2 system!)

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DASY/EASY – Parameters of Probe: ES3DV3 - SN: 3151

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm(μV/(V/m)²)[A]	1.15	1.26	1.19	±10.0%
DCP(mV)[B]	104.5	104.0	102.9	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB√μV	C	D dB	VR mV	Unc[E] (k=2)
0	CW	X	0.0	0.0	1.0	0.00	274.9	±2.3%
		Y	0.0	0.0	1.0		288.7	
		Z	0.0	0.0	1.0		279.3	

The reported uncertainty of measurement is stated as the standard uncertainty of Measurement multiplied by the coverage factor k=2, which for a normal distribution Corresponds to a coverage probability of approximately 95%.

[A] The uncertainties of Norm X, Y, Z do not affect the E^2-field uncertainty inside TSL (see Page 5 and Page 6).
[B] Numerical linearization parameter: uncertainty not required.
[E] Uncertainly is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

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Calibration Parameter Determined in Head Tissue Simulating Media

f [MHz][C]	Relative Permittivity [F]	Conductivity (S/m) [F]	ConvF X	ConvF Y	ConvF Z	Alpha[G]	Depth[G] (mm)	Unct. (k=2)
750	41.9	0.89	6.40	6.40	6.40	0.40	1.50	±12.1%
900	41.5	0.97	6.22	6.22	6.22	0.48	1.40	±12.1%
1450	40.5	1.20	5.51	5.51	5.51	0.37	1.59	±12.1%
1750	40.1	1.37	5.26	5.26	5.26	0.63	1.30	±12.1%
1900	40.0	1.40	5.10	5.10	5.10	0.70	1.24	±12.1%
2300	39.5	1.67	4.89	4.89	4.89	0.90	1.10	±12.1%
2450	39.2	1.80	4.66	4.66	4.66	0.89	1.17	±12.1%
2600	39.0	1.96	4.56	4.56	4.56	0.90	1.15	±12.1%

[C] Frequency validity above 300 MHz of ±100MHz only applies for DASY v4.4 and higher (Page 2), else it is restricted to ±50MHz. The uncertainty is the RSS of ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ± 10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Above 5 GHz frequency validity can be extended to ± 110 MHz.

[F] At frequency below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ±10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ±5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

[G] Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ± 1% for frequencies below 3 GHz and below ± 2% for the frequencies between 3-6 GHz at any distance larger than half the probe tip diameter from the boundary.

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