

SAR Test Report

Report No.: AGC04164150701FH01

FCC ID : EW780-9800-00

APPLICATION PURPOSE : Original Equipment

PRODUCT DESIGNATION : Cordless Phone

BRAND NAME : Polycom

MODEL NAME : VVX D60

CLIENT : VTech Telecommunications Ltd.

DATE OF ISSUE : Sep. 6, 2015

STANDARD(S) : IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE/ANSI C95.1:1992

REPORT VERSION : V1.0

Attestation of Global Compliance(Shenzhen) Co., Ltd.

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Report Revise Record

Report Version	Revise Time	Issued Date	Valid Version	Notes
V1.0	/	Sep. 6,2015	Valid	Original Report

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Test Report Certification

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Applicant Address	:	23/F, Tai Ping Industrial Centre, Block 1, 57 Ting Kok Road, Tai Po, Hong Kong
Manufacturer Name	:	VTech Telecommunications Ltd.
Manufacturer Address	:	23/F, Tai Ping Industrial Centre, Block 1, 57 Ting Kok Road, Tai Po, Hong Kong
Product Designation	:	Cordless Phone
Brand Name	:	Polycom
Model Name	:	VVX D60
Different Description	:	N/A
EUT Voltage	:	DC2.4V by battery
Applicable Standard	:	IEEE Std. 1528:2013; FCC 47CFR § 2.1093; IEEE/ANSI C95.1:1992
Test Date	:	July 31,2015
Performed Location	:	Attestation of Global Compliance(Shenzhen) Co., Ltd. 2 F, Building 2, No.1-No.4, Chaxi Sanwei Technical Industrial Park, Gushu, Xixiang Street, Bao'an District, Shenzhen, China
Report Template	:	AGCRT-US-2.5G/SAR (2015-05-01)

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1.SUMMARY OF MAXIMUM SAR VALUE

The maximum results of Specific Absorption Rate (SAR) found during testing for EUT are as follows:

Highest Reported SAR :

Exposure Position	Frequency Band(MHz)	Highest Reported 1g-SAR(W/Kg)
Head	1924.992	0.033
Body	1924.992	0.025

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits (1.6W/Kg) specified in IEEE Std. 1528:2013; IEEE1528a-2005;47CFR § 2.1093; IEEE/ANSI C95.1 and the following specific FCC Test Procedures:

- KDB 447498 D01 General RF Exposure Guidance v05r02
- KDB 648474 D04 Handset SAR v01r02
- KDB 865664 D01 SAR measurement 100 MHz to 6 GHz v01r04

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2. GENERAL INFORMATION

2.1. EUT Description

General Information	
Product Designation	Cordless Phone
Test Model	VVX D60
Hardware Version	35-200371-003-100
Software Version	N/A
Device Category	Portable
RF Exposure Environment	Uncontrolled
Antenna Type	Internal
DECT Band	
Frequency Range	1900: 1920-1929MHz
Type of modulation	GFSK
Antenna Gain	0dBi
Max. Average Power (Max. Peak Power)	19.12dBm
Accessories	
Battery	Brand name: Corun Model No. : Ni-MH 50AAA800*2 Voltage and Capacitance: 2.4V 800mAH
Adapter	Brand name: N/A Model No. : S008ACM5000120 Input: AC 100-240V, 50/60Hz, 250mA Output: DC 5V, 1200mA
Product	Type
	☒ Production unit ☐ Identical Prototype

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2.2. Test Procedure

1	Setup the EUT and simulators as shown on above.
2	Turn on the power of all equipment.
3	EUT Communicate with CMD60/RTX2012, and test them respectively at DECT bands

2.3. Test Environment

Ambient conditions in the laboratory:

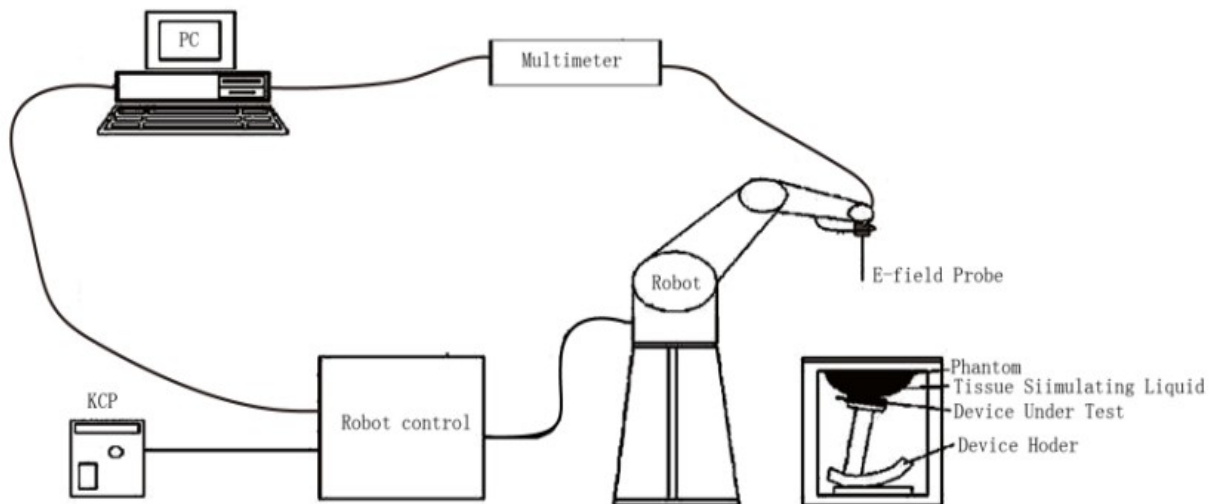
Items	Required	Actual
Temperature (°C)	18-25	21± 2
Humidity (%RH)	30-70	55±2

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3. SAR MEASUREMENT SYSTEM

3.1. SATIMO System Description



The COMOSAR system for performing compliance tests consists of the following items:

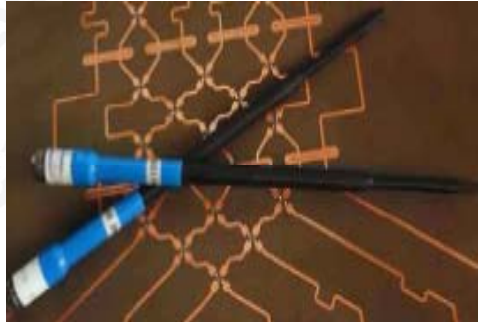
- The PC. It controls most of the bench devices and stores measurement data. A computer running WinXP and the Opensar software
- The E-Field probe. The probe is a 3-axis system made of 3 distinct dipoles. Each dipole returns a voltage in function of the ambient electric field.
- The Keithley multimeter measures each probe dipole voltages.
- The SAM phantom simulates a human head. The measurement of the electric field is made inside the phantom.
- The liquids simulate the dielectric properties of the human head tissues.
- The network emulator controls the mobile phone under test.
- The validation dipoles are used to measure a reference SAR. They are used to periodically check the bench to make sure that there is no drift of the system characteristics over time.
- The phantom, the device holder and other accessories according to the targeted measurement.

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3.2. COMOSAR E-Field Probe

The SAR measurement is conducted with the dissymmetric probe manufactured by SATIMO. The probe is specially designed and calibrated for use in liquid with high permittivity. The dissymmetric probe has special calibration in liquid at different frequency. SATIMO conducts the probe calibration in compliance with international and national standards (e.g. IEEE 1528-2013 and relevant KDB files) Under ISO17025. The calibration data are in Appendix D.

Isotropic E-Field Probe Specification

Model	SSE5	
Manufacture	SATIMO	
Frequency	0.3GHz-3GHz Linearity:±0.09dB(300MHz-3GHz)	
Dynamic Range	0.01W/Kg-100W/Kg Linearity:±0.09dB	
Dimensions	Overall length:330mm Length of individual dipoles:4.5mm Maximum external diameter:8mm Probe Tip external diameter:5mm Distance between dipoles/ probe extremity:2.7mm	
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 3 GHz with precision of better 30%.	

3.3. Robot

The COMOSAR system uses the KUKA robot from SATIMO SA (France).For the 6-axis controller COMOSAR system, the KUKA robot controller version from SATIMO is used.
The XL robot series have many features that are important for our application:

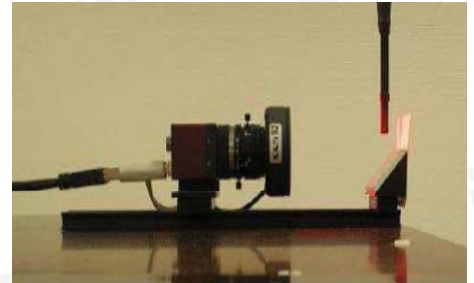
- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller



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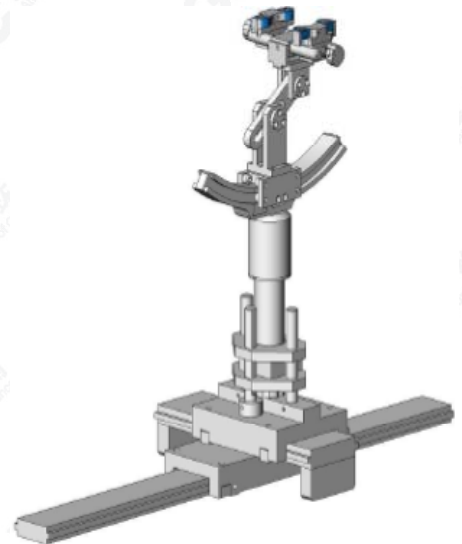
3.4. Video Positioning System

The video positioning system is used in OpenSAR to check the probe. Which is composed of a camera, LED, mirror and mechanical parts. The camera is piloted by the main computer with firewire link. During the process, the actual position of the probe tip with respect to the robot arm is measured, as well as the probe length and the horizontal probe offset. The software then corrects all movements, such that the robot coordinates are valid for the probe tip. The repeatability of this process is better than 0.1 mm. If a position has been taught with an aligned probe, the same position will be reached with another aligned probe within 0.1 mm, even if the other probe has different dimensions. During probe rotations, the probe tip will keep its actual position.



3.5. Device Holder

The COMOSAR device holder is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear reference points). The rotation center for both scales is the ear reference point (EPR). Thus the device needs no repositioning when changing the angles. The COMOSAR device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon_r = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.



3.6. SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left head
- Right head
- Flat phantom



The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

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4. SAR MEASUREMENT PROCEDURE

4.1. Specific Absorption Rate (SAR)

SAR is related to the rate at which energy is absorbed per unit mass in object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and occupational/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element(dv) of given mass density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dV} \right)$$

SAR is expressed in units of Watts per kilogram (W/Kg)

SAR can be obtained using either of the following equations:

$$SAR = \frac{\sigma E^2}{\rho}$$

$$SAR = c_h \left. \frac{dT}{dt} \right|_{t=0}$$

Where

SAR	is the specific absorption rate in watts per kilogram;
E	is the r.m.s. value of the electric field strength in the tissue in volts per meter;
σ	is the conductivity of the tissue in siemens per metre;
ρ	is the density of the tissue in kilograms per cubic metre;
c _h	is the heat capacity of the tissue in joules per kilogram and Kelvin;
$\left. \frac{dT}{dt} \right _{t=0}$	is the initial time derivative of temperature in the tissue in kelvins per second

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4.2. SAR Measurement Procedure

Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurement are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface is 2.7mm This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties,

Step 2: Area Scan

The Area Scan is used as a fast scan in two dimensions to find the area of high field values, before doing a fine measurement around the hot spot. The sophisticated interpolation routines implemented in SATIMO software can find the maximum locations even in relatively coarse grids. When an Area Scan has measured all reachable points, it computes the field maximal found in the scanned area, within a range of the global maximum. The range (in db) is specified in the standards for compliance testing. For example, a 2db range is required in IEEE Standard 1528 and IEC62209 standards, whereby 3db is a requirement when compliance is assessed in accordance with the ARIB standard (Japan) If one Zoom Scan follows the Area Scan, then only the absolute maximum will be taken as reference. For cases where multiple maximum are detected, the number of Zoom Scan has to be increased accordingly.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100MHz to 6GHz

	≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 ± 1 mm	$\frac{1}{2} \cdot \delta \cdot \ln(2) \pm 0.5 \text{ mm}$
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30° ± 1°	20° ± 1°
Maximum area scan spatial resolution: $\Delta x_{\text{Area}}, \Delta y_{\text{Area}}$	≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm
	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

Step 3: Zoom Scan

Zoom Scan are used to assess the peak spatial SAR value within a cubic average volume containing 1g and 10g of simulated tissue. The Zoom Scan measures points(refer to table below) within a cube whose base faces are centered on the maxima found in a preceding area scan job within the same procedure. When the measurement is done, the Zoom Scan evaluates the averaged SAR for 1g and 10g and displays these values next to the job's label.

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Zoom Scan Parameters extracted from KDB865664 d01 SAR Measurement 100MHz to 6GHz

Maximum zoom scan spatial resolution: Δx_{Zoom} , Δy_{Zoom}			≤ 2 GHz: ≤ 8 mm 2 – 3 GHz: ≤ 5 mm*	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{Zoom}(n)$		≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
	graded grid	$\Delta z_{Zoom}(1)$: between 1 st two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
		$\Delta z_{Zoom}(n>1)$: between subsequent points	$\leq 1.5 \cdot \Delta z_{Zoom}(n-1)$	
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm
Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see draft standard IEEE P1528-2011 for details.				
* When zoom scan is required and the <u>reported</u> SAR from the <u>area scan based 1-g SAR estimation</u> procedures of KDB 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.				

Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the same settings. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

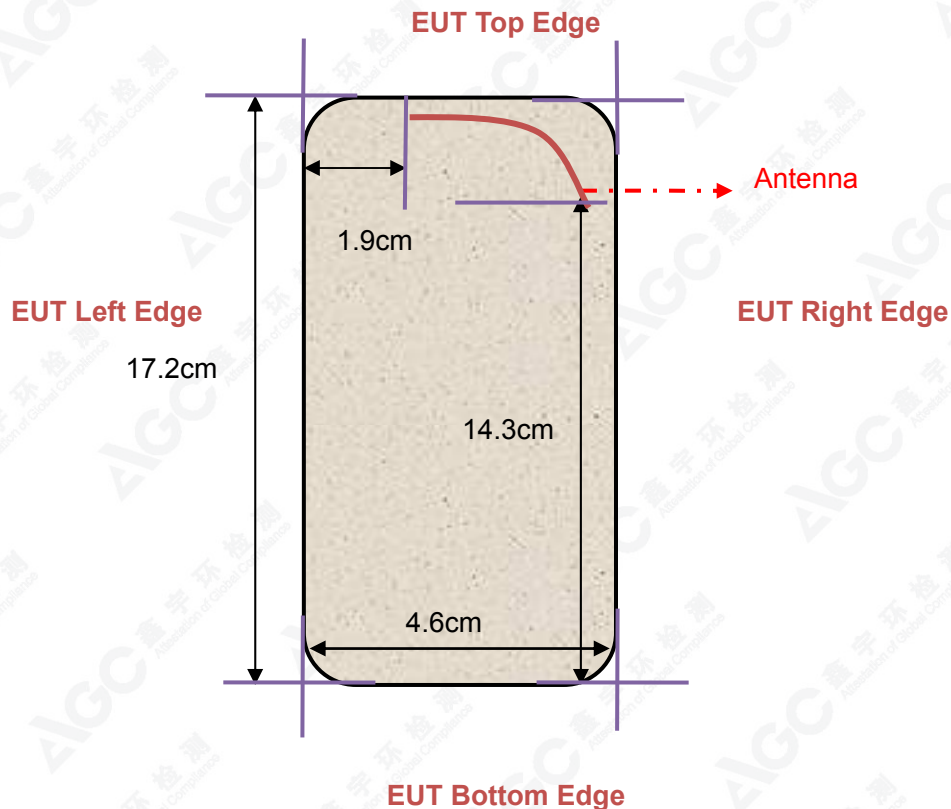
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4.3. RF Exposure Conditions

Test Configuration and setting:

The EUT is a model of DECT. For DECT SAR testing, the device was controlled by using a base station emulator. Communication between the device and the emulator were established by air link. The distance between the EUT and the antenna is larger than 50cm, and the output power radiated from the emulator antenna is at least 30db smaller than the output power of EUT.

Antenna Location: (Back view)



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5. TISSUE SIMULATING LIQUID

For SAR measurement of the field distribution inside the phantom, the phantom must be filled with homogeneous tissue simulating liquid to a depth of at least 15cm. For head SAR testing the liquid height from the ear reference point (ERP) of the phantom to the liquid top surface is larger than 15cm. For body SAR testing, the liquid height from the center of the flat phantom to the liquid top surface is larger than 15cm. The nominal dielectric values of the tissue simulating liquids in the phantom and the tolerance of 5% are listed in 4.2

5.1. The composition of the tissue simulating liquid

Ingredient (% Weight)	1900MHz	1900MHz
	Head	Body
Water	54.9	40.4
Salt	0.18	0.5
Sugar	0.0	58.0
HEC	0.0	1.0
Bactericide	0.0	0.1
DGBE	44.92	0.0

5.2. Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEEE 1528 have been incorporated in the following table. These head parameters are derived from planar layer models simulating the highest expected SAR for the dielectric properties and tissue thickness variations in a human head. Other head and body tissue parameters that have not been specified in IEEE 1528 are derived from the tissue dielectric parameters computed from the 4-Cole-Cole equations described in Reference [12] and extrapolated according to the head parameters specified in IEEE 1528.

Target Frequency (MHz)	head		body	
	ϵ_r	σ (S/m)	ϵ_r	σ (S/m)
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	1.01	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800 – 2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

(ϵ_r = relative permittivity, σ = conductivity and $\rho = 1000 \text{ kg/m}^3$)

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5.3. Tissue Calibration Result

The dielectric parameters of the liquids were verified prior to the SAR evaluation using SATIMO Dielectric Probe Kit and R&S Network Analyzer ZVL6.

Tissue Stimulant Measurement for 1900MHz					
Head	Fr. (MHz)	Dielectric Parameters ($\pm 5\%$)		Tissue Temp [$^{\circ}\text{C}$]	Test time
		$\epsilon_r 40.00(38.00-42.00)$	$\delta[s/m] 1.40(1.33-1.47)$		
	1900	40.08	1.38	21.6	July 31, 2015
	1925	39.46	1.41		July 31, 2015

Tissue Stimulant Measurement for 1900MHz					
Body	Fr. (MHz)	Dielectric Parameters ($\pm 5\%$)		Tissue Temp [$^{\circ}\text{C}$]	Test time
		ϵ_r 53.30 50.635-55.965	$\delta[s/m]$ 1.52 1.444-1.596		
	1900	53.71	1.51	21.7	July 31, 2015
	1925	53.00	1.53		July 31, 2015

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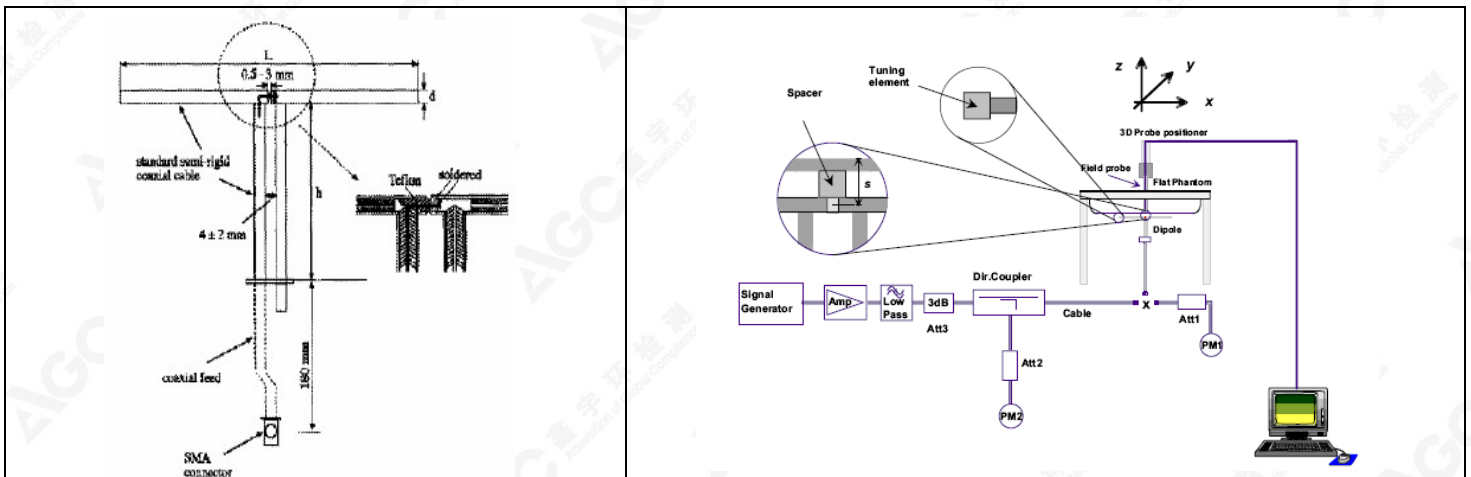
6. SAR SYSTEM CHECK&VALIDATION PROCEDURE

6.1. SAR System Check Procedures

SAR system check is required to confirm measurement accuracy, according to the tissue dielectric media, probe calibration points and other system operating parameters required for measuring the SAR of a test device. The system verification must be performed for each frequency band and within the valid range of each probe calibration point required for testing the device. The same SAR probe(s) and tissue-equivalent media combinations used with each specific SAR system for system verification must be used for device testing. When multiple probe calibration points are required to cover substantially large transmission bands, independent system verifications are required for each probe calibration point. A system verification must be performed before each series of SAR measurements using the same probe calibration point and tissue-equivalent medium. Additional system verification should be considered according to the conditions of the tissue-equivalent medium and measured tissue dielectric parameters, typically every three to four days when the liquid parameters are remeasured or sooner when marginal liquid parameters are used at the beginning of a series of measurements.

Each SATIMO system is equipped with one or more system check kits. These units, together with the predefined measurement procedures within the SATIMO software, enable the user to conduct the system check and system validation. System kit includes a dipole, and dipole device holder.

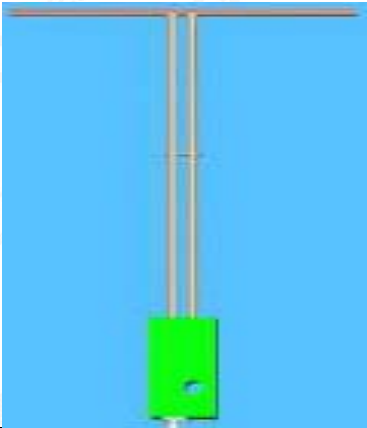
The system check verifies that the system operates within its specifications. It's performed daily or before every SAR measurement. The system check uses normal SAR measurement in the flat section of the phantom with a matched dipole at a specified distance. The system check setup is shown as below.



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6.2. SAR System Check

6.2.1. Dipoles

	The dipoles used is based on the IEEE-1528 standard, and is complied with mechanical and electrical specifications in line with the requirements of both IEEE and FCC Supplement C. the table below provides details for the mechanical and electrical Specifications for the dipoles.
---	---

Frequency	L (mm)	h (mm)	d (mm)
1900MHz	68	39.5	3.6

6.2.2. System Check Result

System Performance Check at 1900MHz								
Validation Kit: SN 46/11DIP 1G900-187								
Frequency [MHz]	Target Value(W/Kg)		Reference Result (± 10%)		Normalized to 1W(W/Kg)		Tissue Temp. [°C]	Test time
	1g	10g	1g	10g	1g	10g		
1900 Head	39.65	20.24	35.685-43.615	18.216-22.264	37.238	19.034	21.6	July 31,2015
1900 Body	40.74	21.43	36.666-44.814	19.287-23.573	40.300	20.320	21.7	July 31,2015

Note:

- (1) We use a CW signal of 18dBm for system check, and then all SAR value are normalized to 1W forward power. The result must be within ±10% of target value.
- (2) Tested normalized SAR (W/kg) = Tested SAR (W/kg) × [1000/ 10^{1.8}]

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6.3. SAR System Validation

The SAR measurement system was validated according to procedures in KDB 865664 D01.
 SAR probe and tissue dielectric parameters are as shown below.

Test Data	Probe S/N	Tested Freq. (MHz)	Tissue Type	Cond.	Perm	CW validation			Mod. validation		
						Sensitivity	Probe Linearity	Probe Isotropy	Mod. Type	Duty Factor	Peak to average power ratio
14/05/2015	SN 22/12 EP159	1900	head	39.55	1.41	PASS	PASS	PASS	GFSK	PASS	N/A
12/06/2015	SN 22/12 EP159	1900	body	53.0	1.49	PASS	PASS	PASS	GFSK	PASS	N/A

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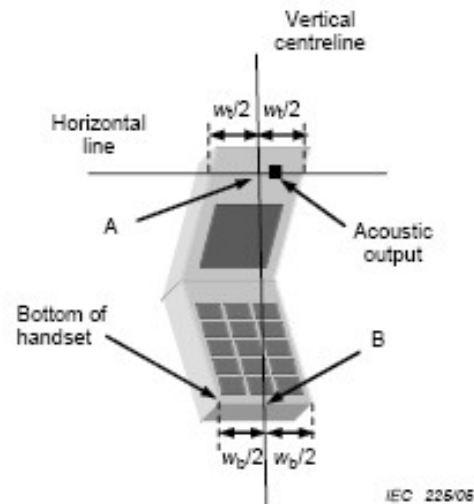
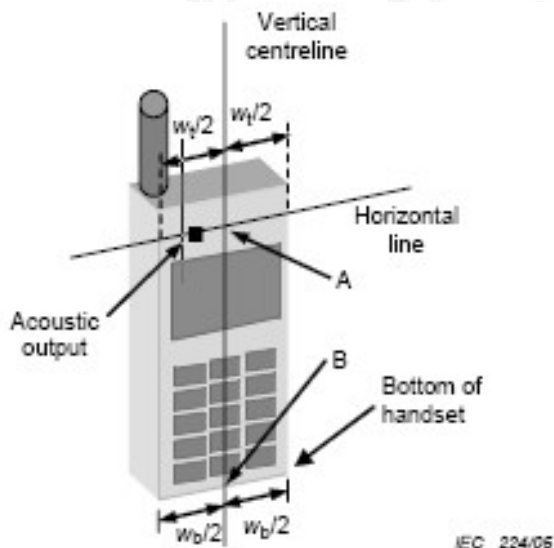


7. EUT TEST POSITION

This EUT was tested in **Right Cheek, Right Titled, Left Cheek, Left Titled, Body back and Body front.**

7.1. Define Two Imaginary Lines on the Handset

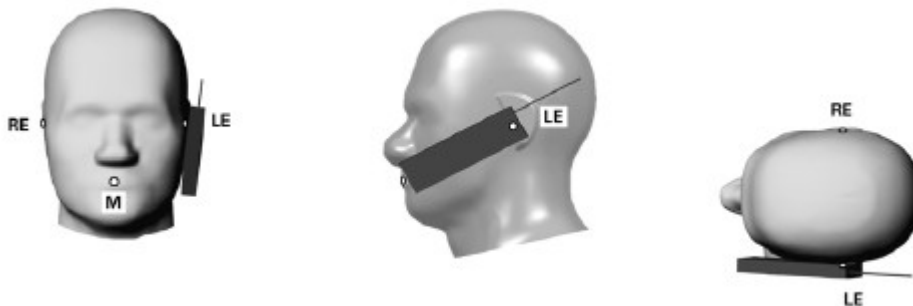
- (1) The vertical centerline passes through two points on the front side of the handset the midpoint of the width w_t of the handset at the level of the acoustic output, and the midpoint of the width w_b of the handset.
- (2) The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output. The horizontal line is also tangential to the face of the handset at point A.
- (3) The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output; however, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily to the front face of the handset, especially for clamshell handsets, handsets with flip covers, and other irregularly shaped handsets.



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7.2. Cheek Position

- (1) To position the device with the vertical center line of the body of the device and the horizontal line crossing the center piece in a plane parallel to the sagittal plane of the phantom. While maintaining the device in this plane, align the vertical center line with the reference plane containing the ear and mouth reference point (M: Mouth, RE: Right Ear, and LE: Left Ear) and align the center of the ear piece with the line RE-LE.
- (2) To move the device towards the phantom with the ear piece aligned with the the line LE-RE until the phone touched the ear. While maintaining the device in the reference plane and maintaining the phone contact with ear, move the bottom of the phone until any point on the front side is in contact with the cheek of the phantom or until contact with the ear is lost



7.3. Title Position

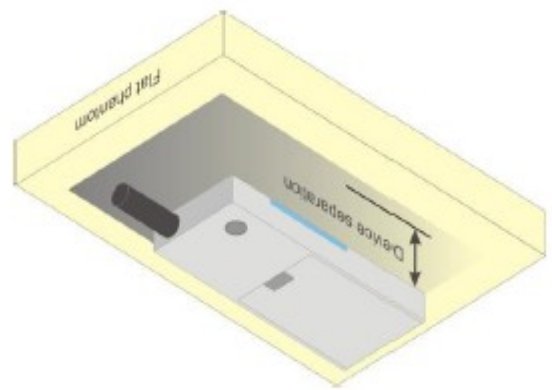
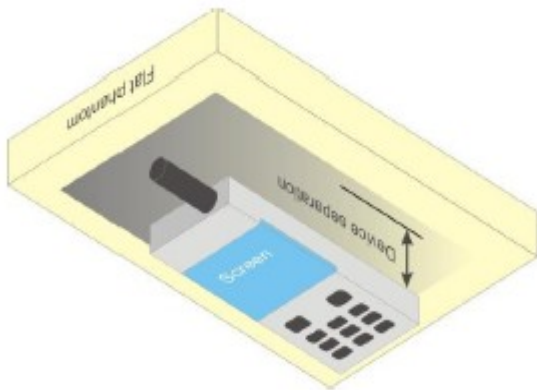
- (1) To position the device in the “cheek” position described above.
- (2) While maintaining the device in the reference plane described above and pivoting against the ear, moves it outward away from the mouth by an angle of 15 degrees or until with the ear is lost.



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7.4. Body Worn Position

- (1) To position the EUT parallel to the phantom surface.
- (2) To adjust the EUT parallel to the flat phantom.
- (3) To adjust the distance between the EUT surface and the flat phantom to **0mm for body back and body front with 5mm.**



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8. SAR EXPOSURE LIMITS

SAR assessments have been made in line with the requirements of IEEE-1528, and comply with ANSI/IEEE C95.1-1992 "Uncontrolled Environments" limits. These limits apply to a location which is deemed as "Uncontrolled Environment" which can be described as a situation where the general public may be exposed to an RF source with no prior knowledge or control over their exposure.

Limits for General Population/Uncontrolled Exposure (W/kg)

Type Exposure	Uncontrolled Environment Limit (W/kg)
Spatial Peak SAR (1g cube tissue for brain or body)	1.60
Spatial Average SAR (Whole body)	0.08
Spatial Peak SAR (Limbs)	4.0

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9. TEST EQUIPMENT LIST

Equipment description	Manufacturer/ Model	Identification No.	Current calibration date	Next calibration date
SAR Probe	SATIMO	SN 22/12 EP159	12/03/2014	12/02/2015
TISSUE Probe	SATIMO	SN 45/11 OCPG45	12/03/2014	12/02/2015
Phantom	SATIMO	SN_4511_SAM90	Validated. No cal required.	Validated. No cal required.
Liquid	SATIMO	-	Validated. No cal required.	Validated. No cal required.
Multimeter	Keithley 2000	1188656	03/06/2015	03/05/2016
Comm Tester	RTX 2012HS-RF	1239-6203	10/21/2014	10/20/2015
Dipole	SATIMO SID1900	SN46/11 DIP 1G900-187	11/14/2013	11/13/2016
Signal Generator	Agilent-E4438C	MY44260051	03/06/2015	03/05/2016
Power Sensor	NRP-Z23	US38261498	03/06/2015	03/05/2016
Spectrum Analyzer E4440	Agilent	US41421290	07/23/2015	07/22/2016
Network Analyzer	Rhode & Schwarz ZVL6	SN100132	03/06/2015	03/05/2016
Attenuator	Warison /WATT-6SR1211	N/A	N/A	N/A
Attenuator	Mini-circuits / VAT-10+	N/A	N/A	N/A
Amplifier	EM30180	SN060552	03/06/2015	03/05/2016
Directional Couple	Werlatone/ C6026-10	SN99482	07/29/2015	07/28/2016
Power Sensor	NRP-Z21	1137.6000.02	10/22/2014	10/21/2015
Power Viewer	R&S	V2.3.1.0	N/A	N/A

Note: Per KDB 865664 Dipole SAR Validation, AGC Lab has adopted 3 years calibration intervals. On annual basis, every measurement dipole has been evaluated and is in compliance with the following criteria:

1. There is no physical damage on the dipole;
2. System validation with specific dipole is within 10% of calibrated value;
3. Return-loss is within 20% of calibrated measurement;
4. Impedance is within 5Ω of calibrated measurement.

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10. MEASUREMENT UNCERTAINTY

SATIMO Uncertainty									
Measurement uncertainty for 300 MHz to 3 GHz averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+-%)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	Vi
Measurement System									
Probe calibration	E.2.1	7.0	N	1	1	1	6.98	6.98	∞
Axial Isotropy	E.2.2	2.5	R	$\sqrt{3}$	1	1	1.16	1.16	∞
Hemispherical Isotropy	E.2.2	4.0	R	$\sqrt{3}$	1	1	2.33	2.33	∞
Boundary effect	E.2.3	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Linearity	E.2.4	5.0	R	$\sqrt{3}$	1	1	2.87	2.87	∞
System detection limits	E.2.5	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Readout Electronics	E.2.6	0.02	N	1	1	1	0.03	0.03	∞
Response Time	E.2.7	3.0	R	$\sqrt{3}$	1	1	1.70	1.70	∞
Integration Time	E.2.8	2.0	R	$\sqrt{3}$	1	1	1.16	1.16	∞
RF ambient Conditions	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.71	1.71	∞
Probe positioner Mechanical Tolerance	E.6.2	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Probe positioning with respect to Phantom Shell	E.6.3	0.05	R	$\sqrt{3}$	1	1	0.03	0.03	∞
Extrapolation, interpolation and integration Algorithms for Max. SAR Evaluation	E.5.2	5.0	R	$\sqrt{3}$	1	1	2.91	2.91	∞
Test sample Related									
Test sample positioning	E.4.2.1	0.03	N	1	1	1	0.05	0.05	N-1
Device Holder Uncertainty	E.4.1.1	5.00	N	1	1	1	4.95	4.95	∞
Output power Variation - SAR drift measurement	6.6.2	0.65	R	$\sqrt{3}$	1	1	0.36	0.36	∞
Phantom and Tissue Parameters									
Phantom Uncertainty (Shape and thickness tolerances)	E.3.1	0.05	R	$\sqrt{3}$	1	1	0.02	0.02	∞
Liquid conductivity deviation from target value	E.3.2	5.00	R	$\sqrt{3}$	0.64	0.43	1.83	1.23	∞
Liquid conductivity - measurement uncertainty	E.3.3	5.00	N	1	0.64	0.43	3.18	2.14	∞
Liquid permittivity - deviation from target value	E.3.2	0.03	R	$\sqrt{3}$	0.6	0.49	0.01	0.01	∞
Liquid permittivity - measurement uncertainty	E.3.3	10.00	N	1	0.6	0.49	6.06	4.95	M
Combined Standard Uncertainty			RSS				11.17	10.63	∞
Expanded Uncertainty (95% Confidence interval)			k				22.34	21.26	

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SATIMO Uncertainty									
System uncertainty for 300 MHz to 3 GHz averaged over 1 gram / 10 gram.									
Uncertainty Component	Sec.	Tol (+ - %)	Prob. Dist.	Div.	Ci (1g)	Ci (10g)	1g Ui (+-%)	10g Ui (+-%)	Vi
Measurement System									
Probe calibration	E.2.1	7.0	N	1	1	1	6.98	6.98	∞
Axial Isotropy	E.2.2	2.5	R	$\sqrt{3}$	1	1	1.16	1.16	∞
Hemispherical Isotropy	E.2.2	4.0	R	$\sqrt{3}$	1	1	2.33	2.33	∞
Boundary Effects	E.2.3	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Linearity	E.2.4	5.0	R	$\sqrt{3}$	1	1	2.87	2.87	∞
System detection limits	E.2.5	1.0	R	$\sqrt{3}$	1	1	0.58	0.58	∞
Readout Electronics	E.2.6	0.02	N	1	1	1	0.03	0.03	∞
Response Time	E.2.7	3.0	R	$\sqrt{3}$	1	1	1.70	1.70	∞
Integration Time	E.2.8	2.0	R	$\sqrt{3}$	1	1	1.16	1.16	∞
RF ambient Conditions	E.6.1	3.0	R	$\sqrt{3}$	1	1	1.71	1.71	∞
Probe positioner Mechanical Tolerance	E.6.2	2.0	R	$\sqrt{3}$	1	1	1.15	1.15	∞
Probe positioning with respect to Phantom Shell	E.6.3	0.05	R	$\sqrt{3}$	1	1	0.03	0.03	∞
Extrapolation, interpolation and integration Algorithms for Max. SAR Evaluation	E.5.2	5.0	R	$\sqrt{3}$	1	1	2.91	2.91	∞
Dipole									
Dipole axis to liquid Distance	8,E.4.2	1.00	N	$\sqrt{3}$	1	1	0.55	0.55	N-1
Input power and SAR drift measurement	8,6.6.2	0.65	R	$\sqrt{3}$	1	1	0.36	0.36	∞
Phantom and Tissue Parameters									
Phantom Uncertainty (Shape and thickness tolerances)	E.3.1	0.05	R	$\sqrt{3}$	1	1	0.02	0.02	∞
Liquid conductivity - deviation from target value	E.3.2	5.00	R	$\sqrt{3}$	0.64	0.43	1.83	1.23	∞
Liquid conductivity - measurement uncertainty	E.3.3	5.00	N	1	0.64	0.43	3.18	2.14	∞
Liquid permittivity - deviation from target value	E.3.2	0.03	R	$\sqrt{3}$	0.6	0.49	0.01	0.01	∞
Liquid permittivity - measurement uncertainty	E.3.3	10.00	N	1	0.6	0.49	6.06	4.95	M
Combined Standard Uncertainty			RSS				10.03	9.42	
Expanded Uncertainty (95% Confidence interval)			k				20.05	18.85	

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11. CONDUCTED POWER MEASUREMENT

DECT BAND

Mode	Frequency (MHz)	Maximum Peak Conducted Power (dBm)
DECT	1921.536	19.12
	1924.992	19.05
	1928.448	19.09

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12. TEST RESULTS

12.1. SAR Test Results Summary

12.1.1. Test position and configuration

Head SAR was performed with the device configured in the positions according to IEEE 1528-2013, and Body SAR was performed with the device 5mm from the phantom.

12.1.2. Operation Mode

1. Per KDB 447498 D01 v05r02 ,for each exposure position, if the highest 1-g SAR is ≤ 0.8 W/kg, testing for low and high channel is optional.
2. Per KDB 865664 D01 v01r04, for each frequency band, if the measured SAR is ≥ 0.8 W/Kg, testing for repeated SAR measurement is required , that the highest measured SAR is only to be tested. When the SAR results are near the limit, the following procedures are required for each device to verify these types of SAR measurement related variation concerns by repeating the highest measured SAR configuration in each frequency band.
 - (1) When the original highest measured SAR is ≥ 0.8 W/Kg, repeat that measurement once.
 - (2) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/Kg.
 - (3) Perform a third repeated measurement only if the original, first and second repeated measurement is ≥ 1.5 W/Kg and ratio of largest to smallest SAR for the original, first and second measurement is ≥ 1.20 .
3. According to KDB 648474 D04 v01r02,when the reported SAR for a body-worn accessory measured without a headset connected to the handset is ≤ 1.2 W/Kg, SAR testing with a headset connected is not required.
4. Maximum Scaling SAR in order to calculate the Maximum SAR values to test under the standard Peak Power, Calculation method is as follows:
Maximum Scaling SAR =tested SAR (Max.) $\times$ [maximum turn-up power (mw)/ maximum measurement output power(mw)]

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12.1.3. Test Result

SAR MEASUREMENT									
Ambient Temperature (°C) : 21.9				Relative Humidity (%): 50.3					
Liquid Temperature (°C) : 21.6				Depth of Liquid (cm):>15					
Product: Cordless Phone									
Test Model: VVX D60									
Position	Mode	Ch.	Fr. (MHz)	Power Drift (<±0.2db)	SAR (1g) (W/kg)	Max. Turn-up Power (dBm)	Meas. output Power (dBm)	Scaled SAR (W/Kg)	Limit W/kg
Left Cheek	voice	2	1924.992	-0.04	0.021	21	19.05	0.033	1.6
Left Tilt	voice	2	1924.992	0.13	0.013	21	19.05	0.020	1.6
Right Cheek	voice	2	1924.992	0.08	0.021	21	19.05	0.033	1.6
Right Tilt	voice	2	1924.992	0.00	0.009	21	19.05	0.014	1.6
Body Back	voice	2	1924.992	--	<0.0015 note⁽²⁾	--	--	--	1.6
Body Front	voice	2	1924.992	-0.09	0.016	21	19.05	0.025	1.6

Note:

- (1). When the 1-g Reported SAR is ≤ 0.8 W/kg, testing for low and high channel is optional. Refer to KDB 447498.
- (2) Due the power of body back mode is so low, it is side out SAR value; and communication normal during test.

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APPENDIX A. SAR SYSTEM CHECK DATA

Test Laboratory: AGC Lab

Date: July 31, 2015

System Check Head 1900MHz

DUT: Dipole 1900 MHz; Type: SID 1900

Communication System: CW; Communication System Band: D1900 (1900.0 MHz); Duty Cycle:1:1; Conv.F=4.31

Frequency: 1900 MHz; Medium parameters used: $f = 1900$ MHz; $\sigma = 1.38$ mho/m; $\epsilon_r = 40.08$; $\rho = 1000$ kg/m³ ;

Phantom section: Flat Section; Input Power=18dBm

Ambient temperature (°C):21.9, Liquid temperature (°C):21.6

SATIMO Configuration:

Probe: SSE5; Calibrated: 12/03/2014; Serial No.: SN 22/12 EP159

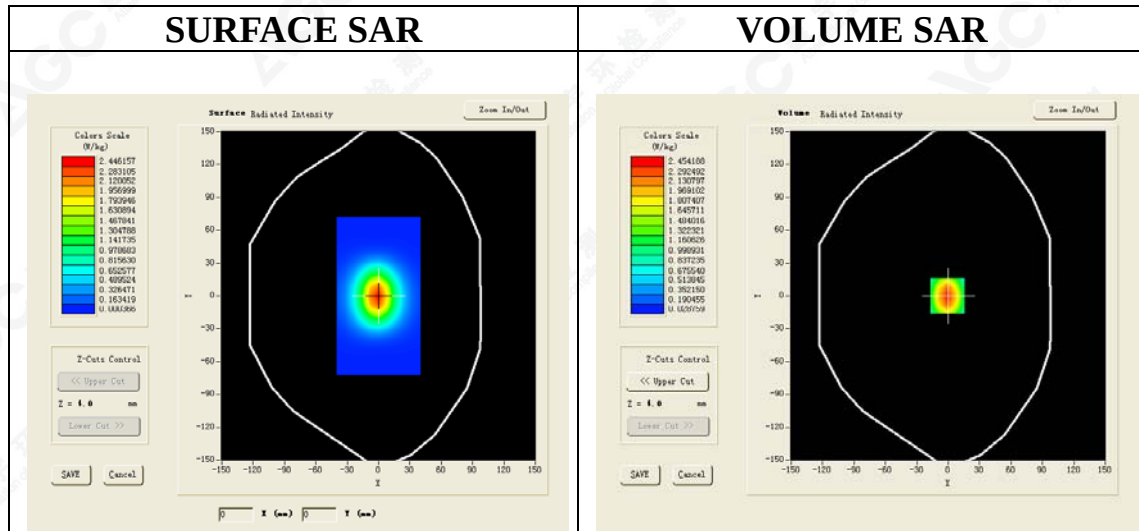
Sensor-Surface: 4mm (Mechanical Surface Detection)

Phantom: SAM twin phantom

Measurement SW: OpenSAR V4_02_01

Configuration/System Check 1900 Head/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/System Check 1900 Head/Zoom Scan: Measurement grid: dx=8mm, dy=8mm, dz=5mm



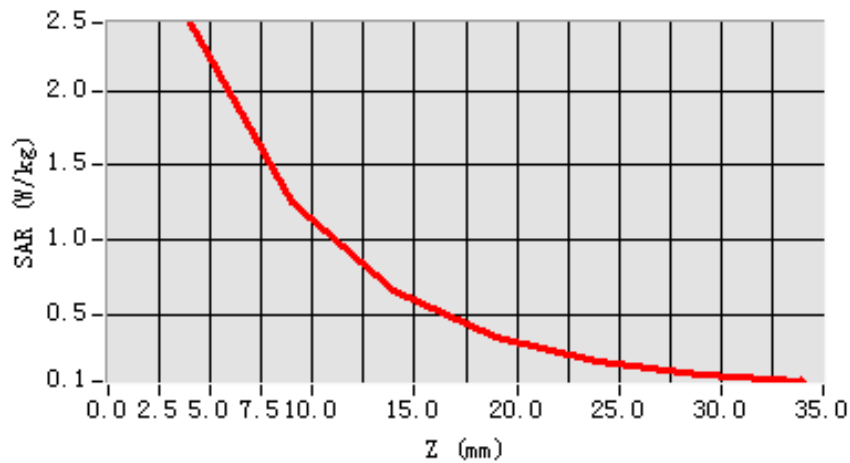
Maximum location: X=-1.00, Y=0.00

SAR 10g (W/Kg)	1.189655
SAR 1g (W/Kg)	2.327348

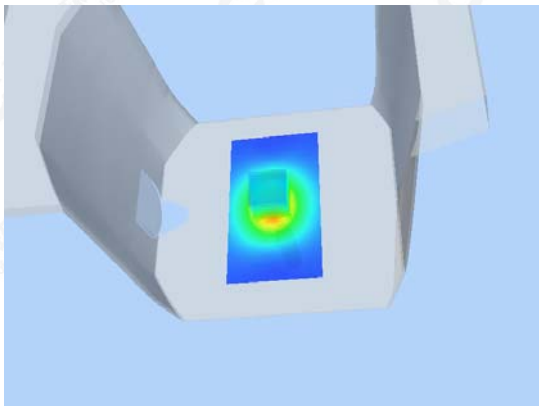
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Z (mm)	0.00	4.00	9.00	14.00	19.00	24.00	29.00
SAR (W/Kg)	0.0000	2.4540	1.2573	0.6646	0.3525	0.1918	0.1031

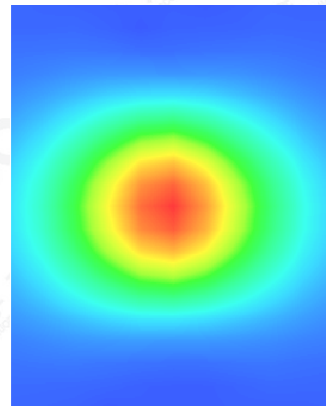
SAR, Z Axis Scan (X = -1, Y = 0)



3D screen shot



Hot spot position



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Test Laboratory: AGC Lab
System Check Body 1900MHz
DUT: Dipole 1900 MHz; Type: SID 1900

Date: July 31,2015

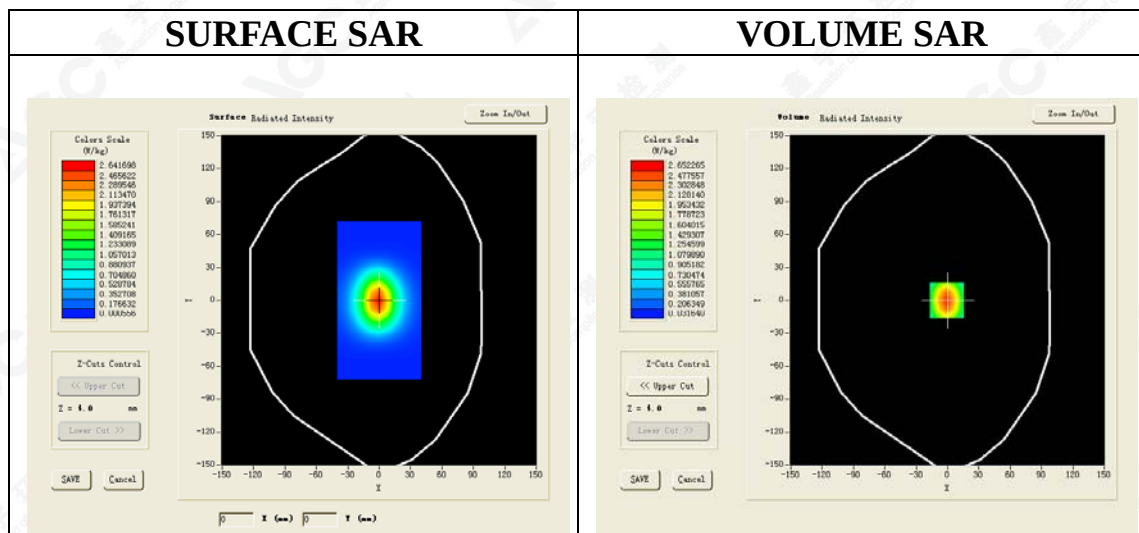
Communication System: CW; Communication System Band: D1900 (1900.0 MHz); Duty Cycle:1:1; Conv.F=4.17
Frequency: 1900 MHz; Medium parameters used: $f = 1900$ MHz; $\sigma = 1.51$ mho/m; $\epsilon_r = 53.71$; $\rho = 1000$ kg/m³ ;
Phantom section: Flat Section; Input Power=18dBm
Ambient temperature (°C):21.9, Liquid temperature (°C):21.7

SATIMO Configuration:

Probe: SSE5; Calibrated: 12/03/2014; Serial No.: SN 22/12 EP159
Sensor-Surface: 4mm (Mechanical Surface Detection)
Phantom: SAM twin phantom
Measurement SW: OpenSAR V4_02_01

Configuration/System Check 1900 Body/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/System Check 1900 Body/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm



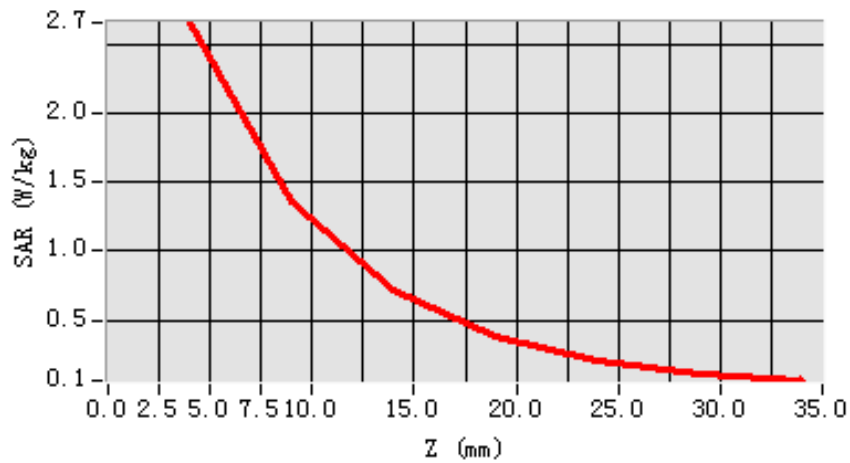
Maximum location: X=-1.00, Y=0.00

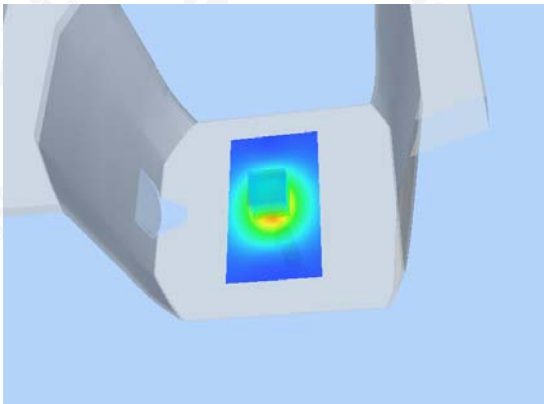
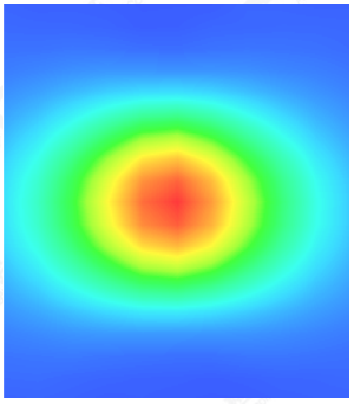
SAR 10g (W/Kg)	1.270023
SAR 1g (W/Kg)	2.518611

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Z (mm)	0.00	4.00	9.00	14.00	19.00	24.00	29.00
SAR (W/Kg)	0.0000	2.6511	1.3518	0.7131	0.3786	0.2041	0.1108

SAR, Z Axis Scan (X = -1, Y = 0)



3D screen shot	Hot spot position
	

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APPENDIX B. SAR MEASUREMENT DATA

Test Laboratory: AGC Lab

1900MHz Mid-Touch- Left

DUT: Cordless Phone Type: VVX D60

Date: July 31,2015

Communication System: DECT; Communication System Band: 1900; Duty Cycle: 1:12, Conv.F=4.31; Frequency: 1924.992 MHz; Medium parameters used: $f = 1900$ MHz; $\sigma = 1.38$ mho/m; $\epsilon_r = 40.08$; $\rho = 1000$ kg/m³ ;
Phantom section: Right Section
Ambient temperature (°C):21.9, Liquid temperature (°C):21.6

SATIMO Configuration:

Probe: SSE5; Calibrated: 12/03/2014; Serial No.: SN 22/12 EP159

Sensor-Surface: 4mm (Mechanical Surface Detection)

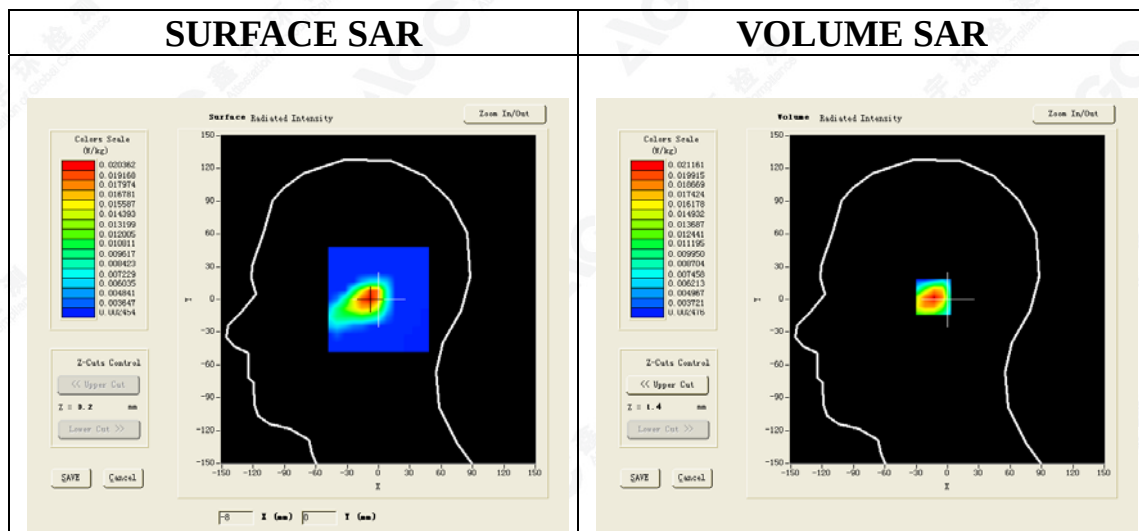
Phantom: SAM twin phantom

Measurement SW: OpenSAR V4_02_01

Configuration/1900 MHz-Touch-Left/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/1900 MHz-Touch-Left/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm;

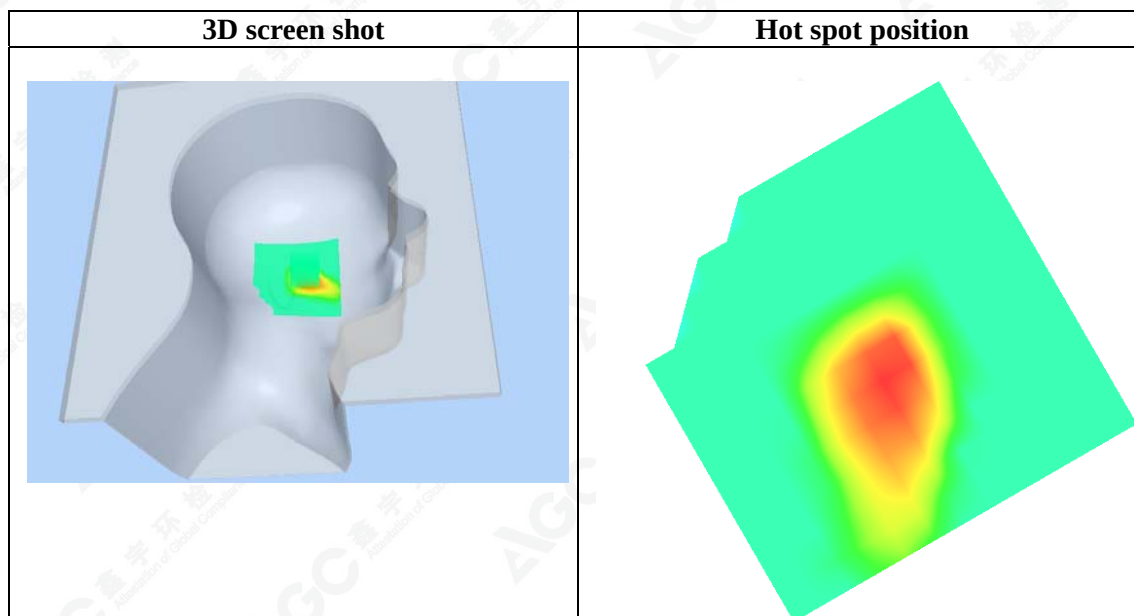
Area Scan	sam_direct_droit2_surf8mm.txt
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Phantom	Left head
Device Position	Cheek
Band	DECT
Channels	Middle
Signal	Crest factor: 12.0



Maximum location: X=-8.00, Y=2.00

SAR 10g (W/Kg)	0.009175
SAR 1g (W/Kg)	0.020782

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Test Laboratory: AGC Lab
1900 MHz Mid-Tilt-Left
DUT: Cordless Phone Type: VVX D60

Date: July 31,2015

Communication System: DECT; Communication System Band: 1900; Duty Cycle: 1:12, Conv.F=4.31; Frequency: 1924.992 MHz; Medium parameters used: $f = 1900$ MHz; $\sigma = 1.38$ mho/m; $\epsilon_r = 40.08$; $\rho = 1000$ kg/m³ ;
Phantom section: Right Section
Ambient temperature (°C):21.9, Liquid temperature (°C):21.6

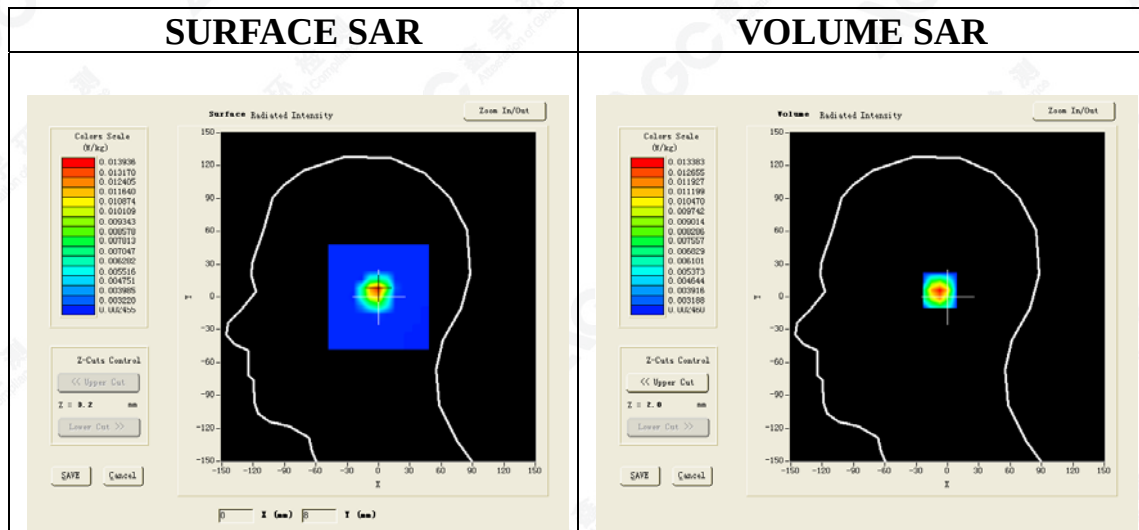
SATIMO Configuration:

Probe: SSE5; Calibrated: 12/03/2014; Serial No.: SN 22/12 EP159
Sensor-Surface: 4mm (Mechanical Surface Detection)
Phantom: SAM twin phantom
Measurement SW: OpenSAR V4_02_01

Configuration/1900 MHz-Tilt-Left/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/1900 MHz-Tilt-Left/Zoom Scan: Measurement grid: dx=8mm, dy=8mm,dz=5mm;

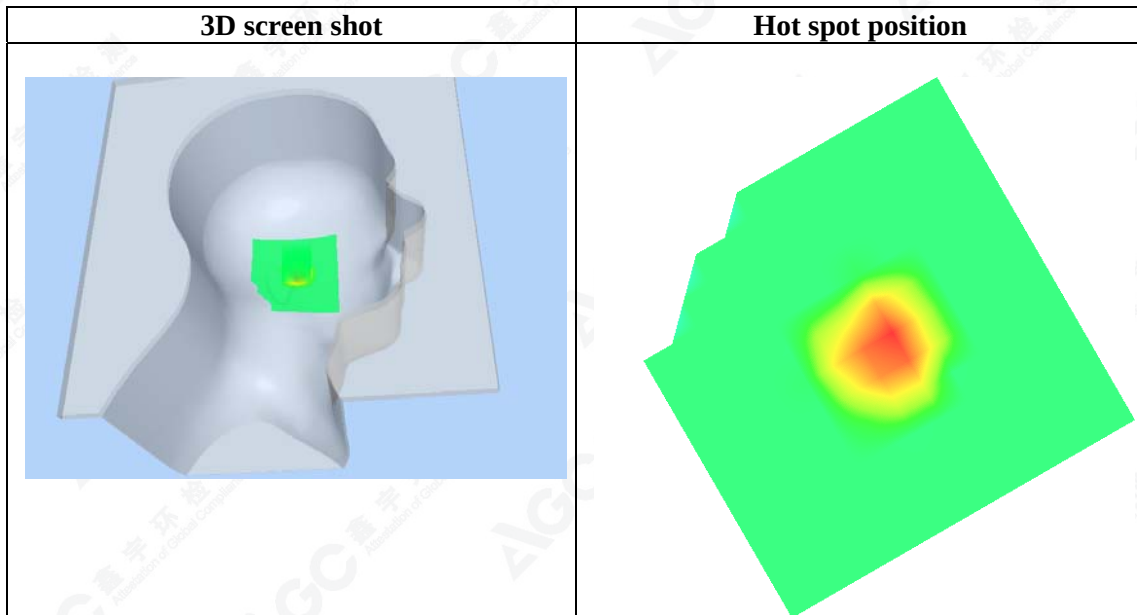
Area Scan	sam_direct_droit2_surf8mm.txt
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Phantom	Left head
Device Position	Tilt
Band	DECT
Channels	Middle
Signal	Crest factor: 12.0



Maximum location: X=-1.00, Y=6.00

SAR 10g (W/Kg)	0.005838
SAR 1g (W/Kg)	0.013017

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Test Laboratory: AGC Lab
1900 MHz Mid-Touch-Right
DUT: Cordless Phone Type: VVX D60

Date: July 31,2015

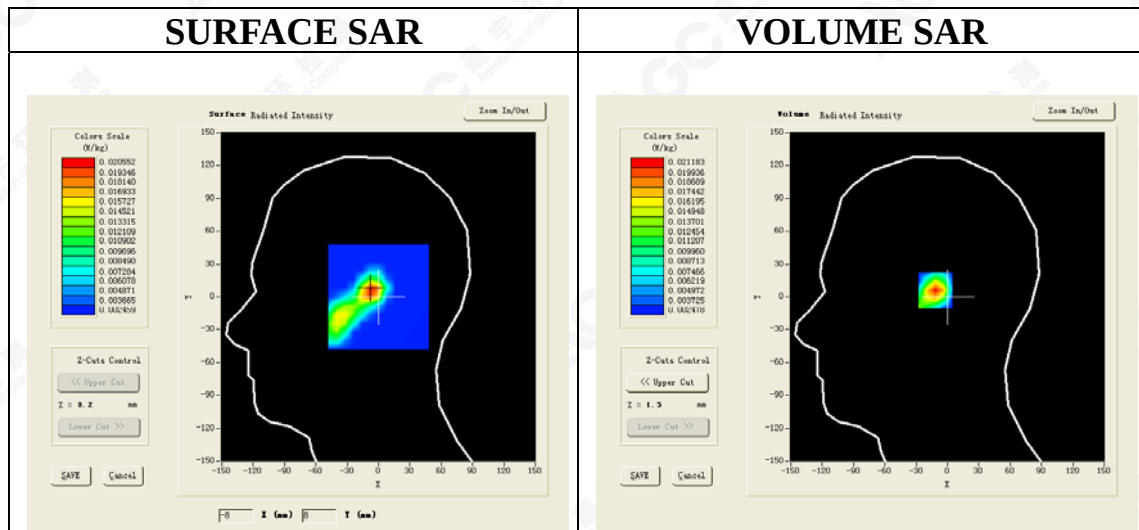
Communication System: DECT; Communication System Band: 1900; Duty Cycle: 1:12, Conv.F=4.31; Frequency: 1924.992 MHz; Medium parameters used: $f = 1900$ MHz; $\sigma = 1.38$ mho/m; $\epsilon_r = 40.08$; $\rho = 1000$ kg/m³ ;
Phantom section: Right Section
Ambient temperature (°C):21.9, Liquid temperature (°C):21.6

SATIMO Configuration:

Probe: SSE5; Calibrated: 12/03/2014; Serial No.: SN 22/12 EP159
Sensor-Surface: 4mm (Mechanical Surface Detection)
Phantom: SAM twin phantom
Measurement SW: OpenSAR V4_02_01

Configuration/1900 MHz-Touch-Right/Area Scan: Measurement grid: dx=8mm, dy=8mm
Configuration/1900 MHz-Touch-Right/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm;

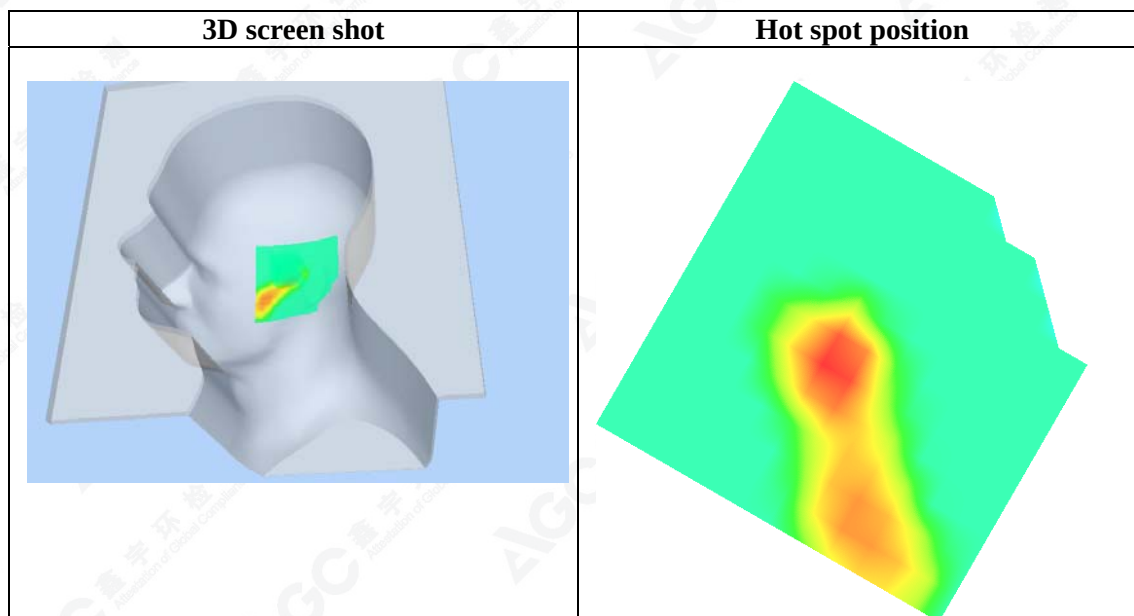
Area Scan	sam_direct_droit2_surf8mm.txt
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Phantom	Right head
Device Position	Cheek
Band	DECT
Channels	Middle
Signal	Crest factor: 12.0



Maximum location: X=-7.00, Y=6.00

SAR 10g (W/Kg)	0.008763
SAR 1g (W/Kg)	0.021224

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Test Laboratory: AGC Lab
1900 MHz Mid-Tilt-Right
DUT: Cordless Phone Type: VVX D60

Date: July 31,2015

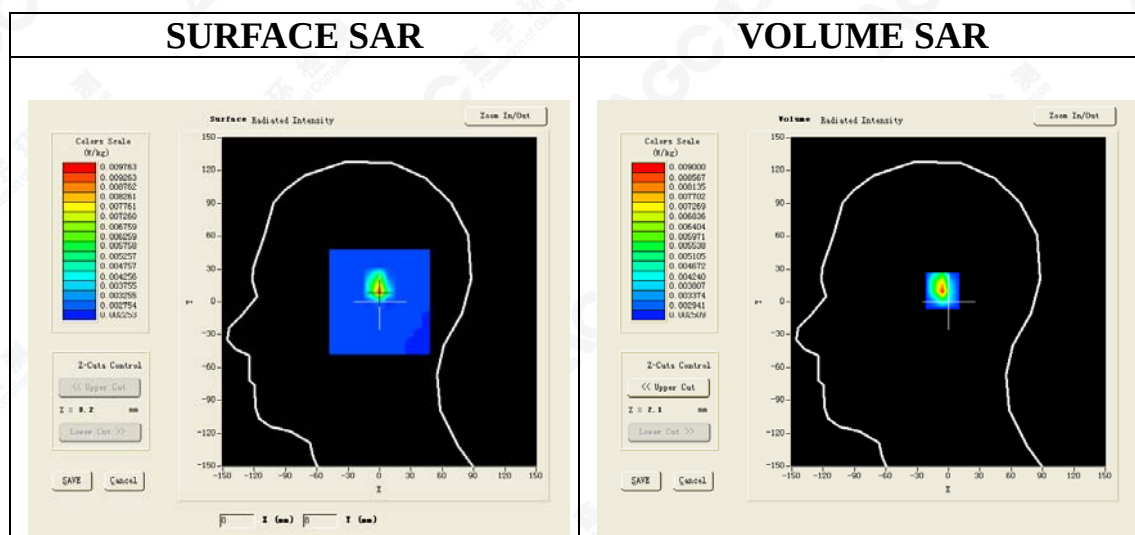
Communication System: DECT; Communication System Band: 1900; Duty Cycle: 1:12, Conv.F=4.31; Frequency: 1924.992 MHz; Medium parameters used: $f = 1900$ MHz; $\sigma = 1.38$ mho/m; $\epsilon_r = 40.08$; $\rho = 1000$ kg/m³ ;
Phantom section: Right Section
Ambient temperature (°C):21.9, Liquid temperature (°C):21.6

SATIMO Configuration:

Probe: SSE5; Calibrated: 12/03/2014; Serial No.: SN 22/12 EP159
Sensor-Surface: 4mm (Mechanical Surface Detection)
Phantom: SAM twin phantom
Measurement SW: OpenSAR V4_02_01

Configuration/1900 MHz-Tilt-Right/Area Scan: Measurement grid: dx=8mm, dy=8mm
Configuration/1900 MHz-Tilt-Right/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm;

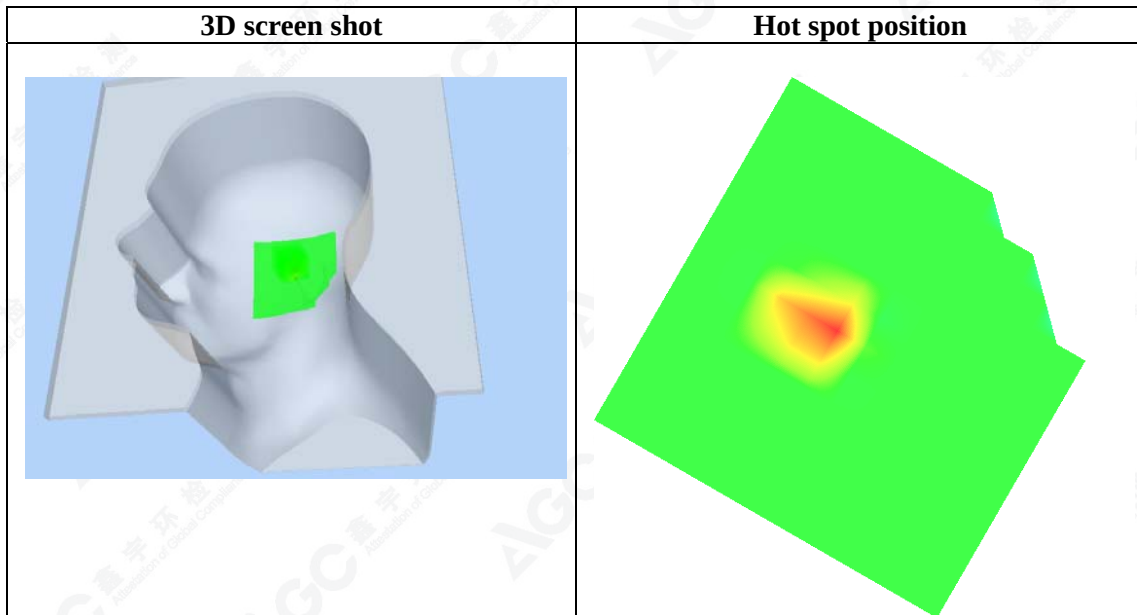
Area Scan	sam_direct_droit2_surf8mm.txt
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Phantom	Right head
Device Position	Tilt
Band	DECT
Channels	Middle
Signal	Crest factor: 12.0



Maximum location: X=0.00, Y=10.00

SAR 10g (W/Kg)	0.004108
SAR 1g (W/Kg)	0.008844

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Test Laboratory: AGC Lab
1900 MHz Mid-Body-front
DUT: Cordless Phone Type: VVX D60

Date: July 31,2015

Communication System: DECT; Communication System Band: 1900; Duty Cycle: 1:12, Conv.F=4.17; Frequency: 1924.992 MHz; Medium parameters used: $f = 1900$ MHz; $\sigma = 1.51$ mho/m; $\epsilon_r = 53.71$; $\rho = 1000$ kg/m³ ;
Phantom section: Flat Section
Ambient temperature (°C):21.9, Liquid temperature (°C):21.7

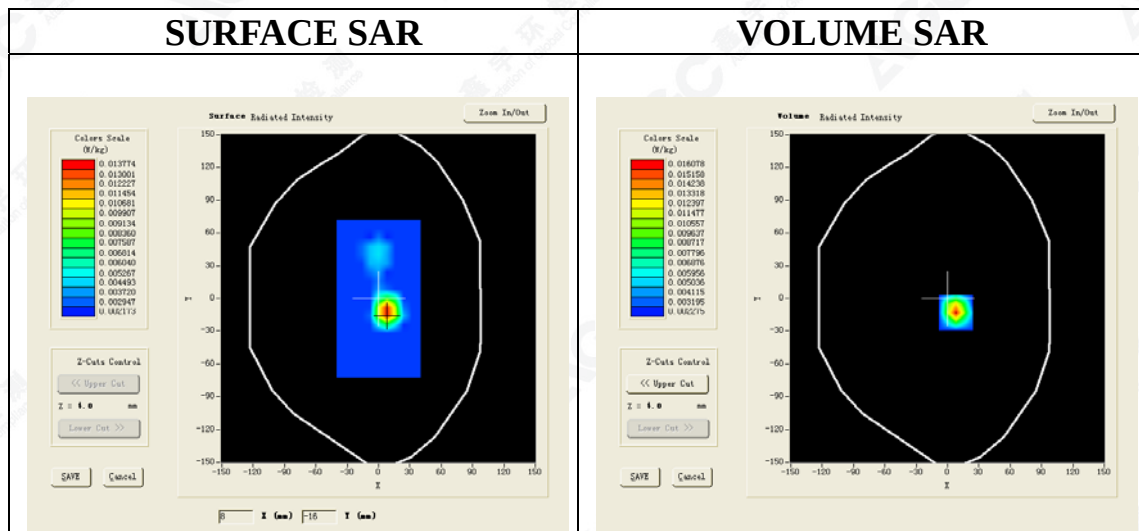
SATIMO Configuration:

Probe: SSE5; Calibrated: 12/03/2014; Serial No.: SN 22/12 EP159
Sensor-Surface: 4mm (Mechanical Surface Detection)
Phantom: SAM twin phantom
Measurement SW: OpenSAR V4_02_01

Configuration/1900 MHz-Body-front/Area Scan: Measurement grid: dx=8mm, dy=8mm

Configuration/1900 MHz- Body-front/Zoom Scan: Measurement grid: dx=8mm,dy=8mm, dz=5mm;

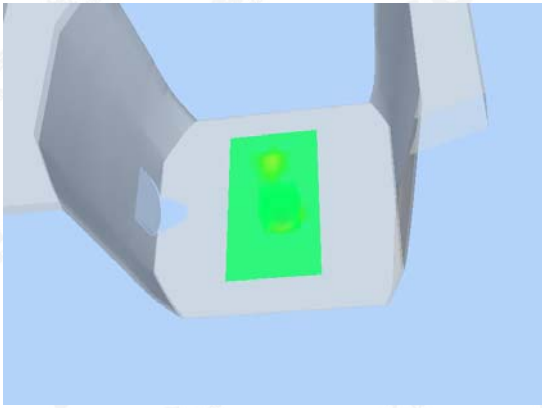
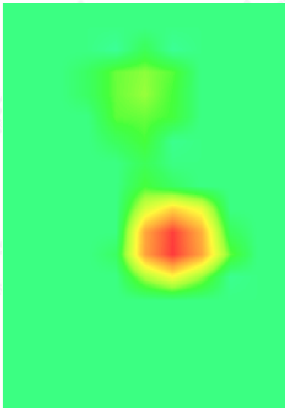
Area Scan	sam_direct_droit2_surf8mm.txt
Zoom Scan	5x5x7,dx=8mm dy=8mm dz=5mm
Phantom	Validation plane
Device Position	Body Front
Band	DECT
Channels	Middle
Signal	Crest factor: 12.0



Maximum location: X=8.00, Y=-13.00

SAR 10g (W/Kg)	0.006429
SAR 1g (W/Kg)	0.016350

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3D screen shot	Hot spot position
	

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APPENDIX C. TEST SETUP PHOTOGRAPHS & EUT PHOTOGRAPHS

Refer to Attached files.

APPENDIX D. CALIBRATION DATA

Refer to Attached files.

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