



**ELECTRONIC TECHNOLOGY SYSTEMS  
DR. GENZ GMBH**

# **TEST - REPORT**

**SAR Compliance Test Report**

**Test report no.:**

**U9M20306-4895-S-8**

# **SAR**

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# 1 General Information

## 1.1 Notes

The purpose of conformity testing is to increase the probability of adherence to the essential requirements or conformity specifications, as appropriate.

The complexity of the technical specifications, however, means that full and thorough testing is impractical for both technical and economic reasons.

Furthermore, there is no guarantee that a test sample which has passed all the relevant tests conforms to a specification.

The existence of the tests nevertheless provides the confidence that the test sample possesses the qualities as maintained and that its performance generally conforms to representative cases of communications equipment.

The test results of this test report relate exclusively to the item tested as specified in 1.5.

The test report may only be reproduced or published in full.

Reproduction or publication of extracts from the report requires the prior written approval of the ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH.

I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualification of all persons taking them.

### Tester:

02.07.2003

N. Kaspar

A handwritten signature in black ink, appearing to read 'i.A. J. Genz'.

Date

ETS-Lab.

Name

Signature

### Technical responsibility for area of testing:

02.07.2003

Dr. Genz

A handwritten signature in black ink, appearing to read 'i.A. Genz'.

Date

ETS-Lab.

Name

Signature

## 1.2 Testing laboratory

### 1.2.1 Location

ELECTRONIC TECHNOLOGY SYSTEM DR. GENZ GMBH (ETS)

Storkower Straße 38c

D-15526 Reichenwalde b. Berlin

Germany

Telephone : +49 33631 888 00

Fax : +49 33631 888 660

### 1.2.2 Details of accreditation status

#### ACCREDITED TESTING LABORATORY

DAR-REGISTRATION NUMBER: TTI-P-G 126/96

FCC FILED TEST LABORATORY REG. No. 96970

#### BLUETOOTH QUALIFICATION TEST FACILITY (BQTF)

ACCREDITED BY BLUETOOTH QUALIFICATION REVIEW BOARD

INDUSTRY CANADA FILED TEST LABORATORY REG. No. IC 3470

A2LA ACCREDITED Certificate Number 1983-01

## 1.3 Details of approval holder

|           |                                          |
|-----------|------------------------------------------|
| Name      | : HHP NC                                 |
| Street    | : 7520 East Independent Blvd., Suite 230 |
| Town      | : Charlotte, NC 28227                    |
| Country   | : U.S.A.                                 |
| Telephone | : +1 315 685 2931                        |
| Fax       | :                                        |
| Contact   | : Mr. Naveen Velagapudi                  |
| Telephone | : +1 315 685 2931                        |

## 1.4 Manufacturer: (if applicable)

|         |   |
|---------|---|
| Name    | : |
| Street  | : |
| Town    | : |
| Country | : |

## 1.5 Application details

Date of receipt of application : 18.06.2003  
Date of receipt of test item : 18.06.2003  
Date of test : 23.06.2003 - 24.06.2003

## 1.6 Test item

FCC ID : HD5950003  
Description of test item : Dolphin 9500 with 802.11b Radio  
Type identification : D9500-03  
Serial number : without; Identical prototype  
Device category : DTS (Digital Transmission System)

## Technical data

TX / RX Frequency range : 2400,0 - 2483,5 MHz  
Tested Frequency : Ch.1 2412,0 MHz  
: Ch.6 2437,0 MHz  
: Ch.11 2462,0 MHz  
Max. Conducted RF output power : 17,75 dBm (59,6 mW)  
Power supply : 7,4 V DC rechargeable battery  
Antenna Tx : integral  
Antenna RX : integral  
Additional information : Tx and Rx. antenna are the same.

## 1.7 Test Results

Max. SAR Measurement : 0.299 W/kg (averaged over 1 gram)

This EUT has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in FCC/OET Bulletin 65 Supplement C (2001) and IEEE Std. 1528-200X (Draft 6.5, January 2002).

**FORMULARDROPDOWN1.8 Test standards**

Standards : - IEEE Std. 1528-200X (Draft 6.5, January 2002)

FCC Rule Part(s) : - FCC OET Bulletin 65, Supplement C, Edition 01-01

**2 Technical test****2.1 Summary of test results**

EUT complies with the RF radiation exposure limits of the FCC as shown by the SAR measurement results. These measurements are taken to simulate the RF effects exposure under worst-case conditions. The EUT complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (e.g. age, gender, activity level, debilitation, or disease). Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables. [1]

**2.2 Test environment**

Room temperature : 22,2 -22,6 ° C

Liquid Temperature: : 22,1-22,4 ° C

Relative humidity content : 20 ... 75 %

Air pressure : 86 ... 103 k P a

Details of power supply : 7,4 V DC

## 2.3 Test equipment utilized

| No.       | Measurement device:                  | Type:              | Manufacturer:    |
|-----------|--------------------------------------|--------------------|------------------|
| ETS 0253  | Spectrum analyzer                    | FSIQ 26            | Rohde & Schwarz  |
| ETS 0449  | Stäubli Robot                        | RX90B L            | Stäubli          |
| ETS 0450  | Stäubli Robot Controller             | CS/MBs&p           | Stäubli          |
| ETS 0451  | DASY 4 Measurement Server            |                    | Schmid & Partner |
| ETS 0452  | Control Pendant                      |                    | Stäubli          |
| ETS 0453  | Compaq Computer                      | Pentium IV, 2 GHz, | Schmid & Partner |
| ETS 0454  | Dabu Acquisition Electronics         | DAE3V1             | Schmid & Partner |
| ETS 0455  | Dummy Probe                          |                    | Schmid & Partner |
| ETS 0456  | Dosimetric E-Field Probe             | ET3DV6             | Schmid & Partner |
| ETS 0457  | Dosimetric E-Field Probe             | ET3DV6             | Schmid & Partner |
| ETS 0458  | Dosimetric H-Field Probe             | H3DV6              | Schmid & Partner |
| ETS 0459  | System Validation Kit                | D900V2             | Schmid & Partner |
| ETS 0460  | System Validation Kit                | D1800V2            | Schmid & Partner |
| ETS 0461  | System Validation Kit                | D1900V2            | Schmid & Partner |
| ETS 0462  | System Validation Kit                | D2450V2            | Schmid & Partner |
| ETS 0463  | Probe Alignment Unit                 | LBV2               | Schmid & Partner |
| ETS 0464  | SAM Twin phantom                     | V 4.0              | Schmid & Partner |
| ETS 0465  | Mounting Device                      | V 3.1              | Schmid & Partner |
| ETS 0224a | Millivoltmeter                       | URV 5              | Rohde & Schwarz  |
| ETS 0219  | Power sensor                         | NRV-Z2             | Rohde & Schwarz  |
| ETS 0268  | RF signal generator                  | SMP 02             | Rohde & Schwarz  |
| ETS 0322  | Insertion unit                       | URV5-Z4            | Rohde & Schwarz  |
| ETS 0466  | Directional Coupler                  | HP 87300B          | HP               |
| ETS0231   | Radio Communication Tester           | CMD65              | Rohde & Schwarz  |
| ETS 0467  | Universal Radio Communication Tester | CMU 200            | Rohde & Schwarz  |
| ETS 0468  | Network Analyzer 300 kHz to 3 GHz    | 8753C              | Agilent          |
| ETS 0469  | Dielectric Probe Kit                 | 85070C             | Agilent          |

## 2.4 Definitions

### 2.4.1 SAR

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy ( $dW$ ) absorbed by (dissipated in) an incremental mass ( $dm$ ) contained in a volume element ( $dV$ ) of a given density ( $\rho_t$ ), expressed in watts per kilogram (W/kg)

$$\text{SAR} = \frac{d}{dt} \left( \frac{dW}{dm} \right) = \frac{d}{dt} \left( \frac{dW}{\rho_t dV} \right) = \frac{\sigma}{\rho_t} |E_t|^2$$

where:

$$\frac{dW}{dt} = \int_v E \cdot J \, dV = \int_v \sigma E^2 \, dV$$

### 2.4.2 Uncontrolled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category, and the general population/uncontrolled exposure limits apply to these devices. [2]

### 2.4.2 Controlled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on the risk of potential exposure and instructions on methods to minimize such exposure risks. [2]

## 2.5 Measurement System Description

### 2.5.1 System Setup

Measurements are performed using the DASY4 automated dosimetric assessment system (figure 1) made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland.



Figure 1

The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- An unit to operate the optical surface detector which is connected to the EOC.
- The Electro-optical converter (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the measurement server.
- The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows NT.
- DASY4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes (see Application Notes).
- System validation dipoles allowing to validate the proper functioning of the system.

## 2.5.2 Phantom Description



Figure 2

The SAM twin phantom V4.0 (figure 2) is a fiberglass shell phantom with 2 mm shell thickness. It has three measurement areas:

- Left hand
- Right hand
- Flat phantom

The phantom is integrated in a wooden table.

The bottom plate of the table contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids).

A cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible.

On the phantom top, three reference markers are provided to identify the phantom positions with respect to the robot.

## 2.5.3 Tissue Simulating Liquids

The parameters of the tissue simulating liquid strongly influence the SAR. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE P1528-200X).

Tissue dielectric properties

|                 | Head                                          |                                 | Body                                          |                                 |
|-----------------|-----------------------------------------------|---------------------------------|-----------------------------------------------|---------------------------------|
| Frequency (MHz) | Relative Dielectric Constant ( $\epsilon_r$ ) | Conductivity ( $\sigma$ ) (S/m) | Relative Dielectric Constant ( $\epsilon_r$ ) | Conductivity ( $\sigma$ ) (S/m) |
| 300             | 45.3                                          | 0.87                            | 58.2                                          | 0.92                            |
| 450             | 43.5                                          | 0.87                            | 56.7                                          | 0.94                            |
| 835             | 41.5                                          | 0.90                            | 55.2                                          | 0.97                            |
| 900             | 41.5                                          | 0.97                            | 55.0                                          | 1.05                            |
| 1450            | 40.5                                          | 1.20                            | 54.0                                          | 1.30                            |
| 1800            | 40.0                                          | 1.40                            | 53.3                                          | 1.52                            |
| 1900            | 40.0                                          | 1.40                            | 53.3                                          | 1.52                            |
| 2000            | 40.0                                          | 1.40                            | 53.3                                          | 1.52                            |
| 2450            | 39.2                                          | 1.80                            | 52.7                                          | 1.95                            |
| 3000            | 38.5                                          | 2.40                            | 52.0                                          | 2.73                            |

## 2.5.4 Device Holder

The DASY device holder (figure 3.1 and 3.2) is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The rotation centers for both scales is the ear opening. Thus the device needs no repositioning when changing the angles.



Figure 3.1



Figure 3.2

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity  $\epsilon = 3$  and loss tangent  $\delta = 0.02$ . The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

## 2.5.5 Probes

The SAR measurements were conducted with the dosimetric probe ET3DV6 (figure 4), designed in the classical triangular configuration and optimized for dosimetric evaluation. [3] The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2<sup>nd</sup> order fitting. The approach is stopped at reaching the maximum.



Figure 4

## Probe Specifications

|                |                                                                                                                                                                                              |
|----------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Calibration:   | In air from 10 MHz to 2.5 GHz<br>In brain and muscle simulating tissue at Frequencies of 835 MHz, 900 MHz, 1800 MHz, 1900 MHz and 2450 MHz<br>Calibration certificates please find attached. |
| Frequency:     | 10 MHz to > 3 GHz; Linearity: $\pm 0.2$ dB (30 MHz to 3 GHz)                                                                                                                                 |
| Directivity:   | $\pm 0.2$ dB in HSL (rotation around probe axis)<br>$\pm 0.4$ dB in HSL (rotation normal probe axis)                                                                                         |
| Dynamic Range: | 5 $\mu$ W/g to > 100 mW/g;                                                                                                                                                                   |
| Linearity:     | $\pm 0.2$ dB                                                                                                                                                                                 |
| Dimensions:    | Overall length: 330 mm<br>Tip length: 16 mm<br>Body diameter: 12 mm<br>Tip diameter: 6.8 mm<br>Distance from probe tip to dipole centers: 2.7 mm                                             |
| Application:   | General dosimetry up to 3 GHz<br>Compliance tests of mobile phones<br>Fast automatic scanning in arbitrary phantoms                                                                          |

## 2.6 Test System Specification

### Positioner

|                |                                              |
|----------------|----------------------------------------------|
| Robot:         | Stäubli Animation Corp. Robot Model: RX90B L |
| Repeatability: | 0.02 mm                                      |
| No. of axis:   | 6                                            |

### Data Acquisition Electronic (DAE) System

#### Cell Controller

|                   |                                                                                     |
|-------------------|-------------------------------------------------------------------------------------|
| Processor:        | Pentium IV                                                                          |
| Clock Speed:      | 2.0 GHz                                                                             |
| Operating System: | Windows 2000                                                                        |
| Data Card:        | DASY4 PC-Board                                                                      |
| Data Converter    |                                                                                     |
| Features:         | Signal Amplifier, multiplexer, A/D converter, & control logic                       |
| Software:         | DASY4 software                                                                      |
| Connecting Lines: | Optical downlink for data and status info.<br>Optical uplink for commands and clock |

### PC Interface Card

|           |                                                                                                                                                                                     |
|-----------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Function: | 24 bit (64 MHz) DSP for real time processing<br>Link to DAE3<br>16 bit A/D converter for surface detection system<br>serial link to robot<br>direct emergency stop output for robot |
|-----------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

**E-Field Probes**

|               |                                              |
|---------------|----------------------------------------------|
| Model:        | ET3DV6 SN1711                                |
| Construction: | Triangular core fiber optic detection system |
| Frequency:    | 10 MHz to 6 GHz                              |
| Linearity:    | $\pm 0.2$ dB (30MHz to 3 GHz)                |

**Phantom**

|                 |                         |
|-----------------|-------------------------|
| Phantom:        | SAM Twin Phantom (V4.0) |
| Shell Material: | Fiberglass              |
| Thickness:      | $2.0 \pm 0.2$ mm        |

**2.7 Measurement Procedure**

The evaluation was performed using the following procedure:

1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing. This fixed location point was measured and used as a reference value.
2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 10mm x 10mm.
3. Based on the area scan data, the area of the maximum absorption was determined by spline interpolation. Around this point, a volume of 30mm x 30mm x 30mm (fine resolution volume scan, zoom scan) was assessed by measuring 5 x 5 x 5 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure:
  - a. The data at the surface was extrapolated, since the center of the dipoles is 2.7mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2mm. The extrapolation was based on a least square algorithm [4]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
  - b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the "Not a knot" condition (in x, y, and z directions) [4] [5]. The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
  - c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
4. The SAR reference value, at the same location as procedure #1, was remeasured. If the value changed by more than 5%, the evaluation is repeated.

## 2.8 Reference Points

### 2.8.1 Ear Reference Points

Figure 5.1 shows the front, back and side views of SAM. The point "M" is the reference point for the center of mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15 mm posterior to the entrance to ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 5.2. The plane passing through the two ear reference points and M is defined as the Reference Plane. The line N-F (Neck-Front) perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 5.3). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines should be marked on the external phantom shell to facilitate handset positioning. Posterior to the N-F line, the thickness of the N-F line, the ear is truncated as illustrated in Figure 5.2. The ear truncation is introduced to avoid the handset from touching the ear lobe, which can cause unstable handset positioning at the cheek. [6]

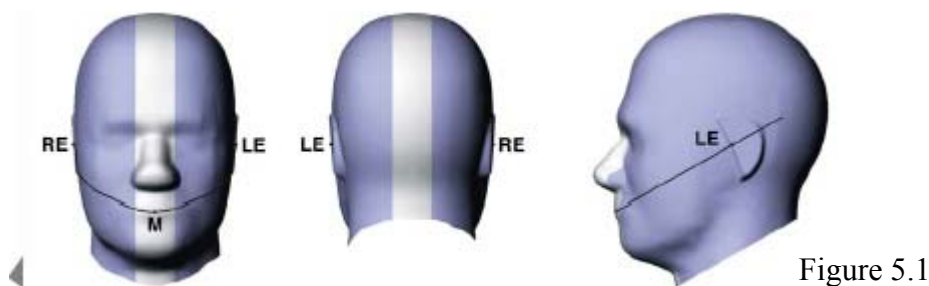


Figure 5.1

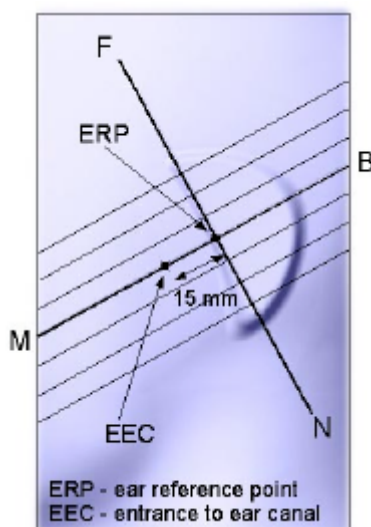


Figure 5.2

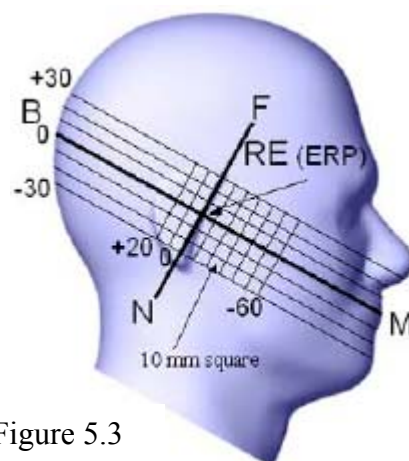


Figure 5.3

## 2.8.2 Handset Reference Points

Two imaginary lines on the handset were defined: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width  $w_t$  of the handset at the level of the acoustic output (point A on Figures 6.1 and 6.2), and the midpoint of the width  $w_b$  of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 6.1). The two lines intersect at point A. For many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. The vertical centerline is not necessarily parallel to the front face of the handset (see Figure 6.2), especially for clamshell handsets, handsets with flip pieces, and other irregularly-shaped handsets. [6]

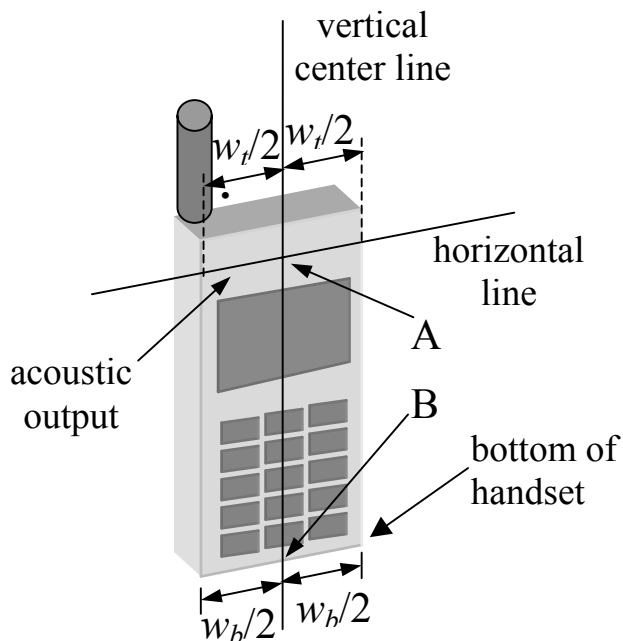


Figure 6.1

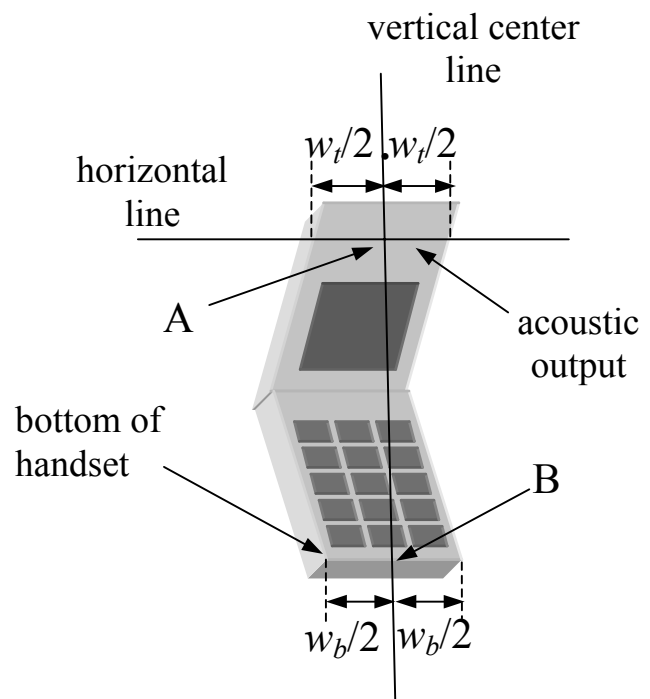


Figure 6.2

## 2.9 Test Positions

### 2.9.1 "Cheek" / "Touch" Position

The EUT was positioned close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 7), such that the plane defined by the vertical center line and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.

The EUT was translated towards the phantom along the line passing through RE and LE until the handset touches the pinna.

While maintaining the handset in this plane, the EUT was rotated it around the LE-RE line until the vertical centerline was in the plane normal to MB-NF including the line MB (called the reference plane).

The EUT was rotated around the vertical centerline until the handset (horizontal line) was symmetrical with respect to the line NF.

While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the handset contact with the pinna, the EUT was rotated about the line NF until any point on the handset was in contact with a phantom point below the pinna (cheek). [6] See Figure 7.

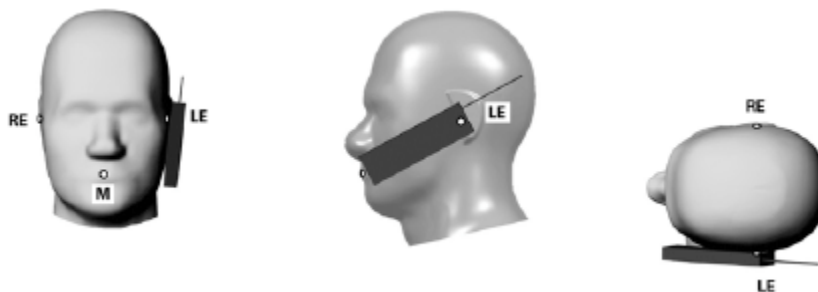


Figure 7

## 2.9.2 "Tilted" Position

The EUT was in "cheek position".

While maintaining the orientation of the handset move the handset away from the pinna along the line passing through RE and LE in order to enable a rotation of the handset by 15 degrees.

The EUT was rotated around the horizontal line by 15 degrees.

While maintaining the orientation of the handset, the EUT was moved towards the phantom on a line passing through RE and LE until any part of the handset touched the ear. The tilted position is obtained when the contact is on the pinna. If the contact was at any location other than the pinna (e.g., the antenna with the back of the phantom head), the angle of the handset would be reduced. In this case, the tilted position is obtained if any part of the handset was in contact with the pinna as well as a second part of the handset was in contact with the phantom (e.g., the antenna with the back of the head). [6] See Figure 8.

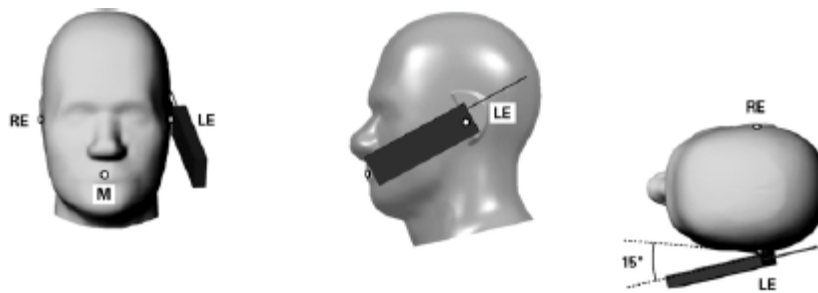


Figure 8

### 2.9.3 Belt Clip/Holster Configuration

Test configurations for body-worn operated EUTs are carried out while the belt-clip and/or holster is attached to the EUT and placed against a flat phantom in a regular configuration (see Figure 9). An EUT with a headset output is tested with a headset connected to the device.

Body dielectric parameters are used.

There are two categories for accessories for body-worn operation configurations:

1. accessories not containing metallic components
2. accessories containing metallic components.

When the EUT is equipped with accessories not containing metallic components the tests are done with the accessory that dictates the closest spacing to the body. For accessories containing metallic parts a test with each one is implemented. If the multiple accessories share an identical metallic component (e.g. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that has the closest spacing to the body is tested.

In case that a EUT authorized to be body-worn is not supplied or has no options to be operated with any accessories, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented.

Transmitters operating in front of a person's face (e.g. push-to-talk configurations) are tested for SAR compliance with the front of the device positioned to face the flat platform. SAR Compliance tests for shoulder, waist or chest-worn transmitters are carried out with the accessories including headsets and microphones attached to the device and placed against a flat phantom in a regular configuration.

The SAR measurements are performed to investigate the worst-case positioning. This is documented and used to perform Body SAR testing. [2]



Figure 9

## 2.10 Measurement uncertainty

The uncertainty budget has been determined for the DASY4 system performance check according to IEEE Str. 1528-200X, (draft), April 2002.

| Error Description                    | Tol.<br>(± %) | Prob.<br>dist. | Div.       | $(^ci)^1$<br>(1g) | Std. unc.<br>(1g) (± %) | $(^vi)^2$ |
|--------------------------------------|---------------|----------------|------------|-------------------|-------------------------|-----------|
| <b>Measurement System</b>            |               |                |            |                   |                         |           |
| Probe Calibration                    | 4.4           | N              | 1          | 1                 | 4.4                     | $\infty$  |
| Axial Isotropy                       | 4.7           | R              | $\sqrt{3}$ | 1                 | 2.7                     | $\infty$  |
| Hemispherical Isotropy               | 0             | R              | $\sqrt{3}$ | 1                 | 0                       | $\infty$  |
| Boundary Effects                     | 8.3           | R              | $\sqrt{3}$ | 1                 | 4.8                     | $\infty$  |
| Linearity                            | 4.7           | R              | $\sqrt{3}$ | 1                 | 2.7                     | $\infty$  |
| System Detection Limit               | 1.0           | R              | $\sqrt{3}$ | 1                 | 0.6                     | $\infty$  |
| Readout Electronics                  | 1.0           | N              | 1          | 1                 | 1.0                     | $\infty$  |
| Response Time                        | 0             | R              | $\sqrt{3}$ | 1                 | 0                       | $\infty$  |
| Integration Time                     | 0             | R              | $\sqrt{3}$ | 1                 | 0                       | $\infty$  |
| RF Ambient Conditions                | 3.0           | R              | $\sqrt{3}$ | 1                 | 1.7                     | $\infty$  |
| Probe Positioner                     | 0.4           | R              | $\sqrt{3}$ | 1                 | 0.2                     | $\infty$  |
| Probe Positioning                    | 2.9           | R              | $\sqrt{3}$ | 1                 | 1.7                     | $\infty$  |
| Algorithms for Max. SAR Evaluation   | 3.9           | R              | $\sqrt{3}$ | 1                 | 2.3                     | $\infty$  |
| <b>Dipole</b>                        |               |                |            |                   |                         |           |
| Dipole Axis to Liquid Distance       | 1.0           | R              | $\sqrt{3}$ | 1                 | 0.6                     | $\infty$  |
| Power Drift                          | 4.7           | R              | $\sqrt{3}$ | 1                 | 2.7                     | $\infty$  |
| <b>Phantom and Tissue Parameter</b>  |               |                |            |                   |                         |           |
| Phantom Uncertainty                  | 4.0           | R              | $\sqrt{3}$ | 1                 | 2.3                     | $\infty$  |
| Liquid Conductivity (target)         | 5.0           | R.             | $\sqrt{3}$ | 0.6               | 1.7                     | $\infty$  |
| Liquid Conductivity (meas.)          | 10.0          | R              | $\sqrt{3}$ | 0.6               | 3.5                     | $\infty$  |
| Liquid Permittivity (target)         | 5.0           | R              | $\sqrt{3}$ | 0.6               | 1.7                     | $\infty$  |
| Liquid Permittivity (meas.)          | 5.0           | R              | $\sqrt{3}$ | 0.6               | 1.7                     | $\infty$  |
| <b>Combined Standard Uncertainty</b> |               |                |            |                   | <b>10.2</b>             | $\infty$  |
| <b>Expanded Uncertainty kp=2</b>     |               |                |            |                   |                         |           |
| <b>Coverage Factor for 95%</b>       |               |                |            |                   | <b>20.3</b>             |           |

### 3. Tissue and System Verification

#### 3.1 Tissue Verification

Dielectric parameters of the simulating liquids were verified using a Dielectric Probe Kit Agilent 85070D to a tolerance of  $\pm 5 \%$ .

**Date:** 23.06.2003  
**Liquid Temperature:** 22,1-22,4 °C  
**Room Temperature:** 22,2 -22,6 °C

|                                                   | Measured Tissue Parameters |          |                 |          |
|---------------------------------------------------|----------------------------|----------|-----------------|----------|
|                                                   | 2450 MHz Brain             |          | 2450 MHz Muscle |          |
|                                                   | Target                     | Measured | Target          | Measured |
| <b>Dielectric Constant: <math>\epsilon</math></b> | N/A                        | N/A      | 52,7            | 52,3     |
| <b>Conductivity: <math>\sigma</math></b>          | N/A                        | N/A      | 1,95            | 1,94     |

#### 3.2 System Verification

Prior to the assessment, the system was verified by using a 2450 MHz validation dipole. Power level of 15,0 dBm was supplied to the dipole antenna placed under the flat section of SAM Phantom.

The system was verified to a tolerance of  $\pm 10 \%$ .

**Liquid Temperature:** 22,1-22,4 °C  
**Room Temperature:** 22,2 -22,6 °C  
**Liquid Depth:** 15.5 cm

| System Dipole Validation Target & Measurement |                        |                 |                        |                        |               |
|-----------------------------------------------|------------------------|-----------------|------------------------|------------------------|---------------|
| Date                                          | System Validation Kit: | Liquid          | Targeted SAR 1g (mW/g) | Measured SAR 1g (mW/g) | Deviation (%) |
| 23.06.2003                                    | D2450V2 SN722          | 2450 MHz Muscle | 54,8                   | 53,76                  | -1,89         |
| 24.06.2003                                    | D2450V2 SN722          | 2450 MHz Muscle | 54,8                   | 55,02                  | 0,40          |

Comment: Please find attached the measurement plot.

## 4. Test Results

### Procedures Used To Establish Test Signal

The EUT was placed into simulated call mode (e.g. AMPS, Cellular CDMA & PCS CDMA modes) using manufacturers test codes. Such test signals offer a consistent means for testing SAR and are recommended for evaluating SAR [2]. The actual transmission is activated through a base station simulator or similar when test modes are not available or inappropriate for testing the EUT.

The EUT is rechargeable battery operated. The battery used for the SAR measurements was completely charged. The device was tested at full power verified by implementing conducted output power measurements. For confirming of the output power it was tested before and after each SAR measurement. The test was repeated if a conducted power deviation of more than 5 % occurred.

**Mixture Type:** 2450 MHz Muscle

**Date:** 23.06.03 -24.06.2003

**Liquid Temperature:** 22,1-22,4 °C

**Room Temperature:** 22,2 -22,6 °C

| Frequency |         |            | Power Drift<br>dB | Antenna Pos. | Phantom<br>Section | SAR (W/kg)   |
|-----------|---------|------------|-------------------|--------------|--------------------|--------------|
| MHz       | Channel | Modulation |                   |              |                    |              |
| 2412,0    | 1       | LAN        | 0,20              | Integral     | Front Side         | 0,0177       |
| 2437,0    | 6       | LAN        | -0,10             | Integral     | Front Side         | 0,0108       |
| 2462,0    | 11      | LAN        | 0,05              | Integral     | Front Side         | 0,0129       |
| 2412,0    | 1       | LAN        | -0,03             | Integral     | Back Side          | <b>0,299</b> |
| 2437,0    | 6       | LAN        | -0,07             | Integral     | Back Side          | 0,284        |
| 2462,0    | 11      | LAN        | -0,03             | Integral     | Back Side          | 0,166        |

### Limits:

| Exposure Limits                                                                       | SAR (W/kg)                                              |                                                 |
|---------------------------------------------------------------------------------------|---------------------------------------------------------|-------------------------------------------------|
|                                                                                       | Uncontrolled Exposure/General<br>Population Environment | Controlled Exposure/Occupational<br>Environment |
| Spatial Average SAR<br>(averaged over the whole body)                                 | 0.08                                                    | 0.40                                            |
| Spatial Peak SAR<br>(averaged over any 1g of tissue)                                  | 1.60                                                    | 8.00                                            |
| Spatial Peak SAR<br>(Hands, Feet, Ankles, Wrist)<br>(averaged over any 10g of tissue) | 4.00                                                    | 20.00                                           |

### Notes:

1. Test data represent the worst case SAR value and test procedure used are according to OET Bulletin 65, Supplement C (01-01).
2. All modes of operation were investigated.

## 5. References

- [1] ANSI/IEEE C95.3 – 1991, *IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic fields, 300 kHz to 100 GHz*, New York: IEEE, Aug. 1992
- [2] Federal Communications Commission, OET Bulletin 65 (Edition 97-01), Supplement C (Edition 01-01), *Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields*, July 2001.
- [3] T. Schmid, O. Egger, N. Kuster, *Automated E-field scanning system for dosimetric assessments*, IEEE Transaction on Microwave Theory and Techniques, vol. 44, Jan. 1996, pp. 105-113.
- [4] W. Gander, *Computermathematics*, Birkhaeuser, Basel, 1992.
- [5] W.H. Press, S.A. Teukolsky, W.T. Vetterling, and B.P. Flannery, *Numerical Recepies in C*, The Art of Scientific Computing, Second edition, Cambridge University Press, 1992.
- [6] IEEE Standards Coordinating Committee 34 – IEEE Std. 1528-200X (Draft 6.1 – January 2002), *Draft Recommended Practice for Determining the Peak Spatial-Average Absorption Rate (SAR in the Human Body Due to Wireless Communications Devices: Experimental Techniques*.
- [7] DASY4 *Dosimetric Assessment System Manual*; Draft; September 6, 2002; Schmid & Partner Engineering AG

## 6. Appendix

- |    |            |                         |                                              |
|----|------------|-------------------------|----------------------------------------------|
| 1. | Appendix A | Calibration Certificate | D2450V2 SN722<br>ET3DV6 SN1711<br>DAE3V1-522 |
| 2. | Appendix B | Measurement Plots       |                                              |
| 3. | Appendix C | Pictures                |                                              |

## **Appendix A**

### **Calibration Certificate**

# Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland, Phone +41 1 245 97 00, Fax +41 1 245 97 79

## Calibration Certificate

### 2450 MHz System Validation Dipole

Type:

**D2450V2**

Serial Number:

**722**

Place of Calibration:

**Zurich**

Date of Calibration:

**November 9, 2002**

Calibration Interval:

**24 months**

Schmid & Partner Engineering AG hereby certifies, that this device has been calibrated on the date indicated above. The calibration was performed in accordance with specifications and procedures of Schmid & Partner Engineering AG.

Wherever applicable, the standards used in the calibration process are traceable to international standards. In all other cases the standards of the Laboratory for EMF and Microwave Electronics at the Swiss Federal Institute of Technology (ETH) in Zurich, Switzerland have been applied.

Calibrated by:



Approved by:



**DASY**

**Dipole Validation Kit**

**Type: D2450V2**

**Serial: 722**

**Manufactured: October 16, 2002**

**Calibrated: November 9, 2002**

## **1. Measurement Conditions**

The measurements were performed in the flat section of the new SAM twin phantom filled with head simulating solution of the following electrical parameters at 2450 MHz:

|                       |                   |            |
|-----------------------|-------------------|------------|
| Relative permittivity | <b>38.0</b>       | $\pm 5\%$  |
| Conductivity          | <b>1.87 mho/m</b> | $\pm 10\%$ |

The DASY4 System with a dosimetric E-field probe ET3DV6 (SN:1507, conversion factor 5.0 at 2450 MHz) was used for the measurements.

The dipole feedpoint was positioned below the center marking and oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 10mm from dipole center to the solution surface. The included distance holder was used during measurements for accurate distance positioning.

The coarse grid with a grid spacing of 15 mm was aligned with the dipole. The 7x7x7 fine cube was chosen for cube integration.

The dipole input power (forward power) was  $250\text{mW} \pm 3\%$ . The results are normalized to 1W input power.

## **2 SAR Measurement**

Standard SAR-measurements were performed according to the measurement conditions described in section 1. The results (see figure supplied) have been normalized to a dipole input power of 1W (forward power). The resulting averaged SAR-values measured with the dosimetric probe ET3DV6 SN:1507 are:

|                                                  |                  |
|--------------------------------------------------|------------------|
| averaged over $1\text{ cm}^3$ (1 g) of tissue:   | <b>54.8 mW/g</b> |
| averaged over $10\text{ cm}^3$ (10 g) of tissue: | <b>24.3 mW/g</b> |

### **3. Dipole impedance and return loss**

The impedance was measured at the SMA-connector with a network analyzer and numerically transformed to the dipole feedpoint. The transformation parameters from the SMA-connector to the dipole feedpoint are:

|                      |                 |                                       |
|----------------------|-----------------|---------------------------------------|
| Electrical delay:    | <b>1.152 ns</b> | (one direction)                       |
| Transmission factor: | <b>0.997</b>    | (voltage transmission, one direction) |

The dipole was positioned at the flat phantom sections according to section 1 and the distance holder was in place during impedance measurements.

|                                  |                                |
|----------------------------------|--------------------------------|
| Feedpoint impedance at 2450 MHz: | $\text{Re}\{Z\} = 51.0 \Omega$ |
|----------------------------------|--------------------------------|

|                               |
|-------------------------------|
| $\text{Im}\{Z\} = 6.2 \Omega$ |
|-------------------------------|

|                         |                  |
|-------------------------|------------------|
| Return Loss at 2450 MHz | <b>- 24.2 dB</b> |
|-------------------------|------------------|

### **4. Handling**

Do not apply excessive force to the dipole arms, because they might bend. Bending of the dipole arms stresses the soldered connections near the feedpoint leading to a damage of the dipole.

### **5. Design**

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.

Small end caps have been added to the dipole arms in order to improve matching when loaded according to the position as explained in Section 1. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

### **6. Power Test**

After long term use with 40W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

Test Laboratory: SPEAG, Zurich, Switzerland  
File Name: SN722\_SN1507\_HSL2450\_061102.da4

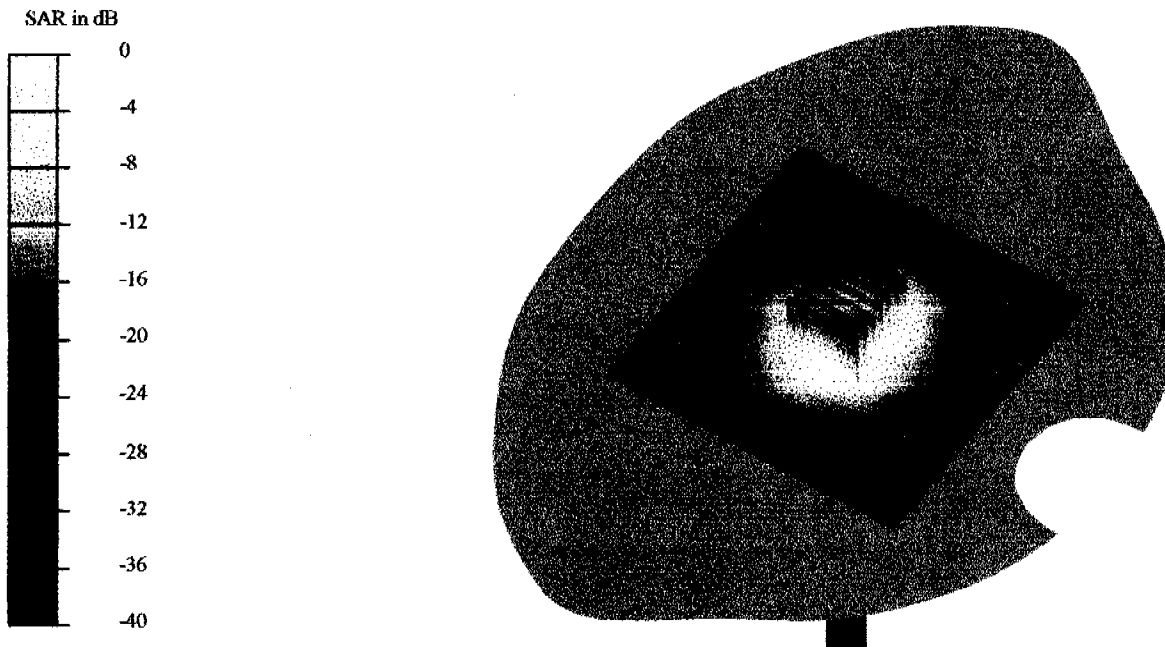
**DUT: Dipole 2450 MHz Type & Serial Number: D2450V2 - SN722**  
**Program: Dipole Calibration; Pin = 250 mW; d = 10 mm**

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1  
Medium: HSL 2450 MHz ( $\sigma = 1.87$  mho/m,  $\epsilon = 38.03$ ,  $\rho = 1000$  kg/m<sup>3</sup>)  
Phantom section: FlatSection

DASY4 Configuration:

- Probe: ET3DV6 - SN1507; ConvF(5, 5, 5); Calibrated: 1/24/2002
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 - SN410; Calibrated: 7/18/2002
- Phantom: SAM 4.0 - TP:1006
- Software: DASY4, V4.0 Build 35

**Area Scan (81x81x1):** Measurement grid: dx=15mm, dy=15mm  
**Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm  
Reference Value = 95.6 V/m  
Peak SAR = 30.2 mW/g  
SAR(1 g) = 13.7 mW/g; SAR(10 g) = 6.08 mW/g  
Power Drift = -0.004 dB



6 Nov 2002 14:02:11

722

CH1 S11 1 U FS

1: 51.008  $\Omega$  6.1641  $\Omega$  400.42  $\mu$ H

2 450.000 000 MHz

↑

De1

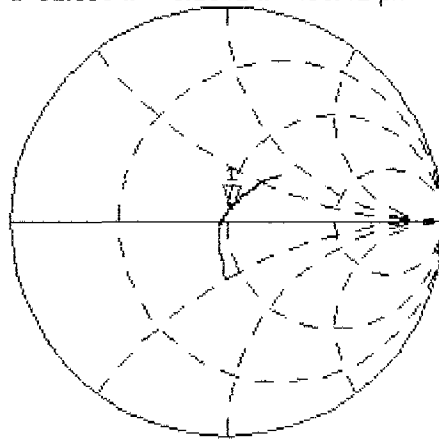
PRM

Cor

Avg

16

↑

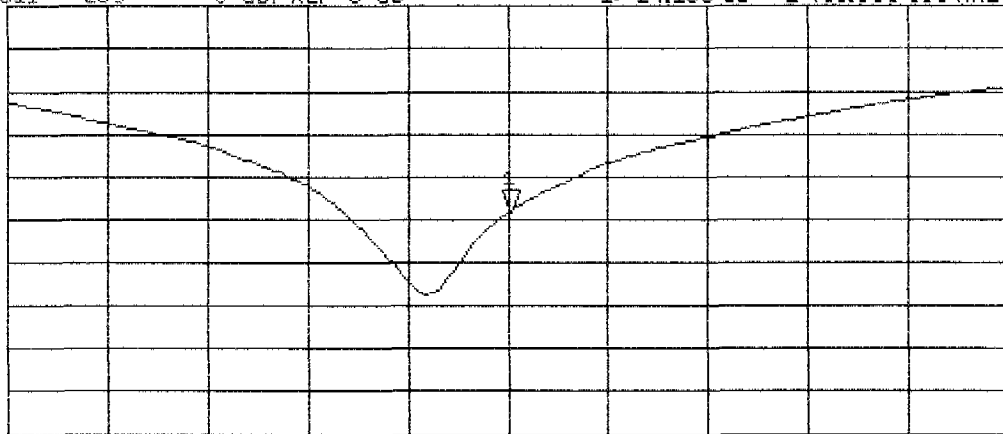


CH2 S11 LOG 5 dB/REF 0 dB 1: -24.183 dB 2 450.000 000 MHz

PRM

Cor

↑



START 2 250.000 000 MHz

STOP 2 650.000 000 MHz

# Schmid & Partner Engineering AG

Zeughausstrasse 43, 8004 Zurich, Switzerland, Phone +41 1 245 97 00, Fax +41 1 245 97 79

## Calibration Certificate

### Dosimetric E-Field Probe

Type:

ET3DV6

Serial Number:

1711

Place of Calibration:

Zurich

Date of Calibration:

September 3, 2002

Calibration Interval:

12 months

Schmid & Partner Engineering AG hereby certifies, that this device has been calibrated on the date indicated above. The calibration was performed in accordance with specifications and procedures of Schmid & Partner Engineering AG.

Wherever applicable, the standards used in the calibration process are traceable to international standards. In all other cases the standards of the Laboratory for EMF and Microwave Electronics at the Swiss Federal Institute of Technology (ETH) in Zurich, Switzerland have been applied.

Calibrated by:

D. Keller

Approved by:

Marie Katten

# Probe ET3DV6

**SN:1711**

|                   |                   |
|-------------------|-------------------|
| Manufactured:     | August 7, 2002    |
| Last calibration: | September 3, 2002 |

**Calibrated for DASY Systems**

(Note: non-compatible with DASY2 system!)

## DASY - Parameters of Probe: ET3DV6 SN:1711

### Sensitivity in Free Space

|       |                                                 |
|-------|-------------------------------------------------|
| NormX | <b>1.38</b> $\mu\text{V}/(\text{V}/\text{m})^2$ |
| NormY | <b>1.60</b> $\mu\text{V}/(\text{V}/\text{m})^2$ |
| NormZ | <b>1.53</b> $\mu\text{V}/(\text{V}/\text{m})^2$ |

### Diode Compression

|       |           |    |
|-------|-----------|----|
| DCP X | <b>97</b> | mV |
| DCP Y | <b>97</b> | mV |
| DCP Z | <b>97</b> | mV |

### Sensitivity in Tissue Simulating Liquid

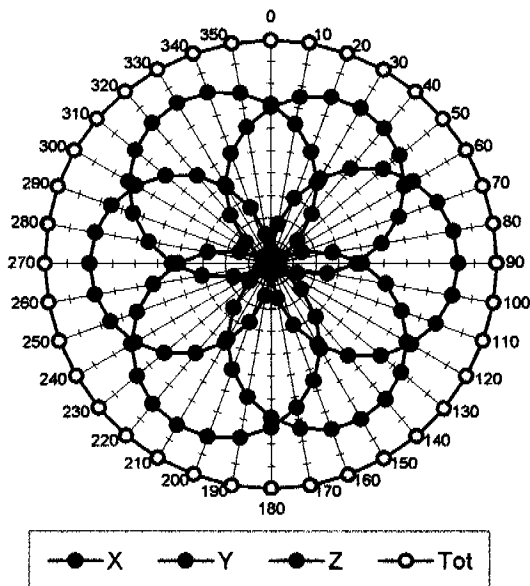
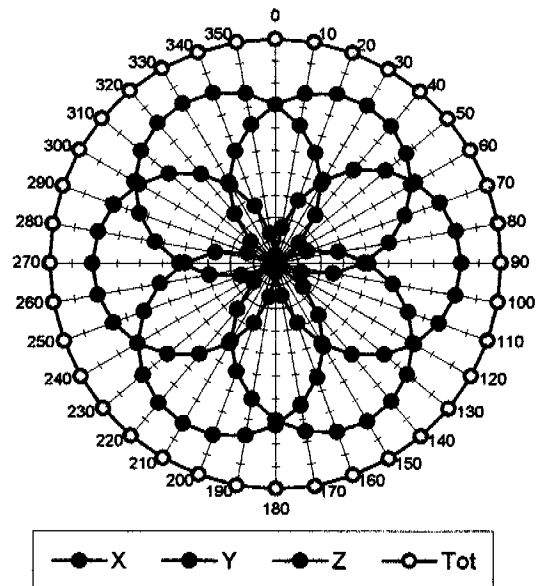
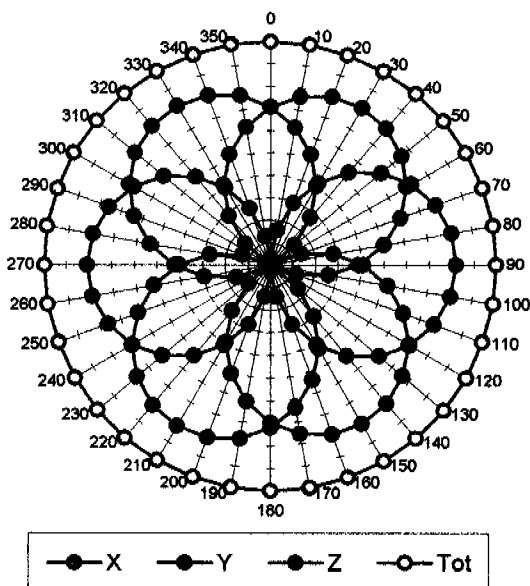
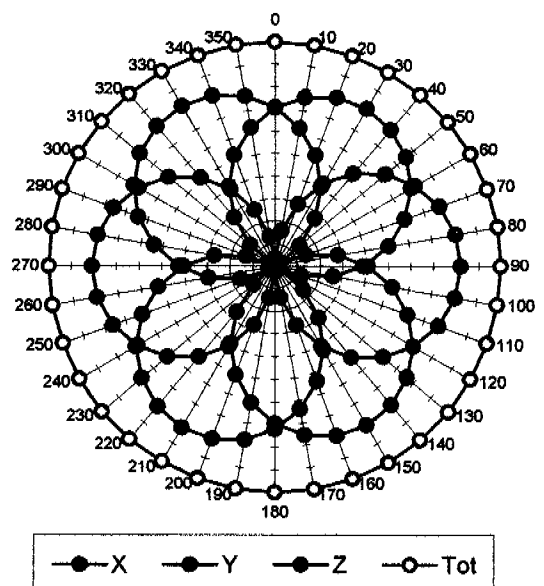
|         |                              |                             |                                       |
|---------|------------------------------|-----------------------------|---------------------------------------|
| Head    | <b>900 MHz</b>               | $\epsilon_r = 41.5 \pm 5\%$ | $\sigma = 0.97 \pm 5\% \text{ mho/m}$ |
| Head    | <b>835 MHz</b>               | $\epsilon_r = 41.5 \pm 5\%$ | $\sigma = 0.90 \pm 5\% \text{ mho/m}$ |
| ConvF X | <b>6.4</b> $\pm 9.5\%$ (k=2) | Boundary effect:            |                                       |
| ConvF Y | <b>6.4</b> $\pm 9.5\%$ (k=2) | Alpha                       | <b>0.47</b>                           |
| ConvF Z | <b>6.4</b> $\pm 9.5\%$ (k=2) | Depth                       | <b>2.17</b>                           |
| Head    | <b>1800 MHz</b>              | $\epsilon_r = 40.0 \pm 5\%$ | $\sigma = 1.40 \pm 5\% \text{ mho/m}$ |
| Head    | <b>1900 MHz</b>              | $\epsilon_r = 40.0 \pm 5\%$ | $\sigma = 1.40 \pm 5\% \text{ mho/m}$ |
| ConvF X | <b>5.3</b> $\pm 9.5\%$ (k=2) | Boundary effect:            |                                       |
| ConvF Y | <b>5.3</b> $\pm 9.5\%$ (k=2) | Alpha                       | <b>0.49</b>                           |
| ConvF Z | <b>5.3</b> $\pm 9.5\%$ (k=2) | Depth                       | <b>2.52</b>                           |

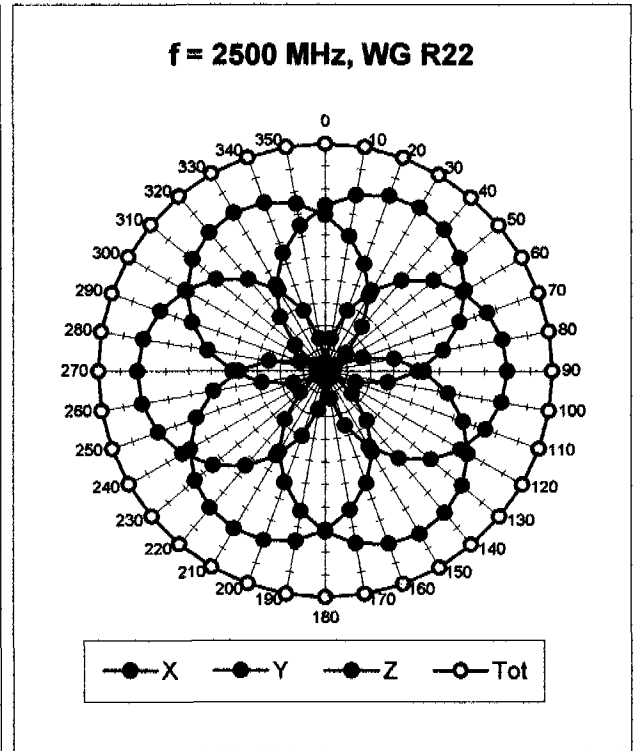
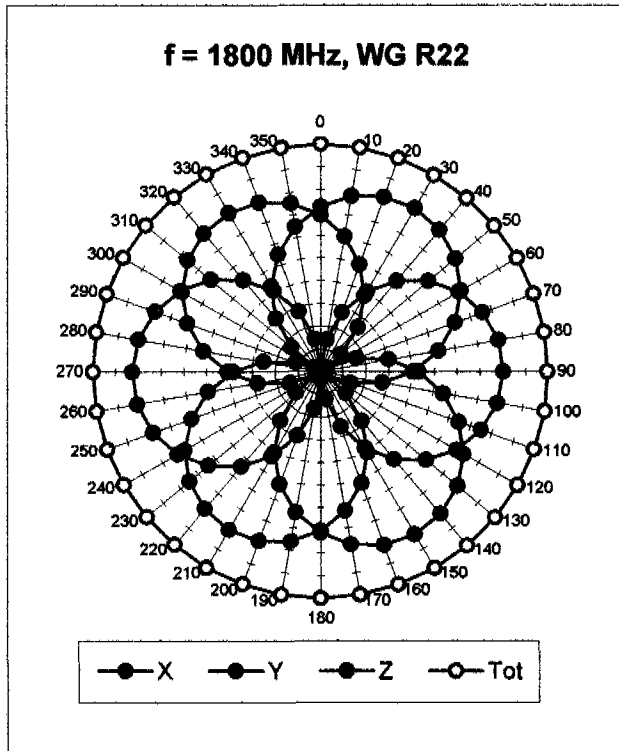
### Boundary Effect

|                                                    |                 |                                   |             |
|----------------------------------------------------|-----------------|-----------------------------------|-------------|
| Head                                               | <b>900 MHz</b>  | Typical SAR gradient: 5 % per mm  |             |
| Probe Tip to Boundary                              |                 | <b>1 mm</b>                       | <b>2 mm</b> |
| SAR <sub>be</sub> [%] Without Correction Algorithm |                 | <b>9.6</b>                        | <b>5.3</b>  |
| SAR <sub>be</sub> [%] With Correction Algorithm    |                 | <b>0.2</b>                        | <b>0.4</b>  |
| Head                                               | <b>1800 MHz</b> | Typical SAR gradient: 10 % per mm |             |
| Probe Tip to Boundary                              |                 | <b>1 mm</b>                       | <b>2 mm</b> |
| SAR <sub>be</sub> [%] Without Correction Algorithm |                 | <b>12.5</b>                       | <b>8.4</b>  |
| SAR <sub>be</sub> [%] With Correction Algorithm    |                 | <b>0.2</b>                        | <b>0.2</b>  |

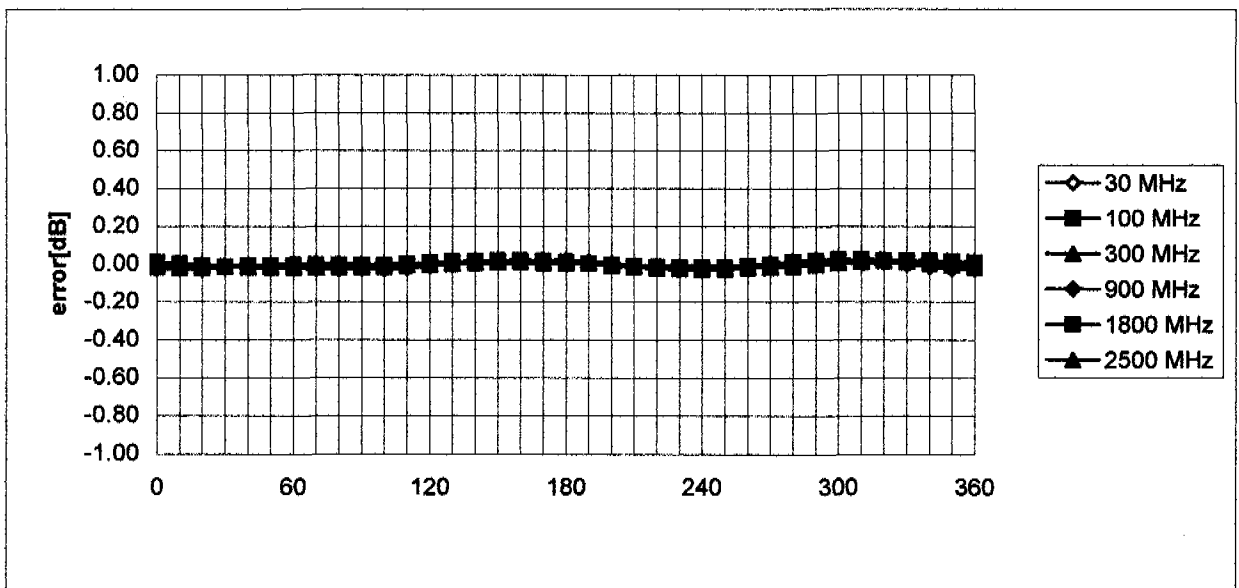
### Sensor Offset

|                            |                                 |    |
|----------------------------|---------------------------------|----|
| Probe Tip to Sensor Center | <b>2.7</b>                      | mm |
| Optical Surface Detection  | <b>1.3 <math>\pm</math> 0.2</b> | mm |

Receiving Pattern ( $\phi$ ),  $\theta = 0^\circ$ **f = 30 MHz, TEM cell ifi110****f = 100 MHz, TEM cell ifi110****f = 300 MHz, TEM cell ifi110****f = 900 MHz, TEM cell ifi110**

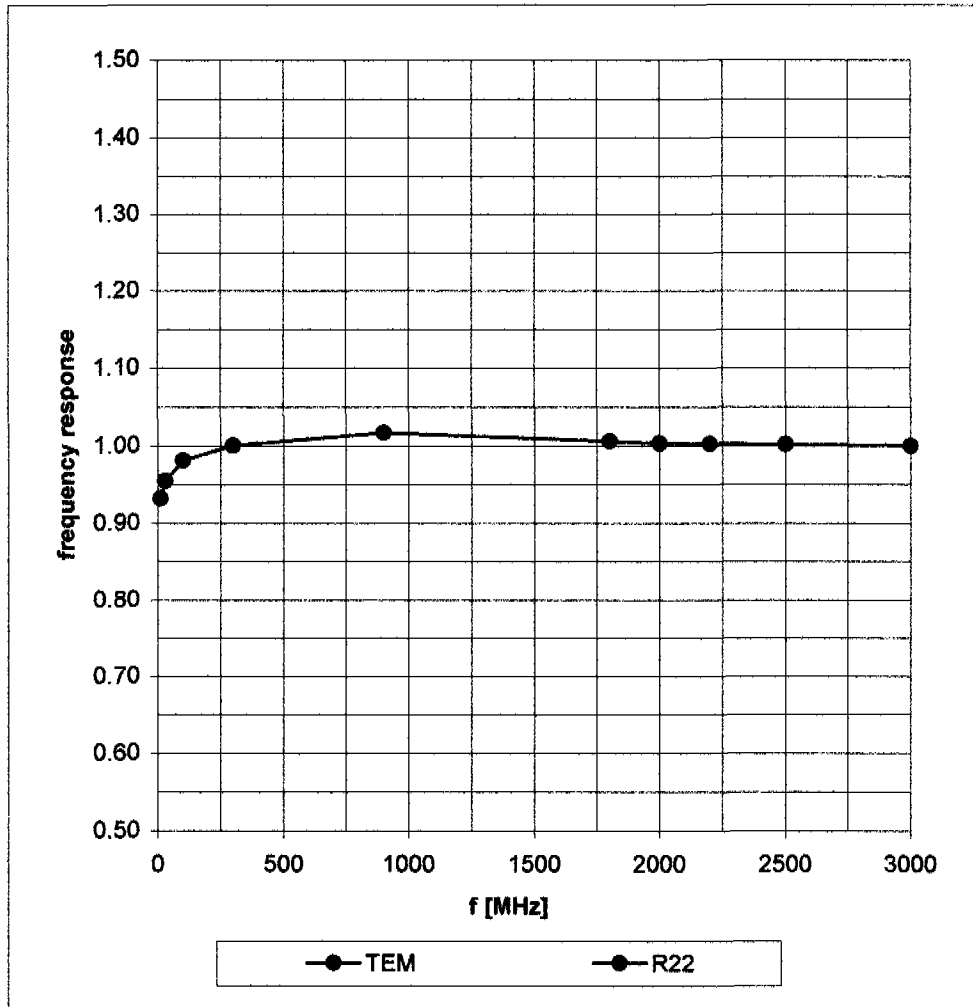


### Isotropy Error ( $\phi$ ), $\theta = 0^\circ$

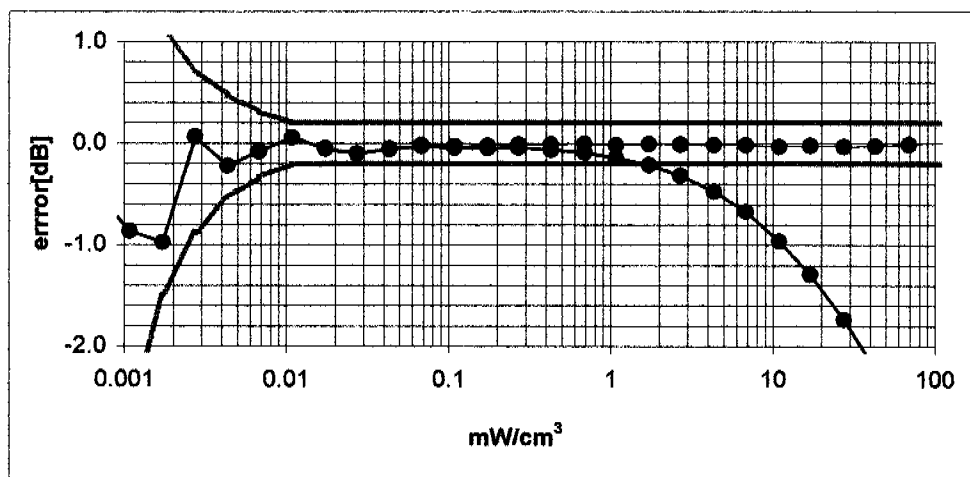
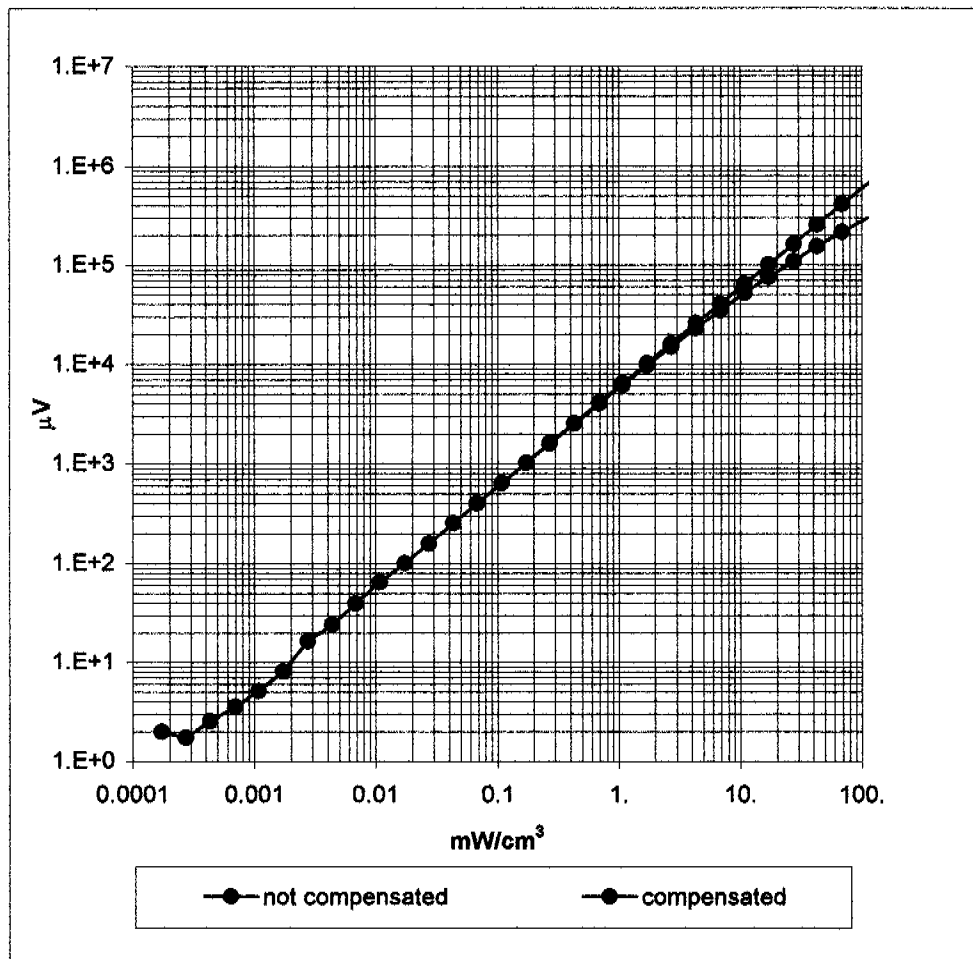


## Frequency Response of E-Field

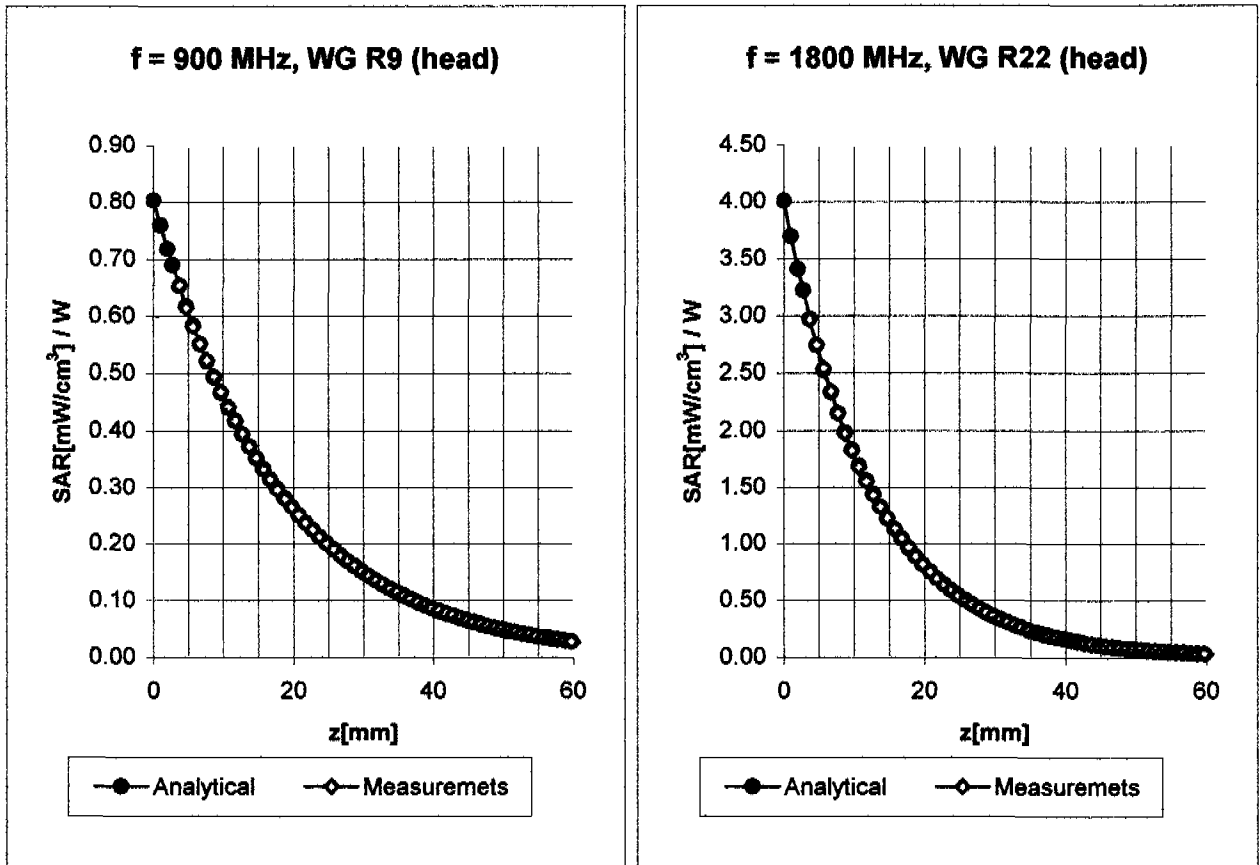
( TEM-Cell:ifi110, Waveguide R22)



## Dynamic Range f(SAR<sub>brain</sub>) ( Waveguide R22 )



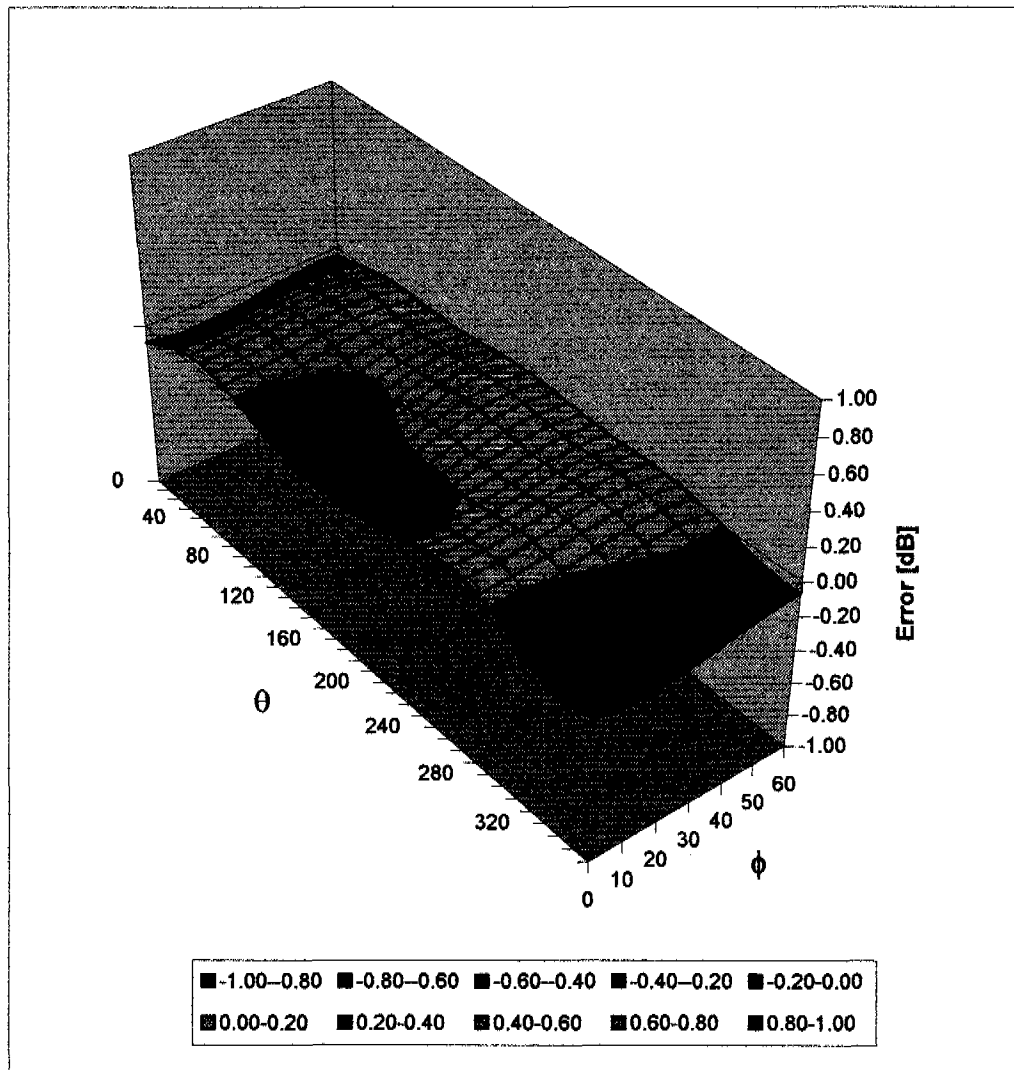
## Conversion Factor Assessment



|      |          |                              |                                       |
|------|----------|------------------------------|---------------------------------------|
| Head | 900 MHz  | $\epsilon_r = 41.5 \pm 5\%$  | $\sigma = 0.97 \pm 5\% \text{ mho/m}$ |
| Head | 835 MHz  | $\epsilon_r = 41.5 \pm 5\%$  | $\sigma = 0.90 \pm 5\% \text{ mho/m}$ |
|      | ConvF X  | <b>6.4</b> $\pm 9.5\%$ (k=2) | Boundary effect:                      |
|      | ConvF Y  | <b>6.4</b> $\pm 9.5\%$ (k=2) | Alpha <b>0.47</b>                     |
|      | ConvF Z  | <b>6.4</b> $\pm 9.5\%$ (k=2) | Depth <b>2.17</b>                     |
|      |          |                              |                                       |
| Head | 1800 MHz | $\epsilon_r = 40.0 \pm 5\%$  | $\sigma = 1.40 \pm 5\% \text{ mho/m}$ |
| Head | 1900 MHz | $\epsilon_r = 40.0 \pm 5\%$  | $\sigma = 1.40 \pm 5\% \text{ mho/m}$ |
|      | ConvF X  | <b>5.3</b> $\pm 9.5\%$ (k=2) | Boundary effect:                      |
|      | ConvF Y  | <b>5.3</b> $\pm 9.5\%$ (k=2) | Alpha <b>0.49</b>                     |
|      | ConvF Z  | <b>5.3</b> $\pm 9.5\%$ (k=2) | Depth <b>2.52</b>                     |

## Deviation from Isotropy in HSL

Error ( $\theta, \phi$ ),  $f = 900$  MHz



## Calibration Certificate

### Dosimetric E-Field Probe

Type:

**ET3DV6**

Serial Number:

**1711**

Place of Calibration:

**Zurich**

Date of Calibration:

**November 26, 2002**

Calibration Interval:

**12 months**

Schmid & Partner Engineering AG hereby certifies, that this device has been calibrated on the date indicated above. The calibration was performed in accordance with specifications and procedures of Schmid & Partner Engineering AG.

Wherever applicable, the standards used in the calibration process are traceable to international standards. In all other cases the standards of the Laboratory for EMF and Microwave Electronics at the Swiss Federal Institute of Technology (ETH) in Zurich, Switzerland have been applied.

Calibrated by:

*D. Vellard*

Approved by:

*F. Bruchalt*

**Probe ET3DV6**

**SN:1711**

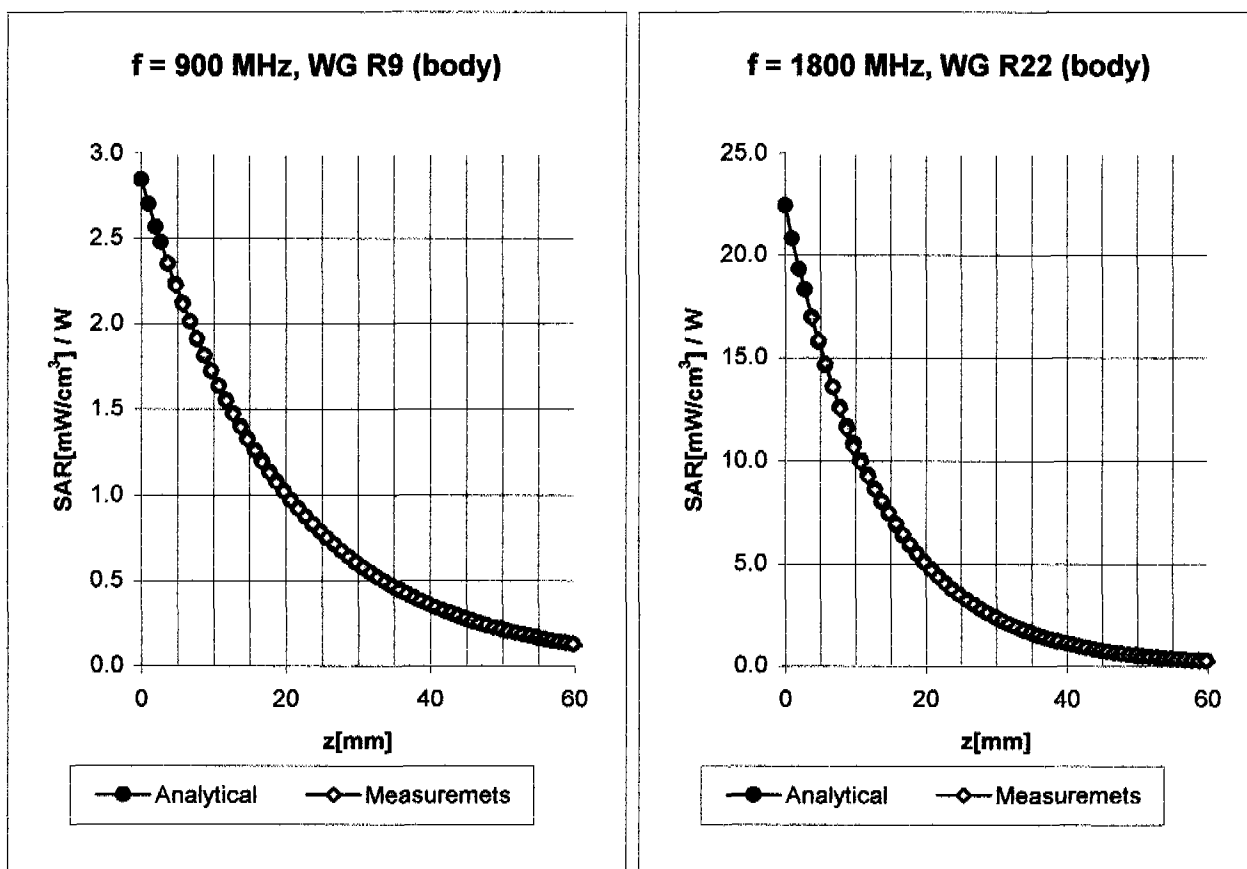
**Additional Conversion Factors**

**Calibrated: November 26, 2002**

**Calibrated for DASY Systems**

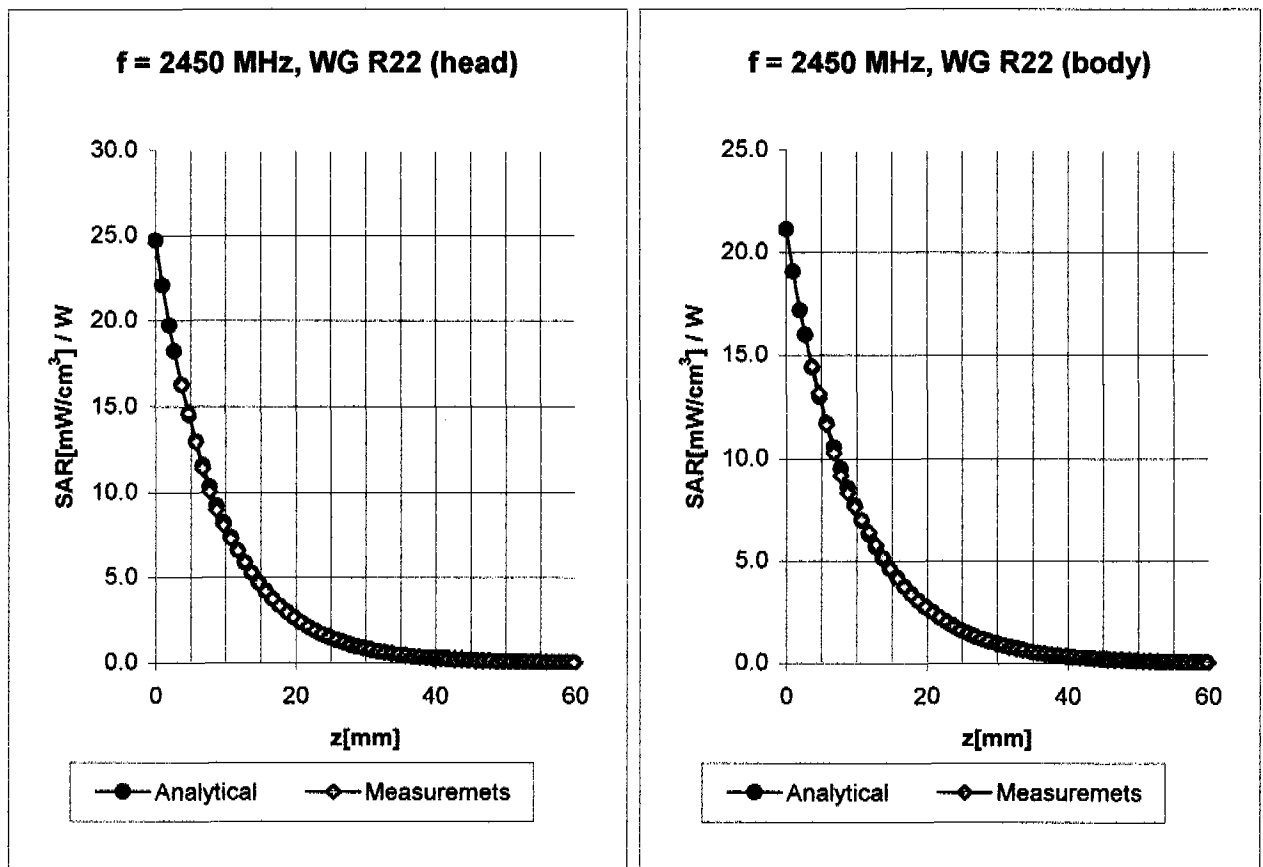
(Note: non-compatible with DASY2 system!)

## Conversion Factor Assessment



|      |          |                             |                                       |
|------|----------|-----------------------------|---------------------------------------|
| Body | 900 MHz  | $\epsilon_r = 55.0 \pm 5\%$ | $\sigma = 1.05 \pm 5\% \text{ mho/m}$ |
| Body | 835 MHz  | $\epsilon_r = 55.2 \pm 5\%$ | $\sigma = 0.97 \pm 5\% \text{ mho/m}$ |
|      | ConvF X  | $6.2 \pm 9.5\% (k=2)$       | Boundary effect:                      |
|      | ConvF Y  | $6.2 \pm 9.5\% (k=2)$       | Alpha <b>0.41</b>                     |
|      | ConvF Z  | $6.2 \pm 9.5\% (k=2)$       | Depth <b>2.49</b>                     |
| Body | 1800 MHz | $\epsilon_r = 53.3 \pm 5\%$ | $\sigma = 1.52 \pm 5\% \text{ mho/m}$ |
| Body | 1900 MHz | $\epsilon_r = 53.3 \pm 5\%$ | $\sigma = 1.52 \pm 5\% \text{ mho/m}$ |
|      | ConvF X  | $5.0 \pm 9.5\% (k=2)$       | Boundary effect:                      |
|      | ConvF Y  | $5.0 \pm 9.5\% (k=2)$       | Alpha <b>0.63</b>                     |
|      | ConvF Z  | $5.0 \pm 9.5\% (k=2)$       | Depth <b>2.26</b>                     |

## Conversion Factor Assessment



|             |             |                              |                             |                                       |
|-------------|-------------|------------------------------|-----------------------------|---------------------------------------|
| <b>2450</b> | <b>Head</b> | <b>MHz</b>                   | $\epsilon_r = 39.2 \pm 5\%$ | $\sigma = 1.80 \pm 5\% \text{ mho/m}$ |
|             | ConvF X     | <b>4.9</b> $\pm 8.9\%$ (k=2) | Boundary effect:            |                                       |
|             | ConvF Y     | <b>4.9</b> $\pm 8.9\%$ (k=2) | Alpha                       | <b>1.00</b>                           |
|             | ConvF Z     | <b>4.9</b> $\pm 8.9\%$ (k=2) | Depth                       | <b>1.72</b>                           |
| <b>2450</b> | <b>Body</b> | <b>MHz</b>                   | $\epsilon_r = 52.7 \pm 5\%$ | $\sigma = 1.95 \pm 5\% \text{ mho/m}$ |
|             | ConvF X     | <b>4.4</b> $\pm 8.9\%$ (k=2) | Boundary effect:            |                                       |
|             | ConvF Y     | <b>4.4</b> $\pm 8.9\%$ (k=2) | Alpha                       | <b>1.00</b>                           |
|             | ConvF Z     | <b>4.4</b> $\pm 8.9\%$ (k=2) | Depth                       | <b>1.85</b>                           |

**DASY - DOSIMETRIC ASSESSMENT SYSTEM**

**CALIBRATION REPORT**

**DATA ACQUISITION ELECTRONICS**

**MODEL:** DAE3 V1

**SERIAL NUMBER:** 522

This Data Acquisition Unit was calibrated and tested using a FLUKE 702 Process Calibrator. Calibration and verification were performed at an ambient temperature of  $23 \pm 5$  °C and a relative humidity of < 70%.

Measurements were performed using the standard DASY software for converting binary values, offset compensation and noise filtering. Software settings are indicated in the reports.

Results from this calibration relate only to the unit calibrated.

**Calibrated by:** Storchenegger

**Calibration Date:** 11. 09. 2002

**DASY Software Version:** DASY3 V3.1c

## 1. DC Voltage Measurement

DA - Converter Values from DAE

High Range: 1LSB =  $6.1\mu\text{V}$ , full range = 400 mV  
 Low Range: 1LSB =  $61\text{nV}$ , full range = 4 mV

Software Set-up: Calibration time: 3 sec Measuring time: 3 sec

| Setup              | X           | Y           | Z           |
|--------------------|-------------|-------------|-------------|
| High Range         | 403.7567398 | 403.5333268 | 403.8600523 |
| Low Range          | 3.90623     | 3.92439     | 3.92633     |
| Connector Position | 44 °        |             |             |

| High Range        | Input | Reading in $\mu\text{V}$ | % Error |
|-------------------|-------|--------------------------|---------|
| Channel X + Input | 200mV | 200000.4                 | 0.00    |
|                   | 20mV  | 19994.9                  | -0.03   |
| Channel X - Input | 20mV  | -19994.4                 | -0.03   |
| Channel Y + Input | 200mV | 199999.9                 | 0.00    |
|                   | 20mV  | 19996.04                 | -0.02   |
| Channel Y - Input | 20mV  | -19995.35                | -0.02   |
| Channel Z + Input | 200mV | 200000                   | 0.00    |
|                   | 20mV  | 19993.57                 | -0.03   |
| Channel Z - Input | 20mV  | -19994.59                | -0.03   |

| Low Range         | Input | Reading in $\mu\text{V}$ | % Error |
|-------------------|-------|--------------------------|---------|
| Channel X + Input | 2mV   | 2000.07                  | 0.00    |
|                   | 0.2mV | 200.266                  | 0.13    |
| Channel X - Input | 0.2mV | -200.669                 | 0.33    |
| Channel Y + Input | 2mV   | 2000.005                 | 0.00    |
|                   | 0.2mV | 199.4087                 | -0.30   |
| Channel Y - Input | 0.2mV | -200.5428                | 0.27    |
| Channel Z + Input | 2mV   | 2000.05                  | 0.00    |
|                   | 0.2mV | 199.285                  | -0.36   |
| Channel Z - Input | 0.2mV | -201.008                 | 0.50    |

## 2. Common mode sensitivity

Software Set-up

Calibration time: 3 sec, Measuring time: 3 sec

High/Low Range

| in $\mu\text{V}$ | Common mode Input Voltage | High Range Reading | Low Range Reading |
|------------------|---------------------------|--------------------|-------------------|
| Channel X        | 200mV                     | 1.89173            | 1.5706            |
|                  | - 200mV                   | -0.957298          | -1.63568          |
| Channel Y        | 200mV                     | 1.06159            | 0.55289           |
|                  | - 200mV                   | -1.07262           | -1.60898          |
| Channel Z        | 200mV                     | -7.02304           | -7.75271          |
|                  | - 200mV                   | 6.48984            | 6.11901           |

## 3. Channel separation

Software Set-up

Calibration time: 3 sec, Measuring time: 3 sec

High Range

| in $\mu\text{V}$ | Input Voltage | Channel X | Channel Y | Channel Z |
|------------------|---------------|-----------|-----------|-----------|
| Channel X        | 200mV         | -         | 0.967802  | -0.38491  |
| Channel Y        | 200mV         | 0.985686  | -         | -0.851851 |
| Channel Z        | 200mV         | 0.469187  | -0.713242 | -         |

## 4. AD-Converter Values with inputs shorted

| in LSB    | Low Range | High Range |
|-----------|-----------|------------|
| Channel X | 14950.9   | 15343      |
| Channel Y | 14931.4   | 15456.6    |
| Channel Z | 15332.2   | 15470.3    |

## 5. Input Offset Measurement

Measured after 15 min warm-up time of the Data Acquisition Electronic.  
Every Measurement is preceded by a calibration cycle.

Software set-up:

Calibration time: 3 sec  
Measuring time: 3 sec  
Number of measurements: 100, Low Range

Input 10M $\Omega$

| in $\mu$ V | Average | min. Offset | max. Offset | Std. Deviation |
|------------|---------|-------------|-------------|----------------|
| Channel X  | -1.11   | -3.70       | 0.56        | 0.65           |
| Channel Y  | 0.79    | -0.47       | 2.26        | 0.38           |
| Channel Z  | -1.60   | -3.56       | -0.55       | 0.34           |

Input shorted

| in $\mu$ V | Average | min. Offset | max. Offset | Std. Deviation |
|------------|---------|-------------|-------------|----------------|
| Channel X  | -1.36   | -2.30       | 0.49        | 0.39           |
| Channel Y  | 0.05    | -0.63       | 1.82        | 0.33           |
| Channel Z  | -0.53   | -1.37       | 0.58        | 0.21           |

## 6. Input Offset Current

| in fA     | Input Offset Current |
|-----------|----------------------|
| Channel X | < 25                 |
| Channel Y | < 25                 |
| Channel Z | < 25                 |

## 7. Input Resistance

|           | Calibrating    | Measuring      |
|-----------|----------------|----------------|
| Channel X | 200 k $\Omega$ | 200 M $\Omega$ |
| Channel Y | 200 k $\Omega$ | 200 M $\Omega$ |
| Channel Z | 200 k $\Omega$ | 200 M $\Omega$ |

## 8. Low Battery Alarm Voltage

| in V           | Alarm Level |
|----------------|-------------|
| Supply (+ Vcc) | 7.83 V      |
| Supply (- Vcc) | -7.62 V     |

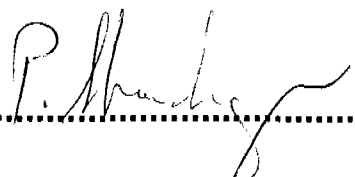
## 9. Power Consumption

| in mA          | Switched off | Stand by | Transmitting |
|----------------|--------------|----------|--------------|
| Supply (+ Vcc) | 0.000        | 5.79     | 13.9         |
| Supply (- Vcc) | -0.011       | -8.07    | -9.24        |

## 10. Functional test

|                             |       |
|-----------------------------|-------|
| Touch async pulse 1         | ok    |
| Touch async pulse 2         | ok    |
| Touch status bit 1          | ok    |
| Touch status bit 2          | ok    |
| Remote power off            | ok    |
| Remote analog Power control | ok    |
|                             |       |
| Modification Status         | B – C |
|                             |       |
|                             |       |

Date: .....11.09.02.....

Signature: ..........

## **Appendix B**

### **Measurement Plots**

Date/Time: 06/23/03 08:27:01

Test Laboratory: ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH

File Name: [Dipol Valid.2400 \(m\) 23.06.03.da4](#)**Dipol Valid.2400 (m) 23.06.03****DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 722****Program: Dipol Valid 2450**

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz ( $\sigma = 1.94$  mho/m,  $\epsilon_r = 52.3$ ,  $\rho = 1000$  kg/m<sup>3</sup>)

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.4, 4.4, 4.4); Calibrated: 11/29/2002
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2002
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**Dipol 2450 (15dBm)/Area Scan (81x81x1):** Measurement grid: dx=10mm, dy=10mm

Reference Value = 30.1 V/m

Power Drift = -0.02 dB

Maximum value of SAR = 1.52 mW/g

**Dipol 2450 (15dBm)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

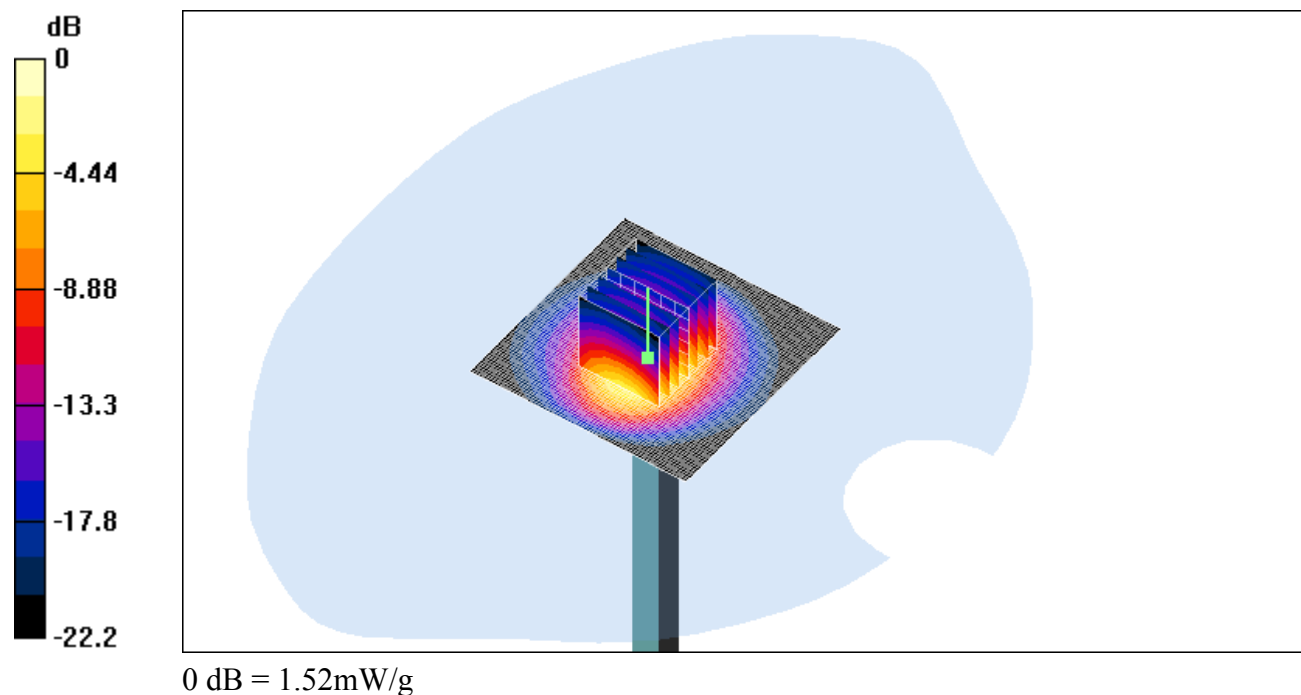
Peak SAR (extrapolated) = 2.58 W/kg

SAR(1 g) = 1.70 mW/g; SAR(10 g) = 0.754 mW/g

Reference Value = 30.1 V/m

Power Drift = -0.02 dB

Maximum value of SAR = 1.52 mW/g



Date/Time: 06/24/03 08:54:41

Test Laboratory: ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH

File Name: [Dipol Valid.2400 \(m\) 24.06.03.da4](#)**Dipol Valid.2400 (m) 24.06.03****DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 722****Program: Dipol Valid 2450**

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz ( $\sigma = 1.94$  mho/m,  $\epsilon_r = 52.3$ ,  $\rho = 1000$  kg/m<sup>3</sup>)

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.4, 4.4, 4.4); Calibrated: 11/29/2002
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2002
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**Dipol 2450 (15dBm)/Area Scan (81x81x1):** Measurement grid: dx=10mm, dy=10mm

Reference Value = 30.1 V/m

Power Drift = -0.02 dB

Maximum value of SAR = 1.53 mW/g

**Dipol 2450 (15dBm)/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

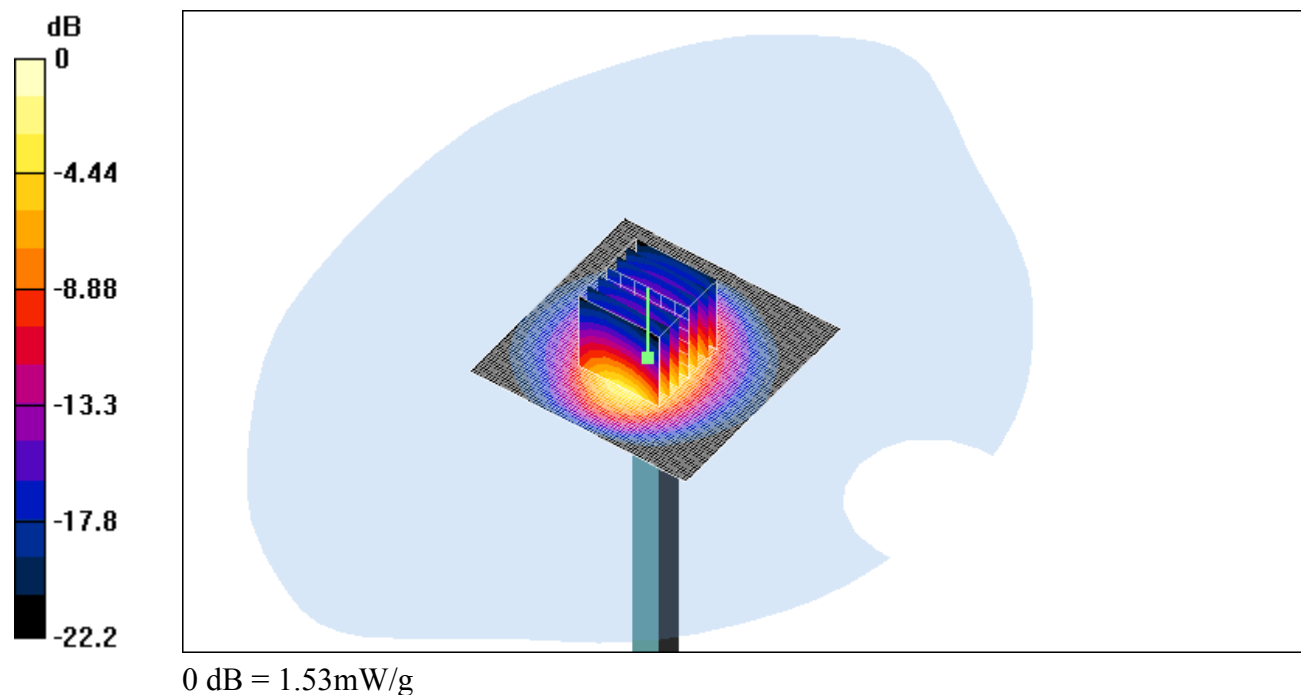
Peak SAR (extrapolated) = 2.58 W/kg

SAR(1 g) = 1.74 mW/g; SAR(10 g) = 0.760 mW/g

Reference Value = 30.1 V/m

Power Drift = -0.03 dB

Maximum value of SAR = 1.53 mW/g



Date/Time: 06/23/03 14:45:34

Test Laboratory: ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH

File Name: [DOLPHIN 9500\\_2450\\_Ch1\\_front.da4](#)**DOLPHIN 9500\_2450\_Ch1\_front****DUT: Handheld device Wireless LAN 802.11b; Type: DOLPHIN 9500, D9500-03; Serial: #1  
Program: LAN 2450 body**

Communication System: LAN 2450; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz ( $\sigma = 1.94$  mho/m,  $\epsilon_r = 52.3$ ,  $\rho = 1000$  kg/m<sup>3</sup>)

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.4, 4.4, 4.4); Calibrated: 11/29/2002
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2002
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**LAN 2450 body/Area Scan (101x241x1):** Measurement grid: dx=10mm, dy=10mm

Reference Value = 1.03 V/m

Power Drift = 0.2 dB

Maximum value of SAR = 0.0186 mW/g

**LAN 2450 body/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

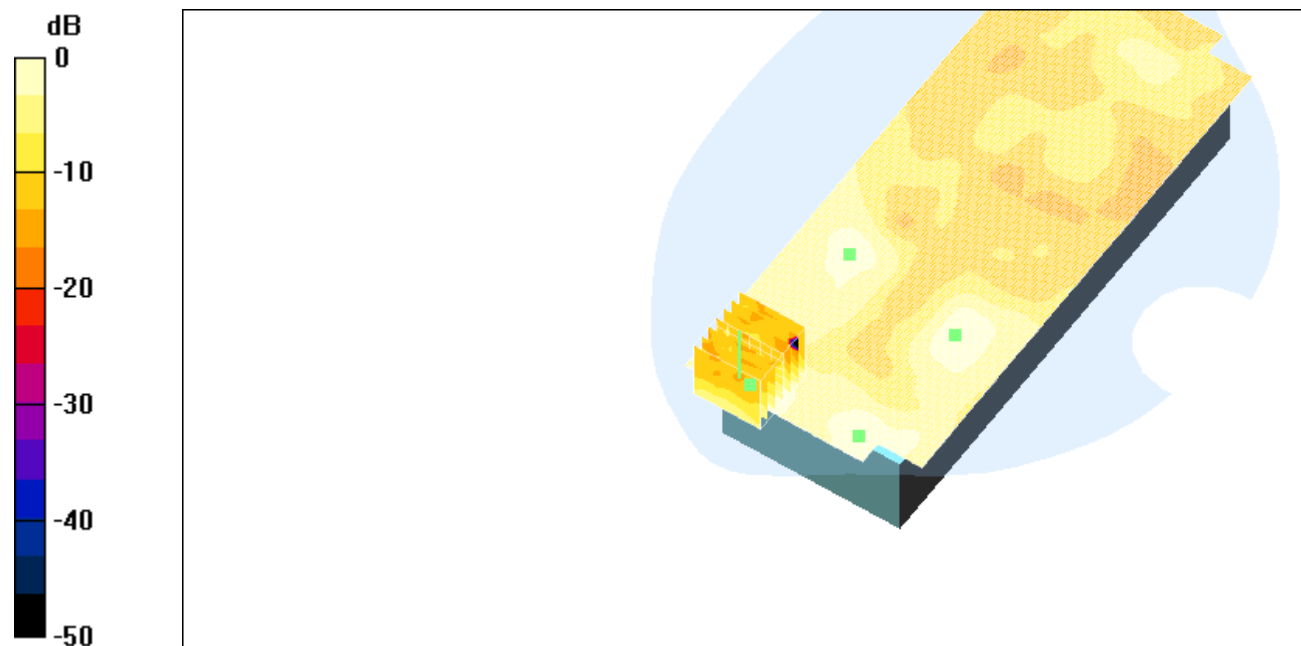
Peak SAR (extrapolated) = 0.0372 W/kg

SAR(1 g) = 0.0177 mW/g; SAR(10 g) = 0.00906 mW/g

Reference Value = 1.03 V/m

Power Drift = 0.2 dB

Maximum value of SAR = 0.0198 mW/g



0 dB = 0.0198mW/g

Date/Time: 06/23/03 15:44:48

Test Laboratory: ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH

File Name: [DOLPHIN 9500\\_2450\\_Ch6\\_front.da4](#)**DOLPHIN 9500\_2450\_Ch6\_front****DUT: Handheld device Wireless LAN 802.11b; Type: DOLPHIN 9500, D9500-03; Serial: #1**  
**Program: LAN 2450 body**

Communication System: LAN 2450; Frequency: 2437 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz ( $\sigma = 1.94$  mho/m,  $\epsilon_r = 52.3$ ,  $\rho = 1000$  kg/m<sup>3</sup>)

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.4, 4.4, 4.4); Calibrated: 11/29/2002
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2002
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**LAN 2450 body/Area Scan (121x101x1):** Measurement grid: dx=10mm, dy=10mm

Reference Value = 1.16 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.0125 mW/g

**LAN 2450 body/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

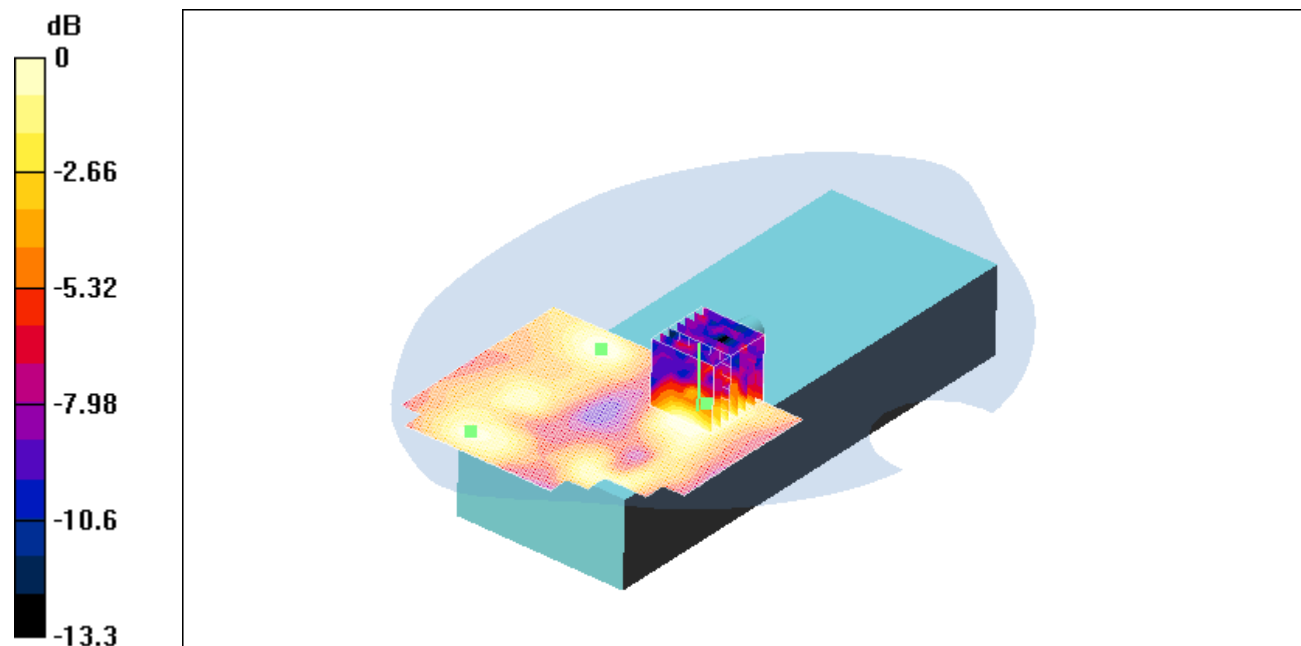
Peak SAR (extrapolated) = 0.0195 W/kg

SAR(1 g) = 0.0108 mW/g; SAR(10 g) = 0.00591 mW/g

Reference Value = 1.16 V/m

Power Drift = -0.1 dB

Maximum value of SAR = 0.0115 mW/g



0 dB = 0.00961mW/g

Date/Time: 06/24/03 08:32:20

Test Laboratory: ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH

File Name: [DOLPHIN 9500\\_2450\\_Ch11\\_front\\_.da4](#)**DOLPHIN 9500\_2450\_Ch11\_front\_**

**DUT: Handheld device Wireless LAN 802.11b; Type: DOLPHIN 9500, D9500-03; Serial: #1**  
**Program: LAN 2450 body**

Communication System: LAN 2450; Frequency: 2462 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz ( $\sigma = 1.94$  mho/m,  $\epsilon_r = 52.3$ ,  $\rho = 1000$  kg/m<sup>3</sup>)

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.4, 4.4, 4.4); Calibrated: 11/29/2002
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2002
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**LAN 2450 body/Area Scan (121x181x1):** Measurement grid: dx=10mm, dy=10mm

Reference Value = 1.12 V/m

Power Drift = 0.5 dB

Maximum value of SAR = 0.0151 mW/g

**LAN 2450 body/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

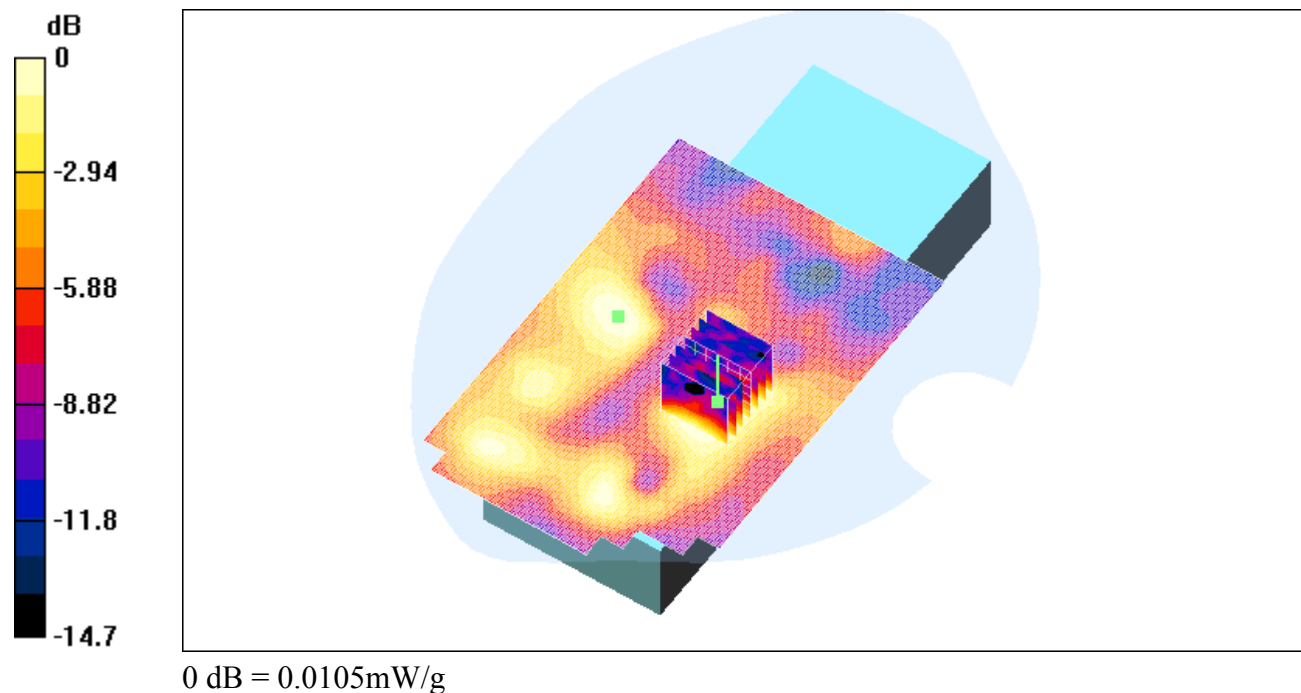
Peak SAR (extrapolated) = 0.022 W/kg

SAR(1 g) = 0.0129 mW/g; SAR(10 g) = 0.00684 mW/g

Reference Value = 1.12 V/m

Power Drift = 0.05 dB

Maximum value of SAR = 0.0142 mW/g



Date/Time: 06/24/03 11:18:00

Test Laboratory: ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH

File Name: [DOLPHIN 9500\\_2450\\_Ch1\\_back.da4](#)**DOLPHIN 9500\_2450\_Ch1\_back****DUT: Handheld device Wireless LAN 802.11b; Type: DOLPHIN 9500, D9500-03; Serial: #1**  
**Program: LAN 2450 body**

Communication System: LAN 2450; Frequency: 2412 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz ( $\sigma = 1.94$  mho/m,  $\epsilon_r = 52.3$ ,  $\rho = 1000$  kg/m<sup>3</sup>)

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.4, 4.4, 4.4); Calibrated: 11/29/2002
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2002
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**LAN 2450 body/Area Scan (121x141x1):** Measurement grid: dx=10mm, dy=10mm

Reference Value = 3.56 V/m

Power Drift = -0.03 dB

Maximum value of SAR = 0.329 mW/g

**LAN 2450 body/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

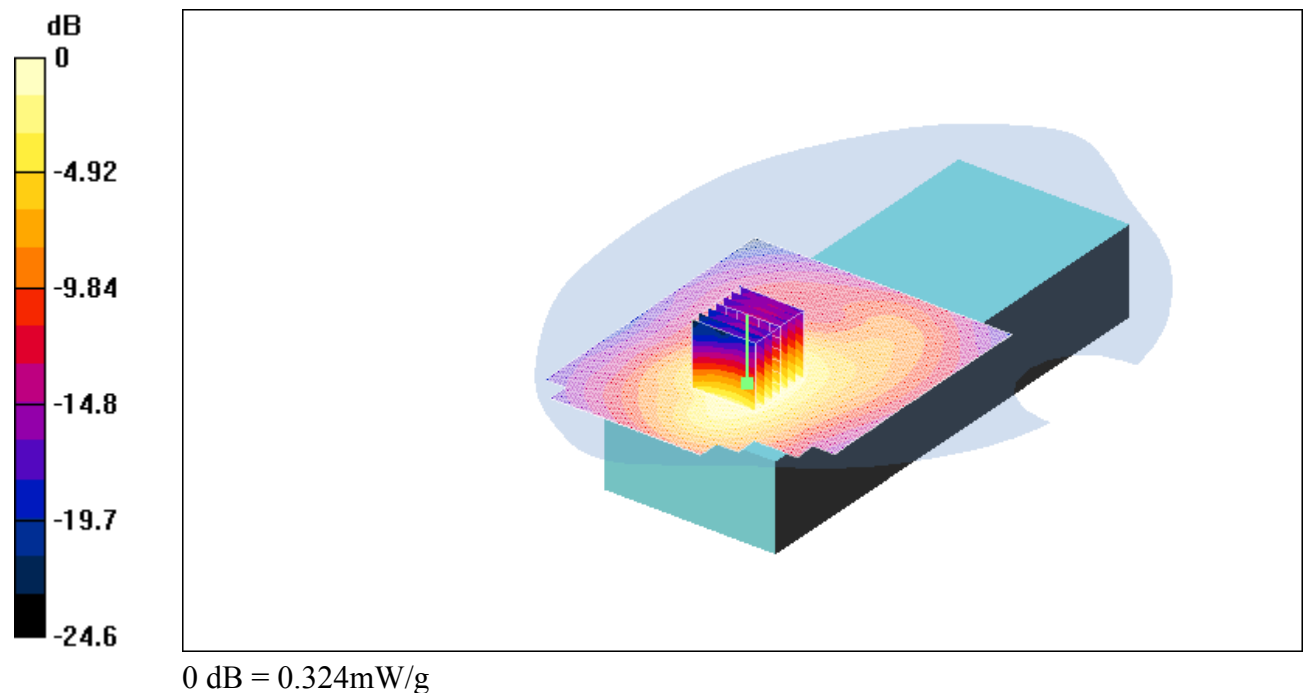
Peak SAR (extrapolated) = 0.527 W/kg

SAR(1 g) = 0.299 mW/g; SAR(10 g) = 0.161 mW/g

Reference Value = 3.56 V/m

Power Drift = -0.03 dB

Maximum value of SAR = 0.324 mW/g



Date/Time: 06/24/03 10:28:10

Test Laboratory: ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH

File Name: [DOLPHIN 9500\\_2450\\_Ch6\\_back.da4](#)**DOLPHIN 9500\_2450\_Ch6\_back****DUT: Handheld device Wireless LAN 802.11b; Type: DOLPHIN 9500, D9500-03; Serial: #1**  
**Program: LAN 2450 body**

Communication System: LAN 2450; Frequency: 2437 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz ( $\sigma = 1.94$  mho/m,  $\epsilon_r = 52.3$ ,  $\rho = 1000$  kg/m<sup>3</sup>)

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.4, 4.4, 4.4); Calibrated: 11/29/2002
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2002
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**LAN 2450 body/Area Scan (121x141x1):** Measurement grid: dx=10mm, dy=10mm

Reference Value = 3.5 V/m

Power Drift = -0.07 dB

Maximum value of SAR = 0.304 mW/g

**LAN 2450 body/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

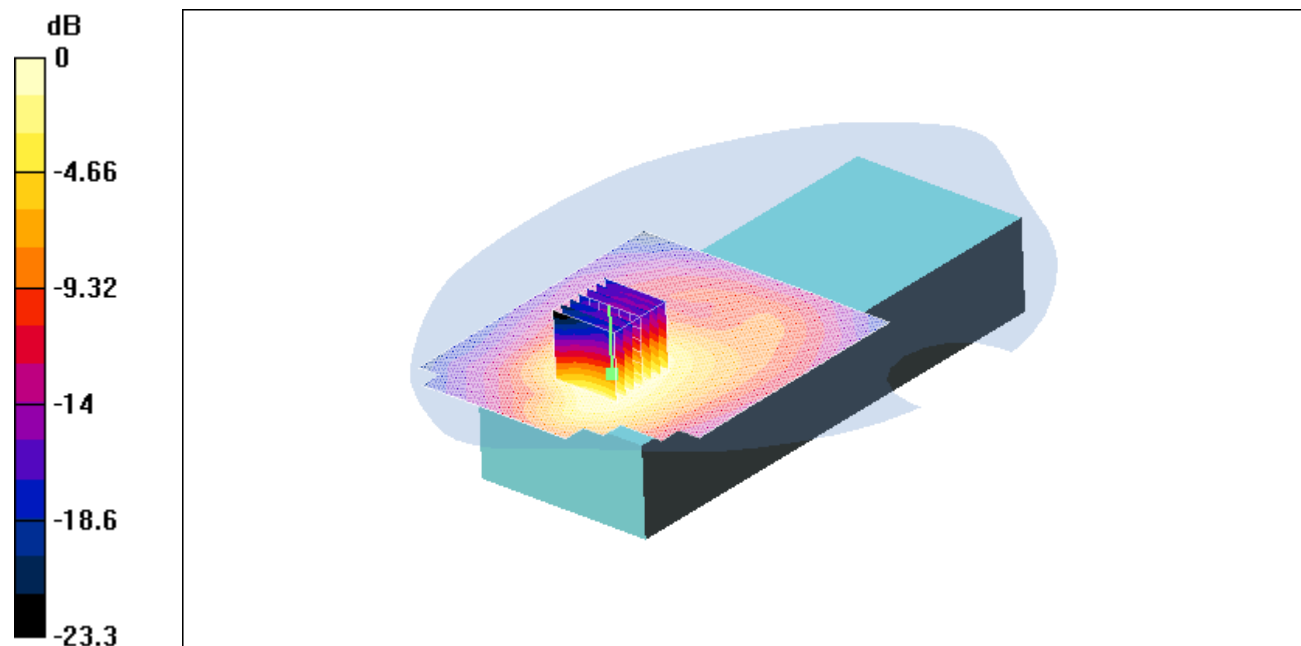
Peak SAR (extrapolated) = 0.506 W/kg

SAR(1 g) = 0.284 mW/g; SAR(10 g) = 0.153 mW/g

Reference Value = 3.5 V/m

Power Drift = -0.07 dB

Maximum value of SAR = 0.307 mW/g



0 dB = 0.307mW/g

Date/Time: 06/24/03 09:24:49

Test Laboratory: ELECTRONIC TECHNOLOGY SYSTEMS DR. GENZ GMBH

File Name: [DOLPHIN 9500\\_2450\\_Ch11\\_back.da4](#)**DOLPHIN 9500\_2450\_Ch11\_back**

**DUT: Handheld device Wireless LAN 802.11b; Type: DOLPHIN 9500, D9500-03; Serial: #1**  
**Program: LAN 2450 body**

Communication System: LAN 2450; Frequency: 2462 MHz; Duty Cycle: 1:1

Medium: Muscle 2450 MHz ( $\sigma = 1.94$  mho/m,  $\epsilon_r = 52.3$ ,  $\rho = 1000$  kg/m<sup>3</sup>)

Phantom section: Flat Section

DASY4 Configuration:

- Probe: ET3DV6 - SN1711; ConvF(4.4, 4.4, 4.4); Calibrated: 11/29/2002
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn522; Calibrated: 9/11/2002
- Phantom: SAM 12; Type: TP-1217; Serial: QD000P40CA
- Measurement SW: DASY4, V4.1 Build 47; Postprocessing SW: SEMCAD, V1.6 Build 115

**LAN 2450 body/Area Scan (121x181x1):** Measurement grid: dx=10mm, dy=10mm

Reference Value = 3.7 V/m

Power Drift = -0.03 dB

Maximum value of SAR = 0.182 mW/g

**LAN 2450 body/Zoom Scan (7x7x7)/Cube 0:** Measurement grid: dx=5mm, dy=5mm, dz=5mm

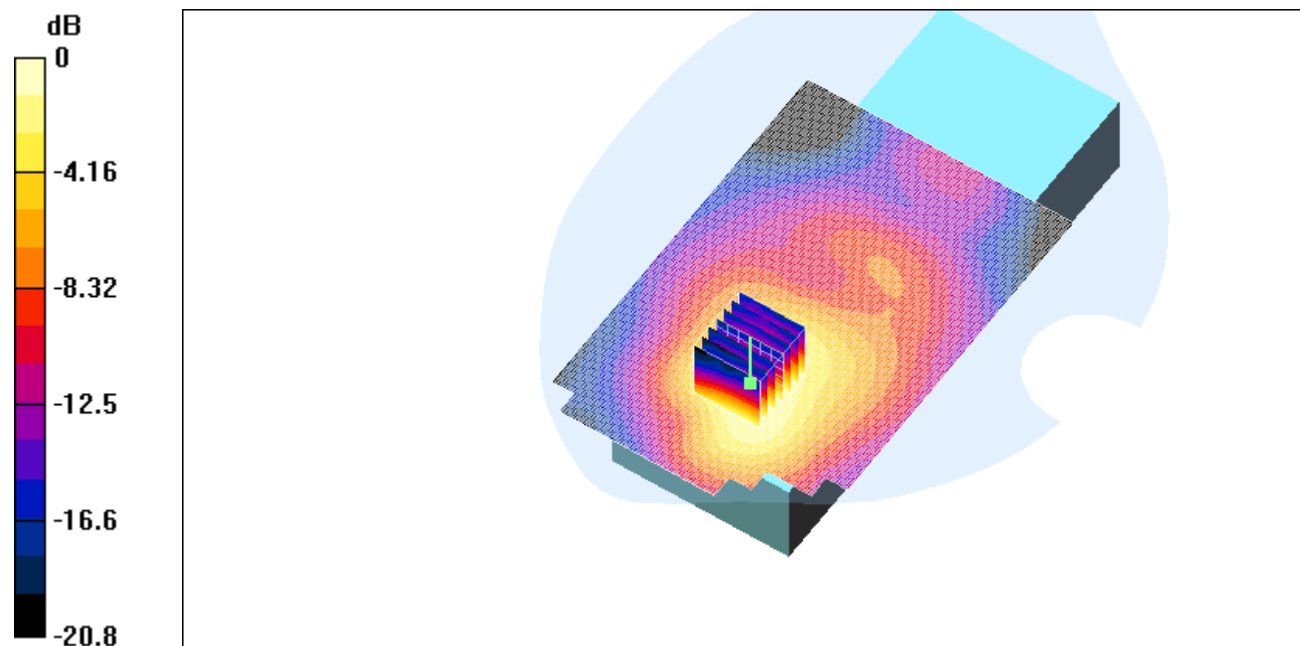
Peak SAR (extrapolated) = 0.298 W/kg

SAR(1 g) = 0.166 mW/g; SAR(10 g) = 0.0897 mW/g

Reference Value = 3.7 V/m

Power Drift = -0.03 dB

Maximum value of SAR = 0.177 mW/g



0 dB = 0.177mW/g

## Appendix C

### Pictures

## Appendix

### C Pictures



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REGISTRATION NUMBER: U9M20306-4895-S-8

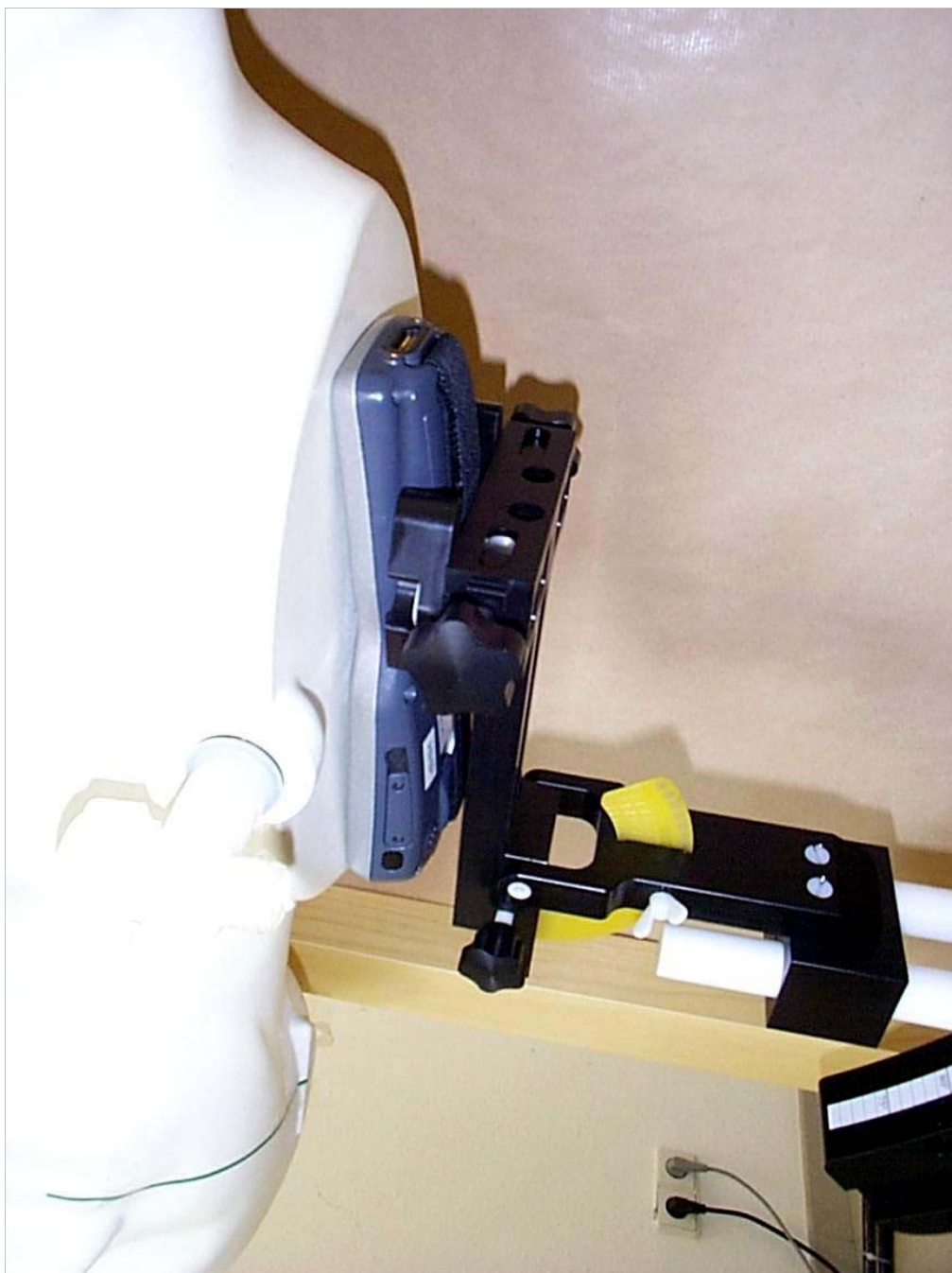
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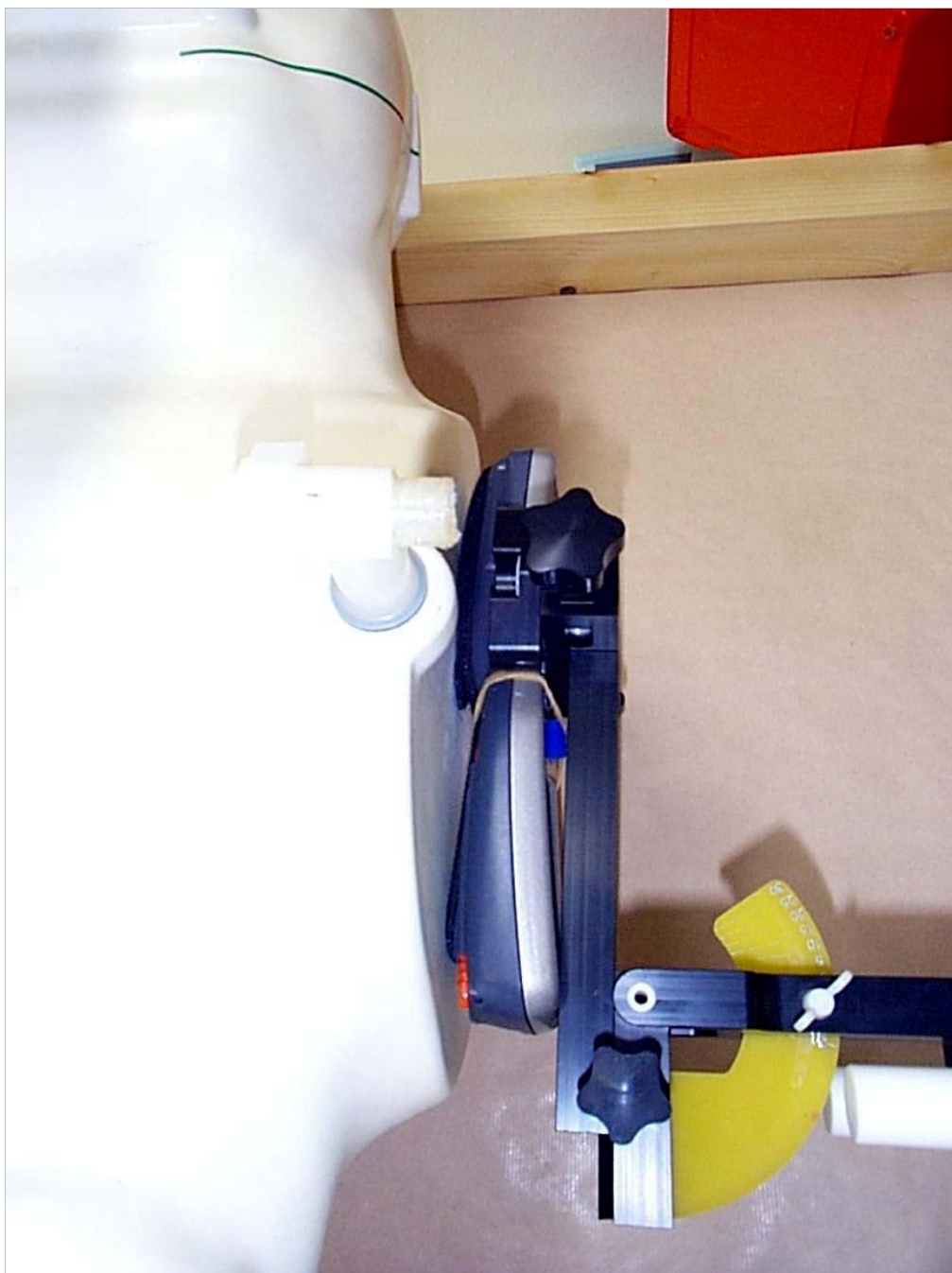
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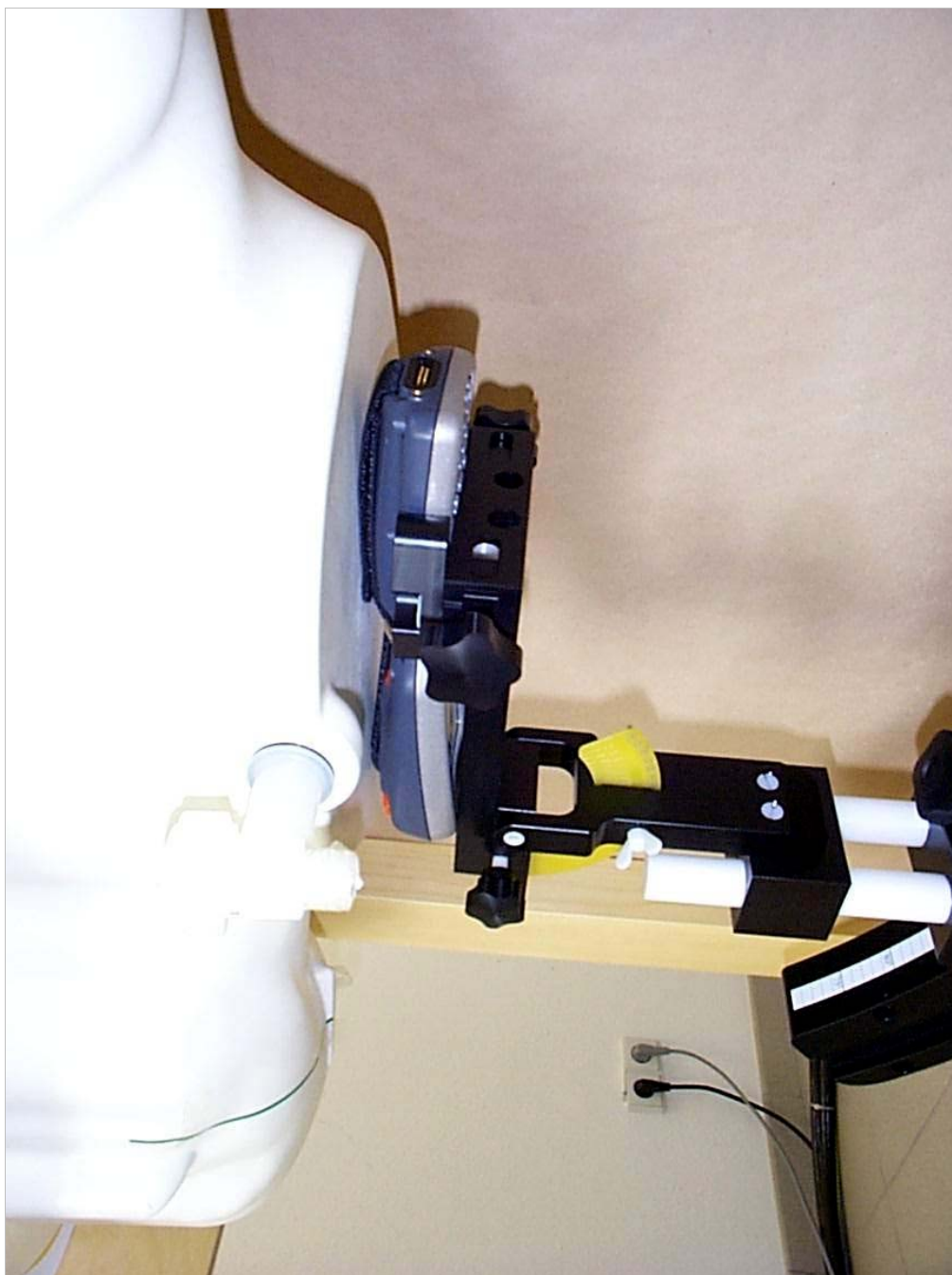
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