



**ELECTRONIC TECHNOLOGY SYSTEMS
DR. GENZ GMBH**

TEST - REPORT

SAR Compliance Test Report

Test report no.:

G5M206070065-S-8

SAR



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1 General Information

1.1 Notes

The purpose of conformity testing is to increase the probability of adherence to the essential requirements or conformity specifications, as appropriate.

The complexity of the technical specifications, however, means that full and thorough testing is impractical for both technical and economic reasons.

Furthermore, there is no guarantee that a test sample which has passed all the relevant tests conforms to a specification.

The existence of the tests nevertheless provides the confidence that the test sample possesses the qualities as maintained and that its performance generally conforms to representative cases of communications equipment.

The test results of this test report relate exclusively to the item tested as specified in 1.5.

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I attest to the accuracy of data. All measurements reported herein were performed by me or were made under my supervision and are correct to the best of my knowledge and belief. I assume full responsibility for the completeness of these measurements and vouch for the qualification of all persons taking them.

Tester:

18.07.2006

M. Cersovsky

i.s. 

Date

ETS-Lab.

Name

Signature

Technical responsibility for area of testing:

18.07.2006

N. Kaspar



Date

ETS

Name

Signature

1.2 Testing laboratory

1.2.1 Location

ELECTRONIC TECHNOLOGY SYSTEM DR. GENZ GMBH (ETS)
Storkower Straße 38c
D-15526 Reichenwalde b. Berlin
Germany
Telephone : +49 33631 888 00
Fax : +49 33631 888 660

1.2.2 Details of accreditation status

ACCREDITED TESTING LABORATORY

DAR-REGISTRATION NUMBER: DAT-P-201/96

FCC FILED TEST LABORATORY REG. No. 96970

BLUETOOTH QUALIFICATION TEST FACILITY (BQTF)

ACCREDITED BY BLUETOOTH QUALIFICATION REVIEW BOARD

INDUSTRY CANADA FILED TEST LABORATORY REG. No. IC 3470

A2LA ACCREDITED Certificate Number 1983-01

Statement: The tests documented within this report are carried out in accordance with the scope of accreditation of test laboratory ETS Dr. Genz GmbH

1.3 Details of approval holder

Name	: Pantech Co., Ltd.
Street	: Sinsong Center Bldg. 8th Fl., 25-12, Yeouido-dong
Town	: Yeoungdeungpo-gu, Seoul
Country	: Korea
Telephone	: +82-2-3660-5862
Fax	: +82-2-3660-5990
Contact	: Mr. B.W. Kim
E-Mail	: bwkim@pantech.co.kr

1.4 Manufacturer: (if applicable)

Name :
Street :
Town :
Country :

1.5 Application details

Date of receipt of application : 11.07.2006
Date of receipt of test item : 11.07.2006
Date of test : 13.07.2006 - 14.07.2006

1.6 Test item

FCC ID : JYCPG-3700
Description of test item : Triple Band GSM 900 (E-GSM)/DCS 1800/PCS 1900 (with WAP & GPRS)
Type identification : PG-6200
Serial number : without; Identical prototype
Device category : PCB (Licensed Base Station)

Technical data

TX Frequency range : 1850,2 - 1909,8 MHz
RX Frequency range : 1930,2 - 1989,8 MHz
Max. Conducted RF output power : PCS 1900 / 29,97 dBm (993,12 mW)
Power supply : 3,8 V DC rechargeable battery
Antenna Tx : integral
Antenna RX : integral
Additional information : Tx and Rx. antenna are the same.
This procedure is requested by customer. This device contains 900 / 1800 MHz not operational in U. S. Territories. This filing is only applicable for 1900 MHz operations.

1.7 Test Results

Max. SAR Measurement (Head) : 1.06 W/kg (averaged over 1 gram)

Max. SAR Measurement (Body) : 1.42 W/kg (averaged over 1 gram)

This EUT has been shown to be capable of compliance for localized specific absorption rate (SAR) for uncontrolled environment/general population exposure limits specified in Radio Protection Standard – Series No. 3 and ANSI/IEEE Std. C95.1-1992 and had been tested in accordance with the measurement procedures specified in Radio communications (Electromagnetic Radiation – Human Exposure) Standard 2003, FCC/OET Bulletin 65 Supplement C (2001) and IEEE Std. 1528-2003, December 2003.

1.8 Test standards

Standards : - Radio communications (Electromagnetic Radiation – Human Exposure) Standard 2003
- IEEE Std. 1528-2003, December 2003

FCC Rule Part(s) : - FCC OET Bulletin 65, Supplement C, Edition 01-01

2 Technical test

2.1 Summary of test results

Applicable Configuration

Handset (Head)	X
Handset (Body)	X
Headset (Head)	
Body Worn Equipment	

EUT complies with the RF radiation exposure limits of the FCC as shown by the SAR measurement results. These measurements are taken to simulate the RF effects exposure under worst-case conditions. The EUT complies with the requirements in respect to all parameters subject to the test. The test results and statements relate only to the item(s) tested.

Please note that the absorption and distribution of electromagnetic energy in the body are very complex phenomena that depend on the mass, shape, and size of the body, the orientation of the body with respect to the field vectors, and the electrical properties of both the body and the environment. Other variables that may play a substantial role in possible biological effects are those that characterize the environment (e.g. ambient temperature, air velocity, relative humidity, and body insulation) and those that characterize the individual (c.g. age, gender, activity level, debilitation, or disease). Because innumerable factors may interact to determine the specific biological outcome of an exposure to electromagnetic fields, any protection guide shall consider maximal amplification of biological effects as a result of field-body interactions, environmental conditions, and physiological variables. [1]

In case of multiple hotspots the secondary hotspots within 2 dB of the maximum SAR value will be recorded and displayed in the measurement plots. The secondary hotspots with a peak SAR value below 0.5 W/kg will not be measured by the system, due to the high margin to the limits.

2.2 Test environment

Room temperature	: 22,1 - 22,6 ° C
Liquid temperature	: 22,0 - 22,3 ° C
Relative humidity content	: 20 ... 75 %
Air pressure	: 86 ... 103 kPa
Details of power supply	: 3,8 V DC

2.3 Test equipment utilized

No.	Measurement device:	Type:	Manufacturer:
ETS 0449	Stäubli Robot	RX90B L	Stäubli
ETS 0450	Stäubli Robot Controller	CS/MBs&p	Stäubli
ETS 0451	DASY 4 Measurement Server		Schmid & Partner
ETS 0452	Control Pendant		Stäubli
ETS 0453	Compaq Computer	Pentium IV, 2 GHz,	Schmid & Partner
ETS 0454	Dabu Acquisition Electronics	DAE3V1	Schmid & Partner
ETS 0455	Dummy Probe		Schmid & Partner
ETS 0456	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner
ETS 0457	Dosimetric E-Field Probe	ET3DV6	Schmid & Partner
ETS 0458	Dosimetric H-Field Probe	H3DV6	Schmid & Partner
ETS 0479	System Validation Kit	D300V3	Schmid & Partner
ETS 0480	System Validation Kit	D450V3	Schmid & Partner
ETS 0459	System Validation Kit	D900V2	Schmid & Partner
ETS 0460	System Validation Kit	D1800V2	Schmid & Partner
ETS 0461	System Validation Kit	D1900V2	Schmid & Partner
ETS 0462	System Validation Kit	D2450V2	Schmid & Partner
ETS 0463	Probe Alignment Unit	LBV2	Schmid & Partner
ETS 0464	SAM Twin phantom	V 4.0	Schmid & Partner
ETS 0513	Flat phantom	V 4.4	Schmid & Partner
ETS 0465	Mounting Device	V 3.1	Schmid & Partner
ETS 0224a	Millivoltmeter	URV 5	Rohde & Schwarz
ETS 0219	Power sensor	NRV-Z2	Rohde & Schwarz
ETS 0268	RF signal generator	SMP 02	Rohde & Schwarz
ETS 0322	Insertion unit	URV5-Z4	Rohde & Schwarz
ETS 0466	Directional Coupler	HP 87300B	HP
ETS0231	Radio Communication Tester	CMD65	Rohde & Schwarz
ETS 0467	Universal Radio Communication Tester	CMU 200	Rohde & Schwarz
ETS 0468	Network Analyzer 300 kHz to 3 GHz	8753C	Agilent
ETS 0469	Dielectric Probe Kit	85070C	Agilent
ERS 0480	Validation Dipol	DB 3	EMCO

2.4 Definitions

2.4.1 SAR

The specific absorption rate (SAR) is defined as the time derivative of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dV) of a given density (ρ_t), expressed in watts per kilogram (W/kg)

$$\text{SAR} = \frac{d(dW)}{dt(dm)} = \frac{d}{dt} \left(\frac{dW}{\rho_t dV} \right) = \frac{\sigma}{\rho_t} |E_t|^2$$

where:

$$\frac{dW}{dt} = \int_v E \cdot J dV = \int_v \sigma E^2 dV$$

2.4.2 Uncontrolled Exposure

The general population/uncontrolled exposure limits are applicable to situations in which the general public may be exposed or in which persons who are exposed as a consequence of their employment may not be made fully aware of the potential for exposure or cannot exercise control over their exposure. Members of the general public would come under this category when exposure is not employment-related; for example, in the case of a wireless transmitter that exposes persons in its vicinity. Warning labels placed on low-power consumer devices such as cellular telephones are not considered sufficient to allow the device to be considered under the occupational/controlled category, and the general population/uncontrolled exposure limits apply to these devices. [2]

2.4.3 Controlled Exposure

In general, occupational/controlled exposure limits are applicable to situations in which persons are exposed as a consequence of their employment, who have been made fully aware of the potential for exposure and can exercise control over their exposure. This exposure category is also applicable when the exposure is of a transient nature due to incidental passage through a location where the exposure levels may be higher than the general population/uncontrolled limits, but the exposed person is fully aware of the potential for exposure and can exercise control over his or her exposure by leaving the area or by some other appropriate means. Awareness of the potential for RF exposure in a workplace or similar environment can be provided through specific training as part of a RF safety program. If appropriate, warning signs and labels can also be used to establish such awareness by providing prominent information on the risk of potential exposure and instructions on the risk of potential exposure and instructions on methods to minimize such exposure risks. [2]

2.5 Measurement System Description

2.5.1 System Setup

Measurements are performed using the DASY4 automated dosimetric assessment system (figure 1) made by Schmid & Partner Engineering AG (SPEAG) in Zurich, Switzerland.



Figure 1

The DASY4 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- An unit to operate the optical surface detector which is connected to the EOC.
- The Electro-optical converter (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the measurement server.
- The functions of the measurement server is to perform the time critical task such as signal filtering, surveillance of the robot operation, fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 2000 or Windows NT.
- DASY4 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes (see Application Notes).
- System validation dipoles allowing to validate the proper functioning of the system.

2.5.2 Phantom Description



Figure 2

The SAM twin phantom V4.0 (figure 2) is a fiberglass shell phantom with 2 mm shell thickness. It has three measurement areas:

- Left hand
- Right hand
- Flat phantom

The phantom is integrated in a wooden table.

The bottom plate of the table contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids).

A cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on the cover are possible.

On the phantom top, three reference markers are provided to identify the phantom positions with respect to the robot.

2.5.3 Tissue Simulating Liquids

The parameters of the tissue simulating liquid strongly influence the SAR. The parameters for the different frequencies are defined in the corresponding compliance standards (e.g., EN 50361, IEEE P1528-2003, Radiocommunications (Electromagnetic Radiation – Human Exposure) Standard 2003).

Tissue dielectric properties

Frequency (MHz)	Head		Body	
	Relative Dielectric Constant (ϵ_r)	Conductivity (σ) (S/m)	Relative Dielectric Constant (ϵ_r)	Conductivity (σ) (S/m)
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
1450	40.5	1.20	54.0	1.30
1800	40.0	1.40	53.3	1.52
1900	40.0	1.40	53.3	1.52
2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73

2.5.4 Device Holder

The DASY device holder (figure 3.1 and 3.2) is designed to cope with different positions given in the standard. It has two scales for the device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The rotation centers for both scales is the ear opening. Thus the device needs no repositioning when changing the angles.



Figure 3.1



Figure 3.2

The DASY device holder has been made out of low-loss POM material having the following dielectric parameters: relative permittivity $\epsilon = 3$ and loss tangent $\delta = 0.02$. The amount of dielectric material has been reduced in the closest vicinity of the device, since measurements have suggested that the influence of the clamp on the test results could thus be lowered.

2.5.5 Probes

The SAR measurements were conducted with the dosimetric probe ET3DV6 (figure 4), designed in the classical triangular configuration and optimized for dosimetric evaluation. [3] The probe is constructed using the thick film technique; with printed resistive lines on ceramic substrates. The probe is equipped with an optical multifiber line ending at the front of the probe tip. It is connected to the EOC box on the robot arm and provides an automatic detection of the phantom surface. Half of the fibers are connected to a pulsed infrared transmitter, the other half to a synchronized receiver. As the probe approaches the surface, the reflection from the surface produces a coupling from the transmitting to the receiving fibers. This reflection increases first during the approach, reaches maximum and then decreases. If the probe is flatly touching the surface, the coupling is zero. The distance of the coupling maximum to the surface is independent of the surface reflectivity and largely independent of the surface to probe angle. The DASY4 software reads the reflection during a software approach and looks for the maximum using a 2nd order fitting. The approach is stopped at reaching the maximum.



Figure 4

Probe Specifications

Calibration:	In air from 10 MHz to 2.5 GHz In brain and muscle simulating tissue at Frequencies of 835 MHz, 900 MHz, 1800 MHz, 1900 MHz and 2450 MHz Calibration certificates please find attached.
Frequency:	10 MHz to > 3 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz)
Directivity:	± 0.2 dB in HSL (rotation around probe axis) ± 0.4 dB in HSL (rotation normal probe axis)
Dynamic Range:	5 μ W/g to > 100 mW/g;
Linearity:	± 0.2 dB
Dimensions:	Overall length: 330 mm Tip length: 16 mm Body diameter: 12 mm Tip diameter: 6.8 mm Distance from probe tip to dipole centers: 2.7 mm
Application:	General dosimetry up to 3 GHz Compliance tests of mobile phones Fast automatic scanning in arbitrary phantoms

2.6 Test System Specification

Positioner

Robot:	Stäubli Animation Corp. Robot Model: RX90B L
Repeatability:	0.02 mm
No. of axis:	6

Data Acquisition Electronic (DAE) System

Cell Controller

Processor:	Pentium IV
Clock Speed:	2.0 GHz
Operating System:	Windows 2000
Data Card:	DASY4 PC-Board
Data Converter	
Features:	Signal Amplifier, multiplexer, A/D converter, & control logic
Software:	DASY4 software
Connecting Lines:	Optical downlink for data and status info. Optical uplink for commands and clock

PC Interface Card

Function:	24 bit (64 MHz) DSP for real time processing Link to DAE3 16 bit A/D converter for surface detection system serial link to robot direct emergency stop output for robot
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E-Field Probes

Model:	ET3DV6 SN1711
Construction:	Triangular core fiber optic detection system
Frequency:	10 MHz to 6 GHz
Linearity:	± 0.2 dB (30MHz to 3 GHz)

Phantom

Phantom:	SAM Twin Phantom (V4.0)
Shell Material:	Fiberglass
Thickness:	2.0 ± 0.2 mm

2.7 Measurement Procedure

The evaluation was performed using the following procedure:

1. The SAR measurement was taken at a selected spatial reference point to monitor power variations during testing. This fixed location point was measured and used as a reference value.
2. The SAR distribution at the exposed side of the head was measured at a distance of 3.9 mm from the inner surface of the shell. The area covered the entire dimension of the head and the horizontal grid spacing was 10 mm x 10 mm.
3. Based on the area scan data, the area of the maximum absorption was determined by spline interpolation. Around this point, a volume of 30 mm x 30 mm x 30 mm (fine resolution volume scan, zoom scan) was assessed by measuring 5 x 5 x 5 points. On this basis of this data set, the spatial peak SAR value was evaluated with the following procedure:
 - a. The data at the surface was extrapolated, since the center of the dipoles is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.2 mm. The extrapolation was based on a least square algorithm [4]. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.
 - b. The maximum interpolated value was searched with a straight-forward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1g or 10g) were computed using the 3D-Spline interpolation algorithm. The 3D-spline is composed of three one-dimensional splines with the “Not a knot” condition (in x, y, and z directions) [4] [5]. The volume was integrated with the trapezoidal algorithm. One thousand points (10 x 10 x 10) were interpolated to calculate the average.
 - c. All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.
4. The SAR reference value, at the same location as procedure # 1, was re-measured. If the value changed by more than 5 %, the evaluation is repeated.

2.8 Reference Points

2.8.1 Ear Reference Points

Figure 5.1 shows the front, back and side views of SAM. The point "M" is the reference point for the center of mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15 mm posterior to the entrance to ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 5.2. The plane passing through the two ear reference points and M is defined as the Reference Plane. The line N-F (Neck-Front) perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 5.3). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines should be marked on the external phantom shell to facilitate handset positioning. Posterior to the N-F line, the thickness of the N-F line, the ear is truncated as illustrated in Figure 5.2. The ear truncation is introduced to avoid the handset from touching the ear lobe, which can cause unstable handset positioning at the cheek. [6]

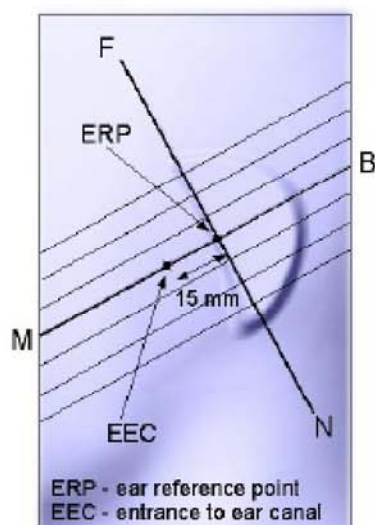
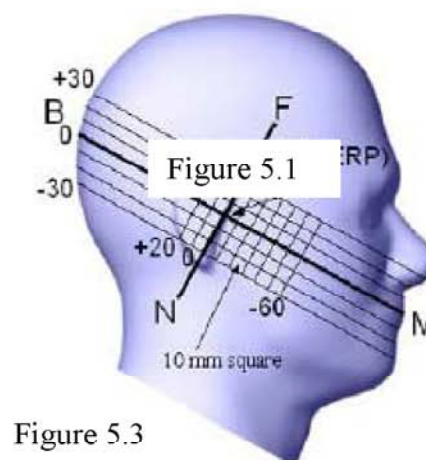


Figure 5.2



2.8.2 Handset Reference Points

Two imaginary lines on the handset were defined: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width w_t of the handset at the level of the acoustic output (point A on Figures 6.1 and 6.2), and the midpoint of the width w_b of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 6.1). The two lines intersect at point A. For many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. The vertical centerline is not necessarily parallel to the front face of the handset (see Figure 6.2), especially for clamshell handsets, handsets with flip pieces, and other irregularly-shaped handsets. [6]

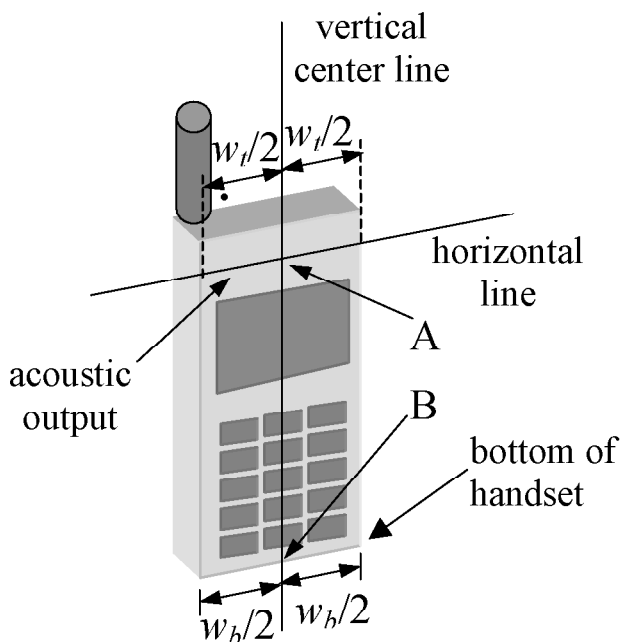


Figure 6.1

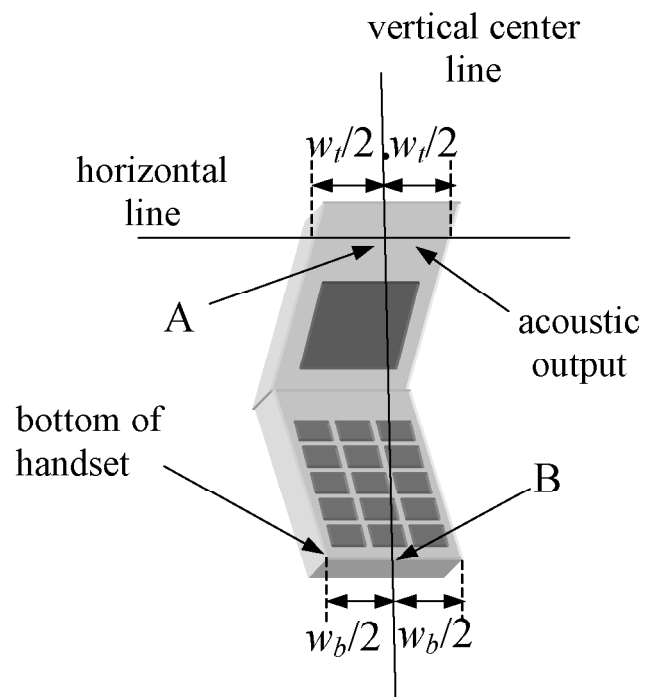


Figure 6.2

2.9 Test Positions

2.9.1 "Cheek" / "Touch" Position

The EUT was positioned close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 7), such that the plane defined by the vertical center line and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.

The EUT was translated towards the phantom along the line passing through RE and LE until the handset touches the pinna.

While maintaining the handset in this plane, the EUT was rotated it around the LE-RE line until the vertical centerline was in the plane normal to MB-NF including the line MB (called the reference plane).

The EUT was rotated around the vertical centerline until the handset (horizontal line) was symmetrical with respect to the line NF.

While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the handset contact with the pinna, the EUT was rotated about the line NF until any point on the handset was in contact with a phantom point below the pinna (cheek). [6] See Figure 7.

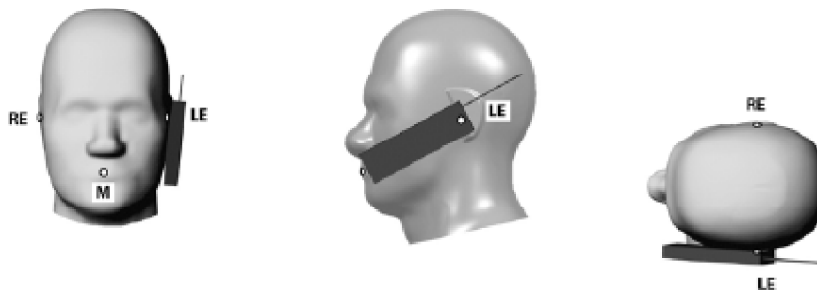


Figure 7

2.9.2 "Tilted" Position

The EUT was in "cheek position".

While maintaining the orientation of the handset move the handset away from the pinna along the line passing through RE and LE in order to enable a rotation of the handset by 15 degrees.

The EUT was rotated around the horizontal line by 15 degrees.

While maintaining the orientation of the handset, the EUT was moved towards the phantom on a line passing through RE and LE until any part of the handset touched the ear. The tilted position is obtained when the contact is on the pinna. If the contact was at any location other than the pinna (e.g., the antenna with the back of the phantom head), the angle of the handset would be reduced. In this case, the tilted position is obtained if any part of the handset was in contact with the pinna as well as a second part of the handset was in contact with the phantom (e.g., the antenna with the back of the head). [6] See Figure 8.

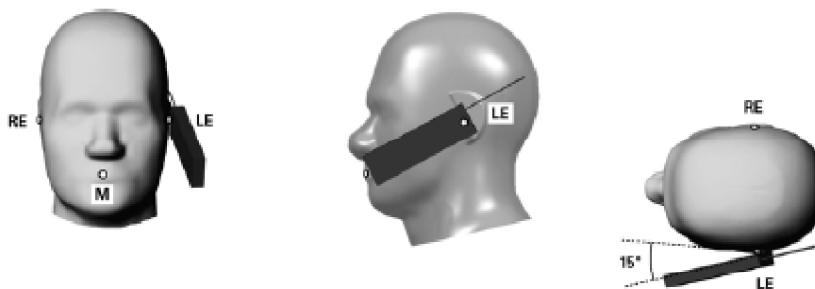


Figure 8

2.9.3 Belt Clip/Holster Configuration

Test configurations for body-worn operated EUTs are carried out while the belt-clip and/or holster is attached to the EUT and placed against a flat phantom in a regular configuration (see Figure 9). An EUT with a headset output is tested with a headset connected to the device.

Body dielectric parameters are used.

There are two categories for accessories for body-worn operation configurations:

1. accessories not containing metallic components
2. accessories containing metallic components.

When the EUT is equipped with accessories not containing metallic components the tests are done with the accessory that dictates the closest spacing to the body. For accessories containing metallic parts a test with each one is implemented. If the multiple accessories share an identical metallic component (e.g. the same metallic belt-clip used with different holsters with no other metallic components) only the accessory that has the closest spacing to the body is tested.

In case that a EUT authorized to be body-worn is not supplied or has no options to be operated with any accessories, a test configuration where a separation distance between the back of the device and the flat phantom is used. All test position spacings are documented.

Transmitters operating in front of a person's face (e.g. push-to-talk configurations) are tested for SAR compliance with the front of the device positioned to face the flat platform. SAR Compliance tests for shoulder, waist or chest-worn transmitters are carried out with the accessories including headsets and microphones attached to the device and placed against a flat phantom in a regular configuration.

The SAR measurements are performed to investigate the worst-case positioning. This is documented and used to perform Body SAR testing. [2].



Figure 9

2.9.4 Headset Configuration

Headsets which have their radiating structure in close proximity to the head are measured according to the following conditions.

- Head tissue liquid is used.
- The EUT is positioned on the surface of the head of phantom according the picture below. Right and left position is tested according to the normal use (see figure 10).
- Additional metallic parts like clips or others are subject of testing, too.



Figure 10

Headsets which have their radiating structure in close proximity to the body are tested as body worn equipment.

2.10 Measurement uncertainty

The uncertainty budget has been determined for the DASY4 system performance check according to IEEE Std. 1528-2003, December 2003.

Error Description	Tol. (± %)	Prob. dist.	Div.	$(c_i)^1$ (1 g)	Std. unc. (1 g) (± %)	$(v_i)^2$
Measurement System						
Probe Calibration	4.8	N	1	1	4.8	∞
Axial Isotropy	4.7	R	$\sqrt{3}$	0.7	1.9	∞
Hemispherical Isotropy	9.6	R	$\sqrt{3}$	0.7	3.9	∞
Boundary Effects	1.0	R	$\sqrt{3}$	1	0.6	∞
Linearity	4.7	R	$\sqrt{3}$	1	2.7	∞
System Detection Limit	1.0	R	$\sqrt{3}$	1	0.6	∞
Readout Electronics	1.0	N	1	1	1.0	∞
Response Time	0.8	R	$\sqrt{3}$	1	0.5	∞
Integration Time	2.6	R	$\sqrt{3}$	1	1.5	∞
RF Ambient Conditions	3.0	R	$\sqrt{3}$	1	1.7	∞
Probe Positioner	0.4	R	$\sqrt{3}$	1	0.2	∞
Probe Positioning	2.9	R	$\sqrt{3}$	1	1.7	∞
Algorithms for Max. SAR Eval.	1.0	R	$\sqrt{3}$	1	0.6	∞
Test Sample Related						
Device Positioning	2.9	N	1	1	2.9	145
Device Holder	3.6	N	1	1	3.6	5
Power Drift	5.0	R	$\sqrt{3}$	1	2.9	∞
Phantom and Setup						
Phantom Uncertainty	4.0	R	$\sqrt{3}$	1	2.3	∞
Liquid Conductivity (target)	5.0	R	$\sqrt{3}$	0.64	1.8	∞
Liquid Conductivity (meas.)	2.6	N	1	0.64	1.7	∞
Liquid Permittivity (target)	5.0	R	$\sqrt{3}$	0.6	1.7	∞
Liquid Permittivity (meas.)	3.8	N	1	0.6	2.3	∞
Combined Standard Uncertainty					10.4	330
Expanded Uncertainty $k_p = 2$						
Coverage Factor for 95 %					20.8	

The budget is valid for the frequency range 300 MHz - 3 GHz and represent a worst case analysis. For specific tests and configurations, the uncertainty could be considerable smaller.

3 Tissue and System Verification

3.1 Tissue Verification

Dielectric parameters of the simulating liquids were verified using a Dielectric Probe Kit Agilent 85070D to a tolerance of $\pm 5\%$.

Room Temperature: 22,1 - 22,6 °C

	Measured Tissue Parameters	
	1900 MHz Brain	
	Target	Measured
Date		13.07.2006
Liquid Temperature: °C		22,1
Dielectric Constant: ε	40,0	39,9
Conductivity: σ	1,40	1,42

Room Temperature: 22,1 - 22,6 °C

	Measured Tissue Parameters	
	1900 MHz Muscle	
	Target	Measured
Date		14.07.2006
Liquid Temperature: °C		22,1
Dielectric Constant: ε	53,3	51,9
Conductivity: σ	1,52	1,58

3.2 System Verification

Prior to the assessment, the system was verified by using a 1900 MHz validation dipole. Power level of 250 mW was supplied to the dipole antenna placed under the flat section of SAM Phantom. This system validation is valid for a frequency range of 900 ± 100 MHz.

The system was verified to a tolerance of ± 10 %.

Liquid Temperature: 22,0 - 22,3 ° C
Room Temperature: 22,1 - 22,6 ° C
Liquid Depth: >15.5 cm

System Dipole Validation Target & Measurement					
Date	System Validation Kit:	Liquid	Targeted SAR 1g (mW/g)	Measured SAR 1g (mW/g)	Deviation (%)
13.07.2006	D1900V2 SN5d025	1900 MHz Hcad	40,4	42,4	4,95
14.07.2006	D1900V2 SN5d025	1900 MHz Muscle	45,6	46,4	1,75

Comment: Please find attached the measurement plots.

4 Test Results

Procedures Used To Establish Test Signal

The EUT was placed into simulated call mode (e.g. AMPS, Cellular CDMA & PCS CDMA modes) using manufacturers test codes. Such test signals offer a consistent means for testing SAR and are recommended for evaluating SAR [2]. The actual transmission is activated through a base station simulator or similar when test modes are not available or inappropriate for testing the EUT.

The EUT is rechargeable battery operated. The battery used for the SAR measurements was completely charged. The device was tested at full power verified by implementing conducted output power measurements. For confirming of the output power it was tested before and after each SAR measurement. The test was repeated if a conducted power deviation of more than 5 % occurred.

Mixture Type: 1900 MHz Head

Date: 13.07.2006

Liquid Temperature: 22,0 - 22,3 °C

Room Temperature: 22,1 - 22,6 °C

Frequency			Power Drift dBm	Antenna Pos.	Phantom Section	Test Position	SAR (W/kg)
MHz	Channel	Modulation					
1850,2	512	GSM	-0,094	Integral ant1	Right Ear	Cheek	0,638
1880,0	661	GSM	0,067	Integral ant1	Right Ear	Cheek	0,608
1880,0	661	GSM	-0,005	Integral ant1	Right Ear	Tilt	0,135
1909,8	810	GSM	0,076	Integral ant1	Right Ear	Cheek	0,779
1850,2	512	GSM	-0,072	Integral ant1	Left Ear	Cheek	0,890
1880,0	661	GSM	0,070	Integral ant1	Left Ear	Cheek	0,946
1880,0	661	GSM	0	Integral ant1	Left Ear	Tilt	0,115
1909,8	810	GSM	0,084	Integral ant1	Left Ear	Cheek	1,06

Mixture Type: 1900 MHz Muscle

Date: 15.03.2006

Liquid Temperature: 22,0 - 22,3 °C

Room Temperature: 22,1 - 22,6 °C

Frequency			Power Drift dBm	Antenna Pos.	Phantom Section	Test Position	SAR (W/kg)
MHz	Channel	Modulation					
1850,2	512	GSM	0,095	Integral	Flat	Back	1
1880,0	661	GSM	0,028	Integral	Flat	Front	0,057
1880,0	661	GSM	0,013	Integral	Flat	Back	1,22
1909,8	810	GSM	0,086	Integral	Flat	Back	1,42

Note: Device positioning: spacing from flat phantom was adjusted at 0.5 cm.

Limits:

Exposure Limits	SAR (W/kg)	
	Uncontrolled Exposure/General Population Environment	Controlled Exposure/Occupational Environment
Spatial Average SAR (averaged over the whole body)	0.08	0.40
Spatial Peak SAR (averaged over any 1g of tissue)	1.60	8.00
Spatial Peak SAR (Hands, Feet, Ankles, Wrist) (averaged over any 10g of tissue)	4.00	20.00

Notes:

1. Test data represent the worst case SAR value and test procedure used are according to OET Bulletin 65, Supplement C (01-01).
2. All modes of operation were investigated.

5 References

- [1] ANSI/IEEE C95.3 - 1991, *IEEE Recommended Practice for the Measurement of Potentially Hazardous Electromagnetic fields, 300 kHz to 100 GHz*, New York: IEEE, Aug. 1992
- [2] Federal Communications Commission, OET Bulletin 65 (Edition 97-01), Supplement C (Edition 01-01), *Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields*, July 2001.
- [3] T. Schmid, O. Egger, N. Kuster, *Automated E-field scanning system for dosimetric assessments*, IEEE Transaction on Microwave Theory and Techniques, vol. 44, Jan. 1996, pp. 105-113.
- [4] W. Gander, *Computermathematics*, Birkhaeuser, Basel, 1992.
- [5] W.H. Press, S.A. Teukolsky, W.T. Vetterling, and B.P. Flannery, *Numerical Recipes in C, The Art of Scientific Computing*, Second edition, Cambridge University Press, 1992.
- [6] IEEE Standards Coordinating Committee 34 – IEEE Std. 1528-2003, December 2003 *Recommended Practice for Determining the Peak Spatial-Average Absorption Rate (SAR) in the Human Body Due to Wireless Communications Devices: Experimental Techniques*.
- [7] DASY4 *Dosimetric Assessment System Manual*; Draft; September 6, 2002; Schmid & Partner Engineering AG
- [8] Radiation Protection Standard – Series No. 3
- [9] Radiocommunication (Electromagnetic Radiation – Human Exposure) Standard 2003

6 Appendix

1. Appendix A Calibration Certificate D1900V2 SN5d025
ET3DV6 SN1711
DAE3V1-522
2. Appendix B Measurement Plots
3. Appendix C Pictures