

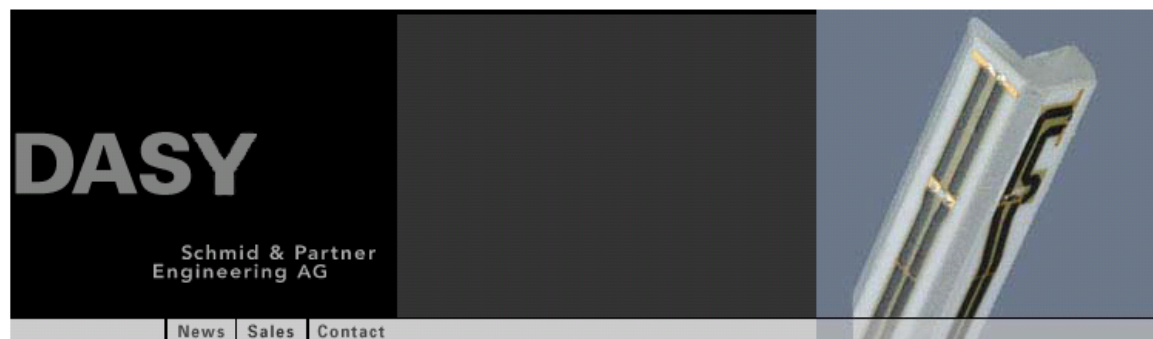
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Author Data Hang Wang	Dates of Test July 28, Aug 4, 2011	Report No RTS-2604-1108-06	FCC ID L6ARDZ21CW

Annex B: Probe and dipole description and calibration certificates

B.1 Probe, measurement chain description, specification and calibration certificate

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DASY Dosimetric Assessment System by Schmid & Partner Engineering AG

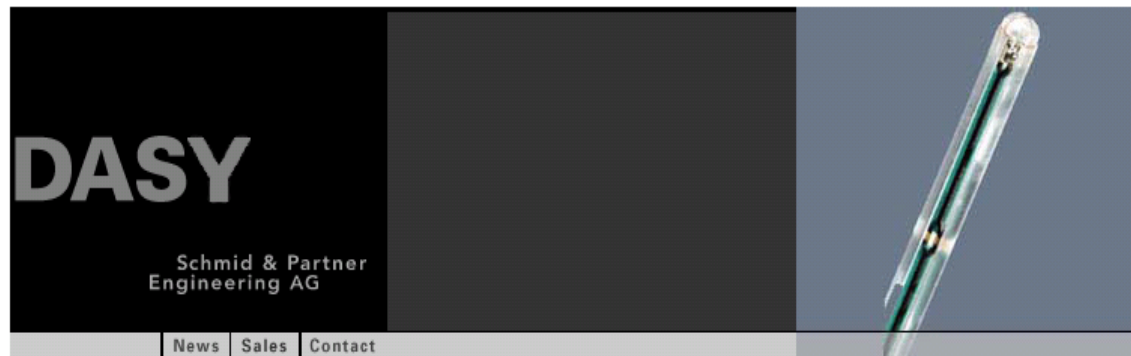


Applications	ER3DV6 ISOTROPIC E-FIELD PROBE FOR GENERAL NEAR-FIELD MEASUREMENTS	
Support & Downloads	 Download Product Flyer (PDF, 192kB)	
Products	Construction One dipole parallel, two dipoles normal to probe axis Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycoether)	
▪ DASY4 Packages	Calibration In air from 100 MHz to 3.0 GHz (absolute accuracy $\pm 6.0\%$, $k=2$)	
▪ EASY4	Frequency 100 MHz to > 6 GHz; Linearity: ± 0.2 dB (100 MHz to 3 GHz)	
▪ Probes - ET3DV6 - Isotropic Dos-Probe - ES3DV3 - Isotropic Dos-Probe - EX3DV4 - Isotropic Dos-Probe - ET1DV3 - D-Probe	Directivity ± 0.2 dB in air (rotation around probe axis) ± 0.4 dB in air (rotation normal to probe axis)	
▪ EUV3 - Universal Vector E-Probe	Dynamic Range 2 V/m to > 1000 V/m; Linearity: ± 0.2 dB	
▪ H3DV6 - Isotropic H-Probe	Dimensions Overall length: 330 mm (Tip: 16 mm) Tip diameter: 8 mm (Body: 12 mm) Distance from probe tip to dipole centers: 2.5 mm	
▪ HUV4 - Universal Vector H-Probe	Application General near-field measurements up to 6 GHz Field component measurements Fast automatic scanning in phantoms	
▪ T1V3 - Temp-Probe		
▪ DP1 - Dummy-Probe		
▪ Data Acquisition System		
▪ Software		
▪ Phantoms		
▪ Robots		
▪ Validation Kits & Calibration Dipoles		
▪ Hearing Aid Compatibility (HAC) Ext		
▪ Tissue Simulating Liquids		
SPEAG Home		

<http://www.dasy4.com/er3.htm>

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DASY Dosimetric Assessment System by Schmid & Partner Engineering AG



Applications
Support & Downloads
Products
▪ DASY4 Packages
▪ EASY4
▪ Probes
ET3DV6 - Isotropic Dos-Probe
ES3DV3 - Isotropic Dos-Probe
EX3DV4 - Isotropic Dos-Probe
ET1DV3 - D-Probe
ER3DV6 - Isotropic E-Probe
EUV3 - Universal Vector E-Probe
HUV4 - Universal Vector H-Probe
T1V3 - Temp-Probe
DP1 - Dummy-Probe
▪ Data Acquisition System
▪ Software
▪ Phantoms
▪ Robots
▪ Validation Kits & Calibration Dipoles
▪ Hearing Aid Compatibility (HAC) Ext
▪ Tissue Simulating Liquids
SPEAG Home

H3DV6 3-DIMENSIONAL H-FIELD PROBE FOR SMALL BAND APPLICATIONS

 [Download Product Flyer \(PDF, 192kB\)](#)

Construction	Three concentric loop sensors with 3.8 mm loop diameters Resistively loaded detector diodes for linear response Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., glycolether)
Frequency	200 MHz to 3 GHz (absolute accuracy $\pm 6.0\%$, $k=2$); Output linearized
Directivity	± 0.25 dB (spherical isotropy error)
Dynamic Range	10 mA/m to 2 A/m at 1 GHz
E-Field Interference	< 10% at 3 GHz (for plane wave)
Dimensions	Overall length: 330 mm (Tip: 40 mm) Tip diameter: 6 mm (Body: 12 mm) Distance from probe tip to dipole centers: 3 mm
Application	General magnetic near-field measurements up to 3 GHz Field component measurements Surface current measurements Measurements in air or liquids Low interaction with the measured field

<http://www.dasy4.com/h3d.htm>

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All measurements were performed to the nearest element point as per the C63.19 standard. Offset distances were entered in the DASY4 software so that the measurement was to the nearest element.

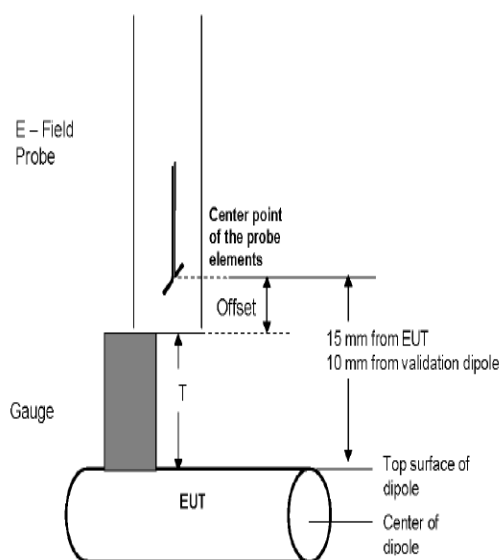
Figures 1 and 2, provided by the manufacturer, illustrate detail of the probe tip and its dimensions.

ER3DV6 E-Field probe: The distances from the probe tip to the closest points on the dipole sensors are 1.45mm for X and Y and 1.25mm for Z. From the probe tip to the center of the sensors is 2.5mm.

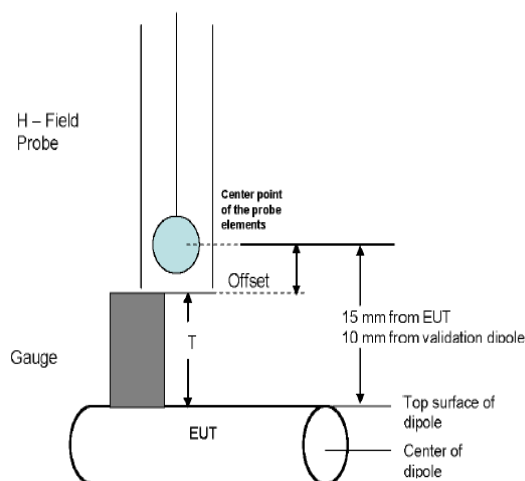
H3DV6 H-Field probe: The distance from the probe tip to the closest point of the X, Y and Z loop sensors is 1.1mm. From the probe tip to the center of the sensor is 3.00mm.



E-Field Probe (ER3DV6)



H-Field Probe (H3DV6)



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The following information is from the system manufacturer user manual describing the process chain:

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i} \quad (20.1)$$

with V_i = compensated signal of channel i (i = x, y, z)
 U_i = input signal of channel i (i = x, y, z)
 cf = crest factor of exciting field (DASY parameter)
 dcp_i = diode compression point (DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$\text{E - fieldprobes : } E_i = \sqrt{\frac{V_i}{Norm_i \cdot ConvF}}$$

$$\text{H - fieldprobes : } H_i = \sqrt{V_i} \cdot \frac{a_{i0} + a_{i1}f + a_{i2}f^2}{f}$$

with V_i = compensated signal of channel i (i = x, y, z)
 $Norm_i$ = sensor sensitivity of channel i (i = x, y, z)
 $\mu V/(V/m)^2$ for E-field Probes
 $ConvF$ = sensitivity enhancement in solution
 a_{ij} = sensor sensitivity factors for H-field probes
 f = carrier frequency [GHz]
 E_i = electric field strength of channel i in V/m
 H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2} \quad (20.2)$$

The measurement / integration time per point is > 500 ms, as per the system manufacturer:

The time response of the field probes has been assessed by exposing the probe to a well-controlled field producing signals larger than HAC E- and H-fields of class M4. The signal response time is evaluated as the time required by the system to reach 90% of the expected final value after an on/off switch of the power source with an integration time of 500 ms and a probe response time of <5 ms. In the current implementation, DASY4 waits longer than 100 ms after having reached the grid point before starting a measurement, i.e., the response time uncertainty is negligible.

If the device under test does not emit a CW signal, the integration time applied to measure the electric field at a specific point may introduce additional uncertainties due to the discretization. The tolerances for the different systems had the worst-case of 2.6%.

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Calibration Laboratory of
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Engineering AG
 Zeughausstrasse 43, 8004 Zurich, Switzerland



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Accreditation No.: **SCS 108**

Client **RTS (RIM Testing Services)**

Certificate No: **ER3-2285_Mar10**

CALIBRATION CERTIFICATE

Object **ER3DV6 - SN:2285**

Calibration procedure(s) **QA CAL-02.v5 and QA CAL-25.v2**
Calibration procedure for E-field probes optimized for close near field evaluations in air

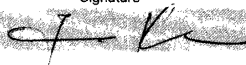
Calibration date: **March 8, 2010**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	1-Apr-09 (No. 217-01030)	Apr-10
Power sensor E4412A	MY41495277	1-Apr-09 (No. 217-01030)	Apr-10
Power sensor E4412A	MY41498087	1-Apr-09 (No. 217-01030)	Apr-10
Reference 3 dB Attenuator	SN: S5054 (3c)	31-Mar-09 (No. 217-01026)	Mar-10
Reference 20 dB Attenuator	SN: S5086 (20b)	31-Mar-09 (No. 217-01028)	Mar-10
Reference 30 dB Attenuator	SN: S5129 (30b)	31-Mar-09 (No. 217-01027)	Mar-10
Reference Probe ER3DV6	SN: 2328	3-Oct-09 (No. ER3-2328_Oct09)	Oct-10
DAE4	SN: 789	23-Dec-09 (No. DAE4-789_Dec09)	Dec-10
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct10

	Name	Function	Signature
Calibrated by:	Jeton Kastrati	Laboratory Technician	
Approved by:	Katja Pokovic	Technical Manager	

Issued: March 10, 2010

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Certificate No: ER3-2285_Mar10

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Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary:

NORM_{x,y,z}	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization ϕ	ϕ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- NORM(f)_{x,y,z}** = NORM_{x,y,z} * frequency_response (see Frequency Response Chart).
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}**: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy)**: in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).

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ER3DV6 SN:2285

March 8, 2010

Probe ER3DV6

SN:2285

Manufactured:	September 20, 2002
Last calibrated:	March 2, 2009
Recalibrated:	March 8, 2010

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

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ER3DV6 SN:2285

March 8, 2010

DASY - Parameters of Probe: ER3DV6 SN:2285

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu\text{V}/(\text{V}/\text{m})^2$)	1.26	1.42	1.61	$\pm 10.1\%$
DCP (mV) ^A	92.1	94.2	96.0	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc ^E (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	$\pm 1.5\%$
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A numerical linearization parameter: uncertainty not required

^E Uncertainty is determined using the maximum deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

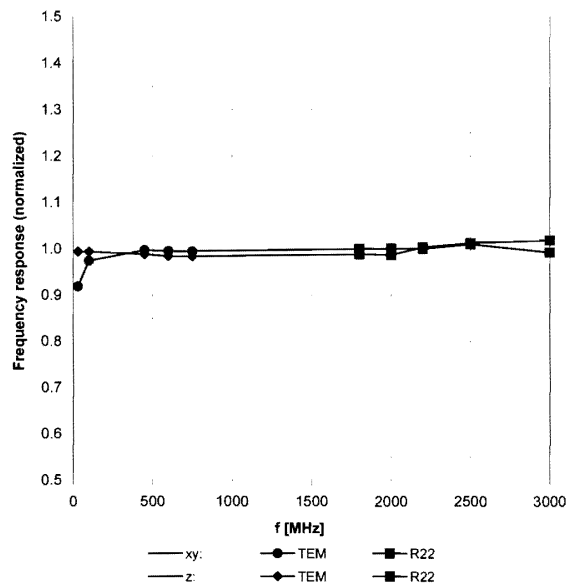
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ER3DV6 SN:2285

March 8, 2010

Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)



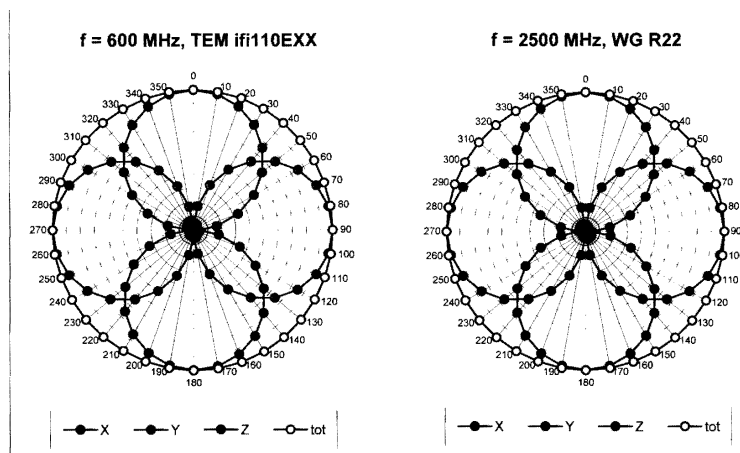
Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

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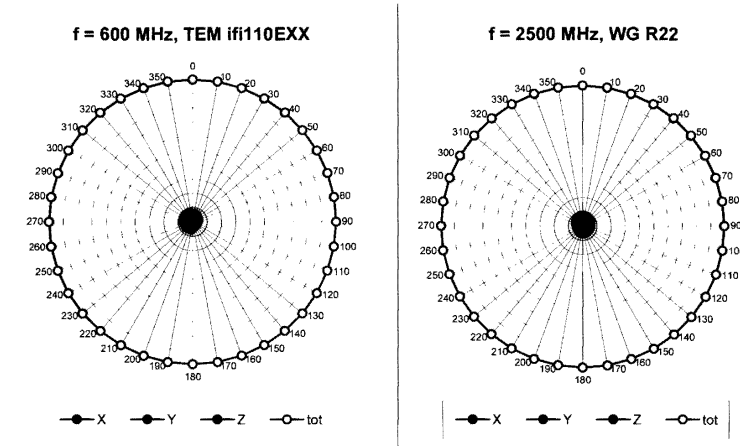
ER3DV6 SN:2285

March 8, 2010

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Receiving Pattern (ϕ), $\vartheta = 90^\circ$

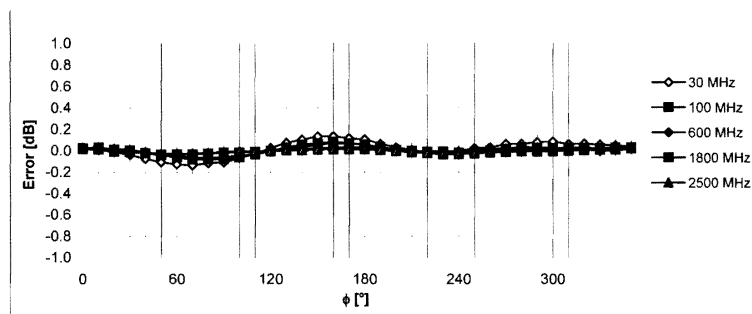


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ER3DV6 SN:2285

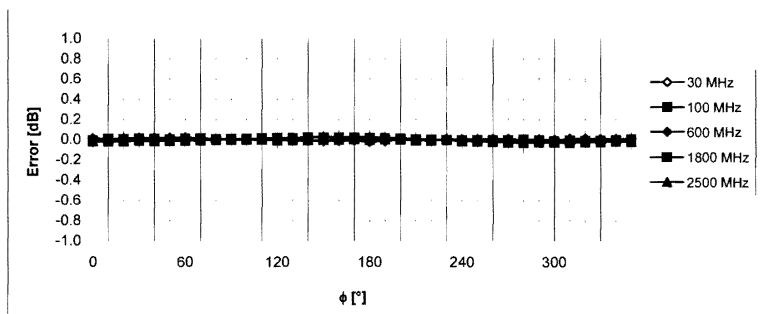
March 8, 2010

Receiving Pattern (ϕ), $\theta = 0^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\theta = 90^\circ$



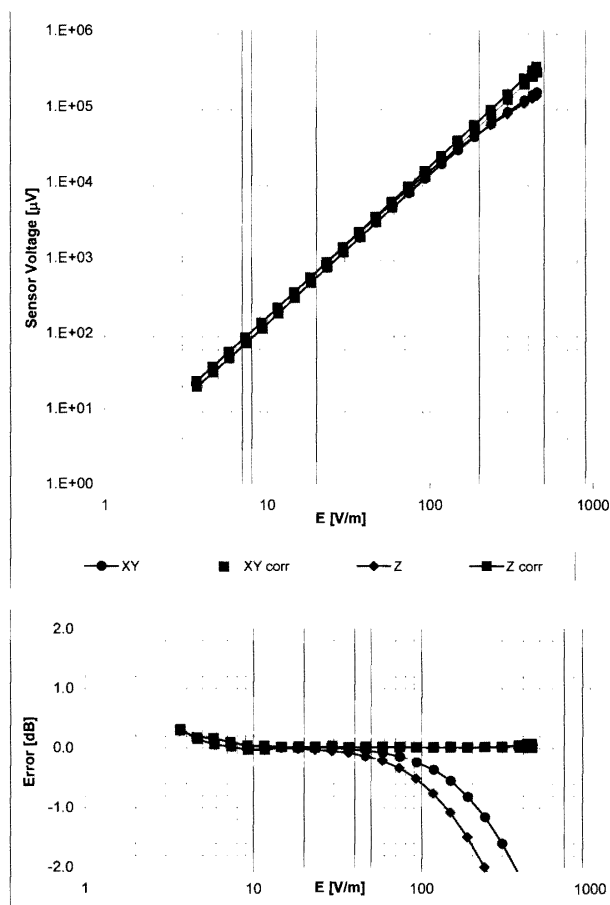
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

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ER3DV6 SN:2285

March 8, 2010

Dynamic Range f(E-field) (Waveguide R22, f = 1800 MHz)



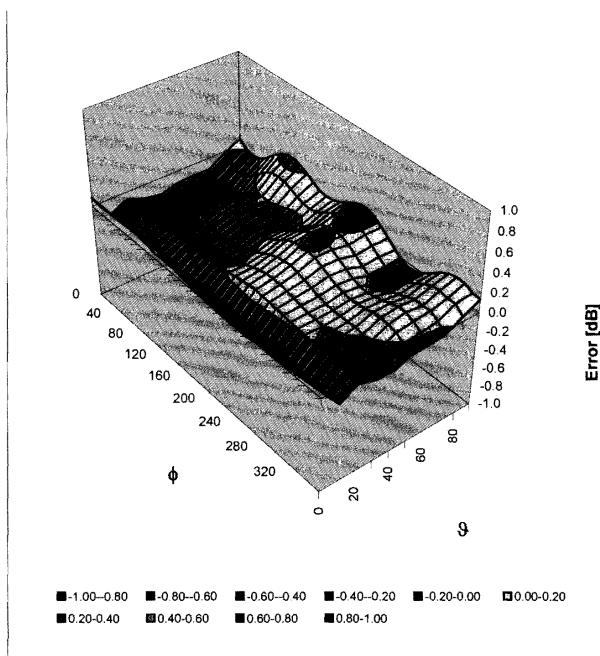
Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

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ER3DV6 SN:2285

March 8, 2010

Deviation from Isotropy in Air Error (ϕ , θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

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ER3DV6 SN:2285

March 8, 2010

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	78.7
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8.0 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

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 Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Client **RTS (RIM Testing Services)**

Certificate No: **H3-6168_Mar10**

CALIBRATION CERTIFICATE

Object **H3DV6 - SN:6168**
 Calibration procedure(s) **QA CAL-03.v5 and QA CAL-25.v2**
Calibration procedure for H-field probes optimized for close near field evaluations in air
 Calibration date: **March 12, 2010**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
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Power sensor E4412A	MY41498087	1-Apr-09 (No. 217-01030)	Apr-10
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Reference 20 dB Attenuator	SN: S5086 (20b)	31-Mar-09 (No. 217-01028)	Mar-10
Reference 30 dB Attenuator	SN: S5129 (30b)	31-Mar-09 (No. 217-01027)	Mar-10
Reference Probe H3DV6	SN: 6182	3-Oct-09 (No. H3-6182_Oct09)	Oct-10
DAE4	SN: 789	23-Dec-09 (No. DAE4-789_Dec09)	Dec-10
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-09)	In house check: Oct-10

Calibrated by: **Claudio Leubler** **Laboratory Technician**
 Approved by: **Katja Pokovic** **Technical Manager**

Issued: March 15, 2010

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Certificate No: H3-6168_Mar10

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Accreditation No.: **SCS 108**

Glossary:

NORM _{x,y,z}	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- $X, Y, Z(f)_{a0a1a2} = X, Y, Z_{a0a1a2} \cdot \text{frequency_response}$ (see Frequency Response Chart).
- DCP_{x,y,z}: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- $A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}$: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the X_{a0a1a2} (no uncertainty required).

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H3DV6 SN:6168

March 12, 2010

Probe H3DV6

SN:6168

Manufactured: July 9, 2003
Last calibrated: March 3, 2009
Recalibrated: March 12, 2010

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

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H3DV6 SN:6168

March 12, 2010

DASY - Parameters of Probe: H3DV6 SN:6168

Basic Calibration Parameters

		Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (A/m / $\sqrt{\mu V}$)	a0	2.76E-3	2.64E-3	3.14E-3	± 5.1%
Norm (A/m / $\sqrt{\mu V}$)	a1	-1.81E-4	-8.57E-5	-2.18E-4	± 5.1%
Norm (A/m / $\sqrt{\mu V}$)	a2	-2.18E-5	-3.81E-5	3.05E-5	± 5.1%
DCP (mV) ^A		81.4	94.7	83.2	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dBuV	C	VR mV	Unc ^E (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	300	± 1.5 %
			Y	0.00	0.00	1.00	300	
			Z	0.00	0.00	1.00	300	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A numerical linearization parameter: uncertainty not required

^E Uncertainty is determined using the maximum deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

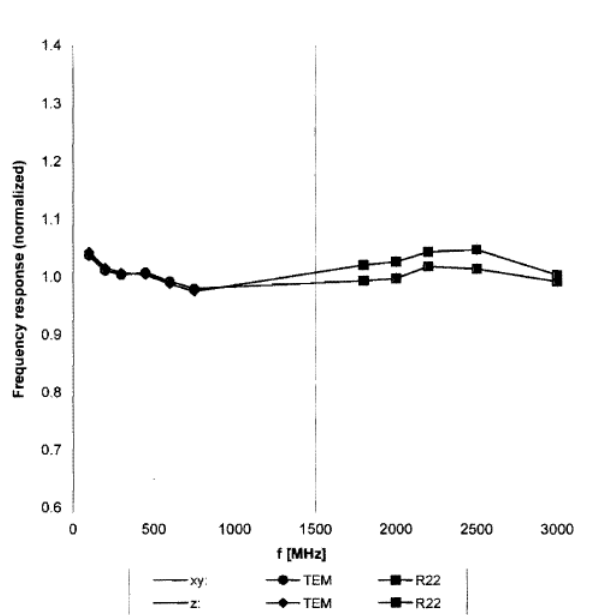
	Document Annex B to Hearing Aid Compatibility RF Emissions Test Report for the BlackBerry® Smartphone model RDZ21CW		Page 20(45)
Author Data Hang Wang	Dates of Test July 28, Aug 4, 2011	Report No RTS-2604-1108-06	FCC ID L6ARDZ21CW

H3DV6 SN:6168

March 12, 2010

Frequency Response of H-Field

(TEM-Cell:ifi110 EXX, Waveguide R22)



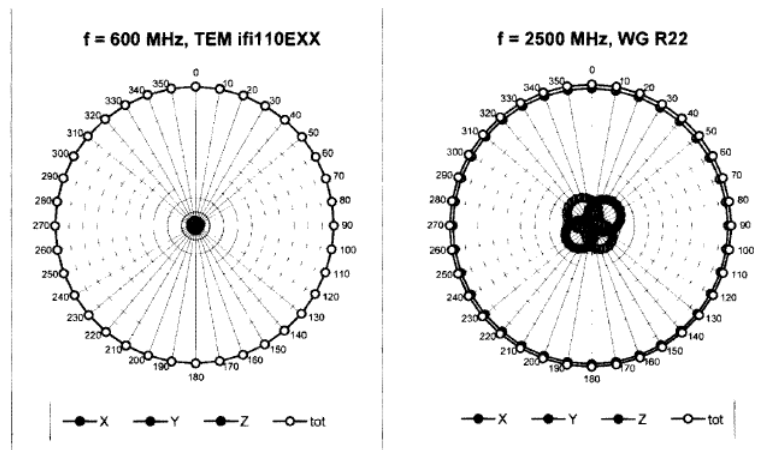
Uncertainty of Frequency Response of H-field: $\pm 6.3\%$ ($k=2$)

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Author Data Hang Wang	Dates of Test July 28, Aug 4, 2011	Report No RTS-2604-1108-06	FCC ID L6ARDZ21CW

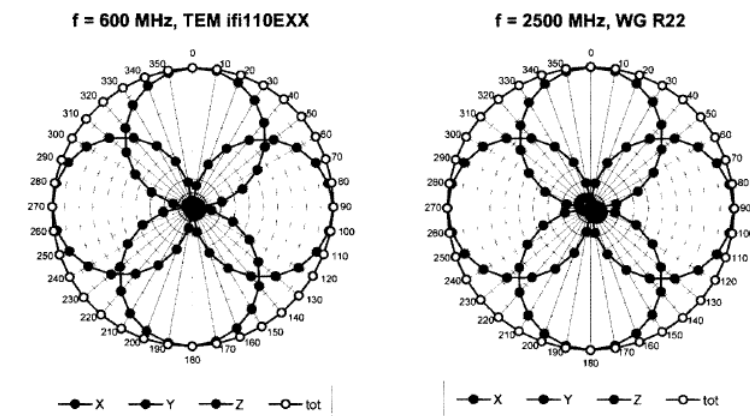
H3DV6 SN:6168

March 12, 2010

Receiving Pattern (ϕ), $\vartheta = 90^\circ$



Receiving Pattern (ϕ), $\vartheta = 0^\circ$

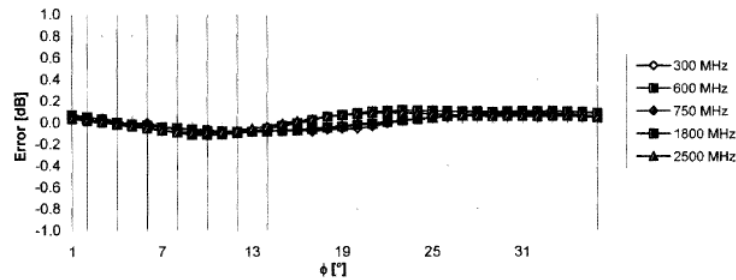


	Document Annex B to Hearing Aid Compatibility RF Emissions Test Report for the BlackBerry® Smartphone model RDZ21CW		Page 22(45)
Author Data Hang Wang	Dates of Test July 28, Aug 4, 2011	Report No RTS-2604-1108-06	FCC ID L6ARDZ21CW

H3DV6 SN:6168

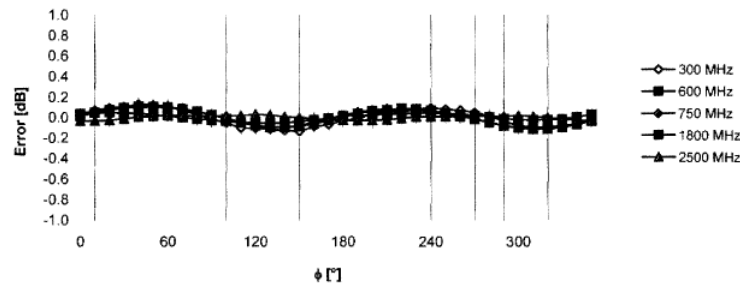
March 12, 2010

Receiving Pattern (ϕ), $\theta = 90^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\theta = 0^\circ$



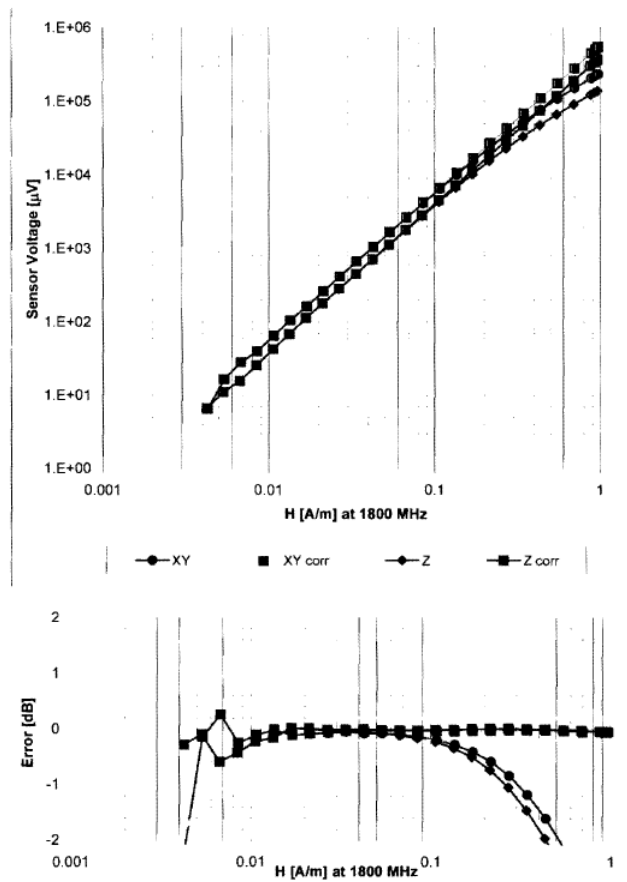
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

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H3DV6 SN:6168

March 12, 2010

Dynamic Range f(H-field) (Waveguide R22, f = 1800 MHz)



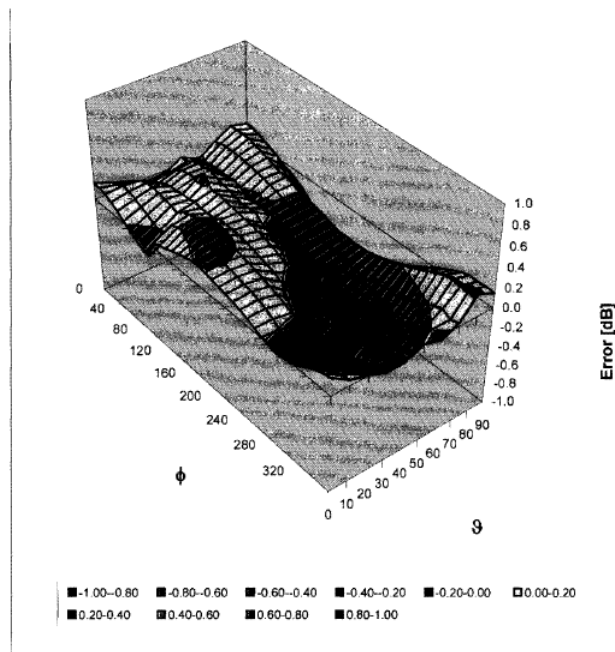
Uncertainty of Linearity Assessment: $\pm 0.6\%$ ($k=2$)

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H3DV6 SN:6168

March 12, 2010

Deviation from Isotropy in Air Error (ϕ , θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

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H3DV6 SN:6168

March 12, 2010

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-232.8
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6.0 mm
Probe Tip to Sensor X Calibration Point	3 mm
Probe Tip to Sensor Y Calibration Point	3 mm
Probe Tip to Sensor Z Calibration Point	3 mm

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Author Data Hang Wang	Dates of Test July 28, Aug 4, 2011	Report No RTS-2604-1108-06	FCC ID L6ARDZ21CW

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Accreditation No.: **SCS 108**

Client **RTS (RIM Testing Services)**

Certificate No: **ER-2286_Jan11**

CALIBRATION CERTIFICATE

Object: **ER3DV6 - SN:2286**

Calibration procedure(s): **QA CAL-02.v6, QA CAL-25.v3**
Calibration procedure for E-field probes optimized for close near field evaluations in air

Calibration date: **January 14, 2011**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	01-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41495277	01-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41498087	01-Apr-10 (No. 217-01136)	Apr-11
Reference 3 dB Attenuator	SN: S5054 (3c)	30-Mar-10 (No. 217-01159)	Mar-11
Reference 20 dB Attenuator	SN: S5086 (20b)	30-Mar-10 (No. 217-01161)	Mar-11
Reference 30 dB Attenuator	SN: S5129 (30b)	30-Mar-10 (No. 217-01160)	Mar-11
Reference Probe ER3DV6	SN: 2328	4-Oct-10 (No. ER3-2328_Oct10)	Oct-11
DAE4	SN: 789	31-Aug-10 (No. DAE4-789_Aug10)	Aug-11
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Oct-09)	In house check: Oct-11
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-10)	In house check: Oct-11

Calibrated by:	Name Marcel Fehr	Function Laboratory Technician	Signature 
Approved by:	Name Katja Pokovic	Function Technical Manager	Signature 

Issued: January 15, 2011

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Author Data Hang Wang	Dates of Test July 28, Aug 4, 2011	Report No RTS-2604-1108-06	FCC ID L6ARDZ21CW

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Accreditation No.: **SCS 108**

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Glossary:

NORM _{x,y,z}	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization ϕ	ϕ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- NORM(f)_{x,y,z}** = NORM_{x,y,z} * frequency_response (see Frequency Response Chart).
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; VR_{x,y,z}**: A, B, C are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy)**: in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).

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ER3DV6 – SN:2286

January 14, 2011

Probe ER3DV6

SN:2286

Manufactured: September 18, 2002
Calibrated: January 14, 2011

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

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ER3DV6- SN:2286

January 14, 2011

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2286

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu\text{V}/(\text{V}/\text{m})^2$)	2.23	1.48	1.51	$\pm 10.1\%$
DCP (mV) ^B	97.6	98.4	97.6	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc ^E (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	179.3	$\pm 3.0\%$
			Y	0.00	0.00	1.00	145.0	
			Z	0.00	0.00	1.00	180.1	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^B Numerical linearization parameter: uncertainty not required.

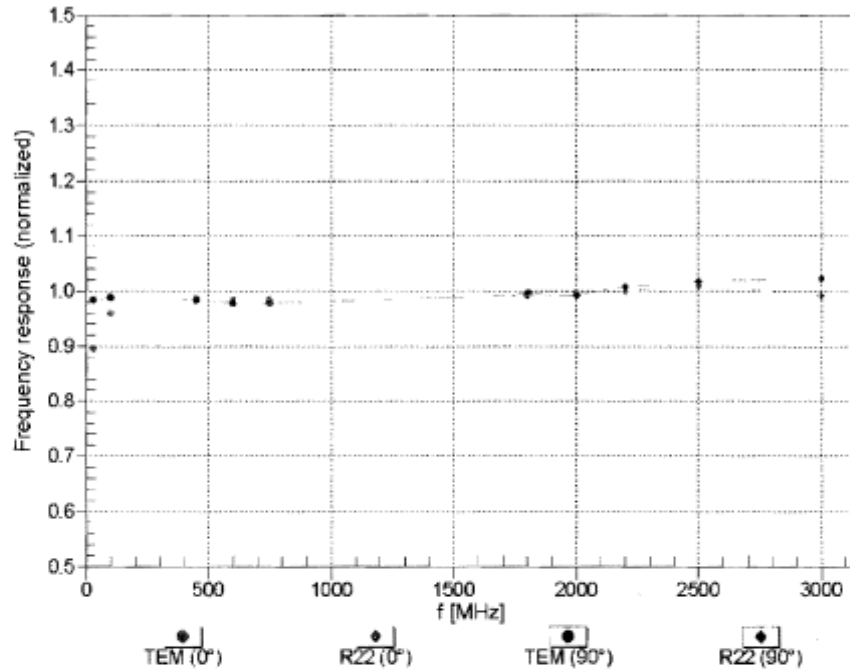
^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

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ER3DV6- SN:2286

January 14, 2011

Frequency Response of E-Field (TEM-Cell:ifi110 EXX, Waveguide: R22)



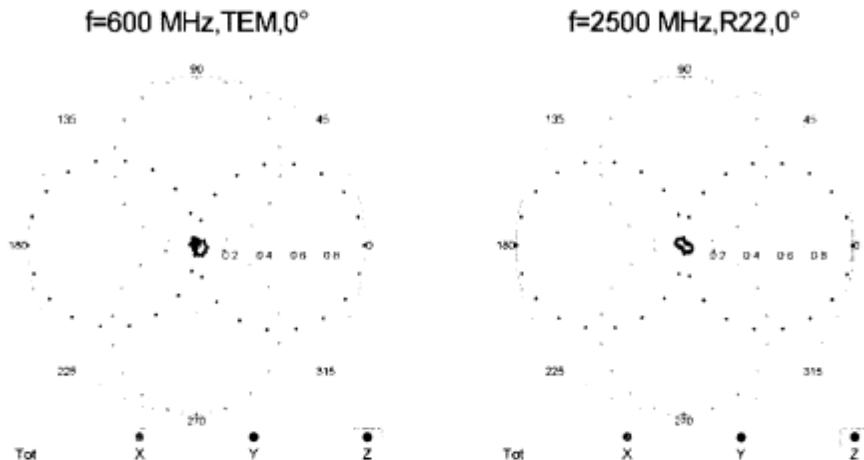
Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

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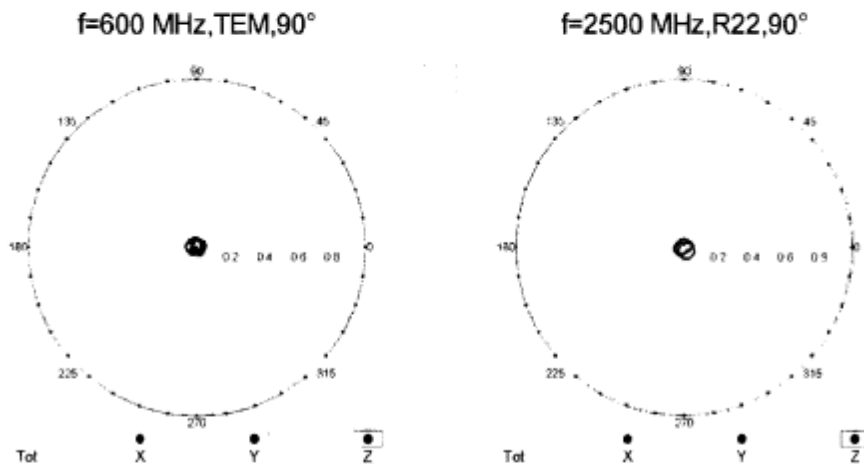
ER3DV6- SN:2286

January 14, 2011

Receiving Pattern (ϕ), $\theta = 0^\circ$



Receiving Pattern (ϕ), $\theta = 90^\circ$

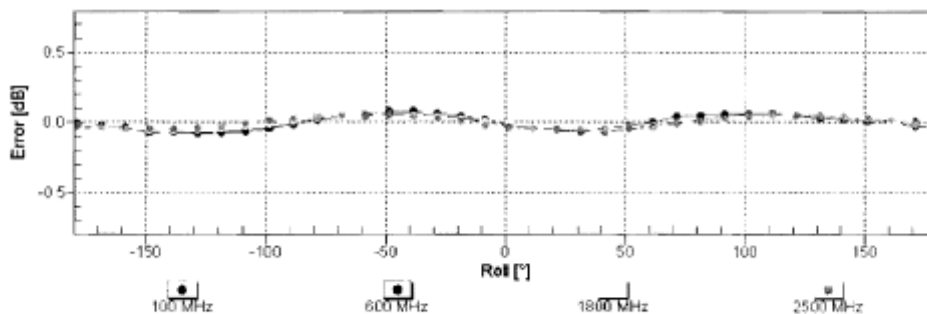


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ER3DV6- SN.2286

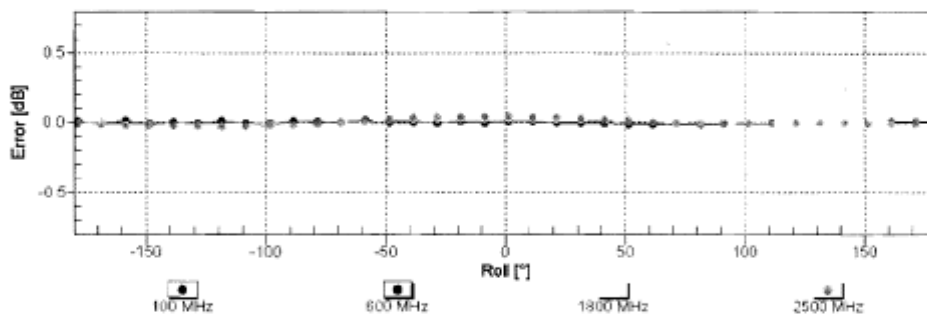
January 14, 2011

Receiving Pattern (ϕ), $\theta = 0^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\theta = 90^\circ$



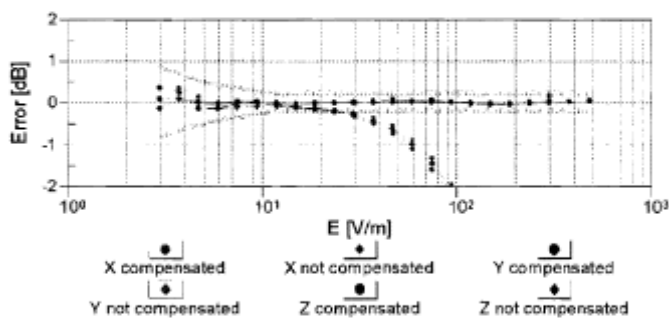
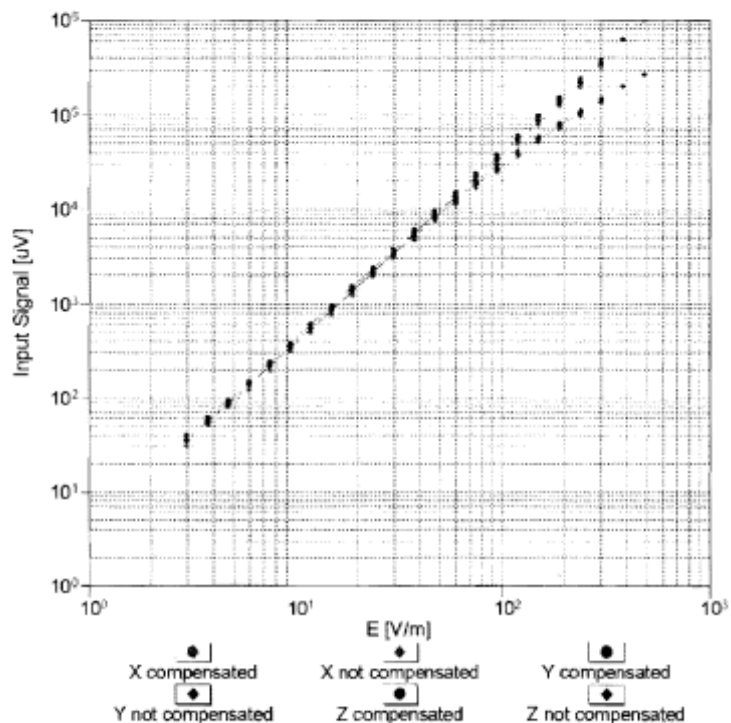
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

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ER3DV6- SN:2286

January 14, 2011

Dynamic Range f(E-field) (TEM cell , f = 900 MHz)



Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

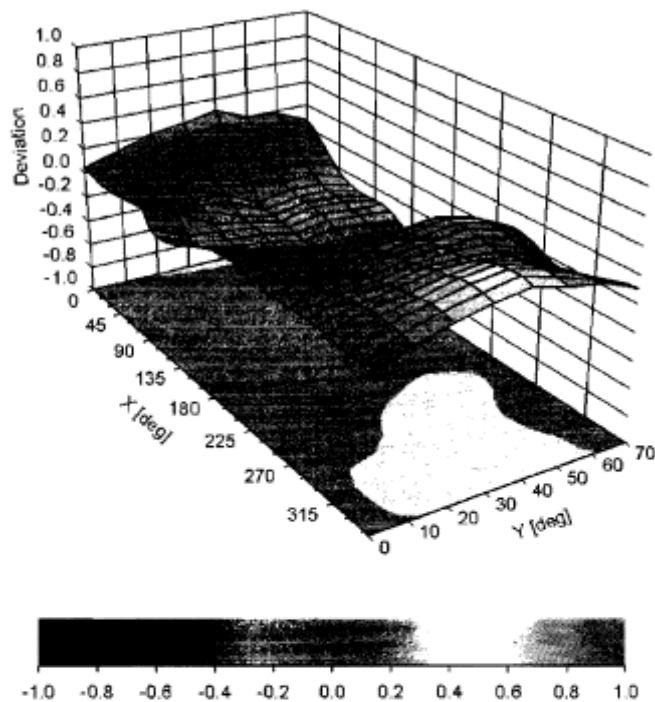
	Document Annex B to Hearing Aid Compatibility RF Emissions Test Report for the BlackBerry® Smartphone model RDZ21CW		Page 34(45)
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ER3DV6- SN:2286

January 14, 2011

Deviation from Isotropy in Air

Error (ϕ , θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

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ER3DV6- SN:2286

January 14, 2011

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2286

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	171.4
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm

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Accreditation No.: **SCS 108**

Client: **RIM**

Certificate No: **H3-6105_Nov10**

CALIBRATION CERTIFICATE

Object: **H3DV6 - SN:6105**

Calibration procedure(s): **QA CAL-03.v5, QA CAL-25.v2**
Calibration procedure for H-field probes optimized for close near field evaluations in air

Calibration date: **November 18, 2010**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%

Calibration Equipment used (M&E critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293674	10-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41495277	10-Apr-10 (No. 217-01136)	Apr-11
Power sensor E4412A	MY41498087	10-Apr-10 (No. 217-01136)	Apr-11
Reference 3 dB Attenuator	SN: S5054 (30)	30-Mar-10 (No. 217-01160)	Mar-11
Reference 20 dB Attenuator	SN: S5086 (20b)	30-Mar-10 (No. 217-01161)	Mar-11
Reference 30 dB Attenuator	SN: S5129 (30b)	30-Mar-10 (No. 217-01160)	Mar-11
Reference Probe H3DV6	SN: 5162	4-Oct-10 (No. H3-6162_Oct10)	Oct-11
DAE4	SN: 769	31-Aug-10 (No. DAE4-769_Aug10)	Aug-11
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US31642001790	4-Aug-09 (in house check Oct-09)	in house check: Oct-11
Network Analyzer HP 8753E	US373805185	18-Oct-01 (in house check Oct-10)	in house check: Oct-11

Calibrated by:	Name Jochen Kestrad	Function Laboratory Technician	 Signature
Approved by:	Name Katja Polzella	Technical Manager	

Issued: November 19, 2010

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Certificate No: **H3-6105_Nov10**

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Accreditation No.: **SCS 108**

Glossary:

NORM_{x,y,z}	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty cycle) of the RF signal
A, B, C	modulation dependent linearization parameters
Polarization α	α rotation around probe axis
Polarization β	β rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\beta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\beta = 0$ for XY sensors and $\beta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- X, Y, Z(f)_a0a1a2** = **X, Y, Z_a0a1a2** * frequency_response (see Frequency Response Chart).
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- A_{x,y,z}, B_{x,y,z}, C_{x,y,z}, VR_{x,y,z}**: **A, B, C** are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. **VR** is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy)**: in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the **X_a0a1a2** (no uncertainty required).

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H3DV6 – SN:6105

November 18, 2010

Probe H3DV6

SN:6105

Manufactured: January 5, 2002
Calibrated: November 18, 2010

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

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H3DV6- SN:6105

November 18, 2010

DASY/EASY - Parameters of Probe: H3DV6 - SN:6105

Basic Calibration Parameters

		Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (A/m / $\sqrt{\text{mV}}$)	a0	2.94E-003	2.71E-003	3.01E-003	$\pm 5.1\%$
Norm (A/m / $\sqrt{\text{mV}}$)	a1	2.83E-005	2.25E-005	6.45E-005	$\pm 5.1\%$
Norm (A/m / $\sqrt{\text{mV}}$)	a2	1.08E-005	2.19E-006	6.61E-006	$\pm 5.1\%$
DCP (mV) ^B		90.4	91.6	92.6	

Modulation Calibration Parameters

UID	Communication System Name	PAR		A dB	B dB	C dB	VR mV	Unc ^C (k=2)
10000	CW	0.00	X	0.00	0.00	1.00	211.2	$\pm 2.95\%$
			Y	0.00	0.00	1.00	233.0	
			Z	0.00	0.00	1.00	239.4	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^B Numerical linearization parameter; uncertainty not required

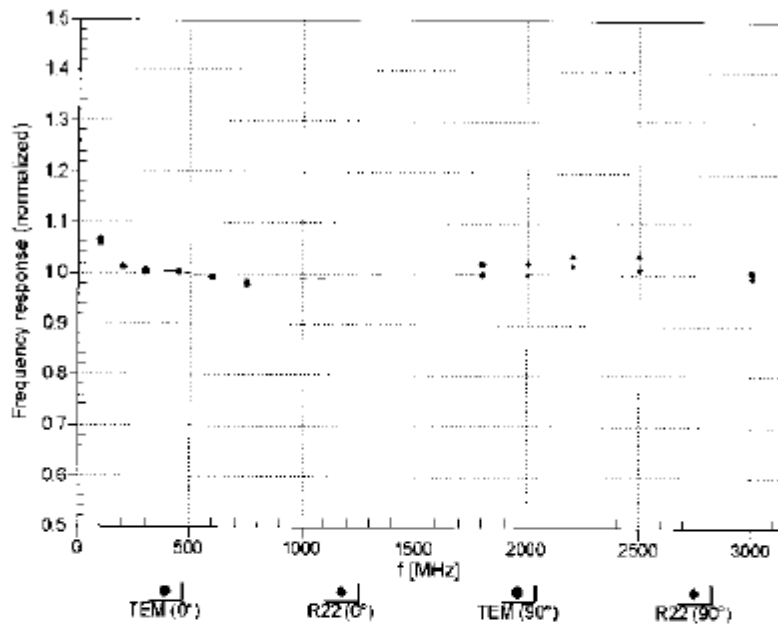
^C Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

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Frequency Response of H-Field (TEM-Cell: ifi110 EXX, Waveguide: R22)



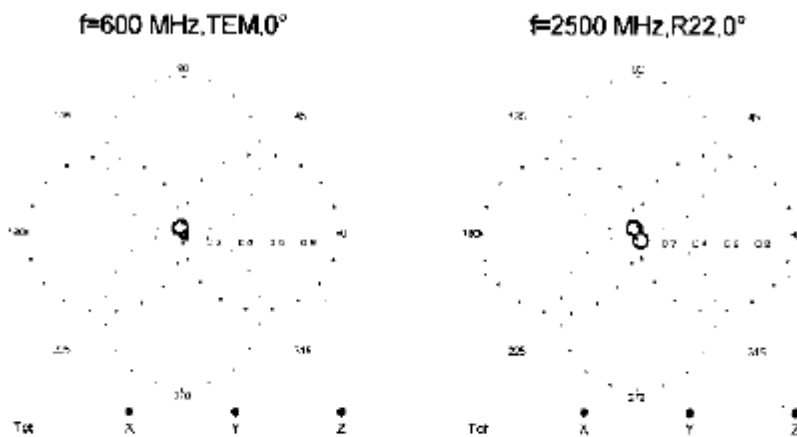
Uncertainty of Frequency Response of H-field: $\pm 6.3\%$ ($k=2$)

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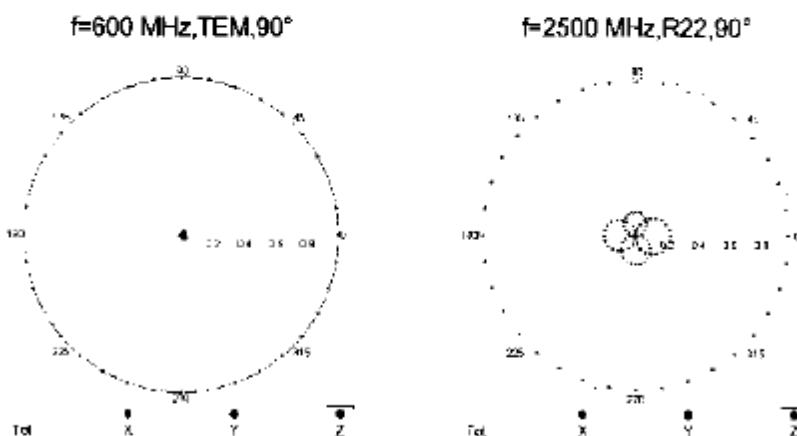
H3DM6-S4:6105

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Receiving Pattern (ϕ), $\theta = 0^\circ$



Receiving Pattern (ϕ), $\theta = 90^\circ$

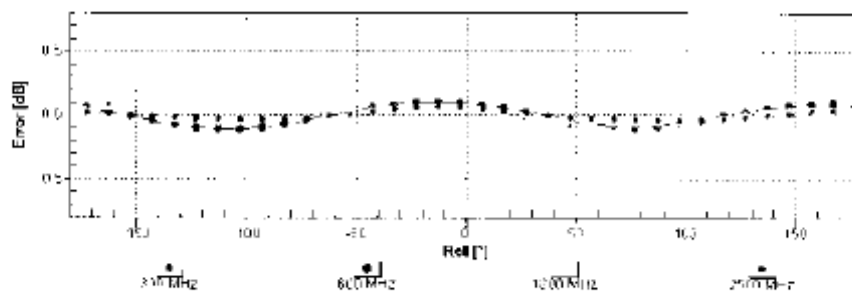


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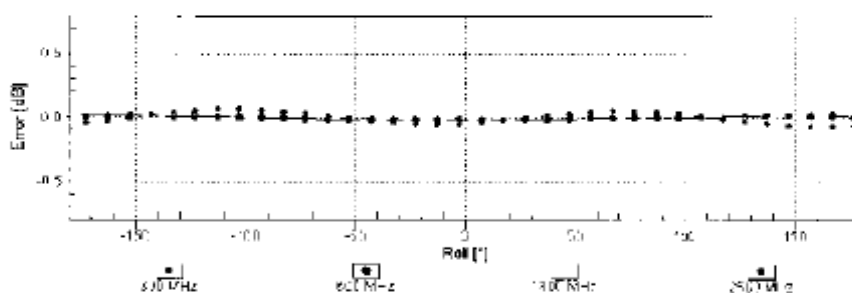
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Receiving Pattern (ϕ), $\theta = 0^\circ$


Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ (k=2)

Receiving Pattern (ϕ), $\theta = 90^\circ$

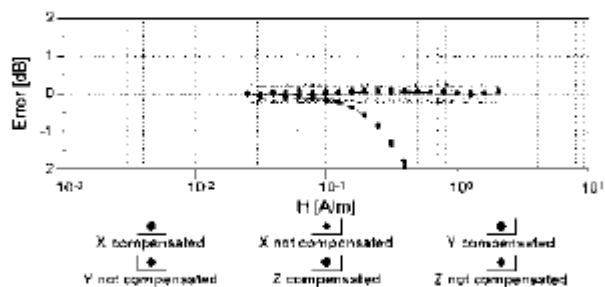
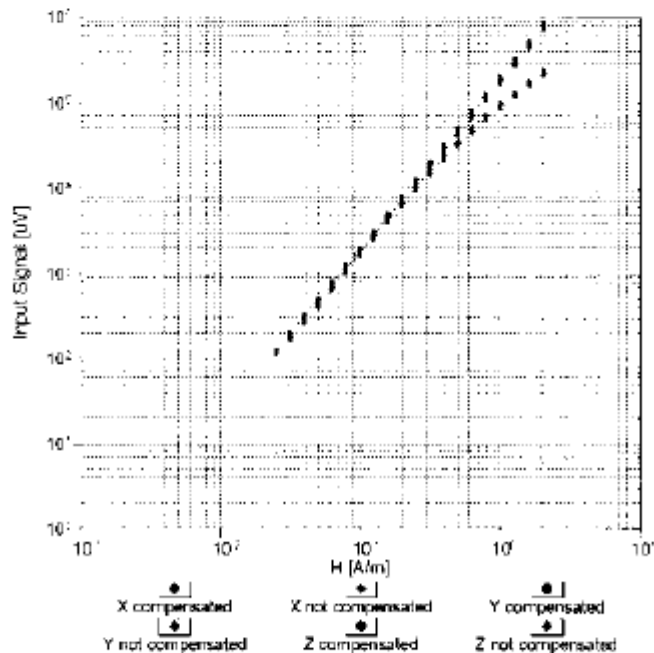

Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ (k=2)

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Dynamic Range f(H-field) (TEM cell, f = 900 MHz)


Uncertainty of Linearity Assessment: $\pm 0.6\%$ (k=2)

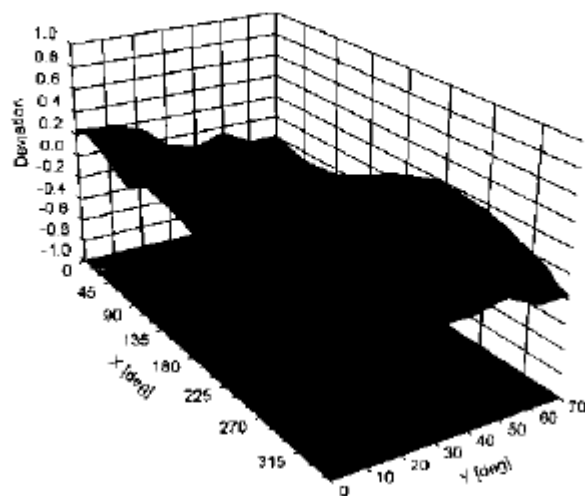
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Deviation from Isotropy in Air

Error (ϕ , θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

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DASY/EASY - Parameters of Probe: H3DV6 - SN:6105

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle [°]	-62.8
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6 mm
Probe Tip to Sensor X Calibration Point	3 mm
Probe Tip to Sensor Y Calibration Point	3 mm
Probe Tip to Sensor Z Calibration Point	3 mm