

PRELIMINARY

pulsar[®]

HART Installation and Operating Manual for Pulsar[®] Model R96

R96 software 1.x

Rate of change
What is the maximum rate of level change will rise or fall?

FPO

*High Performance 6 GHz
Pulse Burst Radar
Level Transmitter*



FPO

Read this Manual Before Installing

This manual provides information on the Pulsar® Model R96 Radar transmitter. It is important that all instructions are read carefully and followed in sequence. The *QuickStart Installation* instructions are a brief guide to the sequence of steps for experienced technicians to follow when installing the equipment. Detailed instructions are included in the *Complete Installation* section of this manual.

Conventions Used in this Manual

Certain conventions are used in this manual to convey specific types of information. General technical material, support data, and safety information are presented in narrative form. The following styles are used for notes, cautions, and warnings.

NOTES

Notes contain information that augments or clarifies an operating step. Notes do not normally contain actions. They follow the procedural steps to which they refer.

Cautions

Cautions alert the technician to special conditions that could injure personnel, damage equipment, or reduce a component's mechanical integrity. Cautions are also used to alert the technician to unsafe practices or the need for special protective equipment or specific materials. In this manual, a caution box indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury.

WARNINGS

Warnings identify potentially dangerous situations or serious hazards. In this manual, a warning indicates an imminently hazardous situation which, if not avoided, could result in serious injury or death.

Safety Messages

The PULSAR Model R96 system is designed for use in Category II, Pollution Degree 2 installations. Follow all standard industry procedures for servicing electrical and computer equipment when working with or around high voltage. Always shut off the power supply before touching any components. Although high voltage is not present in this system, it may be present in other systems.

Electrical components are sensitive to electrostatic discharge. To prevent equipment damage, observe safety procedures when working with electrostatic sensitive components.

This device complies with Part 15 of the FCC rules. Operation is subject to the following two conditions:
(1) This device may not cause harmful interference, and
(2) This device must accept any interference received, including interference that may cause undesired operation.

FCC ID: LPN R95

Any unauthorized changes or modifications not expressly approved by the party responsible for compliance could void user's authority to operate this equipment.

WARNING! Explosion hazard. Do not connect or disconnect designs rated Explosion-proof or Non-incendive unless power has been switched off and/or the area is known to be non-hazardous.

Low Voltage Directive

For use in Installations **Category II, Pollution Degree 2**. If equipment is used in a manner not specified by the manufacturer, protection provided by equipment may be impaired.

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MAGNETROL reserves the right to make changes to the product described in this manual at any time without notice. MAGNETROL makes no warranty with respect to the accuracy of the information in this manual.

Warranty

All MAGNETROL electronic level and flow controls are warranted free of defects in materials or workmanship for one full year from the date of original factory shipment.

If returned within the warranty period; and, upon factory inspection of the control, the cause of the claim is determined to be covered under the warranty; then, MAGNETROL will repair or replace the control at no cost to the purchaser (or owner) other than transportation.

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Quality Assurance

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The MAGNETROL quality assurance system is registered to ISO 9001 affirming its commitment to known international quality standards providing the strongest assurance of product/service quality available.





Pulsar® Pulse Burst Radar Level Transmitter

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1.0 QuickStart Installation

The QuickStart Installation procedures provide an overview of the key steps for mounting, wiring, and configuring the PULSAR Model R96 radar level transmitter. These procedures are intended for experienced installers of electronic level measurement instruments.

See Complete Installation, Section 2.0, for detailed installation instructions.

1.1 Getting Started

Before beginning the QuickStart Installation procedures, have the right equipment, tools, and information available.

1.1.1 Equipment and Tools

No special tools are needed. The following items are recommended:

- Threaded antenna and transmitter 2" (50 mm)
- Transmitter/antenna connection. 1¾" (44 mm)
- Transmitter adjustment 1⅛" (28 mm),
¾" (2.5 mm) Hex
- Torque wrench highly desirable
- Flat-blade screwdriver
- Digital multimeter or volt/ammeter Optional
- 24 VDC (23 mA) power supply. Optional

1.1.2 Configuration Information

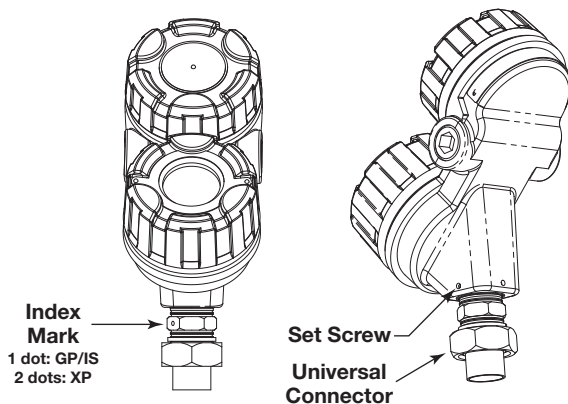
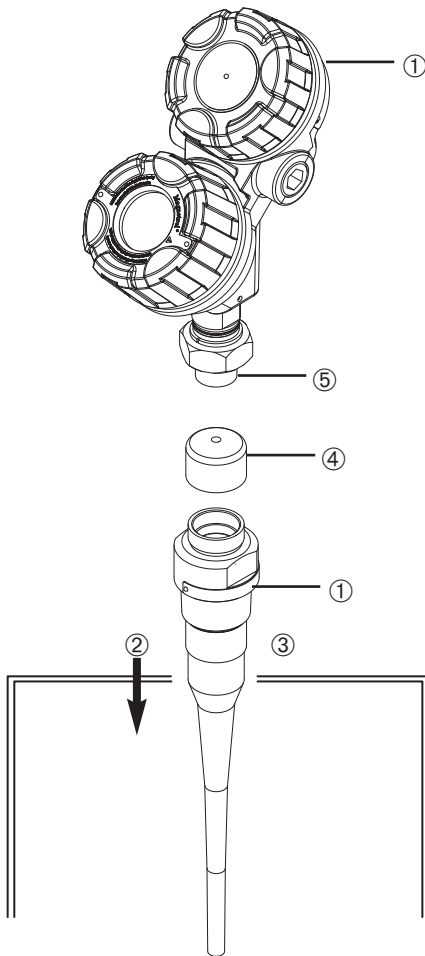
To utilize the QuickStart menu available on the PULSAR Model R96, some key information is required for configuration.

Gather the information and complete the following operating parameters table before beginning configuration.

NOTES: The QuickStart menu is available for Level Only applications.

1. Refer to Section 2.6.5 for configuration menus for Volume applications.
2. These configuration steps are not necessary if the transmitter was pre-configured prior to shipment.

Display	Question	Answer
Level Units	What units of measurement will be used?	_____
Tank Height	What is the tank height?	_____
Antenna Model	What type of antenna is being used? Select first 7 digits of Model number. (See nameplate on side of antenna)	_____
Antenna Extension	What is maximum nozzle length that the antenna can be used? Select last 3 digits of Model number. (See nameplate on side of antenna)	_____
Antenna Mount	Is the antenna mounting NPT, BSP, or flanged?	_____
Dielectric	What is the dielectric of the process medium?	_____
Tank Top	Is the Tank Top Flat, Horizontal Cylinder, Dome, Irregular or other (non-metallic)?	_____
Top Blocking	What is the distance from Sensor Reference point to Maximum Level? Maximum level should never be less than 2" (50 mm) from bottom of antenna.	_____
Bottom Blocking Distance	Is there a region at the very bottom of the vessel that cannot be measured due to heating coils, angle tank bottom, etc.?	_____
Turbulence	Is turbulence a consideration?	_____
Rate of Change	What is the maximum rate the level will rise or fall?	_____
Foam	Will there be foam on the surface?	_____
4 mA Setpoint (LRV)	What is the 0% reference point for the 4.0 mA value?	_____
20 mA Setpoint (URV)	What is the 100% reference point for the 20.0 mA value?	_____
Failure Alarm	What output current is desired when a failure indicator is present?	_____



1.2 QuickStart Mounting

NOTE: Confirm the configuration style and process connection (size and type) of the PULSAR Model R96 radar transmitter. Ensure it matches the requirements of the installation before continuing with the QuickStart installation.

- ① Confirm the model and serial numbers on the nameplates of PULSAR Model R96 electronics and antenna are identical.

1.2.1 Antenna

- ② Carefully place the antenna into the vessel. Mount in a location equal to $\frac{1}{2}$ the radius of tank top. Do not mount in center of vessel nor closer than 18" (45 cm) of tank wall.
- ③ Secure the antenna to the vessel.
- ④ Leave the protective plastic cap in place until ready to install the transmitter.

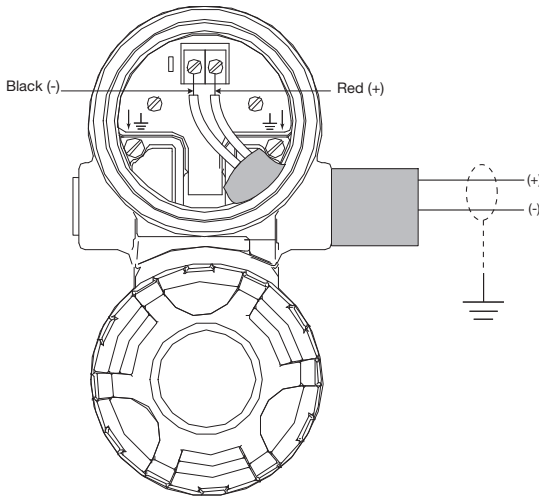
NOTE: Do not use sealing compound or TFE tape on antenna connection to transmitter. This connection is sealed by a Viton® O-ring.

1.2.2 Transmitter

1. Remove the protective plastic cap from the top of the antenna and store for future use. Make sure the bottom of the Universal connector (Teflon®) ⑤ and inside of the antenna are clean and dry. Clean with isopropyl alcohol and cotton swabs if necessary.
 2. Place the transmitter on the antenna.
 3. Ensure the housing/launcher set screw is loose and the housing can be turned. Align the antenna index mark so it is at an angle of 45° to a line from the radar unit to the nearest tank wall.
 4. Rotate the transmitter so that it is in the most convenient position for wiring, configuring, and viewing.
 5. While keeping the housing and launcher aligned, tighten both the housing/launcher set screw and large Universal connector Hex nut. Tighten the universal connector to 30 ft./lbs of force. A torque wrench is highly desirable. **DO NOT LEAVE HAND TIGHT.**
- Do not place insulating material around any part of the Radar transmitter including the antenna flange.

1.3 QuickStart Wiring

WARNING! Explosion hazard. Do not remove covers unless power has been switched off or the area is known to be non-hazardous.



NOTE: Ensure that the electrical wiring to the PULSAR Model R96 radar transmitter is complete and in compliance with all regulations and codes.

1. Remove the cover of the upper wiring compartment.
2. Attach a conduit fitting and mount the conduit plug in the spare opening. Pull the power supply wire through the conduit fitting.
3. If present, connect cable shield to an earth ground at the power supply.
4. Connect the positive supply wire to the (+) terminal and the negative supply wire to the (-) terminal. For Explosion Proof Installations, see Wiring, Section 2.5.3.
5. Replace the cover and tighten.

1.4 QuickStart Configuration

If requested, the PULSAR Model R96 transmitter is shipped fully pre-configured for the application and can be installed immediately. Otherwise it is shipped configured with default values from the factory and can be easily reconfigured in the shop. The minimum configuration instructions follow. Use the information from the operating parameters table before beginning configuration. See Configuration Information, Section 1.1.2.

The Quick Start menu offers a very simple two screen overview showing the basic parameters required for a typical “Level Only” application.

1. Apply power to the transmitter.

The graphic LCD display can be programmed to change every 2 seconds to show pertinent Measured Values on the Home Screen. For example: Level, %Output, and Loop current can all be displayed on a rotating screen.

The LCD can also be programmed to always show just one of the Measured Variables at all times. For example: Level can be the only value displayed on the screen.

2. Remove the cover of the electronic compartment.



STEP 4



STEP 5



STEP 6



3. The push buttons offer multiple forms of functionality for menu navigation and data entry. (See Section 2.6 for complete explanation).
 - ⬆ **UP** moves up through the menu or increases a displayed value.
 - ⬇ **DOWN** moves down through the menu or decreases a displayed value.
 - ⬅ **BACK** exits a branch of the menu or exits without accepting entered value.
 - ➡ **ENTER** enters a branch of the menu or accepts a displayed entry.

NOTE: Holding down ENTER when any menu or parameter is highlighted will show help text in reference to that item.

The default User Password = 0. (If a password is requested, enter it at that time.)

The following configuration entries are the minimum required for a QuickStart configuration. Refer to figures at left.

4. Press any key at the Home Screen to access the Main Menu.
5. Press ➡ ENTER with the DEVICE SETUP menu item highlighted.
6. Press ➡ ENTER with the QUICKSTART menu item highlighted.

The QuickStart shows the basic parameters, with the present value of the highlighted parameter shown at the bottom of the screen.

One can now quickly and easily scroll through the QuickStart configuration items, changing those parameters as required:

- Scroll to the parameter to be changed.
- Press ➡ ENTER at the highlighted parameter.
- Scroll to the desired option, then press ➡ ENTER.
- Scroll to next parameter or press ⬅ BACK when finished to exit the QuickStart menu.

Section 1.4.1 lists and describes the nine parameters in the QuickStart menu.

7. After making all of the necessary changes in the QuickStart menu, press the BACK button three times to return to the Home Screen.
8. The QuickStart configuration is complete. If properly configured, the Model R96 transmitter is measuring level and is ready for service.

1.4.1 QuickStart Menu Options

Level Units		Select the Units of measurement for the level readout: • Inches • Feet • Millimeters • Centimeters • Meters
Tank Height		Enter tank height (in Level Units selected)
Antenna Model		Select the Antenna Model to be used with Model R96: • RAA-x — TFE rod • RAB-G — Polypropylene rod • RAB-L — Polypropylene rod • RAB-x — Halar rod • RA3-x — 3" horn • RA4-x — 4" horn • RA6-x — 6" horn
Antenna Extension		0 For nozzle height $\leq 1"$ (25 mm) (for threaded process connection only) 1 For nozzle height $\leq 4"$ (100 mm) 2 For nozzle height $\leq 8"$ (200 mm) (ESP designation for TFE rod only) 3 For nozzle height $\leq 12"$ (300 mm)
Antenna Mount		Select the type of Antenna Mounting to the vessel: • NPT (National Pipe Thread) • BSP (British Standard Pipe) • Flange (ANSI or DIN)
Dielectric Range		Enter the Dielectric Range for the material to be measured. Below 1.7 (Light Hydrocarbons like Propane and Butane) 1.7 to 3.0 (Most typical hydrocarbons) 3.0 to 10 (Varying dielectric, for example: mixing tanks) Above 10 (Water-based media)
HART Only	4 mA Set Point (LRV)	Enter the level value (0%-point) for the 4 mA point. Lower Range Value (LRV). Refer to Section 1.4.1.1.
	20 mA Set Point (URV)	Enter the level value (100%-point) for the 20 mA point. Upper Range Value (URV). Refer to Section 1.4.1.1.
	Failure Alarm	Enter the desired output state when a Failure Indicator is active. • 22 mA • 3.6 mA • Hold (Hold last value is not recommended)

1.4.1.1 QuickStart Numerical Data Entry

To make numerical entry changes to Tank Height:

- ⬆ **UP** moves up to the next highest digit (0,1,2,3,....,9 or the decimal point).
If held down the digits scroll until the push button is released.
- ⬇ **DOWN** moves up to the next lowest digit (0,1,2,3,....,9 or the decimal point). If held down the digits scroll until the push button is released.
- ⬅ **BACK** moves the cursor to the left and deletes a digit.
If the cursor is already at the leftmost position, then the screen is exited without changing the previously saved value.
- ➡ **ENTER** Moves the cursor to the right. If the cursor is located at a blank character position, the new value is saved.

Scrolling further DOWN in the QuickStart menu results in the remaining parameters appearing one by one, with the present highlighted value shown at the bottom of the screen.

- ⬅ **BACK** returns to the previous menu without changing the original value, which is immediately redisplayed.
- ➡ **ENTER** accepts the displayed value and returns to the previous menu.

2.0 Complete Installation

This section provides detailed procedures for properly installing, wiring, configuring, and, as needed, troubleshooting the PULSAR Model R96 Radar Level Transmitter.

2.1 Unpacking

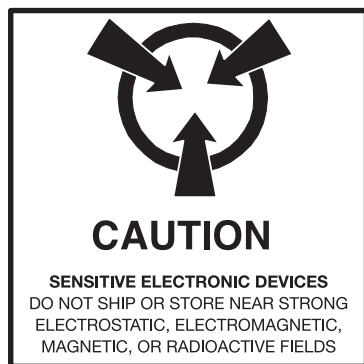
Unpack the instrument carefully. Make sure all components have been removed from the packing material. Check all the contents against the packing slip and report any discrepancies to the factory.

Before proceeding with the installation, do the following:

- Inspect all components for damage. Report any damage to the carrier within 24 hours.
- Make sure the nameplate model number on the antenna and transmitter agree with the packing slip and purchase order.
- Record the model and serial numbers for future reference when ordering parts.

Model Number

Serial Number



2.2 Electrostatic Discharge (ESD) Handling Procedure

MAGNETROL electronic instruments are manufactured to the highest quality standards. These instruments use electronic components that may be damaged by static electricity present in most work environments.

The following steps are recommended to reduce the risk of component failure due to electrostatic discharge.

- Ship and store circuit boards in anti-static bags. If an anti-static bag is not available, wrap the board in aluminum foil. Do not place boards on foam packing materials.
- Use a grounding wrist strap when installing and removing circuit boards. A grounded workstation is recommended.
- Handle circuit boards only by the edges. Do not touch components or connector pins.
- Make sure that all electrical connections are completely made and none are partial or floating. Ground all equipment to a good, earth ground

WARNING! Potential electrostatic charging hazard. Do not rub with dry cloth.

2.3 Before You Begin

2.3.1 Site Preparation

Each PULSAR Model R96 Radar transmitter/antenna is built to match the physical specifications of the required installation. Ensure that the probe process connection is correct for the threaded or flanged mounting on the vessel where the transmitter will be placed. See Mounting, Section 2.4.

Ensure that all local, state, and federal regulations and guidelines are observed. See Wiring, Section 2.5.

Ensure that the wiring between the power supply and PULSAR Model R96 Radar transmitter is complete and correct for the type of installation. See Specifications, Section 3.7.

2.3.2 Equipment and Tools

No special tools are needed. The following items are recommended:

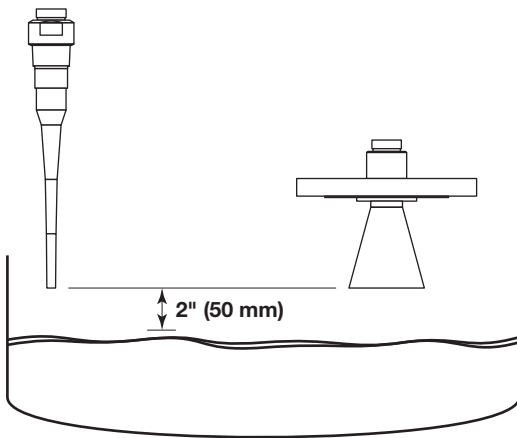
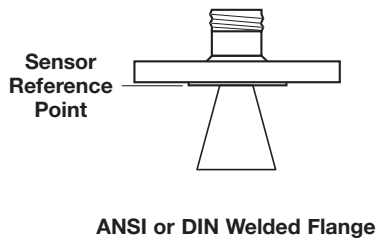
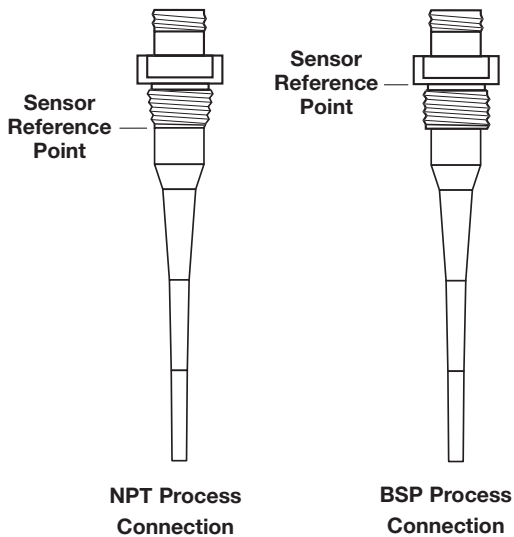
- Threaded antenna and transmitter 2" (50 mm)
- Transmitter/antenna connection. 1 $\frac{3}{4}$ " (44 mm)
- Transmitter adjustment 1 $\frac{1}{8}$ " (28 mm),
..... $\frac{3}{32}$ " (2.5 mm) Hex
- Torque wrench highly desirable
- Flat-blade screwdriver. highly desirable
- Digital multimeter or volt/ammeter Optional
- 24 VDC (23 mA) power supply. Optional

2.3.3 Operational Considerations

Radar applications are characterized by three basic conditions; Dielectric (process medium), Distance (measuring range) and Disturbances (turbulence, foam, false targets, multiple reflections and rate of change). The PULSAR Model R96 Radar transmitter is offered with two antenna configurations—Horn (3", 4" 6") and Dielectric Rod. Ideally, the 6" (DN150) Horn antenna should be used to ensure the best possible performance in all operational conditions.

2.3.3.1 Maximum Distance

The chart on the following page shows the maximum measuring range (Distance) of each antenna based on fundamental conditions of Dielectric, Distance and Turbulence. Distance is measured from the Sensor Reference Point (bottom of NPT thread, top of BSP thread or face of a flange).



“When measurement close to flange is critical.” (LATER)
JH

MAXIMUM DISTANCE feet (meters)

Dielectric	Turbulence	Dielectric Rod (1½")	4" Horn	6" Horn
1.7-3.0	None	35 (10.7)	40 (12.2)	45 (13.7)
	Light, < 0.5"	28 (8.5)	33 (10.1)	37 (11.3)
	Moderate, < 1.0"	21 (6.4)	26 (7.9)	29 (8.8)
	Heavy, > 1.0"	15 (4.6)	17 (5.2)	20 (6.1)
3.0-10.0	None	50 (15.2)	55 (16.8)	60 (18.3)
	Light, < 0.5"	40 (12.2)	44 (13.4)	48 (14.6)
	Moderate, < 1.0"	30 (9.1)	33 (10.1)	35 (10.7)
	Heavy, > 1.0"	20 (6.1)	22 (6.7)	25 (7.6)
10.0-100	None	65 (20)	65 (20)	65 (20)
	Light, < 0.5"	52 (15.8)	52 (15.8)	53 (16.2)
	Moderate, < 1.0"	39 (11.9)	39 (11.9)	41 (12.5)
	Heavy, > 1.0"	25 (7.6)	27 (8.2)	30 (9.1)

Dielectric rod minimum dielectric = 2.0

2.3.3.2 Minimum Distance

If the liquid level is allowed onto the antenna, noise and media build-up drastically decrease reliable measurement. Liquid should not be allowed closer than 8.5 inches (216 mm) from the bottom of the sensor reference point.

2.3.3.3 Problematic Applications; GWR Alternative

Some application concerns can be problematic for Non-Contact Radar. For these, Guided Wave Radar is recommended:

- Extremely low dielectric media ($\epsilon_r < 1.7$)
- Stillwells, standpipes, bridles, cages and bypass columns.
- Very weak reflections from the liquid surface (particularly during turbulence) can cause poor performance.
- Tanks heavily cluttered with false targets (mixers, pumps, ladders, pipes, etc.)
- During times of very low liquid levels of low dielectric media, the metal tank bottom may be detected which can deteriorate performance.
- Foam can either absorb or reflect the microwave energy depending upon the depth, dielectric, density and wall thickness of the bubbles. Due to typical variations in the amount (depth) of foam, it is impossible to quantify performance. It may be possible to receive most, some or none of the transmitted energy.
- When measurement close to flange is critical
 - Extremely high liquid levels (Overflow) conditions when liquid very near the antenna can cause erroneous readings and measurement failure.

Refer to PULSAR Model R96 bulletin 58-102 for additional information

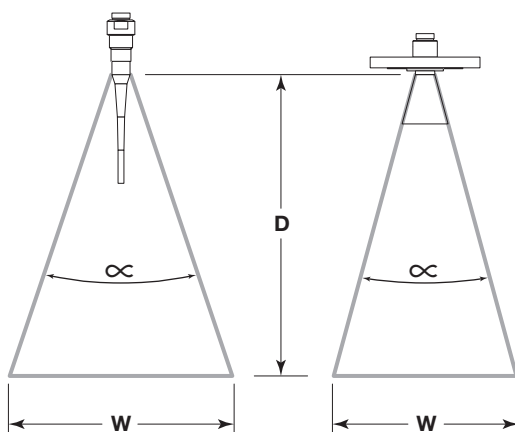
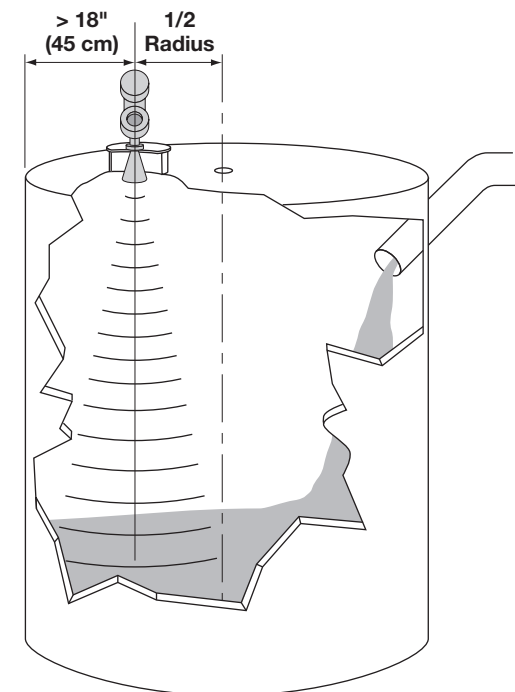
2.4 Mounting

The PULSAR Model R96 Radar transmitter can be mounted to a vessel using a variety of process connections. Generally, either a threaded or flanged connection is used. For information about the sizes and types of connections available, see Antennae Model Numbers, Section 3.8.2.

2.4.1 Installing the Antenna

Before installing, ensure that:

- Model and Serial numbers on the nameplates of the PULSAR Model R96 transmitter and antenna are identical.
- Process temperature, pressure, dielectric, turbulence and distance are within the antenna specifications for the installation.
- Rod of a Dielectric Rod antenna is protected from bending or breaking; there is no metal sub-structure.
- Insulating material is not placed around any part of the Radar transmitter including the antenna flange.
- Protective cap is kept on the antenna if the transmitter is to be installed at a later time.
- Antenna is being mounted in the optimal location. See following sections: Location, Beam Angle, Obstructions and Nozzles for specific information.
- If the liquid level is allowed onto the antenna, noise and media buildup drastically decrease reliable measurement. Liquid should not be allowed closer than 2 inches (50 mm) from the bottom of the antenna.



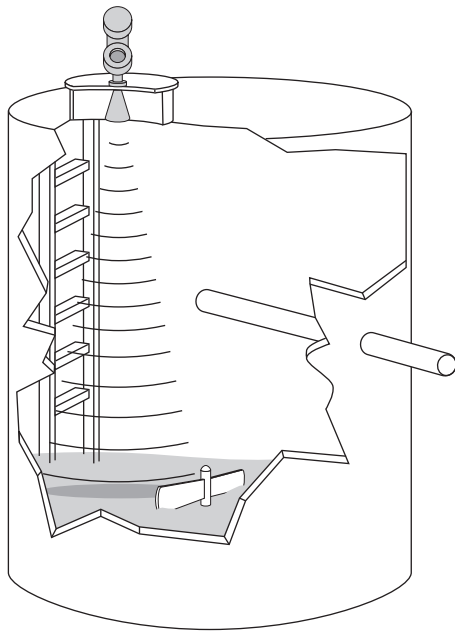
	Beam Spread, W @-3dB; ft (m)		
Antenna	Dielectric Rod	4" Horn	6" Horn
Beam Angle (α)	25°	25°	17°
Distance, D			
10 (3)	4.5 (1.37)	4.5 (1.37)	3.0 (0.91)
20 (6)	8.9 (2.71)	8.9 (2.71)	6.0 (1.83)
30 (9)	13.3 (4.05)	13.3 (4.05)	9.0 (2.74)
40 (12)	17.8 (5.43)	17.8 (5.43)	12.0 (3.66)
50 (15)	22.2 (6.77)	22.2 (6.77)	15.0 (4.57)
60 (18)	26.6 (8.11)	26.6 (8.11)	18.0 (5.49)
65 (20)	28.9 (8.81)	28.9 (8.81)	19.5 (5.95)

2.4.1.1 Location

Ideally, the Radar transmitter should be mounted providing an unobstructed signal path to the liquid surface where it should illuminate (with microwave energy) the largest, possible surface area. See Section 2.4.1.2, Beam Angle. Unavoidable obstacles will produce reflections that must be minimized during field configuration. See Section 3.4.2, Echo Rejection. Mount in a location equal to 1/2 the radius of tank top. Do not mount in center of vessel nor closer than 18" (45 cm) of tank wall.

2.4.1.2 Beam Angle

The various antenna designs exhibit different beam patterns. Ideally, the beam pattern should illuminate with microwave beam the maximum liquid surface with minimum contact with other objects in the vessel including the tank wall. Use the drawings at left to determine the optimum installation location.



2.4.1.3 Obstructions

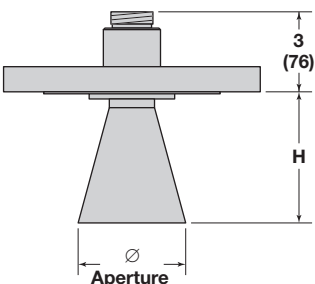
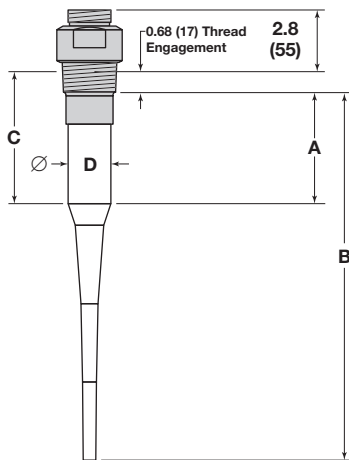
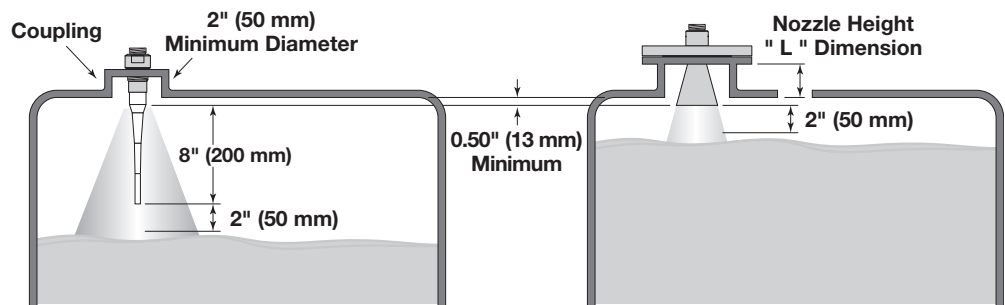
Almost any object that falls within the beam pattern will cause reflections that may be misinterpreted as a false liquid level. Although PULSAR Model R96 has a powerful Echo Rejection routine, all possible precautions should be taken to minimize false target reflections with proper installation and orientation.

2.4.1.4 Nozzles

Improper installation in a nozzle creates “ringing” that will adversely affect measurement. The antenna should always be mounted so the active section of the antenna is a minimum of 0.5" (12mm) outside the nozzle. Antenna extensions are offered to allow the PULSAR Model R96 transmitter to work reliably in nozzles with “L” dimensions of 1" (25 mm), 4" (100mm), 8" (200mm) or 12" (300mm). Standard antennas (no extension) are shown below for reference. See Section 3.7.6 for dimensional drawings of all antenna designs including nozzle extensions.

Dielectric Rod Antenna

Horn Antenna



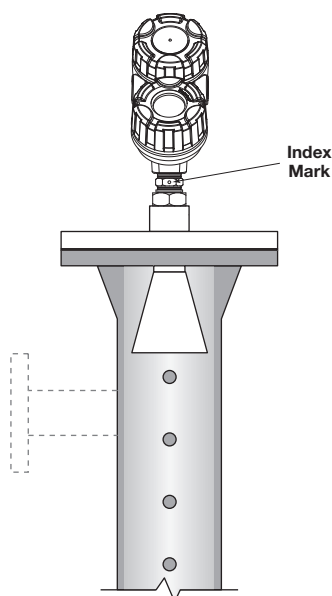
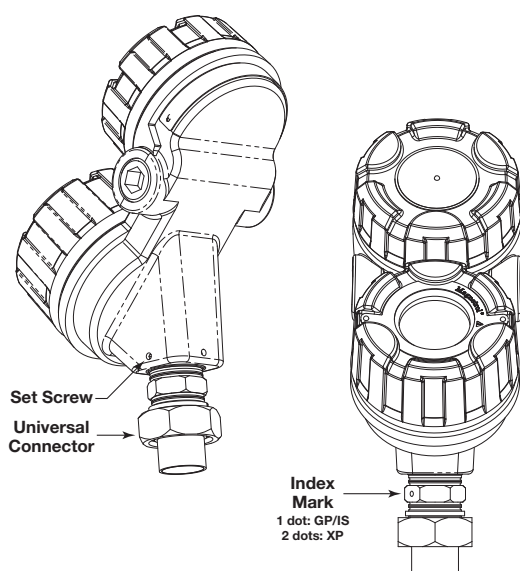
DIELECTRIC RODS

Model #	Antenna Extension (maximum “L” dimension)	All	All	BSP
8th Digit		Dim A	Dim B	Dim C
0	1" (25 mm)	2.2 (56)	11.1 (282)	3.0 (76)
1	4" (100 mm)	5.1 (130)	14.0 (356)	5.9 (150)
2	8" (200 mm)	9.1 (231)	18.0 (457)	9.9 (251)
3	12" (300 mm)	13.1 (333)	22.0 (559)	13.9 (353)

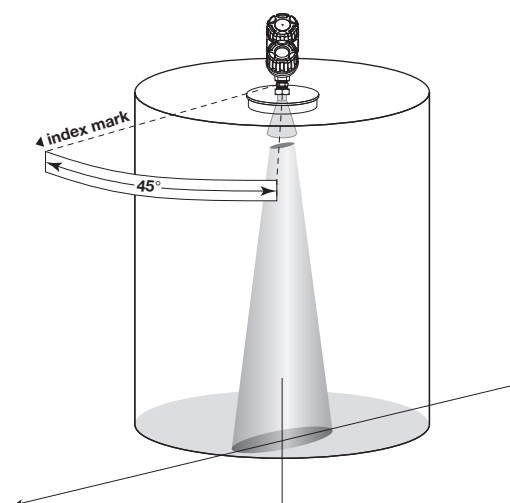
Antenna Extension O.D. Dimension D	
TFE Rod	Ø 1.625 (41)
PP Rod	Ø 1.50 (38)
All-Plastic Rod	Ø 1.625 (41)

HORNS

Model #	Antenna Extension (maximum “L” dimension)	3" Horn	4" Horn	6" Horn
8th Digit		Dim H	Dim H	Dim H
0	1" (25 mm)	2.7 (51)	↓	↓
1	4" (100 mm)	N/A	4.6 (117)	↓
2	8" (200 mm)		8.4 (213)	
3	12" (300 mm)		12.4 (315)	
Aperture		2.95" (75 mm)	3.75" (95 mm)	5.75" (146 mm)



PULSAR Model R96 Mounted in Stillwell (Bridle)



Polarization Pattern

2.4.1.5 Standpipes and Stillwells

The PULSAR Model R96 can be mounted in a standpipe or stillwell but certain items must be considered:

- Metal stillwells only: Sizes 3–8 inches (80–200 mm). (Beyond 8", effects are negligible.)
- Diameter must be consistent throughout length; no reducers.
- Use only horn antennas sized to pipe ID; 3–6" (80–150mm); 8" pipe can use a 6" horn.
- Stillwell length must cover complete range of measurement (i.e., liquid must be in stillwell).
- Welds should be smooth.
- Vents: holes <0.5" diameter, slots <0.5" width.
- If an isolation valve is used, it must be a full port ball valve with an I.D. equal to the pipe diameter.
- Bridles/Bypass Installations: The launcher (index mark) should be rotated 90° from process connections.
- Configuration must include an entry for the PIPE I.D. parameter. See Section 2.6.5.1, Item 35- PIPE I.D.
- There will be some increased dielectric sensitivity; system gain will be reduced when PIPE ID >0.

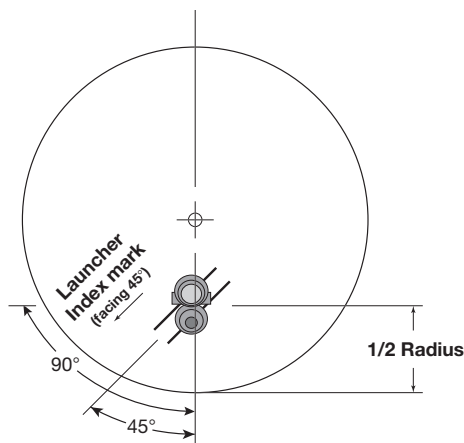
2.4.2 Installing the Transmitter

- Remove the protective plastic cap from the top of antenna. Store the cap in a safe place in case the transmitter has to be removed later.
- Carefully place the transmitter on the antenna.
- Rotate the transmitter to face the most convenient direction for wiring, configuration and viewing. Do not tighten the universal connector (large hex nut) nor the set screw on the housing base. The transmitter launcher must be oriented properly for optimal performance.
- Do not place insulating material around any part of the radar transmitter including the antenna flange.

2.4.2.1 Orientation

The PULSAR Model R96 transmitter utilizes a linearly polarized, microwave beam that can be rotated to improve its performance. Proper orientation can minimize unwanted target reflections, decrease sidewall reflections (multipath) and maximize direct reflections from the liquid surface. The index mark located on the side of the launcher is oriented in the same direction as the polarization.

The index mark is also present for reference (1 dot: GP/IS or 2 dots: XP). The launcher is considered to be at 0° when the index mark is closest to the tank wall. (See figures at left.)



Top View
Mounted 1/2 radius

2.4.2.2 Initial Installation

Ideally, the transmitter should be mounted half the radius from the tank wall. Align the index mark so it is at an angle of 45 degrees to a line from the radar unit to the nearest tank wall. For horizontal cylindrical vessels, align the launcher (index mark) so it is facing along the long axis of the vessel. Once properly oriented, tighten set screws and Universal connector (30 ft-lbs of force).

A transmitter mounted within 18" (45 cm) of a tank wall may demand orientation adjustments to limit multipath and optimize performance. See Section 2.4.2.3 Signal Loss.

NOTE: ALWAYS RUN THE ECHO REJECTION ROUTINE AFTER MAKING CHANGES TO MENU CHOICES (**Antenna Type, Antenna Mount, Tank Height, Blocking Distance, Dielectric, Turbulence, Rate Change, Foam**) or when launcher is repositioned.

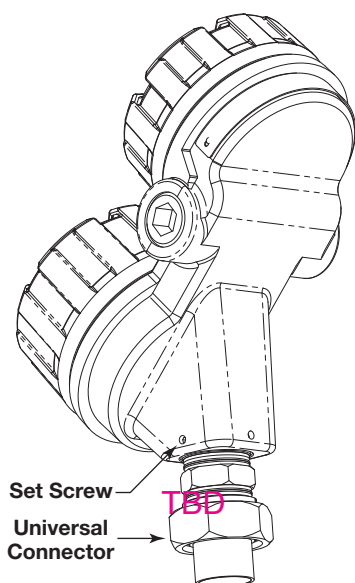
2.4.2.3 Low Echo Margin

Low Echo Margin has many potential causes. Following are two initial areas for investigation.

Launcher Orientation: Initial launcher orientation is always **45 degrees** (see Sections 2.4.1 & 2.4.2). In tall vessels and when antenna is mounted close to the tank wall, improvement in Echo Margin (signal quality) may be attained by rotating the launcher to 90 degrees.

Echo Loss: If the Level signal is lost repeatedly at a specific point in the vessel, it is usually a symptom that multipath (side-wall) reflections are causing cancellation by returning to the transmitter exactly 180° out of phase with the actual Level signal. This can be improved by utilizing the following procedure:

- Scroll to Display Config Menu under Device Setup. This menu shows both Level and Echo Margin.
- Bring the Level up (or down) to the exact point where the signal is repeatedly lost. Monitor the Echo Margin value as this point is being approached. The Echo Margin value will degrade to a low point before it begins to increase.
- When the Echo Margin reaches this low point, loosen both the Universal connector and the set screw. Slowly rotate the launcher clockwise approximately 10–20° (the transmitter can be rotated independently). Allow the unit to stabilize for approximately 1 minute. Repeat this process until the Echo Margin value is optimized.
- Without disturbing the position of the launcher, position the transmitter head back to its most convenient location.
- Tighten both the Universal connector (30 ft-lbs of force) and Launcher set screw.



NOTE: ALWAYS RUN THE TARGET REJECTION ROUTINE AFTER MAKING CHANGES TO MENU CHOICES (**Antenna Type, Antenna Mount, Sensor Offset, Tank Height, Blocking Distance, Dielectric, Turbulence, Rate Change, Foam**) or when launcher is repositioned.

2.5 Wiring

Caution: HART versions of the PULSAR Model R96 transmitter operate at voltages of 11–36 VDC, while FOUNDATION field-bus versions operate at 9–17.5 VDC. Higher voltages will damage the transmitter.

Wiring connections between the power supply and the PULSAR Model R96 Radar Transmitter should be made using 18–22 AWG shielded twisted pair instrument cable. Connections are made to the terminal strip and the ground connections within the top enclosure compartment.

The directions for wiring the PULSAR Model R96 transmitter depend on the application:

- General Purpose or Non-Incendive (Cl I, Div. 2)
- Intrinsically Safe
- Explosion Proof

WARNING! Explosion hazard. Do not disconnect equipment unless power has been switched off or the area is known to be non-hazardous.

2.5.1 General Purpose or Non-incendive (Cl I, Div. 2)

A general purpose installation does not have flammable media present.

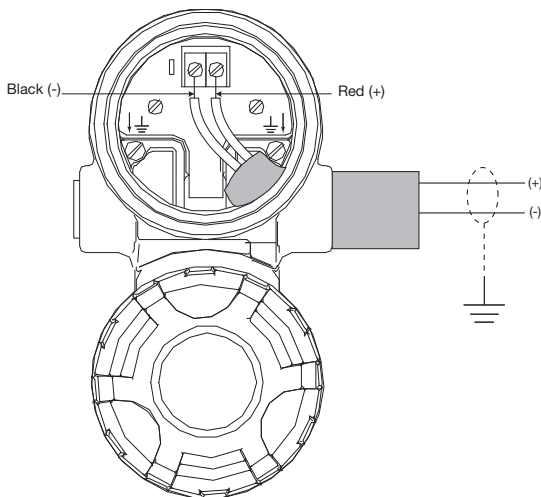
Areas rated Non-Incendive (Cl I, Div. 2) have flammable media present only under abnormal conditions.

No special electrical connections are required.

Caution: If flammable media is contained in the vessel, the transmitter must be installed per Class I, Div 1 standards of area classification.

To install General Purpose or Non-Incendive wiring:

1. Remove the cover from the wiring compartment of the transmitter. Install the conduit plug in the unused opening and use PTFE tape/sealant to ensure a liquid-tight connection.
2. Install a conduit fitting and pull the supply wires.
3. Connect shield to an earth ground at power supply.
4. Connect an earth ground wire to the nearest green ground screw (not shown in illustration).
5. Connect the positive supply wire to the (+) terminal and the negative supply wire to the (-) terminal.



6. Replace and tighten the cover to the transmitter wiring compartment before applying power.

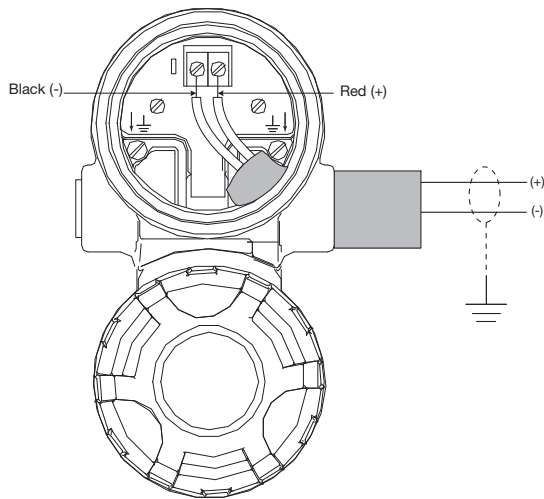
2.5.2 Intrinsically Safe

An Intrinsically Safe (IS) installation potentially has flammable media present. An approved IS barrier must be installed in the non-hazardous (safe) area to limit the available energy out to the hazardous area.

See Agency Drawing – Intrinsically Safe Installation, Section 3.5.1.

To install Intrinsically Safe wiring:

1. Ensure that the IS barrier is properly installed in the safe area (refer to local plant or facility procedures). Complete the wiring from the power supply to the barrier and from the barrier to the PULSAR Model R96 transmitter.
2. Remove the cover from the wiring compartment of the transmitter. Install the conduit plug in the unused opening and use PTFE tape/sealant to ensure a liquid-tight connection.
3. Install a conduit fitting and pull the supply wires.
4. Connect shield to an earth ground at power supply.
5. Connect an earth ground wire to the nearest green ground screw (not shown in illustration).
6. Connect the positive supply wire to the (+) terminal and the negative supply wire to the (-) terminal.
7. Replace and tighten the cover to the wiring compartment of the transmitter before applying power.



2.5.3 Explosion Proof

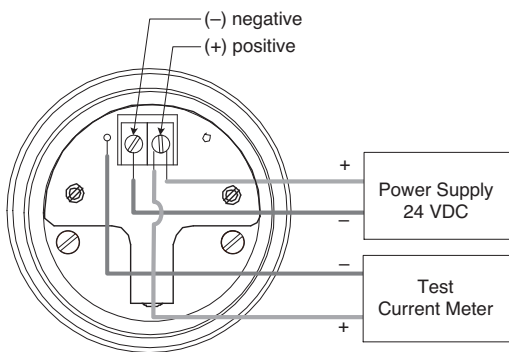
Explosion Proof (also referred to as XP or flameproof) is another method of designing equipment for installation into hazardous areas. A hazardous location is an area in which flammable gases or vapors are (or may be) present in the air in quantities sufficient to produce explosive or ignitable mixtures.

The wiring for the transmitter must be contained in Explosion Proof conduit extending into the safe area.

- Due to the specialized design of the PULSAR MODEL R96 transmitter, no Explosion Proof conduit fitting (EY seal) is required within 18" of the transmitter.
- An Explosion Proof conduit fitting (EY seal) is required between the hazardous and safe areas. See Agency Specifications, Section 3.5.

To install an Explosion Proof transmitter:

1. Install Explosion Proof conduit from the safe area to the conduit connection of the PULSAR Model R96 transmitter (refer to local plant or facility procedures).
2. Remove the cover from the wiring compartment of the transmitter.
3. Connect shield to an earth ground at the power supply.
4. Connect an Earth ground wire to the nearest green ground screw per local electrical code (not shown in illustration).
5. Connect the positive supply wire to the (+) terminal and the negative supply wire to the (-) terminal.
6. Replace and tighten the cover to the wiring compartment of the transmitter before applying power.



Explosion Proof Model

2.6 Configuring the Transmitter

Although the PULSAR Model R96 transmitter can be delivered pre-configured from the factory, it can also be easily reconfigured in the shop or at the installation using the local LCD/Keypad or PACTware/DTM. Bench configuration provides a convenient and efficient way to set up the transmitter before going to the tank site to complete the installation.

Before configuring any transmitter, collect all operating parameters information (refer to Section 1.1.2).

Apply power to the transmitter and follow the step-by-step procedures for the menu-driven transmitter display. Refer to [Sections 2.6.2 and 2.6.4](#).

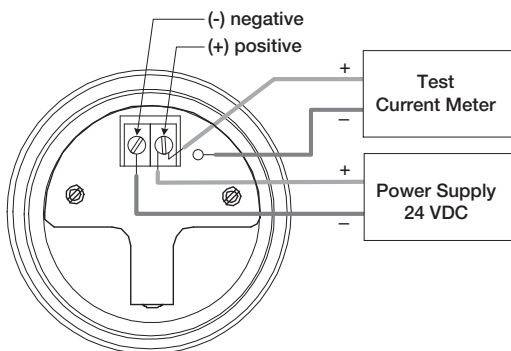
Information on configuring the transmitter using a HART communicator is given in [Section 2.7](#), Configuration Using HART.

Please refer to I/O manual 58-640 for information on FOUNDATION fieldbus output.

2.6.1 Bench Configuration

The PULSAR Model R96 transmitter can be easily configured at a test bench by connecting a standard 24 VDC power supply directly to the transmitter terminals as shown in the accompanying diagram. An optional digital multimeter is shown in the event that mA current measurements are desired.

NOTE: Current measurements taken at these test points are an approximate value. Accurate current readings should be taken with the digital multimeter directly in series with the loop.



G.P./I.S./Explosion Proof Model

NOTE: When using a HART communicator for configuration, a minimum 250-ohm line load resistance is required. Refer to your HART communicator manual for additional information.

NOTE: The transmitter can be configured without the antenna attached. Disregard any diagnostic indicators that may appear.

2.6.2 Menu Traversal and Data Entry

The four push buttons offer various forms of functionality for navigation and data entry.

The PULSAR Model R96 user interface is hierarchical in nature, best described as a tree structure. Each level in the tree contains one or more items. Items are either menu labels or parameter names.

- Menu labels are presented in all capital letters
- Parameters are capital words

2.6.2.1 Navigating the Menu

- ⇧ **UP** moves to the previous item in the menu branch.
- ⇩ **DOWN** moves to the next item in the menu branch.
- ⇐ **BACK** moves back one level to the previous (higher) branch item.
- ⇒ **ENTER** enters into the lower level branch or switches to the entry mode. Holding the ENTER down on any highlighted menu name or parameter will show help text for that item.



2.6.2.2 Data Selection

This method is used for selecting configuration data from a specific list.

- ⇧ **UP** and ⇩ **DOWN** to navigate the menu and highlight the item of interest
- ⇒ **ENTER** allows modification of that selection
- ⇧ **UP** and ⇩ **DOWN** to choose new data selection
- ⇒ **ENTER** to confirm selection

Use ⇐ **BACK** (Escape) key at any time to abort the procedure and escape to previous branch item

2.6.2.3 Entering Numeric Data Using Digit Entry

This method is used to input numeric data, e.g., Tank Height, set 4 mA and set 20 mA.

Push button		Keystroke Action
	Up	Moves up to the next highest digit (0,1,2,3,...,9 or decimal point). If held down the digits scroll until the push button is released.
	Down	Moves up to the next lowest digit (0,1,2,3,...,9 or decimal point). If held down the digits scroll until the push button is released.
	Back	Moves the cursor to the left and deletes a digit. If the cursor is already at the leftmost position, then the screen is exited without changing the previously saved value.
	Enter	Moves the cursor to the right. If the cursor is located at a blank character position, the new value is saved.

All numeric values are left-justified, and new values are entered from left to right. A decimal point can be entered after the first digit is entered, such that .9 is entered as 0.9.

Some configuration parameters can have a negative value. In this case, the leftmost position is reversed for the sign (either "-" for a negative value, or "+" for a positive value).

2.6.2.4 Entering Numeric Data Using Increment/Decrement

Use this method to input the following data into parameters such as Damping and Failure Alarm.

Push button		Keystroke Action
	Up	Increments the displayed value. If held down the digits scroll until the push button is released. Depending on which screen is being revised, the increment amount may increase by a factor of 10 after the value has been incremented 10 times.
	Down	Decrements the displayed value. If held down the digits scroll until the push button is released. Depending on which screen is being revised, the decrement amount may increase by a factor of 10 after the value has been decremented 10 times.
	Back	Returns to the previous menu without changing the original value, which is immediately redisplayed.
	Enter	Accepts the displayed value and returns to the previous menu.

2.6.2.5 Entering Character Data

This method is used for parameters requiring alphanumeric character entry, such as for entering tags, etc.

General Menu Notes:

Push button		Keystroke Action
	Up	Moves to the previous character (Z...Y...X...W). If held down, the characters scroll until the push button is released.
	Down	Moves to the next item character (A...B...C...D). If held down, the characters scroll until the push button is released.
	Back	Moves the cursor back to the left. If the cursor is already at the leftmost position, then the screen is exited without changing the original tag characters.
	Enter	Moves the cursor forward to the right. If the cursor is at the rightmost position, then the new tag is saved.

2.6.3 Password Protection

The PULSAR MODEL R96 Model R96 transmitter has three levels of password protection to restrict access to certain portions of the menu structure that affect the operation of the system. The user password can be changed to any numerical value up to 59999. When the transmitter is programmed for password protection, a password is required whenever configuration values are changed.

User Password

The User Password allows the customer to limit access to the basic configuration parameters.

The default User Password installed in the transmitter at the factory is 0. With a password of 0, the transmitter is no longer password protected and any value in the basic user menus can be adjusted without entering a confirming password.

NOTE: If a User Password is not known or has been misplaced, the menu item New Password in the DEVICE SETUP/ADVANCED CONFIG menu displays an encrypted value representing the present password. Contact Technical Support with this encrypted password to retrieve the original User Password.

Advanced Password

Certain portions of the menu structure that contain more advanced parameters are further protected by an Advanced Password.

This password will be provided, when necessary, by Factory technical support.

Factory Password

Calibration-related and other factory settings are further protected by a Factory Password.

2.6.4 Model R96 Menu: Step-By-Step Procedure

The following tables provide a complete explanation of the software menus displayed by the PULSAR Model R96 transmitter. The menu layout is similar between the local Keypad/LCD interface, the DD, and the DTM.

Use these tables as a step-by-step guide to configure the transmitter based on the desired measurement type from the following selections:

- Level Only
- Level & Volume

HOME SCREEN

The Home Screen consists of a “slide show” sequence of Measured Values screens which are rotated at 2-second intervals. Each Home Measured Value screen can present up to four information items:

- **HART® Tag**
- **Measured Value**
Label, Numerical Value, Units
- **Status**
Will be displayed as text or optionally with NAMUR NE 107 symbol
- **Primary Value Bar Graph** (shown in %)

The Home Screen presentation can be customized by viewing or hiding some of these items. See DISPLAY CONFIG under the DEVICE SETUP menu in Section 2.6.5 — Configuration Menu.

At left is an example of a Home Screen for a Model R96 configured for a Level Only application.





MAIN MENU

Pressing any key on the Home Screen will present the Main Menu, consisting of three basic menu labels shown in all capital letters.

- **DEVICE SETUP**
- **DIAGNOSTICS**
- **MEASURED VALUES**

As shown, the reverse video represents a cursor identifying the selected item, which will appear in reverse video on the LCD. The actions of the keys at this point are:

Push button		Keystroke Action
	Up	No action as the cursor is already at the first item in the MAIN MENU
	Down	Moves the cursor to DIAGNOSTICS
	Back	Moves back to HOME SCREEN, the level above MAIN MENU
	Enter	Presents the selected item, DEVICE SETUP

- NOTES:
1. Items and parameters that are shown in lower level menus will depend on the Measurement Type chosen. Those parameter not applicable to the present Measurement Type will be hidden.
 2. Holding down the Enter key when the cursor is highlighted over a parameter or menu will provide additional information about that item.

DEVICE SETUP

Choosing DEVICE SETUP from the MAIN MENU will result in an LCD presentation as shown at left.

The small down arrow shown at the right hand side of the screen is the indication that more items are available below and can be accessed by pressing the DOWN key.

Section 2.6.5 shows the entire tree menu for the Model R96 DEVICE SETUP Menu.

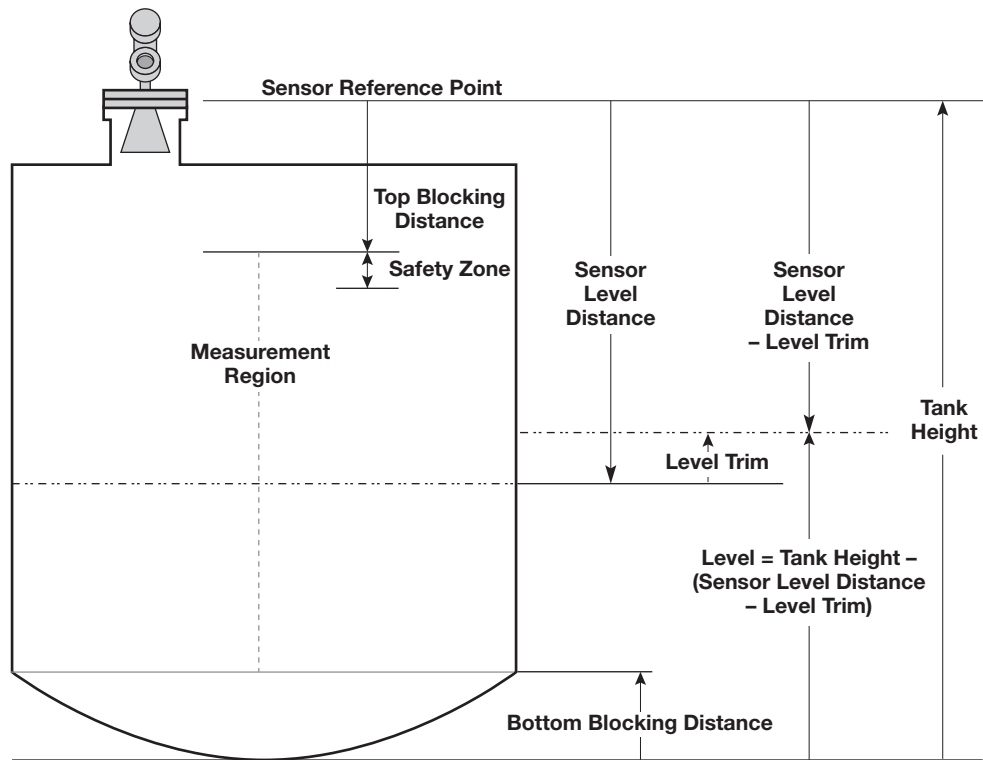


DIAGNOSTICS

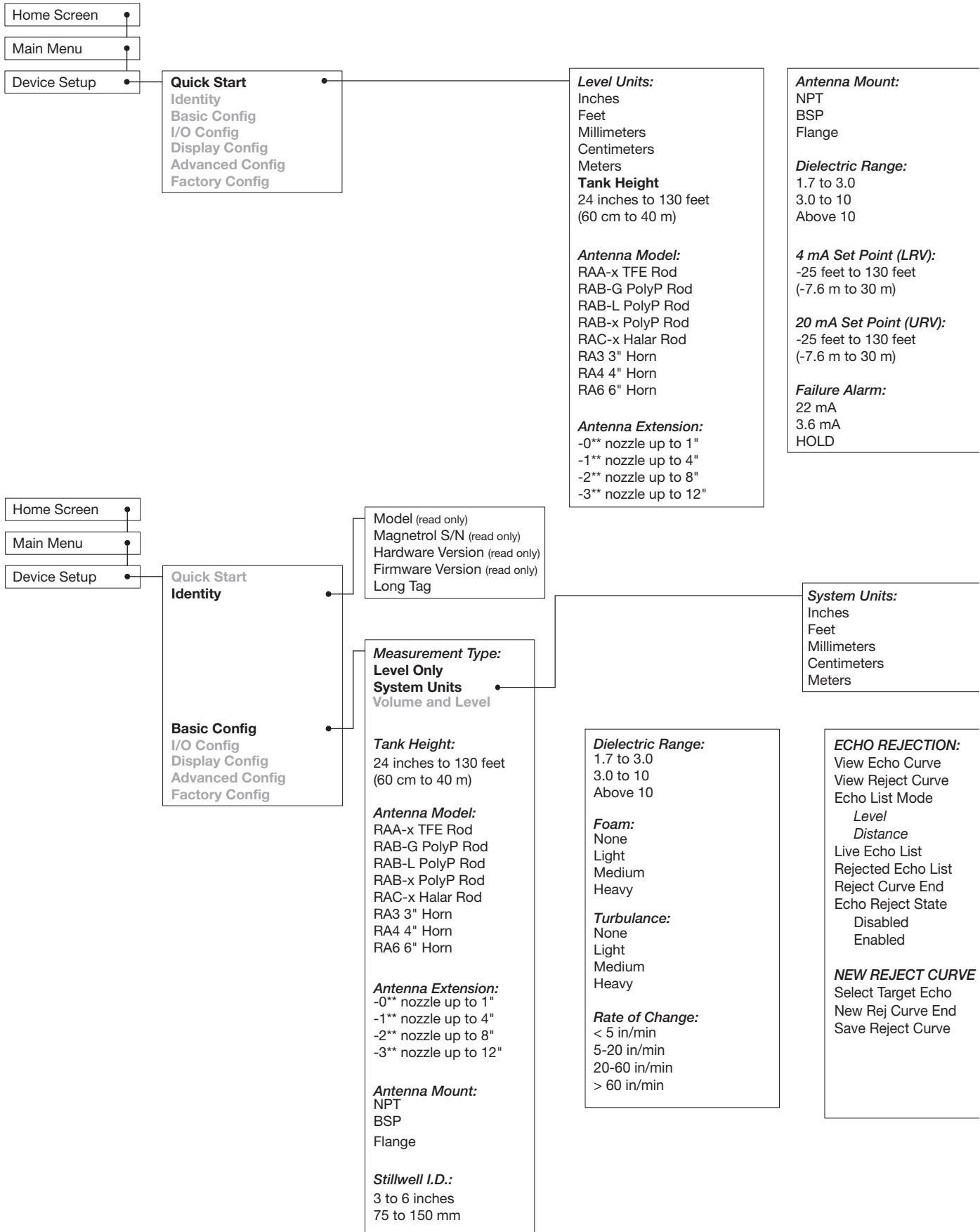
Refer to Section 3.3.4

MEASURED VALUES

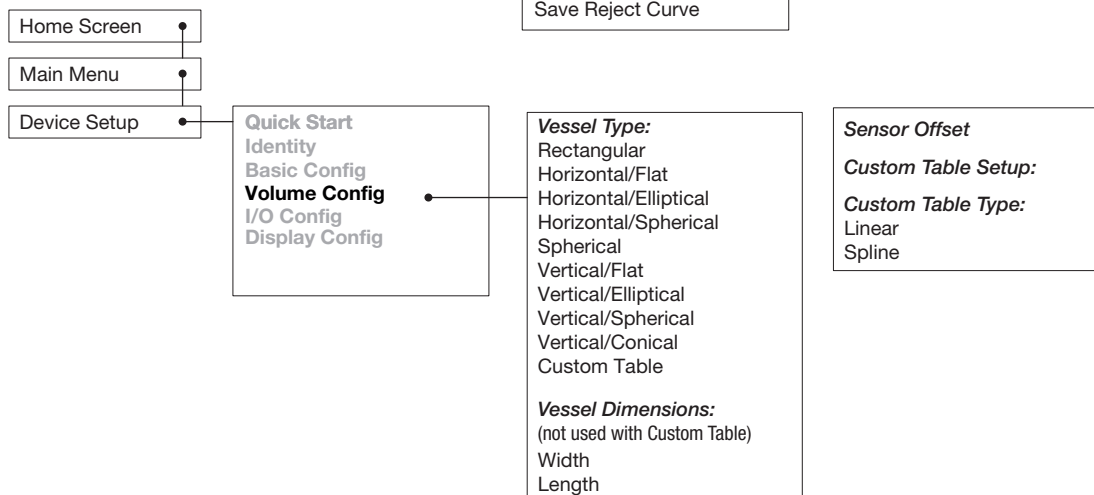
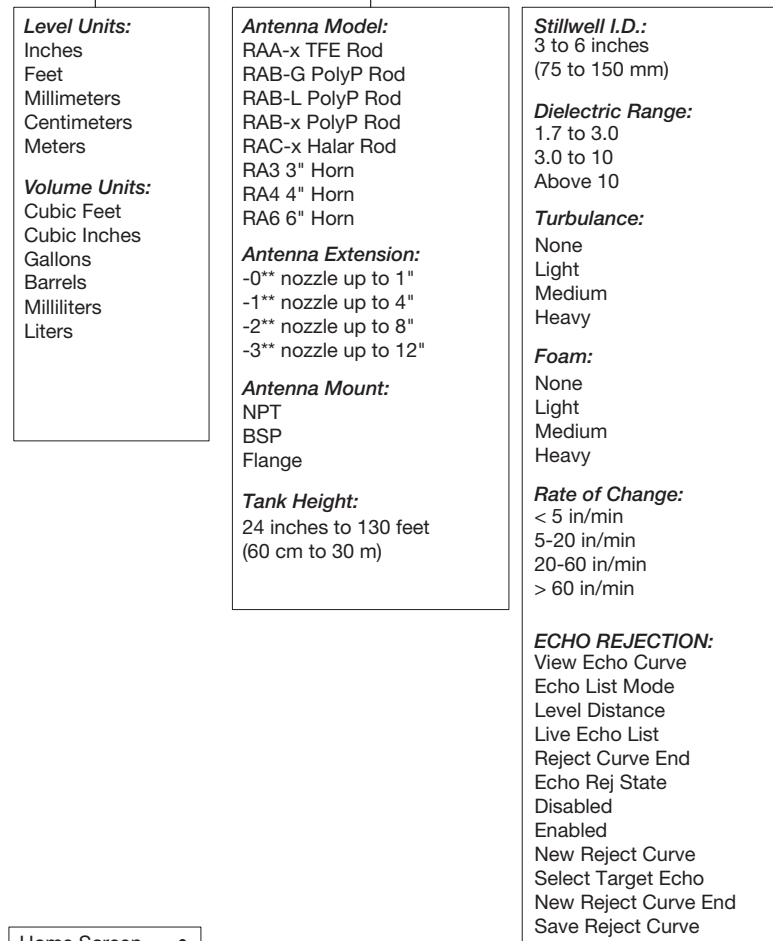
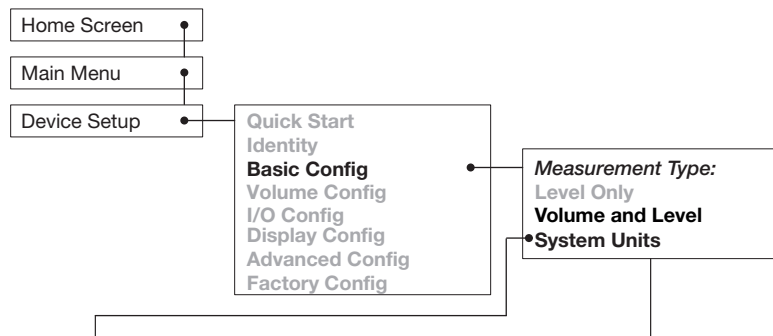
Allows the user to scroll through all of the available measured values for the measurement type chosen.



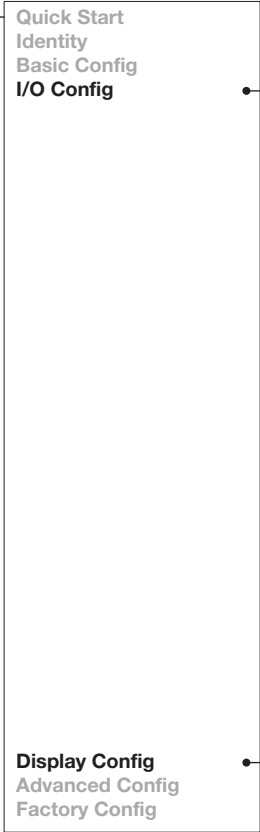
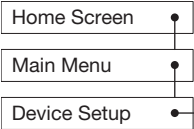
2.6.5 Model R96 Configuration Menu – Device Setup



2.6.5 Model R96 Configuration Menu – Device Setup



2.6.5 Model R96 Configuration Menu – Device Setup



Primary Variable

4 mA Set Pt (LRV):
-25 feet to 130 feet
(-7.6 m to 30 m)
0 to 9999999 gals (Volume)

20 mA Set Pt (URV):
-25 feet to 130 feet
(-7.6 m to 30 m)
0 to 9999999 cf (Volume)

Failure Alarm:
22 mA
3.6 mA
Hold

Damping:
0 to 10 seconds

Language:
English
French
German
Spanish
Russian
Portuguese

Status Symbol:
Hide
View

Long Tag:
Hide
View

PV Bar Graph:
Hide
View

Level:
Hide
View

Volume:
(Volume and Level mode only)
Hide
View

Distance:
Hide
View

% Output:
Hide
View

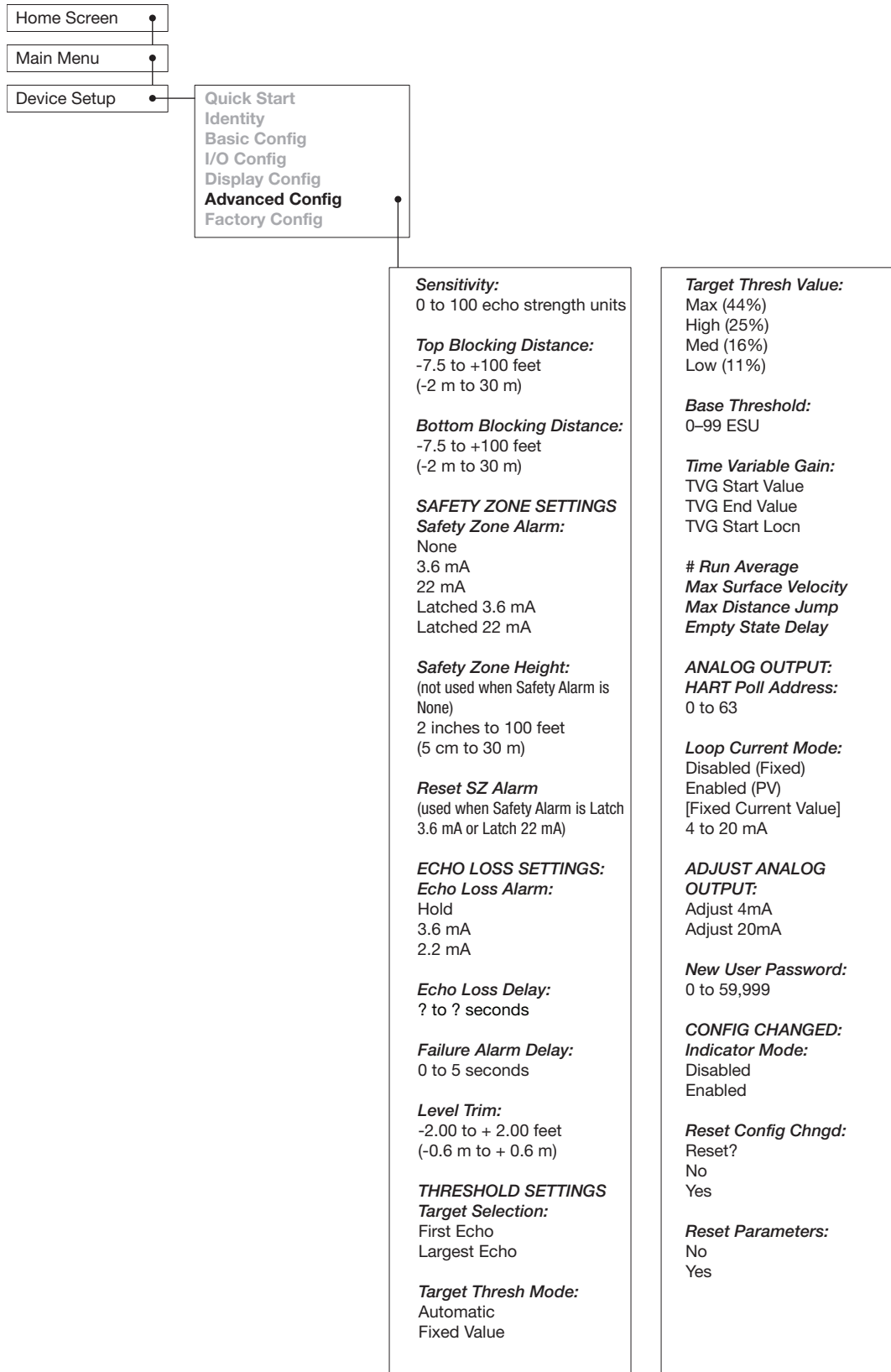
Loop Current:
Hide
View

Echo Strength:
Hide
View

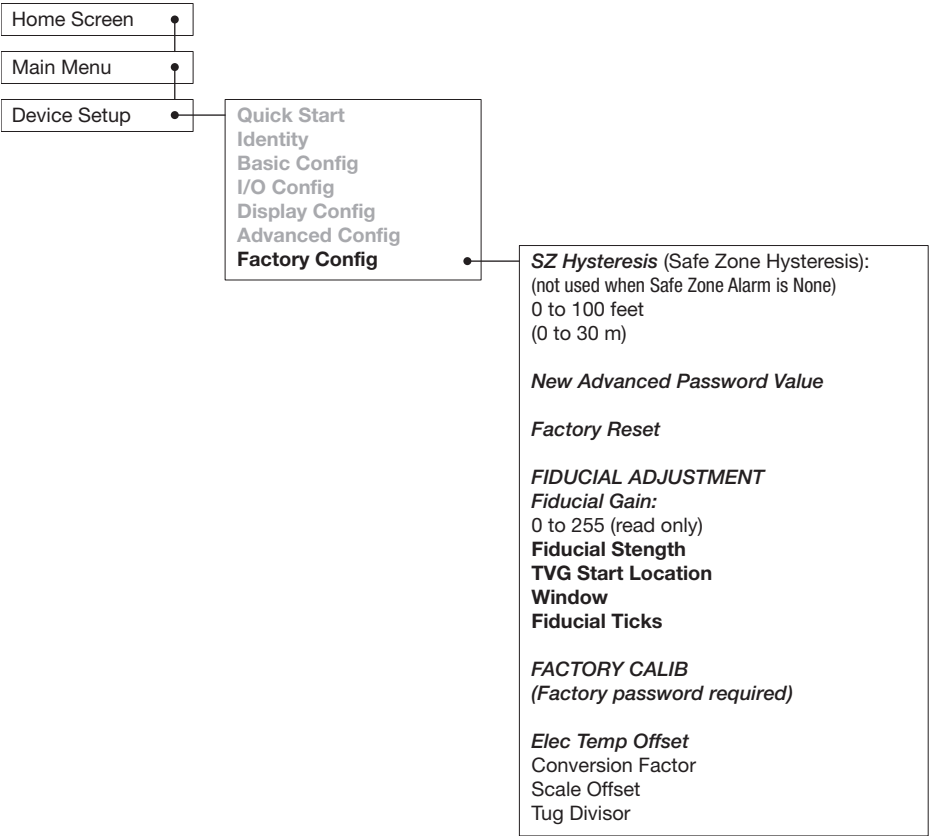
Echo Margin:
Hide
View

Elec Temp:
Hide
View

2.6.5 Model R96 Configuration Menu — Device Setup



2.6.5 Model R96 Configuration Menu – Device Setup



2.7 Configuration Using HART®

A HART (Highway Addressable Remote Transducer) remote unit, such as a HART communicator, can be used to provide a communication link to the PULSAR Model R96 transmitter. When connected to the control loop, the same system measurement readings shown on the transmitter are also shown on the communicator. The communicator can also be used to configure the transmitter.

The HART communicator may need to be updated to include the PULSAR Model R96 software (Device Descriptions). Refer to your HART Communicator Manual for update instructions.

One can also access configuration parameters using *PACTware* and the Model R96 DTM, or using the AMS with EDDL.

2.7.1 Connections

A HART communicator can be operated from a remote location by connecting it to a remote junction or by connecting it directly to the terminal block in the electronics housing of the PULSAR Model R96 transmitter.

HART uses the Bell 202 frequency shift key technique of high-frequency digital signals. It operates on the 4–20 mA loop and requires 250 Ω load resistance. A typical connection between a communicator and the PULSAR Model R96 transmitter is illustrated.

2.7.2 Display Menu

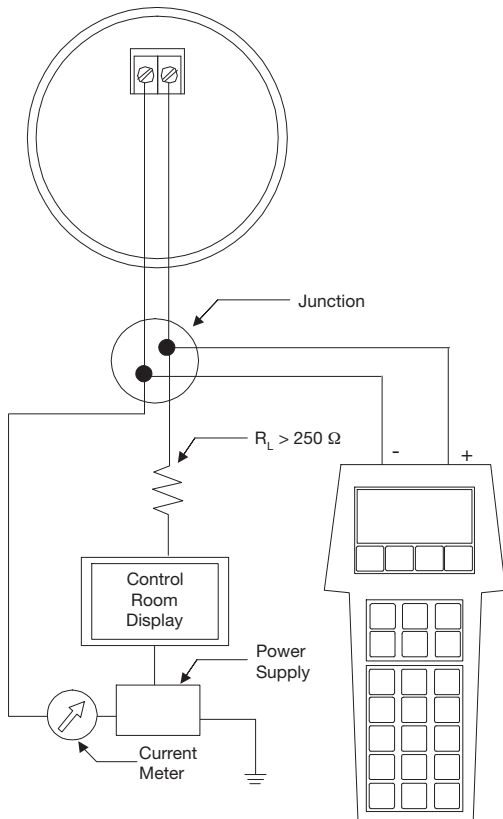
A typical communicator display is an 8-line by 21-character LCD. When connected, the top line of each menu displays the model (Model RX5) and its tag number or address. For detailed operating information, refer to the instruction manual provided with the HART communicator.

The PULSAR Model R96 transmitter online menu trees are shown in the following illustration. Open the menu by pressing the alphanumeric key 4, Device Setup, to display the second-level menu.

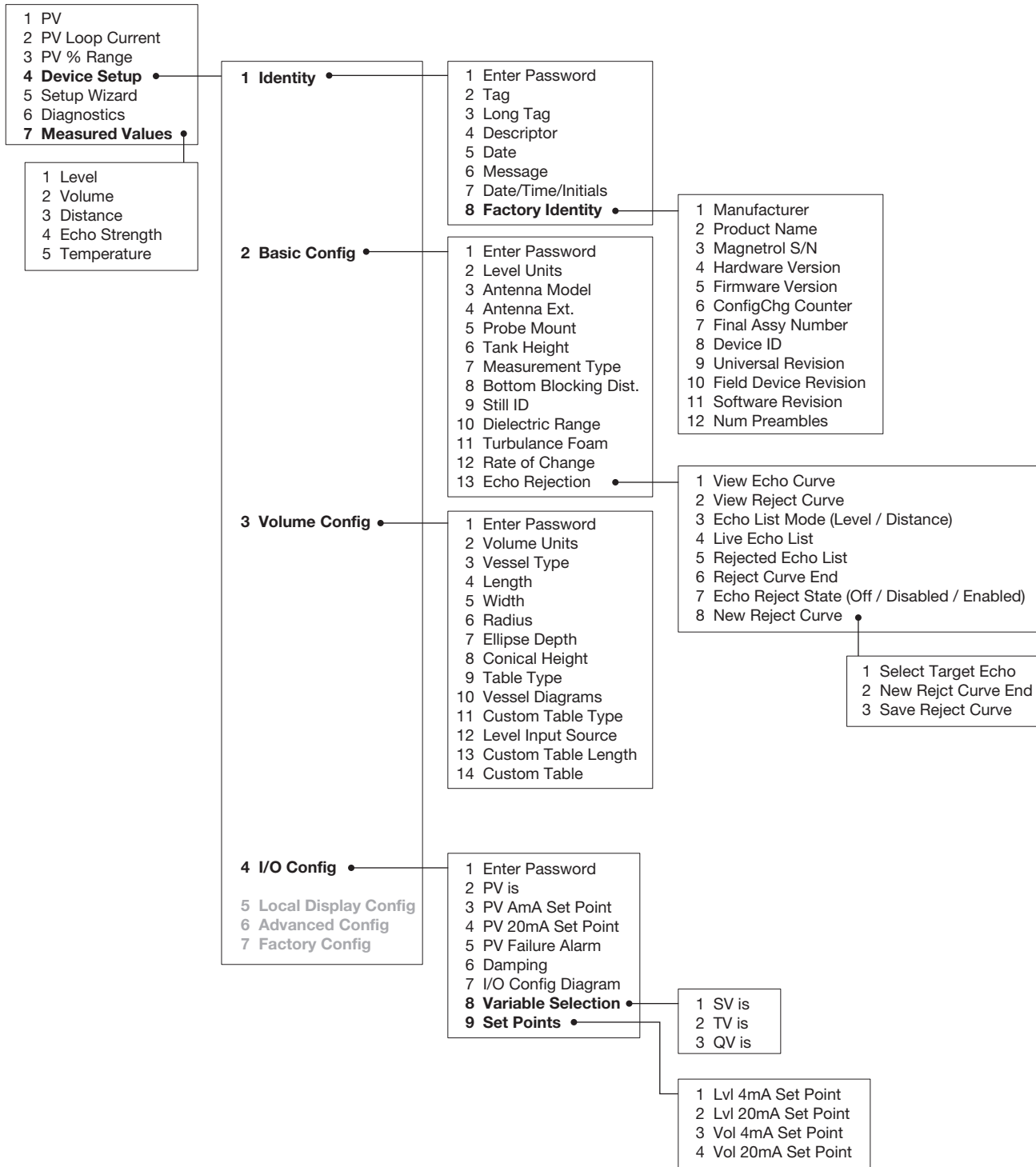
2.7.3 HART Revision Table

2.7.3.1 Model R96

HART Version	HCF Release Date	Compatible with R96 Software
Dev V1 DD1	December 2015	Version 1.0a and later



2.7.4 HART Menu



3.0 Reference Information

This section presents an overview of the operation of the PULSAR Model R96 Radar Level Transmitter, information on troubleshooting, common problems, listings of agency approvals, lists of replacement and recommended spare parts, and detailed physical, functional and performance specifications.

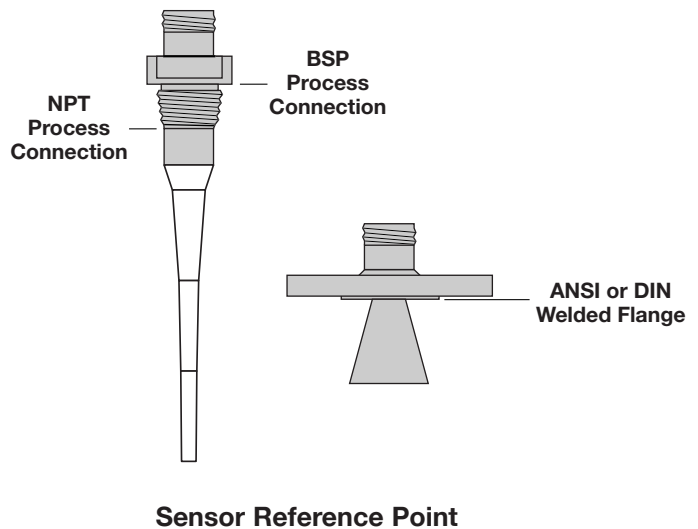
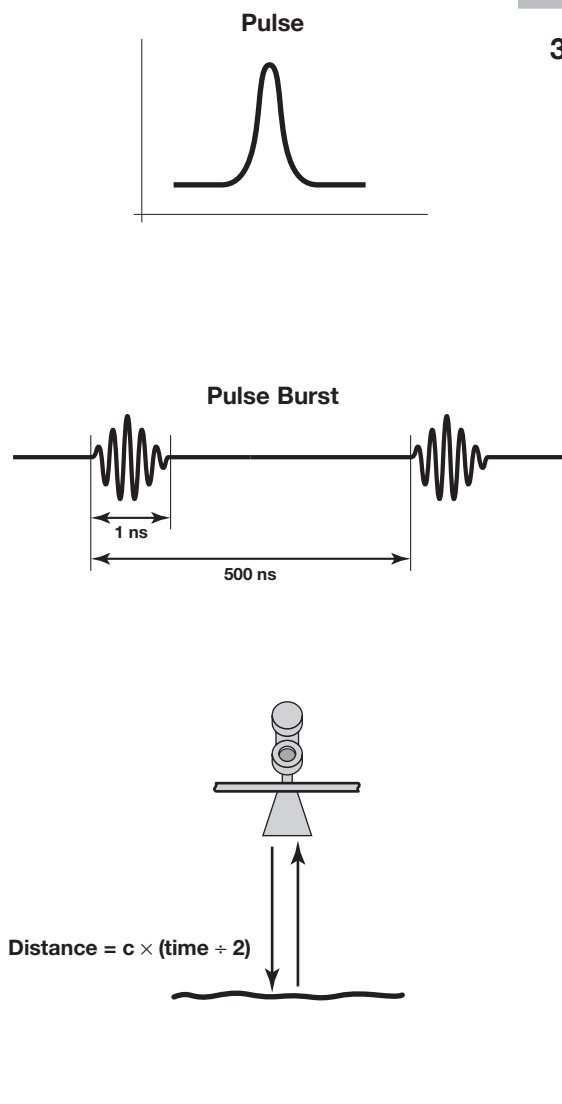
3.1 Description

PULSAR Model R96 is a two-wire, 24 VDC, level transmitter based on the concept of pulse burst radar. The electronics are housed in an ergonomic housing comprised of two tandem compartments angled at a 45 degree angle for ease of wiring and calibration. These two compartments connect via a watertight feed-through.

3.2 Theory of Operation

3.2.1 Pulse Burst Radar

PULSAR Model R96 is a top-mounted, downward-looking pulse burst radar operating at 6 GHz. Unlike true pulse devices (GWR, for example) that transmit a single, sharp (fast rise-time) waveform of wide-band energy, PULSAR Model R96 emits short bursts of 6 GHz energy and measures the transit time of the signal reflected off the liquid surface. Distance is calculated utilizing the equation: $\text{Distance} = C \times \text{Transit time} / 2$, then developing the Level value by factoring in application-specific configuration. The exact reference point for distance and level calculations is the Sensor Reference Point—bottom of an NPT thread, top of a BSP thread or face of a flange.



The exact level measurement is extracted from false target reflections and other background noise via the use of sophisticated signal processing. The new PULSAR Model R96 circuitry is extremely energy efficient so no duty cycling is necessary to accomplish effective measurement.

3.2.2 Equivalent Time Sampling

ETS, or Equivalent Time Sampling, is used to measure the high speed, low power EM (electromagnetic) energy. ETS is a critical key in the application of Radar to vessel level measurement technology. The high speed electromagnetic energy (1000 ft/ μ s) is difficult to measure over short distances and at the resolution required in the process industry. ETS captures the EM signals in real time (nanoseconds) and reconstructs them in equivalent time (milliseconds), which is much easier to measure with today's technology.

ETS is accomplished by scanning the tank to collect thousands of samples. Approximately 3 scans are taken per second; each scan gathers more than 50,000 samples.

3.3 Troubleshooting and Diagnostics

The PULSAR Model R96 transmitter is designed and engineered for trouble-free operation over a wide range of operating conditions. The transmitter continuously runs a series of internal self-tests and displays helpful messages on the large graphic liquid crystal display (LCD) when attention is required.

The combination of these internal tests and diagnostics messages offer a valuable proactive method of troubleshooting. The device not only tells the user what wrong, but also, and more importantly, offers suggestions on how to solve the problem.

All of this information can be obtained directly from the transmitter on the LCD, or remotely by using a HART communicator or PACTware and the PULSAR Model R96 DTM.

PACTware™ PC Program

The PULSAR Model R96 offers the ability to perform more advanced diagnostics such as Trending and Echo Curve analysis using a PACTware DTM. This is a powerful troubleshooting tool that can aid in the resolution of any diagnostic indicators that may appear.

Please refer to section 4.0 “Advanced Configuration/Troubleshooting Techniques” for additional information.

3.3.1 Diagnostics (NAMUR NE 107)

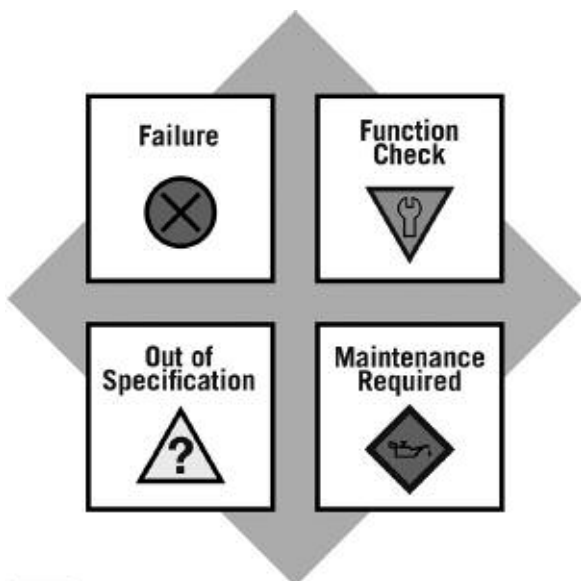
The PULSAR Model R96 transmitter includes an exhaustive list of Diagnostic Indicators which follow the NAMUR NE 107 guidelines.

NAMUR is an international user association of automation technology in process industries, whose goal is to promote the interest of the process industry by pooling experiences among its member companies. In doing so, this group promotes international standards for devices, systems, and technologies.

technologies.

The objective of NAMUR NE 107 was essentially to make maintenance more efficient by standardizing diagnostics information from field devices. This was initially integrated via FOUNDATION Fieldbus, but the concept applies regardless of the communication protocol.

According to the NAMUR NE107 recommendation, "Self Monitoring and Diagnosis of Field Devices," fieldbus diagnostic results should be reliable and viewed in the context of



a given application. The document recommends categorizing internal diagnostics into four standard status signals:

- Failure
- Function Check
- Out of Specification
- Maintenance required

These categories are shown by both symbols and colors, depending on the display capability.

In essence, this approach ensures that the correct diagnostic information is available to the correct person-at the correct time. In addition, it allows diagnostics to be applied, as most appropriate, for a particular plant application (such as process control engineering or asset management maintenance). Customer specific mapping of diagnostics to these categories allows for flexible configuration depending on the user's requirements.

From an external Model R96 transmitter perspective, diagnostic information includes measurement of process conditions, in addition to detection of internal device or system anomalies.

As mentioned above, the indicators can be assignable (via the a DTM or host system) by the user to any (or none) of the NAMUR recommended Status Signal categories: Failure, Function Check, Out of Specification, and Maintenance Required.

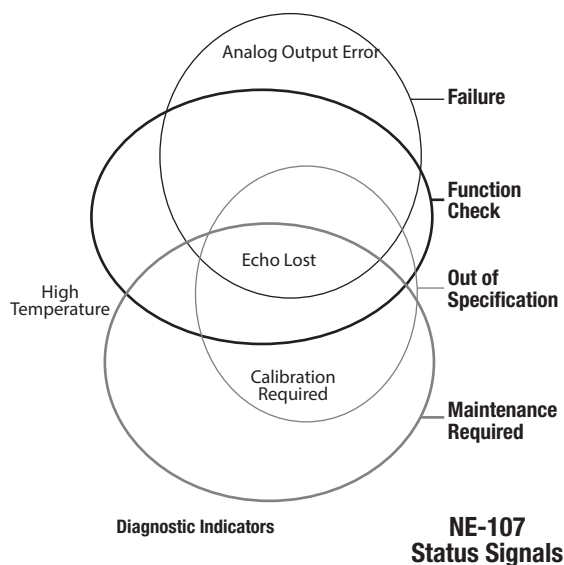
The FOUNDATION fieldbus transmitter version of the Model R96 was implemented according to the Field Diagnostics Profile, which is consistent with the objectives of NE 107.

In the FOUNDATION fieldbus version, diagnostic indicators can be mapped to multiple categories, an example is shown in the diagram at left.

In this example, “Calibration Required” is mapped to both the Out of Specification and Maintenance Required status signals, and the diagnostic indicator named “High Temperature” is mapped to none of the signals.

Indicators that are mapped to the Failure category will normally result in a current loop alarm output. The alarm state for HART transmitters is configurable as high (22 mA), Low (3.6 mA), or Hold (last value).

Users will not have the ability to unassign certain indicators from the Failure signal category as the Model R96 user interfaces will prohibit or reject such re-assignment entries). This is to ensure that current loop alarms are asserted in situations where the device is not able to provide measurements



due to critical failures. (For example, if the alarm selection has not been set to Hold, or a fixed current mode is in effect.)

A default mapping of all diagnostic indicators will be applied initially, and can be re-applied through use of a reset function.

Refer to the Diagnostic Indicator tables in Section 3.3.3 for a complete listing of the Model R96 diagnostic indicators, along with their explanations, default categories, and recommended remedies.

- NOTES:
- 1) The remedies shown in this table can also be seen on the transmitter LCD by viewing the present status screen when the device is in a diagnostic condition.
 - 2) Those indicators showing failure as the default result in an alarm condition.

3.3.2 Diagnostic Indication Simulation

The DD and DTM allow for the ability to manipulate diagnostic indicators. Intended as a means to verify the configuration of the diagnostic parameters and connected equipment, a user can manually change any indicator to and from the active state.

3.3.3 Diagnostic Indicator Table

Shown below and at right is a listing of the Model R96 diagnostic indicators, showing their priority, explanations and recommended remedies. (Priority 1 is highest priority.)

Priority	Indicator Name	Default Category	Explanation	Remedy (Context Sensitive Help)
1	Software Error	Failure	Unrecoverable error occurred in stored program.	Contact MAGNETROL Technical Support.
2	RAM Error	Failure	RAM (read/write) memory failing.	
3	ADC Error	Failure	Analog-to-digital converter failure.	
4	EEPROM Error	Failure	Non-volatile parameter storage failing.	
5	Analog Board Error	Failure	Unrecoverable hardware failure.	
6	Analog Output Error	Failure	Actual loop current deviates from commanded value. Analog output is inaccurate.	Perform Adjust Analog Output maintenance procedure.
7	Spare Indicator 1	OK	Reserved for future use.	
8	Default Parameters		Saved parameters are set to default values.	Perform complete Device Configuration.
9	No Antenna	Failure	No antennae connected to transmitter.	Attach an antennae. Torque HF nut. Clean gold pin on transmitter and socket on probe. Contact MAGNETROL Technical Support.
10	Spare Indicator 2	OK	Reserved for future use.	
11	No Fiducial	Failure	Reference signal too weak to detect.	Torque HF nut. Clean gold pin on transmitter and socket on antenna. Check settings: Fiducial Gain HF Cable Length Window Increase Fid Gain. Contact MAGNETROL Technical Support.
12	Too Many Echoes			
13	Safety Zone Alarm	Failure	Risk of echo loss if liquid rises above Blocking Distance.	Ensure that liquid cannot reach Blocking Distance.
14	Echo Lost	Failure	No signal detected anywhere on probe.	Check settings: Dielectric Range Sensitivity EoP Thresh Value Increase Sensitivity. Lower EoP Thresh. View Echo Curve.
15	Spare Indicator 3	OK	Reserved for future use	
16	Config Conflict	Failure	Measurement type and primary variable selection parameters are inconsistent.	Confirm proper configuration. Check Measurement Type.
17	High Volume Alarm	Failure	Volume calculated from Level reading exceeds capacity of vessel or custom table.	Check settings: Vessel Dimensions, Custom Table entries

Priority	Indicator Name	Default Category	Explanation	Remedy
18	Analog Output Fixed	Function Check	Loop current not following PV. May be caused by existing alarm condition, ongoing Loop Test or Trim Loop operations.	If unexpected, check Loop Current Mode. Ensure device is not in Loop Test.
19	Spare Indicator 4	OK	Reserved for future use.	
20	Initializing	Function Check	Distance measurement is inaccurate while internal filters are settling.	Standard start-up message. Wait for up to 10 seconds.
21	Config Changed	Function Check	A parameter has been modified from the User Interface.	If desired, reset Config Changed indicator in ADVANCED CONFIG menu.
22	Spare Indicator 5	OK	Reserved for future use.	
23	Ramp Slope Error	Out of Spec	Internal signal timing out of limits causing inaccurate distance measurement.	Check accuracy of Level reading. Replace transmitter electronics. Contact MAGNETROL Technical Support.
24	High Elec Temp	Out of Spec	Electronics too hot. May compromise level measurement or damage instrument.	Shield transmitter from heat source or increase air circulation. Locate transmitter remotely in a cooler area.
25	Low Elec Temp	Out of Spec	Electronics too cold. May compromise level measurement or damage instrument.	Insulate transmitter. Locate transmitter remotely in a warmer area.
26	Calibration Req'd	Out of Spec	Factory calibration has been lost. Measurement accuracy may be diminished.	Return transmitter to factory for recalibration.
27	Echo Reject Invalid	Out of Spec	Echo Rejection inoperative. May report erroneous Level readings. Upr Echo may be lost near top of probe.	Save a fresh Echo Rejection Curve.
28	Spare Indicator 6	OK	Reserved for future use.	
29	Inferred Level			
30	Adjust Analog Out	Out of Spec	Loop current is inaccurate.	Perform Adjust Analog Output maintenance procedure.
31	Low Supply Voltage	Out of Spec	Loop current may be incorrect at higher values. Analog output is inaccurate.	Verify loop resistance. Replace loop power supply.
32	Spare Indicator 7	OK	Reserved for future use.	
33	Low Echo Strength	Maintenance Required	Risk of Echo Lost due to weak signal.	Check settings: Dielectric Range Sensitivity View Echo Curve.
34	Low Signal Margin			
35	High Surface Velocity			
36	Spare Indicator 8			
37	Spare Indicator 9			
38	Sequence Record	OK	A Sequence Record number has been stored in Event Log.	If desired, report Sequence Record number to factory.

3.3.4 Diagnostic Help

Selecting **DIAGNOSTICS** from the **MAIN MENU** presents a list of five **ITEMS** from the top level of the **DIAGNOSTICS** tree.

When **Present Status** is highlighted, the highest **MAGNETROL** priority active diagnostic indicator (numerically lowest in Table 3.3.3) is displayed on the bottom LCD line, which is “OK” as shown at left. Pressing the **ENTER** key moves the active diagnostic indicator to the top line outdented and presents in the lower area of the LCD a brief explanation of and possible remedies for the indicated condition. A blank line separates the explanation from the remedies. Additional active diagnostic indicators, if any, appear with their explanations in descending priority order. Each additional active indicator name-explanation pair is separated by a blank line from the one above.

If the explanation and remedy text (and additional name-explanation pairs) exceeds the available space, a ↵ appears in the rightmost column of the last line indicating more text below. In this situation, the **DN** key scrolls text up one line at a time. Similarly, while text exists above the upper line of the text field, a ⬆ appears in the rightmost column of the top (text) line. In this situation, the **UP** key scrolls the text down one line at a time. Otherwise the **DN** and **UP** keys are inoperative. In all cases the **ENT** or **DEL** key reverts to the previous screen.

When the transmitter is operating normally and the highlight cursor is positioned on **Present Status**, the bottom LCD line displays “OK” because no diagnostic indicators are active.

EVENT HISTORY – This menu displays the parameters related to diagnostic event logging.

ADVANCED DIAGNOSTICS – This menu displays parameters related to some of the advanced diagnostics available within the Model R96.

INTERNAL VALUES – Displays read-only internal parameters.

ELEC TEMPERATURES – Displays temperature information as measured in the potted module in degrees F or C.

TRANSMITTER TESTS – Allows the user to manually set the output current to a constant value. This is a method for the user to verify operation of the other equipment in the loop.

ECHO CURVES – This menu allows the user to display the live Echo Curve on the LCD.



ECHO HISTORY SETUP – The Model R96 contains the unique and powerful feature that allows waveforms to be automatically captured based on Diagnostic Events, Time or both. This menu contains those parameters that configure that feature.

Eleven (11) waveforms can be saved directly into the transmitter.

- Nine (9) Troubleshooting Curves
- One (1) Echo Rejection Curve
- One (1) Reference Curve

TREND DATA – A 15-minute trend of the PV can be displayed on the LCD.

3.3.5 Troubleshooting System Problems

Symptom	Problem	Solution
Level reading drops out at a repeatable position in the vessel	Multipath signals may be cancelling good level signal	Orient launcher to reduce multipath; turn launcher 20–30 degrees at a time until multipath at this point disappears. Refer to Section 2.4.2.3
Level reading locked onto a value that is not correct Level	Measurement engine finding a reflection it believes is level signal	1. Is high dielectric ($\epsilon > 20$) foam present 2. Run False Target Rejection routine with Level below this point (or with Empty tank) to eliminate false echoes
LEVEL, % Output and LOOP values are all inaccurate	Basic configuration data questionable	1. Check validity of all configuration data 2. Check DISTANCE value of device against manually measured distance
LEVEL readings are repeatable but consistently high (or low) from actual by a fixed amount	Configuration data does not accurately match tank dimensions	1. Ensure proper values for Tank Height and Bottom Blocking Distance 2. Check vessel for present liquid level. Trim Level can be used to ensure exact measurement 3. Reconfigure LOOP values if necessary
LEVEL reading on Display is correct but LOOP is stuck at 4 mA	HART Poll Address set a value of 1-15	Set HART Poll Address to 0

3.4 Configuration Information

This section is intended to offer additional configuration-related details with respect to some of the parameters shown in the Menu in Section 2.6.

3.4.1 Bottom Blocking Distance Description

The parameter referred to as **Bottom Blocking Distance** in the PULSAR Model R96 DEVICE SETUP/BASIC CONFIG menu is defined as the desired level reading when liquid surface.

The PULSAR Model R96 transmitter is shipped from the factory with Bottom Blocking Distance set to 0. With this configuration, all measurements are referenced from the bottom of the tank. See Example 1.

Example 1 (Bottom Blocking Distance = 0 as shipped from factory):

Application calls for a Model R96 Antenna in an 82-inch tank with an flanged process connection. The process medium is water with the bottom of the probe 10 inches above the bottom of the tank.

The user wants the 4 mA Set Point (LRV) at 24 inches and the 20 mA Set Point (URV) at 60 inches as **referenced from the bottom of the tank**.

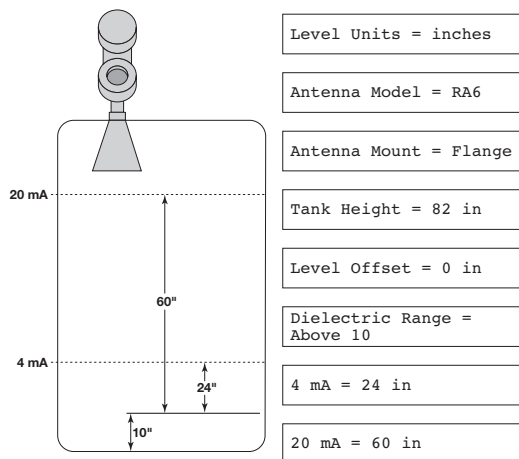
In those applications in which it is desired to reference all measurements from the bottom of the vessel, the value of Level Offset should be changed to the distance between the bottom of the probe and the bottom of the vessel as shown in Example 2.

Example 2:

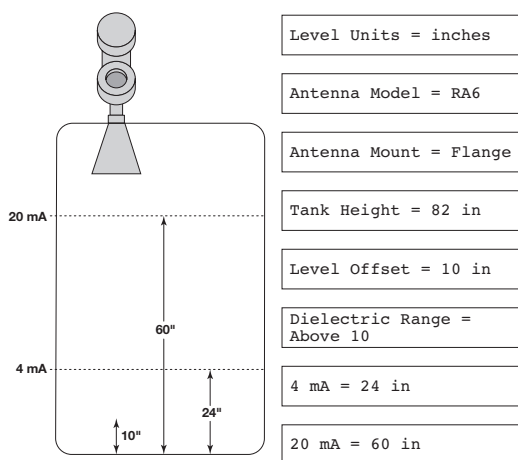
Application calls for a Model R96 Antenna in an 82-inch tank with an flanged process connection. The process medium is water with the bottom of the probe 10 inches above the bottom of the tank.

The user wants the 4 mA Set Point (LRV) at 24 inches and the 20 mA Set Point (URV) at 60 inches as **referenced from the bottom of the tank**.

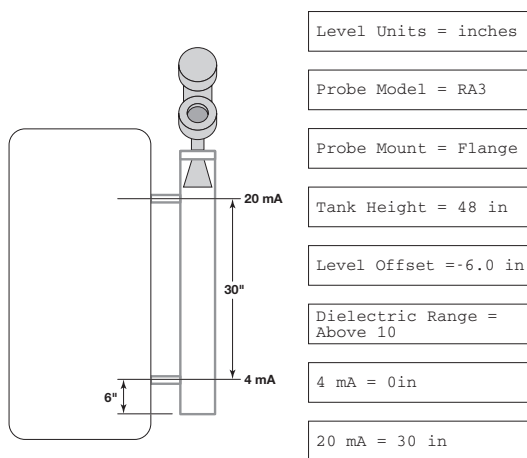
When the PULSAR Model R96 transmitter is mounted in a stillwell, it is usually desirable to configure the unit with the 4 mA Set Point (LRV) at the lower process connection and the 20 mA Set Point (URV) at the upper process connection. The measuring range then becomes the center-to-center dimension. In this case, a negative Bottom Blocking Distance needs to be entered. In doing so, all measurements are then referenced at a point up on the probe, as shown in Example 3.



Example 1



Example 2



Example 3

Example 3:

Application calls for a Model RA3 antenna flanged probe measuring water in a 3-inch chamber with the bottom of the probe extending 6 inches below the lower process connection. The user wants the 4 mA point to be 0 inches at the bottom process connection and the 20 mA point to be 30 inches at the top process connection.

3.4.2 Echo Rejection

Since all Non-Contact radar transmitters are application/installation dependent, Echo Rejection (ignoring false targets) is necessary.

The Model R96 transmitter Echo Rejection feature is located in the DEVICE SETUP/ADVANCED CONFIG menu, and requires an Advanced Password to activate. It is highly recommended that this feature be used with the waveform capture capability of the Model R96 DTM and PACTware™.

Refer to Section 4 “Advanced Configuration/ Troubleshooting Techniques” or contact MAGNETROL Technical Support for additional instructions.

3.4.3 Volumetric Capability

Selecting Measurement Type = Volume and Level allows the Model R96 transmitter to measure volume as the Primary Measured Value.

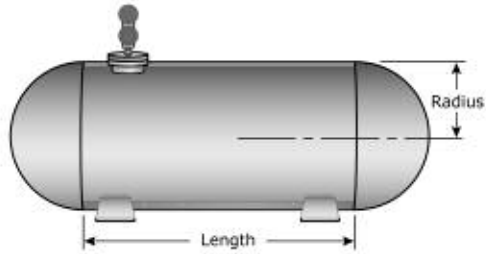
3.4.3.1 Configuration using built-in Vessel Types

The following table provides an explanation of each of the System Configuration parameters required for volume applications that use one of the nine Vessel Types.

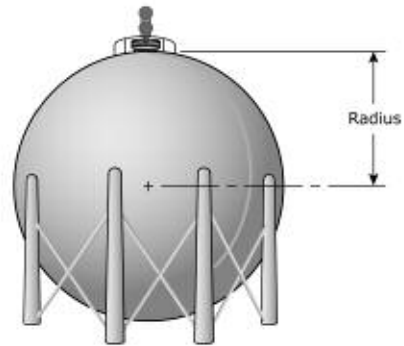
MEASUREMENT TYPE = LEVEL & VOLUME

Configuration Parameter	Explanation
System Units	A selection of Gallons (factory default Volume Unit), Milliliters, Liters, Cubic Feet, or Cubic Inches, is provided.
Vessel Type	Select either Vertical/Flat (factory default Vessel Type), Vertical/Elliptical, Vertical/Spherical, Vertical/Conical, Rectangular, Horizontal/Flat, Horizontal/Elliptical, Horizontal/Spherical, Spherical, or Custom Table. Note: Vessel Dims is the next screen only if a specific Vessel Type was selected. If Custom Table was selected. Refer to page 61 to select the Cust Table Type and Cust Table Vals.
Vessel Dims	See the vessel drawings on the following page for relevant measuring areas.
Radius	Used for all Vessel Types with the exception of Rectangular.
Ellipse Depth	Used for Horizontal and Vertical/Elliptical vessels.
Conical Height	Used for Vertical/Conical vessels.
Width	Used for Rectangular vessels.
Length	Used for Rectangular and Horizontal vessels.

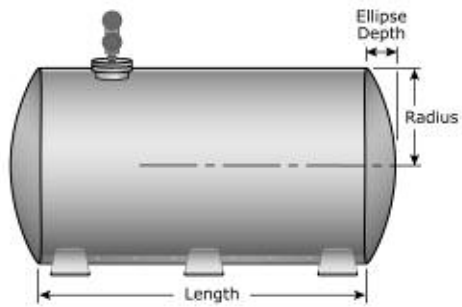
Vessel Types



HORIZONTAL/SPHERICAL



SPHERICAL



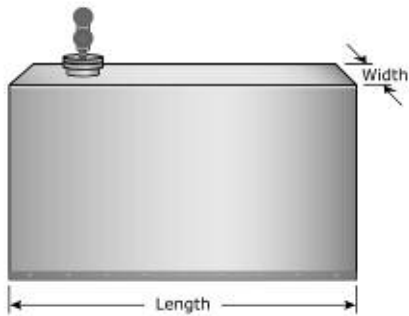
HORIZONTAL/ELLIPTICAL



VERTICAL/ELLIPTICAL



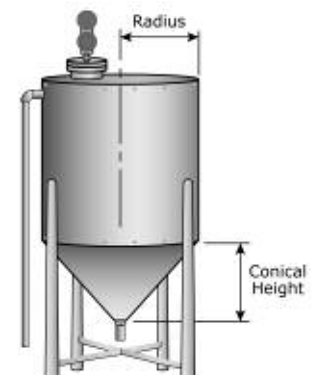
VERTICAL/SPHERICAL



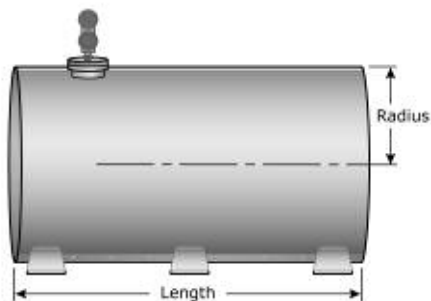
RECTANGULAR



VERTICAL/FLAT



VERTICAL/CONICAL

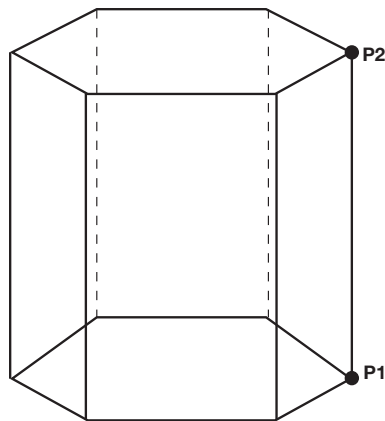


HORIZONTAL/FLAT

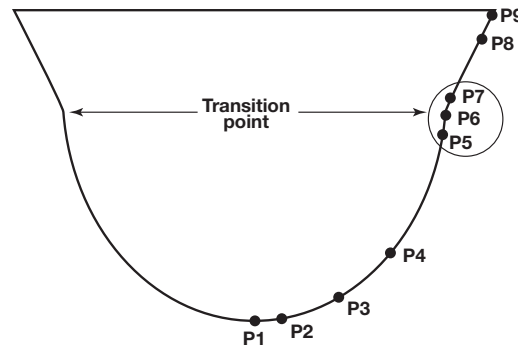
3.4.3.2 Configuration using Custom Table

If none of the nine **Vessel Types** shown can be used, a **Custom Table** can be created. A maximum of 30 points can be used to establish the level to volume relationship. The following table provides an explanation of each of the System Configuration parameters for volume applications where a Custom Table is needed.

Configuration Parameter	Explanation (Custom Volumetric Table)
Volume Units	A selection of Gallons (factory default <i>Volume Unit</i>), Milliliters , Liters , Cubic Feet , or Cubic Inches , is provided.
Vessel Type	Select Custom Table if none of the nine <i>Vessel Types</i> can be used.
Cust Table Type	The <i>Custom Table</i> points can be a Linear (straight line between adjacent points) or Spline (can be a curved line between points) relationship. See below drawing for more information.
Cust Table Vals	A maximum of 30 points can be used in building the <i>Custom Table</i> . Each pair of values will have a level (height) in the units chosen in the <i>Level Units</i> screen, and the associated volume for that level point. The values must be monotonic, i.e. each pair of values must be greater than the previous level/volume pair. The last pair of values should have the highest level value and volume value associated with the level in the vessel.



LINEAR



Use where walls are not perpendicular to base.

Concentrate at least two points at beginning (P1) and end (P9); and three points at either side of transition points.

SPLINE

3.4.4 Reset Function

A parameter labeled “Reset Parameter” is located at the end of the DEVICE SETUP/ADVANCED CONFIG menu. In the event a user gets confused during configuration or advanced troubleshooting, this parameter gives the user the ability to reset the Model R96 transmitter configuration.

Unique to the Model R96 transmitter is the ability for MAGNETROL to fully “pre-configure” devices to customer requests. For that reason, the Reset function will return the device back to the state **at which it left the factory**.

It is recommended that MAGNETROL Technical Support be contacted as the Advanced User password will be required for this reset.

3.5 Agency Approvals



These units are in compliance with the EMC-directive 2004/108/EC, and the ATEX directive 94/9/EC.

Explosion Proof US/Canada: Class I, Div 1, Group B, C, D, T6 Class I, Zone 1 AEx d IIC T6 Class I, Zone 1 Ex d IIC T6 Ta = -40°C to +70°C Type 4X, IP67 Flame Proof ATEX – FM14ATEXXXXXX: II 2/1 G Ex d/ia IIB + H2 T6 to T1 Gb/Ga Ta = -40°C to +70°C IP67 IEC- IECEX FMG XXXXX: Ex d/ia IIB + H2 T6 to T1 Gb/Ga Ta = -40°C to +70°C IP67	Non- Incendive US/Canada: Class I, II, III, Division 2, Group A, B, C, D, E, F, G, T6 Class 1, Zone 2 AEx nA ia IIC T6 Gc Class 1, Zone 2 Ex nA ia IIC T6 Gc Ta = -40°C to +70°C Type 4X, IP67 ATEX FM14ATEXXXXXX: II 1/3 G Ex nA ia IIC T6 Gc Ta = -15°C to +70°C IP67 IEC – IECEX FMG XXXXXX: Ex nA ia IIC T6 Gc Ta = -15°C to + 70°C IP67
Intrinsically Safe US/Canada: Class I, II, III, Div 1, Group A, B, C, D, E, F, G, T6, Class I, Zone 0 AEx ia IIC T6 Ga Class I, Zone 0 Ex ia IIC T6 Ga Ta = -40°C to + 70°C Type 4X, IP67 ATEX – FM14ATEXXXXXX: II 1 G Ex ia IIC T4 Ga Ta = -40°C to +70°C IP67 IEC – IECEX FMG XXXXXX: Ex ia IIC T6 Ga Ta = -40°C to +70°C IP67	Dust Ignition Proof US/Canada: Class II, III, Division 1, Group E, F and G, T6 Ta = -40°C to +70°C Type 4X, IP67 ATEX – FM14ATEXXXXXX: II 1/2 D Ex ia/tb IIIC T85°C to T450°C Da/Db Ta = -15°C to +70°C IP67 IEC – IECEX FMG XXXXXX: Ex ia tb IIIC T85°C to T450°C Db Ex ia IIIC T85°C to T450°C Da Ta = -15°C to +70°C IP67

The following approval standards are applicable:

FM3600:2011, FM3610:2010, FM3611:2004, FM3615:2006, FM3616:2011, FM3810:2005, ANSI/ISA60079-0:2013, ANSI/ISA 60079-1:2009, ANSI/ISA 60079-11:2013, ANSI/ISA 60079-15:2012, ANSI/ISA 60079-26:2011, NEMA 250:2003, ANSI/IEC 60529:2004, C22.2 No. 0.4:2009, C22.2 No. 0.5:2008, C22.2 No. 30:2007, C22.2 No. 94:2001, C22.2 No. 157:2012, C22.2 No. 213:2012, C22.2 No. 1010.1:2009, CAN/CSA 60079-0:2011, CAN/CSA 60079-1:2011, CAN/CSA 60079-11:2011, CAN/CSA 60079-15:2012, C22.2 No. 60529:2005, EN60079-0:2012, EN60079-1:2007, EN60079-11:2012, EN60079-15:2010, EN60079-26:2007, EN60079-31:2009, EN60529+A1:1991-2000, IEC60079-0:2011, IEC60079-1:2007, IEC60079-11:2011, IEC60079-15:2010, IEC60079-26:2006, IEC60079-31:2008

“This equipment with chargeable non-conductive parts, e.g. enclosure’s paint and antenna use PTFE, Co-polymer Polypropylene or Noryl En265, is provided with a warning label referring to the safety measures that must be taken if there is electrostatic charging during operation. For use in hazardous area, the equipment and side to be installed, e.g. tank, must be connected to earth and be attention to not only the measuring object, e.g. liquids, gases, powders and etc., but also the related conditions, e.g. tank container, vessel and etc. (According to IEC 60079-32-1).”

FCC Compliance Statement:

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

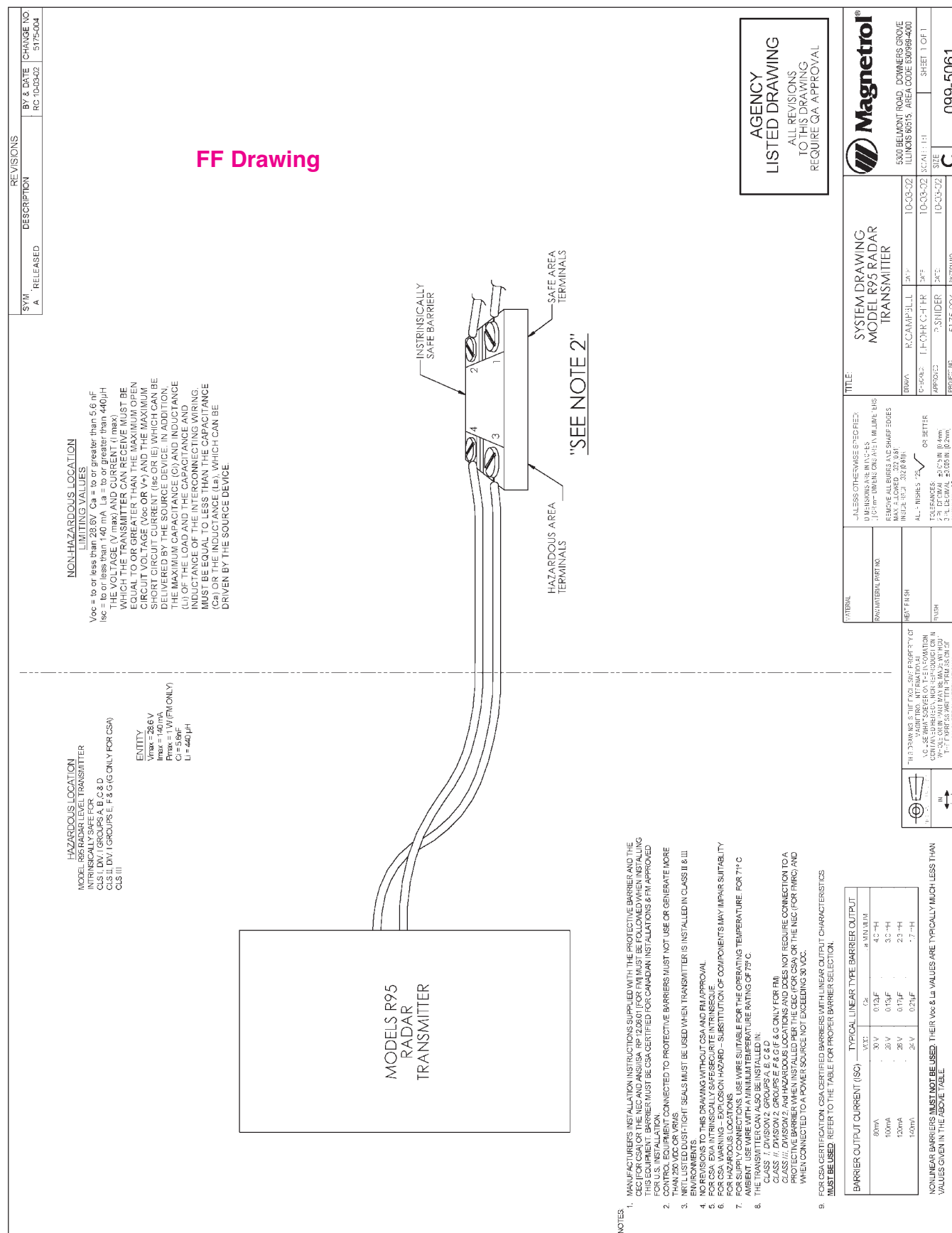
1. This device may not cause in harmful interference, and
2. This device must accept any interference received, including interference that may cause undesired operation.

Changes or modifications not expressly approved by the party responsible for compliance could void the user’s authority to operate the equipment. To comply with FCC/IC RF exposure limits for general population/uncontrolled exposure, the antenna(s) used for this transmitter must be installed to provide a separation distance of at least 20cm from all persons and must not be co-located or operating in conjunction with any other antenna or transmitter.

58-602 Pulsar® Model R96 Radar Transmitter

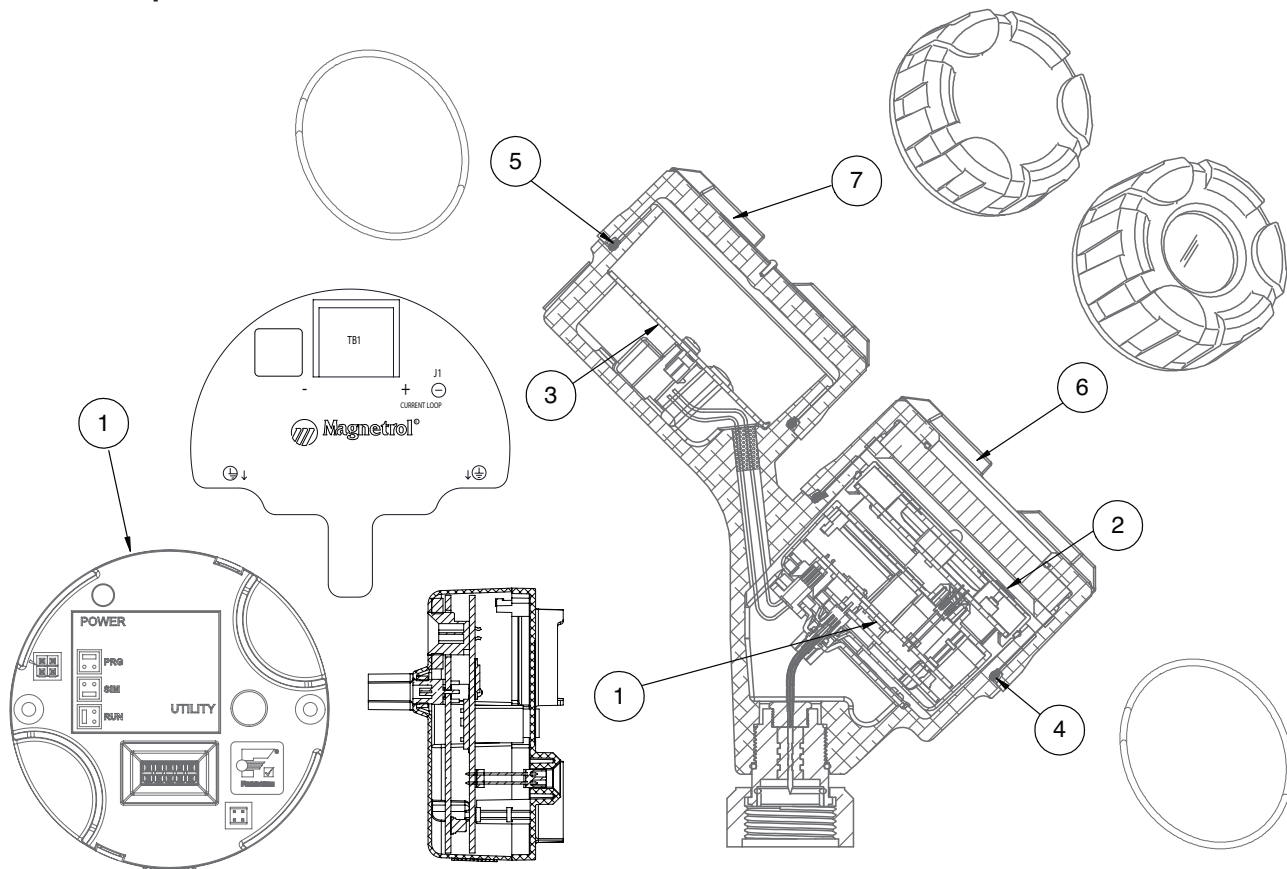


3.5.1 Agency (FM/CSA) Drawing and Entity Parameters



3.6 Parts

3.6.1 Replacement Parts



Electronics:

Digit: 1 2 3 4 5 6 7 8 9 10
Part Number: R 9 6 5
 → X = product with a non-standard customer requirement

Serial Number:

See nameplate, always provide complete part number and serial number when ordering spares.

(1) Electronic Module		
Digit 5	Digit 6	Replacement Part
1	1	Z31-2890-001
2	0	Z31-2890-002

(2) Display Module		
Digit 5	Digit 7	Replacement Part
1 or 2	0, 1 or 2	N/A
	A, B or C	Z31-2850-001

(3) Wiring PC Board		
Digit 5	Digit 6	Replacement Part
1	1	Z30-9165-001
2	0	Z30-9166-001

	Replacement Part
(4) "O"-ring	012-2201-237
(5) "O"-ring	012-2201-237

(6) Housing Cover			
Digit 7	Digit 8	Digit 9	Replacement Part
0, 1 or 2	all	1	004-9225-002
		2	004-9225-003
A, B or C	0, 1 or A	1	036-4413-005
	3		036-4413-001
	B, C or D		036-4413-001
	0, 1, 3 or A	2	036-4413-002
	B, C or D		036-4413-002

(7) Housing Cover	
Digit 9	Replacement Part
1	004-9225-002
2	004-9225-003

3.7 Specifications

3.7.1 Functional – Transmitter

System Design

Measurement Principle	Pulse burst radar 6 GHz
-----------------------	-------------------------

Input

Measured Variable	Level, determined by the time-of-flight of radar pulse reflections
Span	0.5 to 130 feet (0.2 to 40 meters)

Output

Type	4 to 20 mA with HART: 3.8 mA to 20.5 mA useable (per NAMUR NE43)	
	FOUNDATION fieldbus™: H1 (ITK Ver. 6.1.1)	
Range	Analog	.003 mA
	Digital Display	1 mm
Resolution	Analog	0.01 mA
	Digital	0.1"
Loop Resistance	591 ohms @ 24 VDC and 22 mA	
Diagnostic Alarm	Selectable: 3.6 mA, 22 mA (meets requirements of NAMUR NE 43), or HOLD last output	
Diagnostic Indication	Meets requirements of NAMUR NE107	
Damping	Adjustable 0-10	

User Interface

Keypad	4-button menu-driven data entry	
Display	Graphic Liquid Crystal Display	
Digital Communication ①	HART Version 7—with Field Communicator, FOUNDATION fieldbus™, AMS, or FDT DTM (PACTware™), EDDL	
Menu Languages	Transmitter LCD: English, French, German, Spanish, Russian	
	HART DD: English, French, German, Spanish, Russian, Chinese, Portuguese	
	FOUNDATION fieldbus Host System: English	
Power (Measured at instrument terminals)	HART: General Purpose (Weather proof)/Intrinsically Safe/Explosion-proof: 11 VDC minimum under certain conditions (refer to I/O Manual 58-602)	
	FOUNDATION fieldbus™: 9 to 17.5 VDC	
	FISCO FNICO, Explosion Proof, General Purpose and Weather Proof	

Housing

Material	IP67/die cast aluminum A413 (<0.6% copper); optional stainless steel	
Net/Gross Weight	Aluminum:	4.5 lbs. (2.0 kg)
	Stainless Steel:	10.0 lbs. (4.50 kg)
Overall Dimensions	H 8.34" (212 mm) x W 4.03" (102 mm) x D 7.56" (192 mm)	
Cable Entry	½" NPT or M20	
SIL 2 Hardware (Safety Integrity Level)	Safe Failure Fraction = 93% (HART only)	
	Functional Safety to SIL 2 as 1oo1 in accordance with IEC 61508	
	(Full FMEDA report available upon request)	

3.7 Specifications

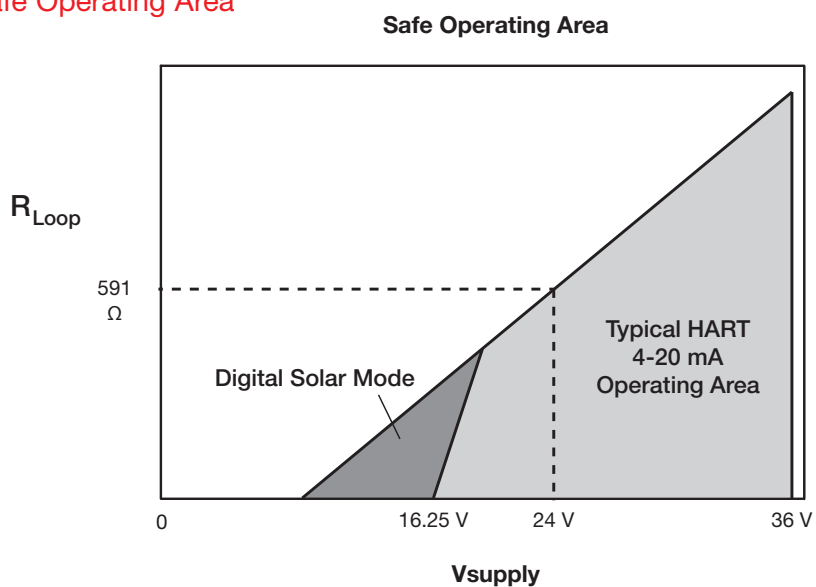
3.7.2 Functional – Environment

Operating Temperature	-40° to +175° F (-40° to +80° C); LCD viewable -5° to +160° F (-20° to +70° C)
Storage Temperature	-50° to +185° F (-45° to +85° C)
Humidity	0–99%, non-condensing
Electromagnetic Compatibility	Meets CE requirement (EN 61326) and NAMUR NE 21
	NOTE: Antennas must be used in metallic vessel or stillwell to maintain CE noise immunity
Surge Protection	Meets CE EN 61326 (1000V)
Shock/Vibration	ANSI/ISA-S71.03 Class SA1 (Shock); ANSI/ISA-S71.03 Class VC2 (Vibration)
Reference Conditions	Reflection from ideal reflector at +70° F (+20° C)
Linearity	±0.3 inch (8 mm) or 0.1% of tank height (whichever is greater)
Measured Error	±0.3 inch (8 mm) or 0.1% of tank height (whichever is greater) (Performance will degrade slightly within 60" (1.5 m) of antenna)
Resolution	0.05 inch (1.2 mm)
Repeatability	±0.2 inch (5 mm) or 0.05% of tank height (whichever is greater)
Response Time	(##'s 0-10 m ##'s 10-20 m #'s 20-30 m)
Initialization Time	< 30 seconds
Ambient Temperature Effect	Temperature effect 0.05% per 10° C
Process Dielectric Effect	< 0.3 inch within selected range
Maximum Rate of Change	180 inches (450 cm)/minute
FOUNDATION™ fieldbus:	
ITK Version	6.1.1
H1 Device Class	Link Master (LAS)—selectable ON/OFF
H1 Profile Class	31PS, 32L
Function Blocks	(6) AI, (2) Transducer, (1) Resource, (1) Arithmetic, (1) Signal Characterizer, (2) PID, (1) Integrator
Quiescent Current	15 mA
Execution Time	15 ms (40 ms PID Block)
Device Revision	01
DD Version	0x01

3.7.3 O-ring (seal) Selection Chart

Material	Code	Maximum Temperature	Maximum Pressure	Min. Temp.	Recommended For Use In	Not Recommended For Use In
Viton® GFLT	0	+400° F @ 232 psig (+200° C @ 16 bar)	750 psig @ +70° F (50 bar @ +20° C)	-40° F (-40° C)	General purpose, steam, ethylene	Ketones (MEK, acetone), skydrol fluids, amines, anhydrous ammonia, low molecular weight esters and ethers, hot hydrofluoric or chlorosulfuric acids, sour HCs
EPDM	1	+250° F @ 200 psig (+125° C @ 14 bar)	750 psig @ +70° F (50 bar @ +20° C)	-60° F (-50° C)	Acetone, MEK, skydrol fluids anhydrous ammonia	Petroleum oils, di-ester base lubricants, propane, steam
Simriz SZ485 (formerly Aegis PF128)	8	+400° F @ 232 psig (+200° C @ 16 bar)	750 psig @ +70° F (50 bar @ +20° C)	-4° F (-20° C)	Inorganic and organic acids (including HF and nitric), aldehydes, ethylene, glycols, organic oils, silicone oils, vinegar, sour HCs, steam, amines, ethylene oxide, propylene oxide	Black liquor, Freon 43, Freon 75, Galden, KEL-F liquid, molten sodium, molten potassium
Kalrez (4079)	2	+400° F @ 232 psig (+200° C @ 16 bar)	750 psig @ +70° F (50 bar @ +20° C)	-40° F (-40° C)	Inorganic and organic acids (including HF and nitric), aldehydes, ethylene, glycols, organic oils, silicone oils, vinegar, sour HCs	Black liquor, hot water/steam, hot aliphatic amines, ethylene oxide, propylene oxide, molten sodium, molten potassium

3.7.2.1 Safe Operating Area



3.7.2.2 Transmitter Terminal Voltage

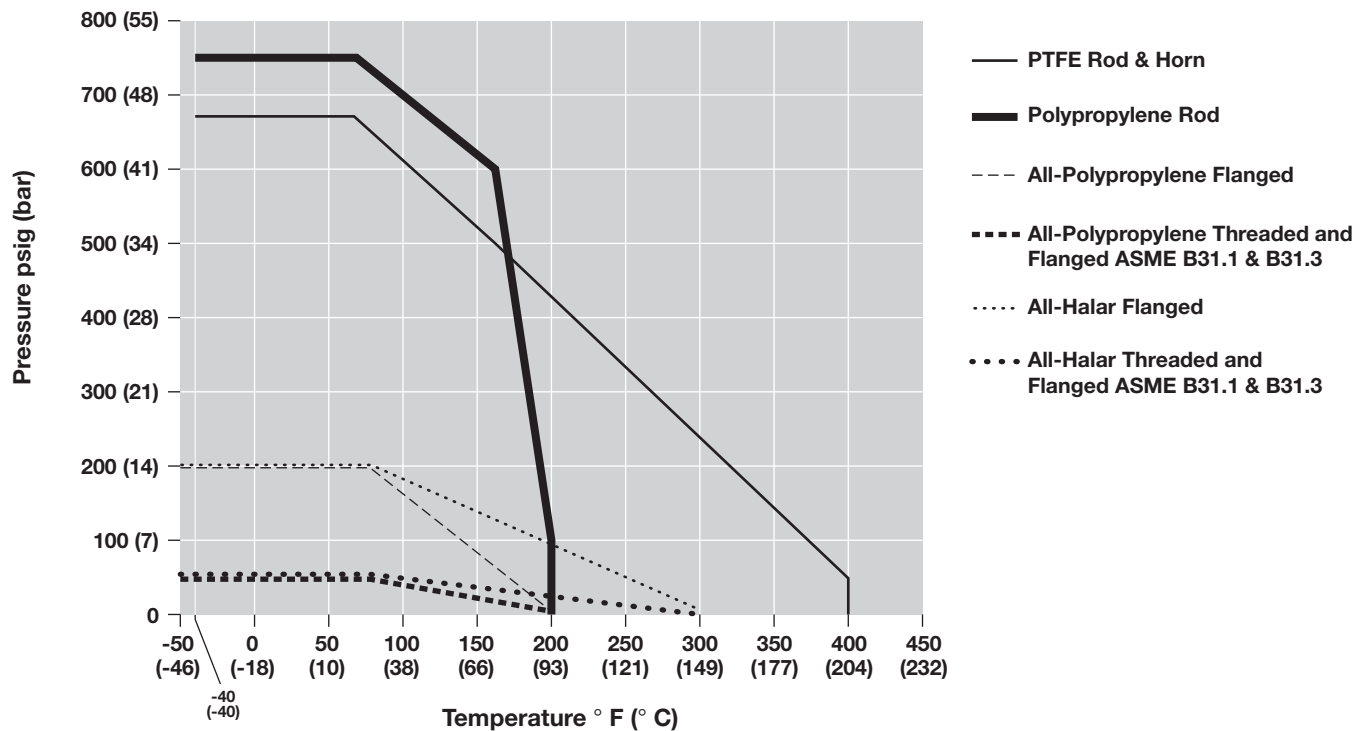
Operational Mode	Current Consumption	Vmin	Vmax
HART			
General Purpose	4mA 20mA	16.25V 11V	36V 36V
Intrinsically Safe	4mA 20mA	16.25V 11V	28.6V 28.6V
Explosion Proof	4mA 20mA	16.25V 11V	36V 36V
Fixed Current-Solar Power Operation (PV transmitter via HART)			
General Purpose	10mA①	11V	36V
Intrinsically Safe	10mA①	11V	28.6V
HART Multi-Drop Mode (Fixed Current)			
Standard	4mA①	16.25V	36V
Intrinsically Safe	4mA①	16.25V	28.6V
FOUNDATION fieldbus™ (Future)			
Supply Voltage	9V to 17.5V	9V to 17.5V	9V to 17.5V

3.7.4 Functional – Antenna

Model	Dielectric Rod TFE	Dielectric Rod ^① Polypropylene	Dielectric Rod All-Halar® Antenna	3", 4", and 6" Horn
Materials	316 SS (Hastelloy® C, Monel® and Kynar® optional), TFE, Viton® O-rings	316 SS, Polypropylene, Viton® O-rings	All-Halar, Viton® O-rings	316 SS (Hastelloy C and Monel optional), TFE, Viton® O-rings
Process Connection	1½" NPT and BSP, ANSI or DIN flanges	1½" NPT and BSP, ANSI or DIN flanges	1½" NPT, BSP, ANSI, or DIN Flanges	6" ANSI or DIN flanges
Maximum Process Temperature	+400° F @ 50 psig (+204° C @ 3.5 bar)	+200° F @ 50 psig (+93° C @ 3.5 bar)	+300° F @ atmos (+150° C @ atmos)	+400° F @ 50 psig (+204° C @ 3.5 bar)
Maximum Process Pressure	-14.7 to 675 psig @ +70° F (-1.0 to 46.5 bar @ +20° C)	-14.7 to 750 psig @ +70° F (-1.0 to 51.7 bar @ +20° C)	-14.7 to 50 psig @ +70° F (-1.0 to 3.5 bar @ +20° C)	-14.7 to 675 psig @ +70° F (-1.0 to 46.5 bar @ +20° C)
Minimum Dielectric (application dependent)	2.0	2.0	2.0	1.4 with stillwells

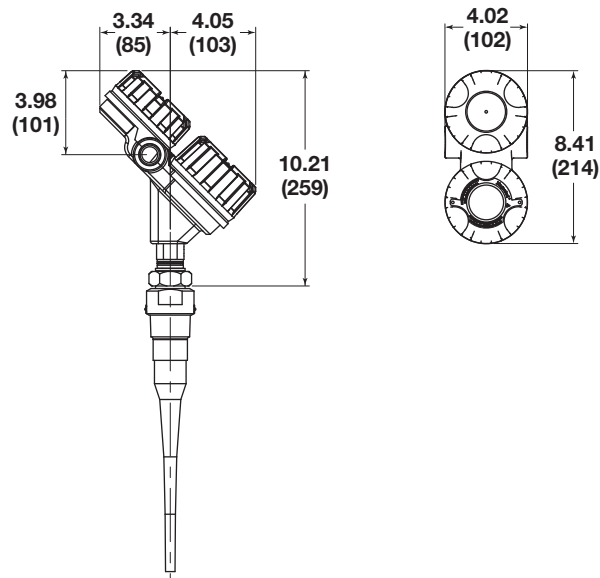
① All-polypropylene construction optional (see chart below for ratings)

3.7.5 PULSAR Model R96 Antenna Pressure / Temperature Ratings

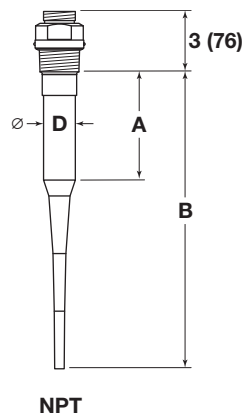


3.7.6 Physical – Inches (mm)

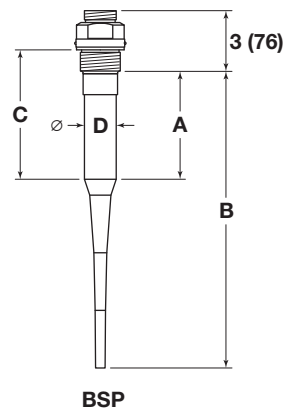
Transmitter



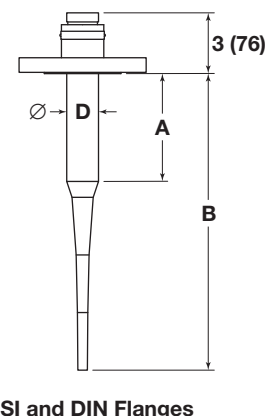
Dielectric Rod



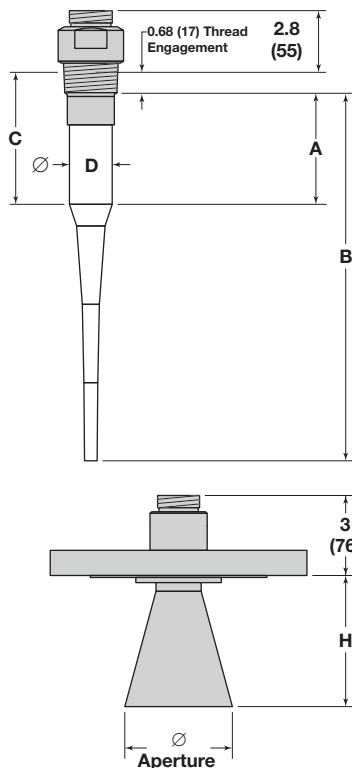
NPT



BSP



ANSI and DIN Flanges



DIELECTRIC RODS

Model #	Antenna Extension (maximum "L" dimension)	All	All	BSP
8th Digit		Dim A	Dim B	Dim C
0	1" (25 mm)	2.3 (58)	11.1 (282)	3.0 (76)
1	4" (100 mm)	5.1 (130)	14.0 (356)	5.9 (150)
2	8" (200 mm)	9.1 (231)	18.0 (457)	9.9 (251)
3	12" (300 mm)	13.1 (333)	22.0 (559)	13.9 (353)

Antenna Extension O.D. Dimension D	
TFE Rod	Ø 1.625 (41)
PP Rod	Ø 1.50 (38)
All-Plastic Rod	Ø 1.625 (41)

HORNS

Model #	Antenna Extension (maximum "L" dimension)	3" Horn	4" Horn	6" Horn
8th Digit		Dim H	Dim H	Dim H
0	1" (25 mm)	2.7 (51)	↓	↓
1	4" (100 mm)	N/A	4.6 (117)	8.3 (211)
2	8" (200 mm)		8.4 (213)	
3	12" (300 mm)		12.4 (315)	
Aperture		2.95" (75 mm)	3.75" (95 mm)	5.75" (146 mm)

3.8 Model Numbers

3.8.1 PULSAR Radar Transmitter

1 | BASIC MODEL NUMBER AND OPERATING FREQUENCY

R96	Through-Air Radar Level Transmitter- 6 GHz Pulse Radar
-----	--

4 | POWER

5	24 VDC, Two-wire
---	------------------

5 | SIGNAL OUTPUT

1	4-20 mA with HART
2	FOUNDATION fieldbus

6 | SAFETY OPTIONS

0	None (FOUNDATION fieldbus only) (5th digit = 2)
1	SIL 2 Hardware - HART only (5th digit = 1)

7 | ACCESSORIES

0	No Digital Display and Keypad
A	Digital Display and Keypad

8 | CLASSIFICATION

0	General Purpose, Weatherproof (IP 67)
1	Intrinsically Safe (FM & CSA CL 1 Div 1, Grps A, B, C, D) (5th digit = 1 or 2)
3	Explosion-proof (FM & CSA CL 1 Div 1, Grps B, C, D)
A	Intrinsically Safe (ATEX/IEC Ex ia IIC T4) (5th digit = 1 or 2)
B	Flame-proof (ATEX/IEC Ex d ia IIC T6) (5th digit = 1 or 2)
C	Non-sparking (ATEX Ex n IIC T6) (5th digit = 1 or 2)

9 | HOUSING/CONDUIT CONNECTION

1	Die-cast Aluminum, Dual-compartment, 45-degree
2	Investment Cast, Stainless Steel, Dual-compartment, 45-degree

10 | CONDUIT CONNECTION

0	½" NPT
1	M20
2	½" NPT with sunshade
3	M20 with sunshade



3.8.2 Radar Antennas – Dielectric Rod

TECHNOLOGY / OPERATING FREQUENCY

R A	PULSAR radar antennas / 6 GHz
-----	-------------------------------

CONFIGURATION / STYLE

A	TFE (Material of Construction codes A, B, C, and K only)
B	Polypropylene (Material of Construction codes A, G, K, and L only)
C	Halar® (Material of Construction codes G and L only)

MATERIAL OF CONSTRUCTION

A	316/316L stainless steel
B	Hastelloy® C
C	Monel®
G	All-Plastic wetted surfaces including flanges (Configuration/Style codes B and C only)
K	316/316L SS; ASME B31.1 and B31.3 (meets CRN specifications)
L	All-Plastic wetted surfaces; ASME B31.1, B31.3 (meets CRN specifications; Configuration/Style codes B and C only)

PROCESS CONNECTION - SIZE/TYPE ①

31	1½" NPT thread	32	1½" BSP (G 1½) thread
43	2" 150# ANSI raised face flange	DA	DN 50, PN 16 DIN 2527 Form B
44	2" 300# ANSI raised face flange	DB	DN 50, PN 25/40 DIN 2527 Form B
45	2" 600# ANSI raised face flange	DD	DN 50, PN 64 DIN 2527 Form E
53	3" 150# ANSI raised face flange	EA	DN 80, PN 16 DIN 2527 Form B
54	3" 300# ANSI raised face flange	EB	DN 80, PN 25/40 DIN 2527 Form B
55	3" 600# ANSI raised face flange	ED	DN 80, PN 64 DIN 2527 Form E
63	4" 150# ANSI raised face flange	FA	DN 100, PN 16 DIN 2527 Form B
64	4" 300# ANSI raised face flange	FB	DN 100, PN 25/40 DIN 2527 Form B
65	4" 600# ANSI raised face flange	FD	DN 100, PN 64 DIN 2527 Form E
73	6" 150# ANSI raised face flange	GA	DN 150, PN 16 DIN 2527 Form B
74	6" 300# ANSI raised face flange	GB	DN 150, PN 25/40 DIN 2527 Form B
75	6" 600# ANSI raised face flange	GD	DN 150, PN 64 DIN 2527 Form E

HYGIENIC PROCESS CONNECTIONS

4P	2" Triclover® type, 16 AMP	6P	4" Triclover type, 16 AMP
5P	3" Triclover type, 16 AMP	7P	6" Triclover type, 16 AMP

① Metal flanges welded to antenna; Plastic flanges and metal flanges with threaded antenna connection ordered separately. Refer to Optional Flanges chart on page 59.

O-RINGS ②

0	Viton® GFLT
1	EPDM
2	Kalrez 4079
8	Simriz SZ485 (formerly Aegis PF128)

② All-Polypropylene and All-Halar antennas (Materials of Construction Codes G and L) use Viton® GFLT O-rings

ANTENNA EXTENSION

0	For nozzle height ≤ 1" (25 mm) (For threaded process connection only)
1	For nozzle height ≤ 4" (100 mm)
2	For nozzle height ≤ 8" (200 mm) (ESP designation for TFE rod only)
3	For nozzle height ≤ 12" (300 mm)

R	A							0	0
---	---	--	--	--	--	--	--	---	---

3.8.3 Radar Antennas – Horn

TECHNOLOGY / OPERATING FREQUENCY

R A	PULSAR radar antennas / 6 GHz
-----	-------------------------------

CONFIGURATION / STYLE

3	3" horn (for Standpipe/Stillwell use only; Materials of Construction codes A & K only)
4	4" horn
6	6" horn

MATERIAL OF CONSTRUCTION

A	316/316L stainless steel
B	Hastelloy C
K	316/316L SS; ASME B31.1 and ASME B31.3 (meets CRN specifications)

PROCESS CONNECTION - SIZE/TYPE (metal flanges welded to antenna)

53	3" 150# ANSI raised face flange	EA	DN 80, PN 16	DIN 2527 Form B
54	3" 300# ANSI raised face flange	EB	DN 80, PN 25/40	DIN 2527 Form B
55	3" 600# ANSI raised face flange	ED	DN 80, PN 64	DIN 2527 Form E
63	4" 150# ANSI raised face flange	FA	DN 100, PN 16	DIN 2527 Form B
64	4" 300# ANSI raised face flange	FB	DN 100, PN 25/40	DIN 2527 Form B
65	4" 600# ANSI raised face flange	FD	DN 100, PN 64	DIN 2527 Form E
73	6" 150# ANSI raised face flange	GA	DN 150, PN 16	DIN 2527 Form B
74	6" 300# ANSI raised face flange	GB	DN 150, PN 25/40	DIN 2527 Form B
75	6" 600# ANSI raised face flange	GD	DN 150, PN 64	DIN 2527 Form E

HYGIENIC PROCESS CONNECTIONS

6P	4" Tri-Clover type, 16 AMP Hygienic Flange
7P	6" Tri-Clover type, 16 AMP Hygienic Flange

O-RINGS

0	Viton® GFLT
1	EPDM
2	Kalrez® 4079
8	Simriz SZ485 (formerly Aegis PF128)

ANTENNA EXTENSION

0	For nozzle height ≤ 1" (25 mm) (For threaded process connection only)
1	For nozzle height ≤ 4" (100 mm)
2	For nozzle height ≤ 8" (200 mm) (ESP designation for TFE rod only)
3	For nozzle height ≤ 12" (300 mm)



R	A									0	0
---	---	--	--	--	--	--	--	--	--	---	---

OPTIONAL FLANGES (for use with Antenna Extension Codes 1–3 only)

Part Number:	2"		3"		4"		6"	
04-6852	150#	300#	150#	300#	150#	300#	150#	300#
316L Stainless Steel	-001	-005	-002	-006	-003	-007	-004	-008
304L Stainless Steel	-009	-013	-010	-014	-011	-015	-012	-016
Carbon Steel	-017	-021	-018	-022	-019	-023	-020	-024
Hastelloy C	-025	-029	-026	-030	-027	-031	-028	-032
Monel	-033	-037	-034	-038	-035	-039	-036	-040

Part Number:	2"		3"		4"		6"	
04-6852	150#	300#	150#	300#	150#	300#	150#	300#
Kynar	-041	-045	-042	-046	-043	-047	-044	-048
PVC	-049	-053	-050	-054	-051	-055	-052	-056
Polypropylene	-057	-061	-058	-062	-059	-063	-060	-064
TFE	-065	-069	-066	-070	-067	-071	-068	-072

4.0 Advanced Configuration/ Troubleshooting Techniques

This section contains information regarding some of the advanced configuration and troubleshooting capability contained within the Model R96 transmitter. These diagnostic options are best suited for use with PACTware and the Model R96 DTM, and should be implemented only after contacting Magnetrol Technical Support.

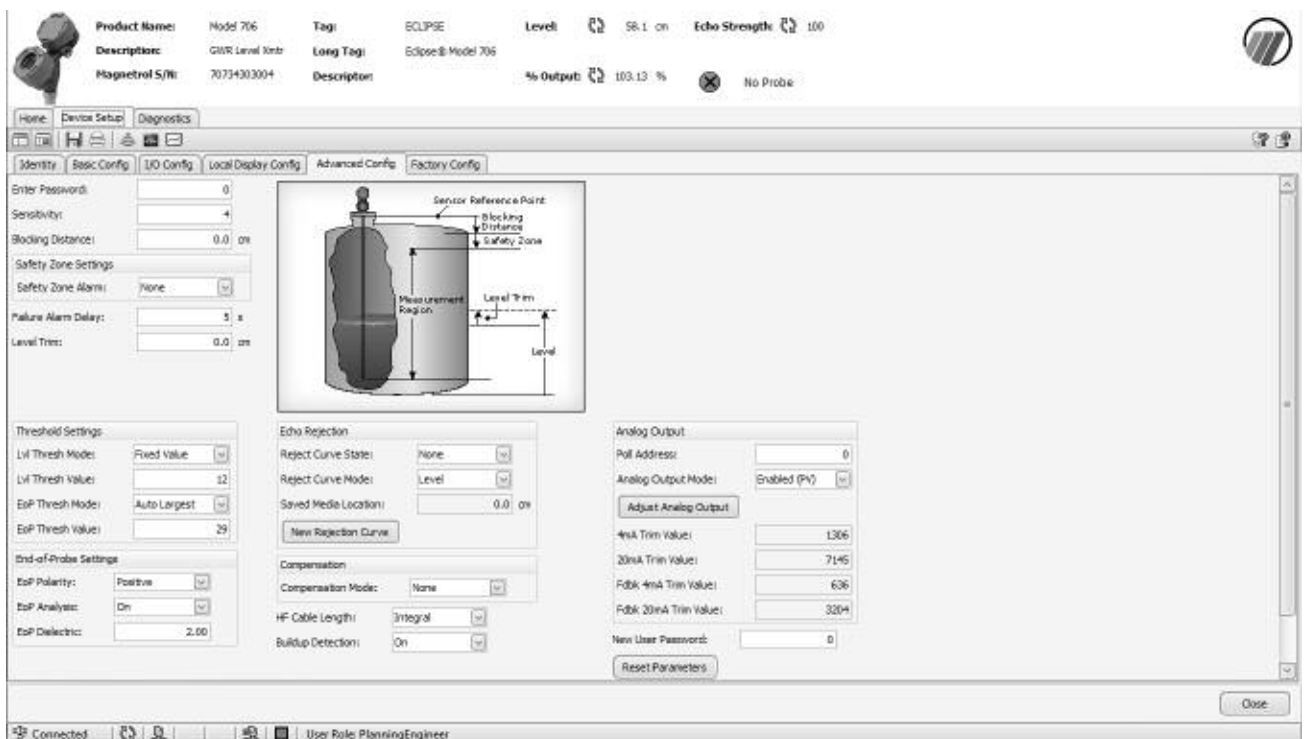
4.1 End-of-Probe Analysis (EOPA)

Please note that due to the operation of this method, End of Probe Analysis cannot be applied with interface measurement, applications with a "water" bottoms, or with stratifying liquids. Therefore, EOPA will not be available when Measurement Type = Interface & Level.

When EOPA is enabled and the calculated (inferred level) is being used, a diagnostic warning shown as "Inferred Level" will be present.

4.1.1 Enable EOPA using PACTware

Click on the Device Setup tab, and then select Advanced Config. In the lower left corner select the correct Polarity for the End of Probe pulse, then turn on the EoP Analysis. The Eop Dielectric box will then appear. Fill in the correct Dielectric of the process medium being measured.



4.1.2 Enable EOPA using keypad/LCD

From the MAIN MENU, select DEVICE SETUP and press Enter.



Scroll down to Advanced Config, and then press Enter.



Scroll down to END of PROBE ANALYSIS, and then press Enter.



Enter the correct polarity for EoP Polarity, turn on EoP Analysis, and then enter the correct value for EoP Dielectric. EoP Dielectric is the dielectric constant of the process medium being measured.



4.2 Sloped Threshold

The Sloped Threshold option contained in the Model R96 allows the user additional level detection capability by allowing the threshold to be sloped (bent) around an unwanted signal. The result is a convenient way to ignore undesired signals.

The use of PACTware and the Model R96 DTM is recommended for this option.

Using PACTware, click on the Device Setup tab, and then select Advanced Config.

In the Threshold Settings section, select “Sloped” within in the Lvl Tresh Mode dropdown box.

Then set the Sloped Start Value, Lvl Tresh Value, and Sloped End Distance.



Product Name: Model 706
Description: GWR Level Xmt
Magnetrol S/N: 70734303004

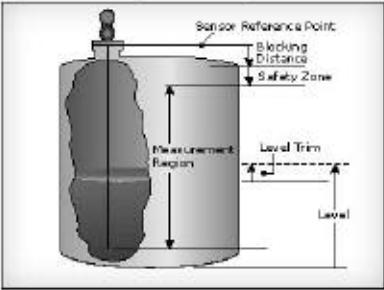
Tag: ECLIPSE
Long Tag: Eclipse® Model 706
Descriptor:

Level: 0.0 cm
Echo Strength: 34
% Output: 0.00 %
Dry Probe

Home | Device Setup | Diagnostics

Identity | Basic Config | I/O Config | Local Display Config | **Advanced Config** | Factory Config

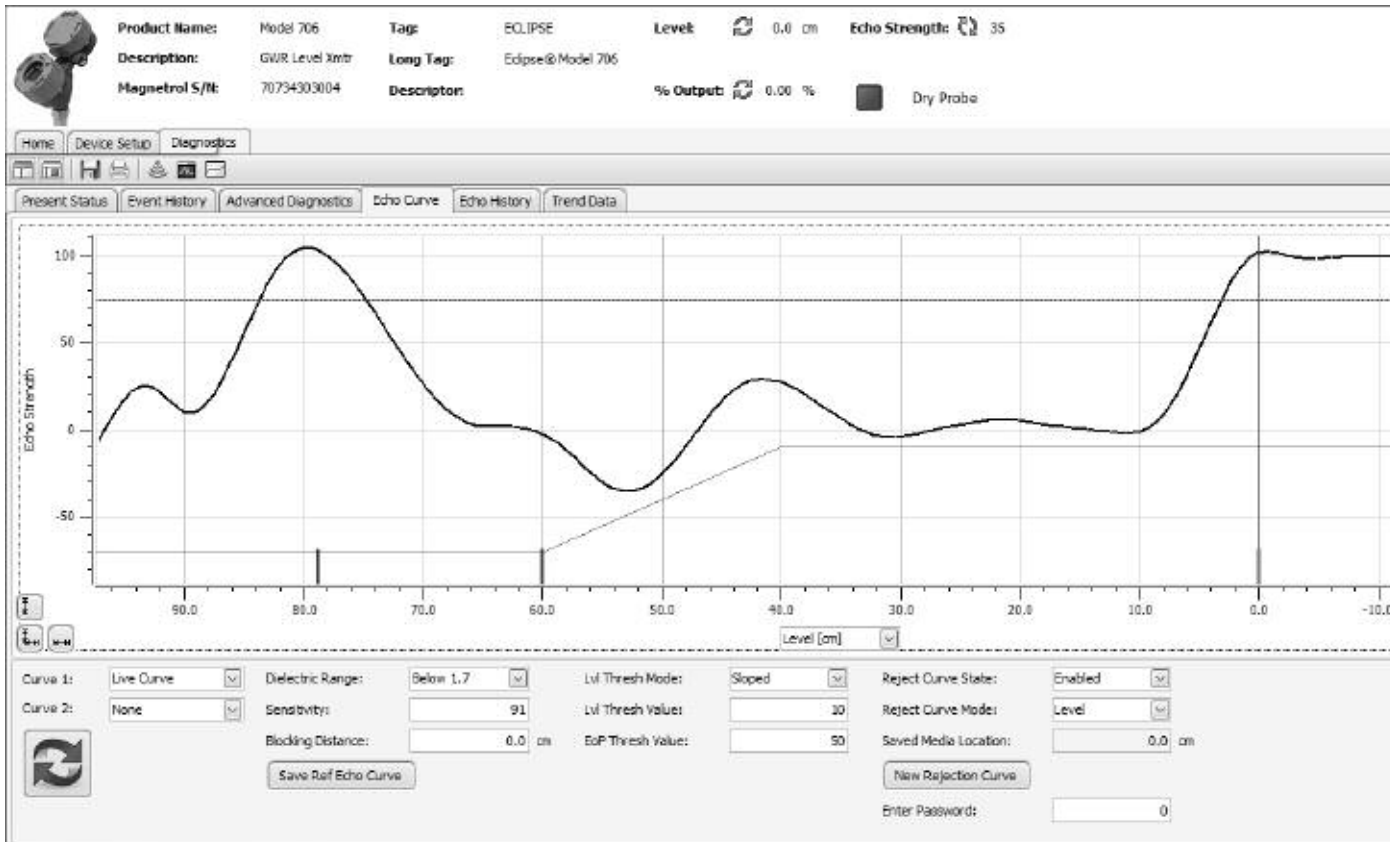
Enter Passwords:
Sensitivity:
Blocking Distance: cm
Safety Zone Settings
Safety Zone Alarm:
Failure Alarm Delay: s
Level Trim: cm



Threshold Settings
Lvl Thresh Mode:
Sloped Start Value:
Lvl Thresh Value:
Sloped End Distance: cm
EoP Thresh Mode:
EoP Thresh Value:
End-of-Probe Settings
EoP Polarity:
EoP Analysis:

Echo Rejection
Reject Curve State:
Reject Curve Mode:
Saved Media Location: cm
New Rejection Curve
Compensation
Compensation Mode:
HF Cable Length:
Buildup Detections:

Analog Output
Poll Address:
Analog Output Mode:
Adjust Analog Output
4mA Trim Value:
20mA Trim Value:
Fdbk 4mA Trim Value:
Fdbk 20mA Trim Value:
New User Password:
Reset Parameters

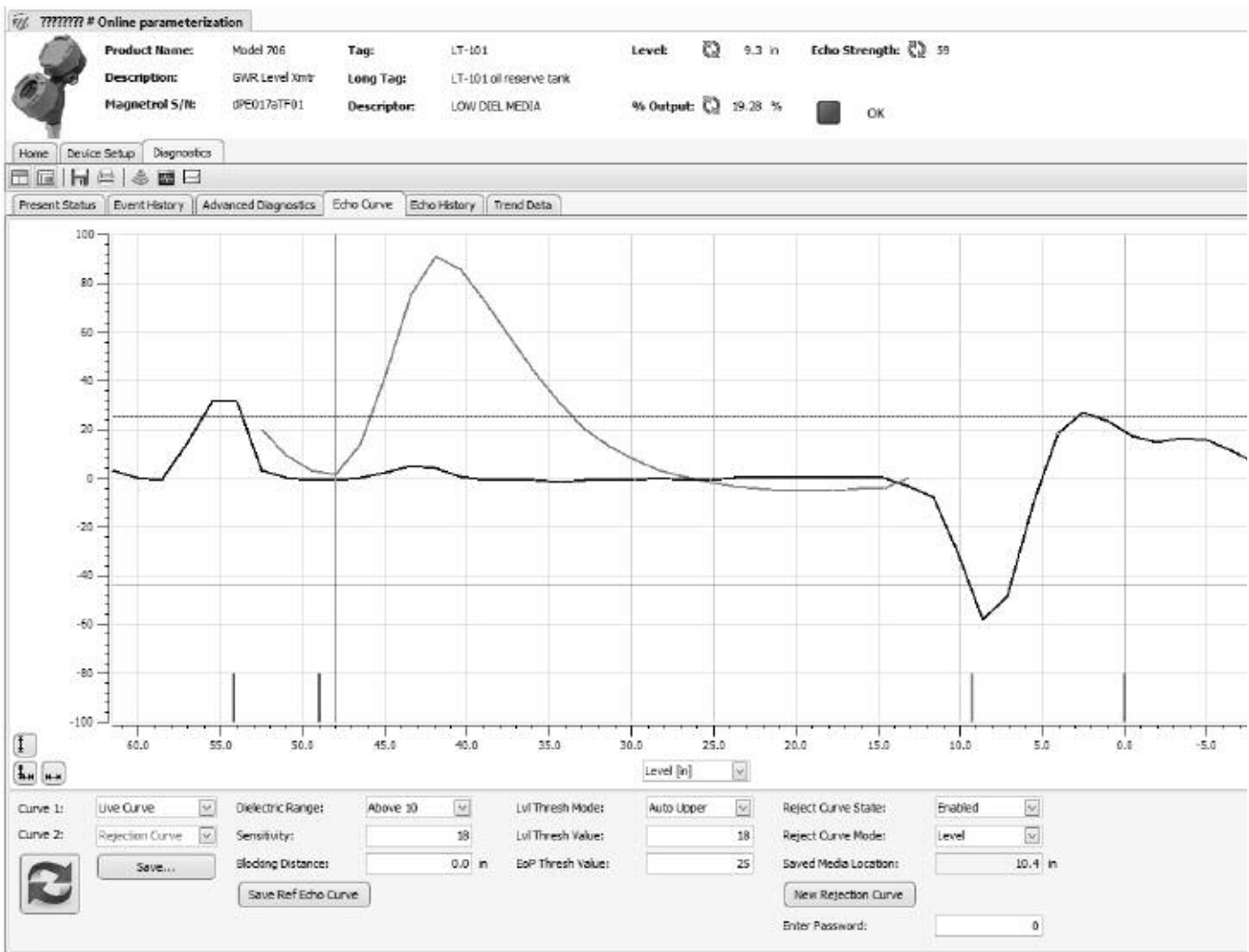


4.3 Echo Rejection

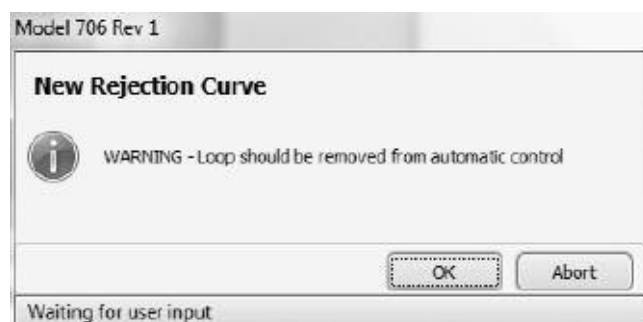
Another way to ignore unwanted signals along the length of the probe is by utilizing the Echo Rejection feature.

Setup using PACTware

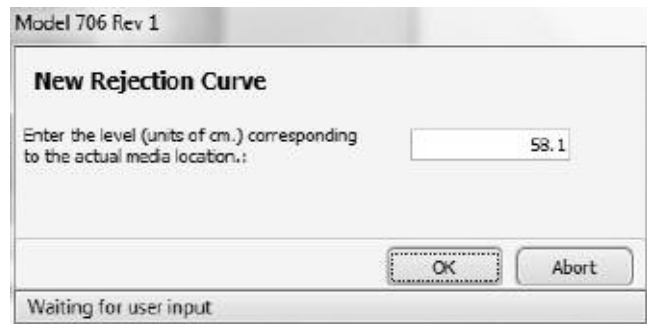
Select the Diagnostics tab and then the Echo Curve tab.
Then click on New Rejection Curve



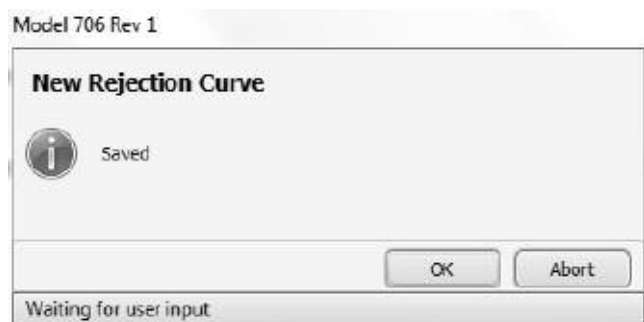
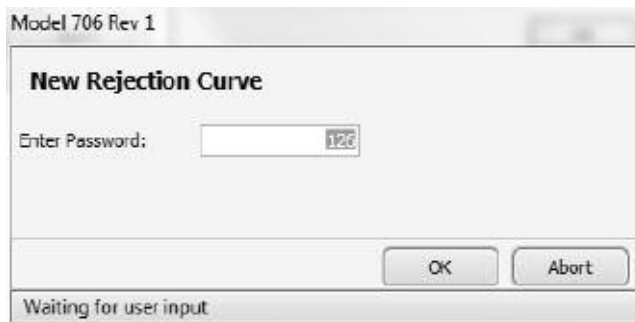
Click on OK at the loop warning message.



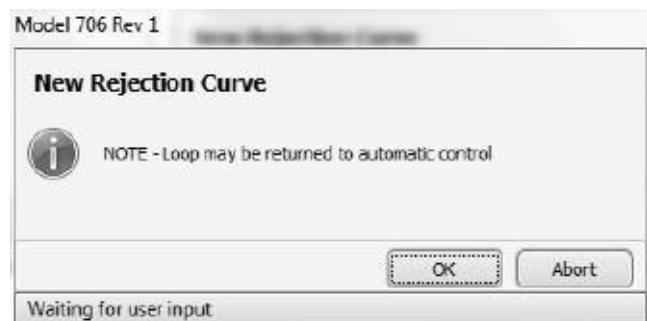
On the next screen, please enter the actual process media location and then hit OK.



A password window will then appear (unless the password was previously entered). Enter the password and hit OK. Then the system calculates the curve, and then saves it. Hit OK to confirm.



A warning screen is then shown so that the loop can be returned to automatic control.



At this point the echo rejection curve can be viewed by selecting Rejection Curve as Curve 2 in the lower left corner of the screen. The Rejection curve will then be displayed in red as shown in the screenshot above.

Alternatively, you can follow the procedure below:

Select the Device Setup tab, and then select the Advanced Config tab. Then click on New Rejection Curve.

Product Name: Model 706 **Tag:** ECLIPSE **Level:** 0.0 cm **Echo Strength:** 0
Description: GWR Level Xmitr **Long Tag:** Eclipse Model 706
Magnetrol S/N: 70734303004 **Descriptor:** **% Output:** 0.00 % **Dry Probe**

Home Device Setup Diagnostics

Identity Basic Config I/O Config Local Display Config Advanced Config Factory Config

Enter Password: 0

Sensitivity: 4

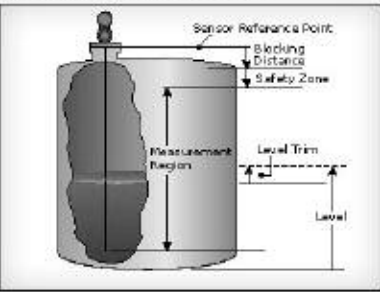
Blocking Distance: 0.0 cm

Safety Zone Settings

Safety Zone Alarm: None

Failure Alarm Delay: 5 s

Level Trim: 0.0 cm



Threshold Settings

Lvl Thresh Mode: Fixed Value

Lvl Thresh Value: 12

EoP Thresh Mode: Auto Largest

EoP Thresh Value: 29

End-of-Probe Settings

EoP Polarity: Positive

EoP Analysis: Off

Echo Rejection

Reject Curve State: Enabled

Reject Curve Mode: Distance

Saved Media Location: 60.0 cm

New Rejection Curve

Compensation

Compensation Mode: None

HF Cable Length: Integral

Buildup Detection: On

Analog Output

Poll Address: 0

Analog Output Mode: Enabled (PV)

Adjust Analog Output

4mA Trim Value: 1306

20mA Trim Value: 7245

Fdbk 4mA Trim Value: 636

Fdbk 20mA Trim Value: 3204

New User Password: 0

Reset Parameters

You will get a warning regarding the loop, hit OK. On the next screen you need to enter the actual media location and then hit OK.

Model 706 Rev 1

New Rejection Curve

 WARNING - Loop should be removed from automatic control

OK Abort

Waiting for user input

Model 706 Rev 1

New Rejection Curve

Enter the level (units of cm.) corresponding to the actual media location.: 58.1

OK Abort

Waiting for user input

Next a password window might appear if not already entered. Then the system calculates the curve, and then saves it. Hit OK to confirm.

Model 706 Rev 1

New Rejection Curve

Enter Password: 123

OK Abort

Waiting for user input

Model 706 Rev 1

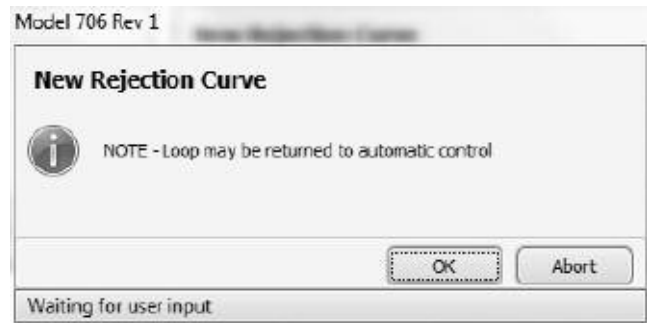
New Rejection Curve

 Saved

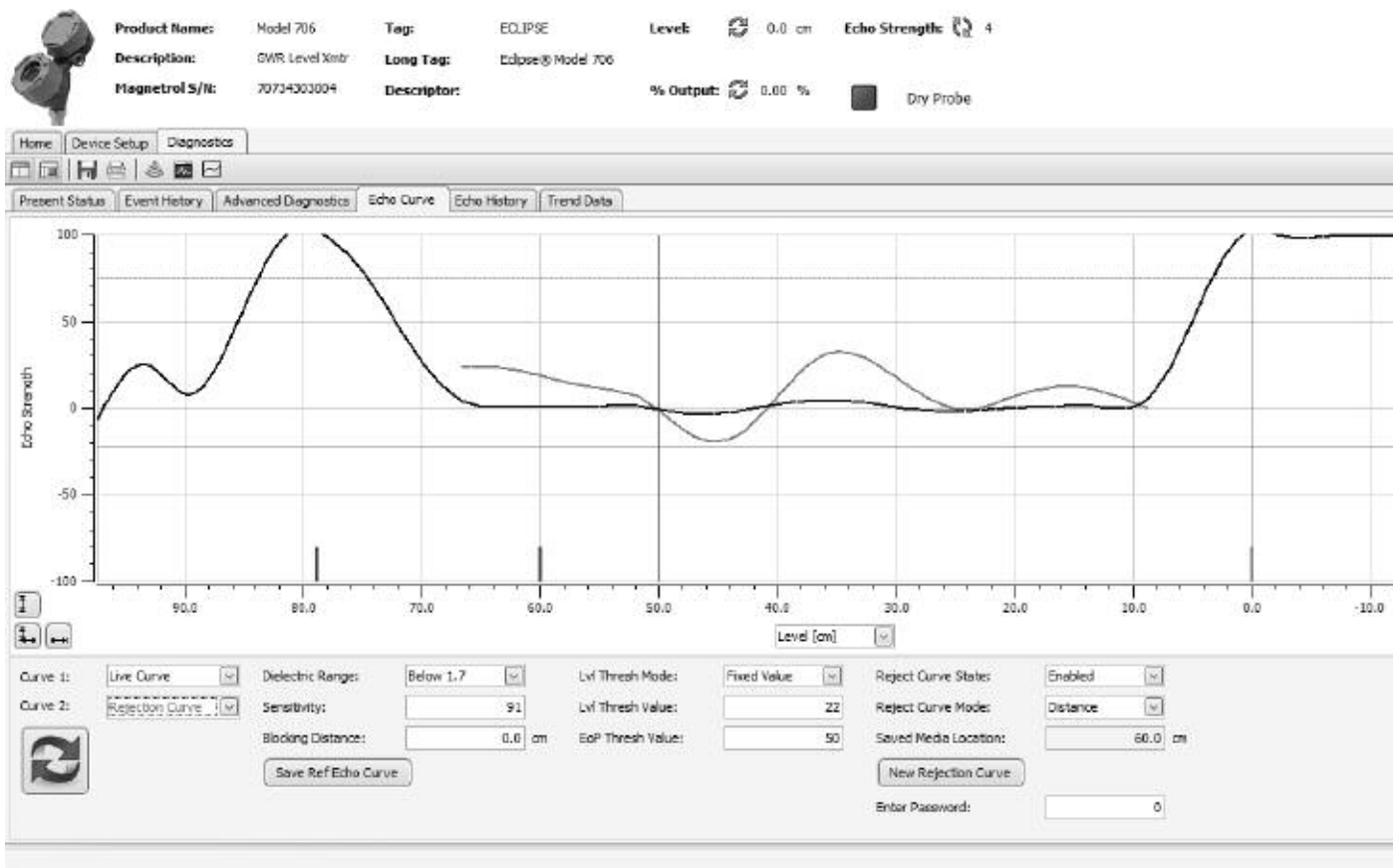
OK Abort

Waiting for user input

A warning screen is shown that the loop can be returned to automatic control.



At this point the echo rejection curve can be viewed by selecting Rejection Curve as Curve 2 in the lower left corner of the Echo Curve screen. The Rejection curve will then be displayed in red as shown in the screenshot below.



4.4 Buildup Detection

A unique feature contained within the Model R96 can be used to obtain an indication of build-up along the length of the probe. This can be set as the HART SV or TV which can be monitored in the control room. An algorithm compares the buildup echo strength as compared to the Lvl Thrsh Value, and outputs value in percent.

4.4.1 Buildup Detection Setup using PACTware

Buildup detection is a feature that needs to be turned on in Advanced Config, see below.

Product Name: Model 706 **Tag:** ECLIPSE **Level:** 0.0 cm **Echo Strength:** 1

Description: GWR Level Xmit **Long Tag:** Eclipse Model 706 **% Output:** 0.00 % **Dry Probe**

Magnetrol S/N: 70734303004 **Descriptor:**

Home **Device Setup** **Diagnostics**

Identity **Basic Config** **I/O Config** **Local Display Config** **Advanced Config** **Factory Config**

Enter Password: 0

Sensitivity: 01

Blocking Distance: 0.0 cm

Safety Zone Settings

Safety Zone Alarm: None

Failure Alarm Delay: 5 s

Level Trim: 0.0 cm

Threshold Settings

Lvl Thrsh Mode: Fixed Value

Lvl Thrsh Value: 22

LoP Thrsh Mode: Auto Largest

LoP Thrsh Value: 50

End-of-Probe Settings

LoP Polarity: Positive

LoP Analysis: Off

Echo Rejection

Reject Curve State: Enabled

Reject Curve Mode: Level

Saved Media Locations: 0.0 cm

New Rejection Curve

Compensation

Compensation Mode: None

HF Cable Length: Integral

Buildup Detection: On

Analog Output

Poll Address: 0

Analog Output Mode: Enabled (PU)

Adjust Analog Output

4mA Trim Value: 1306

20mA Trim Value: 7145

Fdbk 4mA Trim Value: 636

Fdbk 20mA Trim Value: 3204

New User Password: 0

Reset Parameters

Diagram: A cross-sectional diagram of a tank with a radar probe at the top. Labels include: Sensor Reference Point, Blocking Distance, Safety Zone, Measurement Region, Level Trim, and Level.

Once turned on progress can be checked in the Advanced Diagnostics screen, see below.

Product Name: Model 706 **Tag:** ECLIPSE **Level:** 0.0 cm **Echo Strength:** 1

Description: GWR Level Xmit **Long Tag:** Eclipse Model 706 **% Output:** 0.00 % **Dry Probe**

Magnetrol S/N: 70734303004 **Descriptor:**

Home **Device Setup** **Diagnostics**

Present Status **Event History** **Advanced Diagnostics** **Echo Curve** **Echo History** **Trend Data**

Internal Values

Fiducial Ticks: 1371

Fiducial Strength: 38

Level Ticks: 0

Echo Strength: 1

Distance: 60.0 cm

LoP Ticks: 893

LoP Strength: 100

LoP Distance: 55.8 cm

Fdbk Current: 4.031 mA

Elec Temperatures

Present Temperature: 23 °C

Max Temperature: 26 °C

Min Temperature: 15 °C

Reset Max/Min Temps

Transmitter Tests

Analog Output Test

Probe Buildup

Percent of Level Threshold: 6 %

Buildup Location: 62.8 cm

Buildup Rate: 0 %/month

Check

4.4.2 Buildup Detection Setup using the Keypad

From the menu select DEVICE SETUP and hit Enter.



Scroll down to Buildup Detection and hit Enter



Select On and hit Enter



Checking buildup can be done from the main display screen. First the unit must be set up to display the Buildup percentage. Go to the main menu and select DEVICE SETUP then hit Enter.



Scroll down to DISPLAY CONFIG and hit Enter.



Scroll down to Probe Buildup and hit Enter, then select View. From the main screen the Buildup percentage is now shown.



Service Policy

Owners of MAGNETROL may request the return of a control or any part of a control for complete rebuilding or replacement. They will be rebuilt or replaced promptly. Controls returned under our service policy must be returned by Prepaid transportation. MAGNETROL will repair or replace the control at no cost to the purchaser (or owner) other than transportation if:

1. Returned within the warranty period; and
2. The factory inspection finds the cause of the claim to be covered under the warranty.

If the trouble is the result of conditions beyond our control; or, is NOT covered by the warranty, there will be charges for labor and the parts required to rebuild or replace the equipment.

In some cases it may be expedient to ship replacement parts; or, in extreme cases a complete new control, to replace the original equipment before it is returned. If this is desired, notify the factory of both the model and serial numbers of the control to be replaced. In such cases, credit for the materials returned will be determined on the basis of the applicability of our warranty.

No claims for misapplication, labor, direct or consequential damage will be allowed.

Return Material Procedure

So that we may efficiently process any materials that are returned, it is essential that a "Return Material Authorization" (RMA) number be obtained from the factory, prior to the material's return. This is available through a MAGNETROL local representative or by contacting the factory. Please supply the following information:

1. Company Name
2. Description of Material
3. Serial Number
4. Reason for Return
5. Application

Any unit that was used in a process must be properly cleaned in accordance with OSHA standards, before it is returned to the factory.

A Material Safety Data Sheet (MSDS) must accompany material that was used in any media.

All shipments returned to the factory must be by prepaid transportation.

All replacements will be shipped F.O.B. factory.

PULSAR Pulse Burst Radar transmitters may be protected by one or more of the following U.S. Patent Nos.:
US 6,062,095; US 6,980,174; US 7,102,584; US 7,106,248; US 7,271,646



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