



FCC SAR Compliance Test Report

Project Name: DECT Handset

Model : FH28, HSF285

FCC ID : QISFH28

Report No. : SYBH(Z-SAR) 032042013-2

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※ ※ Modified History ※ ※

REV.	DESCRIPTION	ISSUED DATE	REMARK
Rev.1.0	Initial Test Report Release	2013-05-24	Gongzhong
Rev.1.1	Update the KDB 450824D02 to revision 01 on page 7	2013-06-20	Gongzhong

1 General Information

1.1 Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for FH28, HSF285 are as below Table 1.

Band	Position	MAX Reported SAR _{1g} (W/kg)
DECT 2.4G	Left Hand Touched	0.101

Table 1:Summary of test result

The device is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits of 1.6 W/Kg as averaged over any 1 g tissue according to the FCC rule §2.1093, the ANSI/IEEE C95.1:1992, the NCRP Report Number 86 for uncontrolled environment, according to the Industry Canada Radio Standards Specification RSS-102 for General Population/Uncontrolled exposure, and had been tested in accordance with the measurement methods and procedures specified in IEEE Std 1528-2003 & IEEE Std 1528a-2005 and FCC OET Bulletin 65 Supplement C Edition 01-01.

1.2 RF exposure limits

Human Exposure	Uncontrolled Environment General Population	Controlled Environment Occupational
Spatial Peak SAR* (Brain/Body/Arms/Legs)	1.60 mW/g	8.00 mW/g
Spatial Average SAR** (Whole Body)	0.08 mW/g	0.40 mW/g
Spatial Peak SAR*** (Hands/Feet/Ankle/Wrist)	4.00 mW/g	20.00 mW/g

Table 2: RF exposure limits

The limit applied in this test report is shown in **bold** letters

Notes:

- * The Spatial Peak value of the SAR averaged over any 1 gram of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.
- ** The Spatial Average value of the SAR averaged over the whole body.
- *** The Spatial Peak value of the SAR averaged over any 10 grams of tissue (defined as a tissue volume in the shape of a cube) and over the appropriate averaging time.

Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Controlled Environments are defined as locations where there is exposure that may be incurred by persons who are aware of the potential for exposure, (i.e. as a result of employment or occupation.

1.3 EUT Description

Device Information:			
DUT Name:	DECT Handset		
Type Identification:	FH28, HSF285		
FCC ID:	QISFH28		
SN No.:	V4V01A9340100253		
Device Type :	portable device		
Device Phase:	Identical Prototype		
Sample Dimension:	160mmx47mmx25mm		
Exposure Category:	uncontrolled environment / general population		
Hardware Version :	WL1F285H		
Software Version :	V100R001		
Antenna Type :	internal antenna		
Others Accessories	Headset		
Device Operating Configurations:			
Supporting Mode(s)	DECT 2.4G (tested)		
Test Modulation	GFSK		
Operating Frequency Range(s)	Band	Tx (MHz)	Rx (MHz)
	DECT 2.4G	2400-2483.5	2400-2483.5
Test Channels (low-mid-high) :	0-46-94 (DECT 2.4G)		

Table 3:Device information and operating configuration

1.3.1 General Description

DECT Handset FH28/ HSF285 is a DECT signal receives equipment in the DECT system. The DECT frequency band is 2.4G including 2400MHz to 2483.5MHz. FH28/ HSF285 implements such functions as RF signal receiving/sending, keyboard, voice, display and etc.

Battery

Manufacture	Serials number	Description
HUAWEI Technologies Co.LTD.(GY&BYD&GRP)	1#: GRP13010801633 2#: BYD13011703204 3#: HGY13010500202	Battery Model: HNBAAA6-21 Rated capacity: 600mAh Nominal Voltage:  2.4V Charging Voltage:  2.8V

1.4 Test specification(s)

ANSI Std C95.1-1992	Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz – 300 GHz.(IEEE Std C95.1-1991)
IEEE Std 1528-2003	Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques
IEEE Std 1528a-2005	IEEE Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques Amendment 1: CAD File for Human Head Model (SAM Phantom)
OET Bulletin No. 65, Supplement C Edition 01-01– 2001	Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields---Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions
RSS-102	Radio Frequency Exposure Compliance of Radiocommunication Apparatus (All Frequency Bands (Issue 4 of March 2010)
KDB447498 D01	General RF Exposure Guidance v05
KDB865664 D01	SAR measurement 100 MHz to 6 GHz v01
KDB865664 D02	SAR Reporting v01
KDB450824 D01	SAR Probe Calibration and System Verification v01
KDB450824 D02	Dipole SAR Validation Verification v01r01

1.5 Testing laboratory

Test Site	The Reliability Laboratory of Huawei Technologies Co., Ltd.
Test Location	Zone K3,Huawei Industrial Base, Bantian Industry Area, Longgang District, Shenzhen, Guangdong, China
Telephone	+86 755 28780808
Fax	+86 755 89652518
State of accreditation	The Test laboratory (area of testing) is accredited according to ISO/IEC 17025. CNAS Registration number: L0310 A2LA TESTING CERT #2174.01

1.6 Applicant and Manufacturer

Company Name	HUAWEI TECHNOLOGIES CO., LTD
Address	Administration Building, Headquarters of Huawei Technologies Co., Ltd., Bantian, Longgang District, Shenzhen, 518129, P.R.C

1.7 Application details

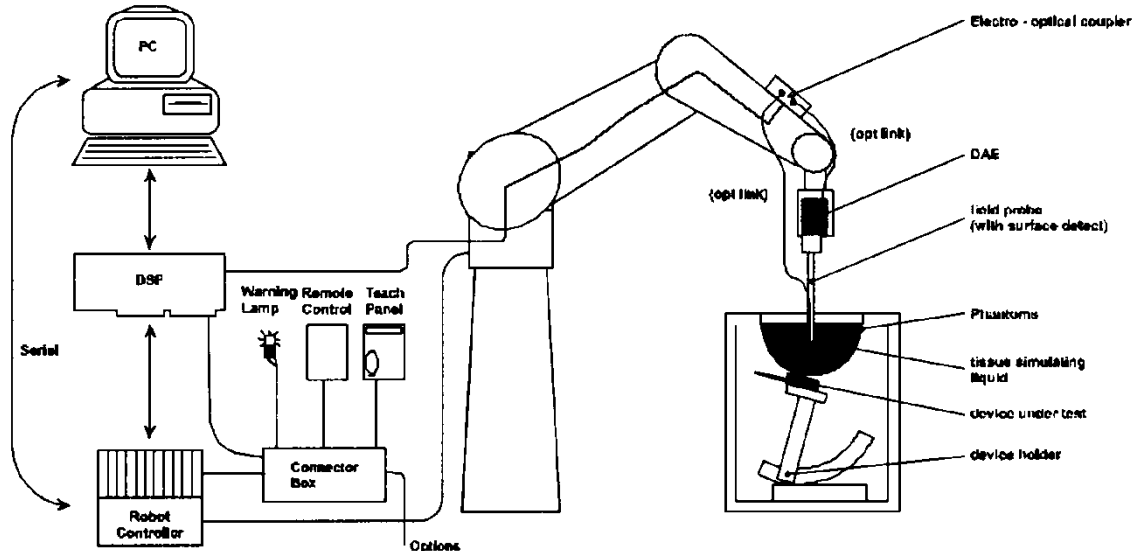
Start Date of test	2013-05-13
End Date of test	2013-05-13

1.8 Ambient Condition

Ambient temperature	20°C – 24°C
Relative Humidity	30% – 70%

2 SAR Measurement System

2.1 SAR Measurement Set-up



The DASY5 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (Stäubli RX family) with controller and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e. an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronic (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- A unit to operate the optical surface detector which is connected to the EOC.
- The Electro-Optical Coupler (EOC) performs the conversion from the optical into a digital electric signal of the DAE. The EOC is connected to the DASY5 measurement server.
- The DASY5 measurement server, which performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation. A computer operating Windows XP.
- DASY5 software and SEMCAD data evaluation software.
- Remote control with teach panel and additional circuitry for robot safety such as warning lamps, etc.
- The generic twin phantom enabling the testing of left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- System check dipoles allowing to validate the proper functioning of the system.

2.2 Test environment

The DASY4 measurement system is placed at the head end of a room with dimensions: 5 x 2.5 x 3 m³, the SAM phantom is placed in a distance of 75 cm from the side walls and 1.1m from the rear wall. Above the test system a 1.5 x 1.5 m² array of pyramid absorbers is installed to reduce reflections from the ceiling.

Picture 1 of the photo documentation shows a complete view of the test environment.

The system allows the measurement of SAR values larger than 0.005 mW/g.

2.3 Data Acquisition Electronics description

The data acquisition electronics (DAE) consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converte and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

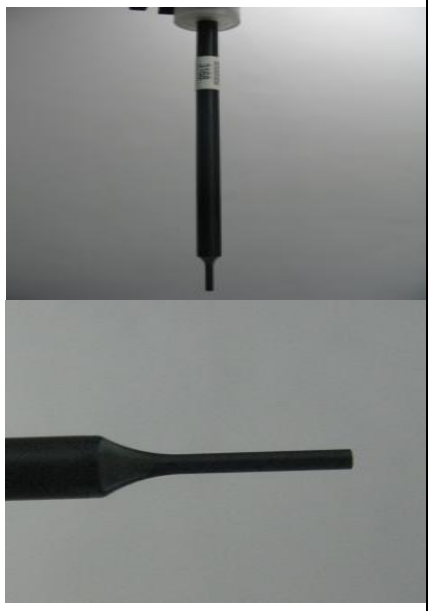
DAE4

Input Impedance	200MOhm	
The Inputs	symmetrical and floating	
Common mode rejection	above 80 dB	

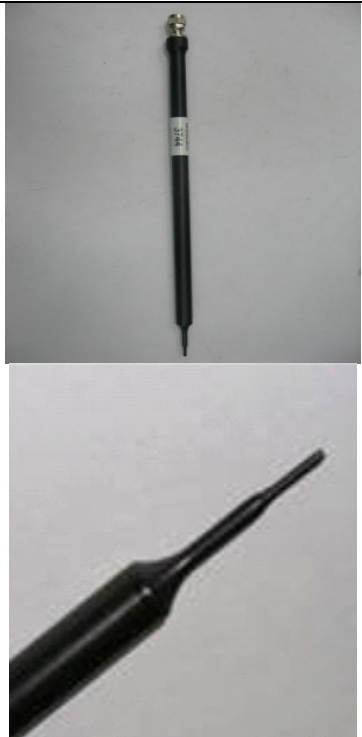
2.4 Probe description

These probes are specially designed and calibrated for use in liquids with high permittivities. They should not be used in air, since the spherical isotropy in air is poor (± 2 dB). The dosimetric probes have special calibrations in various liquids at different frequencies.

Isotropic E-Field Probe ES3DV3 for Dosimetric Measurements

Construction	Symmetrical design with triangular core Interleaved sensors Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	
Calibration	ISO/IEC 17025 calibration service available.	
Frequency	10 MHz to 4 GHz; Linearity: ± 0.2 dB (30 MHz to 4 GHz)	
Directivity	± 0.2 dB in HSL (rotation around probe axis) ± 0.3 dB in tissue material (rotation normal to probe axis)	
Dynamic range	5 μ W/g to > 100 mW/g; Linearity: ± 0.2 dB	
Dimensions	Overall length: 337 mm (Tip: 20 mm) Tip diameter: 3.9 mm (Body: 12 mm) Distance from probe tip to dipole centers: 2.0 mm	
Application	General dosimetry up to 4 GHz Dosimetry in strong gradient fields Compliance tests of mobile phones	

Isotropic E-Field Probe EX3DV4 for Dosimetric Measurements

Construction	Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	
Calibration	ISO/IEC 17025 calibration service available.	
Frequency	10 MHz to >6 GHz; Linearity: ± 0.2 dB (30 MHz to 6 GHz)	
Directivity	± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in tissue material (rotation normal to probe axis)	
Dynamic range	10 μ W/g to > 100 mW/g; Linearity: ± 0.2 dB(noise:typically<1 μ W/g)	
Dimensions	Overall length: 337 mm (Tip:20 mm) Tip diameter:2.5 mm (Body:12 mm) Typical distance from probe tip to dipole centers: 1mm	
Application	High precision dosimetric measurements in any exposure scenario(e.g.,very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precision of better 30%	

2.5 Phantom description

SAM Twin Phantom

Shell Thickness	2mm +/- 0.2 mm; The ear region: 6mm	
Filling Volume	Approximately 30 liters	
Dimensions	Length:1000mm; Width:500mm; Height: adjustable feet	
Measurement Areas	Left hand Right hand Flat phantom	

The bottom plate contains three pairs of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to cover the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on top of this phantom cover are possible. Three reference marks are provided on the phantom counter. These reference marks are used to teach the absolute phantom position relative to the robot.

ELI4 Phantom

Shell Thickness	2mm +/- 0.2 mm	
Filling Volume	Approximately 30 liters	
Dimensions	Length:1000mm; Width:500mm; Height: adjustable feet	
Measurement Areas	Flat phantom	

The ELI4 phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30MHz to 6GHz. ELI4 is fully compatible with the latest draft of the standard IEC 62209-2 and all known tissue simulating liquids.

2.6 Device holder description

The DASY5 device holder has two scales for device rotation (with respect to the body axis) and the device inclination (with respect to the line between the ear openings). The plane between the ear openings and the mouth tip has a rotation angle of 65°. The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. This device holder is used for standard mobile phones or PDA's only. If necessary an additional support of polystyrene material is used.



Larger DUT's (e.g. notebooks) cannot be tested using this device holder. Instead a support of bigger polystyrene cubes and thin polystyrene plates is used to position the DUT in all relevant positions to find and measure spots with maximum SAR values.

Therefore those devices are normally only tested at the flat part of the SAM.

2.7 Test Equipment List

This table gives a complete overview of the SAR measurement equipment
Devices used during the test described are marked ☒

	Manufacturer	Device	Type	Serial number	Date of last calibration)*	Valid period
☒	SPEAG	Dosimetric E-Field Probe	EX3DV4	3898	2013-01-14	One year
☐	SPEAG	835 MHz Dipole	D835V2	4d126	2011-11-07	Three years
☐	SPEAG	1800 MHz Dipole	D1800V2	2d184	2011-03-08	Three years
☐	SPEAG	1900 MHz Dipole	D1900V2	5d143	2011-09-26	Three years
☐	SPEAG	2000 MHz Dipole	D2000V2	1052	2011-03-10	Three years
☐	SPEAG	2300 MHz Dipole	D2300V2	1016	2011-11-22	Three years
☒	SPEAG	2450 MHz Dipole	D2450V2	860	2011-03-08	Three years
☒	SPEAG	Data acquisition electronics	DAE4	852	2012-11-22	One year
☒	SPEAG	Software	DASY 5	N/A	N/A	N/A
☒	SPEAG	Twin Phantom	SAM1	TP-1475	N/A	N/A
☐	SPEAG	Twin Phantom	SAM2	TP-1474	N/A	N/A
☐	SPEAG	Twin Phantom	SAM3	TP-1597	N/A	N/A
☐	SPEAG	Twin Phantom	SAM4	TP-1620	N/A	N/A
☐	SPEAG	Flat Phantom	ELI 4.0	TP-1038	N/A	N/A
☐	SPEAG	Flat Phantom	ELI 4.0	TP-1111	N/A	N/A
☐	R & S	Universal Radio Communication Tester	CMU 200	113989	2012-06-07	One year
☒	Agilent)*	Network Analyser	E5071B	MY42404956	2013-02-27	One year
☒	Agilent	Dielectric Probe Kit	85070E	2484	N/A	N/A
☒	Agilent	Signal Generator	N5181A	MY47420989	2013-02-27	One year
☒	MINI-CIRCUITS	Amplifier	ZHL-42W	QA0746001	N/A	N/A
☒	Agilent	Power Meter	E4417A	MY45101339	2013-02-26	One year
☒	Agilent	Power Meter Sensor	E9321A	MY44420359	2013-02-26	One year

Note: All the test equipments are calibrated once a year, except the dipoles, which are calibrated every three years. Moreover, we have self-calibration every year to the dipoles.

1) Per KDB 450824 D02 requirements for dipole calibration, Huawei SAR lab has adopted three years calibration interval. But each measured dipole is expected to evaluate with the following criteria at least on annual interval in Appendix C.

- There is no physical damage on the dipole;
- System check with specific dipole is within 10% of calibrated value;
- Return-loss is within 10% of calibrated measurement;
- Impedance is within 5Ω from the previous measurement.

2) Network analyzer probe calibration against air, distilled water and a shorting block performed before measuring liquid parameters.

3 SAR Measurement Procedure

3.1 Scanning procedure

The DASY5 installation includes predefined files with recommended procedures for measurements and system check. They are read-only document files and destined as fully defined but unmeasured masks. All test positions (head or body-worn) are tested with the same configuration of test steps differing only in the grid definition for the different test positions.

- The “reference” and “drift” measurements are located at the beginning and end of the batch process. They measure the field drift at one single point in the liquid over the complete procedure. The indicated drift is mainly the variation of the DUT’s output power and should vary max. +/- 5 %.
- The “surface check” measurement tests the optical surface detection system of the DASY5 system by repeatedly detecting the surface with the optical and mechanical surface detector and comparing the results. The output gives the detecting heights of both systems, the difference between the two systems and the standard deviation of the detection repeatability. Air bubbles or refraction in the liquid due to separation of the sugar-water mixture gives poor repeatability (above $\pm 0.1\text{mm}$). To prevent wrong results tests are only executed when the liquid is free of air bubbles. The difference between the optical surface detection and the actual surface depends on the probe and is specified with each probe. (It does not depend on the surface reflectivity or the probe angle to the surface within $\pm 30^\circ$.)
- The “area scan” measures the SAR above the DUT or verification dipole on a parallel plane to the surface. It is used to locate the approximate location of the peak SAR with 2D spline interpolation. The robot performs a stepped movement along one grid axis while the local electrical field strength is measured by the probe. The probe is touching the surface of the SAM during acquisition of measurement values. The standard scan uses large grid spacing for faster measurement. Standard grid spacing for head measurements is 15 mm in x- and y- dimension($\leq 2\text{GHz}$), 12 mm in x- and y- dimension($2-4\text{GHz}$) and 10mm in x- and y- dimension($4-6\text{GHz}$). If a finer resolution is needed, the grid spacing can be reduced. Grid spacing and orientation have no influence on the SAR result. For special applications where the standard scan method does not find the peak SAR within the grid, e.g. mobile phones with flip cover, the grid can be adapted in orientation. Results of this coarse scan are shown in Appendix B.
- A “zoom scan” measures the field in a volume around the 2D peak SAR value acquired in the previous “coarse” scan. This is a fine grid with maximum scan spatial resolution: $\Delta x_{\text{zoom}}, \Delta y_{\text{zoom}} \leq 4\text{GHz} - \leq 5\text{ mm}$ and $4-6\text{ GHz} - \leq 4\text{ mm}$; $\Delta z_{\text{zoom}} \leq 3\text{GHz} - \leq 5\text{ mm}$, $3-4\text{ GHz} - \leq 4\text{ mm}$ and $4-6\text{GHz} - \leq 2\text{mm}$ where the robot additionally moves the probe along the z-axis away from the bottom of the Phantom. DASY is also able to perform repeated zoom scans if more than 1 peak is found during area scan. In this document, the evaluated peak 1g and 10g averaged SAR values are shown in the 2D-graphics in Appendix B. Test results relevant for the specified standard (see chapter 1.4.) are shown in table form in chapter 7.2.
- A Z-axis scan measures the total SAR value at the x-and y-position of the maximum SAR value found during the cube scan. The probe is moved away in z-direction from the bottom of the SAM phantom in 2 mm steps. This measurement shows the continuity of the liquid and can - depending in the field strength – also show the liquid depth. A z-axis scan of the measurement with maximum SAR value is shown in Appendix B.

3.2 Spatial Peak SAR Evaluation

The spatial peak SAR - value for 1 and 10 g is evaluated after the Cube measurements have been done. The basis of the evaluation are the SAR values measured at the points of the fine cube grid consisting of $7 \times 7 \times 7$ points. The algorithm that finds the maximal averaged volume is separated into three different stages.

- The data between the dipole center of the probe and the surface of the phantom are extrapolated. This data cannot be measured since the center of the dipole is 2.7 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is about 1 mm (see probe calibration sheet). The extrapolated data from a cube measurement can be visualized by selecting 'Graph Evaluated'.
- The maximum interpolated value is searched with a straight-forward algorithm. Around this maximum the SAR - values averaged over the spatial volumes (1g or 10 g) are computed using the 3d-spline interpolation algorithm. If the volume cannot be evaluated (i.e., if a part of the grid was cut off by the boundary of the measurement area) the evaluation will be started on the corners of the bottom plane of the cube.
- All neighboring volumes are evaluated until no neighboring volume with a higher average value is found.

Extrapolation

The extrapolation is based on a least square algorithm [W. Gander, Computermathematik, p.168-180]. Through the points in the first 3 cm along the z-axis, polynomials of order four are calculated. These polynomials are then used to evaluate the points between the surface and the probe tip. The points, calculated from the surface, have a distance of 1 mm from each other.

Interpolation

The interpolation of the points is done with a 3d-Spline. The 3d-Spline is composed of three one-dimensional splines with the "Not a knot"-condition [W. Gander, Computermathematik, p.141-150] (x, y and z -direction) [Numerical Recipes in C, Second Edition, p.123ff].

Volume Averaging

At First the size of the cube is calculated. Then the volume is integrated with the trapezoidal algorithm. 8000 points (20x20x20) are interpolated to calculate the average.

Advanced Extrapolation

DASY5 uses the advanced extrapolation option which is able to compensate boundary effects on E-field probes.

3.3 Data Storage and Evaluation

Data Storage

The DASY5 software stores the acquired data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension "DAE4". The software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of incorrect parameter settings. For example, if a measurement has been performed with a wrong crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be re-evaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type ([V/m], [A/m], [°C], [mW/g], [mW/cm²], [dBrel], etc.). Some of these units are not available in certain situations or show meaningless results, e.g., a SAR output in a lossless media will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

Data Evaluation by SEMCAD

The SEMCAD software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	Norm _i , a _{i0} , a _{i1} , a _{i2}
	- Conversion factor	ConvF _i
	- Diode compression point	Dcpi
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY5 components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics.

If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot cf/dcp_i$$

with	V _i	= compensated signal of channel i	(i = x, y, z)
	U _i	= input signal of channel i	(i = x, y, z)
	cf	= crest factor of exciting field (DASY parameter)	
	dcp _i	= diode compression point	(DASY parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

$$E_i = (V_i / \text{Norm}_i \cdot \text{ConvF})^{1/2}$$

$$H_i = (V_i)^{1/2} \cdot (a_{i0} + a_{i1}f + a_{i2}f^2)/f$$

with V_i = compensated signal of channel i (i = x, y, z)
 Norm_i = sensor sensitivity of channel i (i = x, y, z)
[mV/(V/m)²] for E-field Probes
ConvF = sensitivity enhancement in solution
 a_{ij} = sensor sensitivity factors for H-field probes
f = carrier frequency [GHz]
 E_i = electric field strength of channel i in V/m
 H_i = magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{\text{tot}} = (E_x^2 + E_y^2 + E_z^2)^{1/2}$$

The primary field data are used to calculate the derived field units.

$$\text{SAR} = (E_{\text{tot}}^2 \cdot \sigma) / (\rho \cdot 1000)$$

with SAR = local specific absorption rate in mW/g
 E_{tot} = total field strength in V/m
 σ = conductivity in [mho/m] or [Siemens/m]
 ρ = equivalent tissue density in g/cm³

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid. The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{\text{pwe}} = E_{\text{tot}}^2 / 3770 \quad \text{or} \quad P_{\text{pwe}} = H_{\text{tot}}^2 \cdot 37.7$$

with P_{pwe} = equivalent power density of a plane wave in mW/cm²
 E_{tot} = total electric field strength in V/m
 H_{tot} = total magnetic field strength in A/m

4 System Verification Procedure

4.1 Tissue Verification

The simulating liquids should be checked at the beginning of a series of SAR measurements to determine if the dielectric parameters are within the tolerances of the specified target values. The measured conductivity and relative permittivity should be within $\pm 5\%$ of the target values.

The following materials are used for producing the tissue-equivalent materials.

Ingredients (% of weight)	Head Tissue				
Frequency Band (MHz)	835	1800	1900	2450	2600
Water	41.45	52.64	55.242	62.7	55.242
Salt (NaCl)	1.45	0.36	0.306	0.5	0.306
Sugar	56.0	0.0	0.0	0.0	0.0
HEC	1.0	0.0	0.0	0.0	0.0
Bactericide	0.1	0.0	0.0	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0
DGBE	0.0	47.0	44.542	36.8	44.452
Ingredients (% of weight)	Body Tissue				
Frequency Band (MHz)	835	1800	1900	2450	2600
Water	52.4	69.91	69.91	73.2	64.493
Salt (NaCl)	1.40	0.13	0.13	0.04	0.024
Sugar	45.0	0.0	0.0	0.0	0.0
HEC	1.0	0.0	0.0	0.0	0.0
Bactericide	0.1	0.0	0.0	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0
DGBE	0.0	29.96	29.96	26.7	32.252

Table 4: Tissue Dielectric Properties

Salt: 99+% Pure Sodium Chloride; Sugar: 98+% Pure Sucrose; Water: De-ionized, 16M Ω + resistivity
HEC: Hydroxyethyl Cellulose; DGBE: 99+% Di(ethylene glycol) butyl ether, [2-(2-butoxyethoxy)ethanol]
Triton X-100(ultra pure): Polyethylene glycol mono [4-(1,1,3,3-tetramethylbutyl)phenyl]ether

Tissue Type	Measured Frequency (MHz)	Target Tissue		Measured Tissue		Liquid Temp.	Test Date
		ϵ_r (+/-5%)	σ (S/m) (+/-5%)	ϵ_r	σ (S/m)		
2450H	2410	39.30 (37.34~41.26)	1.76 (1.67~1.85)	39.15	1.779	21.4°C	2013-05-13
	2435	39.20 (37.24~41.16)	1.79 (1.70~1.88)	39.18	1.824		
	2450	39.20 (37.24~41.16)	1.80 (1.71~1.89)	39.06	1.820		
	2460	39.20 (37.24~41.16)	1.81 (1.72~1.90)	38.99	1.837		
ϵ_r = Relative permittivity, σ = Conductivity							

Table 5: Measured Tissue Parameter

Note: 1) The dielectric parameters of the tissue-equivalent liquid should be measured under similar ambient conditions and within 2 °C of the conditions expected during the SAR evaluation to satisfy protocol requirements.

2) KDB 450824 was ensured to be applied for probe calibration frequencies greater than or equal to 50MHz of the EUT frequencies.

3) The above measured tissue parameters were used in the DASY software to perform interpolation via the DASY software to determine actual dielectric parameters at the test frequencies. The SAR test plots may slightly differ from the table above since the DASY rounds to three significant digits.

4.2 System Check

The system check is performed for verifying the accuracy of the complete measurement system and performance of the software. The system check is performed with tissue equivalent material according to IEEE P1528 (described above). The following table shows system check results for all frequency bands and tissue liquids used during the tests (Graphic Plot(s) see Appendix A).

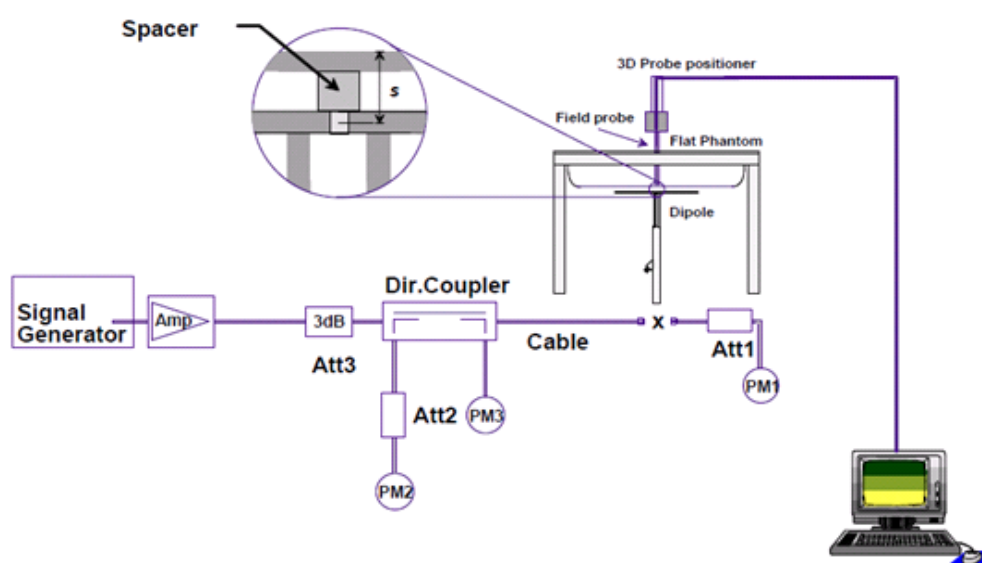
System Check	Target SAR (1W) (+/-10%)		Measured SAR (Normalized to 1W)		Liquid Temp.	Test Date
	1-g (mW/g)	10-g (mW/g)	1-g (mW/g)	10-g (mW/g)		
D2450V2 Head	53.70 (48.33~59.07)	24.90 (22.41~27.39)	54.40	24.00	21.4°C	2013-05-13

Table 6: System Check Results

4.3 System check Procedure

The system check is performed by using a system check dipole which is positioned parallel to the planar part of the SAM phantom at the reference point. The distance of the dipole to the SAM phantom is determined by a plexiglass spacer. The dipole is connected to the signal source consisting of signal generator and amplifier via a directional coupler, N-connector cable and adaption to SMA. It is fed with a power of 250 mW. To adjust this power a power meter is used. The power sensor is connected to the cable before the system check to measure the power at this point and do adjustments at the signal generator. At the outputs of the directional coupler both return loss as well as forward power are controlled during the system check to make sure that emitted power at the dipole is kept constant. This can also be checked by the power drift measurement after the test (result on plot).

System check results have to be equal or near the values determined during dipole calibration (target SAR in table above) with the relevant liquids and test system.



5 Measurement Uncertainty Evaluation

5.1 Measurement uncertainty evaluation for SAR test

The overall combined measurement uncertainty of the measurement system is $\pm 10.9\%$ ($K=1$).

The expanded uncertainty ($k=2$) is assessed to be $\pm 21.9\%$

This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

Error Sources	Uncertainty Value	Probability Distribution	Divisor	c_i 1g	c_i 10g	Standard Uncertainty 1g	Standard Uncertainty 10g	v_i^2 or v_{eff}
Measurement System								
Probe calibration	$\pm 6.0\%$	Normal	1	1	1	$\pm 6.0\%$	$\pm 6.0\%$	∞
Axial isotropy	$\pm 4.7\%$	Rectangular	$\sqrt{3}$	0.7	0.7	$\pm 1.9\%$	$\pm 1.9\%$	∞
Hemispherical isotropy	$\pm 9.6\%$	Rectangular	$\sqrt{3}$	0.7	0.7	$\pm 3.9\%$	$\pm 3.9\%$	∞
Spatial resolution	$\pm 0.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.0\%$	$\pm 0.0\%$	∞
Boundary effects	$\pm 1.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.6\%$	$\pm 0.6\%$	∞
Probe linearity	$\pm 4.7\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 2.7\%$	$\pm 2.7\%$	∞
System detection limits	$\pm 1.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.6\%$	$\pm 0.6\%$	∞
Readout electronics	$\pm 0.3\%$	Normal	1	1	1	$\pm 0.3\%$	$\pm 0.3\%$	∞
Response time	$\pm 0.8\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.5\%$	$\pm 0.5\%$	∞
Integration time	$\pm 2.6\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 1.5\%$	$\pm 1.5\%$	∞
RF ambient conditions	$\pm 3.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 1.7\%$	$\pm 1.7\%$	∞
Probe positioner	$\pm 0.4\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.2\%$	$\pm 0.2\%$	∞
Probe positioning	$\pm 2.9\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 1.7\%$	$\pm 1.7\%$	∞
Max. SAR evaluation	$\pm 1.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.6\%$	$\pm 0.6\%$	∞
Test Sample Related								
Device positioning	$\pm 2.9\%$	Normal	1	1	1	$\pm 2.9\%$	$\pm 2.9\%$	145
Device holder uncertainty	$\pm 3.6\%$	Normal	1	1	1	$\pm 3.6\%$	$\pm 3.6\%$	5
Power drift	$\pm 5.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 2.9\%$	$\pm 2.9\%$	∞
Phantom and Set-up								
Phantom uncertainty	$\pm 4.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 2.3\%$	$\pm 2.3\%$	∞
Liquid conductivity (target)	$\pm 5.0\%$	Rectangular	$\sqrt{3}$	0.64	0.43	$\pm 1.8\%$	$\pm 1.2\%$	∞
Liquid conductivity (meas.)	$\pm 2.5\%$	Normal	1	0.64	0.43	$\pm 1.6\%$	$\pm 1.1\%$	∞
Liquid permittivity (target)	$\pm 5.0\%$	Rectangular	$\sqrt{3}$	0.6	0.49	$\pm 1.7\%$	$\pm 1.4\%$	∞
Liquid permittivity (meas.)	$\pm 2.5\%$	Normal	1	0.6	0.49	$\pm 1.5\%$	$\pm 1.2\%$	∞
Combined Uncertainty	$u_c = \sqrt{\sum_{i=1}^{21} u_i^2}$					$\pm 10.9\%$	$\pm 10.7\%$	387
Expanded Std. Uncertainty	$u_e = 2u_c$	Normal	K=2			$\pm 21.9\%$	$\pm 21.4\%$	

Table 7: Measurement uncertainties

5.2 Measurement uncertainty evaluation for system check

The overall combined measurement uncertainty of the measurement system is $\pm 9.5\%$ ($K=1$).

The expanded uncertainty ($k=2$) is assessed to be $\pm 18.9\%$

This measurement uncertainty budget is suggested by IEEE P1528 and determined by Schmid & Partner Engineering AG. The breakdown of the individual uncertainties is as follows:

Error Sources	Uncertainty Value	Probability Distribution	Divisor	c_i 1g	c_i 10g	Standard Uncertainty 1g	Standard Uncertainty 10g	v_i^2 or v_{eff}
Measurement System								
Probe calibration	$\pm 6.0\%$	Normal	1	1	1	$\pm 6.0\%$	$\pm 6.0\%$	∞
Axial isotropy	$\pm 4.7\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 2.7\%$	$\pm 2.7\%$	∞
Hemispherical isotropy	$\pm 9.6\%$	Rectangular	$\sqrt{3}$	0.7	0.7	$\pm 0.0\%$	$\pm 0.0\%$	∞
Boundary effects	$\pm 1.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.6\%$	$\pm 0.6\%$	∞
Probe linearity	$\pm 4.7\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 2.7\%$	$\pm 2.7\%$	∞
System detection limits	$\pm 1.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.6\%$	$\pm 0.6\%$	∞
Readout electronics	$\pm 0.3\%$	Normal	1	1	1	$\pm 0.3\%$	$\pm 0.3\%$	∞
Response time	$\pm 0.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.0\%$	$\pm 0.0\%$	∞
Integration time	$\pm 0.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.0\%$	$\pm 0.0\%$	∞
RF ambient conditions	$\pm 1.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.6\%$	$\pm 0.6\%$	∞
Probe positioner	$\pm 0.4\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.2\%$	$\pm 0.2\%$	∞
Probe positioning	$\pm 2.9\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 1.7\%$	$\pm 1.7\%$	∞
Max. SAR evaluation	$\pm 1.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 0.6\%$	$\pm 0.6\%$	∞
Dipole								
Deviation of experimental dipole	$\pm 5.5\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 3.2\%$	$\pm 3.2\%$	∞
Dipole axis to liquid distance	$\pm 2.0\%$	Rectangular	1	1	1	$\pm 1.2\%$	$\pm 1.2\%$	∞
Power drift	$\pm 4.7\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 2.7\%$	$\pm 2.7\%$	∞
Phantom and Set-up								
Phantom uncertainty	$\pm 4.0\%$	Rectangular	$\sqrt{3}$	1	1	$\pm 2.3\%$	$\pm 2.3\%$	∞
Liquid conductivity (target)	$\pm 5.0\%$	Rectangular	$\sqrt{3}$	0.64	0.43	$\pm 1.8\%$	$\pm 1.2\%$	∞
Liquid conductivity (meas.)	$\pm 2.5\%$	Normal	1	0.64	0.43	$\pm 1.6\%$	$\pm 1.1\%$	∞
Liquid permittivity (target)	$\pm 5.0\%$	Rectangular	$\sqrt{3}$	0.6	0.49	$\pm 1.7\%$	$\pm 1.4\%$	∞
Liquid permittivity (meas.)	$\pm 2.5\%$	Normal	1	0.6	0.49	$\pm 1.5\%$	$\pm 1.2\%$	∞
Combined Uncertainty	$u_c = \sqrt{\sum_{i=1}^{21} c_i^2 u_i^2}$					$\pm 9.5\%$	$\pm 9.2\%$	
Expanded Std. Uncertainty	$u_e = 2u_c$	Normal	K=2			$\pm 18.9\%$	$\pm 18.4\%$	

Table 8: Measurement uncertainties

6 SAR Test Configuration

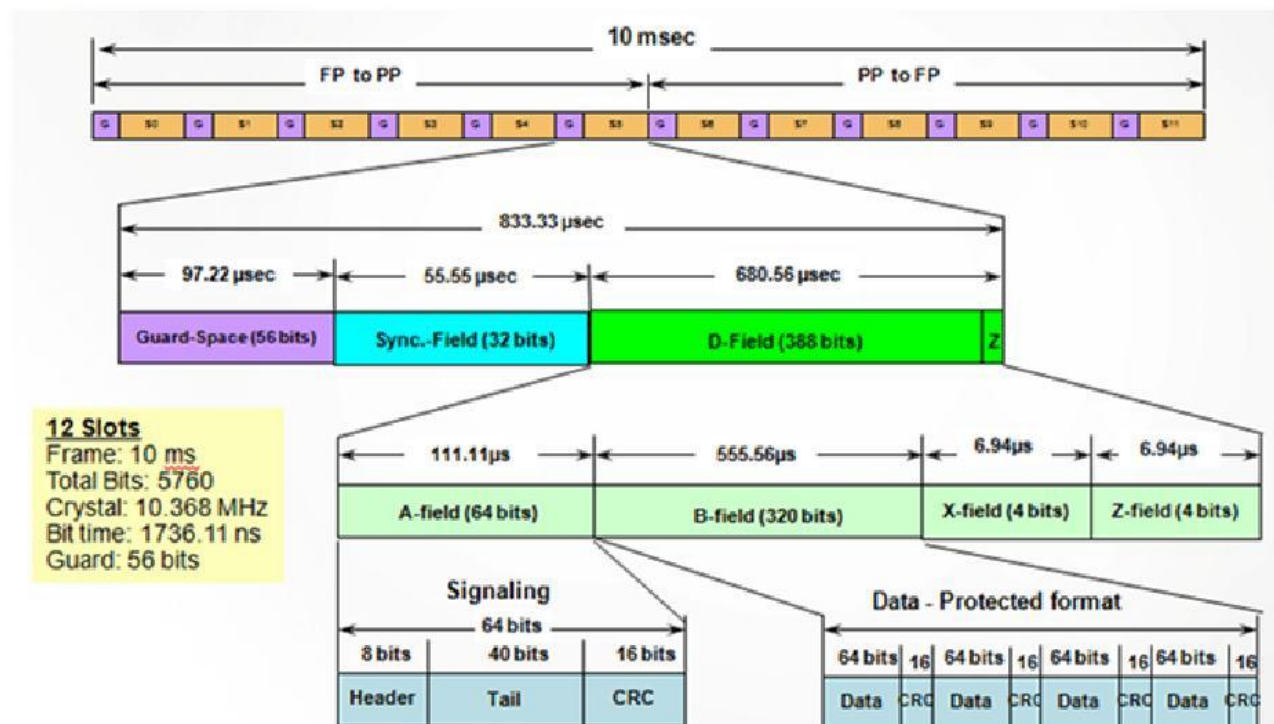
6.1 DECT 2.4G Test Configuration

For the DECT 2.4G SAR test, a communication link is set up with the test mode software for DECT mode test. The Absolute Radio Frequency Channel Number (ARFCN) is allocated to 0, 46 and 94. During the test, at the each test frequency channel, the EUT is operated at the RF continuous emission mode.

DECT 2.4G operating modes are tested independently according to the service requirements in each frequency band. DECT 2.4G modes are tested on channel 0, 46 and 94.

Duty cycle of DECT 2.4G is calculated as below:

$$\frac{833.33 - 97.22 \mu s}{10 \text{ ms}} = \frac{735.78 \mu s}{10 \text{ ms}} = \frac{735.78}{10000} = 7.3578\% = 1:13.5910$$



Note:

- 1) Each frame has only one Tx slot.
- 2) The Guard-Space has no Tx function.

7 SAR Measurement Results

7.1 Conducted power measurements

DECT	Conducted Power (dBm)		
	0CH	46CH	94CH
DECT 2.4G	21.66	21.36	21.18

Table 9:Test results conducted power measurement DECT 2.4G .

7.2 SAR measurement Result

- 1) Per KDB447498 D01v05, testing of other required channels within the operating mode of a frequency band is not required when the reported(Scaled) SAR for the middle channel or highest output power channels is $\leq 0.8\text{W/kg}$. When the maximum output power variation across the required test channels is $> \frac{1}{2}$ dB, instead of the middle channel, the highest output power channel must be used.
- 2) All measurement SAR result is scaled-up to account for tune-up tolerance is compliant.

7.2.1 SAR measurement Result of DECT 2.4G

Test Position of Head	Test channel /Frequency	Test Mode	SAR Value (W/kg)		Power Drift (dB)	Conducted Power (dBm)	Tune-up Power (dBm)	Reported 1-g SAR (W/kg)	Limit (W/kg)	Liquid Temp.
			1-g	10-g						
Test data with battery 1#										
Left Hand Touched	46/2440.8	DECT 2.4G	0.069	0.058	0.010	21.36	23.00	0.101	1.60	21.4°C
Left Hand Tilted 15°	46/2440.8	DECT 2.4G	0.068	0.057	-0.030	21.36	23.00	0.099	1.60	21.4°C
Right Hand Touched	46/2440.8	DECT 2.4G	0.062	0.052	0.080	21.36	23.00	0.090	1.60	21.4°C
Right Hand Tilted 15°	46/2440.8	DECT 2.4G	0.050	0.043	0.060	21.36	23.00	0.073	1.60	21.4°C
Test at the worst position with battery 2#										
Left Hand Touched	46/2440.8	DECT 2.4G	0.054	0.041	-0.040	21.36	23.00	0.079	1.60	21.4°C
Test at the worst position with battery 3#										
Left Hand Touched	46/2440.8	DECT 2.4G	0.049	0.038	0.010	21.36	23.00	0.071	1.60	21.4°C

Table 10: Test results head SAR DECT 2.4G.

Appendix A. System Check Plots
(Pls See Appendix A.)

Appendix B. SAR Measurement Plots
(Pls See Appendix B.)

Appendix C. Calibration Certificate
(Pls See Appendix C.)

Appendix D. Photo documentation
(Pls See Appendix D.)

End