



Annex A - Photo documentation

Appendix No.: 1-9362-25-03-02_TR2-A101-R01

Testing Laboratory

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Photo 1: DASY 8 WPT set up



Photo 2: EUT – Top side view

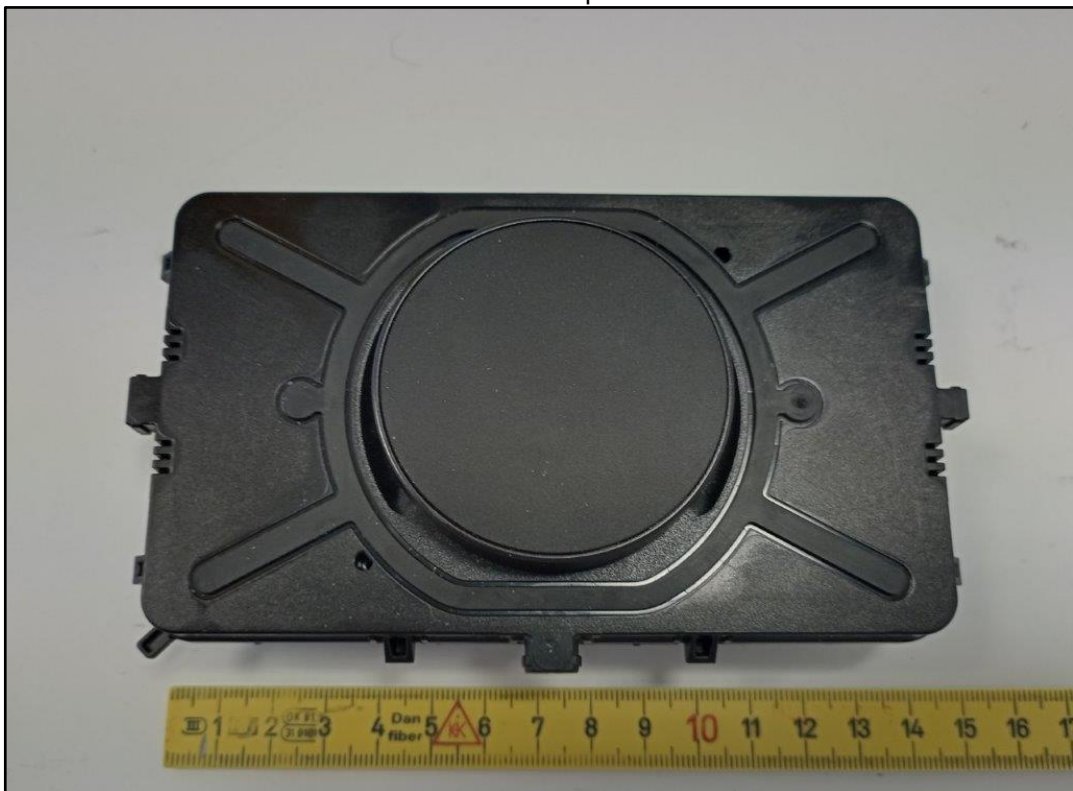


Photo 3: EUT – Side view



Photo 4: EUT – Bottom side view



Photo 5: EUT – Bottom side view (Label – Sample 1 CW 128 kHz)

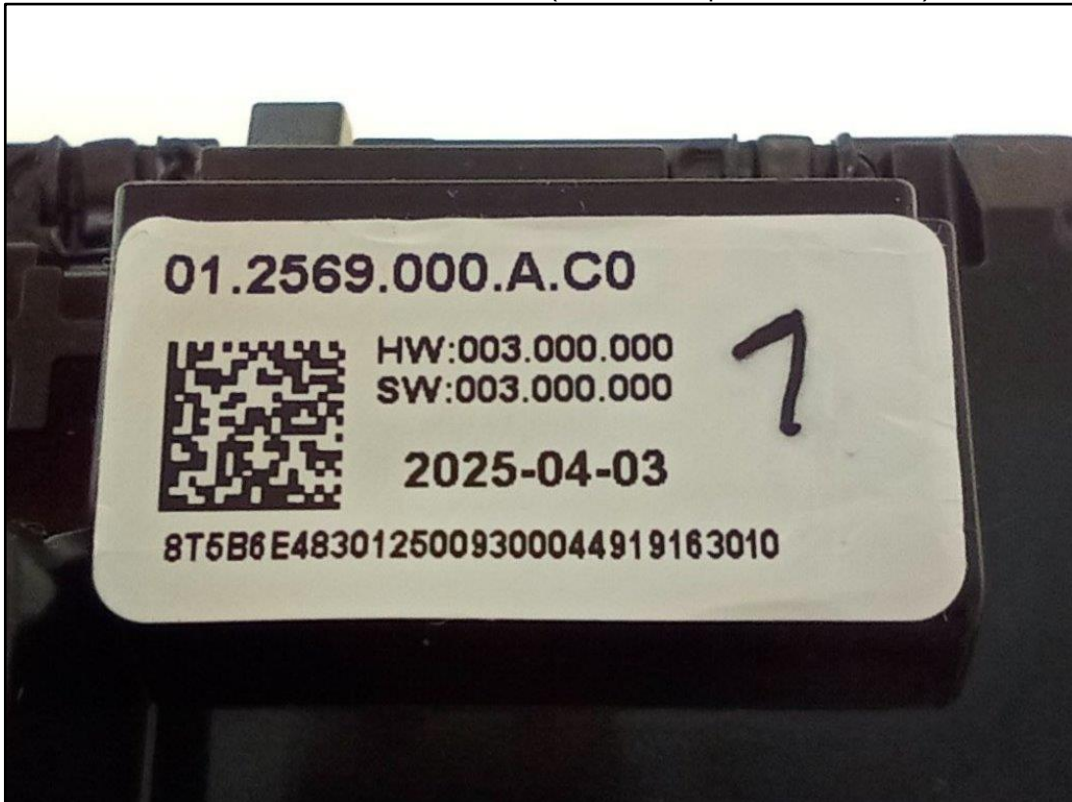


Photo 6: EUT – Bottom side view (Label – Sample 3 CW 360 kHz)



Photo 7: EUT – Bottom side view (Label – Sample 5 – production unit)

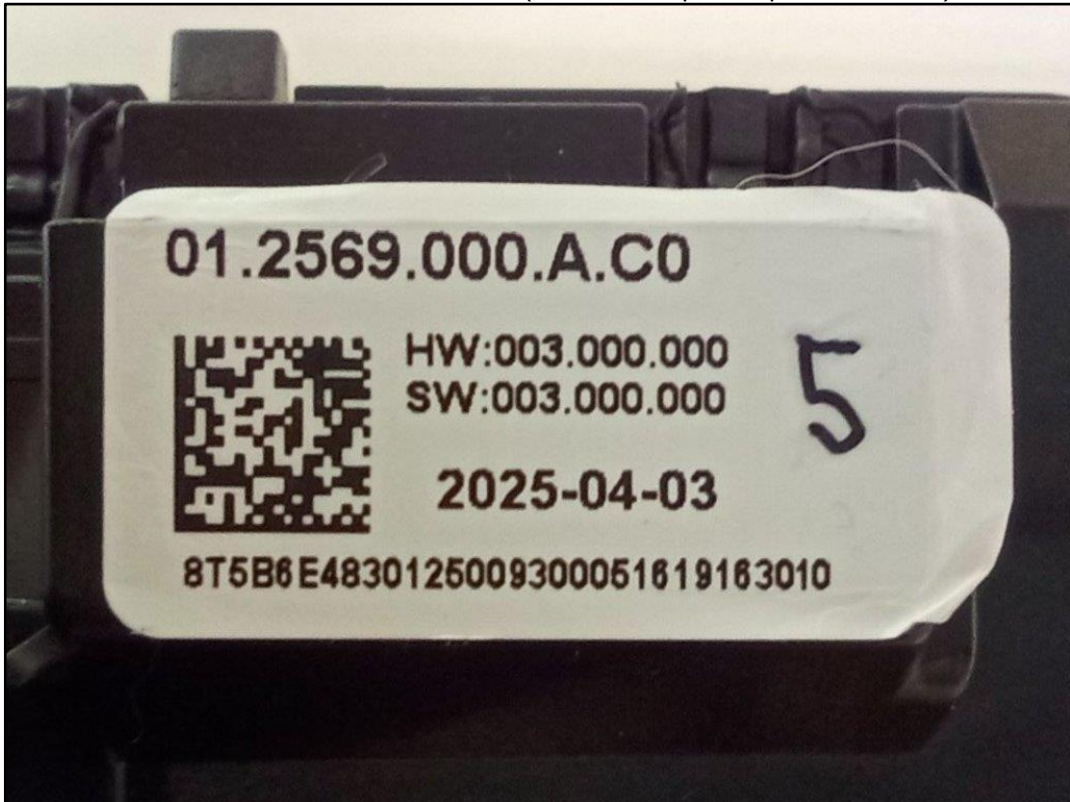


Photo 8: Auxiliary – Dummy Load



Photo 9: Auxiliary – Dummy Load – Side view

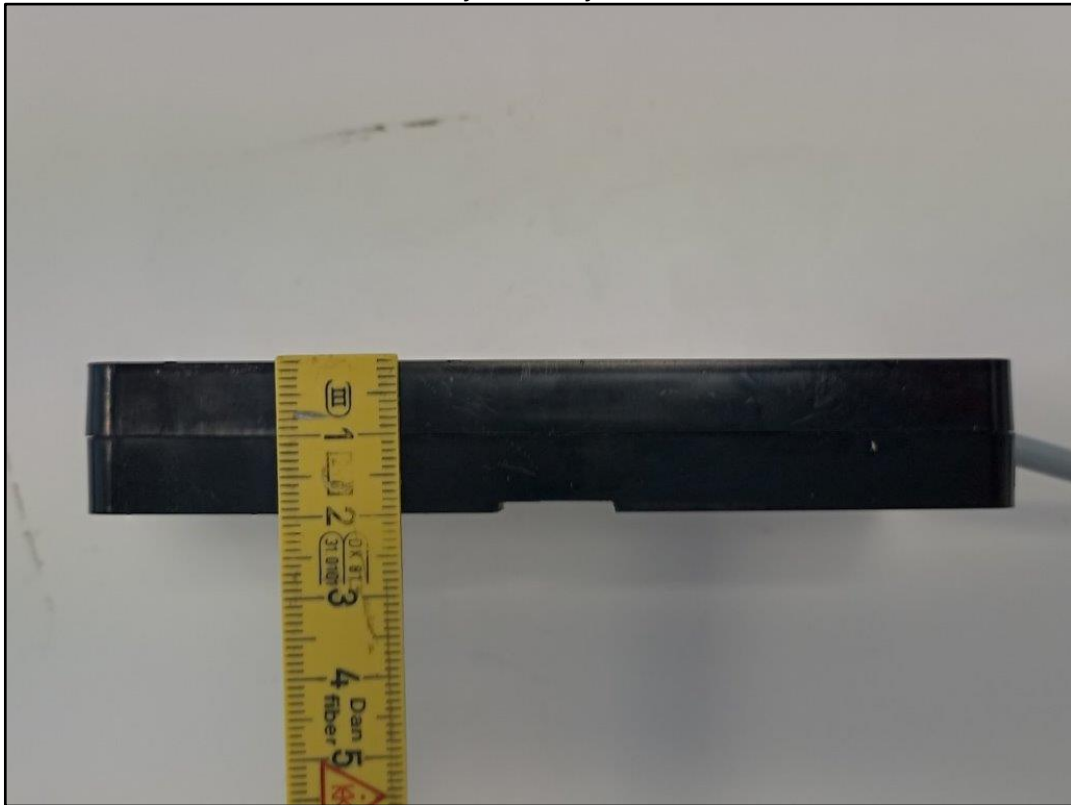


Photo 10: Auxiliary – Dummy Load – bottom side view

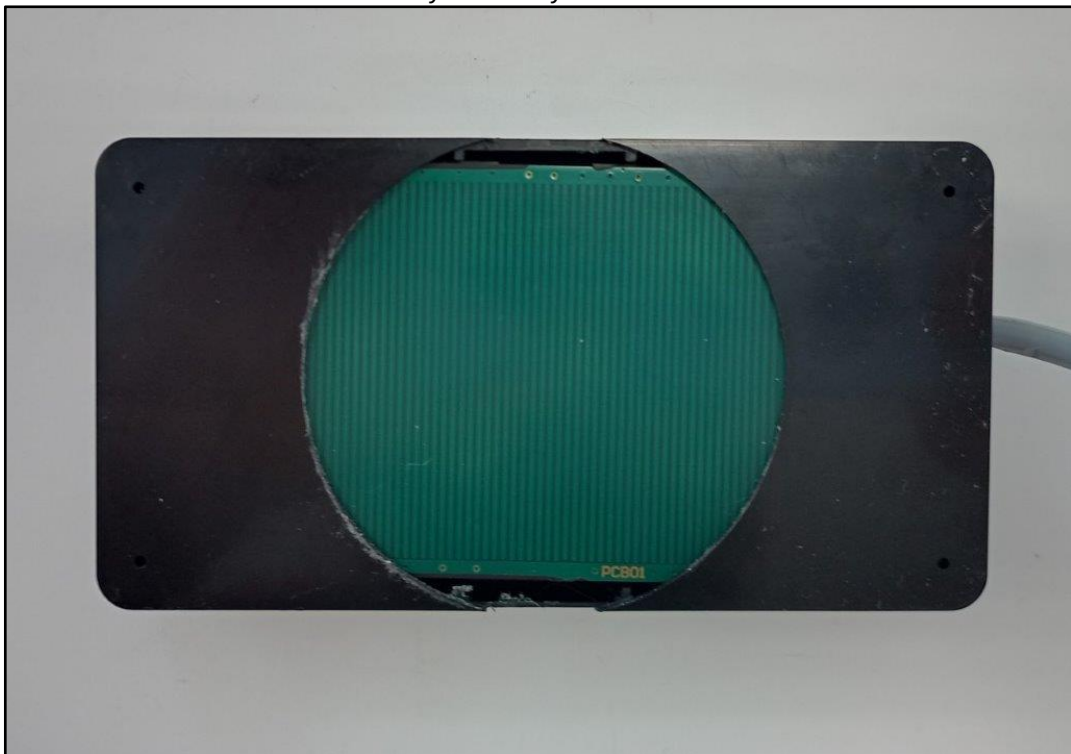


Photo 11: Test pictures – Start position (CW samples)

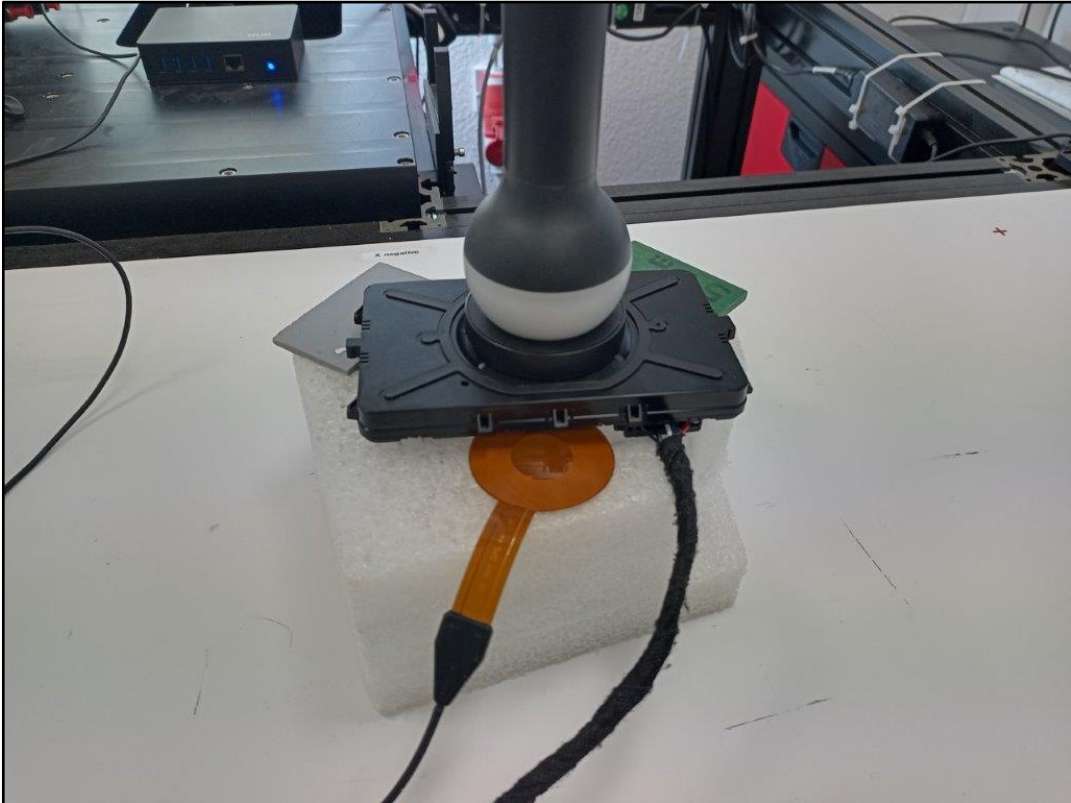


Photo 12: Test pictures – Start position (Close up front - 0mm distance)

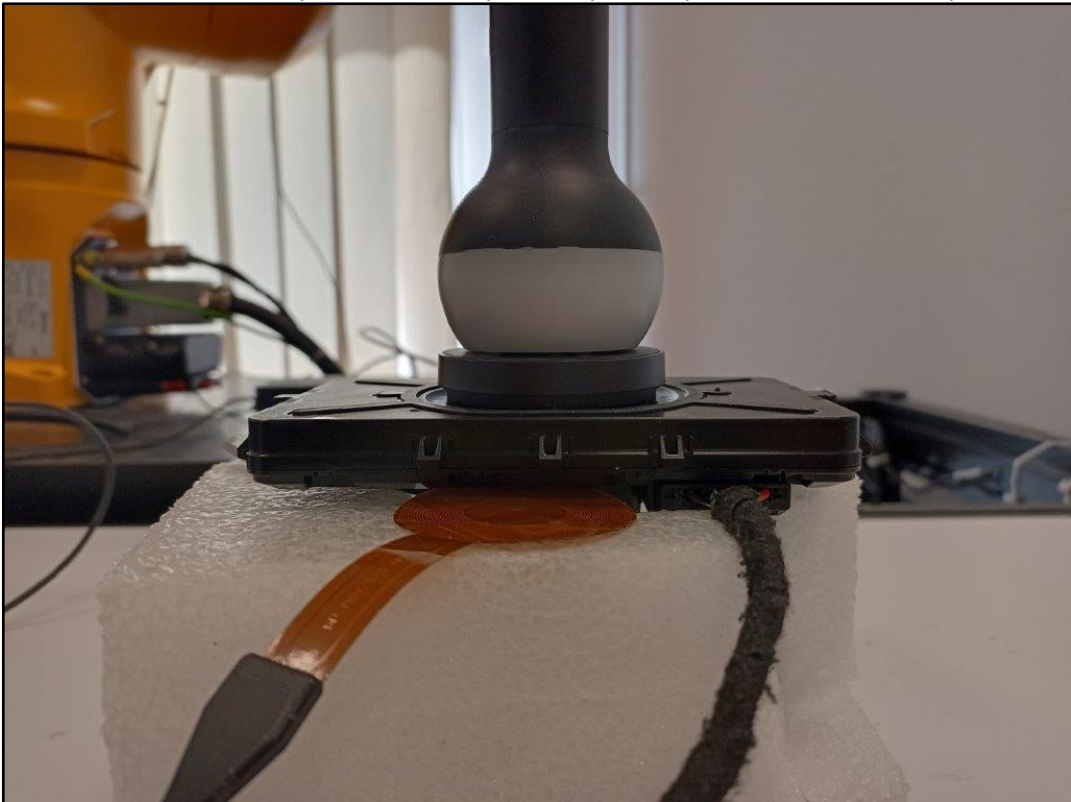


Photo 13: Test pictures – Start position (Close up side - 0mm distance)

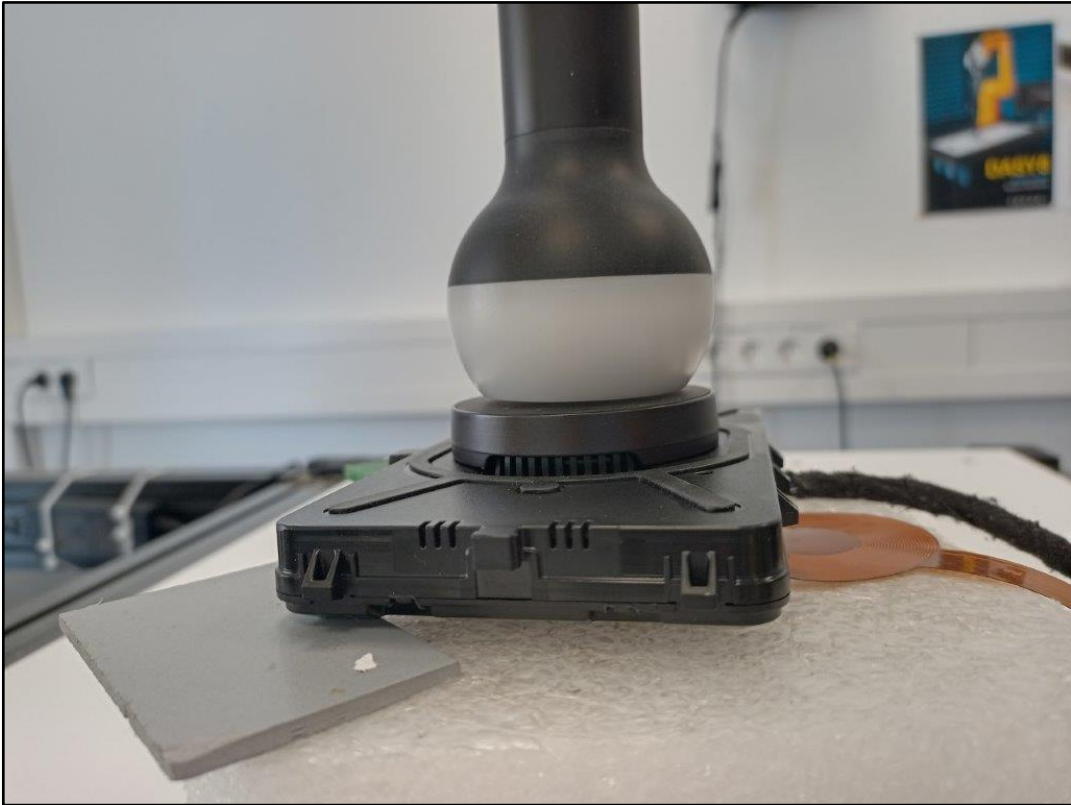


Photo 14: Test pictures – Start position (Sample 5 + Dummy Loads)

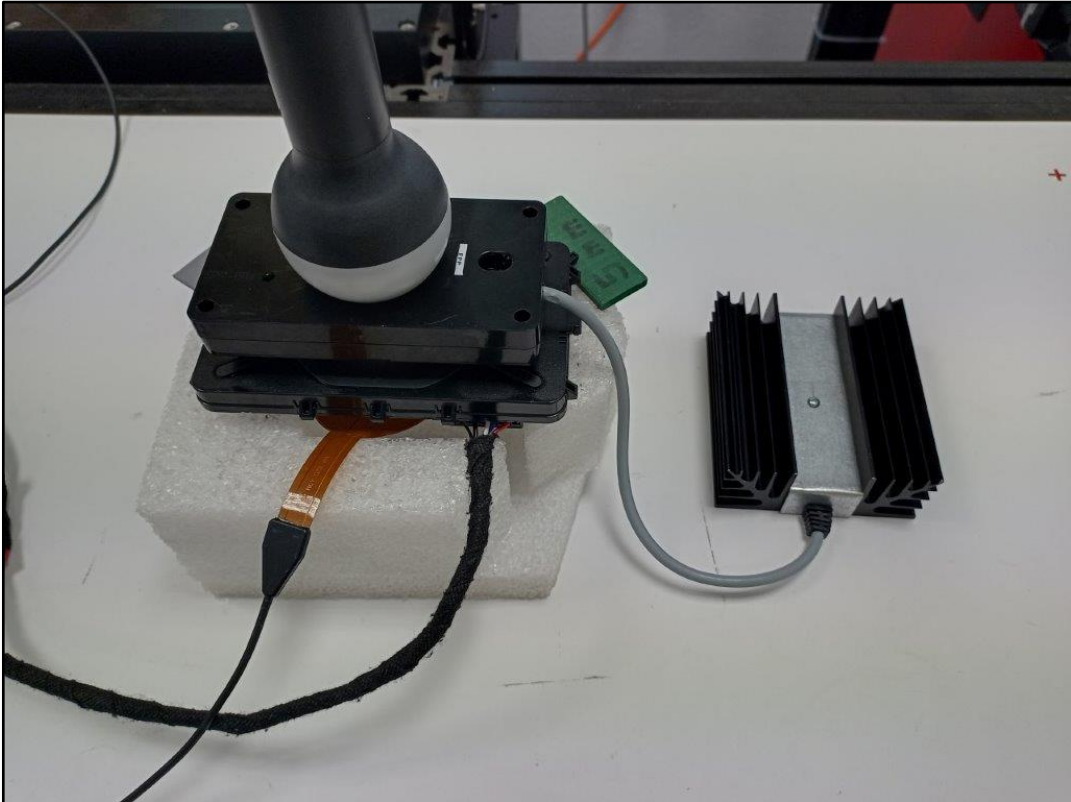


Photo 15: Test pictures – Start position (Close up front - 0mm distance)

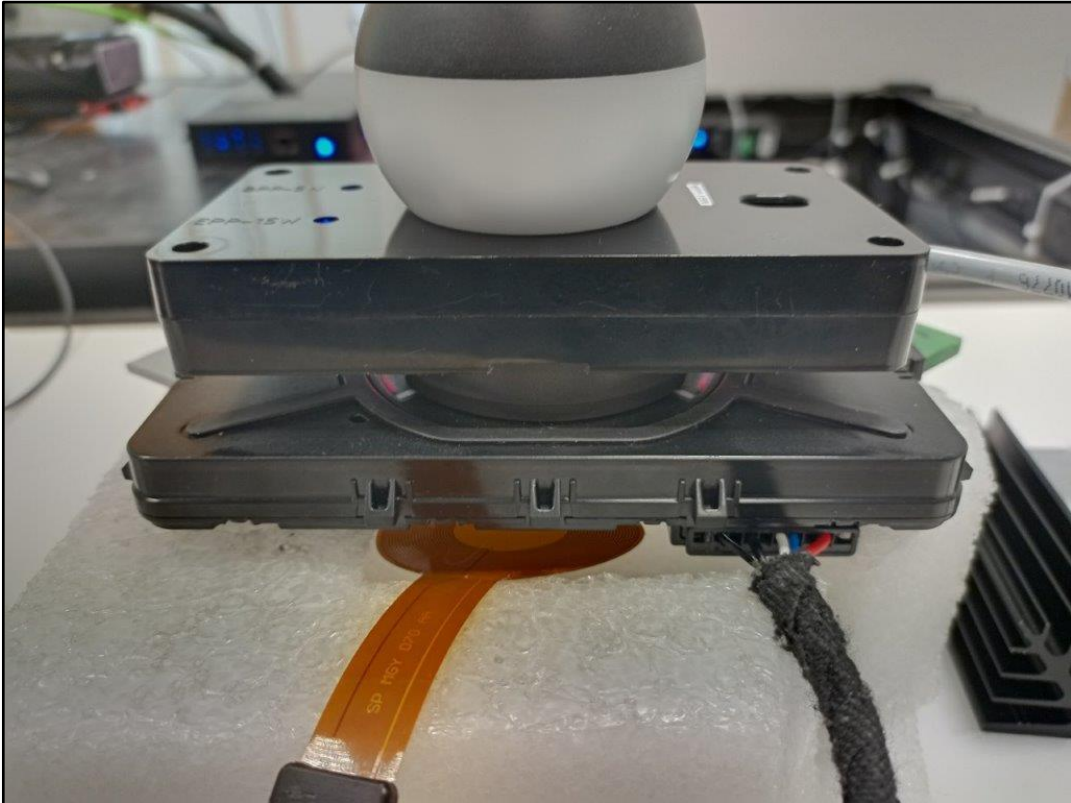


Photo 16: Test pictures – Start position EPP, 15W charging 128 kHz
(Close up side - 0mm distance = 2cm to EUT surface)



Photo 17: Test pictures – Start position MPP, 15W charging 360 kHz (Close up side - 0mm distance)
(Close up side - 0mm distance = 2cm to EUT surface)

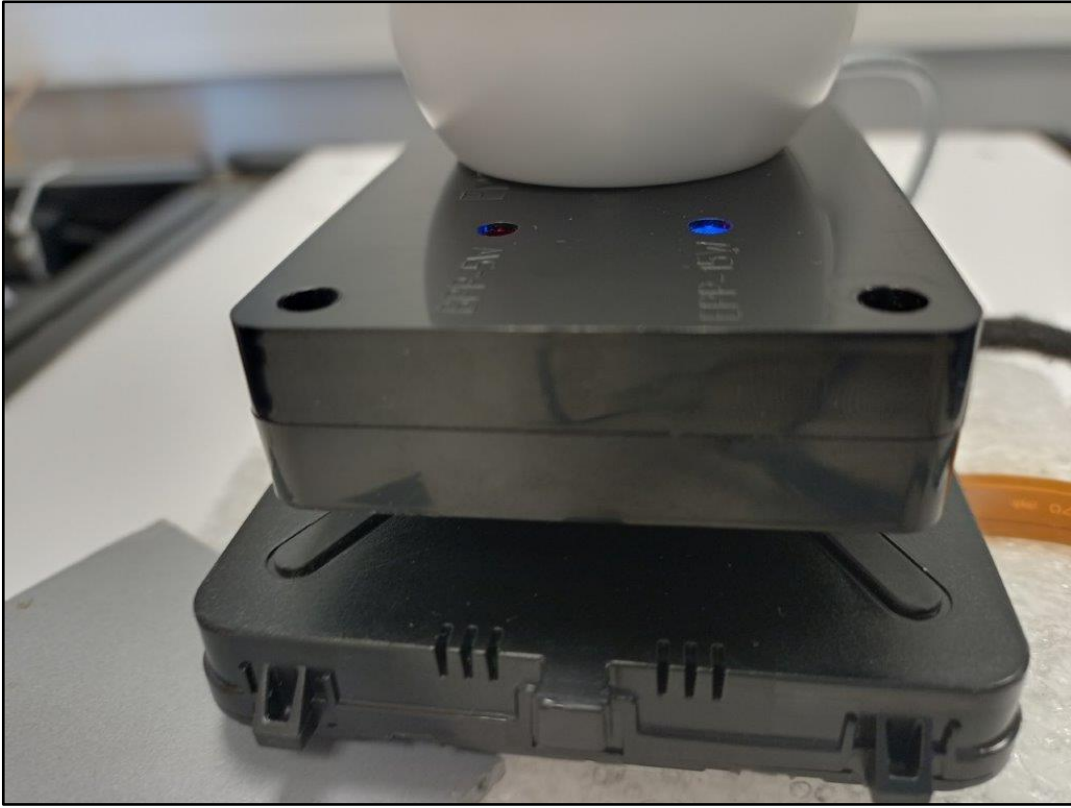


Photo 18: Test pictures – Start position (Close up front - 0mm distance)

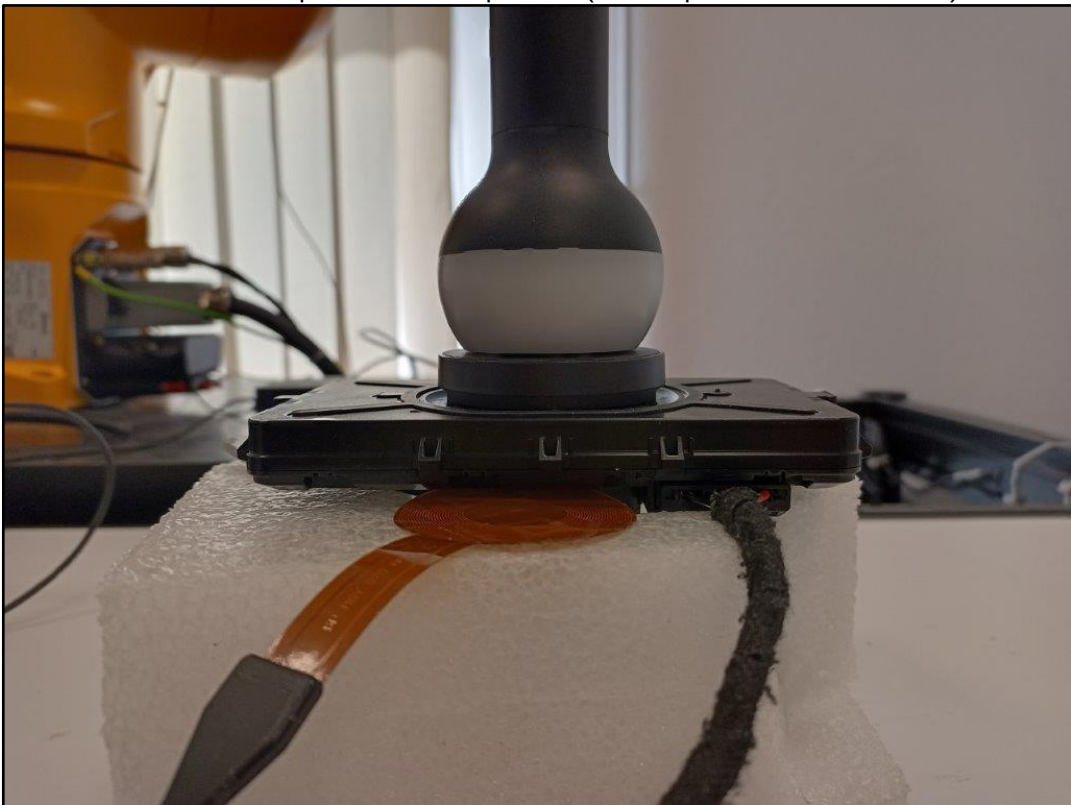


Photo 19: Test pictures – Start position (Close up side - 0mm distance)



Photo 20: Test pictures – Start position (IPHONE - 0mm distance)

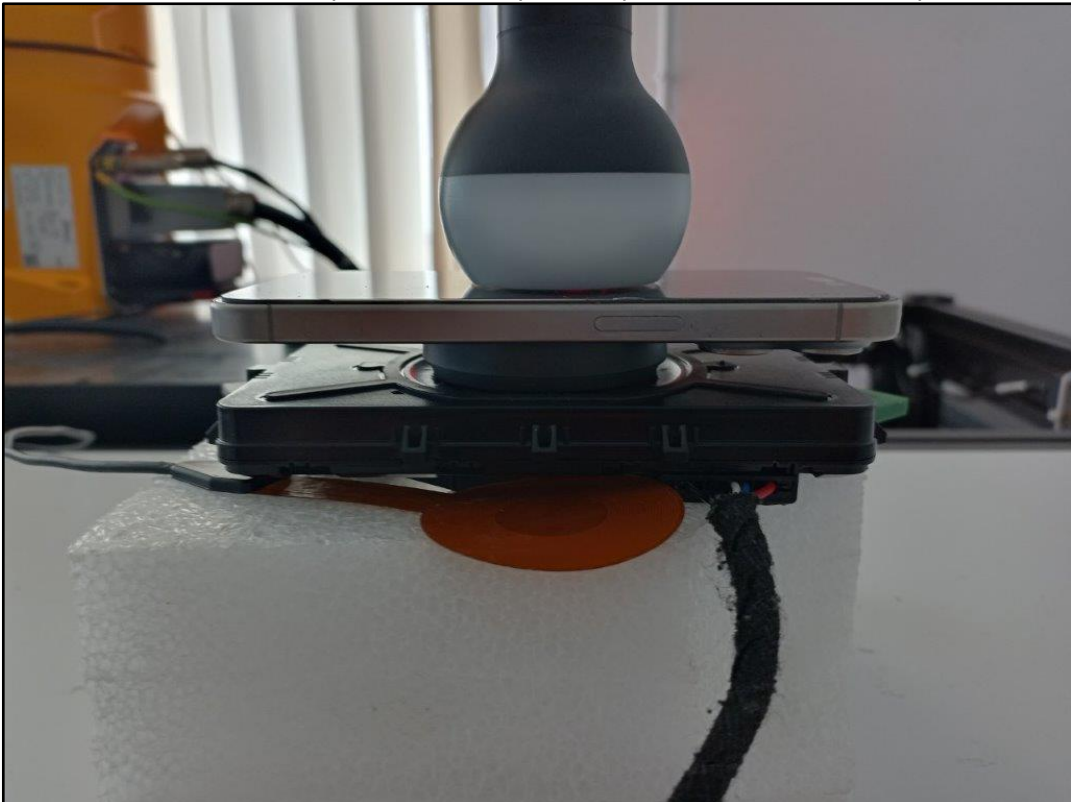


Photo 21: Test pictures – Start position (Close up side - 0mm distance)



Photo 22: Orientation of Robot, EUT and coordinate System

