ANSI/IEEE Std. C95.1-1992
In accordance with the requirements of FCC Report and Order: ET Docket 93-62；FCC 47 CFR Part 2 (2.1093)

FCC SAR TEST REPORT

For

Product Name: Video baby monitor

Brand Name: N/A

Model No.: OT240M

Series Model: OT240M

Test Report Number:
C140311R01-SF

Issued for

MC Devices Co., Ltd.

Suite 516 BLD 4, National Software Base, Ke ji zhong 2 Road, Shenzhen Hi-Tech Park, Shenzhen, China

Issued by

Compliance Certification Services Inc.

Kun shan Laboratory

No.10 Weiye Rd., Innovation park, Eco&Tec, Development Zone, Kunshan City, Jiangsu, China

TEL: 86-512-57355888

FAX: 86-512-57370818

ACCREDITED
TESTING CERT #2541.01

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Revision History

Revision	REPORT NO.	Date	Page Revised	Contents
Original	C140311R01-SF	March 24, 2014	N/A	N/A

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1. CERTIFICATE OF COMPLIANCE (SAR EVALUATION)

Product Name:	Video baby monitor
Brand Name:	N/A
Model Name.:	OT240M
Series Model:	OT240M
Devices supporting GPRS:	N/A
Device Category:	PORTABLE DEVICES
Exposure Category:	GENERAL POPULATION/UNCONTROLLED EXPOSURE
Date of Test:	March 13, 2014
Applicant:	**MC Devices Co., Ltd.** Suite 516 BLD 4, National Software Base, Ke ji zhong 2 Road, Shenzhen Hi-Tech Park, Shenzhen, China
Manufacturer:	**MC Devices Co., Ltd.** Suite 516 BLD 4, National Software Base, Ke ji zhong 2 Road, Shenzhen Hi-Tech Park, Shenzhen, China
Application Type:	Certification

APPLICABLE STANDARDS AND TEST PROCEDURES	
STANDARDS AND TEST PROCEDURES	**TEST RESULT**
ANSI/IEEE C95.1-1992 RSS-102 issue 4: 2010	No non-compliance noted
Deviation from Applicable Standard	
None	

The device was tested by Compliance Certification Services Inc. in accordance with the measurement methods and procedures specified in KDB 865664 The test results in this report apply only to the tested sample of the stated device/equipment. Other similar device/equipment will not necessarily produce the same results due to production tolerance and measurement uncertainties.

Approved by:

Jeff Fang
RF Manager
Compliance Certification Services Inc.

Tested by:

Luck.Fu
Test Engineer
Compliance Certification Services Inc.

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2. EUT DESCRIPTION

Product Name:	Video baby monitor	
Brand Name:	N/A	
Model Name.:	OT240M	
Series Model:	OT240M	
Model Discrepancy:	N/A	
FCC ID:	RS5-OT240MR	
IC:	10850A-OT240MR	
Power reduction:	NO	
DTM Description:	N/A	
Device Category:	Production unit	
Frequency Range:	TX: 2409.75 ~ 2475 MHz	
Transmit Power(Average):	15.5 dBm	
Max. Reported SAR(1g):	0.922 W/kg	
Modulation Technique:	TX : GFSK	
Accessories:	Power supply and ADP（rating）： INPUT: 100-240V 50/60Hz 125mA OUTPUT: 6V, 300mA	Battery（rating）： Capacitance:1800 mAh Rated Voltage:3.6 V
Antenna Specification:	TX: Dipole Antenna	
Operating Mode:	Maximum continuous output	

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3. REQUIREMENTS FOR COMPLIANCE TESTING DEFINED BY THE FCC

The US Federal Communications Commission has released the report and order “Guidelines for Evaluating the Environmental Effects of RF Radiation", ET Docket No. 93-62 in August 1996. The order requires routine SAR evaluation prior to equipment authorization of portable transmitter devices, including portable telephones. For consumer products, the applicable limit is 1.6 W/Kg for an uncontrolled environment and 8.0 W/Kg for an occupational/controlled environment as recommended by the ANSI/IEEE standard C95.1-1992.

4. TEST METHODOLOGY

The Specific Absorption Rate (SAR) testing specification, method and procedure for this device is in accordance with the following standards:

☒ FCC 47 CFR Part 2 (2.1093)
☒ ANSI/IEEE C95.1-1992
☒ IEEE 1528-2003
☒ IEEE 1528-2013
☒ RSS-102 issue 4: 2010
☒ Notice 2013-DRS0911
☒ KDB 447498 D01v05r02 General RF Exposure Guidance v05
☒ KDB 865664 D01v01r03 Measurement 100 MHz to 6 GHz
☒ KDB 865664 D02v01r01 RF Exposure Reporting

5. TEST CONFIGURATION

During GFSK2.4Ghz SAR testing EUT is configured with the WLAN continuous TX tool,and the transmission duty factor was monitored on the spectrum analyzer with zero-span setting
For GFSK2.4Ghz SAR testing, GFSK2.4Ghz engineering test software installed on the EUT can provide continuous transmitting RF signal.

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6. DOSIMETRIC ASSESSMENT SETUP

These measurements were performed with the automated near-field scanning system DASY 5 from ATTENNESSA. The system is based on a high precision robot (working range greater than 0.9 m), which positions the probes with a positional repeatability of better than ± 0.02 mm. Special E- and H-field probes have been developed for measurements close to material discontinuity, the sensors of which are directly loaded with a Schottky diode and connected via highly resistive lines to the data acquisition unit. The SAR measurements were conducted with the E-field PROBE EX3DV4 (manufactured by SPEAG), designed in the classical triangular configuration and optimized for dosimetric evaluation. The probe has been calibrated according to the procedure described in [7] with accuracy of better than ±10%. The spherical isotropy was evaluated with the procedure described in [8] and found to be better than ±0.25 dB. The phantom used was the SAM Twin Phantom as described in FCC supplement C, IEE P1528 and CENELEC EN 62209.

The following table gives the recipes for tissue simulating liquids.

Ingredients (% by weight)	Frequency (MHz)									
	450		835		915		1900		2450	
Tissue Type	Head	Body	Head	Body	Head	Body	Head	Body	Head	Body
Water	38.56	51.16	41.45	52.4	41.05	56.0	54.9	40.4	62.7	73.2
Salt (NaCl)	3.95	1.49	1.45	1.4	1.35	0.76	0.18	0.5	0.5	0.04
Sugar	56.32	46.78	56.0	45.0	56.5	41.76	0.0	58.0	0.0	0.0
HEC	0.98	0.52	1.0	1.0	1.0	1.21	0.0	1.0	0.0	0.0
Bactericide	0.19	0.05	0.1	0.1	0.1	0.27	0.0	0.1	0.0	0.0
Triton X-100	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	36.8	0.0
DGBE	0.0	0.0	0.0	0.0	0.0	0.0	44.92	0.0	0.0	26.7
Dielectric Constant	43.42	58.0	42.54	56.1	42.0	56.8	39.9	54.0	39.8	52.5
Conductivity (S/m)	0.85	0.83	0.91	0.95	1.0	1.07	1.42	1.45	1.88	1.78

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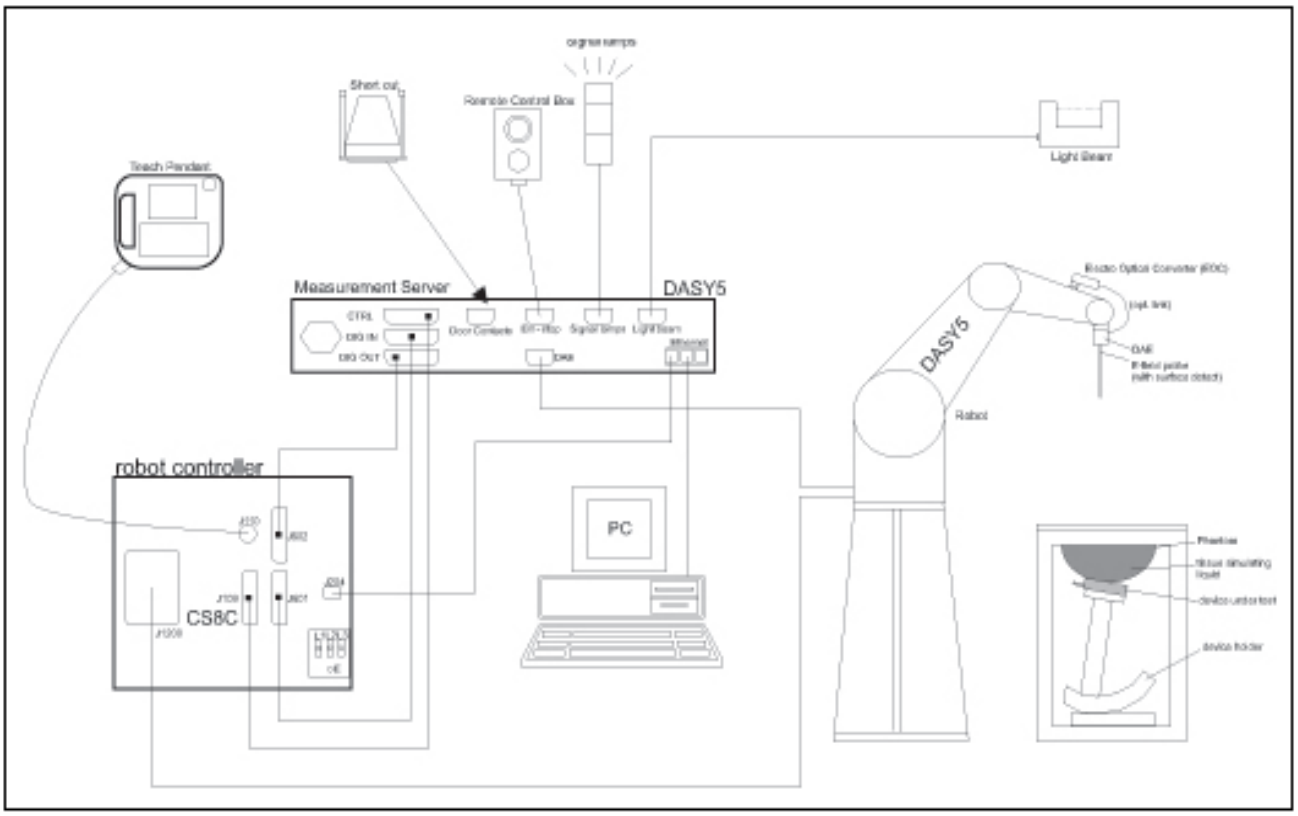
6.1 MEASUREMENT SYSTEM DIAGRAM



The DASY5 system for performing compliance tests consists of the following items:

- A standard high precision 6-axis robot (St¨aubli RX family) with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- A dosimetric probe, i.e., an isotropic E-field probe optimized and calibrated for usage in tissue simulating liquid. The probe is equipped with an optical surface detector system.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion between optical and electrical of the signals for the digital communication to the DAE and for the analog signal from the optical surface detection. The EOC is connected to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the (absolute) accuracy of the probe positioning.
- A computer operating Windows 7.
- DASY5 software.
- Remote control with teach pendant and additional circuitry for robot safety such as warning lamps, etc.
- The SAM twin phantom enabling testing left-hand and right-hand usage.
- The device holder for handheld mobile phones.
- Tissue simulating liquid mixed according to the given recipes.
- Validation dipole kits allowing validating the proper functioning of the system.

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6.2 SYSTEM COMPONENTS

	The DASY5 measurement server is based on a PC/104 CPU board with a 400MHz intel ULV celeron, 128MB chip-disk and 128 MB RAM. The necessary circuits for communication with either the DAE4(or DAE3) electronic box as well as the 16-bit AD-converter system for optical detection and digital I/O interface are contained on the DASY5 I/O-board, which is directly connected to the PC/104 bus of the CPU board. The measurement server performs all real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operation.
	The PC-operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with two expansion slots which are reserved for future applications. Please note that the expansion slots do not have a standardized pinout and therefore only the expansion cards provided by SPEAG can be inserted. Expansion cards from any other supplier could seriously damage the measurement server. Calibration: No calibration required.
Data Acquisition Electronics (DAE)	
	The data acquisition electronics (DAE4) consists of a highly sensitive electrometer grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock. The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection. The input impedance of the DAE4 box is 200MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.
EX3DV4 Isotropic E-Field Probe for Dosimetric Measurements	
	Construction: Symmetrical design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE) **Calibration:** Basic Broad Band Calibration in air: 10-3000 MHz. Conversion Factors (CF) for HSL 900 and HSL 1800 CF-Calibration for other liquids and frequencies upon request. **Frequency:** 10 MHz to > 6 GHz; Linearity: ± 0.2 dB (30 MHz to 3 GHz) **Directivity:** ± 0.3 dB in HSL (rotation around probe axis) ± 0.5 dB in HSL (rotation normal to probe axis) **Dynamic Range:** 10 µW/g to > 100 mW/g; Linearity: ± 0.2 dB (noise: typically < 1 µW/g)

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Dimensions: Overall length: 337 mm (Tip: 9 mm)
Tip diameter: 2.5 mm (Body: 10 mm)
Distance from probe tip to dipole centers: 1 mm

Application: High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields). Only probe which enables compliance testing for frequencies up to 6 GHz with precision of better 30%.

Interior of probe

SAM Twin Phantom

Construction:

The shell corresponds to the specifications of the Specific Anthropomorphic Mannequin (SAM) phantom defined in IEEE 1528, CENELEC 50360 and IEC 62209. It enables the dosimetric evaluation of left and right hand phone usage as well as body mounted usage at the flat phantom region. A cover prevents evaporation of the liquid. Reference markings on the phantom allow the complete setup of all predefined phantom positions and measurement grids by manually teaching three points with the robot.

Shell Thickness: 2 ±0.2 mm

Filling Volume: Approx. 25 liters

Dimensions: Height: 850mm; Length: 1000mm; Width: 750mm

SAM Phantom (ELI4 v4.0)

Description Construction:

Phantom for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with the latest draft of the standard IEC 62209 Part II and all known tissue simulating liquids. ELI4 has been optimized regarding its performance and can be integrated into our standard phantom tables. A cover prevents evaporation of the liquid. Reference markings on the phantom allow installation of the complete setup, including all predefined phantom positions and measurement grids, by teaching three points. The phantom is supported by software version DASY4/DASY5.5 and higher and is compatible with all SPEAG dosimetric probes and dipoles

Shell Thickness: 2.0 ± 0.2 mm (sagging: <1%)

Filling Volume: Approx. 25 liters

Dimensions: Major ellipse axis: 600 mm

Minor axis: 400 mm 500mm

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Device Holder for SAM Twin Phantom

Construction: In combination with the Twin SAM Phantom, the Mounting Device (made from POM) enables the rotation of the mounted transmitter in spherical coordinates, whereby the rotation point is the ear opening. The devices can be easily and accurately positioned according to IEC, IEEE, CENELEC, FCC or other specifications. The device holder can be locked at different phantom locations (left head, right head, and flat phantom).

System Validation Kits for SAM Twin Phantom

Construction: Symmetrical dipole with l/4 balun Enables measurement of feedpoint impedance with NWA Matched for use near flat phantoms filled with brain simulating solutions Includes distance holder and tripod adaptor.

Frequency: 900,1800,2450,5800 MHz

ReTune loss: > 20 dB at specified validation position

Power capability: > 100 W (f < 1GHz); > 40 W (f > 1GHz)

Dimensions:

D835V2: dipole length: 161 mm; overall height: 340 mm
D1800V2: dipole length: 72.5 mm; overall height: 300 mm
D1900V2: dipole length: 67.7 mm; overall height: 300 mm
D2450V2: dipole length: 51.5 mm; overall height: 290 mm
D5GHzV2: dipole length: 20.6 mm; overall height: 300mm

System Validation Kits for ELI4 phantom

Construction: Symmetrical dipole with l/4 balun Enables measurement of feedpoint impedance with NWA Matched for use near flat phantoms filled with brain simulating solutions Includes distance holder and tripod adaptor.

Frequency: 900, 1800, 2450, 5800 MHz

ReTune loss: > 20 dB at specified validation position

Power capability: > 100 W (f < 1GHz); > 40 W (f > 1GHz)

Dimensions:

D835V2: dipole length: 161 mm; overall height: 340 mm
D1800V2: dipole length: 72.5 mm; overall height: 300 mm
D1900V2: dipole length: 67.7 mm; overall height: 300 mm
D2450V2: dipole length: 51.5 mm; overall height: 290 mm
D5GHzV2: dipole length: 20.6 mm; overall height: 300 mm

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7. EVALUATION PROCEDURES

DATA EVALUATION

The DASY 5 post processing software automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software:

Probe parameters:	- Sensitivity	$Norm_i$, a_{i0}, a_{i1}, a_{i2}
	- Conversion factor	$ConvF_i$
	- Diode compression point	dcp_i
Device parameters:	- Frequency	f
	- Crest factor	cf
Media parameters:	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or be imported into the software from the configuration files issued for the DASY 5 components. In the direct measuring mode of the multi-meter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.

The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel can be given as:

$$V_i = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with V_i = Compensated signal of channel i (i = x, y, z)
U_i = Input signal of channel i (i = x, y, z)
cf = Crest factor of exciting field (DASY 5 parameter)
dcp_i = Diode compression point (DASY 5 parameter)

From the compensated input signals the primary field data for each channel can be evaluated:

E-field probes:

$$E_i = \sqrt{\frac{V_i}{Norm_i \bullet ConvF}}$$

H-field probes:

$$H_i = \sqrt{Vi} \cdot \frac{a_{i10} + a_{i11} f + a_{i12} f^2}{f}$$

with V_i = Compensated signal of channel i (i = x, y, z)
$Norm_i$ = Sensor sensitivity of channel i (i = x, y, z)
$\mu V/(V/m)^2$ for E0field Probes
$ConvF$ = Sensitivity enhancement in solution
aij = Sensor sensitivity factors for H-field probes
f = Carrier frequency (GHz)
Ei = Electric field strength of channel i in V/m
Hi = Magnetic field strength of channel i in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude):

$$E_{tot} = \sqrt{E_x^2 + E_y^2 + E_z^2}$$

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The primary field data are used to calculate the derived field units.

$$SAR = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with SAR = local specific absorption rate in mW/g

E_{tot} = total field strength in V/m

σ = conductivity in [mho/m] or [Siemens/m]

ρ = equivalent tissue density in g/cm^3

Note that the density is normally set to 1 (or 1.06), to account for actual brain density rather than the density of the simulation liquid.

The power flow density is calculated assuming the excitation field as a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770} \quad \text{or} \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

with P_{pwe} = Equivalent power density of a plane wave in mW/cm^2

E_{tot} = total electric field strength in V/m

H_{tot} = total magnetic field strength in A/m

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SAR EVALUATION PROCEDURES

The procedure for assessing the peak spatial-average SAR value consists of the following steps:

- **Power Reference Measurement**

  The reference and drift jobs are useful jobs for monitoring the power drift of the device under test in the batch process. Both jobs measure the field at a specified reference position, at a selectable distance from the phantom surface. The reference position can be either the selected section's grid reference point or a user point in this section. The reference job projects the selected point onto the phantom surface, orients the probe perpendicularly to the surface, and approaches the surface using the selected detection method.

- **Area Scan**

  The area scan is used as a fast scan in two dimensions to find the area of high field values, before doing a finer measurement around the hot spot. The sophisticated interpolation routines implemented in DASY 5 software can find the maximum locations even in relatively coarse grids. The scan area is defined by an editable grid. This grid is anchored at the grid reference point of the selected section in the phantom. When the area scan's property sheet is brought-up, grid was at to 15 mm by 15 mm and can be edited by a user.

- **Zoom Scan**

  Zoom scans are used to assess the peak spatial SAR values within a cubic averaging volume containing 1 g and 10 g of simulated tissue. The default zoom scan measures 5 x 5 x 7 points within a cube whose base faces are centered around the maximum found in a preceding area scan job within the same procedure. If the preceding Area Scan job indicates more then one maximum, the number of Zoom Scans has to be enlarged accordingly (The default number inserted is 1).

- **Power Drift measurement**

  The drift job measures the field at the same location as the most recent reference job within the same procedure, and with the same settings. The drift measurement gives the field difference in dB from the reading conducted within the last reference measurement. Several drift measurements are possible for one reference measurement. This allows a user to monitor the power drift of the device under test within a batch process. In the properties of the Drift job, the user can specify a limit for the drift and have DASY 5 software stop the measurements if this limit is exceeded.

- **Z-Scan**

  The Z Scan job measures points along a vertical straight line. The line runs along the Z-axis of a one-dimensional grid. A user can anchor the grid to the current probe location. As with any other grids, the local Z-axis of the anchor location establishes the Z-axis of the grid.

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SPATIAL PEAK SAR EVALUATION

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1529 standard. It can be conducted for 1 g and 10 g.

The DASY 5 system allows evaluations that combine measured data and robot positions, such as:

- maximum search
- extrapolation
- boundary correction
- peak search for averaged SAR

During a maximum search, global and local maximum searches are automatically performed in 2-D after each Area Scan measurement with at least 6 measurement points. It is based on the evaluation of the local SAR gradient calculated by the Quadratic Shepard's method. The algorithm will find the global maximum and all local maxima within -2 dB of the global maxima for all SAR distributions.

Extrapolation

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. Several measurements at different distances are necessary for the extrapolation.

Extrapolation routines require at least 10 measurement points in 3-D space. They are used in the Cube Scan to obtain SAR values between the lowest measurement points and the inner phantom surface. The routine uses the modified Quadratic Shepard's method for extrapolation. For a grid using 5x5x7 measurement points with 5mm resolution amounting to 343 measurement points, the uncertainty of the extrapolation routines is less than 1% for 1 g and 10 g cubes.

Boundary effect

For measurements in the immediate vicinity of a phantom surface, the field coupling effects between the probe and the boundary influence the probe characteristics. Boundary effect errors of different dosimetric probe types have been analyzed by measurements and using a numerical probe model. As expected, both methods showed an enhanced sensitivity in the immediate vicinity of the boundary. The effect strongly depends on the probe dimensions and disappears with increasing distance from the boundary. The sensitivity can be approximately given as:

$$S \approx S_o + S_b exp(-\frac{z}{a}) cos(\pi \frac{z}{\lambda})$$

Since the decay of the boundary effect dominates for small probes ($a \ll \lambda$), the cos-term can be omitted. Factors *Sb* (parameter Alpha in the DASY 5 software) and *a* (parameter Delta in the DASY 5 software) are assessed during probe calibration and used for numerical compensation of the boundary effect. Several simulations and measurements have confirmed that the compensation is valid for different field and boundary configurations.

This simple compensation procedure can largely reduce the probe uncertainty near boundaries. It works well as long as:

- the boundary curvature is small
- the probe axis is angled less than 30_ to the boundary normal
- the distance between probe and boundary is larger than 25% of the probe diameter
- the probe is symmetric (all sensors have the same offset from the probe tip)

Since all of these requirements are fulfilled in a DASY 5 system, the correction of the probe boundary effect in the vicinity of the phantom surface is performed in a fully automated manner via the measurement data extraction during post processing.

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8. MEASUREMENT UNCERTAINTY

UNCERTAINTY BUDGE ACCORDING TO IEEE 1528						
Error Description	**Uncertainty Value ±%**	**Probability distribution**	**Divisor**	**C_1 1g**	**Standard unc.(1g) ±%**	**V_1 or V_{eff}**
Measurement System						
Probe calibration	±5.5	normal	1	1	±5.5	∞
Axial isotropy of probe	±4.7	rectangular	√3	0.7	±1.9	∞
Hemispherical Isotropy of probe	±9.6	rectangular	√3	0.7	±3.9	∞
Probe linearity	±4.7	rectangular	√3	1	±2.7	∞
Detection Limit	±1.0	rectangular	√3	1	±0.6	∞
Boundary effects	±1.0	rectangular	√3	1	±0.6	∞
Readout electronics	±0.3	normal	1	1	±0.3	∞
Response time	±0.8	rectangular	√3	1	±0.5	∞
Integration time	±2.6	rectangular	√3	1	±1.5	∞
Probe positioning	±2.9	rectangular	√3	1	±1.7	∞
Probe positioner	±0.4	rectangular	√3	1	±0.2	∞
RF ambient Noise	±3.0	rectangular	√3	1	±1.7	∞
RF ambient Reflections	±3.0	rectangular	√3	1	±1.7	∞
Max.SAR Eval	±1.0	rectangular	√3	1	±0.6	∞
Test Sample Related						
Device positioning	±2.9	normal	1	1	±2.9	145
Device holder uncertainty	±3.6	normal	1	1	±3.6	5
Power drift	±5.0	rectangular	√3	1	±2.9	∞
Phantom and Set up						
Phantom uncertainty	±4.0	rectangular	√3	1	±2.3	∞
Liquid conductivity(target)	±5.0	rectangular	√3	0.64	±1.8	∞
Liquid conductivity(meas.)	±2.5	rectangular	1	0.64	±1.6	∞
Liquid permittivity(target)	±5.0	rectangular	√3	0.6	±1.7	∞
Liquid permittivity(meas.)	±2.5	rectangular	1	0.6	±1.5	∞
Combined Standard Uncertainty					±10.7	387
Coverage Factor for 95%		kp=2				
Expanded Standard Uncertainty					±21.4	

Table: Worst-case uncertainty for DASY5 assessed according to IEEE1528-2003.
The budge is valid for the frequency range 300 MHz to 6G Hz and represents a worst-case analysis.

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9. EXPOSURE LIMIT

(A). Limits for Occupational/Controlled Exposure (W/kg)

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.4	8.0	20.0

(B). Limits for General Population/Uncontrolled Exposure (W/kg)

Whole-Body	Partial-Body	Hands, Wrists, Feet and Ankles
0.08	1.6	4.0

Note: Whole-Body SAR is averaged over the entire body, **partial-body SAR** is averaged over any 1 gram of tissue defined as a tissue volume in the shape of a cube. **SAR for hands, wrists, feet and ankles** is averaged over any 10 grams of tissue defined as a tissue volume in the shape of a cube.

Population/Uncontrolled Environments are defined as locations where there is the exposure of individuals who have no knowledge or control of their exposure.

Occupational/Controlled Environments are defined as locations where there is exposure that may be incurred by people who are aware of the potential for exposure, (i.e. as a result of employment or occupation).

NOTE
GENERAL POPULATION/UNCONTROLLED EXPOSURE
PARTIAL BODY LIMIT
1.6 W/kg

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10. EUT ARRANGEMENT

Please refer to IEEE1528 illustration below.

10.1 ANTHROPOMORPHIC HEAD PHANTOM

Figure 7-1a shows the front, back and side views of SAM. The point "M" is the reference point for the center of mouth, "LE" is the left ear reference point (ERP), and "RE" is the right ERP. The ERPs are 15 mm posterior to the entrance to ear canal (EEC) along the B-M line (Back-Mouth), as shown in Figure 7-1b. The plane passing through the two ear reference points and M is defined as the Reference Plane. The line N-F (Neck-Front) perpendicular to the reference plane and passing through the RE (or LE) is called the Reference Pivoting Line (see Figure 7-1c). Line B-M is perpendicular to the N-F line. Both N-F and B-M lines should be marked on the external phantom shell to facilitate handset positioning. Posterior to the N-F line, the thickness of the phantom shell with the shape of an ear is a flat surface 6 mm thick at the ERPs. Anterior to the N-F line, the ear is truncated as illustrated in Figure 7-1b. The ear truncation is introduced to avoid the handset from touching the ear lobe, which can cause unstable handset positioning at the cheek.

Figure 7-1a
Front, back and side view of SAM (model for the phantom shell)

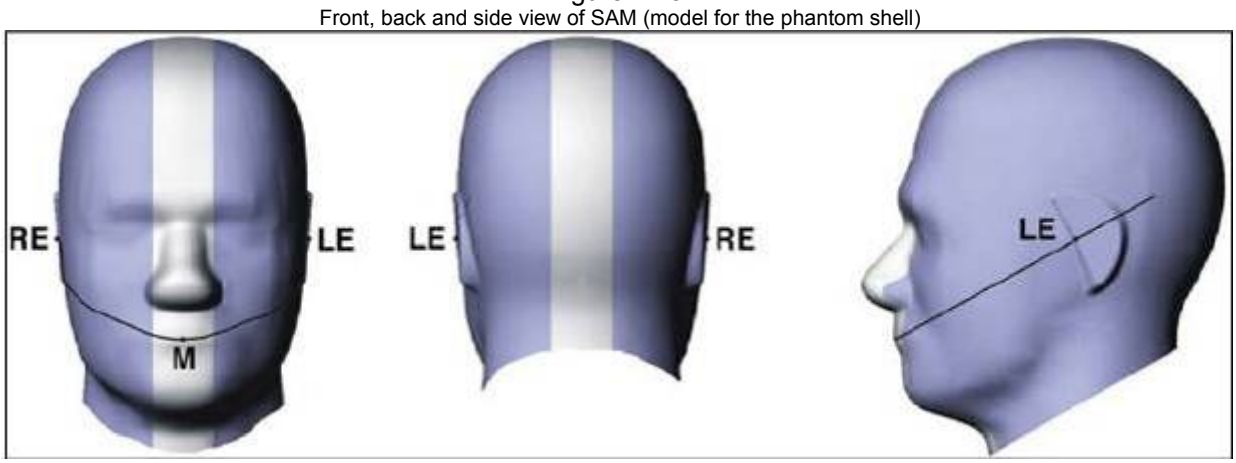

Figure 7-1b
Close up side view of phantom showing the ear region

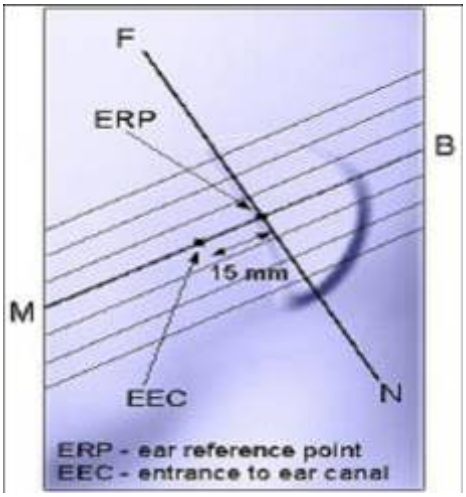

Figure 7-1c
Side view of the phantom showing relevant markings and the 7 cross sectional plane locations

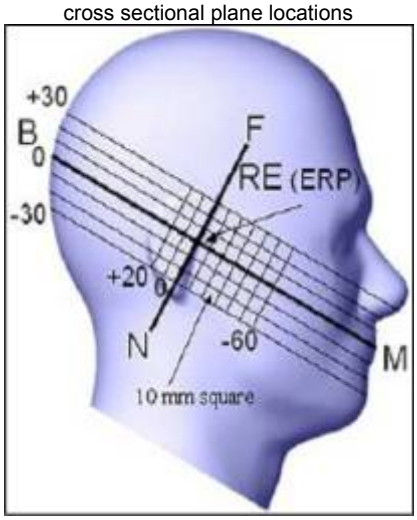

Figure 7-1b
Close up side view of phantom showing the ear region

Figure 7-1c
Side view of the phantom showing relevant markings and the 7 cross sectional plane locations

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10.2 DEFINITION OF THE "CHEEK/TOUCH" POSITION

The "cheek" or "touch" position is defined as follows:

a. Ready the handset for talk operation, if necessary. For example, for handsets with a cover piece, open the cover. (If the handset can also be used with the cover closed both configurations must be tested.)

b. Define two imaginary lines on the handset: the vertical centerline and the horizontal line. The vertical centerline passes through two points on the front side of the handset: the midpoint of the width wt of the handset at the level of the acoustic output (point A on Figures 7-2a and 7-2b), and the midpoint of the width wb of the bottom of the handset (point B). The horizontal line is perpendicular to the vertical centerline and passes through the center of the acoustic output (see Figure 7-2a). The two lines intersect at point A. Note that for many handsets, point A coincides with the center of the acoustic output. However, the acoustic output may be located elsewhere on the horizontal line. Also note that the vertical centerline is not necessarily parallel to the front face of the handset (see Figure 7-2b), especially for clamshell handsets, handsets with flip pieces, and other irregularly-shaped handsets.

c. Position the handset close to the surface of the phantom such that point A is on the (virtual) extension of the line passing through points RE and LE on the phantom (see Figure 7-2c), such that the plane defined by the vertical center line and the horizontal line of the handset is approximately parallel to the sagittal plane of the phantom.

d. Translate the handset towards the phantom along the line passing through RE and LE until the handset touches the pinna.

e. e) While maintaining the handset in this plane, rotate it around the LE-RE line until the vertical centerline is in the plane normal to MB-NF including the line MB (called the reference plane).

f. Rotate the handset around the vertical centerline until the handset (horizontal line) is symmetrical with respect to the line NF.

g. While maintaining the vertical centerline in the reference plane, keeping point A on the line passing through RE and LE and maintaining the handset contact with the pinna, rotate the handset about the line NF until any point on the handset is in contact with a phantom point below the pinna (cheek). See Figure 7-2c. The physical angles of rotation should be noted.

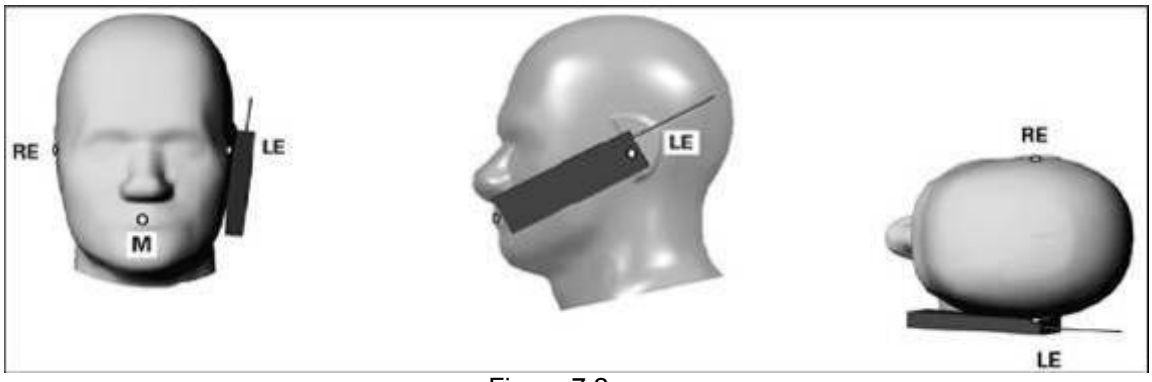

Figure 7.2c
Phone "cheek" or "touch" position. The reference points for the right ear (RE), left ear (LE) and mouth (M), which define the reference plane for handset positioning, are indicated.

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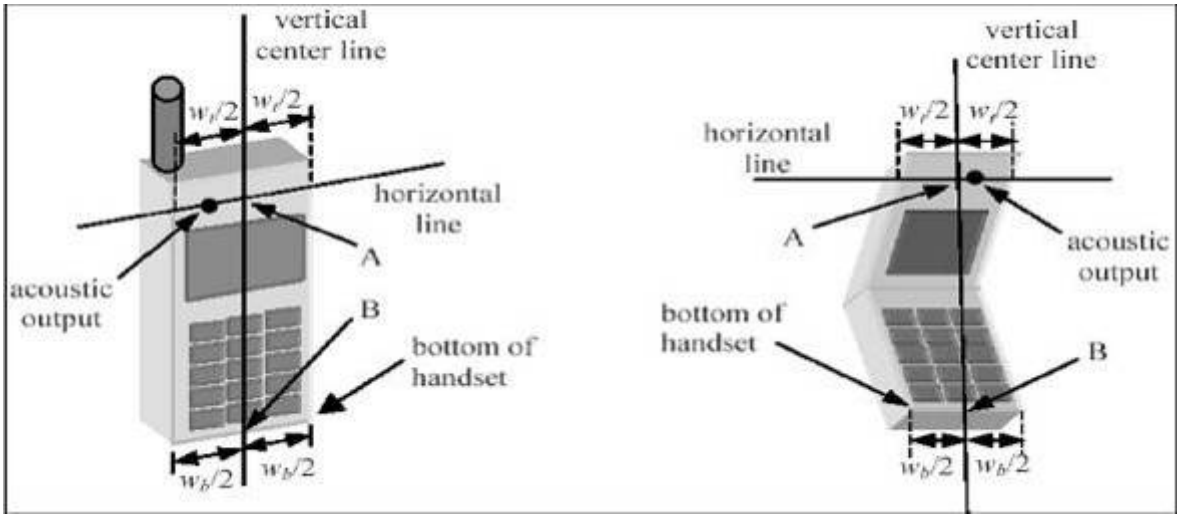

Figure 7.2a Figure 7.2b

10.3 DEFINITION OF THE "TILTED" POSITION

The "tilted" position is defined as follows:

a. Repeat steps (a) – (g) of 7.2 to place the device in the "cheek position."

b. While maintaining the orientation of the handset move the handset away from the pinna along the line passing through RE and LE in order to enable a rotation of the handset by 15 degrees.

c. Rotate the handset around the horizontal line by 15 degrees.

d. While maintaining the orientation of the handset, move the handset towards the phantom on a line passing through RE and LE until any part of the handset touches the ear. The tilted position is obtained when the contact is on the pinna. If the contact is at any location other than the pinna (e.g., the antenna with the back of the phantom head), the angle of the handset should be reduced. In this case, the tilted position is obtained if any part of the handset is in contact with the pinna as well as a second part of the handset is contact with the phantom (e.g., the antenna with the back of the head).

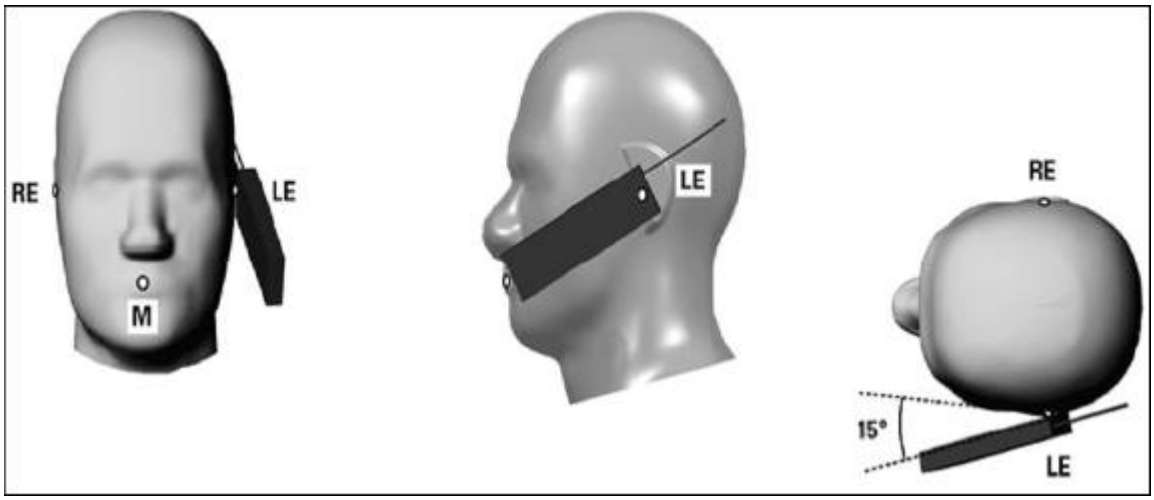

Figure 7-3
Phone "tilted" position. The reference points for the right ear (RE), left ear (LE) and mouth (M), which define the reference plane for handset positioning, are indicated.

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11. MEASUREMENT RESULTS

11.1 TEST LIQUIDS CONFIRMATION

SIMULATED TISSUE LIQUID PARAMETER CONFIRMATION

The dielectric parameters were checked prior to assessment using the HP85070C dielectric probe kit. The dielectric parameters measured are reported in each correspondent section.

KDB868664 D01 RECOMMENDED TISSUE DIELECTRIC PARAMETERS

The head and Body tissue dielectric parameters recommended by the KDB865664 D01 have been incorporated in the following table.

Target Frequency (MHz)	Head		Body	
	ε_r	σ (S/m)	ε_r	σ (S/m)
150	52.3	0.76	61.9	0.80
300	45.3	0.87	58.2	0.92
450	43.5	0.87	56.7	0.94
835	41.5	0.90	55.2	0.97
900	41.5	0.97	55.0	1.05
915	41.5	0.98	55.0	1.06
1450	40.5	1.20	54.0	1.30
1610	40.3	1.29	53.8	1.40
1800-2000	40.0	1.40	53.3	1.52
2450	39.2	1.80	52.7	1.95
3000	38.5	2.40	52.0	2.73
5800	35.3	5.27	48.2	6.00

(ε_r = relative permittivity, σ = conductivity and ρ = 1000 kg/m^3)

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11.2 LIQUID MEASUREMENT RESULTS

The following table show the measuring results for simulating liquid:

Liquid Type	Frequency	Liquid Temp. (°C)	Parameters	Target	Measured	Deviation (%)	Limited (%)	Measured Date
Body2450	2410	21.5	Permitivity(ε)	52.75	51.13	-3.07	± 5	2014-3-13
			Conductivity(σ)	1.90	1.94	2.04	± 5	
Body2450	2442	21.5	Permitivity(ε)	52.71	51.10	-3.06	± 5	2014-3-13
			Conductivity(σ)	1.94	1.96	1.16	± 5	
Body2450	2475	21.5	Permitivity(ε)	52.67	50.86	-3.43	± 5	2014-3-13
			Conductivity(σ)	1.98	2.01	1.29	± 5	

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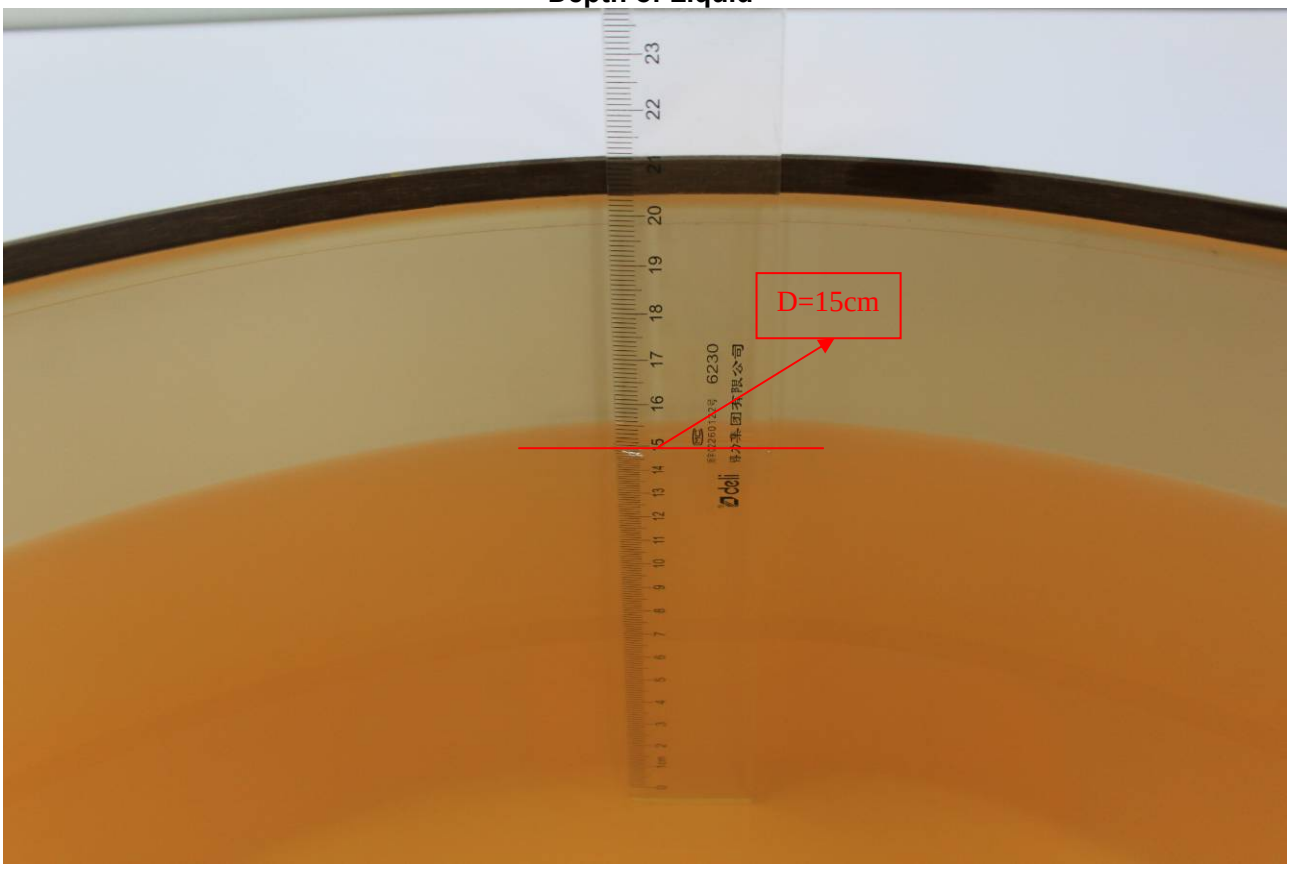
11.3 SYSTEM PERFORMANCE CHECK

The system performance check is performed prior to any usage of the system in order to guarantee reproducible results. The system performance check verifies that the system operates within its specifications of ±10%. The system performance check results are tabulated below. And also the corresponding SAR plot is attached as well in the SAR plots files.

SYSTEM PERFORMANCE CHECK MEASUREMENT CONDITIONS

- The measurements were performed in the flat section of the SAM twin phantom filled with head and body simulating liquid of the following parameters.
- The DASY5 system withan E-fileld probe EX3DV4 SN: 3798 was used for the measurements.
- The dipole was mounted on the small tripod so that the dipole feed point was positioned below the center marking of the flat phantom section and the dipole was oriented parallel to the body axis (the long side of the phantom). The standard measuring distance was 15 mm (below 1 GHz) and 10 mm (above 1 GHz) from dipole center to the simulating liquid surface.
- The coarse grid with a grid spacing of 10mm was aligned with the dipole.
- Special 7x7x7 fine cube was chosen for cube integration (dx= 5 mm, dy= 5 mm, dz= 5 mm).
- Distance between probe sensors and phantom surface was set to 2 mm.
- The dipole input power was 250mW±3%.
- The results are normalized to 1 W input power.

Depth of Liquid



- Note: For SAR testing, the depth is 15cm shown above

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SYSTEM PERFORMANCE CHECK RESULTS

Liquid Type	Ambient Temp. (° C)	Liquid Temp. (°C)	Input Power (W)	Measured SAR_{1g} (W/Kg)	1W Target SAR_{1g}(W/Kg)	1W Normalized SAR_{1g}(W/Kg)	Deviation (%)	Limited (%)	Date
Body2450	22	21.5	0.25	12.20	49.20	48.80	-0.81	± 10	2014-3-13

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11.4 EUT TUNE-UP PROCEDURES AND TEST MODE

The following procedure had been used to prepare the EUT for the SAR test.

Conducted output power(dBm):

Mode	Channel	Frequence	Average power(dBm)
GFSK 2.4Ghz	**0**	**2412 MHZ**	13.95
	9	**2437 MHZ**	14.37
	18	**2462 MHZ**	**14.55**

Mode	The Tune-up Maximum Power(Customer Declared)(dBm)	Range	Measured Conduct Maximum Power(dBm)
GFSK 2.4Ghz	14.5+/-1	13.5~15.5	14.55

So, they are in tune-up range and complied.

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11.5 SAR TEST CONFIGURATIONS

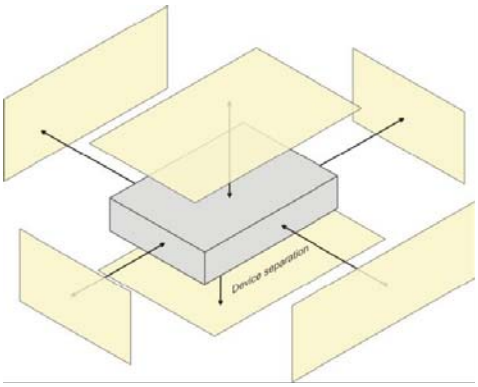
Generic device Exposure Conditions

For a device that can not be categorized as any of the other specific device , it shall be considered to be a generic device; i.e. represented by a closed box incorporating at least one internal RF transmitter and antenna.

The SAR evaluation shall be performed for all surfaces of the DUT that are accessible during intended use, as indicated in Figure . The separation distance in testing shall correspond to the intended use distance as specified in the user instructions provided by the manufacturer. If the intended use is not specified, all surfaces of the DUT shall be tested directly against the flat phantom.

The surface of the generic device (or the surface of the carry accessory holding the DUT) pointing towards the flat phantom shall be parallel to the surface of the phantom.

The generic device principle may be applied to all devices. Where the antenna or the attached RF transmitter is external to the host and the positioning of the antenna or attached RF transmitter is independent of positioning of the host, e.g. transmitter is attached by a cable, it shall be assessed using the generic device procedures.



Test positions for a generic device

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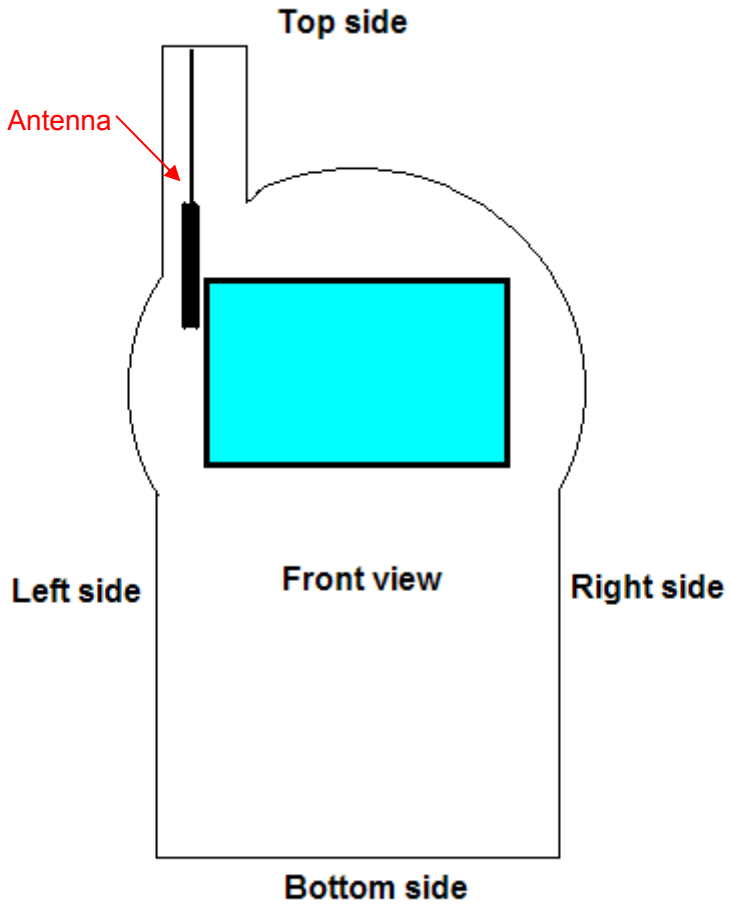
Antenna Position



Device dimensions (H x W): 143 x 75 mm

Antennas	Wireless Interface
TX Antenna	GFSK 2.4GHz

Test Mode

GFSK 2.4GHz	Data transmission mode(2.4Ghz)

Body Exposure Condition for GFSK 2.4GHz

Distance of the Antenna to the EUT surface/edge Test distance: 10 mm						
Antenna	Front (mm)	Rear (mm)	Top side (mm)	Bottom side (mm)	Right side (mm)	Left side (mm)
WWAN	12	6	3	83	72	3

Body test position for GFSK 2.4GHz

Distance of the Antenna to the EUT surface/edge Test distance: 10 mm						
Antenna	Front	Rear	Top side	Bottom side	Right sid	Left side
WWAN	Yes	Yes	Yes	Yes	Yes	Yes

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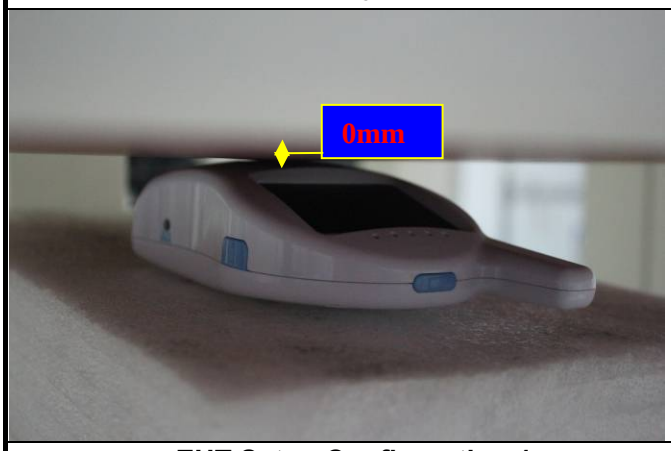
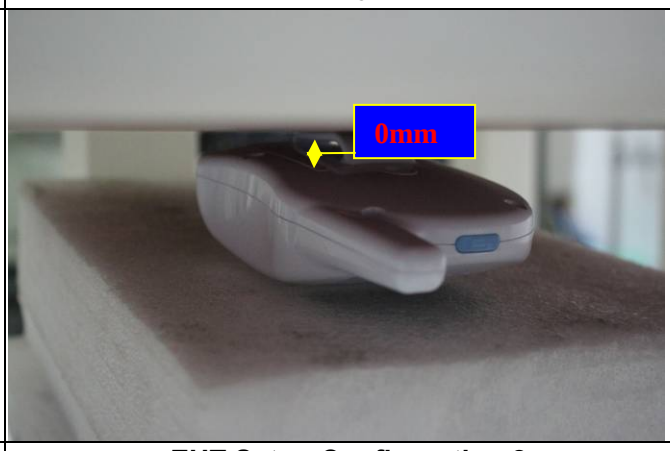
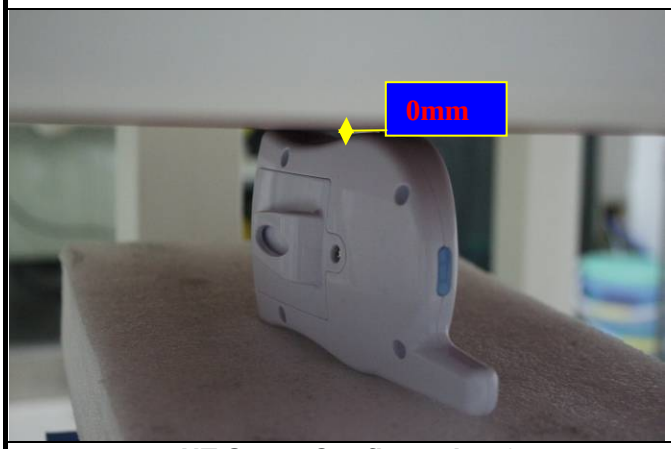
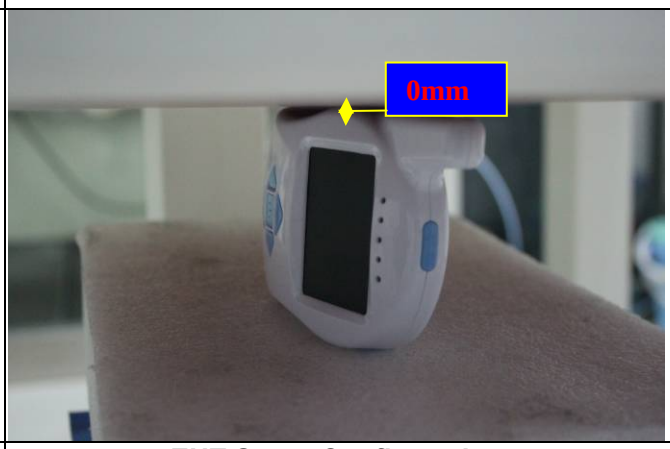
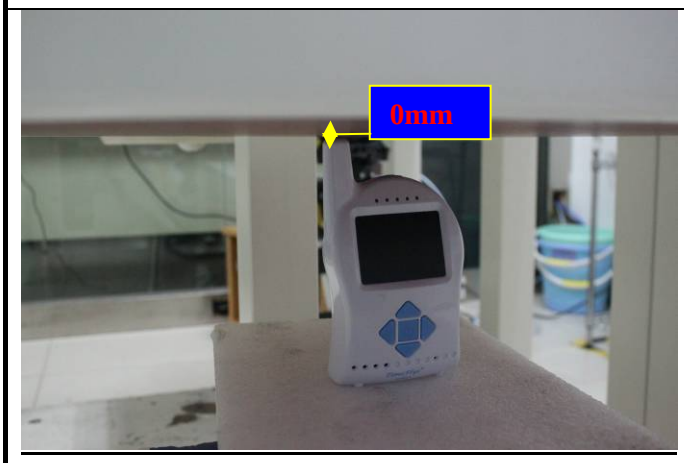
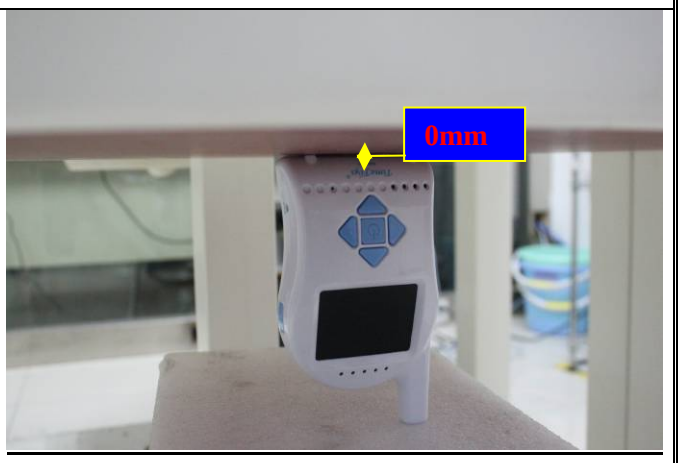
11.6 EUT SETUP PHOTOS

Front in body position	Rear in body position
	
EUT Setup Configuration 1	**EUT Setup Configuration 2**
Right Side in body position	**Left Side in body position**
	
UT Setup Configuration 3	**EUT Setup Configuration 4**
Top Side in body position	**Bottom Side in body position**
	
UT Setup Configuration 5	**EUT Setup Configuration 6**

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11.7 SAR MEASUREMENT RESULTS

Band	Mode	Test Position	Dist. (mm)	Ch.	Freq. (MHZ)	max Power (dBm)	Tune-Up Limit (dBm)	Scaling Factor	Power Drift (dB)	SAR1g (mW/g)	Scaled SAR1g (mW/g)
2.4Ghz	GFSK	Front	0	18	2475	14.55	15.5	1.245	-0.00	0.132	0.164
2.4Ghz	GFSK	Rear	0	18	2475	14.55	15.5	1.245	-0.03	0.159	0.198
2.4Ghz	GFSK	Right	0	18	2475	14.55	15.5	1.245	0.05	0.037	0.046
2.4Ghz	GFSK	Left	0	0	2409.75	13.95	15.5	1.429	-0.08	0.645	**0.922**
2.4Ghz	GFSK	Left	0	9	2442.38	14.57	15.5	1.239	-0.07	0.685	0.849
2.4Ghz	GFSK	Left	0	18	2475	14.55	15.5	1.245	-0.05	0.616	0.767
2.4Ghz	GFSK	Top	0	18	2475	14.55	15.5	1.245	0.09	0.093	0.116
2.4Ghz	GFSK	Bottom	0	18	2475	14.55	15.5	1.245	0.14	0.043	0.054

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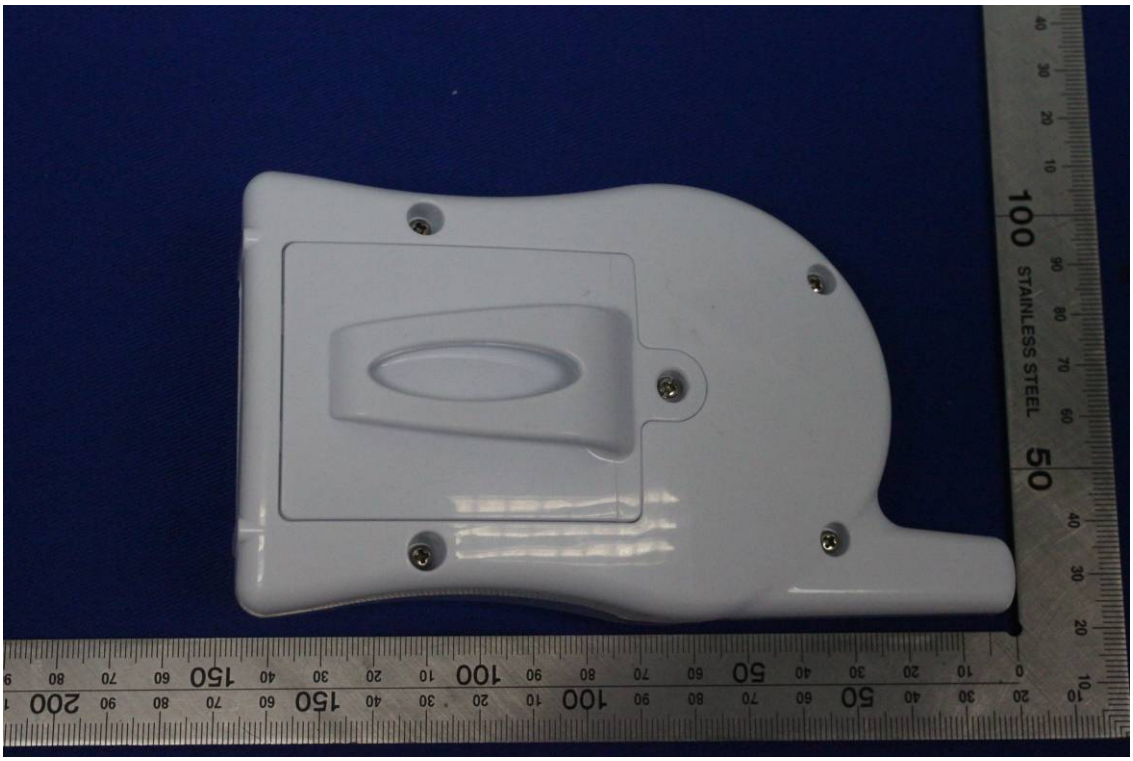
12. EUT PHOTO



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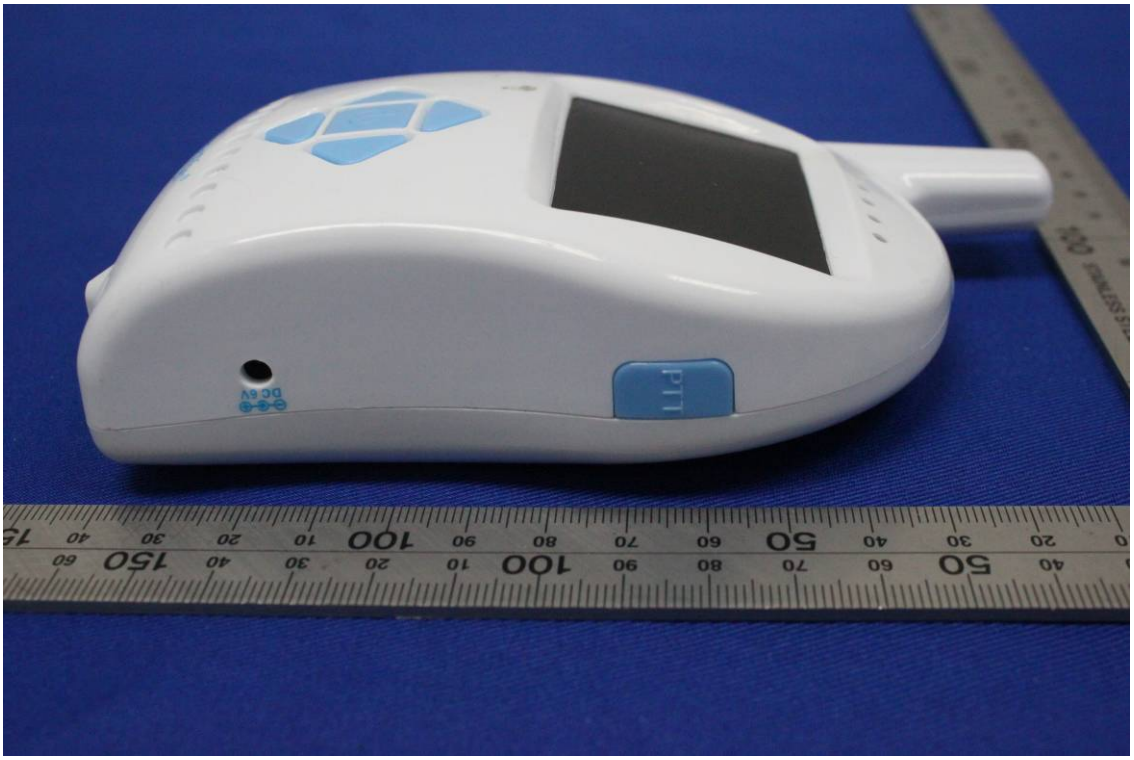

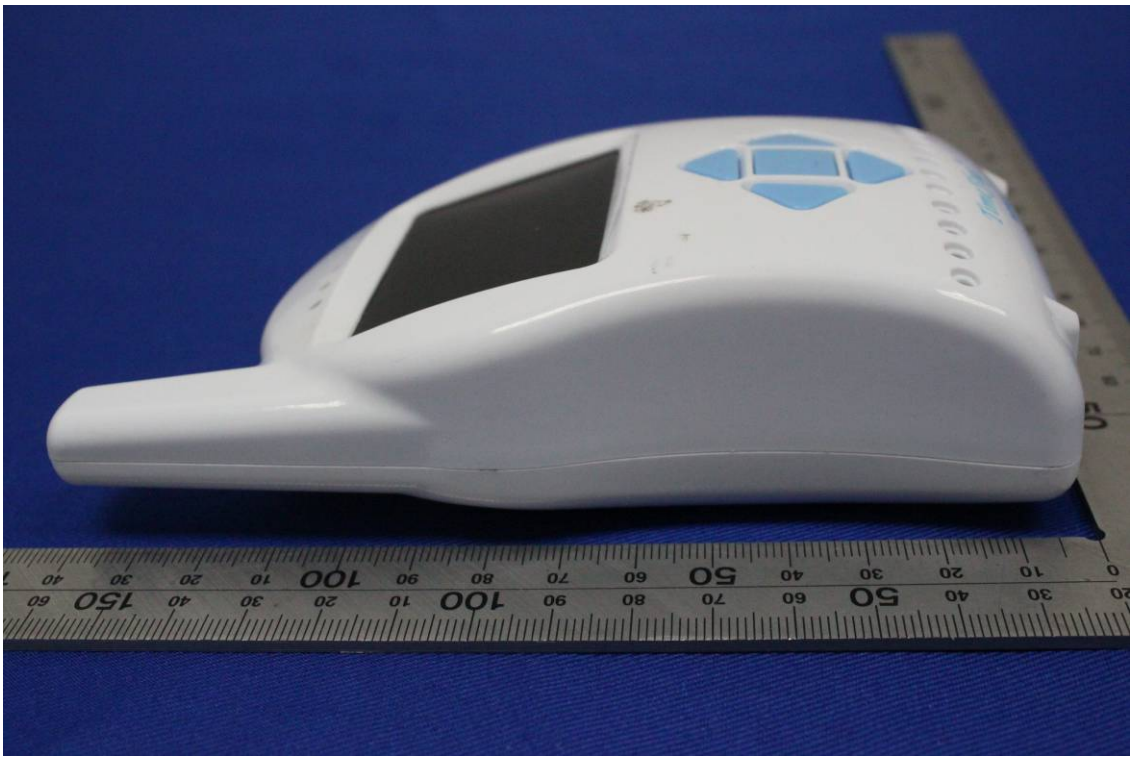

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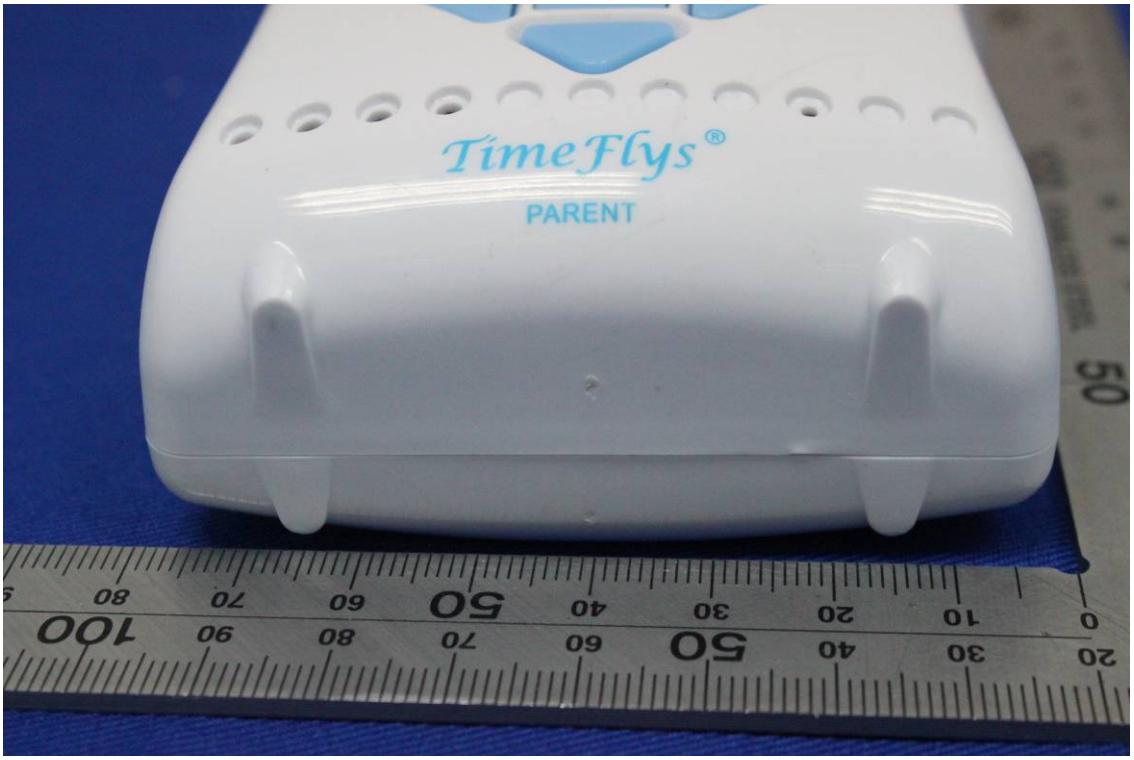

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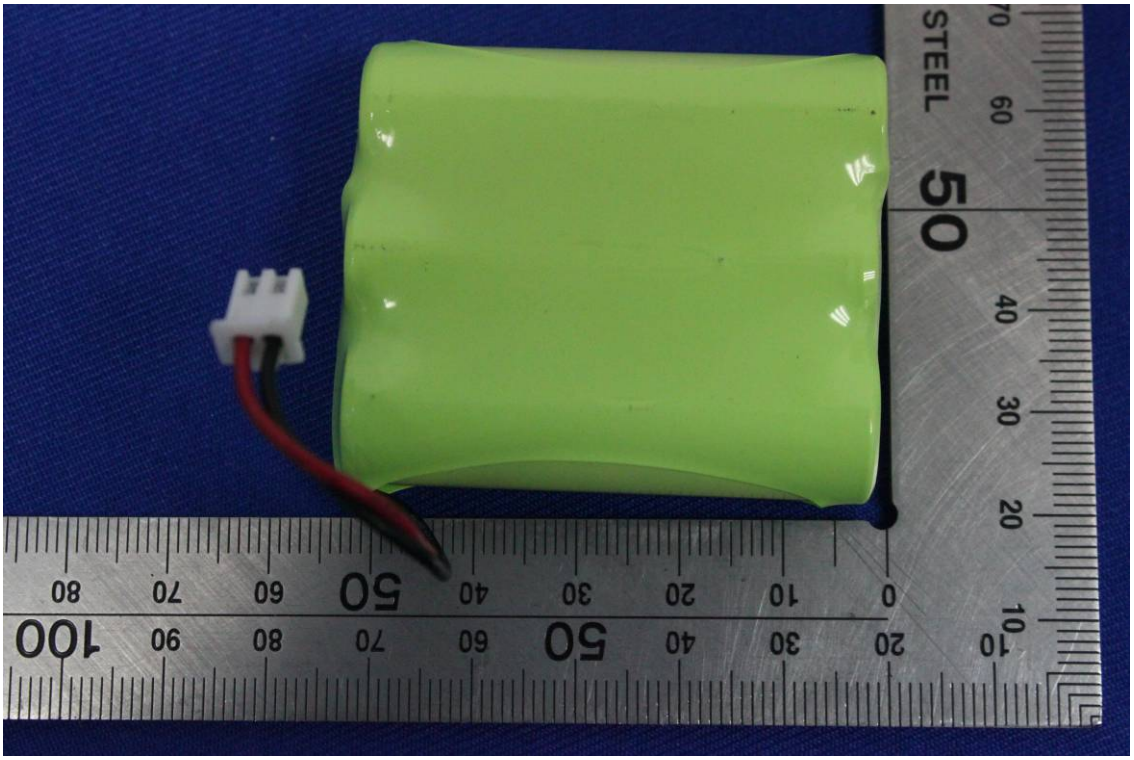

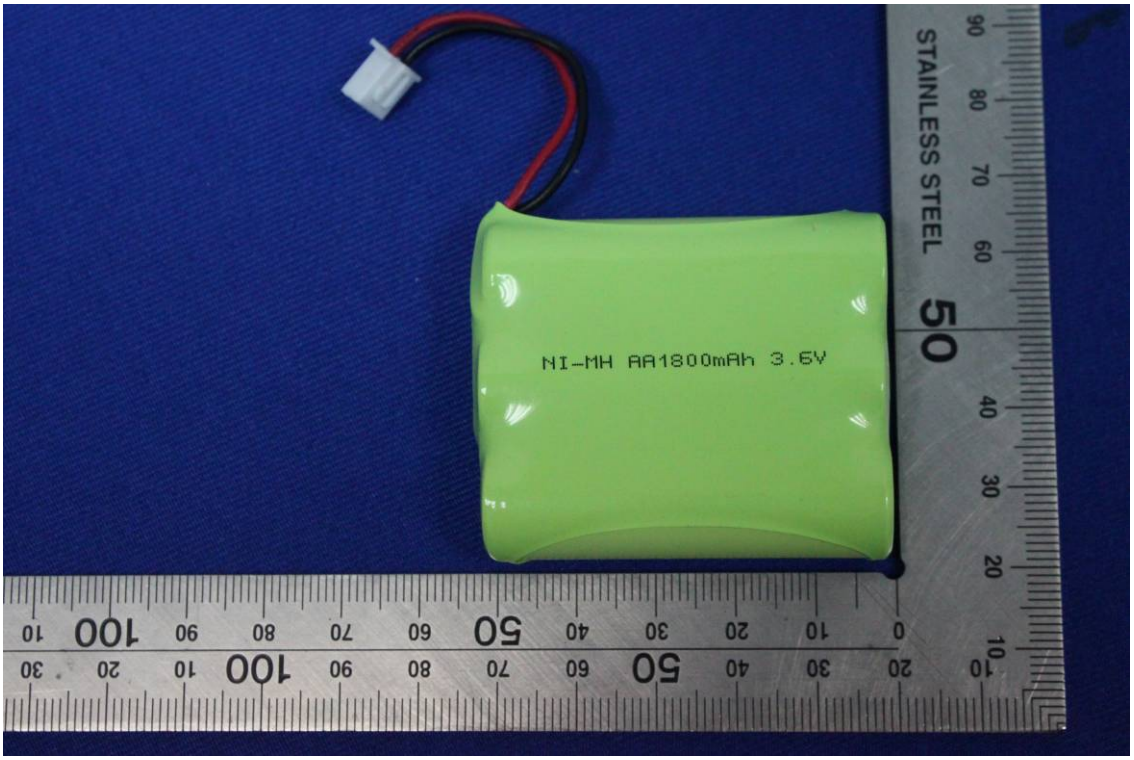

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13. EQUIPMENT LIST & CALIBRATION STATUS

Name of Equipment	Manufacturer	Type/Model	Serial Number	Last Calibration	Calibration Due
P C	HP	Core(rm)3.16G	CZCO48171H	N/A	N/A
Signal Generator	Agilent	E8257C	MY43321570	05/13/2013	05/12/2014
S-Parameter Network Analyzer	Agilent	E5071B	MY42301382	03/11/2013	03/10/2014
Power Meter	Agilent	E4416A	GB41292714	03/16/2013	03/15/2014
Peak & Average sensor	Agilent	E9327A	CF0001	03/16/2013	03/15/2014
E-field PROBE	SPEAG	EX3DV4	3798	07/26/2013	07/25/2014
DAE	SPEAG	DEA4	1245	07/25/2013	07/24/2014
DIPOLE 2450MHZ ANTENNA	SPEAG	D2450V2	817	07/31/2013	07/30/2014
DUMMY PROBE	SPEAG	DP_2	SPDP2001AA	N/A	N/A
SAM PHANTOM (ELI4 v4.0)	SPEAG	QDOVA001BB	1102	N/A	N/A
Twin SAM Phantom	SPEAG	QD000P40CD	1609	N/A	N/A
ROBOT	SPEAG	TX60	F10/5E6AA1/A101	N/A	N/A
ROBOT KRC	SPEAG	CS8C	F10/5E6AA1/C101	N/A	N/A
LIQUID CALIBRATION KIT	ANTENNESSA	41/05 OCP9	00425167	N/A	N/A

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14. FACILITIES

All measurement facilities used to collect the measurement data are located at

☒ No.10, Weiye Rd., Innovation Park, Eco & Tec. Development Part, Kunshan City, Jiangsu Province, China.

15. REFERENCES

[1] Federal Communications Commission, \Report and order: Guidelines for evaluating the environ-mental effects of radiofrequency radiation", Tech. Rep. FCC 96-326, FCC, Washington, D.C. 20554, 1996.

[2] David L. Means Kwok Chan, Robert F. Cleveland, \Evaluating compliance with FCC guidelines for human exposure to radiofrequency electromagnetic fields", Tech. Rep., Federal Communication Commision, O_ce of Engineering & Technology, Washington, DC, 1997.

[3] Thomas Schmid, Oliver Egger, and Niels Kuster, \Automated E-_eld scanning system for dosimetric assessments", IEEE Transactions on Microwave Theory and Techniques, vol. 44, pp. 105{113, Jan. 1996.

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16. ATTACHMENTS

Exhibit	Content
1	System Performance Check Plots
2	Dipole calibration report D2450V2 SN: 817
3	Probe calibration report EX3DV4 SN3798
4	DAE calibration report DEA4 SD000D04BJ SN:1245
5	SAR Test Plots

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APPENDIX A: PLOTS OF PERFORMANCE CHECK

The plots are showing as followings.

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Test Laboratory: Compliance Certification Services Inc. Date: 3/13/2014

System Performance Check-Body D2450

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: 817

Communication System: CW; Communication System Band: D2450 (2450.0 MHz); Frequency: 2450 MHz;Duty Cycle: 1:1

Medium parameters used: f = 2450 MHz; σ = 1.969 S/m; ε_r = 51.052; ρ = 1000 kg/m^3

Room Ambient Temperature: 22°C; Liquid Temperature: 21.5°C

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY Configuration:

- Probe: EX3DV4 - SN3798; ConvF(7.08, 7.08, 7.08); Calibrated: 7/26/2013;
- Sensor-Surface: 2mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1245; Calibrated: 7/25/2013
- Phantom: ELI v4.0; Type: QDOVA001BB; Serial: 1102
- DASY52 52.8.5(1059);
- SEMCAD X Version 14.6.8 (7028)

System Performance Check at Frequencies above 1 GHz/d=10mm, Pin=250 mW, dist=2.0mm (EX-Probe)/Area Scan (8x9x1): Measurement grid: dx=12mm, dy=12mm

Maximum value of SAR (measured) = 18.0 W/kg

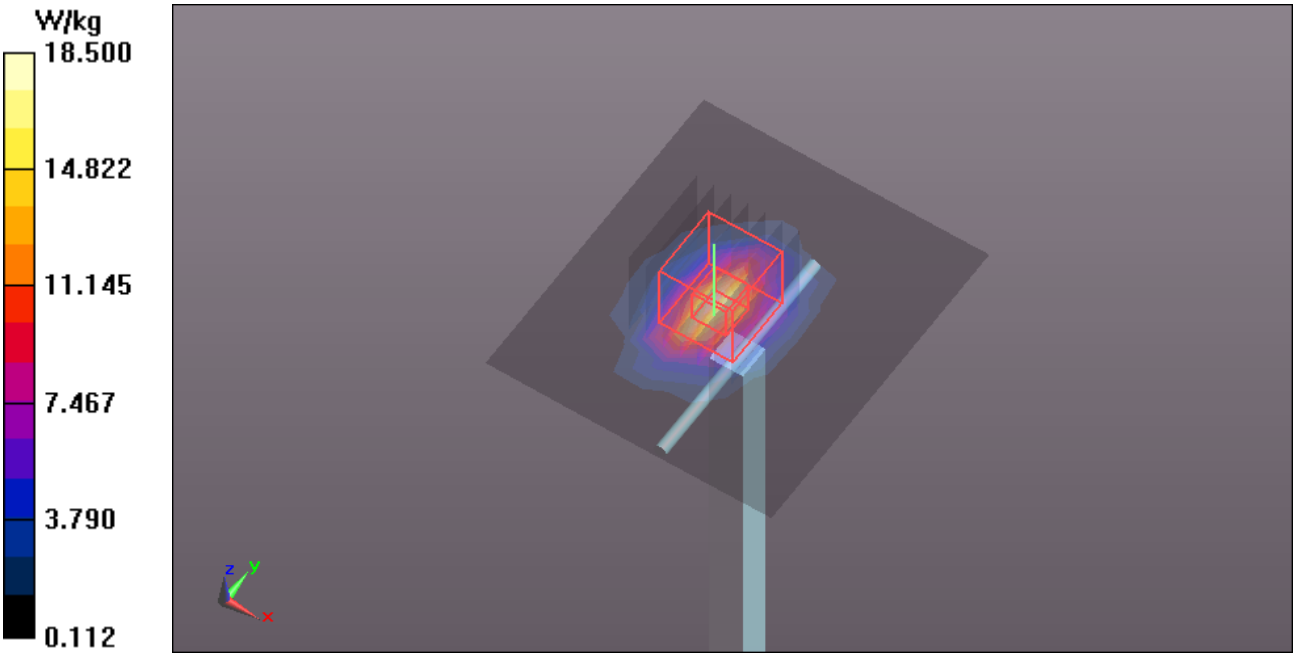
System Performance Check at Frequencies above 1 GHz/d=10mm, Pin=250 mW, dist=2.0mm (EX-Probe)/Zoom Scan (7x7x7) (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 94.083 V/m; Power Drift = -0.16 dB

Peak SAR (extrapolated) = 25.4 W/kg

SAR(1 g) = 12.2 W/kg; SAR(10 g) = 5.69 W/kg

Maximum value of SAR (measured) = 18.5 W/kg



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APPENDIX B: DASY CALIBRATION CERTIFICATE

The DASY Calibration Certificates are showing as followings .

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Accredited by the Swiss Accreditation Service (SAS)
The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client CCS-CN (Auden)

Certificate No: D2450V2-817_Jul13

CALIBRATION CERTIFICATE

Object	D2450V2 - SN: 817
Calibration procedure(s)	QA CAL-05.v9 Calibration procedure for dipole validation kits above 700 MHz
Calibration date:	July 31, 2013

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter EPM-442A	GB37480704	01-Nov-12 (No. 217-01640)	Oct-13
Power sensor HP 8481A	US37292783	01-Nov-12 (No. 217-01640)	Oct-13
Reference 20 dB Attenuator	SN: 5058 (20k)	04-Apr-13 (No. 217-01736)	Apr-14
Type-N mismatch combination	SN: 5047.3 / 06327	04-Apr-13 (No. 217-01739)	Apr-14
Reference Probe ES3DV3	SN: 3205	28-Dec-12 (No. ES3-3205_Dec12)	Dec-13
DAE4	SN: 601	25-Apr-13 (No. DAE4-601_Apr13)	Apr-14

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (in house check Oct-11)	In house check: Oct-13
RF generator R&S SMT-06	100005	04-Aug-99 (in house check Oct-11)	In house check: Oct-13
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (in house check Oct-12)	In house check: Oct-13

	Name	Function	Signature
Calibrated by:	Israe El-Naouq	Laboratory Technician	Israe El-Naouq
Approved by:	Katja Pokovic	Technical Manager	

Issued: July 31, 2013

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Calibration Laboratory of
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Accreditation No.: SCS 108

Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005
c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields; Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

Additional Documentation:

d) DASY4/5 System Handbook

Methods Applied and Interpretation of Parameters:

- *Measurement Conditions:* Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- *Antenna Parameters with TSL:* The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- *Feed Point Impedance and Return Loss:* These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- *SAR measured:* SAR measured at the stated antenna input power.
- *SAR normalized:* SAR as measured, normalized to an input power of 1 W at the antenna connector.
- *SAR for nominal TSL parameters:* The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

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Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY5	V52.8.7
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	2450 MHz ± 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	37.8 ± 6 %	1.81 mho/m ± 6 %
Head TSL temperature change during test	< 0.5 °C	----	----

SAR result with Head TSL

SAR averaged over 1 cm³ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	13.3 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	**52.6 W/kg ± 17.0 % (k=2)**

SAR averaged over 10 cm³ (10 g) of Head TSL	condition	
SAR measured	250 mW input power	6.18 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	**24.5 W/kg ± 16.5 % (k=2)**

Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.0 ± 0.2) °C	50.5 ± 6 %	2.01 mho/m ± 6 %
Body TSL temperature change during test	< 0.5 °C	----	----

SAR result with Body TSL

SAR averaged over 1 cm³ (1 g) of Body TSL	Condition	
SAR measured	250 mW input power	12.6 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	**49.2 W/kg ± 17.0 % (k=2)**

SAR averaged over 10 cm³ (10 g) of Body TSL	condition	
SAR measured	250 mW input power	5.87 W/kg
SAR for nominal Body TSL parameters	normalized to 1W	**23.1 W/kg ± 16.5 % (k=2)**

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Appendix

Antenna Parameters with Head TSL

Impedance, transformed to feed point	53.5 Ω + 2.9 jΩ
Return Loss	- 27.1 dB

Antenna Parameters with Body TSL

Impedance, transformed to feed point	49.7 Ω + 4.5 jΩ
Return Loss	- 27.0 dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.159 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.
No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG
Manufactured on	October 23, 2007

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DASY5 Validation Report for Head TSL

Date: 31.07.2013

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 817

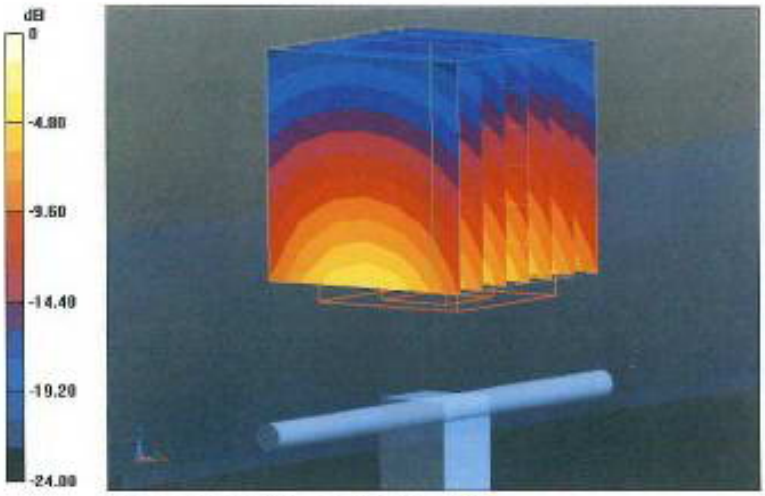
Communication System: UID 0 - CW; Frequency: 2450 MHz
Medium parameters used: f = 2450 MHz; σ = 1.81 S/m; ε_r = 37.8; ρ = 1000 kg/m^3
Phantom section: Flat Section
Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY52 Configuration:

- Probe: ES3DV3 - SN3205; ConvF(4.52, 4.52, 4.52); Calibrated: 28.12.2012;
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 25.04.2013
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA; Serial: 1001
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

Dipole Calibration for Head Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 99.781 V/m; Power Drift = 0.06 dB
Peak SAR (extrapolated) = 27.7 W/kg
SAR(1 g) = 13.3 W/kg; SAR(10 g) = 6.18 W/kg
Maximum value of SAR (measured) = 16.8 W/kg



0 dB = 16.8 W/kg = 12.25 dBW/kg

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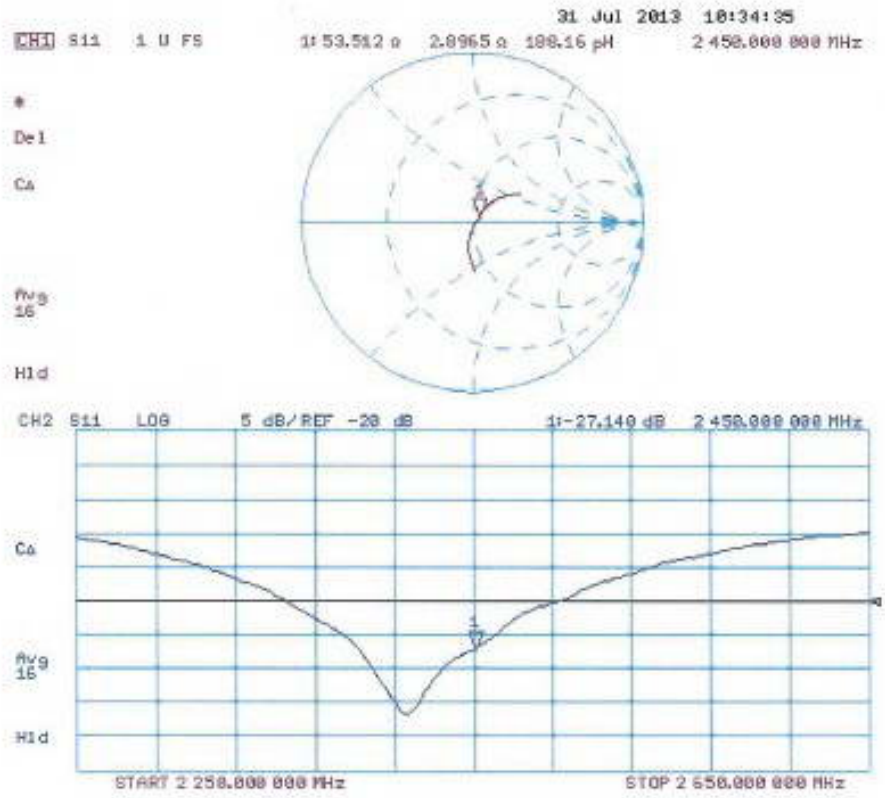
Impedance Measurement Plot for Head TSL



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DASY5 Validation Report for Body TSL

Date: 31.07.2013

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN: 817

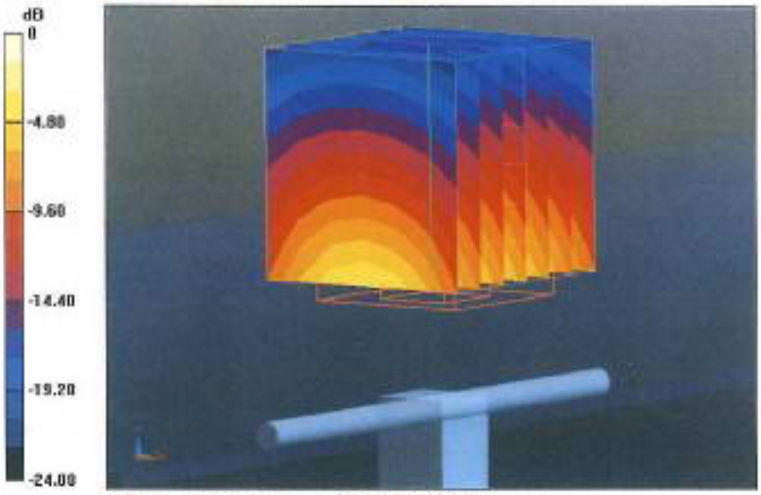
Communication System: UID 0 - CW; Frequency: 2450 MHz
Medium parameters used: f = 2450 MHz; σ = 2.01 S/m; ε_r = 50.5; ρ = 1000 kg/m^3
Phantom section: Flat Section
Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2007)

DASY52 Configuration:

- Probe: ES3DV3 - SN3205; ConvF(4.42, 4.42, 4.42); Calibrated: 28.12.2012;
- Sensor-Surface: 3mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 25.04.2013
- Phantom: Flat Phantom 5.0 (back); Type: QD000P50AA; Serial: 1002
- DASY52 52.8.7(1137); SEMCAD X 14.6.10(7164)

Dipole Calibration for Body Tissue/Pin=250 mW, d=10mm/Zoom Scan (7x7x7)/Cube 0:

Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 94.151 V/m; Power Drift = 0.06 dB
Peak SAR (extrapolated) = 26.3 W/kg
SAR(1 g) = 12.6 W/kg; SAR(10 g) = 5.87 W/kg
Maximum value of SAR (measured) = 16.7 W/kg



0 dB = 16.7 W/kg = 12.23 dBW/kg

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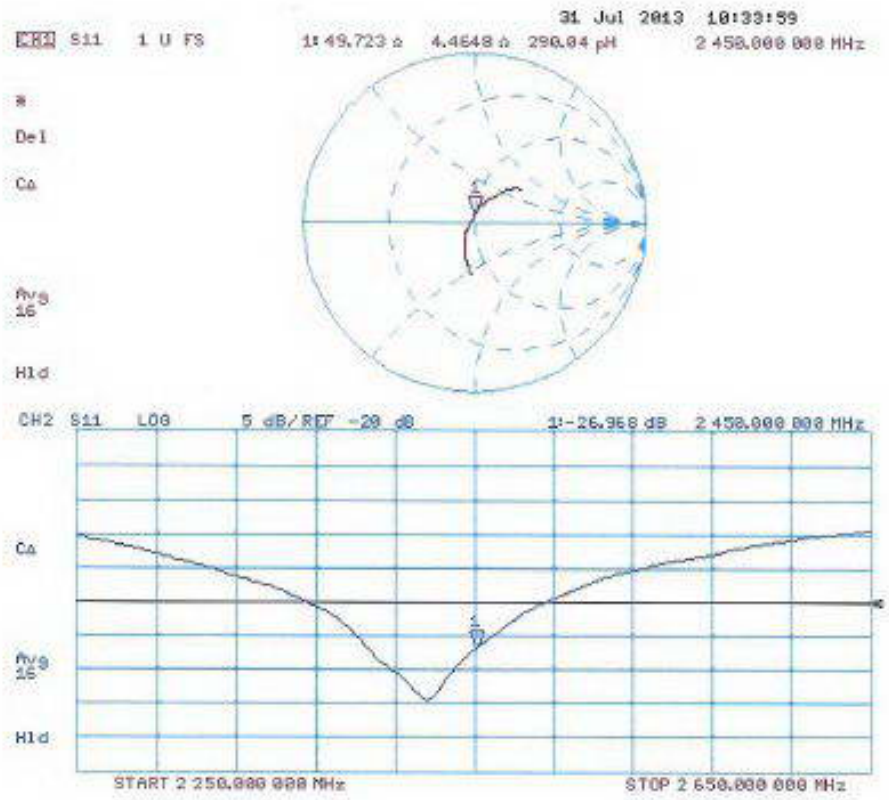
Impedance Measurement Plot for Body TSL



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Schmid & Partner Engineering AG

s p e a g

Zeughausstrasse 43, 8004 Zurich, Switzerland
Phone +41 44 245 9700, Fax +41 44 245 9779
info@speag.com, http://www.speag.com

1245

IMPORTANT NOTICE

USAGE OF THE DAE 4

The DAE unit is a delicate, high precision instrument and requires careful treatment by the user. There are no serviceable parts inside the DAE. Special attention shall be given to the following points:

Battery Exchange: The battery cover of the DAE4 unit is closed using a screw, over tightening the screw may cause the threads inside the DAE to wear out.

Shipping of the DAE: Before shipping the DAE to SPEAG for calibration, remove the batteries and pack the DAE in an antistatic bag. This antistatic bag shall then be packed into a larger box or container which protects the DAE from impacts during transportation. The package shall be marked to indicate that a fragile instrument is inside.

E-Stop Failures: Touch detection may be malfunctioning due to broken magnets in the E-stop. Rough handling of the E-stop may lead to damage of these magnets. Touch and collision errors are often caused by dust and dirt accumulated in the E-stop. To prevent E-stop failure, the customer shall always mount the probe to the DAE carefully and keep the DAE unit in a non-dusty environment if not used for measurements.

Repair: Minor repairs are performed at no extra cost during the annual calibration. However, SPEAG reserves the right to charge for any repair especially if rough unprofessional handling caused the defect.

DASY Configuration Files: Since the exact values of the DAE input resistances, as measured during the calibration procedure of a DAE unit, are not used by the DASY software, a nominal value of 200 MOhm is given in the corresponding configuration file.

Important Note:
Warranty and calibration is void if the DAE unit is disassembled partly or fully by the Customer.

Important Note:
Never attempt to grease or oil the E-stop assembly. Cleaning and readjusting of the E-stop assembly is allowed by certified SPEAG personnel only and is part of the annual calibration procedure.

Important Note:
To prevent damage of the DAE probe connector pins, use great care when installing the probe to the DAE. Carefully connect the probe with the connector notch oriented in the mating position. Avoid any rotational movement of the probe body versus the DAE while turning the locking nut of the connector. The same care shall be used when disconnecting the probe from the DAE.

Schmid & Partner Engineering

TN_BR040315AD DAE4.doc 11.12.2009

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Accreditation No.: SCS 108

Client CCS-CN (Auden)

Certificate No: DAE4-1245_Jul13

CALIBRATION CERTIFICATE

Object	DAE4 - SD 000 D04 BM - SN: 1245
Calibration procedure(s)	QA CAL-06.v26 Calibration procedure for the data acquisition electronics (DAE)
Calibration date:	July 25, 2013

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	02-Oct-12 (No:12728)	Oct-13
Secondary Standards	**ID #**	**Check Date (in house)**	**Scheduled Check**
Auto DAE Calibration Unit	SE UWS 053 AA 1001	07-Jan-13 (in house check)	In house check: Jan-14
Calibrator Box V2.1	SE UMS 006 AA 1002	07-Jan-13 (in house check)	In house check: Jan-14

	Name	Function	Signature
Calibrated by:	Dominique Steffen	Technician	
Approved by:	Fin Bomholt	Deputy Technical Manager	i.V.

Issued: July 25, 2013

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Accreditation No.: SCS 108

Glossary

DAE	data acquisition electronics
Connector angle	information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle*: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
  - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
  - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
  - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
  - *AD Converter Values with Inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
  - *Input Offset Measurement*: Output voltage and statistical results over a large number of zero voltage measurements.
  - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
  - *Input resistance:* Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
  - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
  - *Power consumption:* Typical value for information. Supply currents in various operating modes.

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DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1μV , full range = -100...+300 mV

Low Range: 1LSB = 61nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	405.940 ± 0.02% (k=2)	404.664 ± 0.02% (k=2)	405.801 ± 0.02% (k=2)
Low Range	4.00386 ± 1.50% (k=2)	3.98278 ± 1.50% (k=2)	4.02487 ± 1.50% (k=2)

Connector Angle

Connector Angle to be used in DASY system	30.5 ° ± 1 °

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Appendix

1. DC Voltage Linearity

High Range		Reading (μV)	Difference (μV)	Error (%)
Channel X	+ Input	199992.97	-4.47	-0.00
Channel X	+ Input	20001.91	0.89	0.00
Channel X	- Input	-19999.11	1.66	-0.01
Channel Y	+ Input	199994.30	-3.32	-0.00
Channel Y	+ Input	20001.64	0.75	0.00
Channel Y	- Input	-20000.51	0.28	-0.00
Channel Z	+ Input	199995.90	-1.30	-0.00
Channel Z	+ Input	20000.30	-0.60	-0.00
Channel Z	- Input	-19999.90	0.89	-0.00

Low Range		Reading (μV)	Difference (μV)	Error (%)
Channel X	+ Input	2001.51	0.38	0.02
Channel X	+ Input	201.72	0.21	0.11
Channel X	- Input	-198.76	-0.28	0.14
Channel Y	+ Input	2000.72	-0.41	-0.02
Channel Y	+ Input	199.98	-1.50	-0.74
Channel Y	- Input	-198.85	-0.28	0.14
Channel Z	+ Input	2000.21	-0.84	-0.04
Channel Z	+ Input	200.77	-0.56	-0.28
Channel Z	- Input	-199.95	-1.29	0.65

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	-8.24	-10.01
	- 200	10.27	8.63
Channel Y	200	-7.32	-7.74
	- 200	6.53	6.34
Channel Z	200	-5.94	-6.42
	- 200	5.13	4.65

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	4.16	-2.61
Channel Y	200	8.79	-	3.99
Channel Z	200	9.96	7.22	-

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4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15874	16183
Channel Y	16451	15694
Channel Z	15932	15717

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec
Input 10MΩ

	Average (μV)	min. Offset (μV)	max. Offset (μV)	Std. Deviation (μV)
Channel X	0.94	-0.24	2.04	0.48
Channel Y	-0.42	-1.91	0.54	0.47
Channel Z	-0.83	-2.62	0.57	0.60

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	–0.01	-8	-9

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Calibration Laboratory of
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Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland

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Accredited by the Swiss Accreditation Service (SAS)
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Accreditation No.: SCS 108

Client CCS-CN (Auden)

Certificate No: EX3-3798_Jul13

CALIBRATION CERTIFICATE

Object	EX3DV4 - SN:3798
Calibration procedure(s)	QA CAL-01.v8, QA CAL-14.v3, QA CAL-23.v4, QA CAL-25.v4 Calibration procedure for dosimetric E-field probes
Calibration date:	July 26, 2013

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	04-Apr-13 (No. 217-01733)	Apr-14
Power sensor E4412A	MY41498087	04-Apr-13 (No. 217-01733)	Apr-14
Reference 3 dB Attenuator	SN: S5054 (3c)	04-Apr-13 (No. 217-01737)	Apr-14
Reference 20 dB Attenuator	SN: S5277 (20x)	04-Apr-13 (No. 217-01735)	Apr-14
Reference 30 dB Attenuator	SN: S5129 (30b)	04-Apr-13 (No. 217-01738)	Apr-14
Reference Probe ES3DV2	SN: 3013	28-Dec-12 (No. ES3-3013_Dec12)	Dec-13
DAE4	SN: 660	31-Jan-13 (No. DAE4-660_Jan13)	Jan-14
Secondary Standards	**ID**	**Check Date (in house)**	**Scheduled Check**
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Apr-13)	In house check: Apr-15
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-12)	In house check: Oct-13

	Name	Function	Signature
Calibrated by:	Dimce Iliev	Laboratory Technician	D. Iliev
Approved by:	Katja Pokovic	Technical Manager	

Issued: July 26, 2013

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Accreditation No.: SCS 108

Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConvF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., ϑ = 0 is normal to probe axis

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) IEC 62209-1, "Procedure to measure the Specific Absorption Rate (SAR) for hand-held devices used in close proximity to the ear (frequency range of 300 MHz to 3 GHz)", February 2005

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization ϑ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not affect the E^2-field uncertainty inside TSL (see below *ConvF*).
- *NORM(f)x,y,z = NORMx,y,z * frequency_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of *ConvF*.
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- *PAR:* PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- *Ax,y,z; Bx,y,z; Cx,y,z; Dx,y,z; VRx,y,z: A, B, C, D* are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. *VR* is the maximum calibration range expressed in RMS voltage across the diode.
- *ConvF and Boundary Effect Parameters:* Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z * ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- *Spherical isotropy (3D deviation from isotropy)*: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- *Sensor Offset*: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

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Probe EX3DV4

SN:3798

Manufactured: April 5, 2011
Calibrated: July 26, 2013

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

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DASY/EASY - Parameters of Probe: EX3DV4 - SN:3798

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu V/(V/m)^2$)[A]	0.54	0.51	0.59	± 10.1 %
DCP (mV)[B]	95.9	98.8	98.6	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB√µV	C	D dB	VR mV	Unc[E] (k=2)
0	CW	X	0.0	0.0	1.0	0.00	164.4	±3.0 %
		Y	0.0	0.0	1.0		168.1	
		Z	0.0	0.0	1.0		130.9	

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

[A] The uncertainties of NormX,Y,Z do not affect the E^2-field uncertainty inside TSL (see Pages 5 and 6).
[B] Numerical linearization parameter: uncertainty not required.
[E] Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

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DASY/EASY - Parameters of Probe: EX3DV4 - SN:3798

Calibration Parameter Determined in Head Tissue Simulating Media

f (MHz) [G]	Relative Permittivity [F]	Conductivity (S/m) [F]	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
835	41.5	0.90	9.16	9.16	9.16	0.35	0.94	± 12.0 %
900	41.5	0.97	9.01	9.01	9.01	0.35	0.93	± 12.0 %
1810	40.0	1.40	7.79	7.79	7.79	0.73	0.59	± 12.0 %
1900	40.0	1.40	7.73	7.73	7.73	0.68	0.62	± 12.0 %
2000	40.0	1.40	7.73	7.73	7.73	0.80	0.58	± 12.0 %
2450	39.2	1.80	7.08	7.08	7.08	0.66	0.62	± 12.0 %
5200	36.0	4.66	4.85	4.85	4.85	0.37	1.80	± 13.1 %
5300	35.9	4.76	4.71	4.71	4.71	0.38	1.80	± 13.1 %
5500	35.6	4.96	4.76	4.76	4.76	0.36	1.80	± 13.1 %
5600	35.5	5.07	4.51	4.51	4.51	0.42	1.80	± 13.1 %
5800	35.3	5.27	4.48	4.48	4.48	0.40	1.80	± 13.1 %

[G] Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.
[F] At frequencies below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

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DASY/EASY - Parameters of Probe: EX3DV4 - SN:3798

Calibration Parameter Determined in Body Tissue Simulating Media

f (MHz) [C]	Relative Permittivity [F]	Conductivity (S/m) [F]	ConvF X	ConvF Y	ConvF Z	Alpha	Depth (mm)	Unct. (k=2)
835	55.2	0.97	9.27	9.27	9.27	0.49	0.84	± 12.0 %
900	55.0	1.05	9.11	9.11	9.11	0.80	0.62	± 12.0 %
1810	53.3	1.52	7.45	7.45	7.45	0.37	0.88	± 12.0 %
1900	53.3	1.52	7.32	7.32	7.32	0.37	0.86	± 12.0 %
2000	53.3	1.52	7.54	7.54	7.54	0.29	1.01	± 12.0 %
2450	52.7	1.95	7.08	7.08	7.08	0.80	0.57	± 12.0 %
5200	49.0	5.30	4.38	4.38	4.38	0.41	1.90	± 13.1 %
5300	48.9	5.42	4.22	4.22	4.22	0.41	1.90	± 13.1 %
5500	48.6	5.65	3.93	3.93	3.93	0.46	1.90	± 13.1 %
5600	48.5	5.77	3.92	3.92	3.92	0.38	1.90	± 13.1 %
5800	48.2	6.00	4.24	4.24	4.24	0.46	1.90	± 13.1 %

[C] Frequency validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ± 50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.
[F] At frequencies below 3 GHz, the validity of tissue parameters (ε and σ) can be relaxed to ± 10% if liquid compensation formula is applied to measured SAR values. At frequencies above 3 GHz, the validity of tissue parameters (ε and σ) is restricted to ± 5%. The uncertainty is the RSS of the ConvF uncertainty for indicated target tissue parameters.

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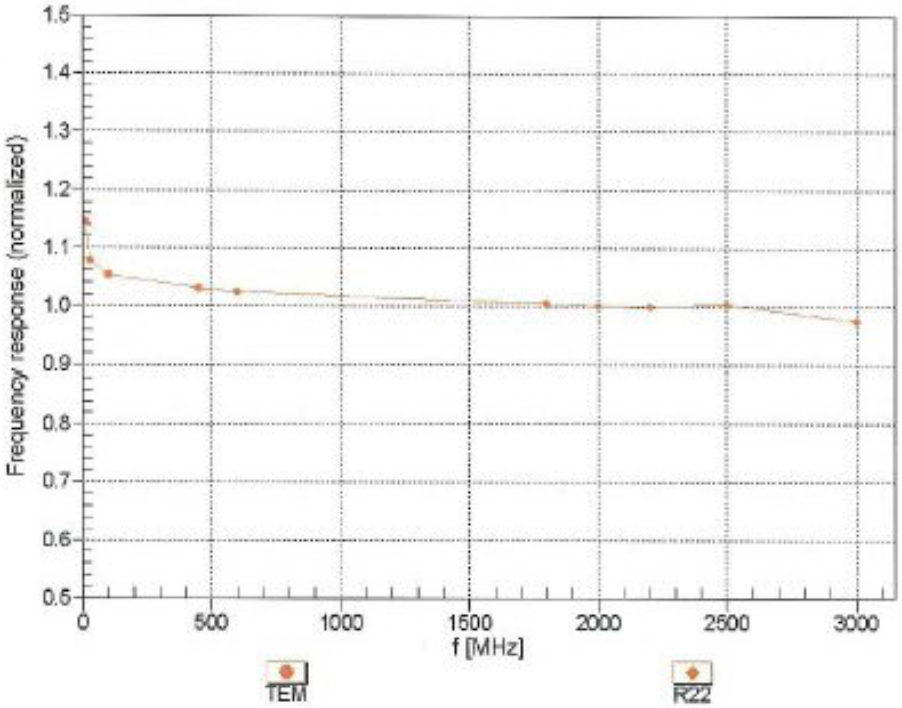
EX3DV4– SN:3798 July 26, 2013

Frequency Response of E-Field
(TEM-Cell:ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

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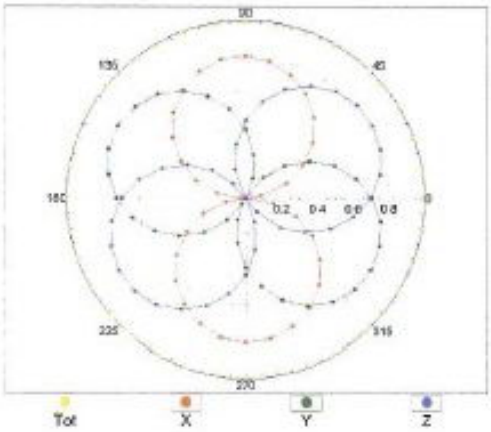
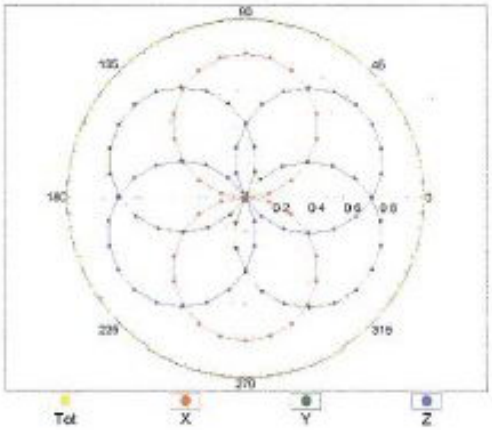
EX3DV4– SN:3798 July 26, 2013

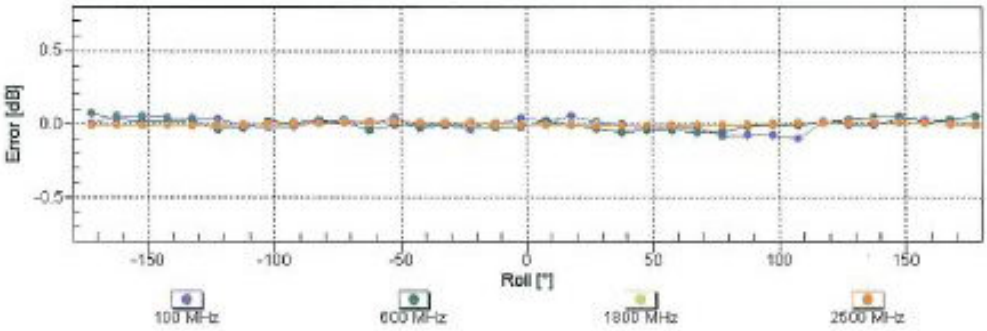
Receiving Pattern (ϕ), ϑ = 0°

f=600 MHz,TEM



f=1800 MHz,R22





Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

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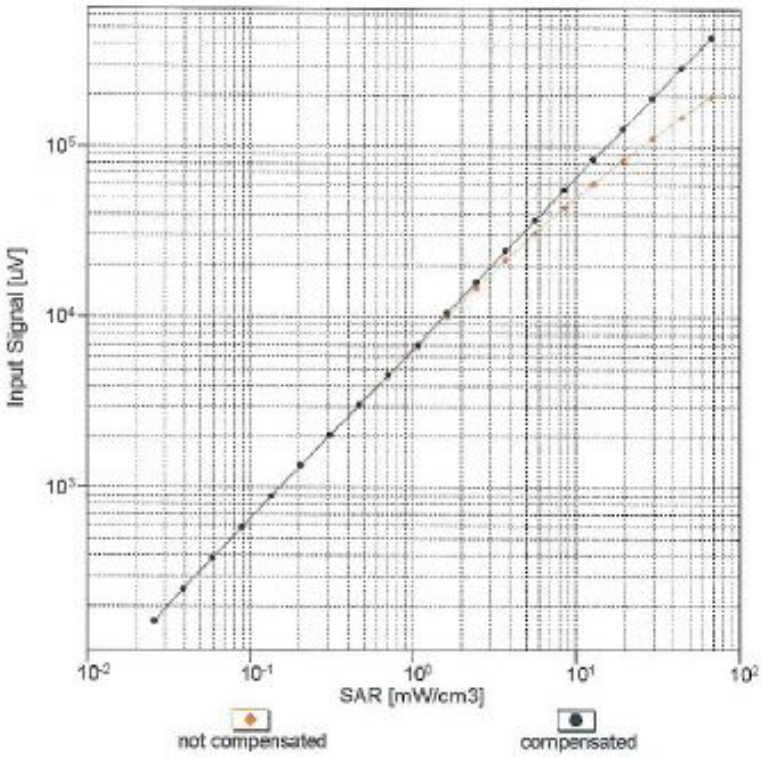
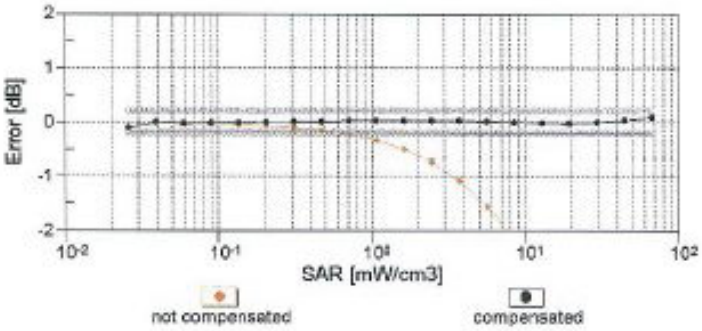
Dynamic Range f(SAR$_{head}$)
(TEM cell , f = 900 MHz)





Uncertainty of Linearity Assessment: ± 0.6% (k=2)

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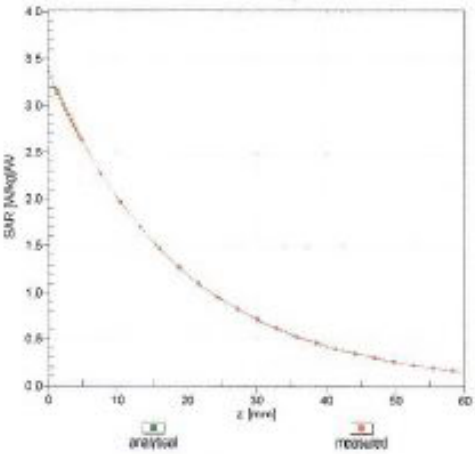
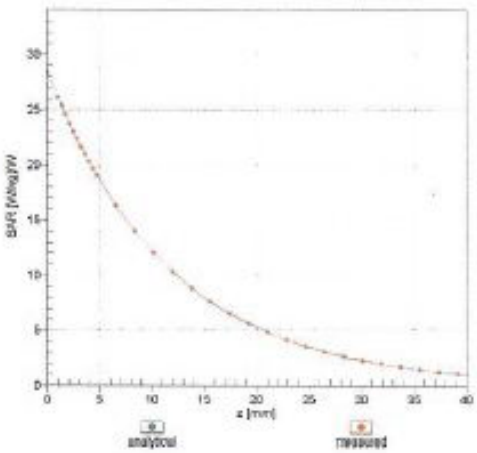
Conversion Factor Assessment

f = 835 MHz,WGLS R9 (H_convF)

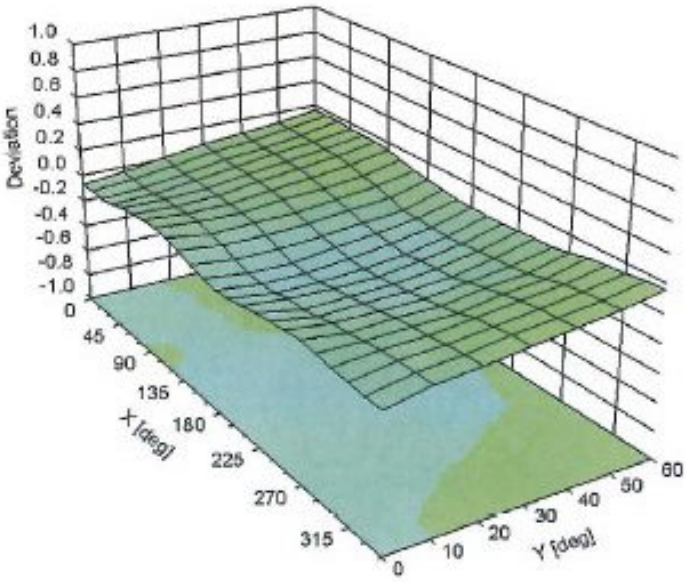


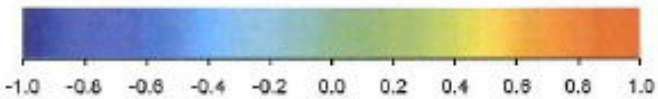
f = 1900 MHz,WGLS R22 (H_convF)



Deviation from Isotropy in Liquid

Error (ϕ, ϑ), f = 900 MHz





Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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DASY/EASY - Parameters of Probe: EX3DV4 - SN:3798

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle (°)	-42.4
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	2 mm

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APPENDIX C: PLOTS OF SAR TEST RESULT

The plots are showing in the file named Appendix C Plots of SAR Test Result

END REPORT

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