Testing Laboratory
1190

Specific Absorption Rate (SAR) Test Report

for

Mototech Inc.

on the

Remote controller

Report No.	:	FA6D0404-1-2-03
Trade Name	:	Mototech
Model Name	:	SR1000
FCC ID	:	RU4-SR1000
Date of Testing	:	Dec. 13, 2006
Date of Report	:	Dec. 13, 2006
Date of Review	:	Dec. 13, 2006

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- Report Version: Rev. 03

SPORTON International Inc.

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Appendix A – System Performance Check Data
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1. Statement of Compliance

The Specific Absorption Rate (SAR) maximum result found during testing for the **Mototech Inc. Remote controller Mototech SR1000 is 0.000847 W/Kg on the WLAN 2.4GHz band body SAR** with expanded uncertainty 20.6%. It is in compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure limits specified in FCC 47 CFR part 2 (2.1093) and ANSI/IEEE C95.1-1999 and had been tested in accordance with the measurement methods and procedures specified in OET Bulletin 65 Supplement C (Edition 01-01).

Approved by

Dr. Daniel Lee
EMC/SAR Director

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2. Administration Data

2.1 Testing Laboratory

Company Name : Sporton International Inc.
Department : Antenna Design/SAR
Address : No.52, Hwa-Ya 1st RD., Hwa Ya Technology Park, Kwei-Shan Hsiang, TaoYuan Hsien, Taiwan, R.O.C.
Telephone Number : 886-3-327-3456
Fax Number : 886-3-327-0973

2.2 Detail of Applicant

Company Name : Mototech Inc.
Address : 9, Park Avenue II. Science-Based Industrial Park, Hsin-Chu, Taiwan, R.O.C.
Telephone Number : 886-3-578-3381 Ext. 353
Fax Number : 886-3-564-3691
Contact Person : Weyden Wang / RD Manager / weyden_wang@mototech.com.tw

2.3 Detail of Manufacturer

Company Name : Mototech Inc.
Address : 9, Park Avenue II. Science-Based Industrial Park, Hsin-Chu, Taiwan, R.O.C.
Telephone Number : 886-3-578-3381 Ext. 353
Fax Number : 886-3-564-3691
Contact Person : Weyden Wang / RD Manager / weyden_wang@mototech.com.tw

2.4 Application Detail

Date of reception of application: Dec. 04, 2006
Start of test : Dec. 13, 2006
End of test : Dec. 13, 2006

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3. Scope

3.1 Description of Device Under Test (DUT)

DUT Type :	Remote controller
Trade Name :	Mototech
Model Name :	SR1000 R0B
FCC ID :	RU4-SR1000
Type of Modulation :	802.11b : DSSS 802.11g : OFDM
Frequency Range :	2400 MHz ~ 2483.5 MHz
Antenna Type :	Chip Antenna
Antenna Gain :	1.5 dBi
Type of Antenna Connector :	N/A
Maximum Output Power to Antenna :	802.11b: 16.60 dBm 802.11g: 15.60 dBm
DUT Stage :	Production Unit
Application Type :	Certificate

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3.2 Product Photo

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3.3 Applied Standards:

The Specific Absorption Rate (SAR) testing specification, method and procedure for this Remote controller is in accordance with the following standards:

47 CFR Part 2 (2.1093),
IEEE C95.1-1999,
IEEE C95.3-2002,
IEEE P1528 -2003, and
OET Bulletin 65 Supplement C (Edition 01-01)

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3.4 Device Category and SAR Limits

This device belongs to portable device category because its radiating structure is allowed to be used within 20 centimeters of the body of the user.

Limit for General Population/Uncontrolled exposure should be applied for this device, it is 1.6 W/kg as averaged over any 1 gram of tissue.

3.5 Test Conditions

3.5.1 Ambient Condition:

Item	MSL_2450
Ambient Temperature (°C)	20 ~ 24℃
Tissue simulating liquid temperature (°C)	21.8℃
Humidity (%)	< 60%

3.5.2 Test Configuration:

The data rates for SAR testing are 11Mbps for 802.11b, and 6Mbps for 802.11g.

Engineering testing software installed on the EUT can provide continuous transmitting RF signal. This RF signal utilized in SAR measurement has almost 100% duty cycle and its crest factor is 1.

The measurements were performed on the lowest, middle, and highest channel, i.e. channel 1, channel 6, and channel 11 for 802.11b, 802.11g each testing position.

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4. Specific Absorption Rate (SAR)

4.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The FCC recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

4.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density.
ρ). The equation description is as below:

$$\mathbf{SAR} = \frac{d}{dt}\left(\frac{dW}{dm}\right) = \frac{d}{dt}\left(\frac{dW}{\rho dv}\right)$$

SAR is expressed in units of Watts per kilogram (W/kg)

SAR measurement can be either related to the temperature elevation in tissue by

$$\mathbf{SAR} = C\frac{\delta T}{\delta t}$$

, where C is the specific head capacity, δT is the temperature rise and δt the exposure duration,

or related to the electrical field in the tissue by

$$\mathbf{SAR} = \frac{\sigma |E|^2}{\rho}$$

, where σ is the conductivity of the tissue, ρ is the mass density of the tissue and ***E*** is the rms electrical field strength.

However for evaluating SAR of low power transmitter, electrical field measurement is typically applied.

5. SAR Measurement Setup

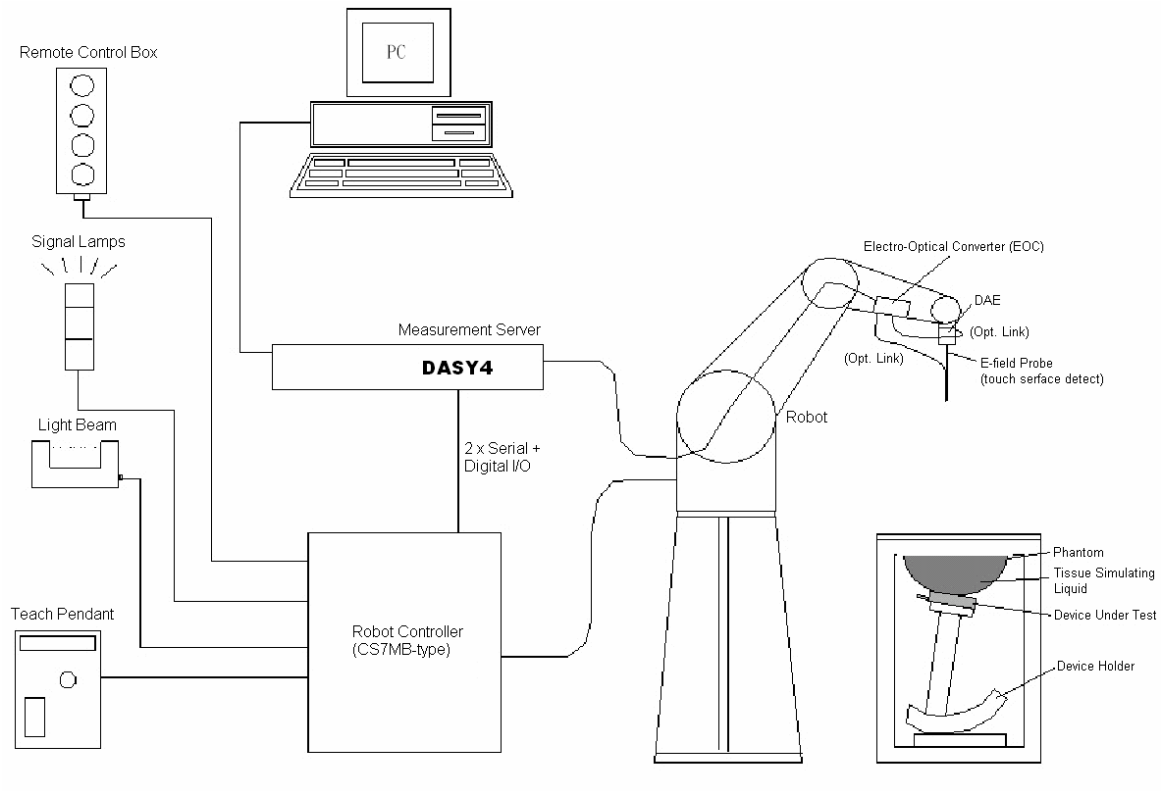

Fig. 5.1 DASY4 system

The DASY4 system for performance compliance tests is illustrated above graphically. This system consists of the following items:

- A standard high precision 6-axis robot with controller, a teach pendant and software
- A data acquisition electronic (DAE) attached to the robot arm extension
- A dosimetric probe equipped with an optical surface detector system
- The electro-optical converter (ECO) performs the conversion between optical and electrical signals
- A measurement server performs the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- A probe alignment unit which improves the accuracy of the probe positioning
- A computer operating Windows XP
- DASY4 software
- Remove control with teach pendant and additional circuitry for robot safety such as warming lamps, etc.
- The SAM twin phantom
- A device holder
- Tissue simulating liquid
- Dipole for evaluating the proper functioning of the system

Some of the components are described in details in the following sub-sections.

5.1 DASY4 E-Field Probe System

The SAR measurement is conducted with the dosimetric probe ET3DV6 (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

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5.1.1 ET3DV6 E-Field Probe Specification

Construction	Symmetrical design with triangular core Built-in optical fiber for surface detection system Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents)
Calibration	Simulating tissue at frequencies of 900MHz, 1.8GHz and 2.45GHz for brain and muscle (accuracy ±8%)
Frequency	10 MHz to > 3 GHz
Directivity	± 0.2 dB in brain tissue (rotation around probe axis) ± 0.4 dB in brain tissue (rotation perpendicular to probe axis)
Dynamic Range	5 μ W/g to > 100mW/g; Linearity: ±0.2dB
Surface Detection	± 0.2 mm repeatability in air and clear liquids on reflecting surface
Dimensions	Overall length: 330mm Tip length: 16mm Body diameter: 12mm Tip diameter: 6.8mm Distance from probe tip to dipole centers: 2.7mm
Application	General dosimetry up to 3GHz Compliance tests for mobile phones and Wireless LAN Fast automatic scanning in arbitrary phantoms

Fig. 5.2 Probe setup on robot

5.1.2 ET3DV6 E-Field Probe Calibration

Each probe needs to be calibrated according to a dosimetric assessment procedure with accuracy better than ± 10%. The spherical isotropy shall be evaluated and within ± 0.25dB. The sensitivity parameters (NormX, NormY, and NormZ), the diode compression parameter (DCP) and the conversion factor (ConvF) of the probe are tested. The calibration data are as below:

Sensitivity	X axis : 1.73 µV		Y axis : 1.67 µV	Z axis : 1.70 µV
Diode compression point	X axis : 95 mV		Y axis : 101 mV	Z axis : 93 mV
Conversion factor (Head/Body)	**Frequency (MHz)**	**X axis**	**Y axis**	**Z axis**
	2350~2550	4.66 / 4.11	4.66 / 4.11	4.66 / 4.11
Boundary effect (Head/Body)	**Frequency (MHz)**	**Alpha**	**Depth**	
	2350~2550	0.68 / 0.60	1.96 / 1.70	

NOTE:

1. The probe parameters have been calibrated by the SPEAG.

5.2 DATA Acquisition Electronics (DAE)

The data acquisition electronics (DAE4) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of the DAE4 is 200M Ohm; the inputs are symmetrical and floating. Common mode rejection is above 80dB.

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5.3 Robot

The DASY4 system uses the high precision robots RX90BL type out of the newer series from Stäubli SA (France). For the 6-axis controller DASYS system, the CS7MB robot controller version from Stäubli is used. The RX robot series have many features that are important for our application:

- High precision (repeatability 0.02 mm)
- High reliability (industrial design)
- Jerk-free straight movements
- Low ELF interference (the closed metallic construction shields against motor control fields)
- 6-axis controller

5.4 Measurement Server

The DASY4 measurement server is based on a PC/104 CPU board with
166 MHz CPU
32 MB chipset and
64 MB RAM.

Communication with
the DAE4 electronic box
the 16-bit AD-converter system for optical detection and digital I/O interface.

The measurement server performs all the real-time data evaluation for field measurements and surface detection, controls robot movements and handles safety operations.

5.5 SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region where shell thickness increases to 6mm). It has three measurement areas:

- Left head
- Right head
- Flat phantom

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections.

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A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters.

On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

The phantom can be used with the following tissue simulating liquids:
*Water-sugar based liquid
*Glycol based liquids

Fig. 5.3 Top view of twin phantom

Fig. 5.4 Bottom view of twin phantom

5.6 Data Storage and Evaluation

5.6.1 Data Storage

The DASY4 software stores the assessed data from the data acquisition electronics as raw data (in microvolt readings from the probe sensors), together with all the necessary software parameters for the data evaluation (probe calibration data, liquid parameters and device frequency and modulation data) in measurement files with the extension .DA4. The postprocessing software evaluates the desired unit and format for output each time the data is visualized or exported. This allows verification of the complete software setup even after the measurement and allows correction of erroneous parameter settings. For example, if a measurement has been performed with an incorrect crest factor parameter in the device setup, the parameter can be corrected afterwards and the data can be reevaluated.

The measured data can be visualized or exported in different units or formats, depending on the selected probe type (e.g., [V/m], [A/m], [mW/g]). Some of these units are not available in certain situations or give meaningless results, e.g., a SAR-output in a loseless media, will always be zero. Raw data can also be exported to perform the evaluation with other software packages.

5.6.2 Data Evaluation

The DASY4 postprocessing software (SEMCAD) automatically executes the following procedures to calculate the field units from the microvolt readings at the probe connector. The parameters used in the evaluation are stored in the configuration modules of the software：

Probe parameters：	- Sensitivity	$Norm_i$, a_{i0}, a_{i1}, a_{i2}
	- Conversion factor	$ConvF_i$
	- Diode compression point	dcp_i
Device parameters：	- Frequency	f
	- Crest factor	cf
Media parameters：	- Conductivity	σ
	- Density	ρ

These parameters must be set correctly in the software. They can be found in the component documents or they can be imported into the software from the configuration files issued for the DASY components. In the direct measuring mode of the multimeter option, the parameters of the actual system setup are used. In the scan visualization and export modes, the parameters stored in the corresponding document files are used.
The first step of the evaluation is a linearization of the filtered input signal to account for the compression characteristics of the detector diode. The compensation depends on the input signal, the diode type and the DC-transmission factor from the diode to the evaluation electronics. If the exciting field is pulsed, the crest factor of the signal must be known to correctly compensate for peak power. The formula for each channel

can be given as :

$$Vi = U_i + U_i^2 \cdot \frac{cf}{dcp_i}$$

with ***V_i = compensated signal of channel i (i = x, y, z)***
U_i = input signal of channel i (i = x, y, z)
cf = crest factor of exciting field (DASY parameter)
dcp_i = diode compression point (DASY parameter)

From the compensated input signals, the primary field data for each channel can be evaluated :

E-field probes : $E_i = \sqrt{\frac{V_i}{Norm_i ConvF}}$

H-field probes : $H_i = \sqrt{V_i} \frac{a_{i0+} a_{i1} f + a_{i2} f^2}{f}$

with ***V_i*** = compensated signal of channel *i* (*i* = x, y, z)
$Norm_i$ = sensor sensitivity of channel i (*i* = x, y, z)
μ V/(V/m)2 for E-field Probes
ConvF = sensitivity enhancement in solution
a_{ij} = sensor sensitivity factors for H-field probes
f = carrier frequency [GHz]
E_i = electric field strength of channel *i* in V/m
H_i = magnetic field strength of channel *i* in A/m

The RSS value of the field components gives the total field strength (Hermitian magnitude) :

$$E_{tot} = \sqrt{E_X^2 + E_Y^2 + E_Z^2}$$

The primary field data are used to calculate the derived field units.

$$\text{SAR} = E_{tot}^2 \cdot \frac{\sigma}{\rho \cdot 1000}$$

with ***SAR*** = local specific absorption rate in mW/g
Etot = total field strength in V/m
σ = conductivity in [mho/m] or [Siemens/m]
ρ = equivalent tissue density in g/ cm^3

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∗Note that the density is set to 1, to account for actual head tissue density rather than the density of the tissue simulating liquid.

The power flow density is calculated assuming the excitation field to be a free space field.

$$P_{pwe} = \frac{E_{tot}^2}{3770} \quad \text{or} \quad P_{pwe} = H_{tot}^2 \cdot 37.7$$

with P_{pwe} = equivalent power density of a plane wave in mW/cm^2
E_{tot} = total electric field strength in V/m
H_{tot} = total magnetic field strength in A/m

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5.7 Test Equipment List

Manufacture	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	Due Date
SPEAG	Dosimetric E-Filed Probe	ET3DV6	1788	Sep. 19, 2006	Sep. 19, 2007
SPEAG	835MHz System Validation Kit	D835V2	499	Mar. 15, 2006	Mar. 15, 2008
SPEAG	900MHz System Validation Kit	D900V2	190	Jul. 19, 2005	Jul. 19, 2007
SPEAG	1800MHz System Validation Kit	D1800V2	2d076	Jul. 20, 2005	Jul. 20, 2007
SPEAG	1900MHz System Validation Kit	D1900V2	5d041	Mar. 21, 2006	Mar. 21, 2008
SPEAG	2450MHz System Validation Kit	D2450V2	736	Jul. 12, 2005	Jul. 12, 2007
SPEAG	Data Acquisition Electronics	DAE3	577	Nov. 21, 2006	Nov. 21, 2007
SPEAG	Device Holder	N/A	N/A	NCR	NCR
SPEAG	Phantom	QD 000 P40 C	TP-1150	NCR	NCR
SPEAG	Robot	Staubli RX90BL	F03/5W15A1/A/01	NCR	NCR
SPEAG	Software	DASY4 V4.7 Build 44	N/A	NCR	NCR
SPEAG	Software	SEMCAD V1.8 Build 171	N/A	NCR	NCR
SPEAG	Measurement Server	SE UMS 001 BA	1021	NCR	NCR
Agilent	ENA series Network Analyzer	E5071B	MY42403579	Mar. 16, 2006	Mar. 16, 2007
Agilent	Dielectric Probe Kit	85070D	US01440205	NCR	NCR
Agilent	Dual Directional Coupler	778D	50422	NCR	NCR
Agilent	Power Amplifier	8449B	3008A01917	NCR	NCR
R&S	Radio Communication Tester	CMU200	105513	Jul. 25, 2006	Jul. 24, 2007
Agilent	Power Meter	E4416A	GB41292344	Jan. 23, 2006	Jan. 23, 2008
Agilent	Power Sensor	E9327A	US40441548	Feb. 6, 2006	Feb. 6, 2007
Agilent	Signal Generator	E8247C	MY43320596	Mar. 1, 2006	Mar. 1, 2008

Table 5.1 Test Equipment List

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6. Tissue Simulating Liquids

For the measurement of the field distribution inside the SAM phantom with DASY4, the phantom must be filled with around 25 liters of homogeneous body tissue simulating liquid. The liquid height from the bottom of the phantom body is 15.2 centimeters, which is shown in Fig. 6.1.

The following ingredients for tissue simulating liquid are used:

- **Water**: deionized water (pure H_20), resistivity $\geqq 16M\Omega$ - as basis for the liquid
- **Sugar**: refined sugar in crystals, as available in food shops – to reduce relative permittyvity
- **Salt**: pure NaCl – to increase conductivity
- **Cellulose**: Hydroxyethyl-cellulose, medium viscosity (75-125 mPa.s, 2% in water, 20°C), CAS#54290-to increase viscosity and to keep sugar in solution.
- **Preservative**: Preventol D-7 Bayer AG, D-51368 Leverkusen, CAS#55965-84-9- to prevent the spread of bacteria and molds.
- **DGMBE**: Deithlenglycol-monobuthyl ether (DGMBE), Fluka Chemie GmbH, CAS#112-34-5 – to reduce relative permittivity.

Table 6.1 gives the recipes for one liter of tissue simulating liquid for frequency band 2450 MHz.

Ingredient	MSL-2450
Water	698.3 ml
DGMBE	301.7 ml
Total amount	1 liter (1.0 kg)
Dielectric Parameters at 22°	f = 2450MHz ε_r= 52.7±5%, σ = 1.95±5% S/m

Table 6.1

The dielectric parameters of the liquids were verified prior to the SAR evaluation using an Agilent 85070D Dielectric Probe Kit and an Agilent Network Analyzer.

Table 6.2 shows the measuring results for muscle simulating liquid.

Bands	Frequency(MHz)	Permittivity (ε_r)	Conductivity (σ)	Measurement date
2450 MHz	2412	53	1.91	Dec. 13, 2006
	2437	53	1.95	
	2462	52.9	1.97	

Table 6.2

The measuring data are consistent with $\varepsilon_r = 52.7 \pm 5\%$ and $\sigma = 1.95 \pm 5\%$.

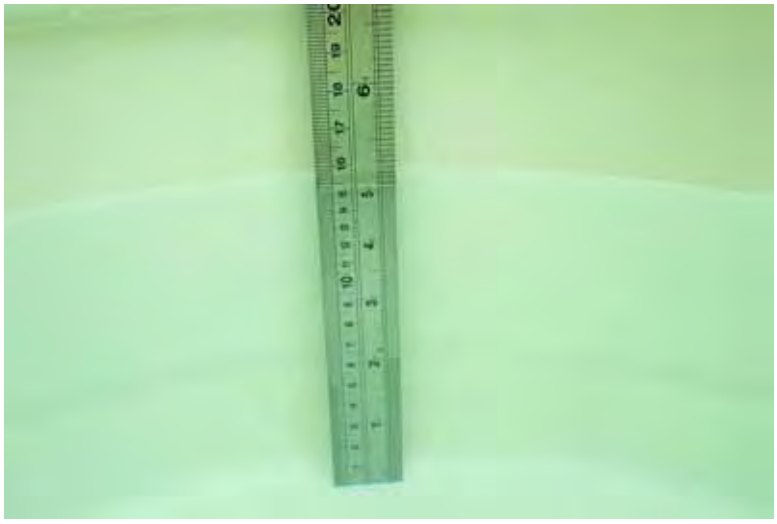

Fig. 6.1

7. Uncertainty Assessment

The component of uncertainly may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainly by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table 7.1

Uncertainty Distributions	Normal	Rectangular	Triangular	U-shape
Multiplying factor[(a)]	1/k [(b)]	$1/\sqrt{3}$	$1/\sqrt{6}$	$1/\sqrt{2}$

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity
(b) κ is the coverage factor

Table 7.1

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY4 uncertainty Budget is showed in Table 7.2.

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Error Description	Uncertainty Value ± %	Probability Distribution	Divisor	C_i 1g	Standard Unc. (1-g)	v_i or V_{eff}
Measurement System						
Probe Calibration	± 4.8	Normal	1	1	±4.8	∞
Axial Isotropy	± 4.7	Rectangular	√3	0.7	±1.9	∞
Hemispherical Isotropy	± 9.6	Rectangular	√3	0.7	±3.9	∞
Boundary Effect	± 1.0	Rectangular	√3	1	±0.6	∞
Linearity	± 4.7	Rectangular	√3	1	±2.7	∞
System Detection Limit	± 1.0	Rectangular	√3	1	±0.6	∞
Readout Electronics	± 1.0	Normal	1	1	±1.0	∞
Response Time	± 0.8	Rectangular	√3	1	± 0.5	∞
Integration time	± 2.6	Rectangular	√3	1	± 1.5	∞
RF Ambient Conditions	± 3.0	Rectangular	√3	1	±1.7	∞
Probe Positioner Mech. Tolerance	± 0.4	Rectangular	√3	1	±0.2	∞
Probe Positioning with respect to Phantom Shell	± 2.9	Rectangular	√3	1	±1.7	∞
Extrapolation and Interpolation Algorithms for Max. SAR Evaluation	± 1.0	Rectangular	√3	1	±0.6	∞
Test sample Related						
Test sample Positioning	±2.9	Normal	1	1	±2.9	145
Device Holder Uncertainty	±3.6	Normal	1	1	±3.6	5
Output Power Variation-SAR drift measurement	±5.0	Rectangular	√3	1	±2.9	∞
Phantom and Setup						
Phantom uncertainty(Including shap and thickness tolerances)	±4.0	Rectangular	√3	1	±2.3	∞
Liquid Conductivity Target tolerance	±5.0	Rectangular	√3	0.64	±1.8	∞
Liquid Conductivity measurement uncertainty	±2.5	Normal	1	0.64	±1.6	∞
Liquid Permittivity Target tolerance	±5.0	Rectangular	√3	0.6	±1.7	∞
Liquid Permittivity measurement uncertainty	±2.5	Normal	1	0.6	±1.5	∞
Combined standard uncertainty					±10.3	330
Coverage Factor for 95 %		***K=2***				
Expanded uncertainty (Coverage factor = 2)			**Normal (k=2) 27**		**±20.6**	

Table 7.2 Uncertainty Budget of DASY

8. SAR Measurement Evaluation

Each DASY system is equipped with one or more system validation kits. These units, together with the predefined measurement procedures within the DASY software, enable the user to conduct the system performance check and system validation. System validation kit includes a dipole, tripod holder to fix it underneath the flat phantom and a corresponding distance holder.

8.1 Purpose of System Performance check

The system performance check verifies that the system operates within its specifications. System and operator errors can be detected and corrected. It is recommended that the system performance check be performed prior to any usage of the system in order to guarantee reproducible results. The system performance check uses normal SAR measurements in a simplified setup with a well characterized source. This setup was selected to give a high sensitivity to all parameters that might fail or vary over time. The system check does not intend to replace the calibration of the components, but indicates situations where the system uncertainty is exceeded due to drift or failure.

8.2 System Setup

In the simplified setup for system evaluation, the DUT is replaced by a calibrated dipole and the power source is replaced by a continuous wave which comes from a signal generator at frequency 2450 MHz. The calibrated dipole must be placed beneath the flat phantom section of the SAM twin phantom with the correct distance holder. The distance holder should touch the phantom surface with a light pressure at the reference marking and be oriented parallel to the long side of the phantom. The equipment setup is shown below:

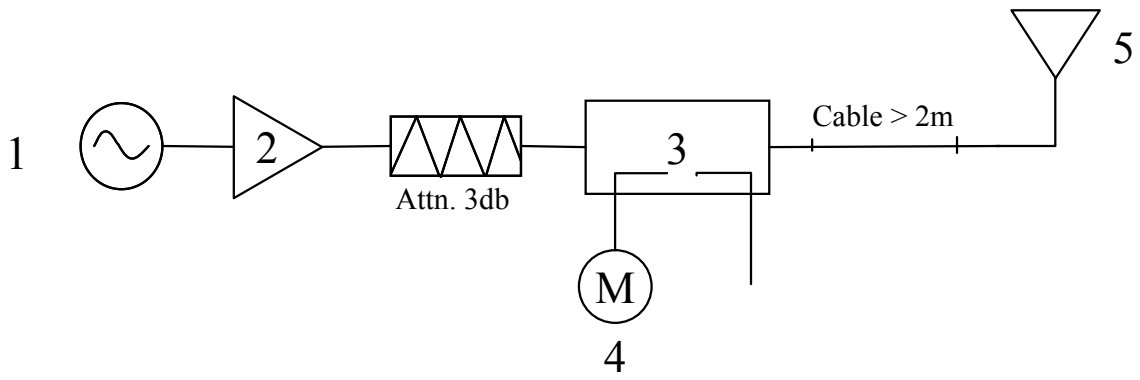

Fig. 8.1

1. Signal Generator
2. Amplifier
3. Directional Coupler
4. Power Meter
5. 2450 MHz Dipole

The output power on dipole port must be calibrated to 100 mW (20 dBm) before dipole is connected.

Fig 8.2 Dipole Setup

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8.3 Validation Results

Comparing to the original SAR value provided by Speag, the validation data should within its specification of 10 %. Table 8.1 shows the target SAR and measured SAR after normalized to 1W input power.

		Target (W/kg)	Measurement data (W/kg)	Variation	Measurement date
2450 MHz	SAR (1g)	52.8	53.5	1.3 %	Dec. 13, 2006
	SAR (10g)	24.5	24.8	1.2 %	

Table 8.1

The table above indicates the system performance check can meet the variation criterion.

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9. Description for DUT Testing Position

This DUT was tested in 2 different positions. They are “Keypad Up with Touch”, and “Keypad Down with Touch”.

Fig. 9.1 Keypad Up with Touch

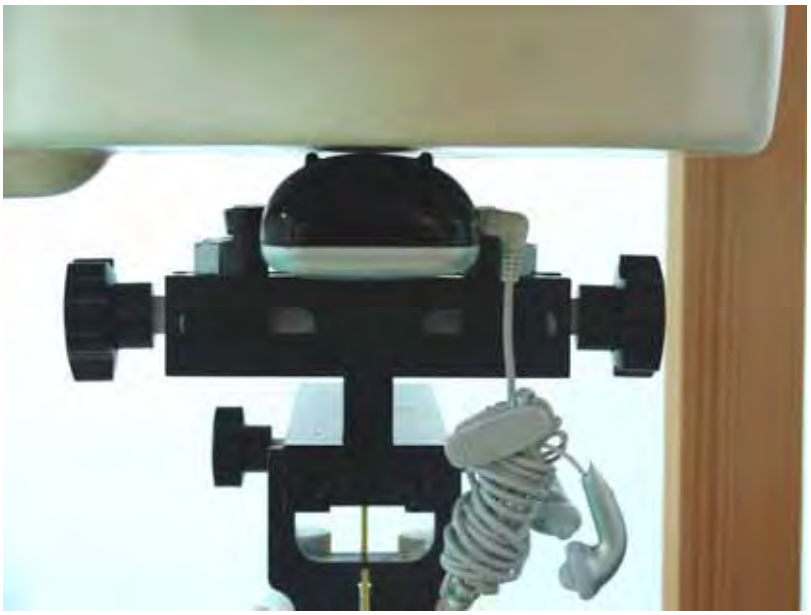

Fig. 9.2 Keypad Down with Touch

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10. Measurement Procedures

The measurement procedures are as follows:

- Using engineering software to transmit RF power continuously (continuous Tx) in the middle channel
- Placing the DUT in the positions described in the last section
- Setting scan area, grid size and other setting on the DASY4 software
- Taking data for the middle channel
- Repeat the previous steps for the low and high channels.

According to the IEEE P1528 draft standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- Power reference measurement
- Area scan
- Zoom scan
- Power reference measurement

10.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the IEEE1528-2003 standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY4 software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

Base on the Draft: SCC-34, SC-2, WG-2-Computational Dosimetry, P1528/D1.2 (Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques), a new algorithm has been implemented. The spatial-peak SAR can be computed over any required mass.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose , the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

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The entire evaluation of the spatial peak values is performed within the postprocessing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- extraction of the measured data (grid and values) from the Zoom Scan
- calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- generation of a high-resolution mesh within the measured volume
- interpolation of all measured values form the measurement grid to the high-resolution grid
- extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- calculation of the averaged SAR within masses of 1g and 10g

10.2 Scan Procedures

First **Area Scan** is used to locate the approximate location(s) of the local peak SAR value(s). The measurement grid within an **Area Scan** is defined by the grid extent, grid step size and grid offset. Next, in order to determine the EM field distribution in a three-dimensional spatial extension, **Zoom Scan** is required. The **Zoom Scan** measures 5x5x7 points with step size 8, 8 and 5 mm. The **Zoom Scan** is performed around the highest E-field value to determine the averaged SAR-distribution over 1 g.

10.3 SAR Averaged Methods

In DASY4, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.

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11. SAR Test Results

11.1 Keypad Up with Touch

Mode	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
802.11b	1	2412(Low)	CCK	16.6	-0.175	0.0000432	1.6	Pass
	6	2437(Mid)	CCK	16.25	0.176	0.000847	1.6	Pass
	11	2462(High)	CCK	16.25	-0.141	0.000119	1.6	Pass
802.11g	1	2412(Low)	OFDM	15.23	-	-	-	-
	6	2437(Mid)	OFDM	15.02	-0.199	0.000139	1.6	Pass
	11	2462(High)	OFDM	15.6	-	-	-	-

11.2 Keypad Down with Touch

Mode	Chan.	Freq (MHz)	Modulation type	Conducted Power (dBm)	Power Drift (dB)	Measured 1g SAR (W/kg)	Limits (W/Kg)	Results
802.11b	1	2412(Low)	CCK	16.6	-	-	-	-
	6	2437(Mid)	CCK	16.25	-0.182	0.000143	1.6	Pass
	11	2462(High)	CCK	16.25	-	-	-	-
802.11g	1	2412(Low)	OFDM	15.23	-	-	-	-
	6	2437(Mid)	OFDM	15.02	-	-	-	-
	11	2462(High)	OFDM	15.6	-	-	-	-

Test Engineer：Gordon Lin

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12. References

[1] FCC 47 CFR Part 2 "Frequency Allocations and Radio Treaty Matters; General Rules and Regulations"
[2] IEEE Std. P1528-2003, "Recommended Practice for Determining the Peak Spatial-Average Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", April 21,2003.
[3] Supplement C (Edition 01-01) to OET Bulletin 65 (Edition 97-01), "Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to RF Emissions", June 2001
[4] IEEE Std. C95.3-2002, "IEEE Recommended Practice for the Meaurement of Potentially Hazardous Electromagnetic Fields-RF and Microwave", 2002
[5] IEEE Std. C95.1-1999, "IEEE Standard for Safety Levels with Respect to Human Exposure to Radio Frequency Electromagnetic Fields, 3 kHz to 300 GHz", 1999
[6] Robert J. Renka, "Multivariate Interpolation Of Large Sets Of Scattered Data", University of Noth Texas ACM Transactions on Mathematical Software, vol. 14, no. 2, June 1988, pp. 139-148
[7] DAYS4 System Handbook

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Appendix A - System Performance Check Data

Test Laboratory: Sporton International Inc. SAR Testing Lab Date/Time: 12/13/2006 8:59:14 AM

System Check_Body_2450MHz_20061213

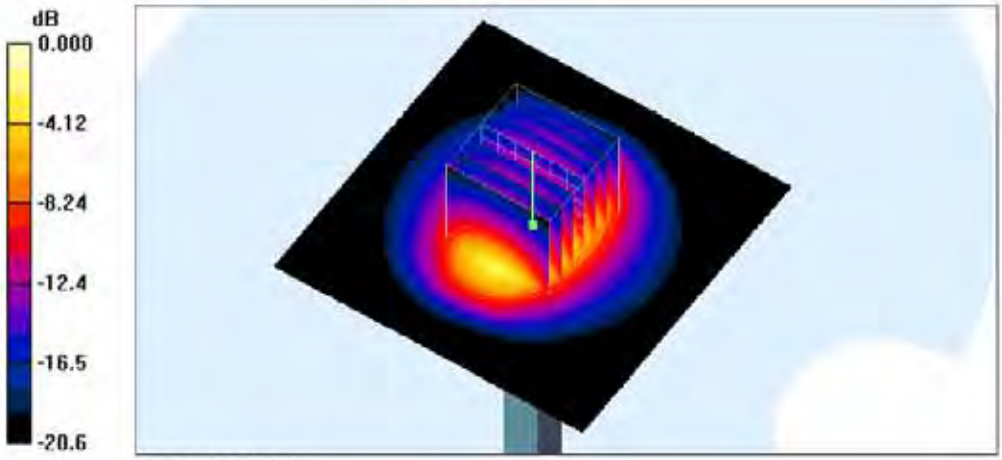
DUT: Dipole 2450 MHz

Communication System: CW; Frequency: 2450 MHz;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: f = 2450 MHz; σ = 1.96 mho/m; ε_r = 53; ρ = 1000 kg/m^3
Ambient Temperature : 22.0 ℃; Liquid Temperature : 21.8 ℃

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(4.11, 4.11, 4.11); Calibrated: 9/19/2006
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/21/2006
- Phantom: SAM-A; Type: QD 000 P40 C; Serial: TP-1303
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Pin=100mW/Area Scan (91x91x1): Measurement grid: dx=10mm, dy=10mm
Maximum value of SAR (interpolated) = 6.16 mW/g

Pin=100mW/Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 56.2 V/m; Power Drift = 0.010 dB
Peak SAR (extrapolated) = 12.5 W/kg
SAR(1 g) = 5.35 mW/g; SAR(10 g) = 2.48 mW/g
Maximum value of SAR (measured) = 5.97 mW/g



0 dB = 5.97mW/g

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Appendix B - SAR Measurement Data

Test Laboratory: Sporton International Inc. SAR Testing Lab Date/Time: 12/13/2006 2:28:17 PM

Body_802.11b Ch1_Keypad Up with EUT Touch_20061213

DUT: 6D0404

Communication System: 802.11b ; Frequency: 2412 MHz;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: f = 2412 MHz; σ = 1.91 mho/m; ε_r = 53; ρ = 1000 kg/m^3
Ambient Temperature : 22.0 ℃; Liquid Temperature : 21.8 ℃

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(4.11, 4.11, 4.11); Calibrated: 9/19/2006
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/21/2006
- Phantom: SAM-A; Type: QD 000 P40 C; Serial: TP-1303
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Ch1/Area Scan (61x201x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 0.001 mW/g

Ch1/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 0.285 V/m; Power Drift = -0.275 dB
Peak SAR (extrapolated) = 0.004 W/kg
SAR(1 g) = 4.32e-005 mW/g; SAR(10 g) = 1.58e-005 mW/g
Maximum value of SAR (measured) = 0.004 mW/g

0 dB = 0.004mW/g

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Test Laboratory: Sporton International Inc. SAR Testing Lab Date/Time: 12/13/2006 10:22:13 AM

Body_802.11b Ch6_Keypad Up with EUT Touch_20061213

DUT: 6D0404

Communication System: 802.11b ; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: f = 2437 MHz; σ = 1.95 mho/m; ε_r = 53; ρ = 1000 kg/m^3
Ambient Temperature : 22.0 ℃; Liquid Temperature : 21.8 ℃

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(4.11, 4.11, 4.11); Calibrated: 9/19/2006
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/21/2006
- Phantom: SAM-A; Type: QD 000 P40 C; Serial: TP-1303
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Ch6/Area Scan (61x201x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 0.002 mW/g

Ch6/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 0.295 V/m; Power Drift = 0.176 dB
Peak SAR (extrapolated) = 0.016 W/kg
SAR(1 g) = 0.000847 mW/g; SAR(10 g) = 0.000104 mW/g
Maximum value of SAR (measured) = 0.007 mW/g

0 dB = 0.007mW/g

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Test Laboratory: Sporton International Inc. SAR Testing Lab Date/Time: 12/13/2006 2:55:45 PM

Body_802.11b Ch11_Keypad Up with EUT Touch_20061213

DUT: 6D0404

Communication System: 802.11b ; Frequency: 2462 MHz;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: f = 2462 MHz; σ = 1.97 mho/m; ε_r = 52.9; ρ = 1000 kg/m^3
Ambient Temperature : 22.0 ℃; Liquid Temperature : 21.8 ℃

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(4.11, 4.11, 4.11); Calibrated: 9/19/2006
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/21/2006
- Phantom: SAM-A; Type: QD 000 P40 C; Serial: TP-1303
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Ch11/Area Scan (61x201x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 0.005 mW/g

Ch11/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 0.556 V/m; Power Drift = -0.141 dB
Peak SAR (extrapolated) = 0.003 W/kg
SAR(1 g) = 0.000119 mW/g; SAR(10 g) = 1.78e-005 mW/g
Maximum value of SAR (measured) = 0.003 mW/g

0 dB = 0.003mW/g

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Test Laboratory: Sporton International Inc. SAR Testing Lab Date/Time: 12/13/2006 10:02:16 AM

Body_802.11g Ch6_Keypad Up with EUT Touch_20061213

DUT: 6D0404

Communication System: 802.11g; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: f = 2437 MHz; σ = 1.95 mho/m; ε_r = 53; ρ = 1000 kg/m^3
Ambient Temperature : 22.0 ℃; Liquid Temperature : 21.8 ℃

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(4.11, 4.11, 4.11); Calibrated: 9/19/2006
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/21/2006
- Phantom: SAM-A; Type: QD 000 P40 C; Serial: TP-1303
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Ch6/Area Scan (61x201x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 0.000 mW/g

Ch6/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 0.227 V/m; Power Drift = -0.199 dB
Peak SAR (extrapolated) = 0.002 W/kg
SAR(1 g) = 0.000139 mW/g; SAR(10 g) = 2.84e-005 mW/g
Maximum value of SAR (measured) = 0.002 mW/g

0 dB = 0.002mW/g

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Test Laboratory: Sporton International Inc. SAR Testing Lab Date/Time: 12/13/2006 1:53:16 PM

Body_802.11b Ch6_Keypad Down with EUT Touch_20061213

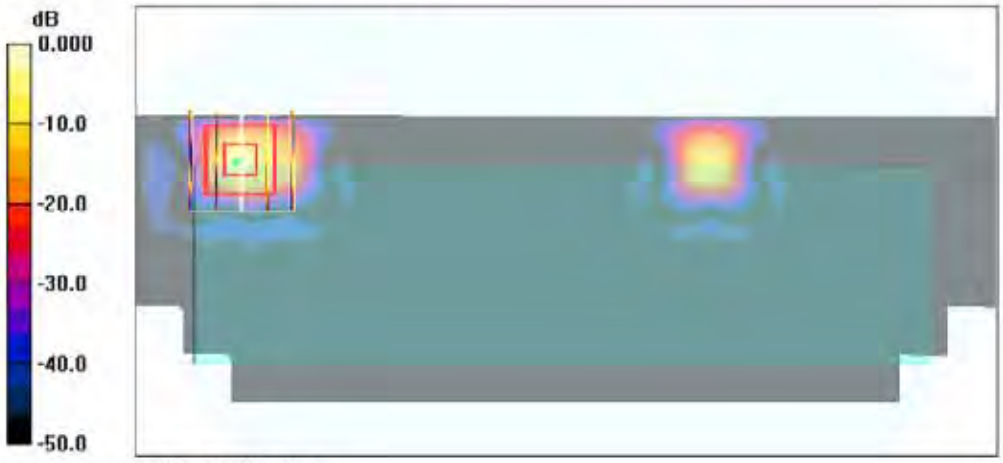
DUT: 6D0404

Communication System: 802.11b ; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: f = 2437 MHz; σ = 1.95 mho/m; ε_r = 53; ρ = 1000 kg/m^3
Ambient Temperature : 22.0 ℃; Liquid Temperature : 21.8 ℃

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(4.11, 4.11, 4.11); Calibrated: 9/19/2006
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/21/2006
- Phantom: SAM-A; Type: QD 000 P40 C; Serial: TP-1303
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Ch6/Area Scan (61x201x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 0.002 mW/g

Ch6/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 0.496 V/m; Power Drift = -0.182 dB
Peak SAR (extrapolated) = 0.004 W/kg
SAR(1 g) = 0.000143 mW/g; SAR(10 g) = 1.58e-005 mW/g
Maximum value of SAR (measured) = 0.004 mW/g



0 dB = 0.004mW/g

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Test Laboratory: Sporton International Inc. SAR Testing Lab Date/Time: 12/13/2006 10:22:13 AM

Body_802.11b Ch6_Keypad Up with EUT Touch_20061213_2D

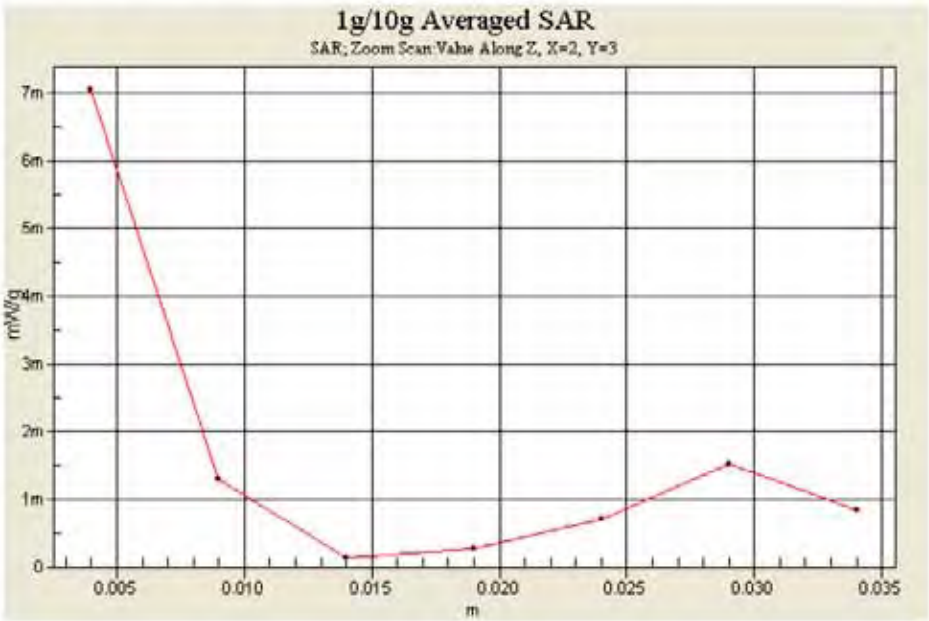
DUT: 6D0404

Communication System: 802.11b ; Frequency: 2437 MHz;Duty Cycle: 1:1
Medium: MSL_2450 Medium parameters used: f = 2437 MHz; σ = 1.95 mho/m; ε_r = 53; ρ = 1000 kg/m^3
Ambient Temperature : 22.0 ℃; Liquid Temperature : 21.8 ℃

DASY4 Configuration:
- Probe: ET3DV6 - SN1788; ConvF(4.11, 4.11, 4.11); Calibrated: 9/19/2006
- Sensor-Surface: 4mm (Mechanical And Optical Surface Detection)
- Electronics: DAE3 Sn577; Calibrated: 11/21/2006
- Phantom: SAM-A; Type: QD 000 P40 C; Serial: TP-1303
- Measurement SW: DASY4, V4.7 Build 44; Postprocessing SW: SEMCAD, V1.8 Build 171

Ch6/Area Scan (61x201x1): Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 0.002 mW/g

Ch6/Zoom Scan (5x5x7)/Cube 0: Measurement grid: dx=8mm, dy=8mm, dz=5mm
Reference Value = 0.295 V/m; Power Drift = 0.176 dB
Peak SAR (extrapolated) = 0.016 W/kg
SAR(1 g) = 0.000847 mW/g; SAR(10 g) = 0.000104 mW/g
Maximum value of SAR (measured) = 0.007 mW/g



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Appendix C – Calibration Data

Calibration Laboratory of
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Engineering AG
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S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
S Servizio svizzero di taratura
Swiss Calibration Service

Accredited by the Swiss Federal Office of Metrology and Accreditation
The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: SCS 108

Client Sporton (Auden)

Certificate No: D2450V2-736_Jul05

CALIBRATION CERTIFICATE

Object	D2450V2 - SN: 736
Calibration procedure(s)	QA CAL-05.v6 Calibration procedure for dipole validation kits
Calibration date	July 12, 2005
Condition of the calibrated item	In Tolerance

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter EPM E442	GB37480704	12-Oct-04 (METAS, No. 251-00412)	Oct-05
Power sensor HP 8481A	US37292783	12-Oct-04 (METAS, No. 251-00412)	Oct-05
Reference 20 dB Attenuator	SN: 5086 (20g)	10-Aug-04 (METAS, No 251-00402)	Aug-05
Reference 10 dB Attenuator	SN: 5047.2 (10r)	10-Aug-04 (METAS, No 251-00402)	Aug-05
Reference Probe ES3DV2	SN 3025	28-Oct-04 (SPEAG, No. ES3-3025_Oct04)	Oct-05
DAE4	SN 601	07-Jan-05 (SPEAG, No. DAE4-601_Jan05)	Jan-06

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power sensor HP 8481A	MY41092317	18-Oct-02 (SPEAG, in house check Oct-03)	In house check: Oct-05
RF generator R&S SML-03	100698	27-Mar-02 (SPEAG, in house check Dec-03)	In house check: Dec-05
Network Analyzer HP 8753E	US37390585 S4206	18-Oct-01 (SPEAG, in house check Nov-04)	In house check: Nov-05

	Name	Function	Signature
Calibrated by:	Mike Meili	Laboratory Technician	
Approved by:	Katja Pokovic	Technical Manager	

Issued: July 12, 2005

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Certificate No: D2450V2-736_Jul05 Page 1 of 9

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Calibration Laboratory of
Schmid & Partner
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Swiss Calibration Service

Accredited by the Swiss Federal Office of Metrology and Accreditation
The Swiss Accreditation Service is one of the signatories to the EA Multilateral Agreement for the recognition of calibration certificates

Accreditation No.: **SCS 108**

Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001
c) Federal Communications Commission Office of Engineering & Technology (FCC OET), "Evaluating Compliance with FCC Guidelines for Human Exposure to Radiofrequency Electromagnetic Fields: Additional Information for Evaluating Compliance of Mobile and Portable Devices with FCC Limits for Human Exposure to Radiofrequency Emissions", Supplement C (Edition 01-01) to Bulletin 65

Additional Documentation:

d) DASY4 System Handbook

Methods Applied and Interpretation of Parameters:

- *Measurement Conditions:* Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- *Antenna Parameters with TSL:* The dipole is mounted with the spacer to position its feed point exactly below the center marking of the flat phantom section, with the arms oriented parallel to the body axis.
- *Feed Point Impedance and Return Loss:* These parameters are measured with the dipole positioned under the liquid filled phantom. The impedance stated is transformed from the measurement at the SMA connector to the feed point. The Return Loss ensures low reflected power. No uncertainty required.
- *Electrical Delay:* One-way delay between the SMA connector and the antenna feed point. No uncertainty required.
- *SAR measured:* SAR measured at the stated antenna input power.
- *SAR normalized:* SAR as measured, normalized to an input power of 1 W at the antenna connector.
- *SAR for nominal TSL parameters:* The measured TSL parameters are used to calculate the nominal SAR result.

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Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY4	V4.6
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom V5.0	
Distance Dipole Center - TSL	10 mm	with Spacer
Area Scan resolution	dx, dy = 15 mm	
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	2450 MHz ± 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 ± 0.2) °C	38.5 ± 6 %	1.73 mho/m ± 6 %
Head TSL temperature during test	(22.0 ± 0.2) °C	----	----

SAR result with Head TSL

SAR averaged over 1 cm³ (1 g) of Head TSL	condition	
SAR measured	250 mW input power	13.1 mW / g
SAR normalized	normalized to 1W	52.4 mW / g
SAR for nominal Head TSL parameters [1]	normalized to 1W	**52.8 mW / g ± 17.0 % (k=2)**

SAR averaged over 10 cm³ (10 g) of Head TSL	condition	
SAR measured	250 mW input power	6.13 mW / g
SAR normalized	normalized to 1W	24.5 mW / g
SAR for nominal Head TSL parameters [1]	normalized to 1W	**24.7 mW / g ± 16.5 % (k=2)**

[1] Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

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Body TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Body TSL parameters	22.0 °C	52.7	1.95 mho/m
Measured Body TSL parameters	(22.2 ± 0.2) °C	52.5 ± 6 %	2.02 mho/m ± 6 %
Body TSL temperature during test	(22.2 ± 0.2) °C	—	—

SAR result with Body TSL

SAR averaged over 1 cm³ (1 g) of Body TSL	condition	
SAR measured	250 mW input power	13.5 mW / g
SAR normalized	normalized to 1W	54.0 mW / g
SAR for nominal Body TSL parameters [2]	normalized to 1W	**52.8 mW / g ± 17.0 % (k=2)**

SAR averaged over 10 cm³ (10 g) of Body TSL	condition	
SAR measured	250 mW input power	6.26 mW / g
SAR normalized	normalized to 1W	25.0 mW / g
SAR for nominal Body TSL parameters [2]	normalized to 1W	**24.5 mW / g ± 16.5 % (k=2)**

[2] Correction to nominal TSL parameters according to d), chapter "SAR Sensitivities"

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Appendix

Antenna Parameters with Head TSL

Impedance, transformed to feed point	53.6 Ω + 3.7 jΩ
Return Loss	-26.0 dB

Antenna Parameters with Body TSL

Impedance, transformed to feed point	49.9 Ω + 5.3 jΩ
Return Loss	- 25.5 dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.157 ns

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals.
No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG
Manufactured on	August 26, 2003

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DASY4 Validation Report for Head TSL

Date/Time: 12.07.2005 12:53:00

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN736

Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1
Medium: HSL U10 BB
Medium parameters used: f = 2450 MHz; σ = 1.73 mho/m; ε_r = 38.5; ρ = 1000 kg/m^3
Phantom section: Flat Section
Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV2 - SN3025; ConvF(4.4, 4.4, 4.4); Calibrated: 29.10.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 22.07.2004
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA
- Measurement SW: DASY4, V4.5 Build 30; Postprocessing SW: SEMCAD, V1.8 Build 149

Pin = 250 mW; d = 10 mm 2/Area Scan (41x61x1):
Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 16.6 mW/g

Pin = 250 mW; d = 10 mm 2/Zoom Scan (7x7x7)/Cube 0:
Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 91.6 V/m; Power Drift = 0.077 dB
Peak SAR (extrapolated) = 27.0 W/kg
SAR(1 g) = 13.1 mW/g; SAR(10 g) = 6.13 mW/g
Maximum value of SAR (measured) = 15.0 mW/g

0 dB = 15.0mW/g

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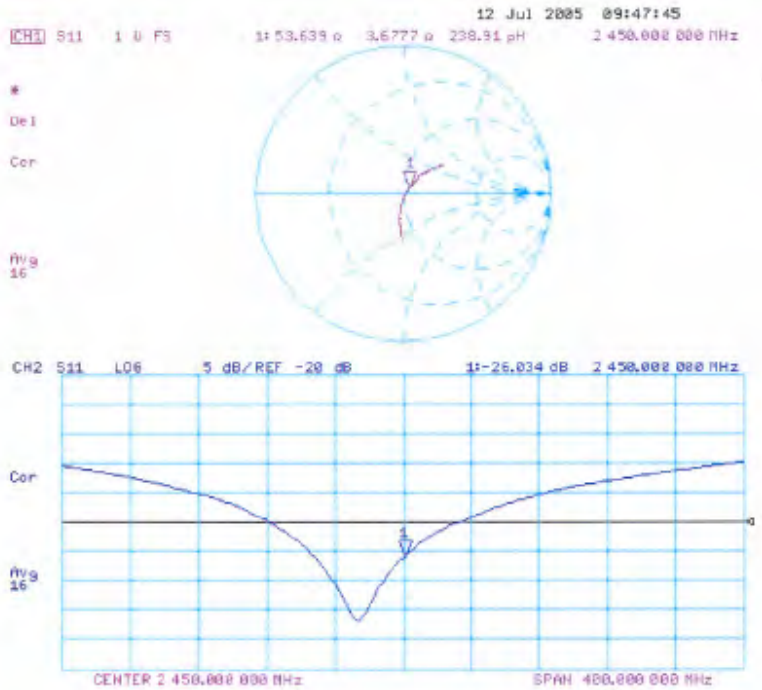
Impedance Measurement Plot for Head TSL



Certificate No: D2450V2-736_Jul05 Page 7 of 9

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DASY4 Validation Report for Body TSL

Date/Time: 11.07.2005 17:33:35

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN736

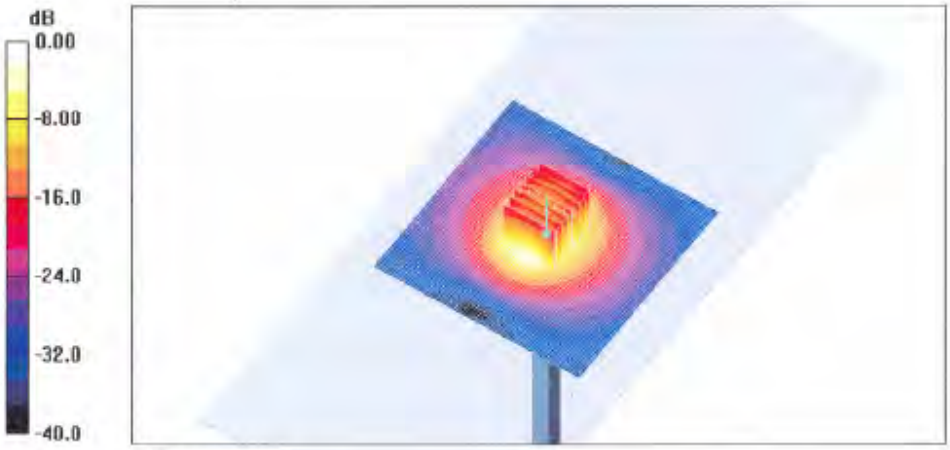
Communication System: CW-2450; Frequency: 2450 MHz; Duty Cycle: 1:1
Medium: MSL 2450
Medium parameters used: f = 2450 MHz; σ = 2.02 mho/m; ε_r = 52.5; ρ = 1000 kg/m^3
Phantom section: Flat Section
Measurement Standard: DASY4 (High Precision Assessment)

DASY4 Configuration:

- Probe: ES3DV2 - SN3025; ConvF(4.13, 4.13, 4.13); Calibrated: 29.10.2004
- Sensor-Surface: 4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 22.07.2004
- Phantom: Flat Phantom 5.0 (front); Type: QD000P50AA
- Measurement SW: DASY4, V4.6 Build 4; Postprocessing SW: SEMCAD, V1.8 Build 149

Pin = 250 mW; d = 10 mm/Area Scan (81x81x1):
Measurement grid: dx=15mm, dy=15mm
Maximum value of SAR (interpolated) = 15.8 mW/g

Pin = 250 mW; d = 10 mm/Zoom Scan (7x7x7)/Cube 0:
Measurement grid: dx=5mm, dy=5mm, dz=5mm
Reference Value = 85.9 V/m; Power Drift = 0.160 dB
Peak SAR (extrapolated) = 27.6 W/kg
SAR(1 g) = 13.5 mW/g; SAR(10 g) = 6.26 mW/g
Maximum value of SAR (measured) = 15.5 mW/g



0 dB = 15.5mW/g

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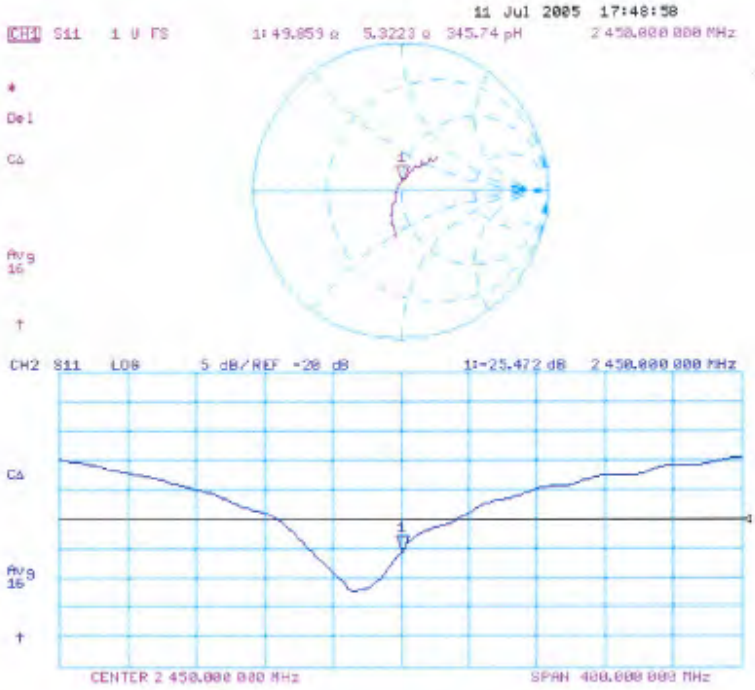
Impedance Measurement Plot for Body TSL



Certificate No: D2450V2-736_Jul05 Page 9 of 9

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Accreditation No.: SCS 108

Client Sporton (Auden)

Certificate No: ET3-1788_Sep06

CALIBRATION CERTIFICATE

Object	ET3DV6 - SN:1788
Calibration procedure(s)	QA CAL-01.v5 Calibration procedure for dosimetric E-field probes
Calibration date:	September 19, 2006
Condition of the calibrated item	In Tolerance

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	5-Apr-06 (METAS, No. 251-00557)	Apr-07
Power sensor E4412A	MY41495277	5-Apr-06 (METAS, No. 251-00557)	Apr-07
Power sensor E4412A	MY41498087	5-Apr-06 (METAS, No. 251-00557)	Apr-07
Reference 3 dB Attenuator	SN: S5054 (3c)	10-Aug-06 (METAS, No. 217-00592)	Aug-07
Reference 20 dB Attenuator	SN: S5086 (20b)	4-Apr-06 (METAS, No. 251-00558)	Apr-07
Reference 30 dB Attenuator	SN: S5129 (30b)	10-Aug-06 (METAS, No. 217-00593)	Aug-07
Reference Probe ES3DV2	SN: 3013	2-Jan-06 (SPEAG, No. ES3-3013_Jan06)	Jan-07
DAE4	SN: 654	21-Jun-06 (SPEAG, No. DAE4-654_Jun06)	Jun-07

Secondary Standards	ID #	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4 Aug 99 (SPEAG, in house check Nov-05)	In house check: Nov-07
Network Analyzer HP 8753E	US37390585	18-Oct-01 (SPEAG, in house check Nov-05)	In house check: Nov-06

	Name	Function	Signature
Calibrated by:	Katja Pokovic	Technical Manager	
Approved by:	Niels Kuster	Quality Manager	

Issued: September 19, 2006

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Certificate No: ET3-1788_Sep06 Page 1 of 9

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Accreditation No.: SCS 108

Glossary:

TSL	tissue simulating liquid
NORMx,y,z	sensitivity in free space
ConF	sensitivity in TSL / NORMx,y,z
DCP	diode compression point
Polarization φ	φ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., ϑ = 0 is normal to probe axis

Calibration is Performed According to the Following Standards:

a) IEEE Std 1528-2003, "IEEE Recommended Practice for Determining the Peak Spatial-Averaged Specific Absorption Rate (SAR) in the Human Head from Wireless Communications Devices: Measurement Techniques", December 2003
b) CENELEC EN 50361, "Basic standard for the measurement of Specific Absorption Rate related to human exposure to electromagnetic fields from mobile phones (300 MHz - 3 GHz), July 2001

Methods Applied and Interpretation of Parameters:

- *NORMx,y,z:* Assessed for E-field polarization ϑ = 0 (f ≤ 900 MHz in TEM-cell; f > 1800 MHz: R22 waveguide). NORMx,y,z are only intermediate values, i.e., the uncertainties of NORMx,y,z does not effect the E^2-field uncertainty inside TSL (see below *ConvF*).
- *NORM(f)x,y,z = NORMx,y,z * frequency_response* (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of *ConvF*.
- *DCPx,y,z:* DCP are numerical linearization parameters assessed based on the data of power sweep (no uncertainty required). DCP does not depend on frequency nor media.
- *ConvF and Boundary Effect Parameters:* Assessed in flat phantom using E-field (or Temperature Transfer Standard for f ≤ 800 MHz) and inside waveguide using analytical field distributions based on power measurements for f > 800 MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to *NORMx,y,z * ConvF* whereby the uncertainty corresponds to that given for *ConvF*. A frequency dependent *ConvF* is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- *Spherical Isotropy (3D deviation from Isotropy):* in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- *Sensor Offset:* The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.

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ET3DV6 SN:1788 September 19, 2006

Probe ET3DV6

SN:1788

Manufactured:	May 28, 2003
Last calibrated:	September 30, 2004
Recalibrated:	September 19, 2006

Calibrated for DASY Systems

(Note: non-compatible with DASY2 system!)

Certificate No: ET3-1788_Sep06 Page 3 of 9

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ET3DV6 SN:1788 September 19, 2006

DASY - Parameters of Probe: ET3DV6 SN:1788

Sensitivity in Free Space[A]

NormX	1.73 ± 10.1%	$\mu V/(V/m)^2$	DCP X	95 mV
NormY	1.67 ± 10.1%	$\mu V/(V/m)^2$	DCP Y	101 mV
NormZ	1.70 ± 10.1%	$\mu V/(V/m)^2$	DCP Z	93 mV

Diode Compression[B]

Sensitivity in Tissue Simulating Liquid (Conversion Factors)

Please see Page 8.

Boundary Effect

TSL 900 MHz Typical SAR gradient: 5 % per mm

Sensor Center to Phantom Surface Distance		3.7 mm	4.7 mm
SAR_{be} [%]	Without Correction Algorithm	7.9	4.3
SAR_{be} [%]	With Correction Algorithm	0.1	0.3

TSL 1810 MHz Typical SAR gradient: 10 % per mm

Sensor Center to Phantom Surface Distance		3.7 mm	4.7 mm
SAR_{be} [%]	Without Correction Algorithm	11.8	7.0
SAR_{be} [%]	With Correction Algorithm	0.2	0.4

Sensor Offset

Probe Tip to Sensor Center 2.7 mm

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

[A] The uncertainties of NormX,Y,Z do not affect the E^2-field uncertainty inside TSL (see Page 8).

[B] Numerical linearization parameter: uncertainty not required.

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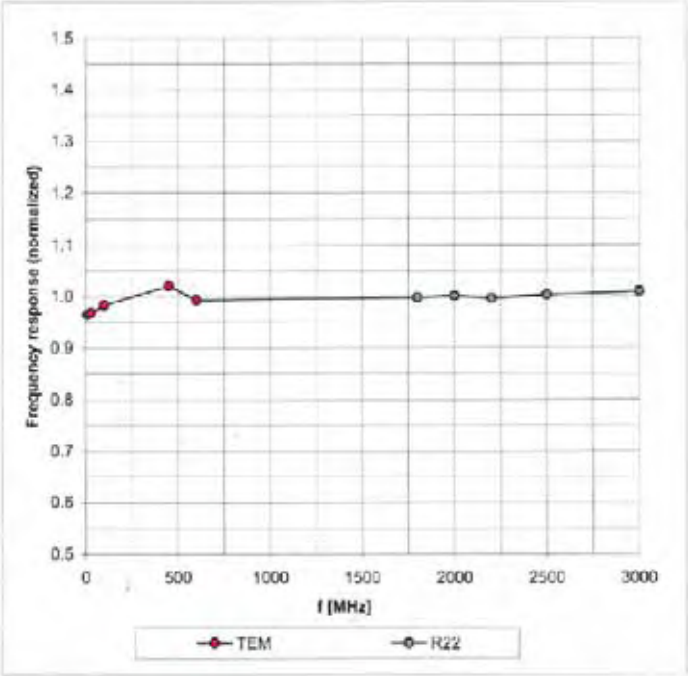
ET3DV6 SN:1788 September 19, 2006

Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of E-field: ± 6.3% (k=2)

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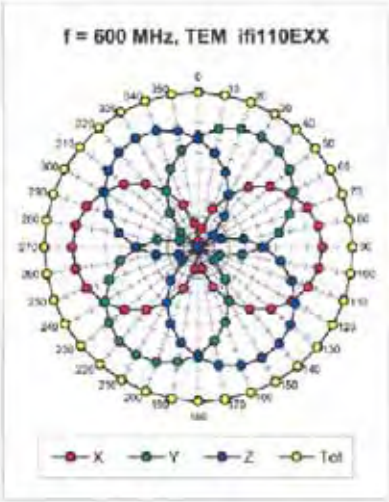
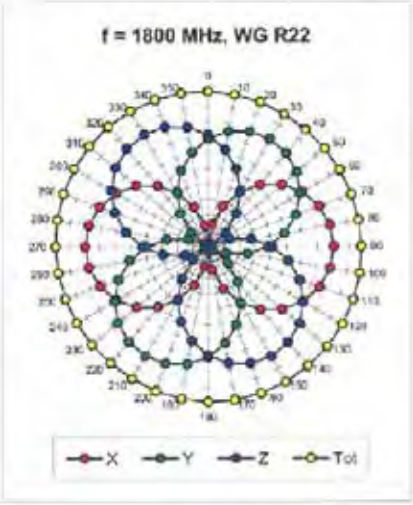
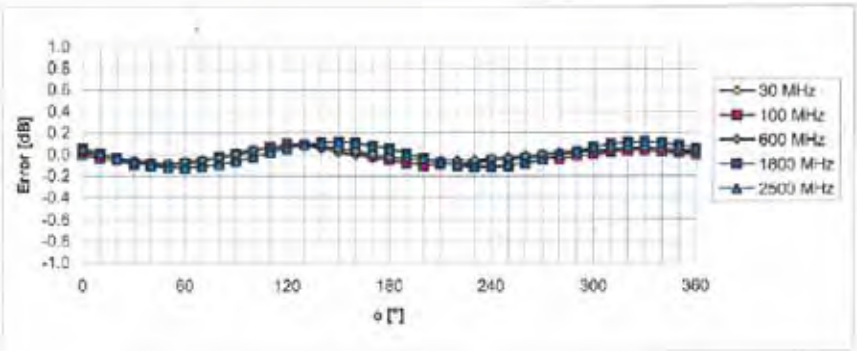
Receiving Pattern (ϕ), ϑ = 0°







Uncertainty of Axial Isotropy Assessment: ± 0.5% (k=2)

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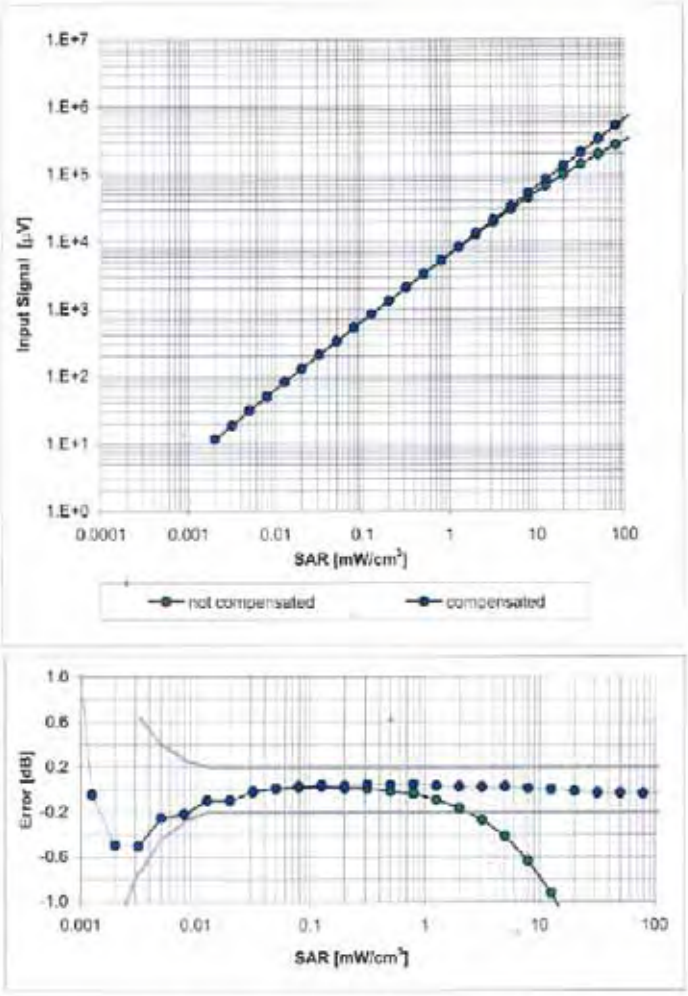
Dynamic Range f(SAR_{head})

(Waveguide R22, f = 1800 MHz)



Uncertainty of Linearity Assessment: ± 0.6% (k=2)

Certificate No: ET3-1788_Sep06 Page 7 of 9

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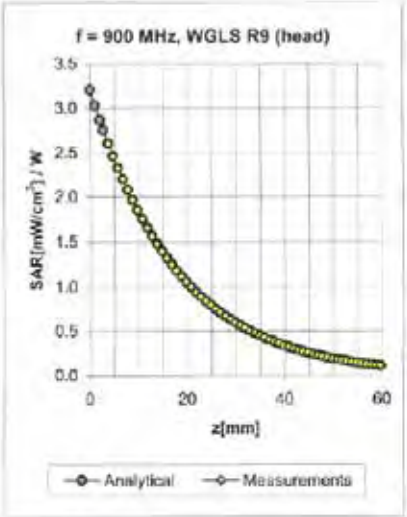
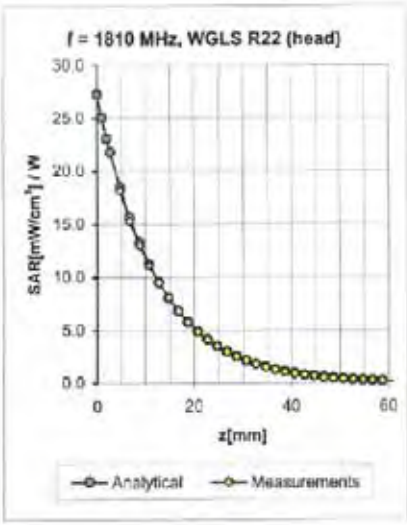
ET3DV6 SN:1788 September 19, 2006

Conversion Factor Assessment





f [MHz]	Validity [MHz][C]	TSL	Permittivity	Conductivity	Alpha	Depth	ConvF Uncertainty
900	± 50 / ± 100	Head	41.5 ± 5%	0.97 ± 5%	0.49	1.94	6.60 ± 11.0% (k=2)
1810	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.48	2.74	5.30 ± 11.0% (k=2)
2000	± 50 / ± 100	Head	40.0 ± 5%	1.40 ± 5%	0.53	2.75	5.00 ± 11.0% (k=2)
2450	± 50 / ± 100	Head	39.2 ± 5%	1.80 ± 5%	0.58	1.96	4.66 ± 11.8% (k=2)
900	± 50 / ± 100	Body	55.0 ± 5%	1.05 ± 5%	0.45	2.12	6.33 ± 11.0% (k=2)
1810	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.59	2.89	4.87 ± 11.0% (k=2)
2000	± 50 / ± 100	Body	53.3 ± 5%	1.52 ± 5%	0.56	2.79	4.50 ± 11.0% (k=2)
2450	± 50 / ± 100	Body	52.7 ± 5%	1.95 ± 5%	0.60	1.70	4.11 ± 11.8% (k=2)

[C] The validity of ± 100 MHz only applies for DASY v4.4 and higher (see Page 2). The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band.

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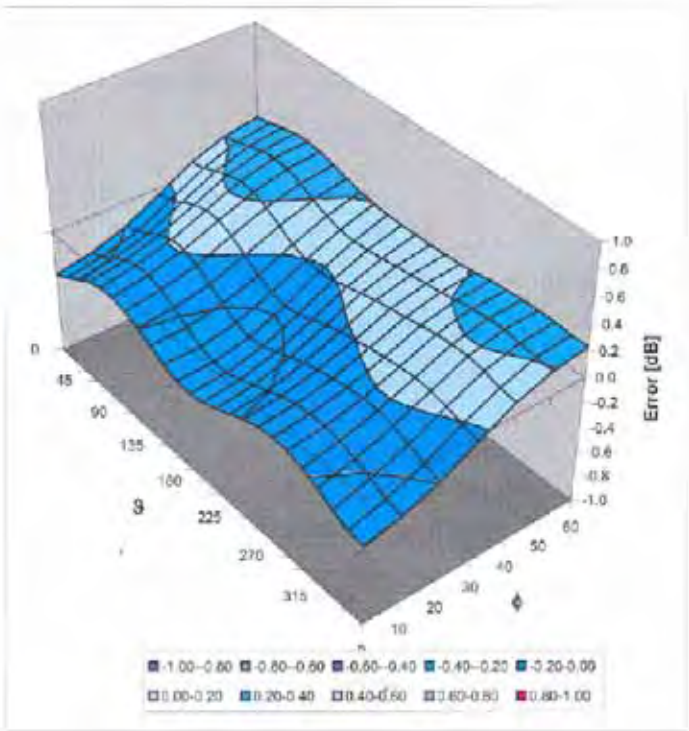
ET3DV6 SN:1788

September 19, 2006

Deviation from Isotropy in HSL

Error (φ, θ), f = 900 MHz



Uncertainty of Spherical Isotropy Assessment: ± 2.6% (k=2)

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Accreditation No.: SCS 108

Client Sporton (Auden)

Certificate No: DAE3-577_Nov06

CALIBRATION CERTIFICATE

Object	DAE3 - SD 000 D03 AA - SN: 577
Calibration procedure(s)	QA CAL-06.v12 Calibration procedure for the data acquisition electronics (DAE)
Calibration date:	November 21, 2006
Condition of the calibrated item	In Tolerance

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI). The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Calibrated by, Certificate No.)	Scheduled Calibration
Fluke Process Calibrator Type 702	SN: 6295803	13-Oct-06 (Elcal AG, No. 5492)	Oct-07
Keithley Multimeter Type 2001	SN: 0810278	03-Oct-06 (Elcal AG, No. 5478)	Oct-07
Secondary Standards	**ID #**	**Check Date (in house)**	**Scheduled Check**
Calibrator Box V1.1	SE UMS 006 AB 1002	15-Jun-06 (SPEAG, in house check)	In house check Jun-07

	Name	Function	Signature
Calibrated by:	Eric Hainfeld	Technician	
Approved by:	Fin Bomholt	R&D Director	F. Bomholt

Issued: November 21, 2006

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Certificate No: DAE3-577_Nov06 Page 1 of 5

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Accreditation No.: **SCS 108**

Glossary

DAE	data acquisition electronics
Connector angle	information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle*: The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters contain technical information as a result from the performance test and require no uncertainty.
- *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
- *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
- *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
- *AD Converter Values with Inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
- *Input Offset Measurement*: Output voltage and statistical results over a large number of zero voltage measurements.
- *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
- *Input resistance:* DAE input resistance at the connector, during internal auto-zeroing and during measurement.
- *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
- *Power consumption:* Typical value for information. Supply currents in various operating modes.

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DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1μV , full range = -100...+300 mV

Low Range: 1LSB = 61nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	404.355 ± 0.1% (k=2)	403.806 ± 0.1% (k=2)	404.276 ± 0.1% (k=2)
Low Range	3.92854 ± 0.7% (k=2)	3.93862 ± 0.7% (k=2)	3.93591 ± 0.7% (k=2)

Connector Angle

Connector Angle to be used in DASY system	268 ° ± 1 °

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Appendix

1. DC Voltage Linearity

High Range		Input (µV)	Reading (µV)	Error (%)
Channel X	+ Input	200000	199999.5	0.00
Channel X	+ Input	20000	20005.87	0.03
Channel X	- Input	20000	-19998.71	-0.01
Channel Y	+ Input	200000	200000	0.00
Channel Y	+ Input	20000	20004.22	0.02
Channel Y	- Input	20000	-20003.23	0.02
Channel Z	+ Input	200000	200000.6	0.00
Channel Z	+ Input	20000	20005.24	0.03
Channel Z	- Input	20000	-20001.80	0.01

Low Range		Input (µV)	Reading (µV)	Error (%)
Channel X	+ Input	2000	1999.9	0.00
Channel X	+ Input	200	200.27	0.13
Channel X	- Input	200	-200.73	0.36
Channel Y	+ Input	2000	2000.1	0.00
Channel Y	+ Input	200	199.22	-0.39
Channel Y	- Input	200	-200.86	0.43
Channel Z	+ Input	2000	1999.9	0.00
Channel Z	+ Input	200	199.28	-0.36
Channel Z	- Input	200	-200.94	0.47

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (µV)	Low Range Average Reading (µV)
Channel X	200	14.24	12.49
	- 200	-12.13	-12.92
Channel Y	200	-6.51	-7.06
	- 200	6.05	5.81
Channel Z	200	1.09	0.86
	- 200	-2.86	-2.63

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (µV)	Channel Y (µV)	Channel Z (µV)
Channel X	200	-	2.51	0.09
Channel Y	200	0.43	-	3.37
Channel Z	200	-0.55	0.96	-

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4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	15970	16306
Channel Y	15851	16305
Channel Z	16208	17088

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec
Input 10MΩ

	Average (µV)	min. Offset (µV)	max. Offset (µV)	Std. Deviation (µV)
Channel X	-0.51	-1.55	0.47	0.50
Channel Y	-2.06	-4.32	-0.65	0.60
Channel Z	-1.63	-2.56	-0.15	0.35

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance

	Zeroing (MOhm)	Measuring (MOhm)
Channel X	0.2000	199.8
Channel Y	0.2000	200.7
Channel Z	0.2000	199.8

8. Low Battery Alarm Voltage (verified during pre test)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (verified during pre test)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.0	+6	+14
Supply (- Vcc)	-0.01	-8	-9

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