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Accreditation No.: **SCS 108**

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Multilateral Agreement for the recognition of calibration certificates

Client **Auden**

Certificate No: **DAE4-910_Dec13**

CALIBRATION CERTIFICATE

Object **DAE4 - SD 000 D04 BK - SN: 910**

Calibration procedure(s) **QA CAL-06.v26**
Calibration procedure for the data acquisition electronics (DAE)

Calibration date: **December 17, 2013**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature $(22 \pm 3)^{\circ}\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Keithley Multimeter Type 2001	SN: 0810278	01-Oct-13 (No:13976)	Oct-14
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Auto DAE Calibration Unit	SE UWS 053 AA 1001	07-Jan-13 (in house check)	In house check: Jan-14
Calibrator Box V2.1	SE UMS 006 AA 1002	07-Jan-13 (in house check)	In house check: Jan-14

Calibrated by:	Name R.Mayoraz	Function Technician	Signature 
Approved by:	Fin Bornholt	Deputy Technical Manager	

Issued: December 17, 2013

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Glossary

DAE data acquisition electronics
Connector angle information used in DASY system to align probe sensor X to the robot coordinate system.

Methods Applied and Interpretation of Parameters

- *DC Voltage Measurement:* Calibration Factor assessed for use in DASY system by comparison with a calibrated instrument traceable to national standards. The figure given corresponds to the full scale range of the voltmeter in the respective range.
- *Connector angle:* The angle of the connector is assessed measuring the angle mechanically by a tool inserted. Uncertainty is not required.
- The following parameters as documented in the Appendix contain technical information as a result from the performance test and require no uncertainty.
 - *DC Voltage Measurement Linearity:* Verification of the Linearity at +10% and -10% of the nominal calibration voltage. Influence of offset voltage is included in this measurement.
 - *Common mode sensitivity:* Influence of a positive or negative common mode voltage on the differential measurement.
 - *Channel separation:* Influence of a voltage on the neighbor channels not subject to an input voltage.
 - *AD Converter Values with inputs shorted:* Values on the internal AD converter corresponding to zero input voltage
 - *Input Offset Measurement:* Output voltage and statistical results over a large number of zero voltage measurements.
 - *Input Offset Current:* Typical value for information; Maximum channel input offset current, not considering the input resistance.
 - *Input resistance:* Typical value for information: DAE input resistance at the connector, during internal auto-zeroing and during measurement.
 - *Low Battery Alarm Voltage:* Typical value for information. Below this voltage, a battery alarm signal is generated.
 - *Power consumption:* Typical value for information. Supply currents in various operating modes.

DC Voltage Measurement

A/D - Converter Resolution nominal

High Range: 1LSB = 6.1 μ V , full range = -100...+300 mV

Low Range: 1LSB = 61nV , full range = -1.....+3mV

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Calibration Factors	X	Y	Z
High Range	403.322 $\pm$ 0.02% (k=2)	402.723 $\pm$ 0.02% (k=2)	403.207 $\pm$ 0.02% (k=2)
Low Range	3.98182 $\pm$ 1.50% (k=2)	3.94224 $\pm$ 1.50% (k=2)	3.94936 $\pm$ 1.50% (k=2)

Connector Angle

Connector Angle to be used in DASY system	233.0 ° $\pm$ 1 °
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Appendix

1. DC Voltage Linearity

High Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	200032.32	-0.83	-0.00
Channel X + Input	20004.60	1.54	0.01
Channel X - Input	-20002.78	3.07	-0.02
Channel Y + Input	200035.16	1.90	0.00
Channel Y + Input	20001.98	-1.07	-0.01
Channel Y - Input	-20006.13	-0.17	0.00
Channel Z + Input	200035.21	2.05	0.00
Channel Z + Input	20002.94	-0.06	-0.00
Channel Z - Input	-20006.08	-0.02	0.00

Low Range	Reading (μV)	Difference (μV)	Error (%)
Channel X + Input	2000.35	0.48	0.02
Channel X + Input	200.15	0.15	0.08
Channel X - Input	-200.04	0.14	-0.07
Channel Y + Input	2000.33	0.65	0.03
Channel Y + Input	199.54	-0.32	-0.16
Channel Y - Input	-201.29	-1.11	0.55
Channel Z + Input	2001.04	1.27	0.06
Channel Z + Input	198.05	-1.62	-0.81
Channel Z - Input	-201.41	-1.23	0.61

2. Common mode sensitivity

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Common mode Input Voltage (mV)	High Range Average Reading (μV)	Low Range Average Reading (μV)
Channel X	200	-14.07	-15.91
	- 200	17.64	15.36
Channel Y	200	5.92	6.01
	- 200	-6.42	-6.96
Channel Z	200	-11.90	-12.13
	- 200	9.23	9.49

3. Channel separation

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	Input Voltage (mV)	Channel X (μV)	Channel Y (μV)	Channel Z (μV)
Channel X	200	-	5.20	-3.06
Channel Y	200	10.28	-	5.40
Channel Z	200	11.13	8.33	-

4. AD-Converter Values with inputs shorted

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

	High Range (LSB)	Low Range (LSB)
Channel X	16187	15921
Channel Y	15383	16628
Channel Z	16716	16362

5. Input Offset Measurement

DASY measurement parameters: Auto Zero Time: 3 sec; Measuring time: 3 sec

Input 10M Ω

	Average (μ V)	min. Offset (μ V)	max. Offset (μ V)	Std. Deviation (μ V)
Channel X	-0.00	-1.68	1.68	0.70
Channel Y	0.62	-0.76	1.86	0.60
Channel Z	-1.19	-2.62	0.29	0.69

6. Input Offset Current

Nominal Input circuitry offset current on all channels: <25fA

7. Input Resistance (Typical values for information)

	Zeroing (kOhm)	Measuring (MOhm)
Channel X	200	200
Channel Y	200	200
Channel Z	200	200

8. Low Battery Alarm Voltage (Typical values for information)

Typical values	Alarm Level (VDC)
Supply (+ Vcc)	+7.9
Supply (- Vcc)	-7.6

9. Power Consumption (Typical values for information)

Typical values	Switched off (mA)	Stand by (mA)	Transmitting (mA)
Supply (+ Vcc)	+0.01	+6	+14
Supply (- Vcc)	-0.01	-8	-9



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Client **Sporton-CN (Auden)**

Certificate No: **ER3-2528_Mar14**

CALIBRATION CERTIFICATE

Object **ER3DV6 - SN:2528**

Calibration procedure(s) **QA CAL-02.v8, QA CAL-25.v6**
 Calibration procedure for E-field probes optimized for close near field
 evaluations in air

Calibration date: **March 24, 2014**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
 The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature $(22 \pm 3)^{\circ}\text{C}$ and humidity $< 70\%$.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter E4419B	GB41293874	04-Apr-13 (No. 217-01733)	Apr-14
Power sensor E4412A	MY41498087	04-Apr-13 (No. 217-01733)	Apr-14
Reference 3 dB Attenuator	SN: S5054 (3c)	04-Apr-13 (No. 217-01737)	Apr-14
Reference 20 dB Attenuator	SN: S5277 (20x)	04-Apr-13 (No. 217-01735)	Apr-14
Reference 30 dB Attenuator	SN: S5129 (30b)	04-Apr-13 (No. 217-01738)	Apr-14
Reference Probe ER3DV6	SN: 2328	10-Oct-13 (No. ER3-2328_Oct13)	Oct-14
DAE4	SN: 789	15-May-13 (No. DAE4-789_May13)	May-14
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Apr-13)	In house check: Apr-16
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-13)	In house check: Oct-14

Calibrated by:	Name Claudio Leubler	Function Laboratory Technician	Signature
Approved by:	Name Katja Pokovic	Function Technical Manager	Signature

Issued: March 26, 2014

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Glossary:

$NORM_{x,y,z}$	sensitivity in free space
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization ϕ	ϕ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005
- CTIA Test Plan for Hearing Aid Compatibility, April 2010.

Methods Applied and Interpretation of Parameters:

- $NORM_{x,y,z}$: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- $NORM(f)_{x,y,z} = NORM_{x,y,z} * frequency\_response$ (see Frequency Response Chart).
- $DCP_{x,y,z}$: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- $A_{x,y,z}$; $B_{x,y,z}$; $C_{x,y,z}$; $D_{x,y,z}$; $VR_{x,y,z}$: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy): in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle: The angle is assessed using the information gained by determining the $NORM_{x,y,z}$ (no uncertainty required).

Probe ER3DV6

SN:2528

Manufactured: April 26, 2010
Calibrated: March 24, 2014

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2528

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm ($\mu\text{V}/(\text{V}/\text{m})^2$)	1.95	1.61	1.88	$\pm 10.1 \%$
DCP (mV) ^B	98.5	100.1	98.9	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Unc ^E (k=2)
0	CW	X	0.0	0.0	1.0	0.00	163.4	$\pm 3.5 \%$
		Y	0.0	0.0	1.0		217.8	
		Z	0.0	0.0	1.0		201.0	
10011-CAB	UMTS-FDD (WCDMA)	X	3.27	66.5	18.4	2.91	132.5	$\pm 0.9 \%$
		Y	3.32	67.0	18.8		130.7	
		Z	3.21	66.0	18.0		122.4	
10021-DAB	GSM-FDD (TDMA, GMSK)	X	24.54	99.8	29.1	9.39	112.5	$\pm 2.2 \%$
		Y	24.27	99.3	29.1		114.2	
		Z	29.16	99.9	29.7		130.0	
10039-CAB	CDMA2000 (1xRTT, RC1)	X	5.08	67.2	19.4	4.57	137.1	$\pm 1.4 \%$
		Y	5.07	67.3	19.5		131.4	
		Z	4.90	66.3	18.7		122.6	
10081-CAB	CDMA2000 (1xRTT, RC3)	X	4.08	66.3	18.8	3.97	131.4	$\pm 0.9 \%$
		Y	4.07	66.4	18.9		125.5	
		Z	3.93	65.3	18.1		118.2	
10295-AAB	CDMA2000, RC1, SO3, 1/8th Rate 25 fr.	X	18.84	99.2	39.7	12.49	99.9	$\pm 3.5 \%$
		Y	19.81	99.6	39.5		148.7	
		Z	22.15	99.6	38.7		104.6	

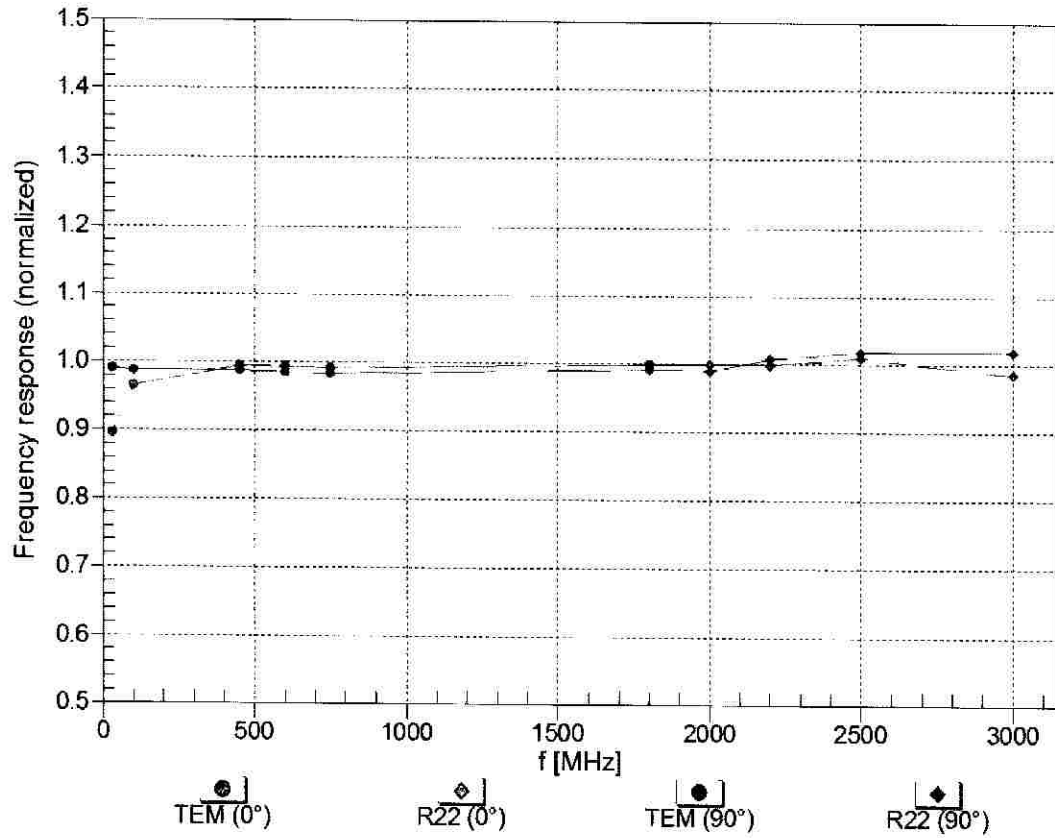
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^B Numerical linearization parameter: uncertainty not required.

^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

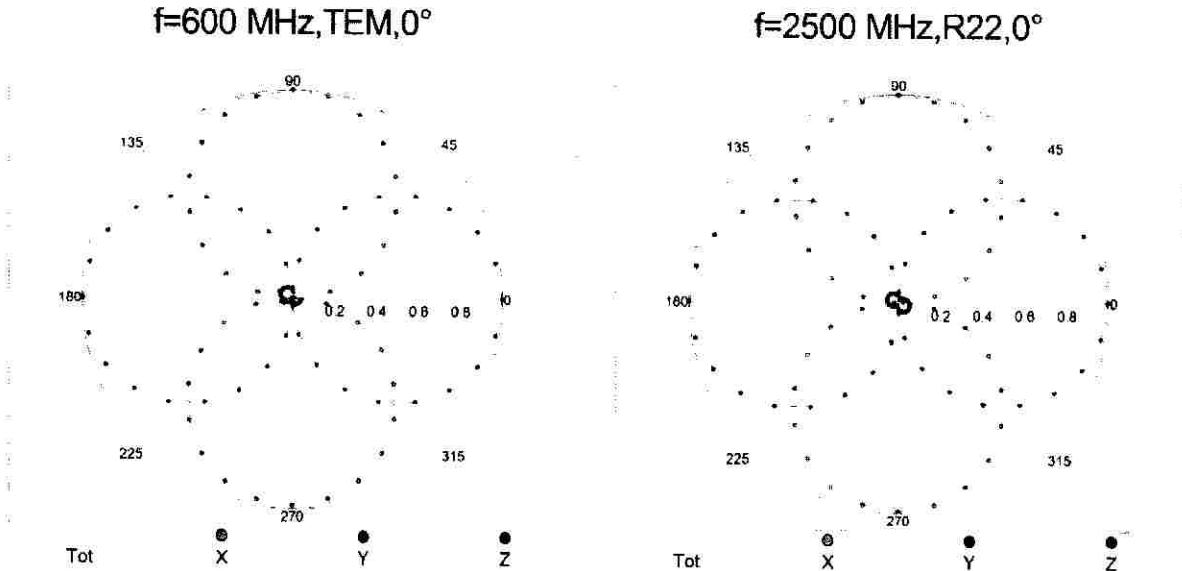
Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide: R22)

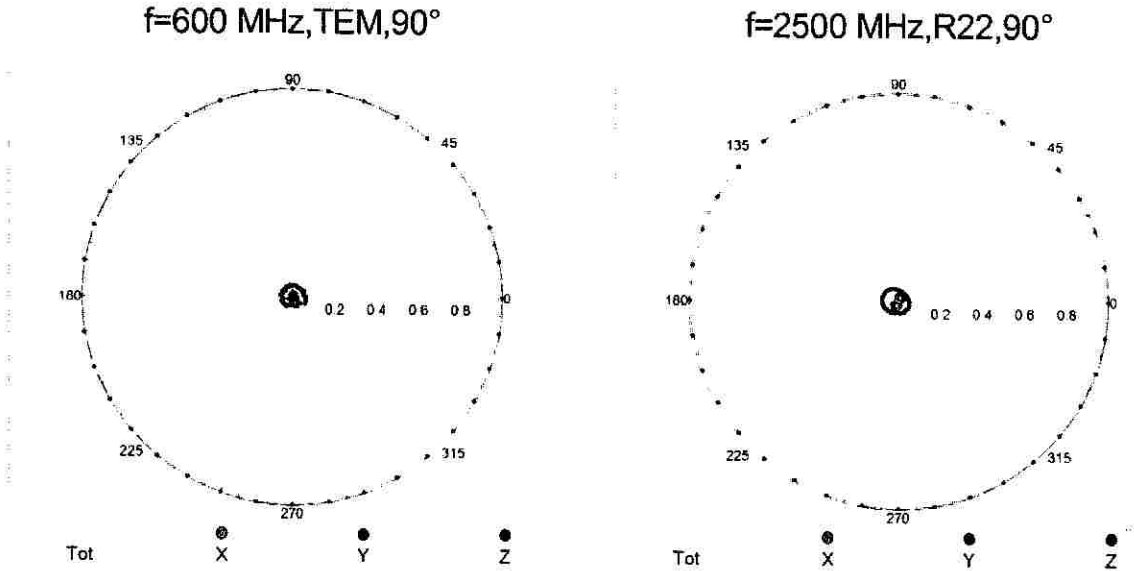


Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

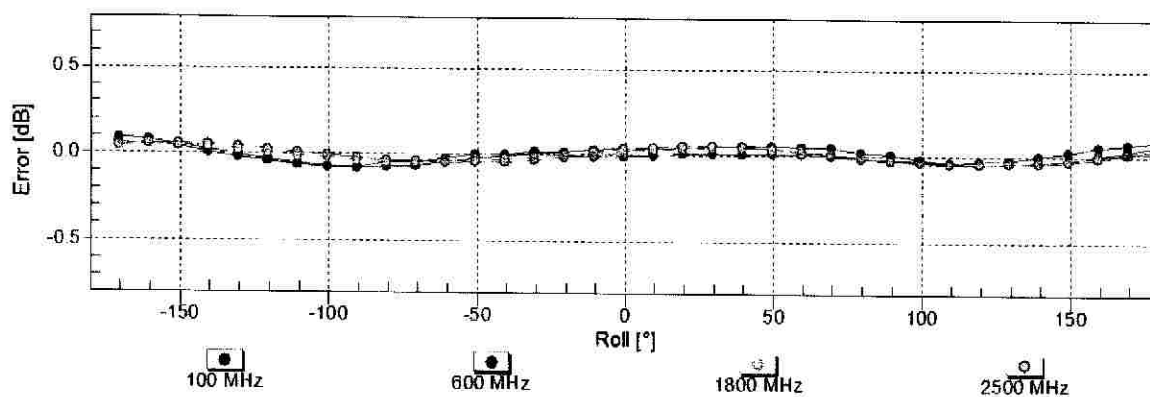
Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Receiving Pattern (ϕ), $\vartheta = 90^\circ$

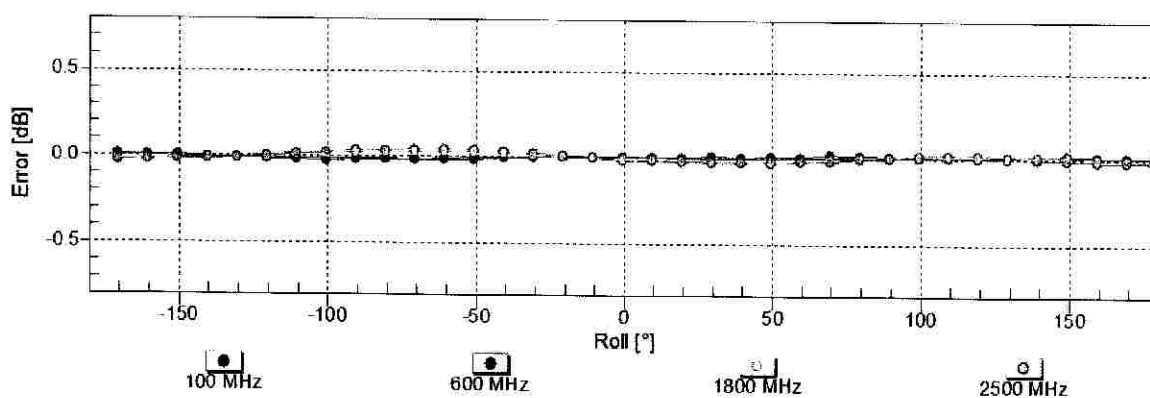


Receiving Pattern (ϕ), $\vartheta = 0^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

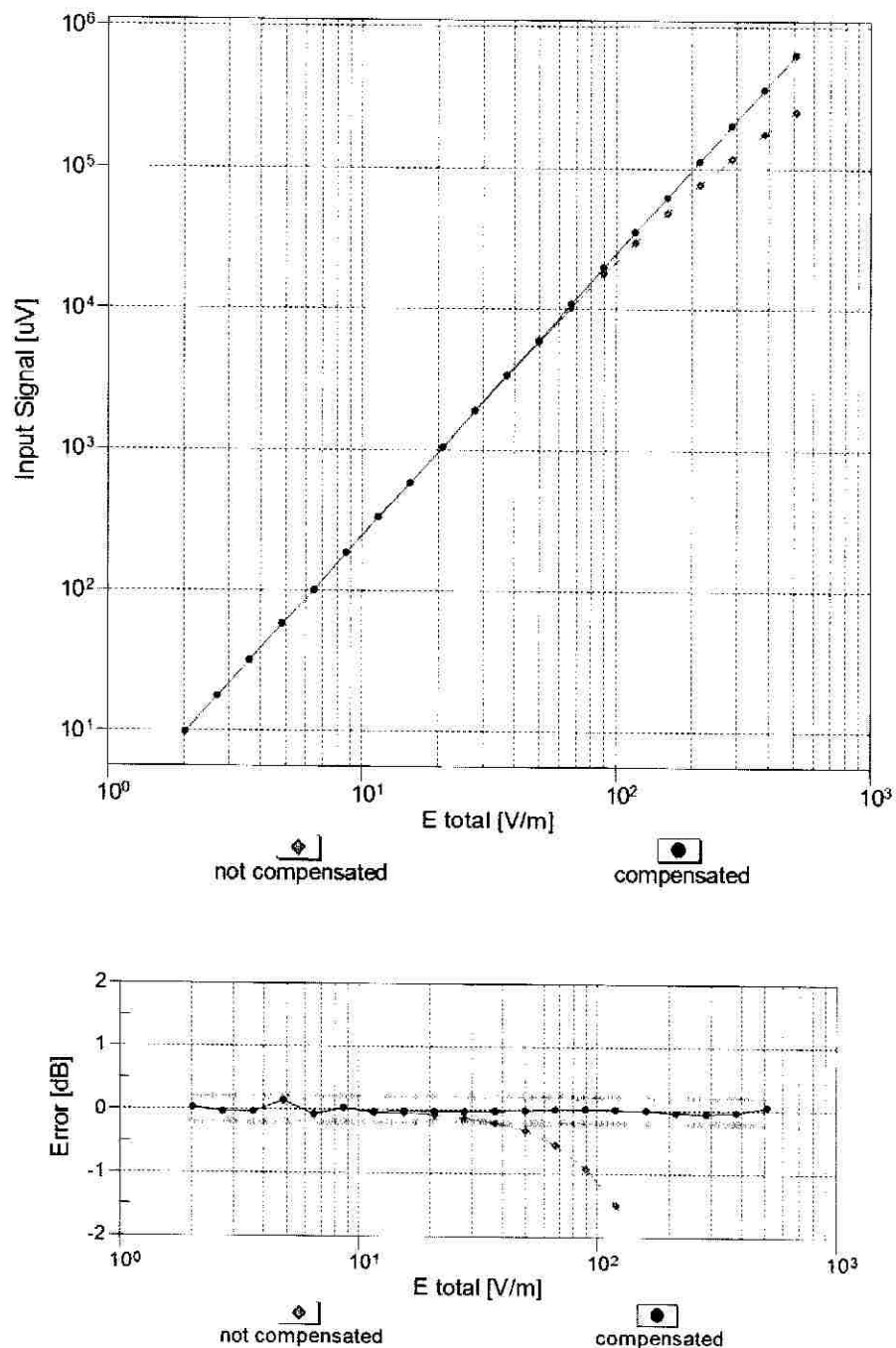
Receiving Pattern (ϕ), $\vartheta = 90^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Dynamic Range f(E-field)

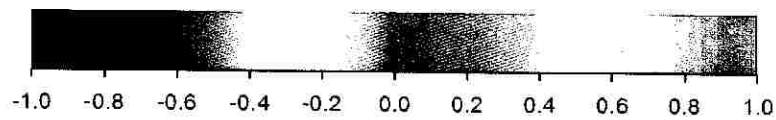
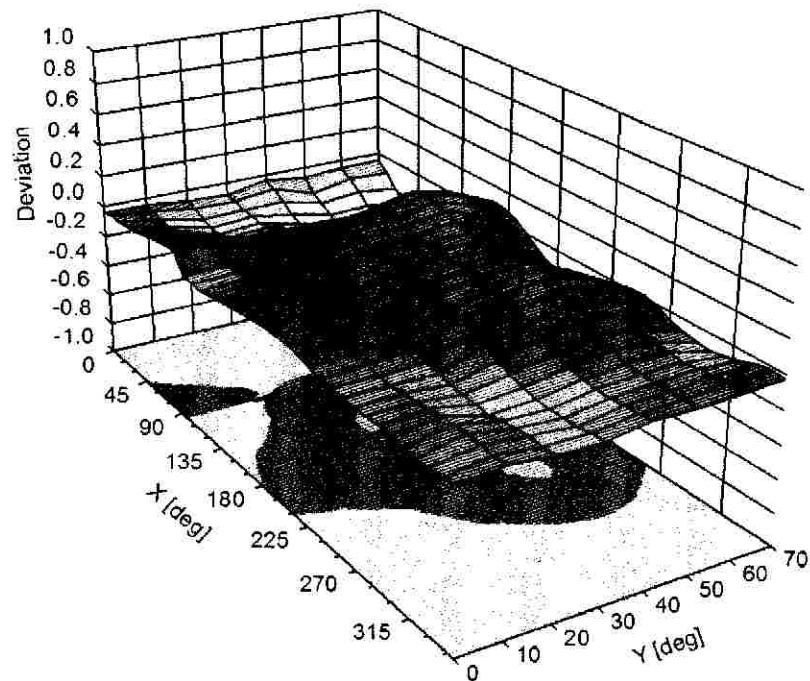
(TEM cell , f = 900 MHz)



Uncertainty of Linearity Assessment: $\pm 0.6\%$ ($k=2$)

Deviation from Isotropy in Air

Error (ϕ , θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

DASY/EASY - Parameters of Probe: ER3DV6 - SN:2528

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	-20.7
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	10 mm
Tip Diameter	8 mm
Probe Tip to Sensor X Calibration Point	2.5 mm
Probe Tip to Sensor Y Calibration Point	2.5 mm
Probe Tip to Sensor Z Calibration Point	2.5 mm



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Client **Sporton-CN (Auden)**

Certificate No: **H3-6342_Mar14**

CALIBRATION CERTIFICATE

Object **H3DV6 - SN:6342**

Calibration procedure(s) **QA CAL-03.v8, QA CAL-25.v6**
 Calibration procedure for H-field probes optimized for close near field
 evaluations in air

Calibration date: **March 24, 2014**

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Power sensor E4412A	MY41498087	04-Apr-13 (No. 217-01733)	Apr-14
Reference 3 dB Attenuator	SN: S5054 (3c)	04-Apr-13 (No. 217-01737)	Apr-14
Reference 20 dB Attenuator	SN: S5277 (20x)	04-Apr-13 (No. 217-01735)	Apr-14
Reference 30 dB Attenuator	SN: S5129 (30b)	04-Apr-13 (No. 217-01738)	Apr-14
Reference Probe H3DV6	SN: 6182	10-Oct-13 (No. H3-6182 Oct13)	Oct-14
DAE4	SN: 789	15-May-13 (No. DAE4-789 May13)	May-14
Secondary Standards	ID	Check Date (in house)	Scheduled Check
RF generator HP 8648C	US3642U01700	4-Aug-99 (in house check Apr-13)	In house check: Apr-16
Network Analyzer HP 8753E	US37390585	18-Oct-01 (in house check Oct-13)	In house check: Oct-14

Calibrated by:	Name Claudio Leubler	Function Laboratory Technician	Signature
Approved by:	Katja Pokovic	Technical Manager	
			Issued: March 26, 2014

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Glossary:

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CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization ϕ	ϕ rotation around probe axis
Polarization ϑ	ϑ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\vartheta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEEE Std 1309-2005, "IEEE Standard for calibration of electromagnetic field sensors and probes, excluding antennas, from 9 kHz to 40 GHz", December 2005.
- CTIA Test Plan for Hearing Aid Compatibility, April 2010.

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\vartheta = 0$ for XY sensors and $\vartheta = 90$ for Z sensor ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide).
- X, Y, Z(f)_a0a1a2** = **X, Y, Z_a0a1a2** * *frequency_response* (see Frequency Response Chart).
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal (no uncertainty required). DCP does not depend on frequency nor media.
- PAR**: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; D_{x,y,z}; VR_{x,y,z}; A, B, C, D** are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- Spherical isotropy (3D deviation from isotropy)**: in a locally homogeneous field realized using an open waveguide setup.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the **X_a0a1a2** (no uncertainty required).

Probe H3DV6

SN:6342

Manufactured: August 3, 2010
Calibrated: March 24, 2014

Calibrated for DASY/EASY Systems
(Note: non-compatible with DASY2 system!)

DASY/EASY - Parameters of Probe: H3DV6 - SN:6342

Basic Calibration Parameters

		Sensor X	Sensor Y	Sensor Z	Unc (k=2)
Norm (A/m / $\sqrt{\text{mV}}$)	a0	2.61E-003	2.67E-003	2.88E-003	$\pm 5.1 \%$
Norm (A/m / $\sqrt{\text{mV}}$)	a1	-7.30E-006	-2.33E-005	6.58E-005	$\pm 5.1 \%$
Norm (A/m / $\sqrt{\text{mV}}$)	a2	-2.78E-005	-3.37E-005	-3.74E-005	$\pm 5.1 \%$
DCP (mV) ^B		95.6	93.5	93.5	

Modulation Calibration Parameters

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Unc ^E (k=2)
0	CW	X	0.0	0.0	1.0	0.00	135.9	$\pm 3.5 \%$
		Y	0.0	0.0	1.0		132.6	
		Z	0.0	0.0	1.0		135.9	

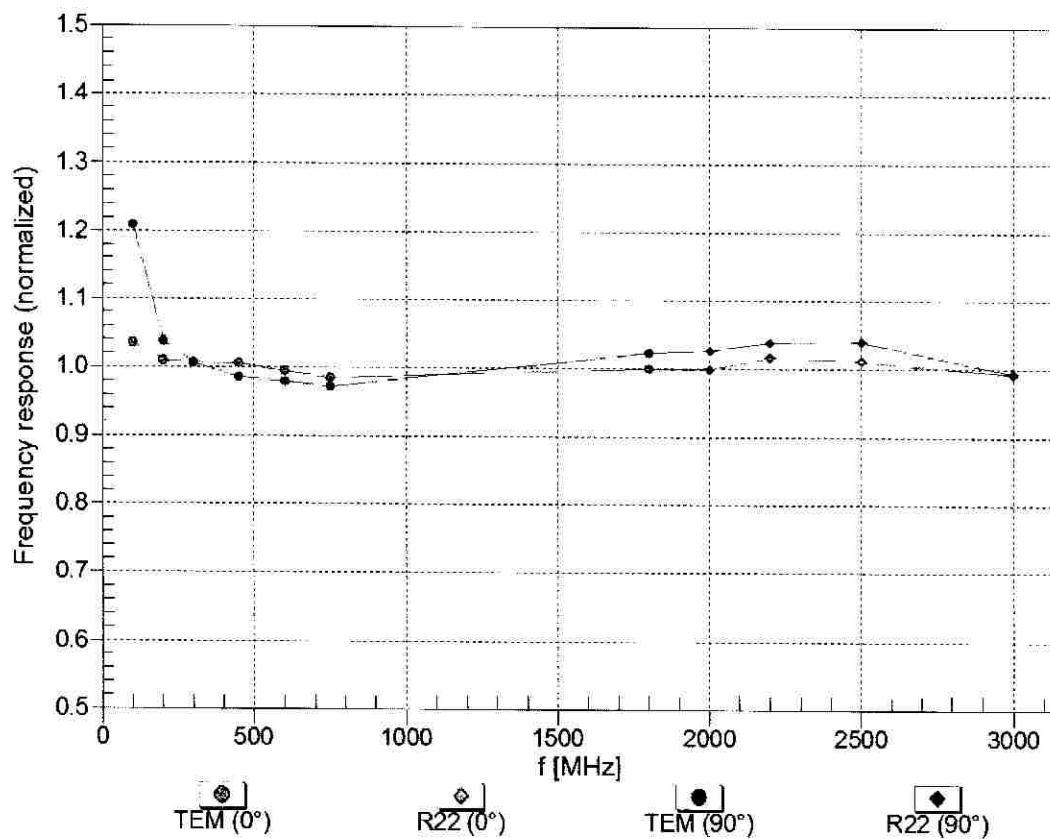
The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^B Numerical linearization parameter: uncertainty not required.

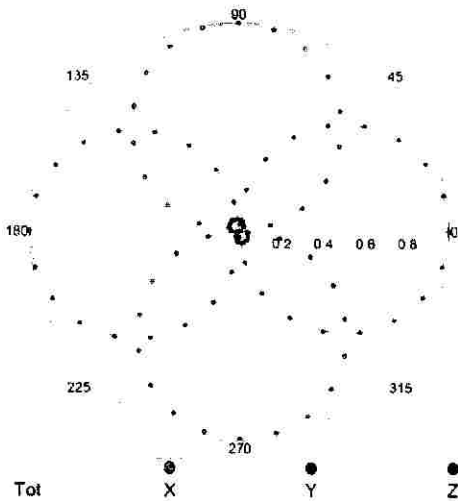
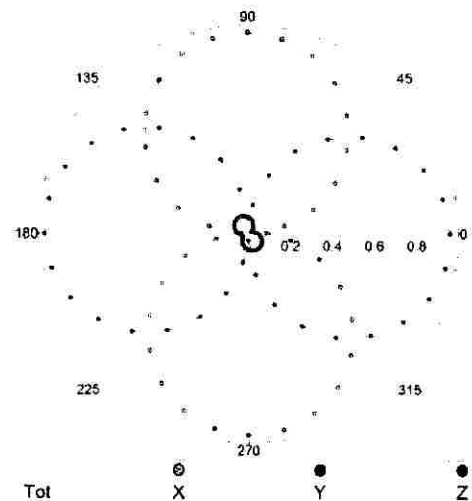
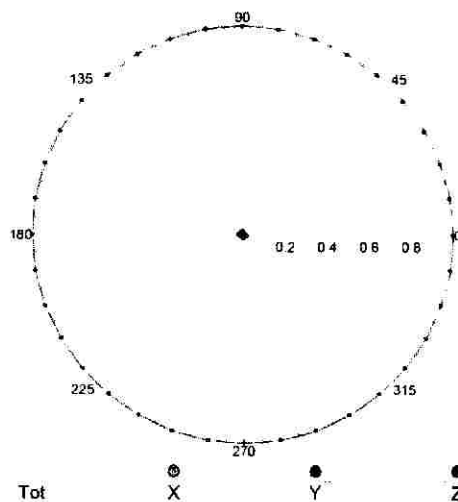
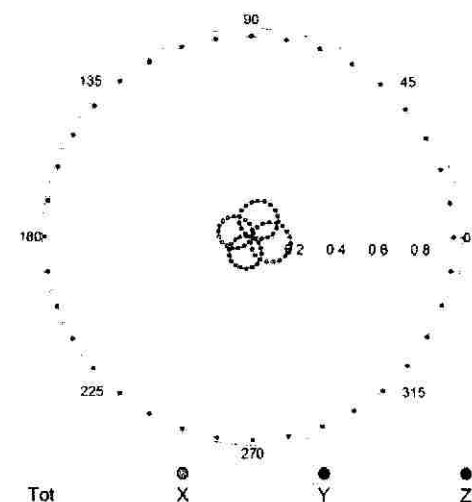
^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

Frequency Response of H-Field

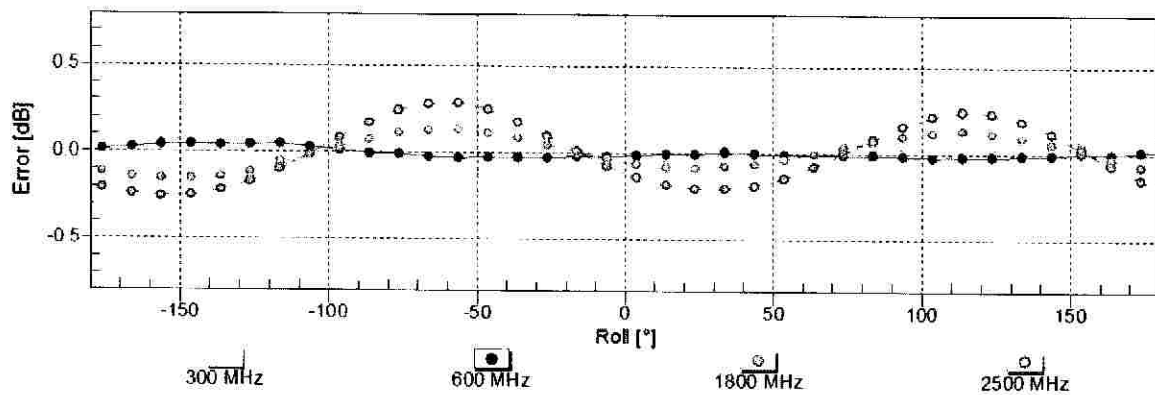
(TEM-Cell:ifi110 EXX, Waveguide: R22)



Uncertainty of Frequency Response of H-field: $\pm 6.3\%$ ($k=2$)

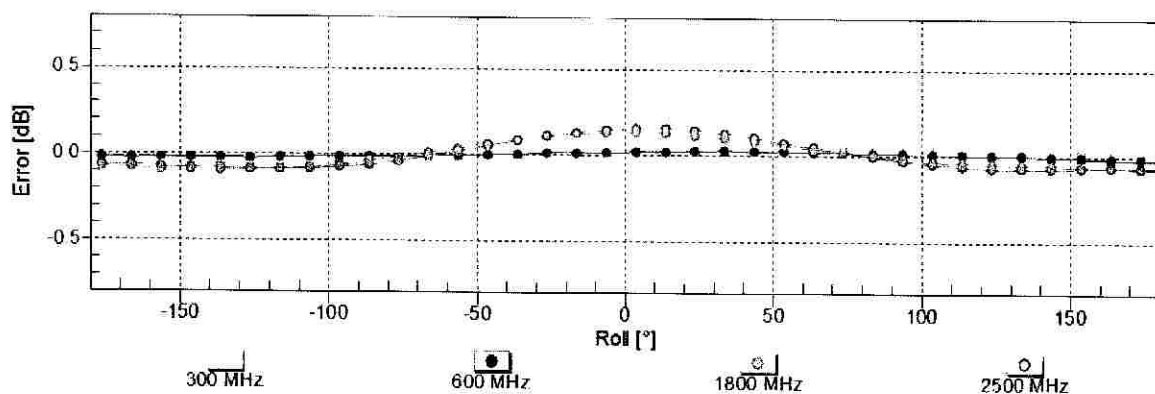
Receiving Pattern (ϕ), $\vartheta = 0^\circ$ **f=600 MHz, TEM, 0°** **f=2500 MHz, R22, 0°** **Receiving Pattern (ϕ), $\vartheta = 90^\circ$** **f=600 MHz, TEM, 90°** **f=2500 MHz, R22, 90°** 

Receiving Pattern (ϕ), $\vartheta = 0^\circ$



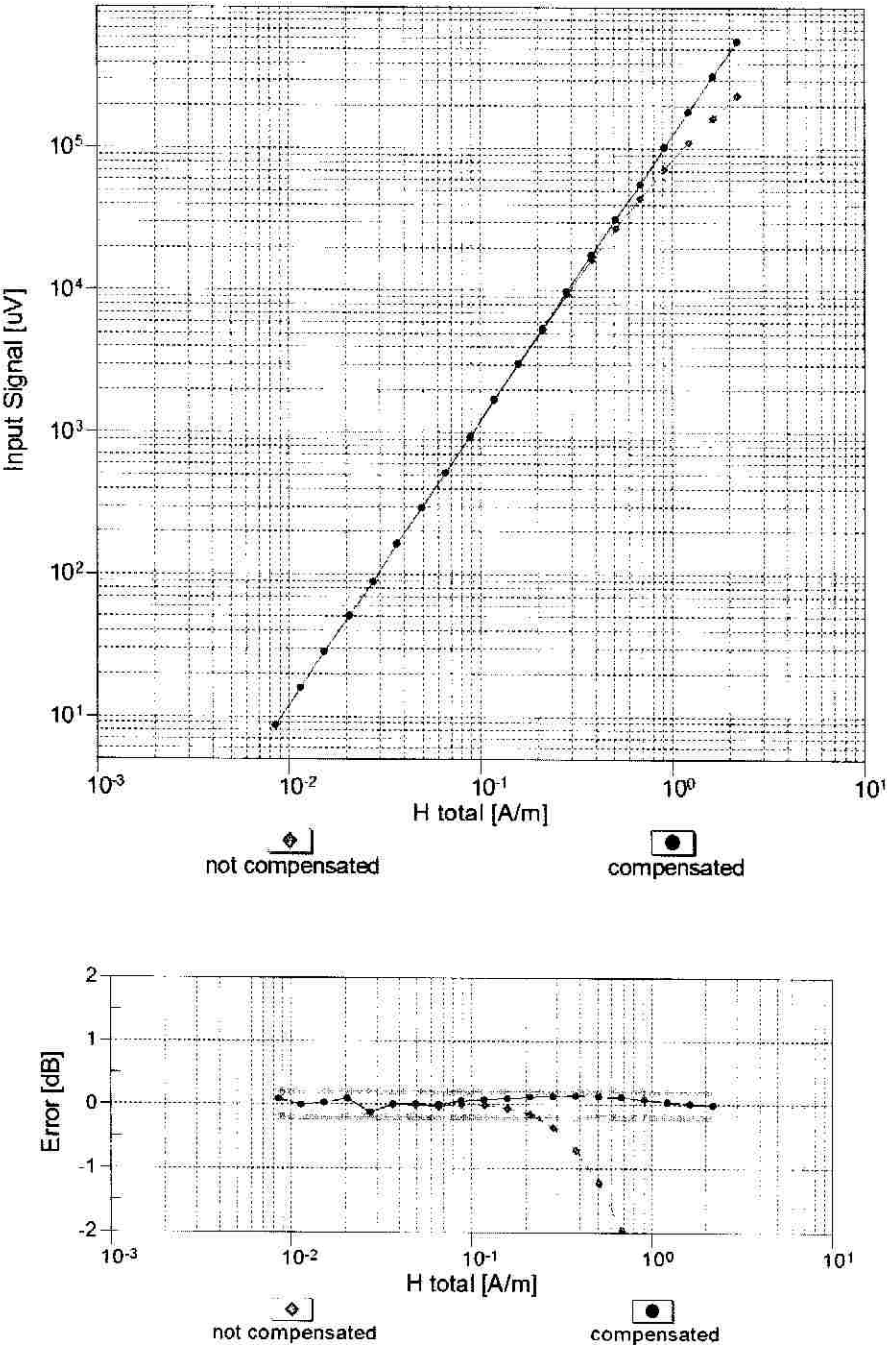
Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

Receiving Pattern (ϕ), $\vartheta = 90^\circ$



Uncertainty of Axial Isotropy Assessment: $\pm 0.5\%$ ($k=2$)

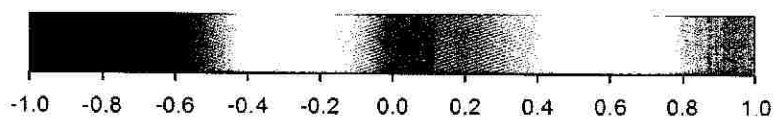
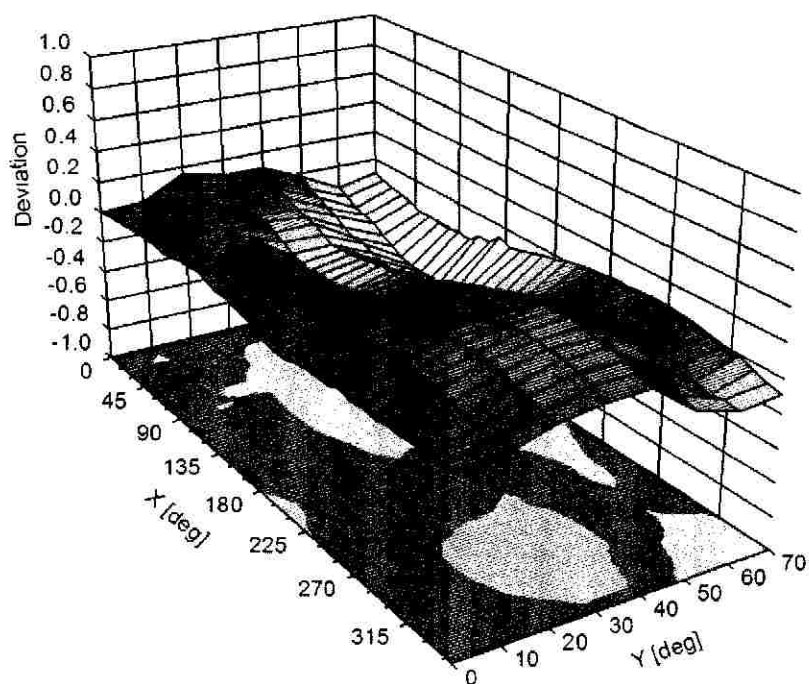
Dynamic Range f(H-field)
(TEM cell, f = 900 MHz)



Uncertainty of Linearity Assessment: $\pm 0.6\%$ ($k=2$)

Deviation from Isotropy in Air

Error (ϕ , θ), $f = 900$ MHz



Uncertainty of Spherical Isotropy Assessment: $\pm 2.6\%$ ($k=2$)

DASY/EASY - Parameters of Probe: H3DV6 - SN:6342

Other Probe Parameters

Sensor Arrangement	Rectangular
Connector Angle (°)	163.7
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	20 mm
Tip Diameter	6 mm
Probe Tip to Sensor X Calibration Point	3 mm
Probe Tip to Sensor Y Calibration Point	3 mm
Probe Tip to Sensor Z Calibration Point	3 mm