



中认信通

CHINA CERTIFICATION ICT CO., LTD (DONGGUAN)



SAR TEST REPORT

Applicant: Winplus Co., Ltd.

Address: Suites 6-11, 7th Floor, Corporation Park, 11 On La Shatin, Hong Kong

Product Name: Minicam

FCC ID: WUI-BEON

Standard(s): 47 CFR Part 2(2.1093)

The above equipment has been tested and found compliant with the requirement of the relativestandards by China Certification ICT Co., Ltd (Dongguan)

Report Number: 2403T53154E-20

Date Of Issue: 2024/05/25

Reviewed By: Ken Zong

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SAR TEST RESULTSSUMMARY

Operation Frequency Bands	Highest Reported 1g SAR (W/kg)		Limits (W/kg)
	Face Up (Gap 0mm)	Body (Gap 0mm)	
WLAN 2.4G	0.02	0.10	1.6
Maximum Simultaneous Transmission SAR			
Items	Face Up (Gap 0mm)	Body (Gap 0mm)	Limits
Sum SAR(W/kg)	N/A	N/A	1.6
SPLSR	N/A	N/A	0.04
EUT Received Date:	2024/05/16		
Tested Date:	2024/05/23		
Tested Result:	Pass		

Note:
Face Up can share data with Body Front ,because Body uses 0mm separation distance to evaluate SAR.

Test Facility

The Test site used by China Certification ICT Co., Ltd (Dongguan) to collect test data is located on the No. 113, Pingkang Road, Dalang Town, Dongguan, Guangdong, China.

The lab has been recognized as the FCC accredited lab under the KDB 974614 D01 and is listed in the FCC Public Access Link (PAL) database, FCC Registration No. : 442868, the FCC Designation No. : CN1314.

Declarations

China Certification ICT Co., Ltd (Dongguan) is not responsible for the authenticity of any test data provided by the applicant. Data included from the applicant that may affect test results are marked with a triangle symbol “▲”. Customer model name, addresses, names, trademarks etc. are not considered data.

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DOCUMENT REVISION HISTORY

Revision Number	Report Number	Description of Revision	Date of Revision
1.0	2403T53154E-20	Original Report	2024/05/25

1. GENERAL INFORMATION

1.1 Product Description for Device under Test (EUT)

EUT Name:	Minicam
EUT Model:	BT534349
Device Type:	Portable
Exposure Category:	Population / Uncontrolled
Antenna Type(s):	Internal Antenna
Body-Worn Accessories:	None
Proximity Sensor:	None
Operation modes:	WLAN
Frequency Band:	WLAN 2.4G: 2412-2462 MHz/2422MHz-2452 MHz(TX/RX)
Conducted RF Power:	WLAN 2.4G: 18.6dBm
Dimensions (L*W*H):	48mm (L) *28mm (W) *25mm (H)
Rated Input Voltage:	DC3.7V from Rechargeable Battery
Serial Number:	2L9L-1
Normal Operation:	Face Up and Body

1.2 Test Specification, Methods and Procedures

The tests documented in this report were performed in accordance with FCC 47 CFR § 2.1093, IEEE 1528-2013, the following FCC Published RF exposure KDB procedures:

KDB 447498 D01 General RF Exposure Guidance v06
KDB 648474 D04 Handset SAR v01r03
KDB865664 D01 SAR Measurement 100 MHz to 6 GHz v01r04
KDB865664 D02 RF Exposure Reporting v01r02
KDB 248227 D01 802.11 Wi-Fi SAR v02r02

TCB Workshop April 2019:RF Exposure Procedures

1.3 SAR Limits

FCC Limit

EXPOSURE LIMITS	SAR (W/kg)	
	(General Population / Uncontrolled Exposure Environment)	(Occupational / Controlled Exposure Environment)
Spatial Average (averaged over the whole body)	0.08	0.4
Spatial Peak (averaged over any 1 g of tissue)	1.60	8.0
Spatial Peak (hands/wrists/feet/ankles averaged over 10 g)	4.0	20.0

Population/Uncontrolled Environments are defined as locations where there is the exposure of individual who have no knowledge or control of their exposure.

Occupational/Controlled Environments are defined as locations where there is exposure that maybe incurred by people who are aware of the potential for exposure (i.e. as a result of employment or occupation).

General Population/Uncontrolled environments Spatial Peak limit 1.6W/kg for 1g SAR applied to the EUT.

1.4 FACILITIES

The Test site used by China Certification ICT Co., Ltd (Dongguan) to collect test data is located on the No. 113, Pingkang Road, Dalang Town, Dongguan,Guangdong, China.

The test sites and measurement facilities used to collect data are located at:

☒ SAR Lab 1☐ SAR Lab 2

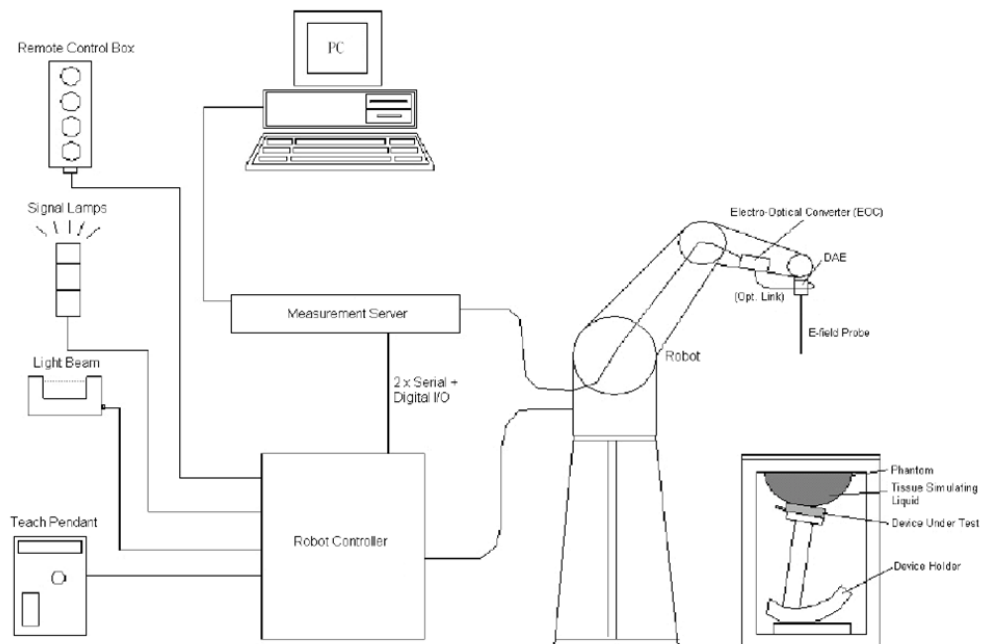
2. SAR MEASUREMENT SYSTEM

These measurements were performed with the automated near-field scanning system DASY5 from Schmid & Partner Engineering AG (SPEAG) which is the Fifth generation of the system shown in the figure hereinafter:



DASY5 System Description

The DASY5 system for performing compliance tests consists of the following items:



- A standard high precision 6-axis robot with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal application, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running Win7 professional operating system and the DASY52 software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

DASY5 Measurement Server

The DASY5 measurement server is based on a PC/104 CPU board with a 400MHz Intel ULVCeleron, 128MB chip-disk and 128MB RAM. The necessary circuits for communication with the DAE4 (or DAE3) electronics box, as well as the 16 bit AD-converter system for optical detection and digital I/O interface are contained on the DASY5 I/O board, which is directly connected to the PC/104 bus of the CPU board.



The measurement server performs all real-time data evaluation of field measurements and surface detection, controls robot movements and handles safety operation. The PC operating system cannot interfere with these time critical processes. All connections are supervised by a watchdog, and disconnection of any of the cables to the measurement server will automatically disarm the robot and disable all program-controlled robot movements. Furthermore, the measurement server is equipped with an expansion port which is reserved for future applications. Please note that this expansion port does not have a standardized point out, and therefore only devices provided by SPEAG can be connected. Devices from any other supplier could seriously damage the measurement server.

Data Acquisition Electronics

The data acquisition electronics (DAE4) consist of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder with a control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information, as well as an optical uplink for commands and the clock.

The mechanical probe mounting device includes two different sensor systems for frontal and sideways probe contacts. They are used for mechanical surface detection and probe collision detection.

The input impedance of both the DAE4 as well as of the DAE3 box is 200M Ω ; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.

EX3DV4 E-Field Probes

Frequency	4 MHz - 10 GHz Linearity: ± 0.2 dB (30 MHz to 10 GHz)
Directivity	± 0.1 dB in TSL (rotation around probe axis) ± 0.3 dB in TSL (rotation normal to probe axis)
Dynamic Range	10 μ W/g to > 100 mW/g Linearity: ± 0.2 dB (noise: typically < 1 μ W/g)
Dimensions	Overall length: 337 mm (Tip: 20 mm) Tip diameter: 2.5 mm (Body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm
Application	High precision dosimetric measurements in any exposure scenario (e.g., very strong gradient fields); the only probe that enables compliance testing for frequencies up to 6 GHz with precision of better 30%.
Compatibility	DASY3, DASY4, DASY52, DASY6, DASY8 SAR, EASY6, EASY4/MRI

Calibration Frequency Points for EX3DV4 E-Field Probes SN: 7329 Calibrated: 2024/3/27

Calibration Frequency Point(MHz)	Frequency Range(MHz)		Conversion Factor		
	From	To	X	Y	Z
750 Head	650	850	8.79	10.07	9.05
900 Head	850	1000	8.42	9.50	8.93
1750 Head	1650	1850	7.56	8.56	7.71
1900 Head	1850	2000	7.37	8.32	7.54
2300 Head	2200	2400	7.21	8.13	7.41
2450 Head	2400	2550	7.05	7.92	7.22
2600 Head	2550	2700	6.91	7.77	7.08
5250 Head	5140	5360	4.96	5.61	5.16
5500 Head	5390	5610	4.38	4.98	4.56
5750 Head	5640	5860	4.54	5.16	4.70

SAM Twin Phantom

The SAM twin phantom is a fiberglass shell phantom with 2mm shell thickness (except the ear region, where shell thickness increases to 6 mm). The phantom has three measurement areas:

- _ Left Head
- _ Right Head
- _ Flat phantom

The phantom table for the DASY systems based on the robots have the size of 100 x 50 x 85 cm (L x W x H). For easy dislocation these tables have fork lift cut outs at the bottom.

The bottom plate contains three pairs of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. Only one device holder is necessary if two phantoms are used (e.g., for different liquids)



A white cover is provided to cover the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. Free space scans of devices on top of this phantom cover are possible. Three reference marks are provided on the phantom counter. These reference marks are used to teach the absolute phantom position relative to the robot.

Robots

The DASY5 system uses the high precision industrial robot. The robot offers the same features important for our application:

- High precision (repeatability 0.02mm)
- High reliability (industrial design)
- Low maintenance costs (virtually maintenance free due to direct drive gears; no belt drives)
- Jerk-free straight movements (brushless synchrony motors; no stepper motors)
- Low ELF interference (motor control fields shielded via the closed metallic construction shields)

The above mentioned robots are controlled by the Staubli CS8c robot controllers. All information regarding the use and maintenance of the robot arm and the robot controller is contained on the CDs delivered along with the robot. Paper manuals are available upon request direct from Staubli.

SAR Scan Procedures

Step 1: Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. The minimum distance of probe sensors to surface is 1.4 mm. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

Step 2: Area Scans

Area scans are defined prior to the measurement process being executed with a user defined variable spacing between each measurement point (integral) allowing low uncertainty measurements to be conducted. Scans defined for FCC applications utilize a 15mm² step integral, with 1.5mm interpolation used to locate the peak SAR area used for zoom scan assessments.

Where the system identifies multiple SAR peaks (which are within 25% of peak value) the system will provide the user with the option of assessing each peak location individually for zoom scan averaging.

Area Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz

	≤ 3 GHz	> 3 GHz
Maximum distance from closest measurement point (geometric center of probe sensors) to phantom surface	5 mm ± 1 mm	$\frac{1}{2} \cdot \delta \cdot \ln(2)$ mm ± 0.5 mm
Maximum probe angle from probe axis to phantom surface normal at the measurement location	30° ± 1°	20° ± 1°
Maximum area scan spatial resolution: Δx_{Area} , Δy_{Area}	≤ 2 GHz: ≤ 15 mm 2 – 3 GHz: ≤ 12 mm	3 – 4 GHz: ≤ 12 mm 4 – 6 GHz: ≤ 10 mm
	When the x or y dimension of the test device, in the measurement plane orientation, is smaller than the above, the measurement resolution must be ≤ the corresponding x or y dimension of the test device with at least one measurement point on the test device.	

Step 3: Zoom Scan (Cube Scan Averaging)

The averaging zoom scan volume utilized in the DASY5 software is in the shape of a cube and the side dimension of a 1 g or 10 g mass is dependent on the density of the liquid representing the simulated tissue. A density of 1000 kg/m³ is used to represent the head and body tissue density and not the phantom liquid density, in order to be consistent with the definition of the liquid dielectric properties, i.e. the side length of the 1g cube is 5mm, with the side length of the 10g cube is 21.5mm.

Zoom Scan Parameters extracted from KDB 865664 D01 SAR Measurement 100 MHz to 6 GHz

			≤ 3 GHz	> 3 GHz
Maximum zoom scan spatial resolution: Δx_{Zoom} , Δy_{Zoom}			≤ 2 GHz: ≤ 8 mm 2 – 3 GHz: ≤ 5 mm*	3 – 4 GHz: ≤ 5 mm* 4 – 6 GHz: ≤ 4 mm*
Maximum zoom scan spatial resolution, normal to phantom surface	uniform grid: $\Delta z_{\text{Zoom}}(n)$		≤ 5 mm	3 – 4 GHz: ≤ 4 mm 4 – 5 GHz: ≤ 3 mm 5 – 6 GHz: ≤ 2 mm
	graded grid	$\Delta z_{\text{Zoom}}(1)$: between 1 st two points closest to phantom surface	≤ 4 mm	3 – 4 GHz: ≤ 3 mm 4 – 5 GHz: ≤ 2.5 mm 5 – 6 GHz: ≤ 2 mm
		$\Delta z_{\text{Zoom}}(n>1)$: between subsequent points	$\leq 1.5 \cdot \Delta z_{\text{Zoom}}(n-1)$ mm	
Minimum zoom scan volume	x, y, z		≥ 30 mm	3 – 4 GHz: ≥ 28 mm 4 – 5 GHz: ≥ 25 mm 5 – 6 GHz: ≥ 22 mm
Note: δ is the penetration depth of a plane-wave at normal incidence to the tissue medium; see IEEE Std 1528-2013 for details.				
* When zoom scan is required and the <i>reported</i> SAR from the <i>area scan based 1-g SAR estimation</i> procedures of KDB Publication 447498 is ≤ 1.4 W/kg, ≤ 8 mm, ≤ 7 mm and ≤ 5 mm zoom scan resolution may be applied, respectively, for 2 GHz to 3 GHz, 3 GHz to 4 GHz and 4 GHz to 6 GHz.				

Step 4: Power Drift Measurement

The Power Drift Measurement measures the field at the same location as the most recent power reference measurement within the same procedure, and with the same settings. The Power Drift Measurement gives the field difference in dB from the reading conducted within the last Power Reference Measurement. This allows a user to monitor the power drift of the device under test within a batch process. The measurement procedure is the same as Step 1.

When the cube intersects with the surface of the phantom, it is oriented so that 3 vertices touch the surface of the shell or the center of a face is tangent to the surface. The face of the cube closest to the surface is modified in order to conform to the tangent surface.

The zoom scan integer steps can be user defined so as to reduce uncertainty, but normal practice for typical test applications (including FCC) utilize a physical step of 7 x 7 x 7 (5mmx5mmx5mm) providing a volume of 30 mm in the X & Y & Z axis.

Tissue Dielectric Parameters for Head and Body Phantoms

The head tissue dielectric parameters recommended by the IEC 62209-1:2016

Recommended Tissue Dielectric Parameters for Head liquid

Table A.3 – Dielectric properties of the head tissue-equivalent liquid

Frequency MHz	Relative permittivity ϵ_r	Conductivity (σ) S/m
300	45,3	0,87
450	43,5	0,87
<i>750</i>	<i>41,9</i>	<i>0,89</i>
835	41,5	0,90
900	41,5	0,97
1 450	40,5	1,20
<i>1 500</i>	<i>40,4</i>	<i>1,23</i>
<i>1 640</i>	<i>40,2</i>	<i>1,31</i>
<i>1 750</i>	<i>40,1</i>	<i>1,37</i>
1 800	40,0	1,40
1 900	40,0	1,40
2 000	40,0	1,40
<i>2 100</i>	<i>39,8</i>	<i>1,49</i>
<i>2 300</i>	<i>39,5</i>	<i>1,67</i>
2 450	39,2	1,80
<i>2 600</i>	<i>39,0</i>	<i>1,96</i>
3 000	38,5	2,40
<i>3 500</i>	<i>37,9</i>	<i>2,91</i>
<i>4 000</i>	<i>37,4</i>	<i>3,43</i>
<i>4 500</i>	<i>36,8</i>	<i>3,94</i>
<i>5 000</i>	<i>36,2</i>	<i>4,45</i>
<i>5 200</i>	<i>36,0</i>	<i>4,66</i>
<i>5 400</i>	<i>35,8</i>	<i>4,86</i>
<i>5 600</i>	<i>35,5</i>	<i>5,07</i>
<i>5 800</i>	<i>35,3</i>	<i>5,27</i>
<i>6 000</i>	<i>35,1</i>	<i>5,48</i>

NOTE For convenience, permittivity and conductivity values at those frequencies which are not part of the original data provided by Drossos et al. [33] or the extension to 5 800 MHz are provided (i.e. the values shown *in italics*). These values were linearly interpolated between the values in this table that are immediately above and below these values, except the values at 6 000 MHz that were linearly extrapolated from the values at 3 000 MHz and 5 800 MHz.

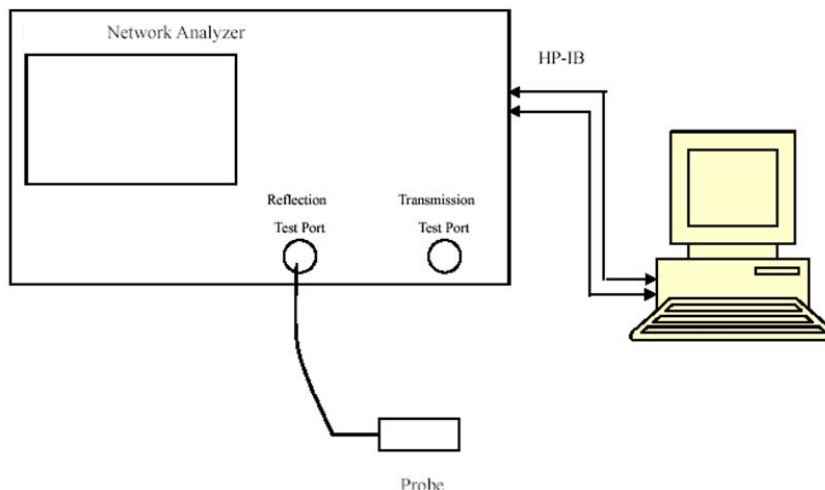
3. EQUIPMENT LIST AND CALIBRATION

3.1 Equipments List & Calibration Information

Equipment	Model	S/N	Calibration Date	Calibration Due Date
DASY5 Test Software	DASY52.10	N/A	NCR	NCR
DASY5 Measurement Server	DASY5 4.5.12	1567	NCR	NCR
Data Acquisition Electronics	DAE4	1354	2023/11/17	2024/11/16
E-Field Probe	EX3DV4	7329	2024/3/27	2025/3/26
Mounting Device	MD4HHTV5	BJPCTC0152	NCR	NCR
Twin SAM	Twin SAM V5.0	1412	NCR	NCR
Dipole, 2450 MHz	D2450V2	1102	2023/3/27	2026/3/26
Simulated Tissue Liquid Head(500-9500 MHz)	HBBL600-10000V6	220420-2	Each Time	/
Network Analyzer	8753B	2828A00170	2023/10/17	2024/10/16
Dielectric assessment kit	1319	SM DAK 040 CA	NCR	NCR
MXG Vector Signal Generator	N5182B	MY51350144	2024/4/1	2025/3/31
Power Meter	ML2495A	1106009	2023/8/4	2024/8/3
Pulse Power Sensor	MA2411A	10780	2023/8/4	2024/8/3
Power Amplifier	ZVE-6W-83+	637202210	NCR	NCR
Directional Coupler	441493	520Z	NCR	NCR
Attenuator	20dB, 100W	LN749	NCR	NCR
Attenuator	6dB, 150W	2754	NCR	NCR
Thermometer	DTM3000	3892	2024/4/1	2025/3/31
Thermohygrometer	HTC-1	N/A	2024/4/1	2025/3/31
Spectrum Analyzer	FSU26	100147	2024/4/1	2025/3/31

4. SAR MEASUREMENT SYSTEM VERIFICATION

4.1 Liquid Verification



Liquid Verification Setup Block Diagram

Liquid Verification Results

Frequency (MHz)	LiquidType	Liquid Parameter		Target Value		Delta (%)		Tolerance (%)
		ϵ_r	σ (S/m)	ϵ_r	σ (S/m)	$\Delta\epsilon_r$	$\Delta\sigma$ (S/m)	
2400	Simulated Tissue Liquid Head	39.869	1.731	39.3	1.76	1.45	-1.65	± 5
2410	Simulated Tissue Liquid Head	39.805	1.753	39.28	1.77	1.34	-0.96	± 5
2420	Simulated Tissue Liquid Head	39.725	1.767	39.26	1.77	1.18	-0.17	± 5
2430	Simulated Tissue Liquid Head	39.616	1.771	39.24	1.78	0.96	-0.51	± 5
2440	Simulated Tissue Liquid Head	39.566	1.795	39.22	1.79	0.88	0.28	± 5
2450	Simulated Tissue Liquid Head	39.498	1.803	39.2	1.8	0.76	0.17	± 5
2460	Simulated Tissue Liquid Head	39.377	1.814	39.19	1.81	0.48	0.22	± 5
2470	Simulated Tissue Liquid Head	39.264	1.819	39.17	1.82	0.24	-0.05	± 5
2480	Simulated Tissue Liquid Head	39.131	1.826	39.16	1.83	-0.07	-0.22	± 5
2490	Simulated Tissue Liquid Head	39.033	1.837	39.15	1.84	-0.3	-0.16	± 5
2500	Simulated Tissue Liquid Head	38.803	1.864	39.13	1.85	-0.84	0.76	± 5

*Liquid Verification above was performed on 2024/05/23.

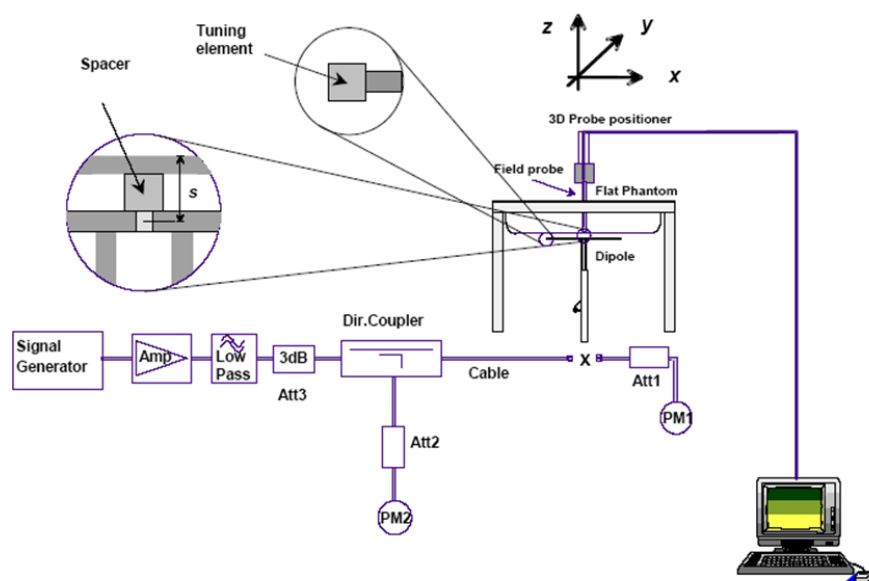
4.2 System Accuracy Verification

Prior to the assessment, the system validation kit was used to test whether the system was operating within its specifications of $\pm 10\%$. The validation results are tabulated below. And also the corresponding SAR plot is attached as well in the SAR plots files.

The spacing distances in the **System Verification Setup Block Diagram** is given by the following:

- $s = 15 \text{ mm} \pm 0,2 \text{ mm}$ for $300 \text{ MHz} \leq f \leq 1\,000 \text{ MHz}$;
- $s = 10 \text{ mm} \pm 0,2 \text{ mm}$ for $1\,000 \text{ MHz} < f \leq 3\,000 \text{ MHz}$;
- $s = 10 \text{ mm} \pm 0,2 \text{ mm}$ for $3\,000 \text{ MHz} < f \leq 6\,000 \text{ MHz}$.

System Verification Setup Block Diagram



System Accuracy Check Results

Date	Frequency Band	Liquid Type	Input Power (mW)	Measured SAR (W/kg)	Normalized to 1W (W/kg)	Target Value (W/kg)	Delta (%)	Tolerance (%)
2024/05/23	2450	Simulated Tissue Liquid Head	100	1g 5.35	53.5	50.9	5.11	± 10

*The SAR values above are normalized to 1 Watt forward power.

4.3 SAR SYSTEM VALIDATION DATA

System Performance 2450MHz Head

DUT: D2450V2; Type: 2450 MHz; Serial: 1102

Communication System: CW; Frequency: 2450 MHz; Duty Cycle: 1:1

Medium parameters used: $f = 2450$ MHz; $\sigma = 1.803$ S/m; $\epsilon_r = 39.498$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7329; ConvF(7.05, 7.92, 7.22) @2450 MHz; Calibrated: 2024/3/27
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2023/11/17
- Phantom: Twin SAM; Type: Twin SAM V5.0; Serial: TP:1412
- Measurement SW: DASY52, Version 52.10 (2); SEMCAD X Version 14.6.12 (7470)

Area Scan (9x9x1): Measurement grid: dx=12mm, dy=12mm

Maximum value of SAR (measured) = 9.64 W/kg

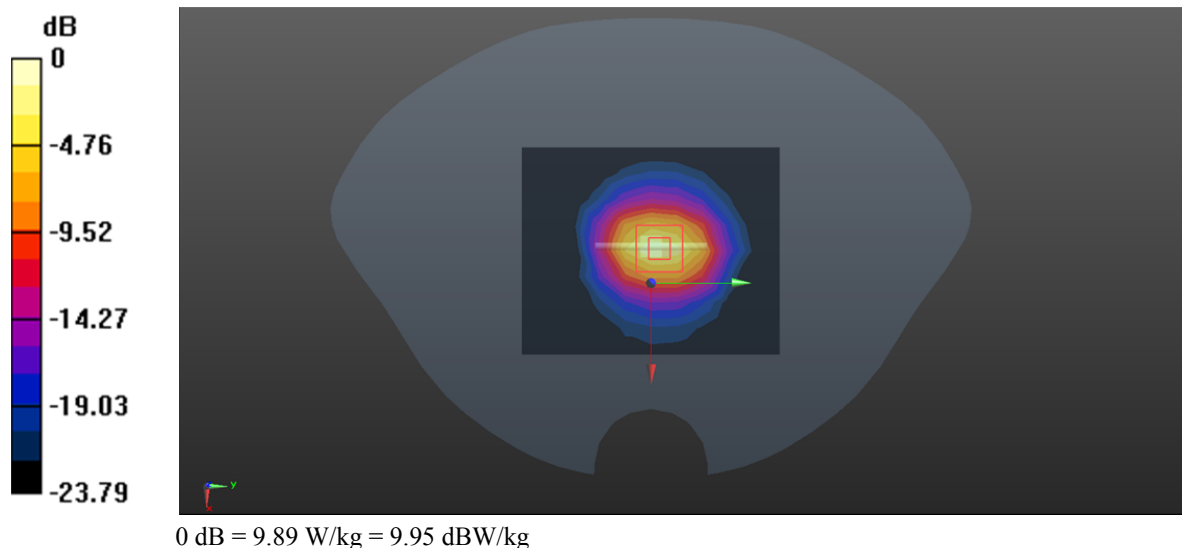
Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 57.22 V/m; Power Drift = 0.04 dB

Peak SAR (extrapolated) = 11.8 W/kg

SAR(1 g) = 5.35 W/kg; SAR(10 g) = 2.43 W/kg

Maximum value of SAR (measured) = 9.89 W/kg



5. EUT TEST STRATEGY AND METHODOLOGY

5.1 Test positions for Front-of-face configurations

A typical example of a front-of-face device is a two-way radio that is held at a close distance from the face of the user while transmitting.

When performing measurements against the flat phantom, the DUT-to-phantom separation distance may be set according to the following hierarchy.

- a) Regulatory requirement: When there is a national regulatory requirement that specifies the DUT separation distance to the phantom, the DUT shall be positioned according to this requirement.
- b) “Intended use distance” specified by the manufacturer: When there is no regulatory requirement, the intended use condition or distance specified by the manufacturer shall be used. This information shall be acquired from the user documentation accompanying the DUT.
- c) Default separation distance: When there is neither a regulatory requirement nor an intended use distance specified by the manufacturer, the DUT shall be measured with each accessible face in direct contact with the surface of the phantom.

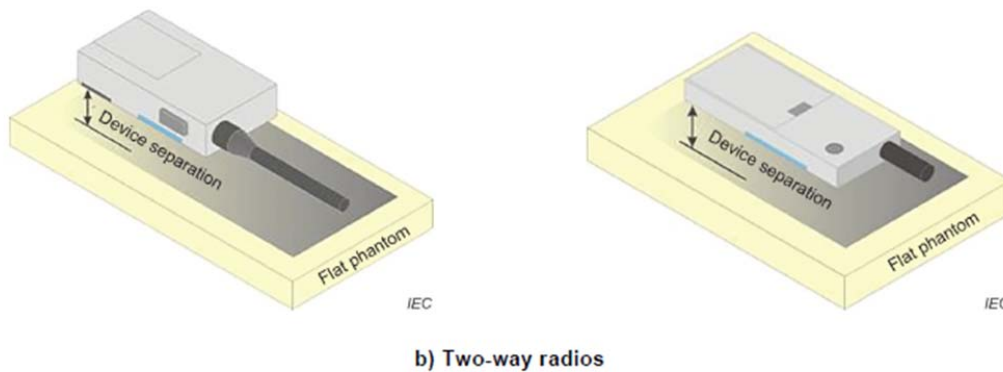


Figure 10 – Test positions for front-of-face devices

5.2 Test positions for body-worn and other configurations

Body-worn operating configurations should be tested with the belt-clips and holsters attached to the device and positioned against a flat phantom in normal use configurations. Devices with a headset output should be tested with a headset connected to the device. When multiple accessories that do not contain metallic components are supplied with the device, the device may be tested with only the accessory that dictates the closest spacing to the body. When multiple accessories that contain metallic components are supplied with the device, the device must be tested with each accessory that contains a unique metallic component. If multiple accessories share an identical metallic component (e.g., the same metallic belt-clip used with different holsters with no other metallic components), only the accessory that dictates the closest spacing to the body must be tested.

Body-worn accessories may not always be supplied or available as options for some devices that are intended to be authorized for body-worn use. A separation distance of 1.5 cm between the back of the device and a flat phantom is recommended for testing body-worn SAR compliance under such circumstances. Other separation distances may be used, but they should not exceed 2.5 cm. In these cases, the device may use body-worn accessories that provide a separation distance greater than that tested for the device provided however that the accessory contains no metallic components.

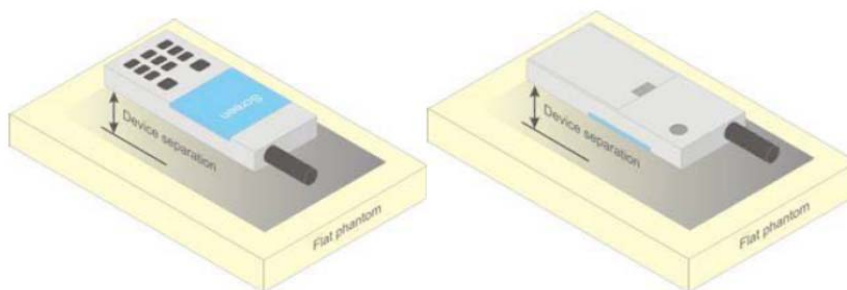


Figure 5 – Test positions for body-worn devices

5.3 Test Distance for SAR Evaluation

In this case the EUT(Equipment Under Test) is set 0mm away from the phantom, the test distance is 0mm.

5.4 SAR Evaluation Procedure

The evaluation was performed with the following procedure:

Step 1: Measurement of the SAR value at a fixed location above the ear point or central position was used as a reference value for assessing the power drop. The SAR at this point is measured at the start of the test and then again at the end of the testing.

Step 2: The SAR distribution at the exposed side of the head was measured at a distance of 4 mm from the inner surface of the shell. The area covered the entire dimension of the head or radiating structures of the EUT, the horizontal grid spacing was 15 mm x 15 mm, and the SAR distribution was determined by integrated grid of 1.5mm x 1.5mm. Based on these data, the area of the maximum absorption was determined by spline interpolation. The first Area Scan covers the entire dimension of the EUT to ensure that the hotspot was correctly identified.

Step 3: Around this point, a volume of 30 mm x 30 mm x 30 mm was assessed by measuring 7x 7 x 7 points. On the basis of this data set, the spatial peak SAR value was evaluated under the following procedure:

- 1) The data at the surface were extrapolated, since the center of the dipoles is 1.2 mm away from the tip of the probe and the distance between the surface and the lowest measuring point is 1.3 mm. The extrapolation was based on a least square algorithm. A polynomial of the fourth order was calculated through the points in z-axes. This polynomial was then used to evaluate the points between the surface and the probe tip.

- 2) The maximum Measured value was searched with a straightforward algorithm. Around this maximum the SAR values averaged over the spatial volumes (1 g or 10 g) were computed by the 3D-Spline interpolation algorithm. The 3D-Spline is composed of three one dimensional splines with the "Not a knot"-condition (in x, y and z-directions). The volume was integrated with the trapezoidal-algorithm. One thousand points (10 x 10 x 10) were Measured to calculate the averages.

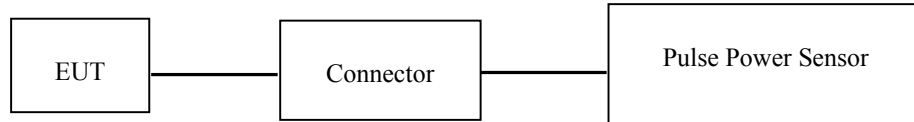
All neighboring volumes were evaluated until no neighboring volume with a higher average value was found.

Step 4: Re-measurement of the SAR value at the same location as in Step 1. If the value changed by more than 5%, the evaluation was repeated.

6. CONDUCTED OUTPUT POWER MEASUREMENT

6.1 Test Procedure

The RF output of the transmitter was connected to the input port of the Pulse Power Sensor through Connector.



WLAN

6.2 Maximum Target Output Power

Max Target Power(dBm)			
Mode/Band	Channel		
	Low	Middle	High
WLAN 2.4G(802.11b)	19	19	19
WLAN 2.4G(802.11g)	14.5	14.5	14.5
WLAN 2.4G(802.11n ht20)	15	15	15
WLAN 2.4G(802.11n ht40)	15	15	15

6.3 Test Results:

WLAN 2.4G:

Mode	Channel frequency (MHz)	Duty cycle (%)	RF Conducted Output Power (dBm)
802.11b	2412	100	18.6
	2437		18.58
	2462		18.32
802.11g	2412	100	14.36
	2437		14.15
	2462		14.18
802.11n ht20	2412	100	14.55
	2437		14.38
	2462		14.31
802.11n ht40	2422	100	14.62
	2437		14.61
	2452		14.51

Antennas Location:



7. SAR MEASUREMENT RESULTS

This page summarizes the results of the performed dosimetric evaluation.

7.1 SAR Test Data

Environmental Conditions

Temperature:	23.2-23.6℃
Relative Humidity:	46 %
ATM Pressure:	100.3 kPa
Test Date:	2024/5/23

Testing was performed by Aixlee Li.

WLAN 2.4G:

EUT Position	Frequency (MHz)	Test Mode	Max. Meas. Power (dBm)	Max. Rated Power (dBm)	1g SAR (W/kg)				
					Scaled Factor	Duty cycle Factor	Meas. SAR	Scaled SAR	Plot
Body Front (0mm)	2412	802.11b	/	/	/	/	/	/	/
	2437	802.11b	18.58	19	1.102	1	0.014	0.02	1#
	2462	802.11b	/	/	/	/	/	/	/
Body Back (0mm)	2412	802.11b	/	/	/	/	/	/	/
	2437	802.11b	18.58	19	1.102	1	0.010	0.01	2#
	2462	802.11b	/	/	/	/	/	/	/
Body Left (0mm)	2412	802.11b	/	/	/	/	/	/	/
	2437	802.11b	18.58	19	1.102	1	0.09	0.10	3#
	2462	802.11b	/	/	/	/	/	/	/
Body Right (0mm)	2412	802.11b	/	/	/	/	/	/	/
	2437	802.11b	18.58	19	1.102	1	0.00887	0.01	4#
	2462	802.11b	/	/	/	/	/	/	/
Body Top (0mm)	2412	802.11b	/	/	/	/	/	/	/
	2437	802.11b	18.58	19	1.102	1	0.00126	< 0.01	5#
	2462	802.11b	/	/	/	/	/	/	/
Body Bottom (0mm)	2412	802.11b	/	/	/	/	/	/	/
	2437	802.11b	18.58	19	1.102	1	0.00456	0.01	6#
	2462	802.11b	/	/	/	/	/	/	/

Note:

- When the 1-g SAR is $\leq 0.8\text{W/kg}$, testing for other channels are optional.
- When SAR or MPE is not measured at the maximum power level allowed for production units, the results must be scaled to the maximum tune-up tolerance limit according to the power applied to the individual channels tested to determine compliance.
- According 2016 Oct. TCB, for SAR testing of 2.4 WIFI 802.11b signal with non-100% duty cycle, the measured SAR is scaled-up by the duty cycle scaling factor which is equal to "1/(duty cycle)".

8. Measurement Variability

In accordance with published RF Exposure KDB procedure 865664 D01 SAR measurement 100 MHz to 6 GHz v01. These additional measurements are repeated after the completion of all measurements requiring the same head or body tissue-equivalent medium in a frequency band. The test device should be returned to ambient conditions (normal room temperature) with the battery fully charged before it is re-mounted on the device holder for the repeated measurement(s) to minimize any unexpected variations in the repeated results

- 1) Repeated measurement is not required when the original highest measured SAR is < 0.80 W/kg; steps 2) through 4) do not apply.
- 2) When the original highest measured SAR is ≥ 0.80 W/kg, repeat that measurement once.
- 3) Perform a second repeated measurement only if the ratio of largest to smallest SAR for the original and first repeated measurements is > 1.20 or when the original or repeated measurement is ≥ 1.45 W/kg ($\sim 10\%$ from the 1-g SAR limit).
- 4) Perform a third repeated measurement only if the original, first or second repeated measurement is ≥ 1.5 W/kg and the ratio of largest to smallest SAR for the original, first and second repeated measurements is > 1.20 .

Note: The same procedures should be adapted for measurements according to extremity and occupational exposure limits by applying a factor of 2.5 for extremity exposure and a factor of 5 for occupational exposure to the corresponding SAR thresholds.

The Highest Measured SAR Configuration in Each Frequency Band

Head

SAR probe calibration point	Frequency Band	Freq.(MHz)	EUT Position	Meas. SAR (W/kg)		Largest to Smallest SAR Ratio
				Original	Repeated	
/	/	/	/	/	/	/

Body

SAR probe calibration point	Frequency Band	Freq.(MHz)	EUT Position	Meas. SAR (W/kg)		Largest to Smallest SAR Ratio
				Original	Repeated	
/	/	/	/	/	/	/

Note:

1. Second Repeated Measurement is not required since the ratio of the largest to smallest SAR for the original and first repeated measurement is not > 1.20 .
2. The measured SAR results **do not** have to be scaled to the maximum tune-up tolerance to determine if repeated measurements are required.
3. SAR measurement variability must be assessed for each frequency band, which is determined by the **SAR probe calibration point and tissue-equivalent medium** used for the device measurements.

9. SAR Plots

Plot 1#: 2.4G WIFI Mid_Body Front

DUT: Minicam; Type: BT534349; Serial: 2L9L-1

Communication System: UID 0, 802.11 b(0); Frequency: 2437 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 2437$ MHz; $\sigma = 1.788$ S/m; $\epsilon_r = 39.581$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7329; ConvF(7.05, 7.92, 7.22) @ 2437 MHz; Calibrated: 2024/3/27
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2023/11/17
- Phantom: SAM 1; Type: QD000P40CC; Serial: TP:1412
- Measurement SW: DASY52, Version 52.10 (2); SEMCAD X Version 14.6.12 (7470)

Area Scan (6x8x1): Measurement grid: dx=12mm, dy=12mm

Maximum value of SAR (measured) = 0.0259 W/kg

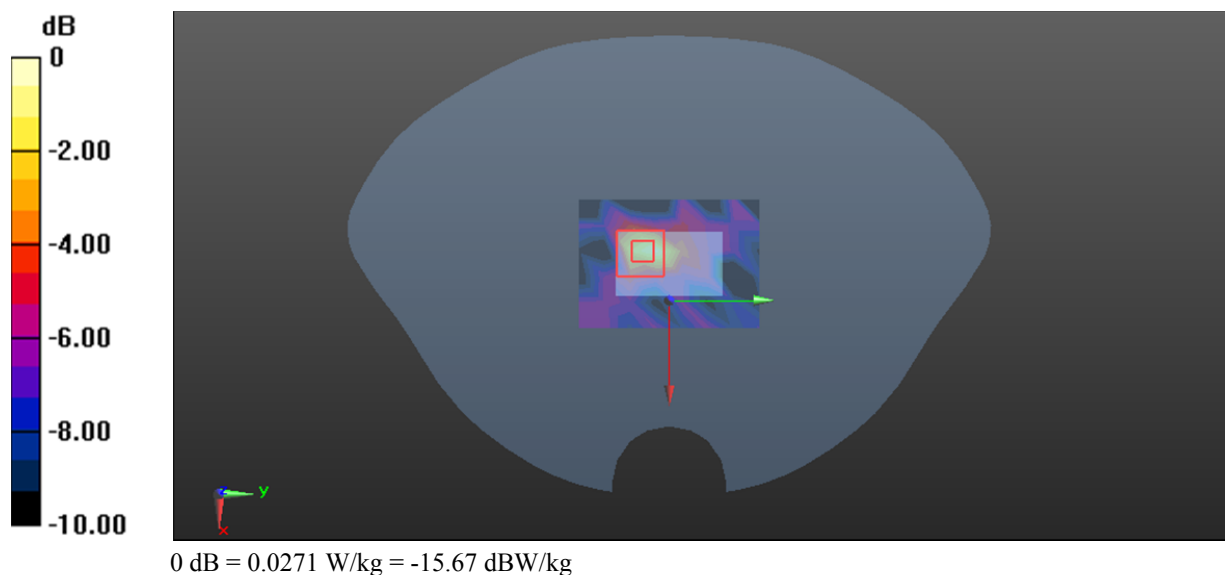
Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.935 V/m; Power Drift = -0.18 dB

Peak SAR (extrapolated) = 0.0370 W/kg

SAR(1 g) = 0.014 W/kg; SAR(10 g) = 0.00727 W/kg

Maximum value of SAR (measured) = 0.0271 W/kg



Plot 2#: 2.4G WIFI Mid_Body Back**DUT: Minicam; Type: BT534349; Serial: 2L9L-1**

Communication System: UID 0, 802.11 b(0); Frequency: 2437 MHz;Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 2437$ MHz; $\sigma = 1.788$ S/m; $\epsilon_r = 39.581$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7329; ConvF(7.05, 7.92, 7.22) @ 2437 MHz; Calibrated: 2024/3/27
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2023/11/17
- Phantom: SAM 1; Type: QD000P40CC; Serial: TP:1412
- Measurement SW: DASY52, Version 52.10 (2); SEMCAD X Version 14.6.12 (7470)

Area Scan (6x8x1): Measurement grid: dx=12mm, dy=12mm

Maximum value of SAR (measured) = 0.0272 W/kg

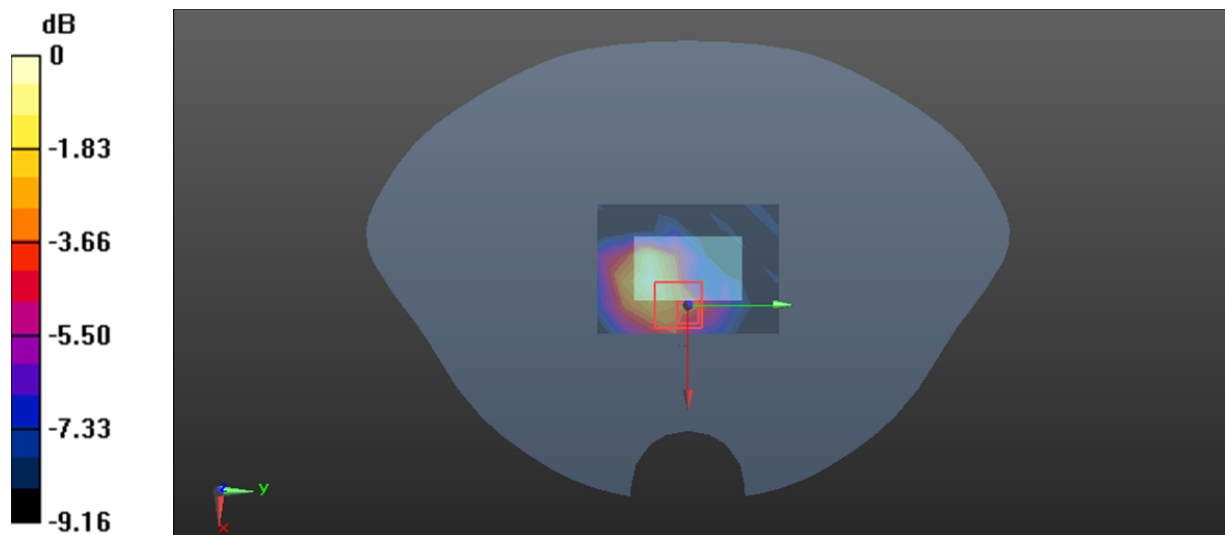
Zoom Scan (9x9x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 3.324 V/m; Power Drift = 0.19 dB

Peak SAR (extrapolated) = 0.0600 W/kg

SAR(1 g) = 0.010 W/kg; SAR(10 g) = 0.00343 W/kg

Maximum value of SAR (measured) = 0.0296 W/kg



0 dB = 0.0296 W/kg = -15.29 dBW/kg

Plot 3#: 2.4G WIFI Mid_Body Left**DUT: Minicam; Type: BT534349; Serial: 2L9L-1**

Communication System: UID 0, 802.11 b(0); Frequency: 2437 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 2437$ MHz; $\sigma = 1.788$ S/m; $\epsilon_r = 39.581$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7329; ConvF(7.05, 7.92, 7.22) @ 2437 MHz; Calibrated: 2024/3/27
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2023/11/17
- Phantom: SAM 1; Type: QD000P40CC; Serial: TP:1412
- Measurement SW: DASY52, Version 52.10 (2); SEMCAD X Version 14.6.12 (7470)

Area Scan (6x8x1): Measurement grid: dx=12mm, dy=12mm

Maximum value of SAR (measured) = 0.236 W/kg

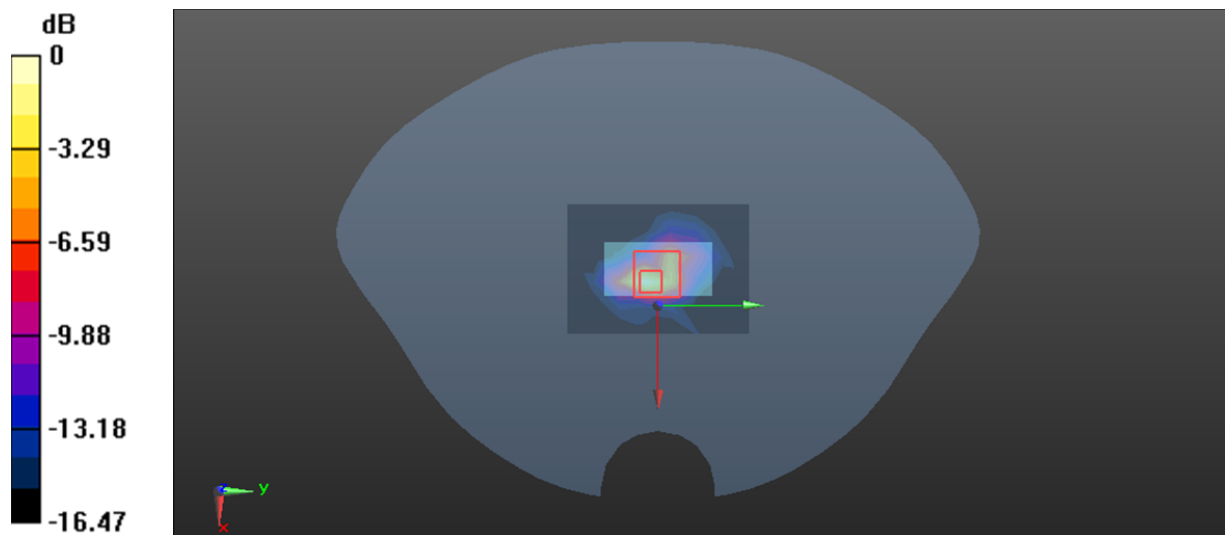
Zoom Scan (8x8x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 8.976 V/m; Power Drift = -0.17 dB

Peak SAR (extrapolated) = 0.332 W/kg

SAR(1 g) = 0.090 W/kg; SAR(10 g) = 0.031 W/kg

Maximum value of SAR (measured) = 0.228 W/kg



Plot 4#: 2.4G WIFI Mid_Body Right**DUT: Minicam; Type: BT534349; Serial: 2L9L-1**

Communication System: UID 0, 802.11 b(0); Frequency: 2437 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 2437$ MHz; $\sigma = 1.788$ S/m; $\epsilon_r = 39.581$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7329; ConvF(7.05, 7.92, 7.22) @ 2437 MHz; Calibrated: 2024/3/27
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2023/11/17
- Phantom: SAM 1; Type: QD000P40CC; Serial: TP:1412
- Measurement SW: DASY52, Version 52.10 (2); SEMCAD X Version 14.6.12 (7470)

Area Scan (6x8x1): Measurement grid: dx=12mm, dy=12mm

Maximum value of SAR (measured) = 0.0129 W/kg

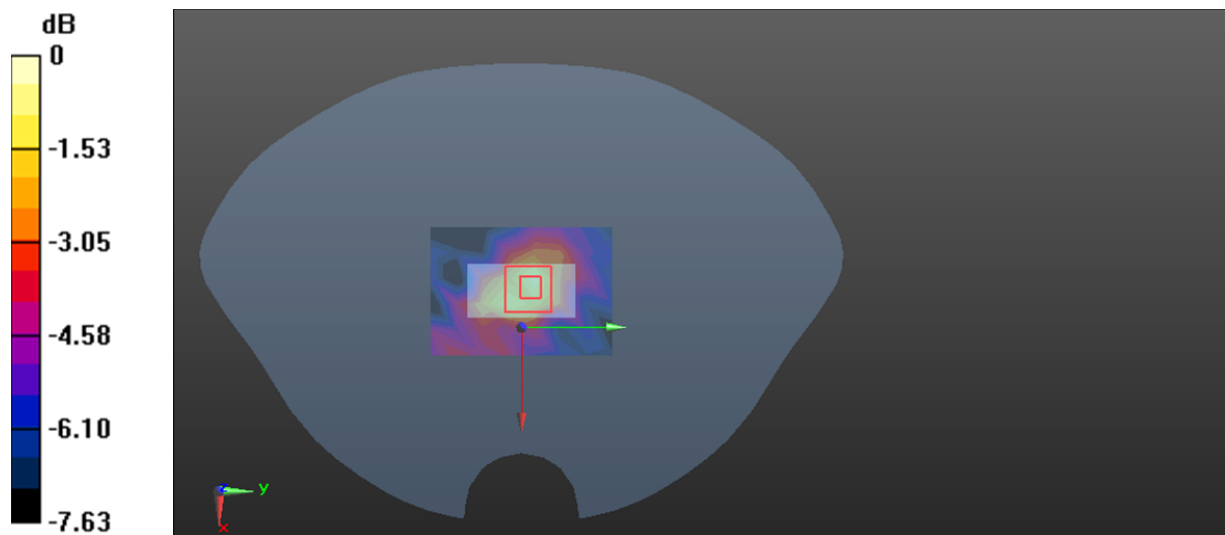
Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.877 V/m; Power Drift = -0.12 dB

Peak SAR (extrapolated) = 0.0170 W/kg

SAR(1 g) = 0.00887 W/kg; SAR(10 g) = 0.00355 W/kg

Maximum value of SAR (measured) = 0.0148 W/kg



0 dB = 0.0148 W/kg = -18.30 dBW/kg

Plot 5#: 2.4G WIFI Mid_Body Top**DUT: Minicam; Type: BT534349; Serial: 2L9L-1**

Communication System: UID 0, 802.11 b(0); Frequency: 2437 MHz; Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 2437$ MHz; $\sigma = 1.788$ S/m; $\epsilon_r = 39.581$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7329; ConvF(7.05, 7.92, 7.22) @ 2437 MHz; Calibrated: 2024/3/27
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2023/11/17
- Phantom: SAM 1; Type: QD000P40CC; Serial: TP:1412
- Measurement SW: DASY52, Version 52.10 (2); SEMCAD X Version 14.6.12 (7470)

Area Scan (6x6x1): Measurement grid: dx=12mm, dy=12mm

Maximum value of SAR (measured) = 0.00618 W/kg

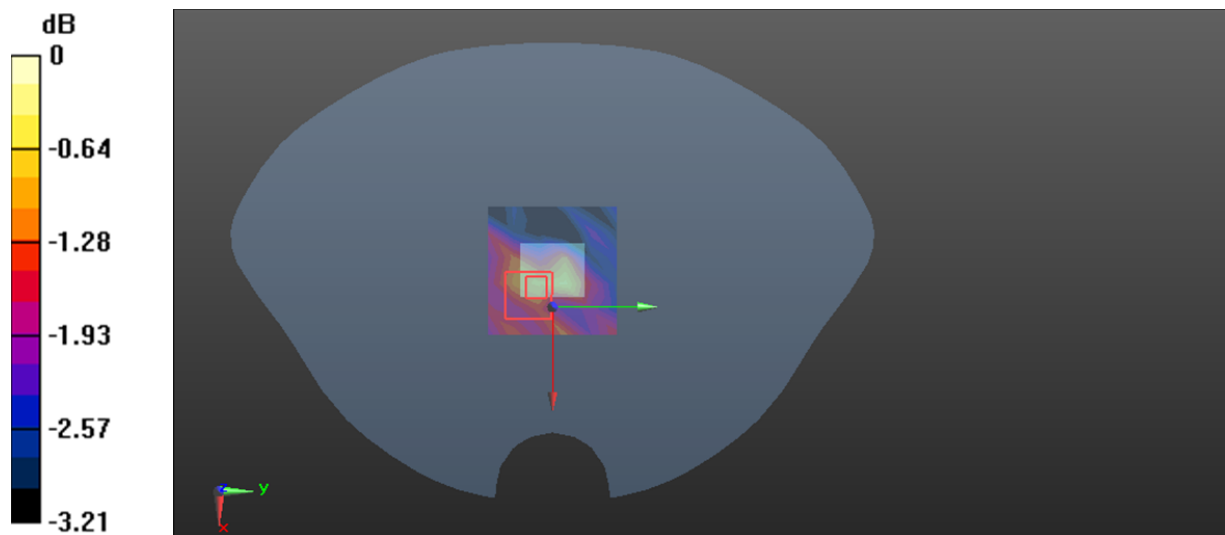
Zoom Scan (7x8x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 1.013 V/m; Power Drift = -0.17 dB

Peak SAR (extrapolated) = 0.00888 W/kg

SAR(1 g) = 0.00126 W/kg; SAR(10 g) = 0.000418 W/kg

Maximum value of SAR (measured) = 0.00487 W/kg



0 dB = 0.00487 W/kg = -23.12 dBW/kg

Plot 6#: 2.4G WIFI Mid_Body Bottom**DUT: Minicam; Type: BT534349; Serial: 2L9L-1**

Communication System: UID 0, 802.11 b(0); Frequency: 2437 MHz;Duty Cycle: 1:1

Medium parameters used (interpolated): $f = 2437$ MHz; $\sigma = 1.788$ S/m; $\epsilon_r = 39.581$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

DASY5 Configuration:

- Probe: EX3DV4 - SN7329; ConvF(7.05, 7.92, 7.22) @ 2437 MHz; Calibrated: 2024/3/27
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn1354; Calibrated: 2023/11/17
- Phantom: SAM 1; Type: QD000P40CC; Serial: TP:1412
- Measurement SW: DASY52, Version 52.10 (2); SEMCAD X Version 14.6.12 (7470)

Area Scan (6x6x1): Measurement grid: dx=12mm, dy=12mm

Maximum value of SAR (measured) = 0.00878 W/kg

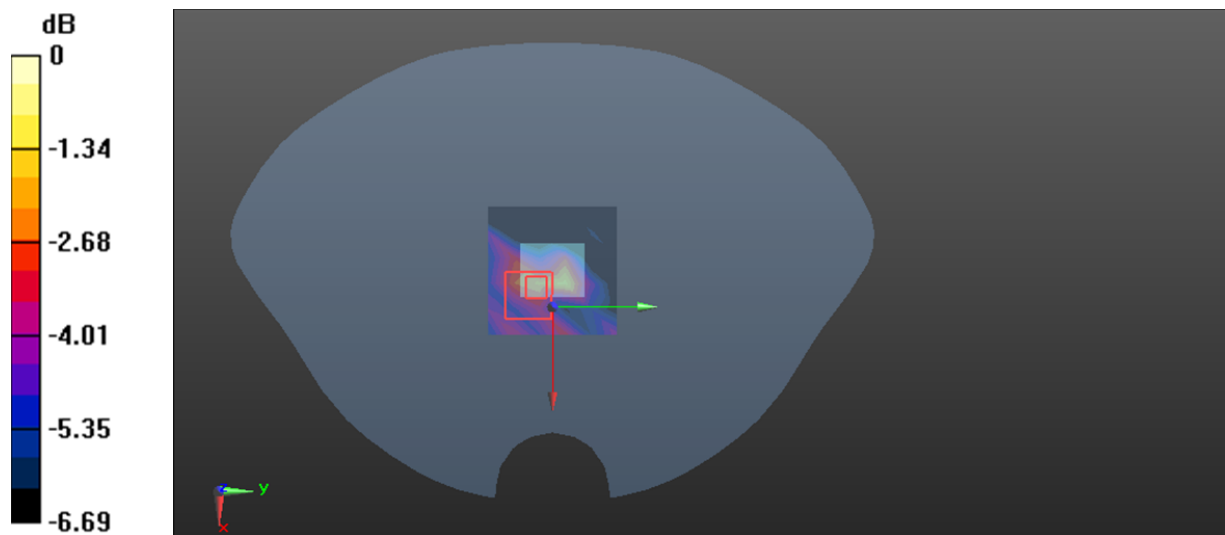
Zoom Scan (7x7x7)/Cube 0: Measurement grid: dx=5mm, dy=5mm, dz=5mm

Reference Value = 2.156 V/m; Power Drift = 0.15 dB

Peak SAR (extrapolated) = 0.0180 W/kg

SAR(1 g) = 0.00456 W/kg; SAR(10 g) = 0.00154 W/kg

Maximum value of SAR (measured) = 0.0124 W/kg



0 dB = 0.0124 W/kg = -19.07 dBW/kg

APPENDIX A MEASUREMENT UNCERTAINTY

The uncertainty budget has been determined for the measurement system and is given in the following Table.

Measurement uncertainty evaluation for IEEE1528-2013 SAR test

Source of uncertainty	Tolerance/uncertainty ± %	Probability distribution	Divisor	ci (1 g)	ci (10 g)	Standard uncertainty ± %, (1 g)	Standard uncertainty ± %, (10 g)
Measurement system							
Probe calibration	6.55	N	1	1	1	6.3	6.3
Axial Isotropy	4.7	R	$\sqrt{3}$	1	1	2.7	2.7
Hemispherical Isotropy	9.6	R	$\sqrt{3}$	0	0	0.0	0.0
Boundary effect	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Linearity	4.7	R	$\sqrt{3}$	1	1	2.7	2.7
Detection limits	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Readout electronics	0.3	N	1	1	1	0.3	0.3
Response time	0.0	R	$\sqrt{3}$	1	1	0.0	0.0
Integration time	0.0	R	$\sqrt{3}$	1	1	0.0	0.0
RF ambient conditions – noise	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
RF ambient conditions– reflections	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Probe positioner mech. Restrictions	0.8	R	$\sqrt{3}$	1	1	0.5	0.5
Probe positioning with respect to phantom shell	6.7	R	$\sqrt{3}$	1	1	3.9	3.9
Post-processing	2.0	R	$\sqrt{3}$	1	1	1.2	1.2
Test sample related							
Test sample positioning	2.8	N	1	1	1	2.8	2.8
Device holder uncertainty	6.3	N	1	1	1	6.3	6.3
Drift of output power	5.0	R	$\sqrt{3}$	1	1	2.9	2.9
Phantom and set-up							
Phantom uncertainty (shape and thickness tolerances)	4.0	R	$\sqrt{3}$	1	1	2.3	2.3
Liquid conductivity target)	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2
Liquid conductivity meas.)	2.5	N	1	0.64	0.43	1.6	1.1
Liquid permittivity target)	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4
Liquid permittivity meas.)	2.5	N	1	0.6	0.49	1.5	1.2
Combined standard uncertainty		RSS				12.2	12.0
Expanded uncertainty 95 % confidence interval)						24.1	23.7

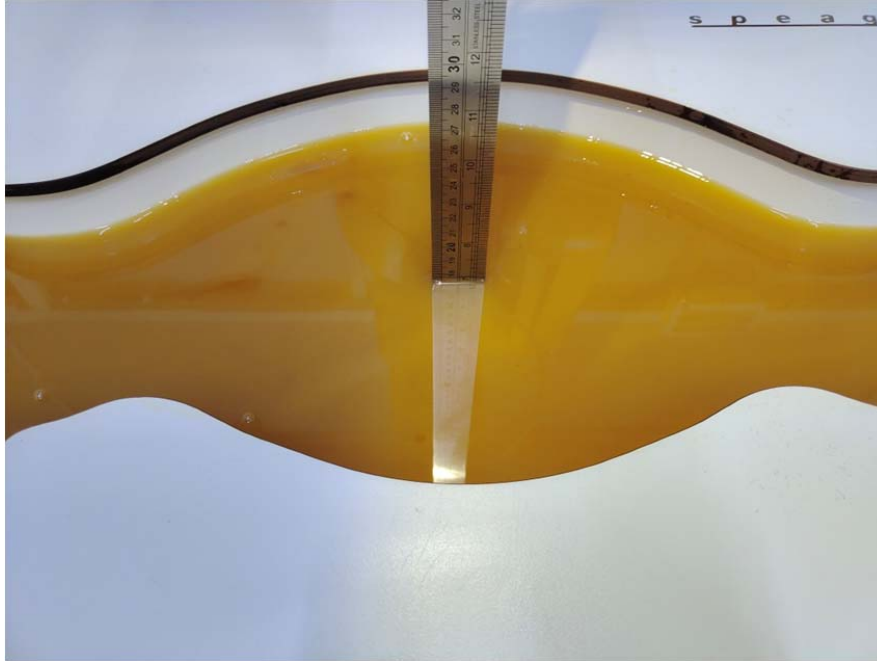
Measurement uncertainty evaluation for IEC62209-1 SAR test

Source of uncertainty	Tolerance/ uncertainty ± %	Probability distribution	Divisor	ci (1 g)	ci (10 g)	Standard uncertainty ± %, (1 g)	Standard uncertainty ± %, (10 g)
Measurement system							
Probe calibration	6.55	N	1	1	1	6.3	6.3
Axial Isotropy	4.7	R	$\sqrt{3}$	1	1	2.7	2.7
Hemispherical Isotropy	9.6	R	$\sqrt{3}$	0	0	0.0	0.0
Boundary effect	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Linearity	4.7	R	$\sqrt{3}$	1	1	2.7	2.7
Detection limits	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Readout electronics	0.3	N	1	1	1	0.3	0.3
Response time	0.0	R	$\sqrt{3}$	1	1	0.0	0.0
Integration time	0.0	R	$\sqrt{3}$	1	1	0.0	0.0
RF ambient conditions – noise	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Probe positioning with respect to phantom shell	6.7	R	$\sqrt{3}$	1	1	3.9	3.9
Probe positioner mech. Restrictions	0.8	R	$\sqrt{3}$	1	1	0.5	0.5
RF ambient conditions– reflections	1.0	R	$\sqrt{3}$	1	1	0.6	0.6
Post-processing	2.0	R	$\sqrt{3}$	1	1	1.2	1.2
Test sample related							
Test sample positioning	2.8	N	1	1	1	2.8	2.8
Device holder uncertainty	6.3	N	1	1	1	6.3	6.3
Drift of output power	5.0	R	$\sqrt{3}$	1	1	2.9	2.9
Phantom and set-up							
Phantom uncertainty (shape and thickness tolerances)	4.0	R	$\sqrt{3}$	1	1	2.3	2.3
Liquid conductivity target)	5.0	R	$\sqrt{3}$	0.64	0.43	1.8	1.2
Liquid conductivity meas.)	2.5	N	1	0.64	0.43	1.6	1.1
Liquid permittivity target)	5.0	R	$\sqrt{3}$	0.6	0.49	1.7	1.4
Liquid permittivity meas.)	2.5	N	1	0.6	0.49	1.5	1.2
Combined standard uncertainty		RSS				12.2	12.0
Expanded uncertainty 95 % confidence interval)						24.0	23.6

APPENDIX B EUT TEST POSITION PHOTOS

Liquid depth $\geq 15\text{cm}$

Phantom: Twin SAM; Type: Twin SAM V5.0; Serial: TP:1412



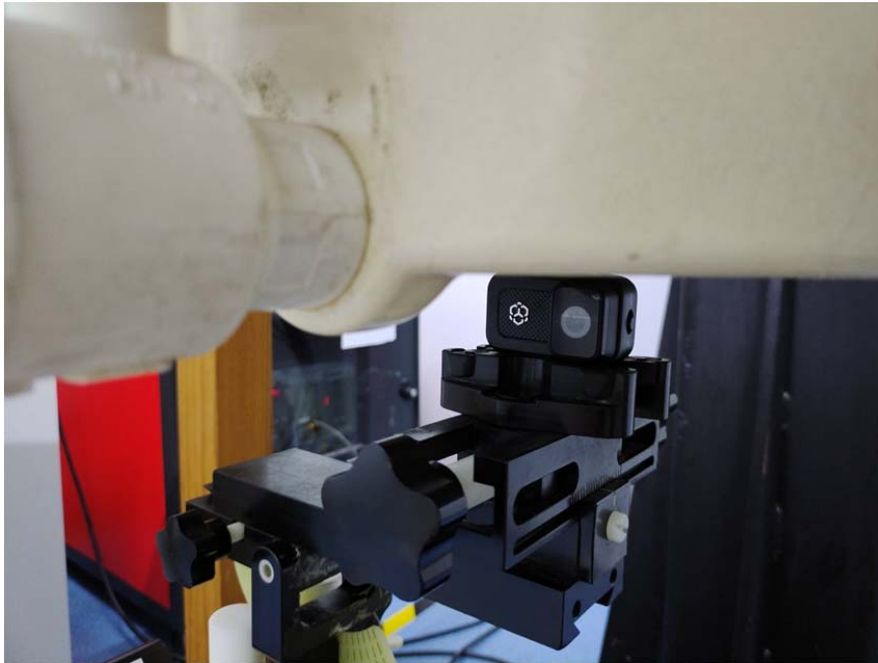
Body Front Setup Photo (0mm)



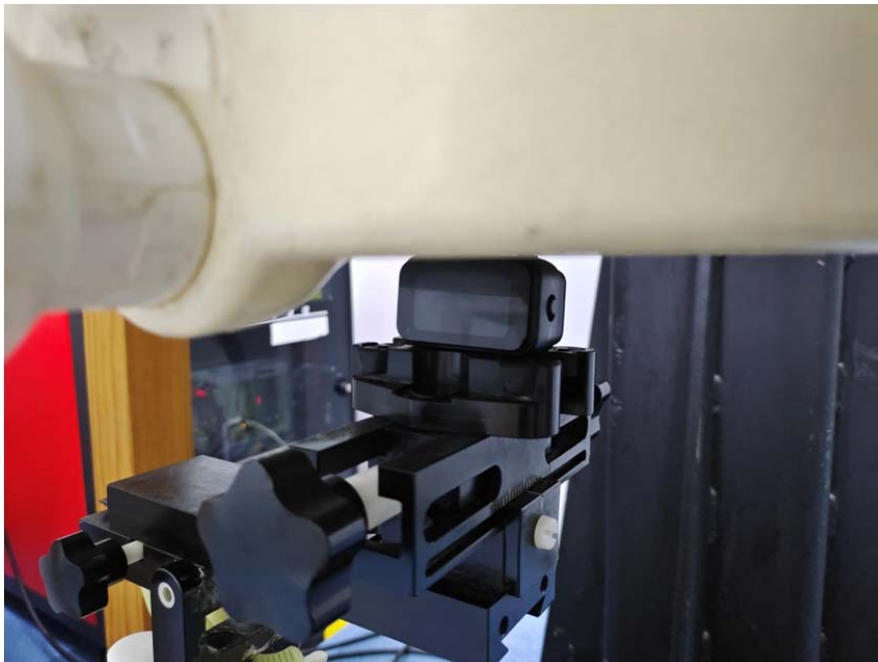
Body Back Setup Photo (0mm)



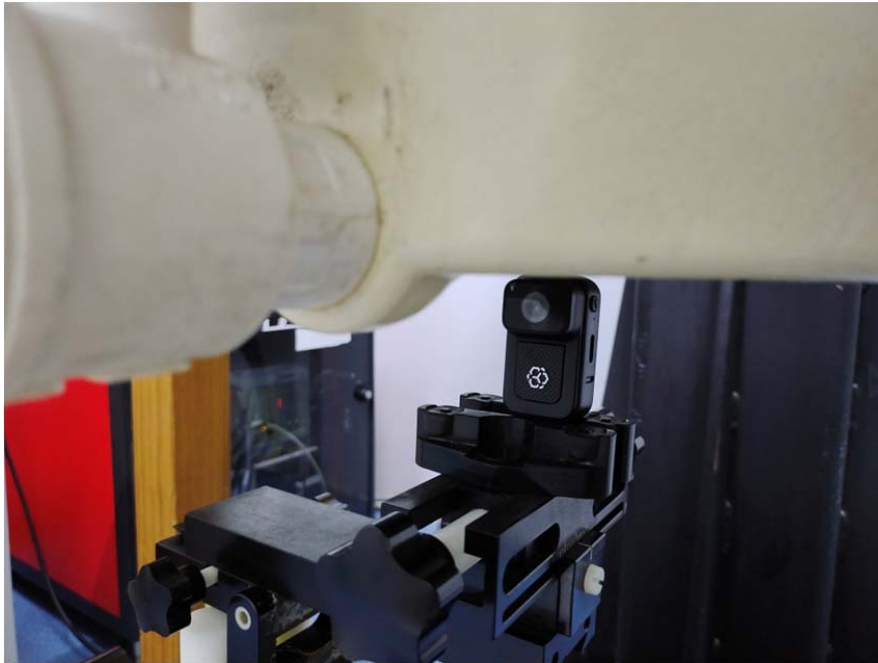
Body Left Setup Photo (0mm)



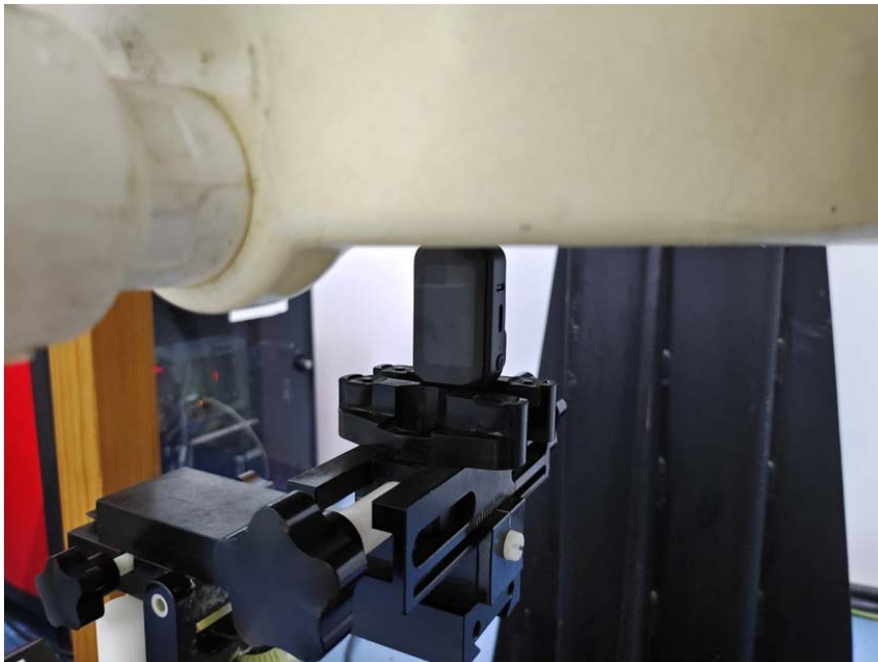
Body Right Setup Photo (0mm)



Body Top Setup Photo (0mm)



Body Bottom Setup Photo (0mm)



APPENDIX C CALIBRATION CERTIFICATES

Calibration Laboratory of
Schmid & Partner
Engineering AG
Zeughausstrasse 43, 8004 Zurich, Switzerland



S Schweizerischer Kalibrierdienst
C Service suisse d'étalonnage
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Accreditation No.: SCS 0108

Client
BACL
Shenzhen

Certificate No. **EX-7329_Mar24**

CALIBRATION CERTIFICATE

Object **EX3DV4 - SN:7329**

Calibration procedure(s) **QA CAL-01.v10, QA CAL-12.v10, QA CAL-14.v7, QA CAL-23.v6,
QA CAL-25.v8
Calibration procedure for dosimetric E-field probes**

Calibration date **March 27, 2024**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.
All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3) °C and humidity < 70%.
Calibration Equipment used (M&E critical for calibration)

Primary Standards	ID	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP2	SN: 104778	30-Mar-23 (No. 217-03804/03805)	Mar-24
Power sensor NRP-Z91	SN: 103244	30-Mar-23 (No. 217-03804)	Mar-24
OCP DAK-3.5 (weighted)	SN: 1249	05-Oct-23 (OCP-DAK3.5-1249_Oct23)	Oct-24
OCP DAK-12	SN: 1016	05-Oct-23 (OCP-DAK12-1016_Oct23)	Oct-24
Reference 20 dB Attenuator	SN: CC2552 (20x)	30-Mar-23 (No. 217-03809)	Mar-24
DAE4	SN: 660	23-Feb-24 (No. DAE4-660_Feb24)	Feb-25
Reference Probe EX3DV4	SN: 7349	03-Nov-23 (No. EX3-7349_Nov23)	Nov-24

Secondary Standards	ID	Check Date (in house)	Scheduled Check
Power meter E4419B	SN: GB41293874	06-Apr-16 (in house check Jun-22)	In house check: Jun-24
Power sensor E4412A	SN: MY41498087	06-Apr-16 (in house check Jun-22)	In house check: Jun-24
Power sensor E4412A	SN: 000110210	06-Apr-16 (in house check Jun-22)	In house check: Jun-24
RF generator HP 8648C	SN: US3642U01700	04-Aug-99 (in house check Jun-22)	In house check: Jun-24
Network Analyzer E8358A	SN: US41080477	31-Mar-14 (in house check Oct-22)	In house check: Oct-24

	Name	Function	Signature
Calibrated by	Joanna Uleshaj	Laboratory Technician	
Approved by	Sven Kühn	Technical Manager	

Issued: March 27, 2024

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Glossary

TSL	tissue simulating liquid
NORM _{x,y,z}	sensitivity in free space
ConvF	sensitivity in TSL / NORM _{x,y,z}
DCP	diode compression point
CF	crest factor (1/duty_cycle) of the RF signal
A, B, C, D	modulation dependent linearization parameters
Polarization φ	φ rotation around probe axis
Polarization θ	θ rotation around an axis that is in the plane normal to probe axis (at measurement center), i.e., $\theta = 0$ is normal to probe axis
Connector Angle	information used in DASY system to align probe sensor X to the robot coordinate system

Calibration is Performed According to the Following Standards:

- IEC/IEEE 62209-1528, "Measurement Procedure For The Assessment Of Specific Absorption Rate Of Human Exposure To Radio Frequency Fields From Hand-Held And Body-Worn Wireless Communication Devices – Part 1528: Human Models, Instrumentation And Procedures (Frequency Range of 4 MHz to 10 GHz)", October 2020.
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Methods Applied and Interpretation of Parameters:

- NORM_{x,y,z}**: Assessed for E-field polarization $\theta = 0$ ($f \leq 900$ MHz in TEM-cell; $f > 1800$ MHz: R22 waveguide). NORM_{x,y,z} are only intermediate values, i.e., the uncertainties of NORM_{x,y,z} does not affect the E²-field uncertainty inside TSL (see below ConvF).
- NORM(f)_{x,y,z} = NORM_{x,y,z} * frequency_response** (see Frequency Response Chart). This linearization is implemented in DASY4 software versions later than 4.2. The uncertainty of the frequency response is included in the stated uncertainty of ConvF.
- DCP_{x,y,z}**: DCP are numerical linearization parameters assessed based on the data of power sweep with CW signal. DCP does not depend on frequency nor media.
- PAR**: PAR is the Peak to Average Ratio that is not calibrated but determined based on the signal characteristics
- A_{x,y,z}; B_{x,y,z}; C_{x,y,z}; D_{x,y,z}; VR_{x,y,z}**: A, B, C, D are numerical linearization parameters assessed based on the data of power sweep for specific modulation signal. The parameters do not depend on frequency nor media. VR is the maximum calibration range expressed in RMS voltage across the diode.
- ConvF and Boundary Effect Parameters**: Assessed in flat phantom using E-field (or Temperature Transfer Standard for $f \leq 800$ MHz) and inside waveguide using analytical field distributions based on power measurements for $f > 800$ MHz. The same setups are used for assessment of the parameters applied for boundary compensation (alpha, depth) of which typical uncertainty values are given. These parameters are used in DASY4 software to improve probe accuracy close to the boundary. The sensitivity in TSL corresponds to NORM_{x,y,z} * ConvF whereby the uncertainty corresponds to that given for ConvF. A frequency dependent ConvF is used in DASY version 4.4 and higher which allows extending the validity from ± 50 MHz to ± 100 MHz.
- Spherical isotropy (3D deviation from isotropy)**: in a field of low gradients realized using a flat phantom exposed by a patch antenna.
- Sensor Offset**: The sensor offset corresponds to the offset of virtual measurement center from the probe tip (on probe axis). No tolerance required.
- Connector Angle**: The angle is assessed using the information gained by determining the NORM_x (no uncertainty required).

EX3DV4 - SN:7329

March 27, 2024

Parameters of Probe: EX3DV4 - SN:7329

Basic Calibration Parameters

	Sensor X	Sensor Y	Sensor Z	Unc (k = 2)
Norm ($\mu\text{V}/(\text{V}/\text{m})^2$) ^A	0.51	0.41	0.62	±10.1%
DCP (mV) ^B	99.8	102.9	106.5	±4.7%

Calibration Results for Modulation Response

UID	Communication System Name		A dB	B dB $\sqrt{\mu\text{V}}$	C	D dB	VR mV	Max dev.	Max Unc ^E k = 2
0	CW	X	0.00	0.00	1.00	0.00	141.4	±1.4%	±4.7%
		Y	0.00	0.00	1.00		139.4		
		Z	0.00	0.00	1.00		136.0		

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor k=2, which for a normal distribution corresponds to a coverage probability of approximately 95%.

^A The uncertainties of Norm X,Y,Z do not affect the E²-field uncertainty inside TSL (see Page 5).
^B Linearization parameter uncertainty for maximum specified field strength.
^E Uncertainty is determined using the max. deviation from linear response applying rectangular distribution and is expressed for the square of the field value.

EX3DV4 - SN:7329

March 27, 2024

Parameters of Probe: EX3DV4 - SN:7329

Other Probe Parameters

Sensor Arrangement	Triangular
Connector Angle	-29.0°
Mechanical Surface Detection Mode	enabled
Optical Surface Detection Mode	disabled
Probe Overall Length	337 mm
Probe Body Diameter	10 mm
Tip Length	9 mm
Tip Diameter	2.5 mm
Probe Tip to Sensor X Calibration Point	1 mm
Probe Tip to Sensor Y Calibration Point	1 mm
Probe Tip to Sensor Z Calibration Point	1 mm
Recommended Measurement Distance from Surface	1.4 mm

Note: Measurement distance from surface can be increased to 3–4 mm for an Area Scan job.

EX3DV4 - SN:7329

March 27, 2024

Parameters of Probe: EX3DV4 - SN:7329**Calibration Parameter Determined in Head Tissue Simulating Media**

f (MHz) ^C	Relative Permittivity ^F	Conductivity ^F (S/m)	ConvF X	ConvF Y	ConvF Z	Alpha ^G	Depth ^G (mm)	Unc (k = 2)
750	41.9	0.89	8.79	10.07	9.05	0.38	1.27	±11.0%
900	41.5	0.97	8.42	9.50	8.93	0.37	1.27	±11.0%
1750	40.1	1.37	7.56	8.56	7.71	0.27	1.27	±11.0%
1900	40.0	1.40	7.37	8.32	7.54	0.29	1.27	±11.0%
2300	39.5	1.67	7.21	8.13	7.41	0.30	1.27	±11.0%
2450	39.2	1.80	7.05	7.92	7.22	0.29	1.27	±11.0%
2600	39.0	1.96	6.91	7.77	7.08	0.29	1.27	±11.0%
5250	35.9	4.71	4.96	5.61	5.16	0.38	1.53	±13.1%
5600	35.5	5.07	4.38	4.98	4.56	0.35	1.74	±13.1%
5750	35.4	5.22	4.54	5.16	4.70	0.35	1.83	±13.1%

^C Frequency validity above 300 MHz of ±100 MHz only applies for DASY v4.4 and higher (see Page 2), else it is restricted to ±50 MHz. The uncertainty is the RSS of the ConvF uncertainty at calibration frequency and the uncertainty for the indicated frequency band. Frequency validity below 300 MHz is ±10, 25, 40, 50 and 70 MHz for ConvF assessments at 30, 64, 128, 150 and 220 MHz respectively. Validity of ConvF assessed at 6 MHz is 4–9 MHz, and ConvF assessed at 13 MHz is 9–19 MHz. Above 5 GHz frequency validity can be extended to ±110 MHz.

^F The probes are calibrated using tissue simulating liquids (TSL) that deviate for ϵ and σ by less than ±5% from the target values (typically better than ±3%) and are valid for TSL with deviations of up to ±10% if SAR correction is applied.

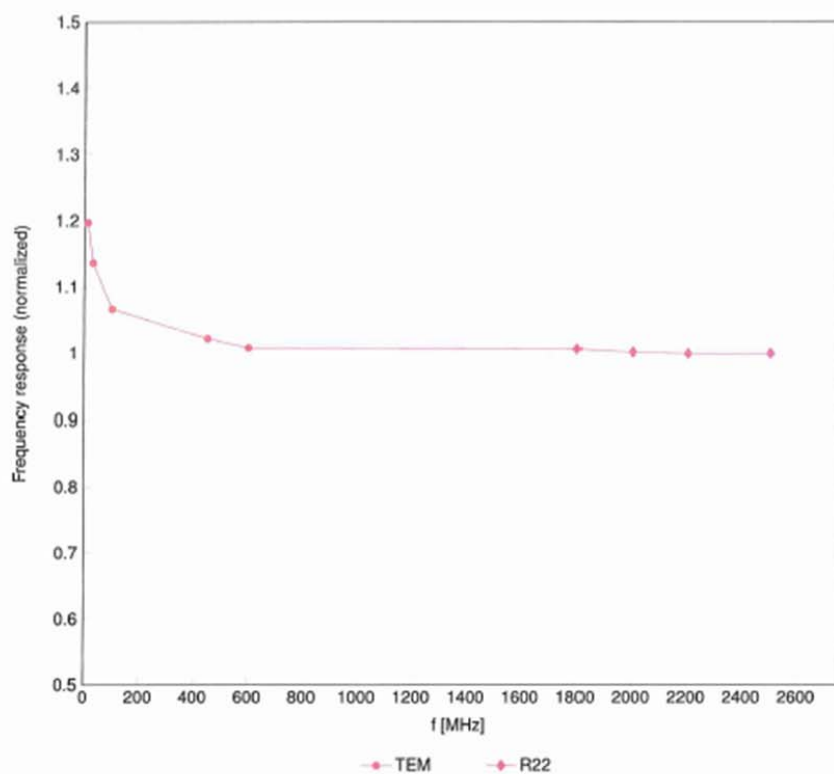
^G Alpha/Depth are determined during calibration. SPEAG warrants that the remaining deviation due to the boundary effect after compensation is always less than ±1% for frequencies below 3 GHz and below ±2% for frequencies between 3–6 GHz at any distance larger than half the probe tip diameter from the boundary.

EX3DV4 - SN:7329

March 27, 2024

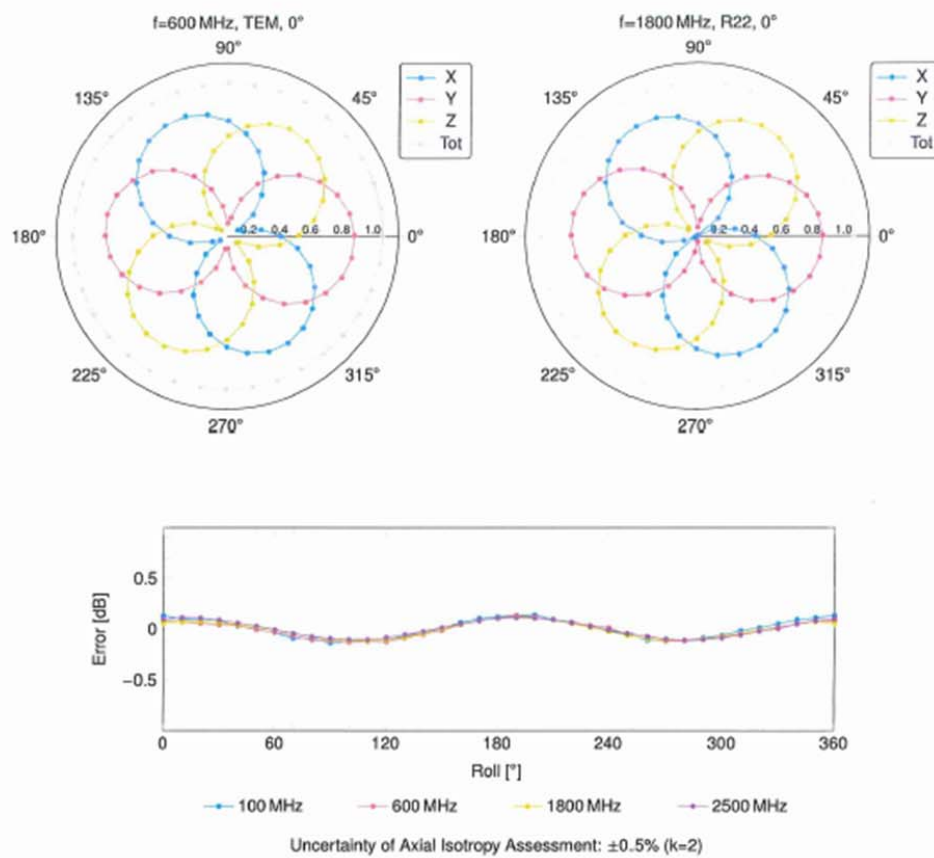
Frequency Response of E-Field

(TEM-Cell:ifi110 EXX, Waveguide:R22)

Uncertainty of Frequency Response of E-field: $\pm 6.3\%$ ($k=2$)

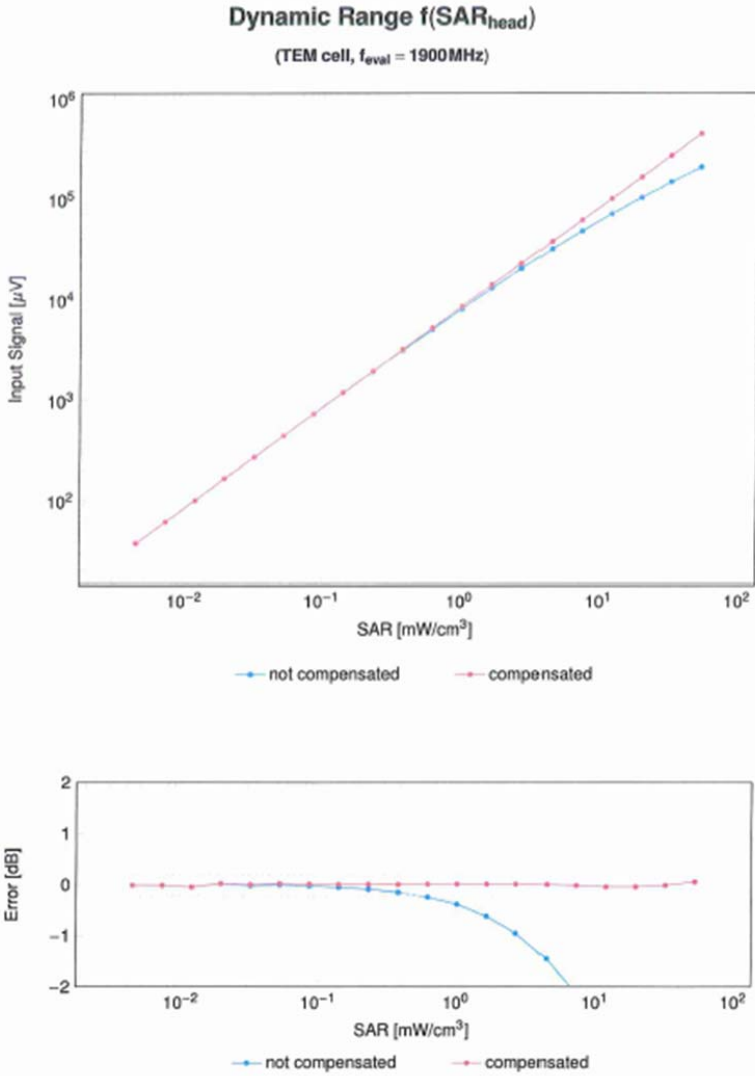
EX3DV4 - SN:7329

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Receiving Pattern (ϕ), $\theta = 0^\circ$ 

EX3DV4 - SN:7329

March 27, 2024

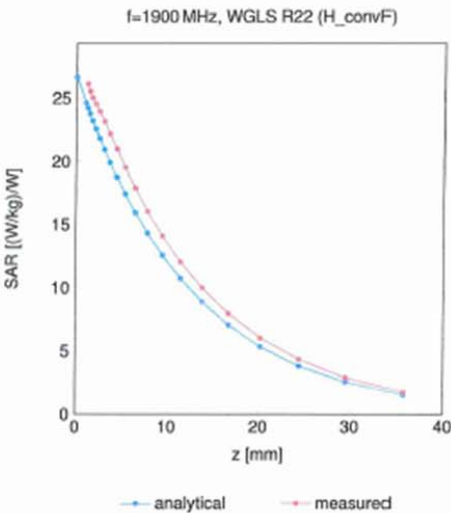


Uncertainty of Linearity Assessment: ±0.6% (k=2)

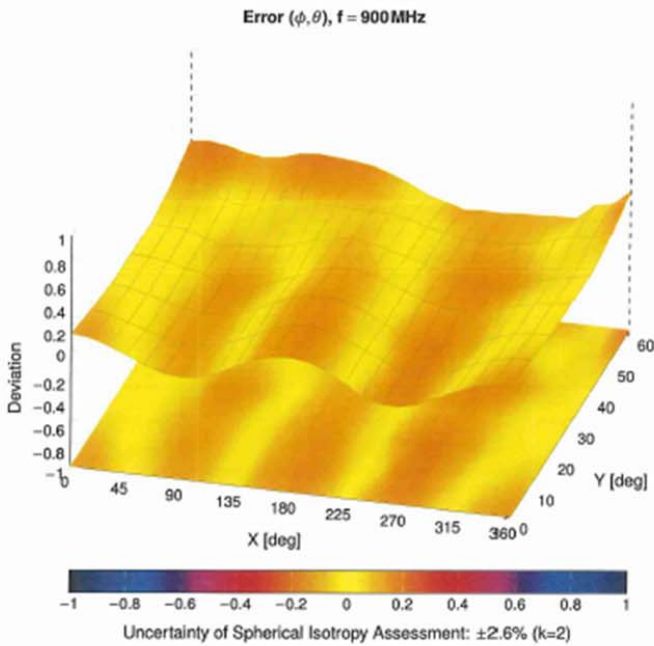
EX3DV4 - SN:7329

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Conversion Factor Assessment



Deviation from Isotropy in Liquid



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Client **BACL**
Sunnyvale, USA

Certificate No. **D2450V2-1102_Mar23**

CALIBRATION CERTIFICATE

Object **D2450V2 - SN:1102**

Calibration procedure(s) **QA CAL-05.v12**
Calibration Procedure for SAR Validation Sources between 0.7-3 GHz

Calibration date: **March 27, 2023**

This calibration certificate documents the traceability to national standards, which realize the physical units of measurements (SI).
The measurements and the uncertainties with confidence probability are given on the following pages and are part of the certificate.

All calibrations have been conducted in the closed laboratory facility: environment temperature (22 ± 3)°C and humidity < 70%.

Calibration Equipment used (M&TE critical for calibration)

Primary Standards	ID #	Cal Date (Certificate No.)	Scheduled Calibration
Power meter NRP	SN: 104778	04-Apr-22 (No. 217-03525/03524)	Apr-23
Power sensor NRP-Z91	SN: 103244	04-Apr-22 (No. 217-03524)	Apr-23
Power sensor NRP-Z91	SN: 103245	04-Apr-22 (No. 217-03525)	Apr-23
Reference 20 dB Attenuator	SN: BH9394 (20k)	04-Apr-22 (No. 217-03527)	Apr-23
Type-N mismatch combination	SN: 310982 / 06327	04-Apr-22 (No. 217-03528)	Apr-23
Reference Probe EX3DV4	SN: 7349	10-Jan-23 (No. EX3-7349_Jan23)	Jan-24
DAE4	SN: 601	19-Dec-22 (No. DAE4-601_Dec22)	Dec-23
Secondary Standards	ID #	Check Date (in house)	Scheduled Check
Power meter E4419B	SN: GB39512475	30-Oct-14 (in house check Oct-22)	In house check: Oct-24
Power sensor HP 8481A	SN: US37292783	07-Oct-15 (in house check Oct-22)	In house check: Oct-24
Power sensor HP 8481A	SN: MY41093315	07-Oct-15 (in house check Oct-22)	In house check: Oct-24
RF generator R&S SMT-06	SN: 100972	15-Jun-15 (in house check Oct-22)	In house check: Oct-24
Network Analyzer Agilent E8358A	SN: US41080477	31-Mar-14 (in house check Oct-22)	In house check: Oct-24

	Name	Function	Signature
Calibrated by:	Jeton Kastrati	Laboratory Technician	
Approved by:	Sven Kühn	Technical Manager	

Issued: March 27, 2023

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Certificate No: D2450V2-1102_Mar23

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Accreditation No.: **SCS 0108**

Glossary:

TSL	tissue simulating liquid
ConvF	sensitivity in TSL / NORM x,y,z
N/A	not applicable or not measured

Calibration is Performed According to the Following Standards:

- IEC/IEEE 62209-1528, "Measurement Procedure For The Assessment Of Specific Absorption Rate Of Human Exposure To Radio Frequency Fields From Hand-Held And Body-Worn Wireless Communication Devices - Part 1528: Human Models, Instrumentation And Procedures (Frequency Range of 4 MHz to 10 GHz)", October 2020.
- KDB 865664, "SAR Measurement Requirements for 100 MHz to 6 GHz"

Additional Documentation:

- DASY System Handbook

Methods Applied and Interpretation of Parameters:

- Measurement Conditions:** Further details are available from the Validation Report at the end of the certificate. All figures stated in the certificate are valid at the frequency indicated.
- Antenna Parameters with TSL:** The source is mounted in a touch configuration below the center marking of the flat phantom.
- Return Loss:** This parameter is measured with the source positioned under the liquid filled phantom (as described in the measurement condition clause). The Return Loss ensures low reflected power. No uncertainty required.
- SAR measured:** SAR measured at the stated antenna input power.
- SAR normalized:** SAR as measured, normalized to an input power of 1 W at the antenna connector.
- SAR for nominal TSL parameters:** The measured TSL parameters are used to calculate the nominal SAR result.

The reported uncertainty of measurement is stated as the standard uncertainty of measurement multiplied by the coverage factor $k=2$, which for a normal distribution corresponds to a coverage probability of approximately 95%.

Measurement Conditions

DASY system configuration, as far as not given on page 1.

DASY Version	DASY52	V52.10.4
Extrapolation	Advanced Extrapolation	
Phantom	Modular Flat Phantom	
Distance Dipole Center - TSL	10 mm	with Spacer
Zoom Scan Resolution	dx, dy, dz = 5 mm	
Frequency	2450 MHz $\pm$ 1 MHz	

Head TSL parameters

The following parameters and calculations were applied.

	Temperature	Permittivity	Conductivity
Nominal Head TSL parameters	22.0 °C	39.2	1.80 mho/m
Measured Head TSL parameters	(22.0 $\pm$ 0.2) °C	38.0 $\pm$ 6 %	1.81 mho/m $\pm$ 6 %
Head TSL temperature change during test	< 0.5 °C	----	----

SAR result with Head TSL

SAR averaged over 1 cm ³ (1 g) of Head TSL	Condition	
SAR measured	250 mW input power	12.9 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	50.9 W/kg $\pm$ 17.0 % (k=2)

SAR averaged over 10 cm ³ (10 g) of Head TSL	condition	
SAR measured	250 mW input power	6.07 W/kg
SAR for nominal Head TSL parameters	normalized to 1W	24.1 W/kg $\pm$ 16.5 % (k=2)

Appendix (Additional assessments outside the scope of SCS 0108)**Antenna Parameters with Head TSL**

Impedance, transformed to feed point	53.9 Ω + 4.8 j Ω
Return Loss	- 24.6 dB

General Antenna Parameters and Design

Electrical Delay (one direction)	1.155 ns
----------------------------------	----------

After long term use with 100W radiated power, only a slight warming of the dipole near the feedpoint can be measured.

The dipole is made of standard semirigid coaxial cable. The center conductor of the feeding line is directly connected to the second arm of the dipole. The antenna is therefore short-circuited for DC-signals. On some of the dipoles, small end caps are added to the dipole arms in order to improve matching when loaded according to the position as explained in the "Measurement Conditions" paragraph. The SAR data are not affected by this change. The overall dipole length is still according to the Standard.

No excessive force must be applied to the dipole arms, because they might bend or the soldered connections near the feedpoint may be damaged.

Additional EUT Data

Manufactured by	SPEAG
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DASY5 Validation Report for Head TSL

Date: 27.03.2023

Test Laboratory: SPEAG, Zurich, Switzerland

DUT: Dipole 2450 MHz; Type: D2450V2; Serial: D2450V2 - SN:1102

Communication System: UID 0 - CW; Frequency: 2450 MHz

Medium parameters used: $f = 2450$ MHz; $\sigma = 1.81$ S/m; $\epsilon_r = 38$; $\rho = 1000$ kg/m³

Phantom section: Flat Section

Measurement Standard: DASY5 (IEEE/IEC/ANSI C63.19-2011)

DASY52 Configuration:

- Probe: EX3DV4 - SN7349; ConvF(7.88, 7.88, 7.88) @ 2450 MHz; Calibrated: 10.01.2023
- Sensor-Surface: 1.4mm (Mechanical Surface Detection)
- Electronics: DAE4 Sn601; Calibrated: 19.12.2022
- Phantom: Flat Phantom 5.0 (front); Type: QD 000 P50 AA; Serial: 1001
- DASY52 52.10.4(1535); SEMCAD X 14.6.14(7501)

Dipole Calibration for Head Tissue/ $P_{in}=250$ mW, $d=10$ mm/Zoom Scan (7x7x7)/Cube 0:Measurement grid: $dx=5$ mm, $dy=5$ mm, $dz=5$ mm

Reference Value = 115.0 V/m; Power Drift = -0.01 dB

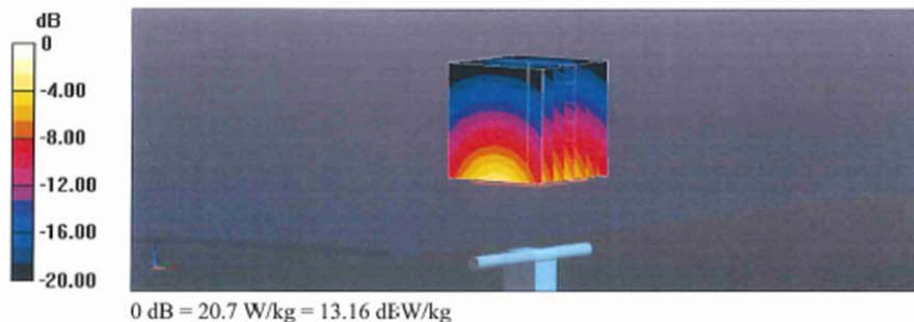
Peak SAR (extrapolated) = 24.7 W/kg

SAR(1 g) = 12.9 W/kg; SAR(10 g) = 6.07 W/kg

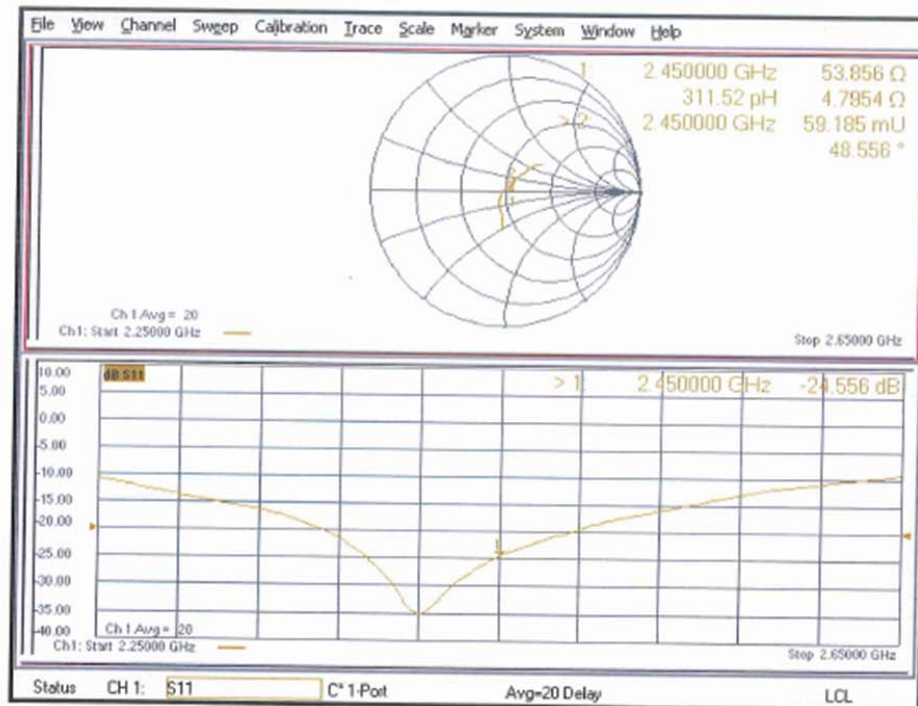
Smallest distance from peaks to all points 3 dB below = 9 mm

Ratio of SAR at M2 to SAR at M1 = 51.9%

Maximum value of SAR (measured) = 20.7 W/kg



Impedance Measurement Plot for Head TSL



***** END OF REPORT *****