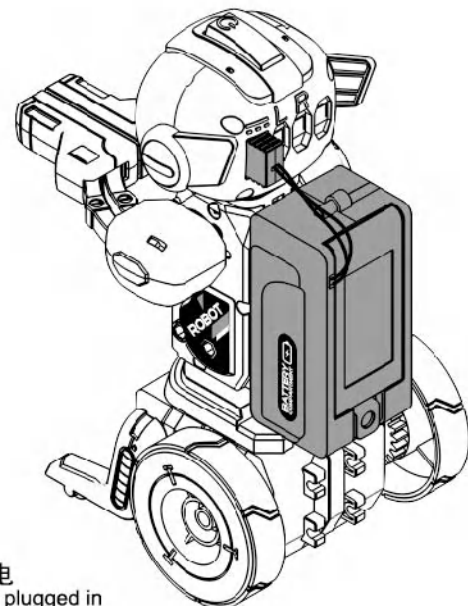
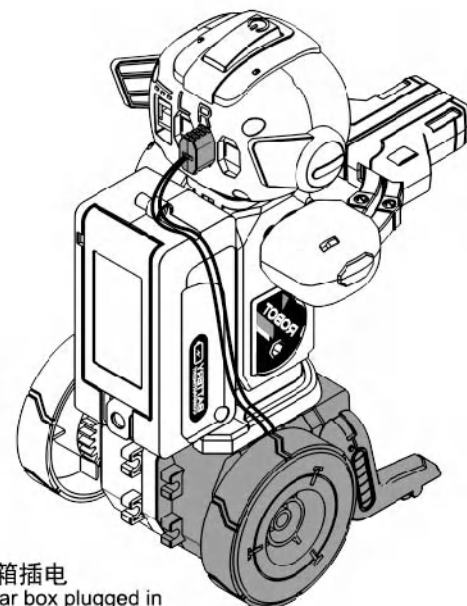
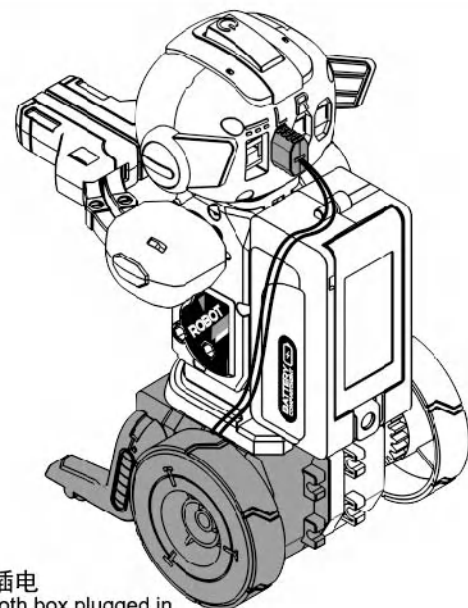




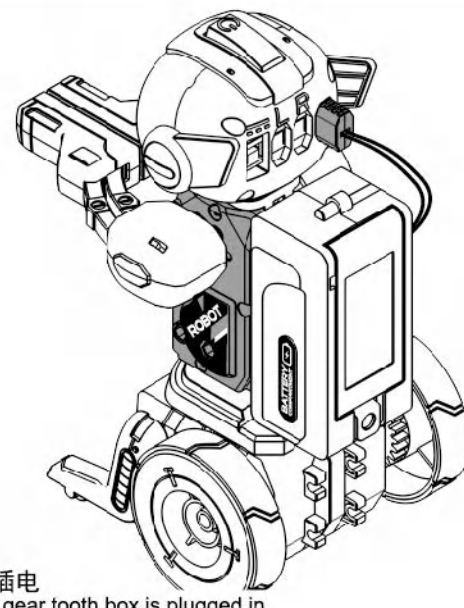
电池盒插电
Battery box plugged in



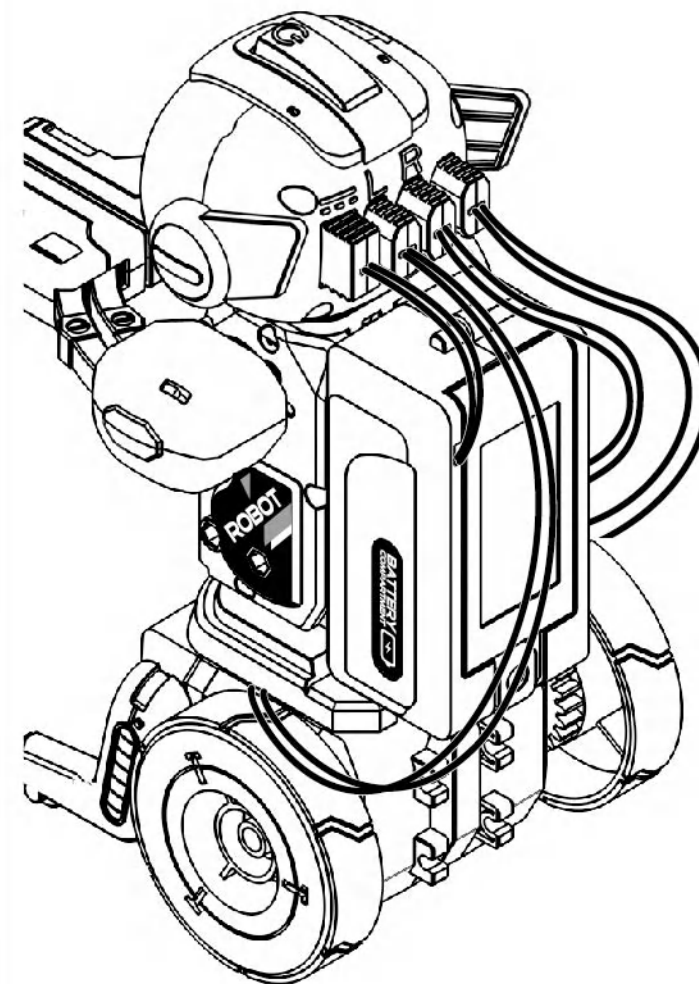
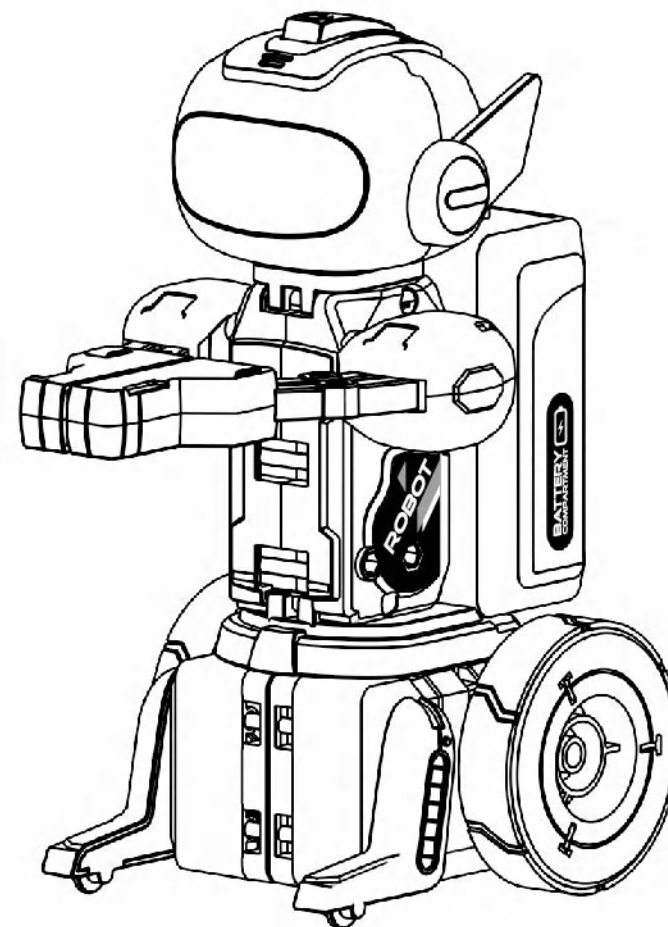
右齿轮箱插电
Right gear box plugged in



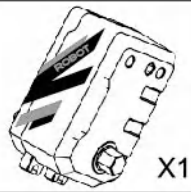
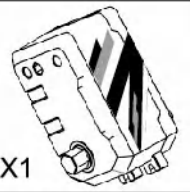
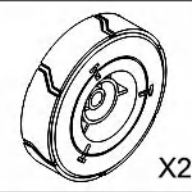
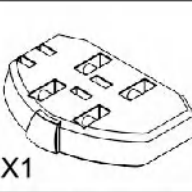
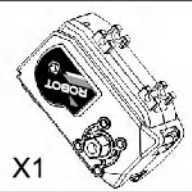
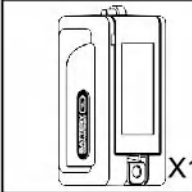
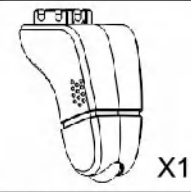
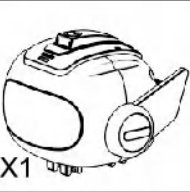
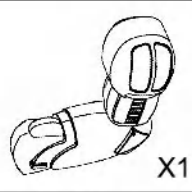
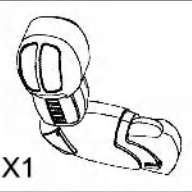
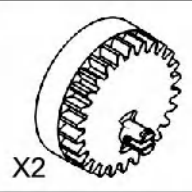
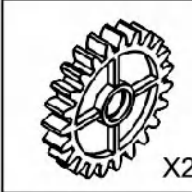
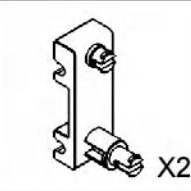
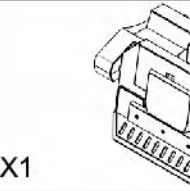
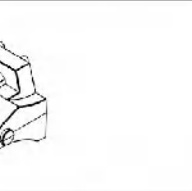
左齿轮箱插电
Left gear tooth box plugged in



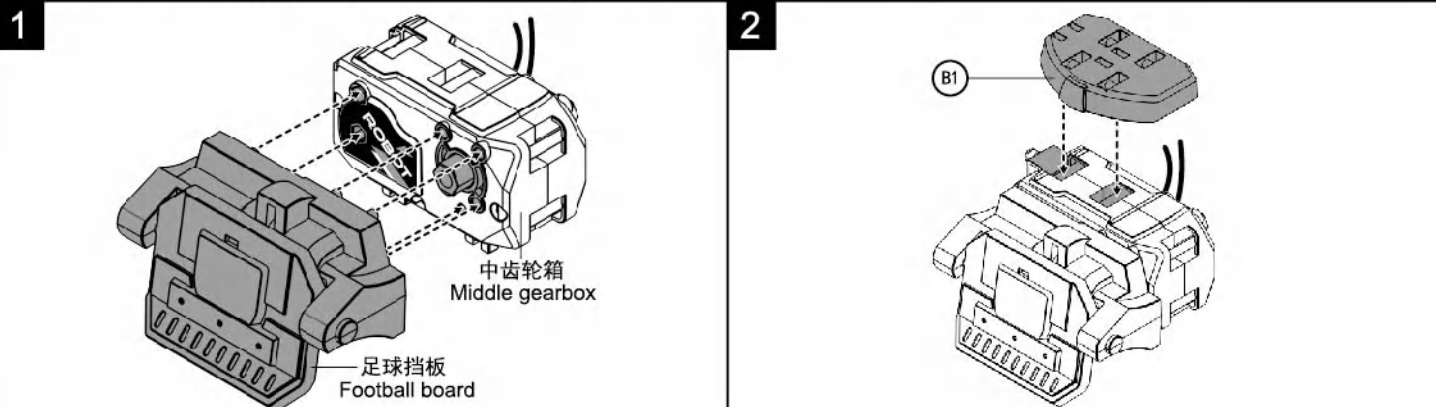
中齿轮箱插电
The middle gear tooth box is plugged in.



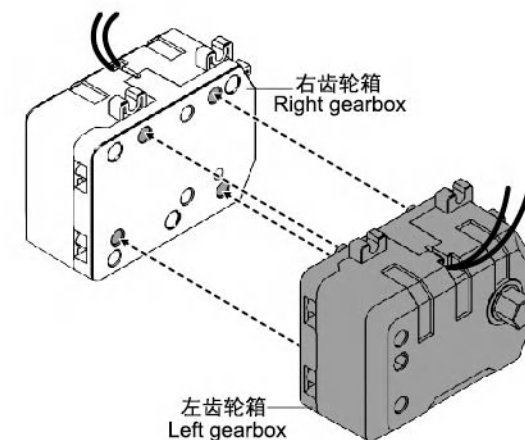
足球小健将清单 List of young football players

 X1 左齿轮箱 Left gearbox	 X1 右齿轮箱 Right gearbox	 X2 轮胎 Tire	 X1 B1配件 B1 Accessories	 X1 中齿轮箱 Middle gearbox	 X1 电池盒 Battery box
 X1 钢珠轮 Steel ball wheel	 X1 头部 Head	 X1 左手臂 Left arm	 X1 右手臂 Right arm	 X2 F10配件 F10 Accessories	 X2 F11配件 F11 Accessories
 X2 A12配件 A12 Accessories	 X1 足球挡板 Football gearboard	 X2 F3配件 F3 Accessories			

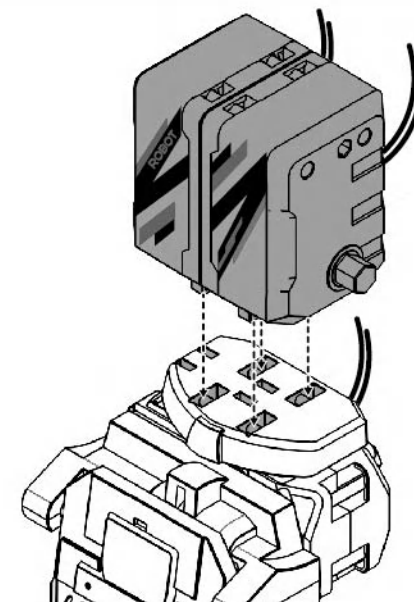
足球小健将合成组装 Football player synthetic assembly



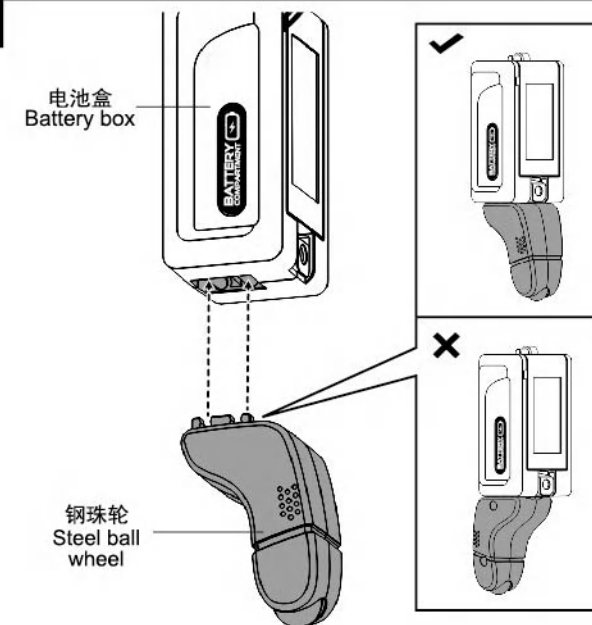
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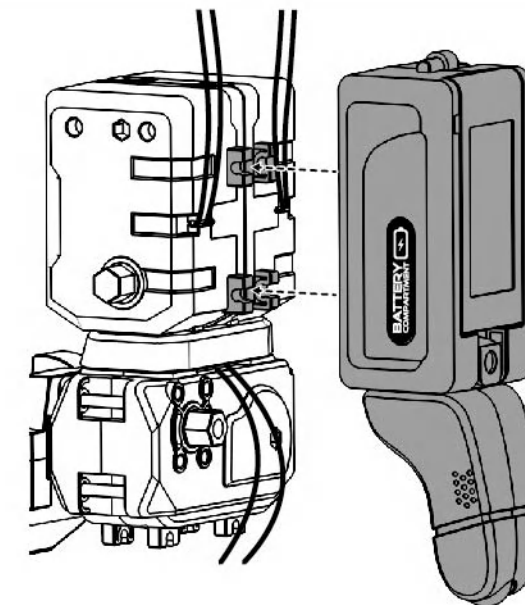
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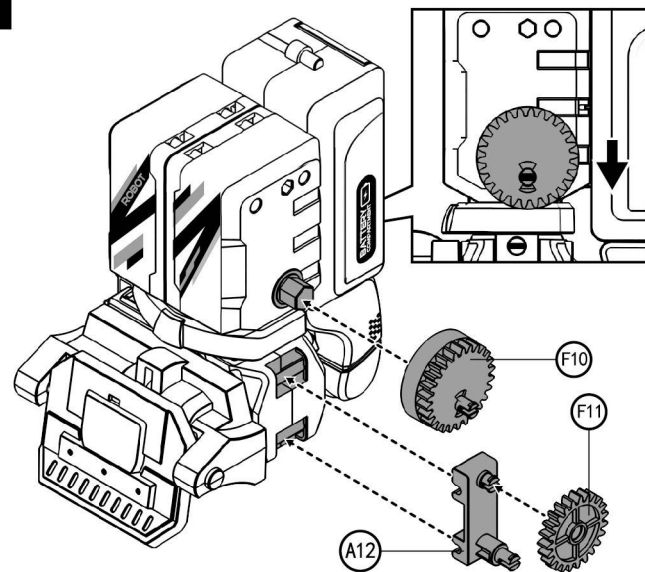
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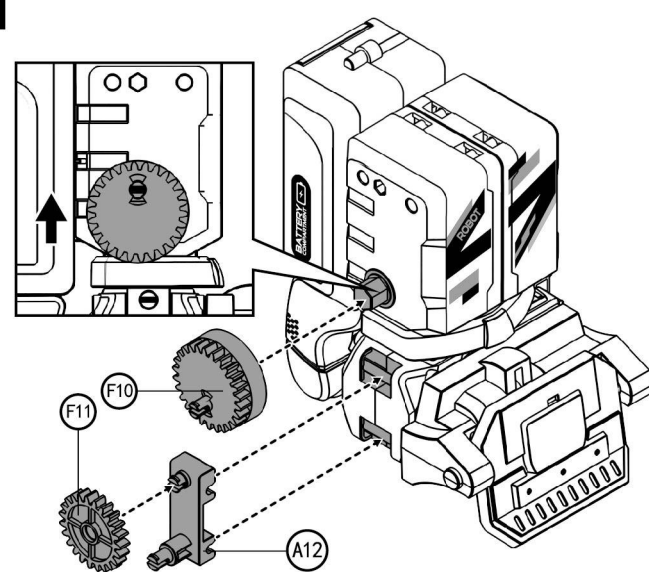
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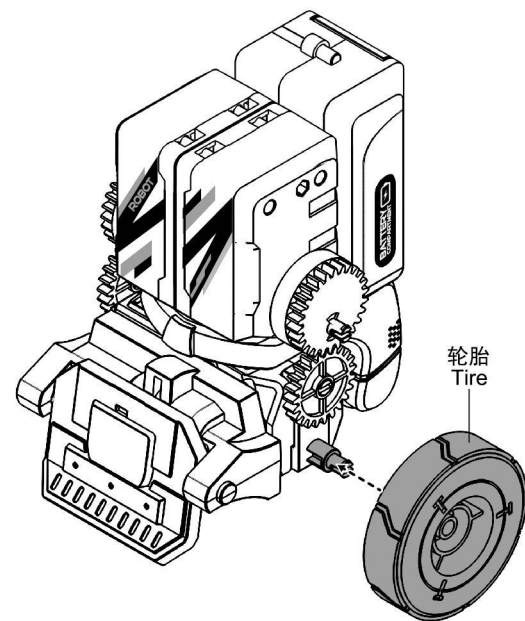
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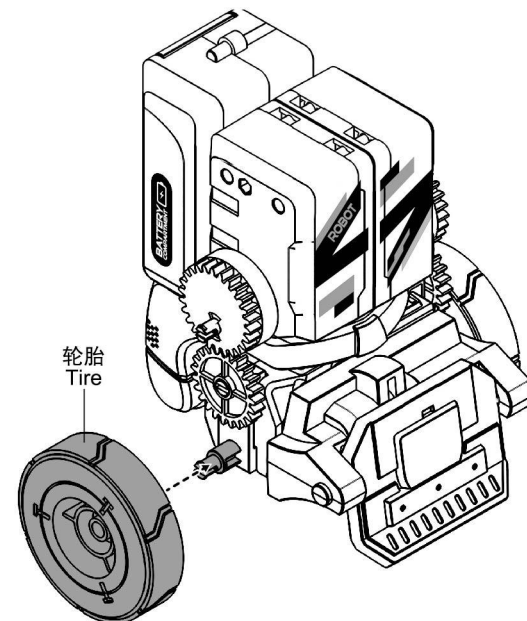
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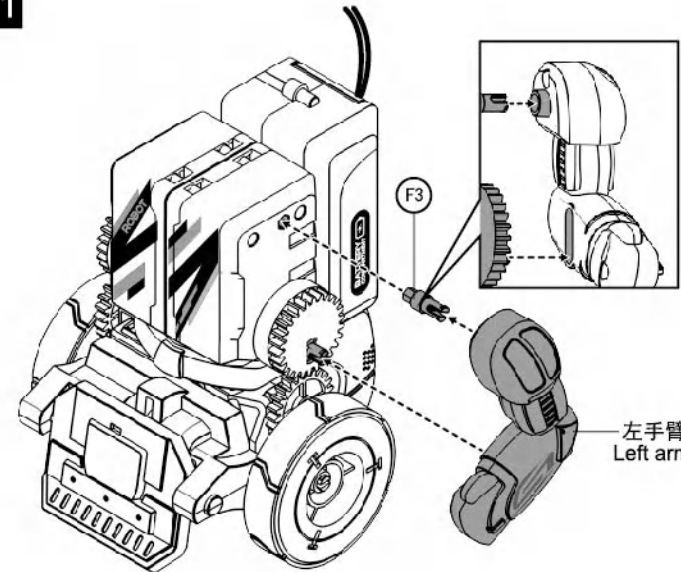
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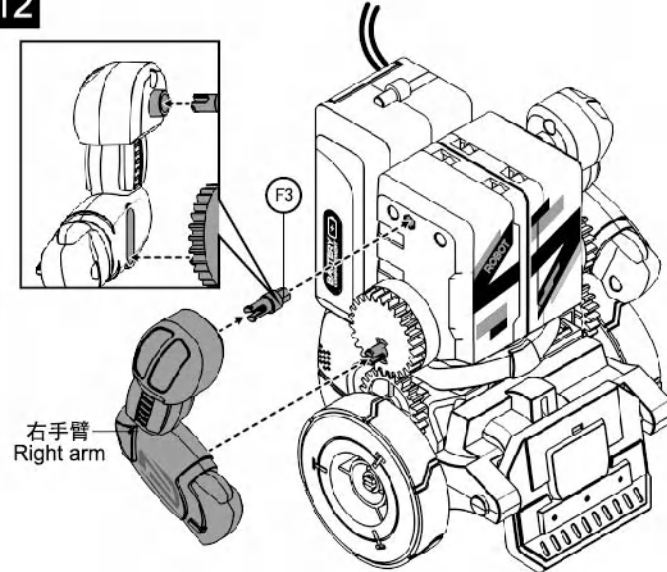
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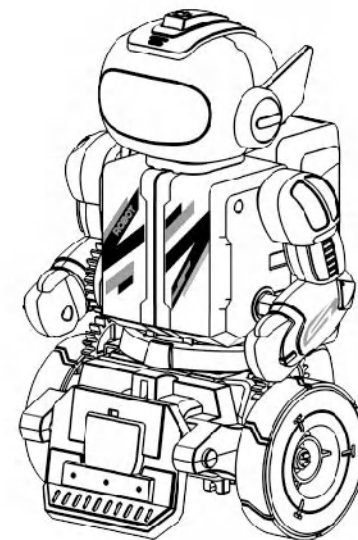
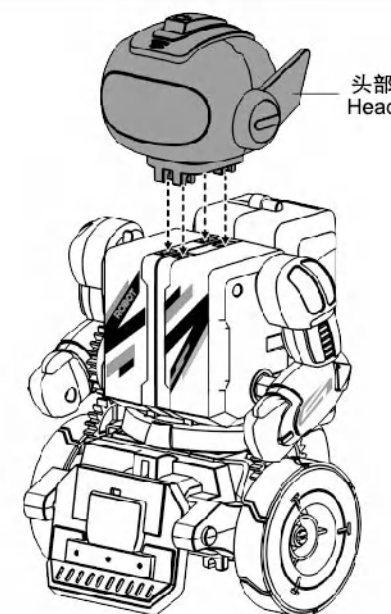
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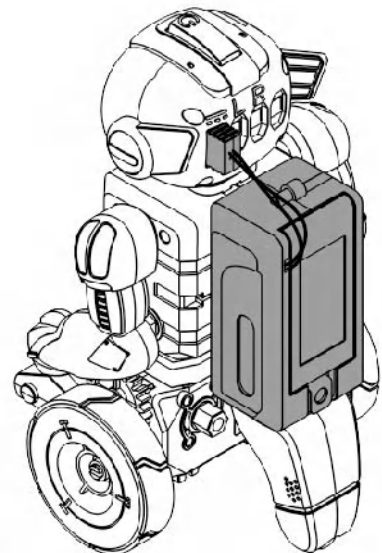


12

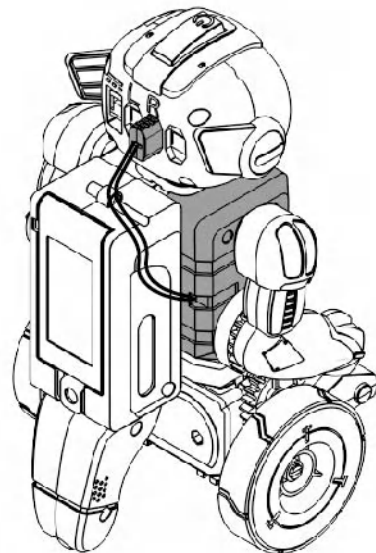
左手臂
Left arm右手臂
Right arm

13

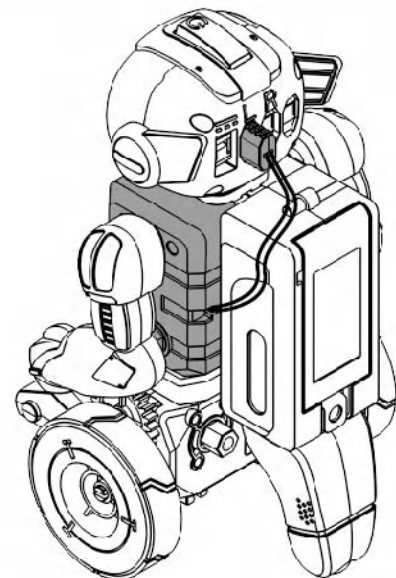




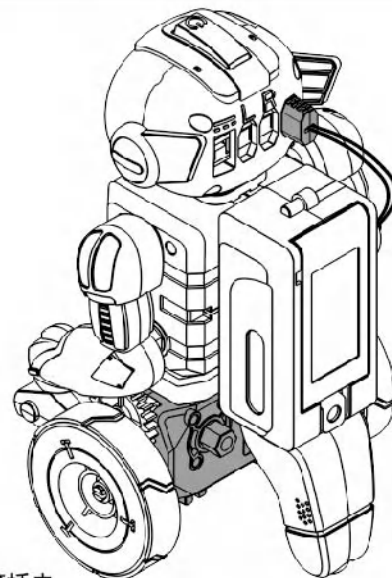
电池盒插电
Battery box plugged in



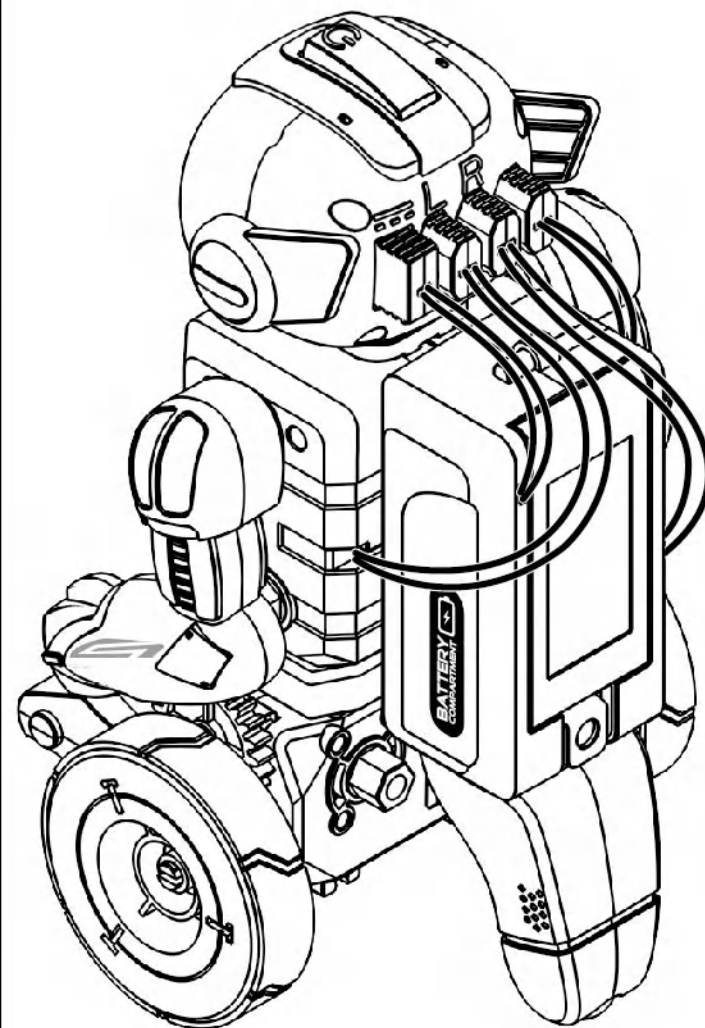
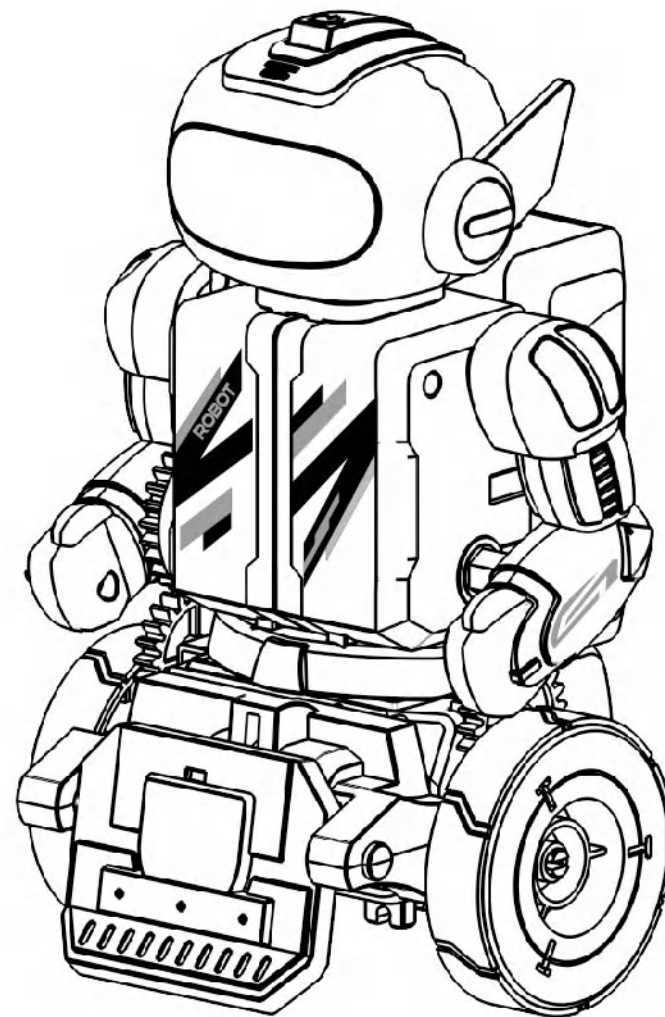
右齿轮箱插电
Right gear box plugged in



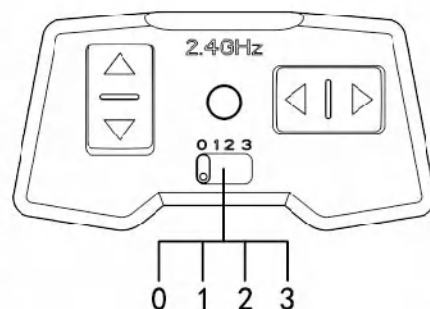
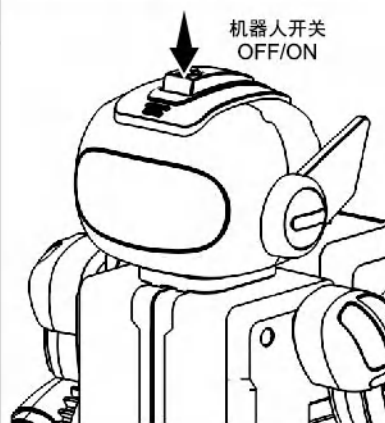
左齿轮箱插电
Left gear tooth box plugged in



中齿轮箱插电
The middle gear tooth box is plugged in.



遥控信号对频教程 Signal frequency tutorial



1. 打开机器人开关，按下头部按钮
2. 拨动遥控器开关
 - 0挡—关掉开关
 - 1挡—对应“狙击神射手”，对频成功机器人会发出声音“滴”
 - 2挡—对应“夹物小能手”，对频成功机器人会发出声音“滴滴”
 - 3挡—对应“足球小健将”，对频成功机器人会发出声音“滴滴滴”

1. Turn on the robot switch and press the head button.
2. Unplug the remote control switch

Turn off the switch with 0 gear.
A pair of An "sniper shooters" in the first gear, and the successful robot will make a sound "drip"

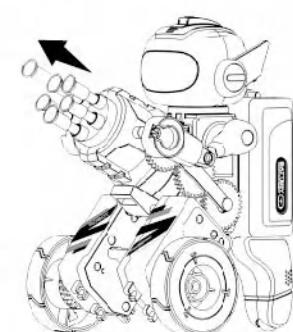
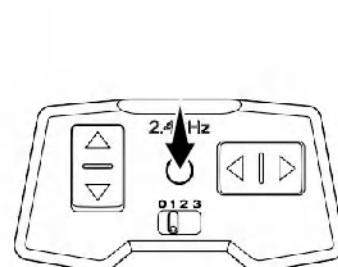
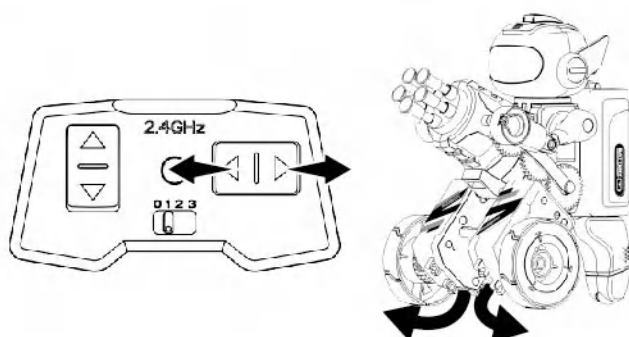
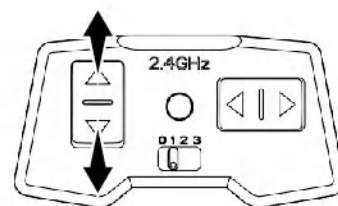
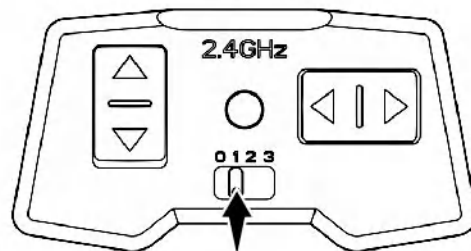
The second gear corresponds to the "clamp robot", and the successful robot will make a sound. Didi

The 3rd gear corresponds to the "football player", and the successful robot will make a sound. Didi

When the robot makes a sound indicating that the frequency is successful, it can start to control your robot.

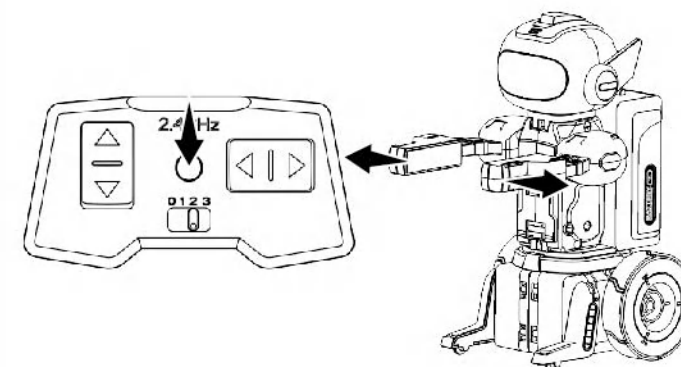
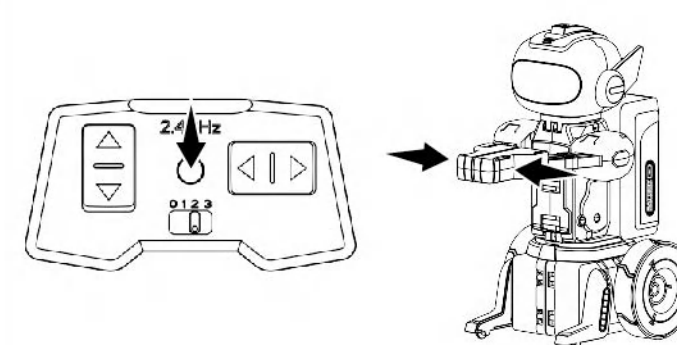
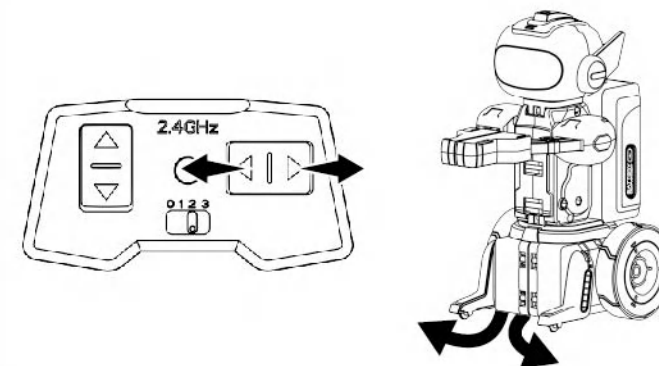
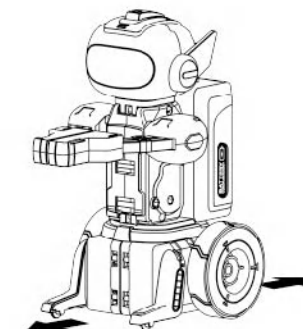
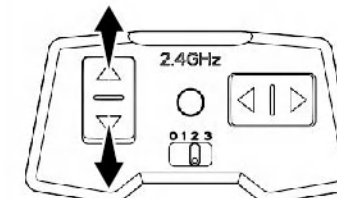
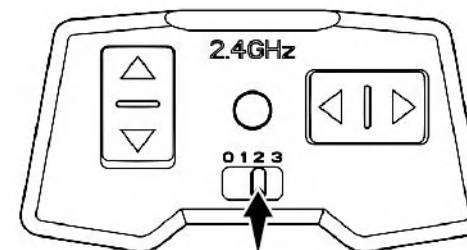
遥控教程-狙击神射手 Remote Control Tutorial Sniper Shooter

将开关调至1档操控狙击神射手
Adjust the switch to 1 to control the sniper shooter.



遥控教程-夹物小能手 Remote Control Tutorial - Clamp Robot

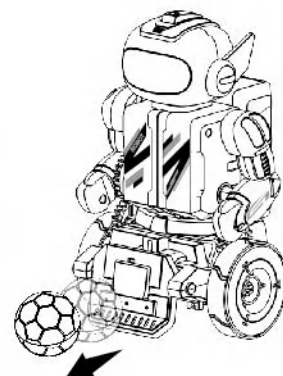
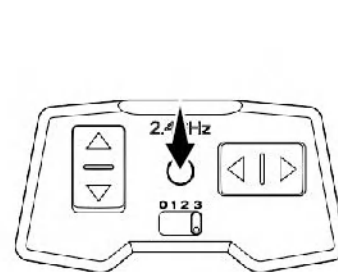
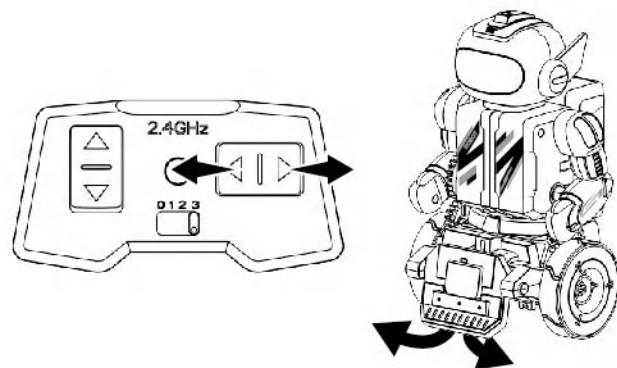
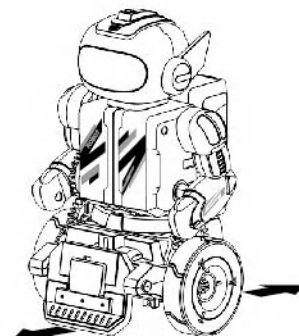
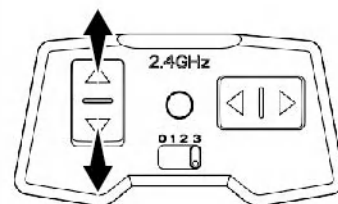
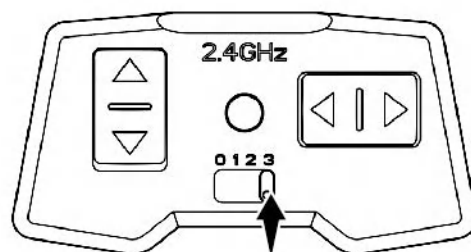
将开关调至2档操控夹物小能手
Adjust the back to the 2-speed control clamp robot.



遥控教程-足球小健将 Remote Control Tutorial - Football Player

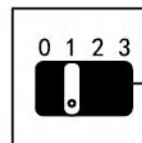
将开关调至3档操控足球小健将

Adjust the switch to the third gear to control the football player.



编程教程-狙击神射手 Programming Tutorial Sniper Shooter

步骤1
Step 1 将遥控器开关切换至1档
Switch the remote control switch to 1

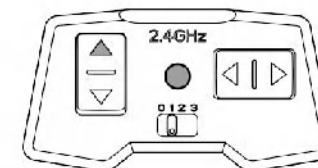


切换档位
Switch gears

遥控中央键
Remote control central key

步骤2
Step 2

进入编程模式：前进键+中央键，同时长按持续2秒钟，机器人发出声音“滴滴”进入编程模式，同样方式再次操作回到遥控模式，循环切换模式。
Enter the programming mode, move forward and health + central health. At the same time, press for 2 seconds. The robot makes a sound "Didi" to enter the programming mode. In the same way, it will operate back to the remote control mode and switch mode in a loop.



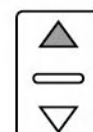
进入编程模式
Go to programming mode
遥控中央键
Remote control central key

步骤3
Step 3

开始编程设计机器人动作/行走路线
Start programming and designing robot movements and walking routes.

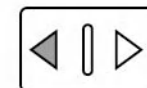
编程示范——请依据实际状况编程，以下示范仅供参考
Programming demonstration Please program according to the actual situation. The following demonstration is for reference only.

前进 Forward



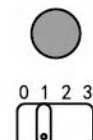
x3

左旋转 Turn left



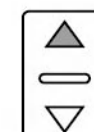
x7

射击 Shooting



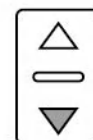
x1

前进 Forward



x3

后退 Backwards



x1

射击 Shooting



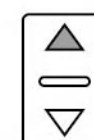
x2

左旋转 Turn left



x6

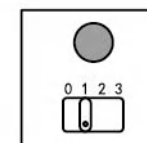
前进 Forward



x2

步骤4
Step 4

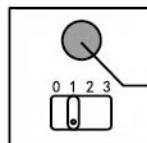
完成编程指令后，长按中央键持续2秒钟
After completing the programming instruction, press the center key for 2 seconds.



完成
Complete
遥控中央键
Remote control central key

步骤5 Step 5

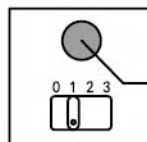
短按一次中央键，机器人开始执行指令动作
Press the central key once, and the robot begins to execute the command action



执行
Perform
遥控中央键
Remote control central key

重复执行 repetitive execution

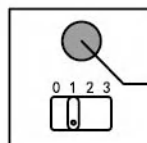
当机器人完成动作后，玩家可以再次短按中央键命令机器人重复执行前次动作
Repeat When the robot completes the action, the player can briefly press the center button again to command the robot to repeat the previous action.



重复执行
repetitive execution
遥控中央键
Remote control central key

重置编程 Reset the programming

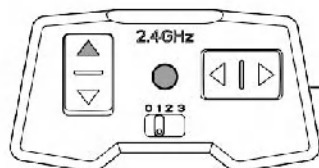
长按中央键持续2秒，玩家可以重新设计编程指令
Repeat programming Long press the center key for 2 seconds, and players can redesign programming instructions.



重置编程
Reset the programming
遥控中央键
Remote control central key

返回遥控模式 Return to remote mode

前进键+中央键，同时长按持续2秒钟，机器人切换为遥控模式
Forward key + center key, press for 2 seconds at the same time, and the robot switches to remote control mode.

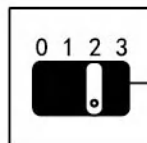


返回遥控模式
Return to remote mode
遥控中央键
Remote control central key

编程教程-夹物小能手 Programming Tutorial Clip Robot

步骤1 Step 1

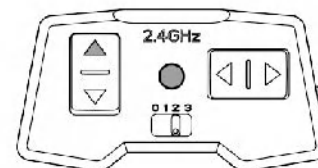
将遥控器开关切换至2档
Switch the remote control switch to 2



切换档位
Switch gears
遥控中央键
Remote control central key

步骤2 Step 2

进入编程模式：前进键+中央键，同时长按持续2秒钟，机器人发出声音“滴滴”进入编程模式，同样方式再次操作回到遥控模式，循环切换模式。
Enter the programming mode, move forward and health + central health. At the same time, press for 2 seconds. The robot makes a sound "Didi" to enter the programming mode. In the same way, it will operate back to the remote control mode and switch mode in a loop.

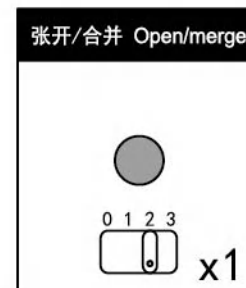
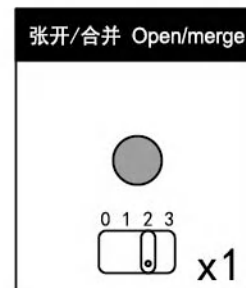
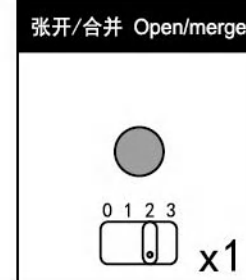
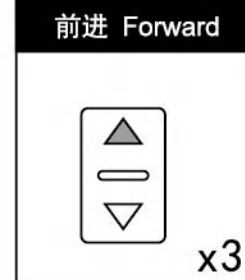
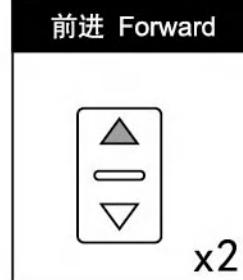


进入编程模式
Go to programming mode
遥控中央键
Remote control central key

步骤3 Step 3

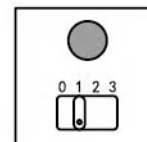
开始编程设计机器人动作/行走路线
Start programming and designing robot movements and walking routes.

编程示范——请依据实际状况编程，以下示范仅供参考
Programming demonstration Please program according to the actual situation. The following demonstration is for reference only.



步骤4 Step 4

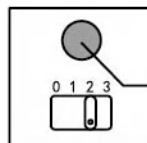
完成编程指令后，长按中央键持续2秒钟
After completing the programming instruction, press the center key for 2 seconds.



完成
Complete
遥控中央键
Remote control central key

步骤5 Step 5

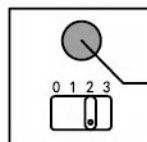
短按一次中央键，机器人开始执行指令动作
Press the central key once, and the robot begins to execute the command action



执行
Perform
遥控中央键
Remote control central key

重复执行 repetitive execution

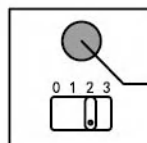
当机器人完成动作后，玩家可以再次短按中央键命令机器人重复执行前次动作
Repeat When the robot completes the action, the player can briefly press the center button again to command the robot to repeat the previous action.



重复执行
repetitive execution
遥控中央键
Remote control central key

重置编程 Reset the programming

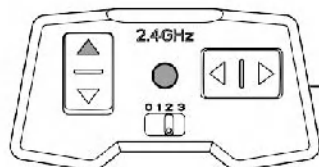
长按中央键持续2秒，玩家可以重新设计编程指令
Repeat programming Long press the center key for 2 seconds, and players can redesign programming instructions.



重置编程
Reset the programming
遥控中央键
Remote control central key

返回遥控模式 Return to remote mode

前进键+中央键，同时长按持续2秒钟，机器人切换为遥控模式
Forward key + center key, press for 2 seconds at the same time, and the robot switches to remote control mode.

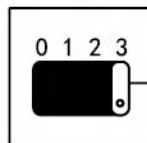


返回遥控模式
Return to remote mode
遥控中央键
Remote control central key

编程教程-足球小健将 Programming Tutorial Football player

步骤1 Step 1

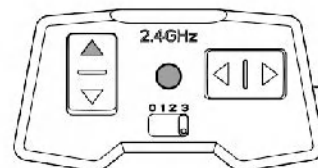
将遥控器开关切换至3档
Switch the remote control switch to 3



切换档位
Switch gears
遥控中央键
Remote control central key

步骤2 Step 2

进入编程模式：前进键+中央键，同时长按持续2秒钟，机器人发出声音“滴滴”进入编程模式，同样方式再次操作回到遥控模式，循环切换模式。
Enter the programming mode, move forward and health + central health. At the same time, press for 2 seconds. The robot makes a sound "Didi" to enter the programming mode. In the same way, it will operate back to the remote control mode and switch mode in a loop.

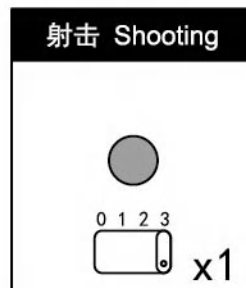
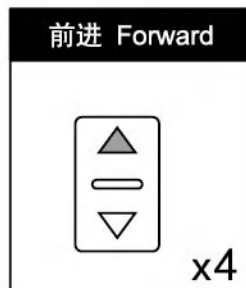
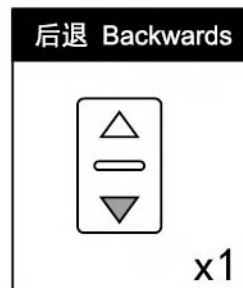
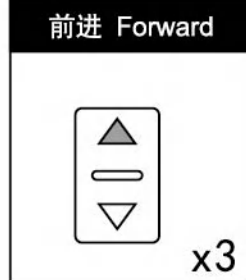
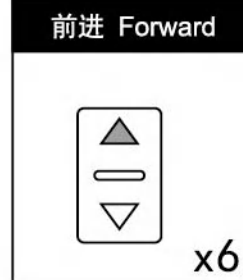


进入编程模式
Go to programming mode
遥控中央键
Remote control central key

步骤3 Step 3

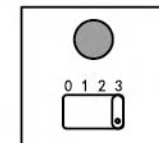
开始编程设计机器人动作/行走路线
Start programming and designing robot movements and walking routes.

编程示范——请依据实际状况编程，以下示范仅供参考
Programming demonstration Please program according to the actual situation. The following demonstration is for reference only.



步骤4 Step 4

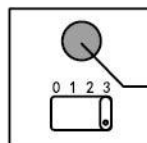
完成编程指令后，长按中央键持续2秒钟
After completing the programming instruction, press the center key for 2 seconds.



完成
Complete
遥控中央键
Remote control central key

步骤5 Step 5

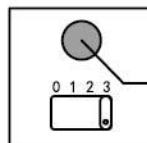
短按一次中央键，机器人开始执行指令动作
Press the central key once, and the robot begins to execute the command action



执行
Perform
遥控中央键
Remote control central key

重复执行 repetitive execution

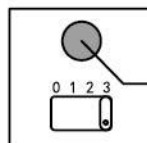
当机器人完成动作后，玩家可以再次短按中央键命令机器人重复执行前次动作
Repeat When the robot completes the action, the player can briefly press the center button again to command the robot to repeat the previous action.



重复执行
repetitive execution
遥控中央键
Remote control central key

重置编程 Reset the programming

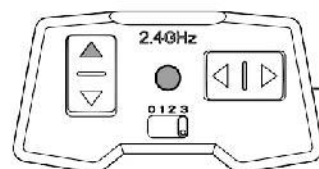
长按中央键持续2秒，玩家可以重新设计编程指令
Repeat programming Long press the center key for 2 seconds, and players can redesign programming instructions.



重置编程
Reset the programming
遥控中央键
Remote control central key

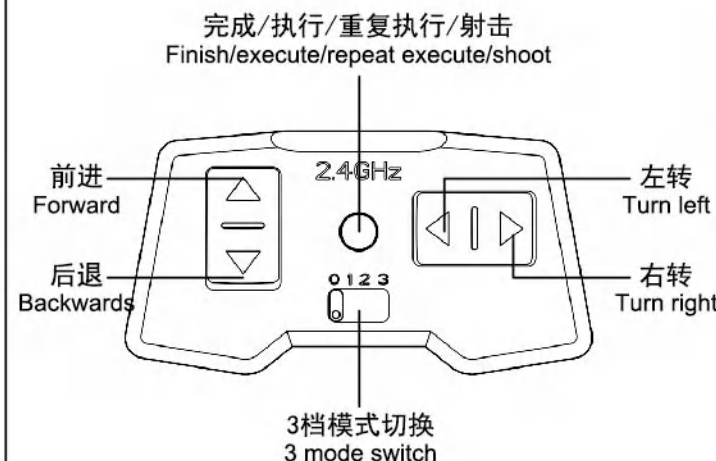
返回遥控模式 Return to remote mode

前进键+中央键，同时长按持续2秒钟，机器人切换为遥控模式
Forward key + center key, press for 2 seconds at the same time, and the robot switches to remote control mode.



返回遥控模式
Return to remote mode
遥控中央键
Remote control central key

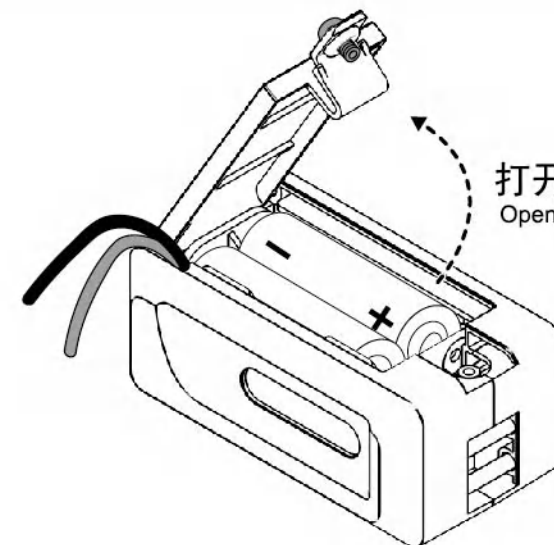
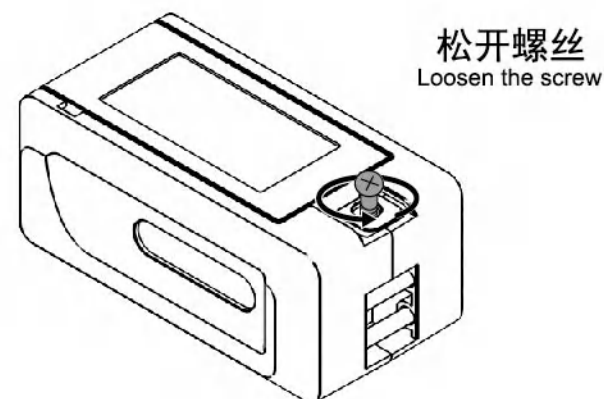
操作方式 How to operate

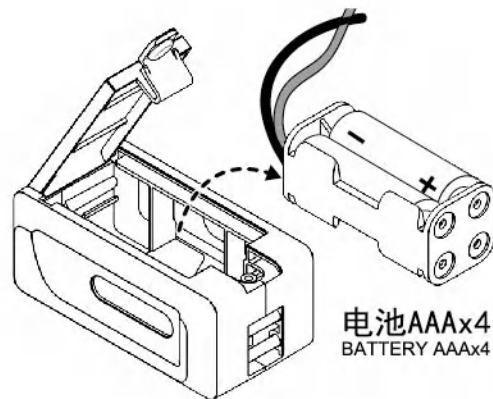


操作指引 How-to guidelines

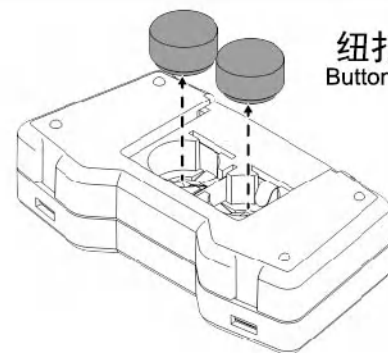
- 每次最多可输入64个指令，当输入第65个指令时，机器人会发出“滴~~滴滴”（一长两短音）警示声拒绝接收指令
- 当机器人闲置超过1分钟时会发出“滴-滴”声提示，只需按任意键即可唤醒机器人并继续游玩。当发出“滴-滴”声提示之后还无人操作，“滴-滴”声会持续30秒，然后进入休眠状态，即无法再操控机器人
- 当机器人进入休眠状态时，需要重启机器人开关以及遥控器开关，重新信号对频（参考第50页“遥控信号对频教程”）才能继续操控机器人
- You can enter up to 64 fingers at a time. When the 65th instruction is programmed, the robot will issue "Didi" (One long and two short notes) Warning sound refuses to receive instructions
- When the robot is idle for more than 1 minute, it will make a "drip-drop" sound prompt. Just press any health to wake up the robot and continue to play. When no one operates after issuing a "drip-drop" sound prompt, the "drip-drop" sound will last for 30 seconds, and then enters a dormant state, that is, the robot can no longer be controlled.
- When the robot enters a hibernation state, it is necessary to restart the robot switch and the remote control switch, and re-signal frequency matching (refer to the 50p "Signal Frequency Tutorial") to maintain the control of the robot.

更换电池方式 Battery replacement method



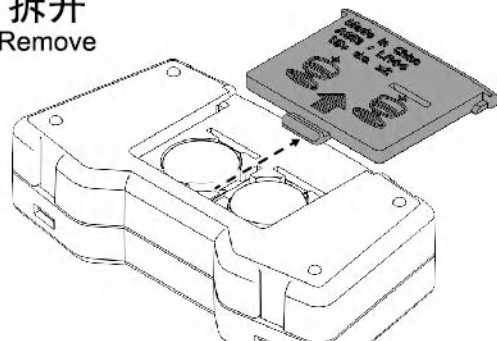


电池AAAx4
BATTERY AAAx4

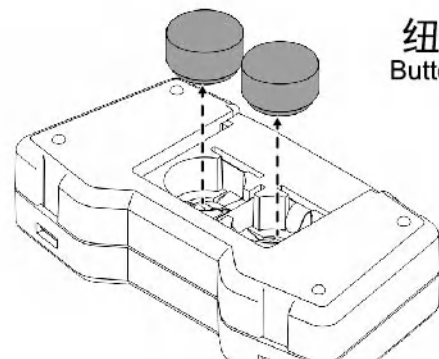


纽扣电池
Button batteries

拆开
Remove



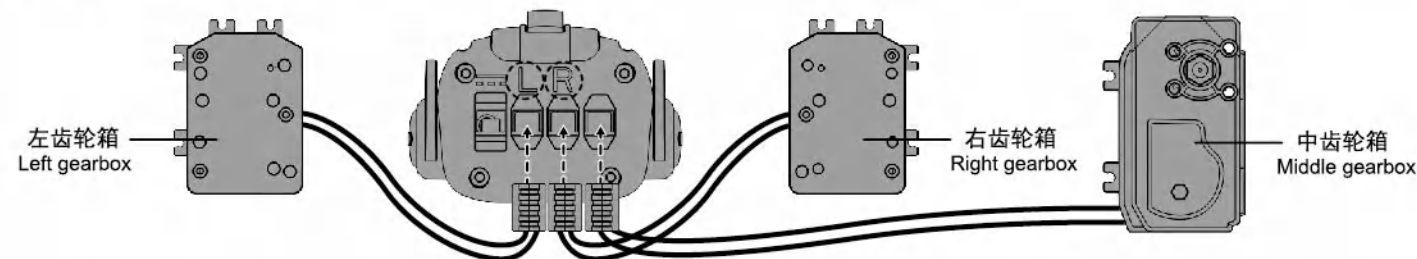
- 电池移除或更换应由成人或在成人监督下进行。
 - 请避免电池或电池连接器端子短路。
 - 电池长期不用或电力耗尽时请取出以避免电池漏液。
 - 请勿混用新旧电池及不同厂牌、种类的电池，以免造成危险或电器损耗。
 - 请勿混合碱性、碳锌电池或充电电池使用。
 - 电池放入前请先确认正确正负极性方向。
 - 请勿试图对非充电电池进行充电。
 - 充电电池应在成人监督下进行充电。
 - 本产品不能连接多于一个电源。
 - 充电电池在充电前应从玩具中取出。
- Battery removal or replacement should be performed by an adult or under an adult meal.
 - Avoid short circuits from battery or battery connector terminals.
 - Remove the battery when it is not used for a long time or when power runs out to avoid leakage.
 - Do not mix new day batteries with different brands and types of batteries, so as not to Causing danger or electrical loss.
 - Do not mix shouting, carbon-zinc batteries or rechargeable batteries.
 - Please confirm the correct direction of positive and negative polarity before placing the battery.
 - Do not attempt to charge a non-rechargeable battery.
 - Rechargeable batteries should be charged under adult supervision.
 - This product cannot be connected more than A power supply.
 - The rechargeable battery should be removed from the toy before charging.



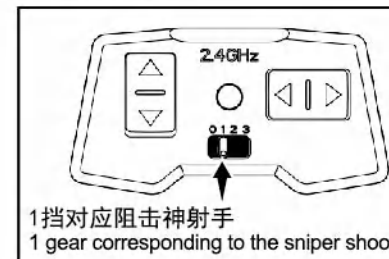
纽扣电池
Button batteries

简易故障排除 Simple troubleshooting

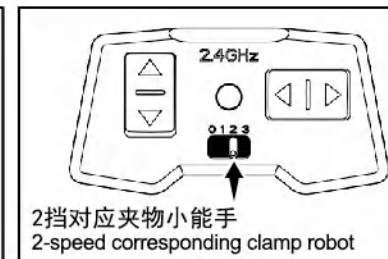
1. 请确认电池安装位置是否正确，参考第21页，步骤4
Please identify whether the battery is installed correctly, please refer to page 21, step 4
2. 如果机器人未正确的依循遥控/编程动作，请确认左、中、右齿轮箱和电池盒插电位置是否正确
If the robot does not correctly follow the remote control and programming actions, please confirm that the left center and right gearbox and battery are plugged in correctly.



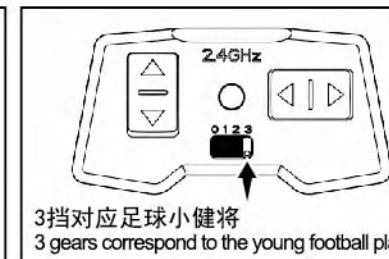
3. 如机器人未正确的依循遥控/编程动作，请确认遥控器开关位置是否正确重复体现1挡对应狙击神射手，2挡对应夹物小能手，3挡对应足球小健将
If the robot does not correctly follow the remote control and programming actions, please confirm whether the remote control switch position is correctly and repeatedly reflects the first gear corresponding to the sniper shooter, the second gear corresponds to the clamp robot, and the third gear corresponds to the football player.



1挡对应狙击神射手
1 gear corresponding to the sniper shooter



2挡对应夹物小能手
2-speed corresponding clamp robot



3挡对应足球小健将
3 gears correspond to the young football player.

4. 如狙击神射手无法正常射击，请确认“狙击神射手合成组装”是否安装正确，参考第35页，步骤10-12
If the sniper shooter cannot shoot normally, please confirm whether the "sniper shooter synthesis assembly" is installed correctly. Please refer to page 35, step 10-12
5. 如夹物小能手无法正常打开手臂或者合并手臂，请确认“夹物小能手合成组装”是否安装正确，参考第41页，步骤8-9
If the clamp robot can't open or merge the arm normally, please confirm whether the clamp robot synthesis assembly is installed correctly. Please refer to page 41, steps 8-9
6. 如足球小健将无法正常射击，请确认是否安装正确，参考第44页，步骤1
If the football player is unable to shoot normally, please confirm whether it is installed correctly. Please refer to page 44, steps 1

NOTE: This equipment has been tested and found to comply with the limits for a Class B digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions , may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/TV technician for help.

Changes or modifications not expressly approved by the party responsible for compliance could void the user's authority to operate the equipment.